

# ETH ROBOTICS SUMMER SCHOOL

## LINUX & ROS CHEAT SHEET

AUTHOR: YIZE WANG  
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## File Commands

\$ ls	list contents of current directory
\$ ls -a	list hidden contents of current directory
\$ cd \$DIR	change working directory to \$DIR
\$ cd	change working directory to home
\$ mkdir \$DIR	create a directory named \$DIR
\$ pwd	print working directory
\$ rm \$FILE	remove \$FILE
\$ rm -r \$DIR	remove \$DIR
\$ rm -f \$FILE	force remove \$FILE
\$ rm -rf \$DIR	force remove \$DIR
\$ cp \$FILE \$DIR	copy \$FILE to \$DIR
\$ cp -r \$DIR1 \$DIR2	copy \$DIR1 to \$DIR2 recursively
\$ mv \$FILE \$DIR	move \$FILE to \$DIR
\$ ln -s \$FILE \$LINK	create symbolic link \$LINK to \$FILE
\$ touch \$FILE	create \$FILE
\$ cat \$FILE	view content of \$FILE
\$ cat > \$FILE	write input into \$FILE
\$ more \$FILE	print content of \$FILE
\$ head \$FILE	print the first 10 lines of \$FILE
\$ tail \$FILE	print the last 10 lines of \$FILE
\$ gedit \$FILE	edit \$FILE using GUI text editor
\$ vim \$FILE	edit \$FILE using Vim

## System Information

<b>\$ env</b>	print environment variables
<b>\$ date</b>	print system date and time
<b>\$ man \$COMMAND</b>	print user manual of <b>\$COMMAND</b>
<b>\$ whereis \$APP</b>	print locations of <b>\$APP</b>
<b>\$ which \$APP</b>	print executable file of <b>\$APP</b>
<b>\$ ps</b>	print process status
<b>\$ ps -aux</b>	print all running process
<b>\$ htop</b>	print currently running processes and more
path symbolic links	<ul style="list-style-type: none"><li>.</li><li>..</li><li>~</li><li>\</li></ul>
output direction	<ul style="list-style-type: none"><li>&gt;</li><li>&gt;&gt;</li><li> </li></ul>

## Linux Shell

<b>Ctrl+Alt+T</b>	launch a new terminal
<b>Ctrl+C</b>	kill the current process
<b>Ctrl+Z</b>	suspend the current process
<b>fg</b>	resume the suspended process in foreground
<b>bg</b>	resume the suspended process in background
<b>Ctrl+D</b>	log out of the current session
<b>Ctrl+W</b>	erase one word in the current line
<b>Ctrl+U</b>	erase the whole current line
<b>Ctrl+R</b>	reverse search in the previous commands
<b>Ctrl+A</b>	go to the beginning of the line
<b>Ctrl+E</b>	go to the end of the line
<b>!!</b>	execute the last command
<b>exit</b>	log out of the current session
<b>clear</b>	clear the terminal screen

Use **Ctrl+R** to reverse search, type part of a command and hit **Ctrl+R** repeatedly. **Ctrl+A** is especially useful when you forget to add **sudo** before the command.

## Terminator

<b>Ctrl+Shift+E</b>	split terminals vertically
<b>Ctrl+Shift+O</b>	split terminals horizontally
<b>Ctrl+Shift+T</b>	open a new tab
<b>Ctrl+Shift+I</b>	open a new window

## Secure Shell (SSH)

\$ ssh \$USER@\$HOST	connect to \$HOST as \$USER
\$ ssh \$IP_ADDRESS	connect to \$IP_ADDRESS
\$ ssh -p \$PORT \$USER@\$HOST	connect to \$HOST on \$PORT as \$USER
\$ ssh-copy-id \$USER@\$HOST	add the key to \$HOST as \$USER

## Package

<b>\$ apt-get update</b>	synchronize package index files from sources
<b>\$ apt-get upgrade</b>	install latest versions of installed packages
<b>\$ apt-get install \$PACKAGE</b>	install <code>\$PACKAGE</code>
<b>\$ dpkg -i \$PACKAGE.deb</b>	install a Debian package <code>\$PACKAGE.deb</code>
<b>./configure</b>	configure building settings
<b>\$ make</b>	build the program from source code
<b>\$ make install</b>	install the program

## Searching

\$ grep <b>\$PATTERN</b> <b>\$FILES</b>	search for <b>\$PATTERN</b> in <b>\$FILES</b>
\$ grep -r <b>\$PATTERN</b> <b>\$DIR</b>	search for <b>\$PATTERN</b> recursively in <b>\$DIR</b>
\$ grep -n <b>\$PATTERN</b> <b>\$FILES</b>	search for <b>\$PATTERN</b> and print line numbers
\$ grep -C1 <b>\$PATTERN</b> <b>\$FILES</b>	search for <b>\$PATTERN</b> and print 1-line context
\$ <b>\$CMD</b>   grep <b>\$PATTERN</b>	search for <b>\$PATTERN</b> in <b>\$CMD</b> 's output
\$ locate <b>\$FILE_NAME</b>	find files whose name contain <b>\$FILE_NAME</b>

## Git

<code>\$ git clone \$URL</code>	clone the repository from <code>\$URL</code>
<code>\$ git status</code>	print current branch status <code>\$BRANCH</code>
<code>\$ git branch \$BRANCH</code>	create a new branch named <code>\$BRANCH</code>
<code>\$ git checkout \$BRANCH</code>	switch to the branch named <code>\$BRANCH</code>
<code>\$ git merge \$BRANCH</code>	combine <code>\$BRANCH</code> into the current one
<code>\$ git fetch</code>	download all history from GitHub
<code>\$ git merge</code>	combine remote branches into local branch
<code>\$ git push</code>	upload all local branch commits to GitHub
<code>\$ git pull</code>	update local branch from GitHub
<code>\$ git log</code>	list version history for current branch
<code>\$ git log --follow \$FILE</code>	list version history for <code>\$FILE</code>
<code>\$ git show \$COMMIT</code>	output content changes of <code>\$COMMIT</code>
<code>\$ git add \$FILE</code>	stage <code>\$FILE</code>
<code>\$ git commit -m "\$MESSAGE"</code>	commit staged file with <code>\$MESSAGE</code>
<code>\$ git reset \$FILE</code>	reset <code>\$FILE</code>
<code>\$ git reset --hard</code>	reset all uncommitted changes
<code>\$ git clean -fd</code>	recursively force remove unstaged files

## Tips

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Hitting **Tab** while typing a command, file name, and option will auto-complete it.

**sudo** (superuser do) runs command with elevated privilege.

**tar** (tape archive) deal with tape drives backup.

Appending **--help** after a command will print command usage help.

## Docker

[illegible]

## ROS Catkin Workspace

\$ roscd <b>\$PACKAGE</b>	change directory to <b>\$PACKAGE</b>
\$ catkin build	build the whole workspace
\$ catkin build <b>\$PACKAGE</b>	build <b>\$PACKAGE</b>
\$ catkin clean	clean the whole workspace
\$ catkin clean <b>\$PACKAGE</b>	clear <b>\$PACKAGE</b>
Always remember to <b>\$ source /catkin_ws/devel/setup.bash</b> .	

## ROS Run

\$ roscore	invoke the core of ROS
\$ roslaunch <b>\$PACKAGE</b> <b>\$LAUNCHFILE</b>	launch <b>\$LAUNCHFILE</b> in <b>\$PACKAGE</b>
\$ rosrun <b>\$PACKAGE</b> <b>\$EXECUTABLE</b> ( <b>\$PARAM</b> :- <b>\$VALUE</b> )	
run node <b>\$EXECUTABLE</b> from <b>\$PACKAGE</b> (with <b>\$PARAM</b> set to <b>\$VALUE</b> )	

## ROS Environmental Variables

ROS_ROOT	location of core ROS packages
ROS_MASTER_URI	location of the master
ROS_PACKAGE_PATH	locations for more ROS packages
ROS_HOSTNAME	network address of a node
ROS_IP	IP address of a node

## ROS Node

\$ rosnode ping <b>\$NODE</b>	test connectivity to <b>\$NODE</b>
\$ rosnode list	list active nodes
\$ rosnode info <b>\$NODE</b>	print information about <b>\$NODE</b>
\$ rosnode machine	list nodes running on the machine
\$ rosnode kill <b>\$NODE</b>	kill a running node

## ROS Service

\$ rosservice list	list active services
\$ rosservice call <b>\$SERVICE</b> <b>\$ARGS</b>	call <b>\$SERVICE</b> with <b>\$ARGS</b>
\$ rosservice find <b>\$TYPE</b>	find services with <b>\$TYPE</b>
\$ rosservice info <b>\$SERVICE</b>	print information about <b>\$SERVICE</b>
\$ rosservice type <b>\$SERVICE</b>	print type of <b>\$SERVICE</b>
\$ rosservice uri <b>\$SERVICE</b>	print uri of <b>\$SERVICE</b>
\$ rossrv show <b>\$TYPE</b>	print structure of <b>\$TYPE</b>

## ROS Topic

\$ rostopic list	print information about active topics
\$ rostopic bw <b>\$TOPIC</b>	display bandwidth used by <b>\$TOPIC</b>
\$ rostopic echo <b>\$TOPIC</b>	print messages from <b>\$TOPIC</b>
\$ rostopic find <b>\$TYPE</b>	find topics with <b>\$TYPE</b>
\$ rostopic hz <b>\$TOPIC</b>	display publishing rate of <b>\$TOPIC</b>
\$ rostopic info <b>\$TOPIC</b>	print information about <b>\$TOPIC</b>
\$ rostopic pub <b>\$TOPIC</b>	publish data to <b>\$TOPIC</b>
\$ rostopic type <b>\$TOPIC</b>	print type of <b>\$TOPIC</b>
\$ rosmmsg show <b>\$TYPE</b>	print structure of <b>\$TYPE</b>

## ROS Parameter

\$ rosparam list	list all parameter names
\$ rosparam set <b>\$PARAM</b> <b>\$VAL</b>	set <b>\$PARAM</b> to <b>\$VAL</b>
\$ rosparam get <b>\$PARAM</b>	print value of <b>\$PARAM</b>
\$ rosparam load <b>\$YAML</b>	load parameters from <b>\$YAML</b>
\$ rosparam dump <b>\$YAML</b>	dump parameters to <b>\$YAML</b>
\$ rosparam delete <b>\$PARAM</b>	delete <b>\$PARAM</b>

## ROS Bag

\$ rosbag record <b>\$TOPIC</b>	record <b>\$TOPIC</b> into bag
\$ rosbag info <b>\$BAG</b>	print content summary of <b>\$BAG</b>
\$ rosbag play <b>\$BAG</b>	play back content of <b>\$BAG</b>
\$ rosbag check <b>\$BAG</b>	check play-ability of <b>\$BAG</b> in current system
\$ rosbag compress <b>\$BAG</b>	compress <b>\$BAG</b> using BZ2
\$ rosbag decompress <b>\$BAG</b>	decompress <b>\$BAG</b> using BZ2

When simulating in ROS, remember **\$ set use\_sim\_time true** and to append **--clock**.

## ROS Packge Structure

package.xml	manifest, dependencies and plugins
CMakeLists.txt	description of compilation procedure
src/	C and C++ source codes
build/	generated makefiles and support files
devel/	compiled binaries, libraries, headers
include/	C and C++ header files
scripts/	Python and bash scripts
config/	ymal configuration files
cfg/	dynamics reconfigure scripts
launch/	launch files

## ROS Visualization Tools

\$ rviz	3D visualization of data and models
\$ gzclient	Gazebo GUI
\$ rqt	powerful GUI tool
\$ rqt_plot	simple and lightweight plotting
\$ rqt_bag	visualize content of a bag
\$ rqt_image_view	visualize camera images
\$ rqt_graph	visualize computation graph

# TODO

is git reset unstage or reset?  
roscat machine  
CMakeList  
catkin build / clean / make  
ros variable

# Compression

\$ tar cf \$FILE.tar \$FILES	convert \$FILES into \$FILE.tar
\$ tar xf \$FILE.tar	extract files from \$FILE.tar
\$ tar czf \$FILE.tar.gz \$FILES	compress \$FILES into \$FILE.tar.gz using Gzip
\$ tar xzf \$FILE.tar.gz	extract files from \$FILE.tar.gz using Gzip
\$ gzip \$FILE	compress \$FILE and rename it as \$FILE.gz
\$ gzip -d \$FILE.gz	decompress \$FILE.gz back to \$FILE

# Network

\$ ip address	print all internet protocol addresses
\$ ping \$HOST	ping \$HOST and print results
\$ whois \$DOMAIN	print information about \$DOMAIN
\$ dig \$DOMAIN	print DNS of \$DOMAIN
\$ dig -x \$HOST	reverse lookup \$HOST
\$ wget \$FILE	download \$FILE