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**Linear System Theory**  
**Solutions to Problem Set 1**  
**Linear Spaces, Linear Maps, and Representations**  
**Issue date: September 23, 2019**  
**Due date: October 7, 2019**

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**Solution 1. (Linear spaces [40 points in total])**

1. [18 points in total] We verify the axioms of a vector space.

- Associativity of  $\oplus$ : trivial.
- The identity element of  $\oplus$  (that is, the zero vector) is the constant function  $\theta(x) = 1$  for all  $x \in S$ . Indeed  $[\theta \oplus f](x) = \theta(x)f(x) = 1f(x) = f(x)$  for all  $x \in S$ .
- The inverse of a function  $f$  is the function  $f^-$  defined as  $f^-(x) = \frac{1}{f(x)}$  for all  $x \in S$ . Indeed  $[f^- \oplus f](x) = f^-(x)f(x) = \frac{1}{f(x)}f(x) = 1 = \theta(x)$  for all  $x \in S$ .
- Commutativity of  $\oplus$ : trivial.
- Associativity of  $\odot$ : for all  $\alpha, \beta \in \mathbb{R}$  and  $f \in F$ ,  $[\alpha \odot [\beta \odot f]](x) = [\beta \odot f](x)^\alpha = f(x)^{\alpha\beta} = [(\alpha\beta) \odot f](x)$ .
- Multiplication identity:  $[1 \odot f](x) = f(x)^1 = f(x)$ .
- Distributivity, first property:  $[(\alpha + \beta) \odot f](x) = f(x)^{\alpha+\beta} = f(x)^\alpha f(x)^\beta = [\alpha \odot f](x)[\beta \odot f](x) = [[\alpha \odot f] \oplus [\beta \odot f]](x)$ .
- Distributivity, second property:  $[\alpha \odot [f_1 \oplus f_2]](x) = (f_1(x)f_2(x))^\alpha = f_1(x)^\alpha f_2(x)^\alpha = [\alpha \odot f_1](x)[\alpha \odot f_2](x) = [[\alpha \odot f_1] \oplus [\alpha \odot f_2]](x)$ .

2. [12 points in total] Suppose that  $\alpha \odot f_1 \oplus \beta \odot f_2 = \theta$ . Then

$$1 = [\alpha \odot f_1 \oplus \beta \odot f_2](a) = f_1(a)^\alpha f_2(a)^\beta = 2^\alpha 1^\beta = 2^\alpha$$

$$1 = [\alpha \odot f_1 \oplus \beta \odot f_2](b) = f_1(b)^\alpha f_2(b)^\beta = 1^\alpha 3^\beta = 3^\beta$$

Therefore, it must hold  $\alpha = \beta = 0$ , and  $\{f_1, f_2\}$  are linearly independent. To show that  $\{f_1, f_3\}$  are linearly dependent, it suffices to recognize that  $f_3(x) = f_1(x)^2$ , or  $f_3 = 2 \odot f_1$ ; hence  $2 \odot f_1 \oplus (-1) \odot f_3 = \theta$  with nonzero coefficients.

3. [10 points in total] We verify the definition of linearity: For all  $f_1, f_2, f \in F$  and  $\alpha \in \mathbb{R}$ ,

$$\begin{aligned} [\varphi(f_1 \oplus f_2)](x) &= \sqrt{[f_1 \oplus f_2](x)} \\ &= \sqrt{f_1(x)f_2(x)} \\ &= \sqrt{f_1(x)}\sqrt{f_2(x)} \\ &= [\varphi(f_1) \oplus \varphi(f_2)](x) \end{aligned}$$

and

$$\begin{aligned}
[\varphi(\alpha \odot f)](x) &= \sqrt{[\alpha \odot f](x)} \\
&= \sqrt{f(x)^\alpha} \\
&= \left(\sqrt{f(x)}\right)^\alpha \\
&= [\alpha \odot \varphi(f)](x).
\end{aligned}$$

**Solution 2. (Range and null space [40 points in total])**

1. [10 points in total] Note that by definition  $\dim(\text{RANGE}(\mathcal{A}))$  is nonnegative. We also have  $\text{RANGE}(\mathcal{A}) \subseteq F^m$ , and therefore  $\dim(\text{RANGE}(\mathcal{A})) \leq m$ .

Let  $\{b_1, \dots, b_n\}$  be a basis of  $F^n$ . Then,  $\text{RANGE}(\mathcal{A}) \subseteq \text{span}\{\mathcal{A}(b_1), \dots, \mathcal{A}(b_n)\}$ . This follows since for any  $y \in \text{RANGE}(\mathcal{A})$ ,  $\exists x \in F^n$  such that  $\mathcal{A}(x) = y$ , and  $x$  can be written as  $x = \sum_{i=1}^n \xi_i b_i$ , and thus  $y = \mathcal{A}(x) = \sum_{i=1}^n \xi_i \mathcal{A}(b_i) \in \text{span}\{\mathcal{A}(b_1), \dots, \mathcal{A}(b_n)\}$ . We obtain

$$\dim(\text{RANGE}(\mathcal{A})) \leq \dim(\text{span}\{\mathcal{A}(b_1), \dots, \mathcal{A}(b_n)\}) \leq n.$$

Finally, we have:

$$0 \leq \dim(\text{RANGE}(\mathcal{A})) \leq \min\{m, n\}.$$

2. [15 points in total]

Our proof approach is as follows. We first show that:

$$\dim(\text{NULL}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\text{NULL}(\mathcal{A})) + \dim(\text{NULL}(\mathcal{B})),$$

Then, we use the rank-nullity theorem to obtain the statement given in the problem.

Clearly, we have  $\text{NULL}(\mathcal{A}) \subseteq \text{NULL}(\mathcal{B} \circ \mathcal{A})$ . This follows since if  $x \in F^n$  is such that  $\mathcal{A}(x) = 0$ , then  $\mathcal{B}(\mathcal{A}(x)) = 0$ . Next, consider  $\tilde{\mathcal{A}}$  as a restriction of  $\mathcal{A}$ :

$$\tilde{\mathcal{A}} : \text{NULL}(\mathcal{B} \circ \mathcal{A}) \rightarrow F^m.$$

For the map above, we have  $\text{NULL}(\tilde{\mathcal{A}}) = \text{NULL}(\mathcal{A})$ . Moreover, since  $\text{RANGE}(\tilde{\mathcal{A}})$  is contained in  $\text{NULL}(\mathcal{B})$  by construction, we have  $\dim(\text{RANGE}(\tilde{\mathcal{A}})) \leq \dim(\text{NULL}(\mathcal{B}))$ . The rank-nullity theorem applied to  $\tilde{\mathcal{A}}$  gives

$$\dim(\text{NULL}(\mathcal{B} \circ \mathcal{A})) = \dim(\text{NULL}(\tilde{\mathcal{A}})) + \dim(\text{RANGE}(\tilde{\mathcal{A}})) \leq \dim(\text{NULL}(\mathcal{A})) + \dim(\text{NULL}(\mathcal{B})).$$

Subtracting  $n$  from both sides and multiplying by  $-1$ , we get

$$n - \dim(\text{NULL}(\mathcal{B} \circ \mathcal{A})) \geq n - \dim(\text{NULL}(\mathcal{A})) - \dim(\text{NULL}(\mathcal{B})).$$

Finally, applying the rank-nullity theorem again, we obtain the desired result

$$\dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \geq \dim(\text{RANGE}(\mathcal{A})) + \dim(\text{RANGE}(\mathcal{B})) - m.$$

**Alternative Solution:[15 points in total]**

Consider  $\tilde{\mathcal{B}}$  as a restriction of  $\mathcal{B}$ :

$$\tilde{\mathcal{B}} : \text{RANGE}(\mathcal{A}) \rightarrow F^p.$$

It follows that  $\text{NULL}(\tilde{\mathcal{B}}) \subseteq \text{NULL}(\mathcal{B})$ . Moreover,  $\text{RANGE}(\tilde{\mathcal{B}}) = \text{RANGE}(\mathcal{B} \circ \mathcal{A})$ . Applying the rank-nullity theorem to the map  $\tilde{\mathcal{B}}$  and subsequently to the map  $\mathcal{B}$ , we obtain

$$\begin{aligned} \dim(\text{RANGE}(\mathcal{A})) &= \dim(\text{NULL}(\tilde{\mathcal{B}})) + \dim(\text{RANGE}(\tilde{\mathcal{B}})) \\ &\leq \dim(\text{NULL}(\mathcal{B})) + \dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \\ &= m - \dim(\text{RANGE}(\mathcal{B})) + \dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \end{aligned}$$

We conclude that

$$\dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \geq \dim(\text{RANGE}(\mathcal{A})) + \dim(\text{RANGE}(\mathcal{B})) - m.$$

**3. [15 points in total]**

We have  $\text{RANGE}(\mathcal{B} \circ \mathcal{A}) \subseteq \text{RANGE}(\mathcal{B})$ . This follows since for any  $y \in \text{RANGE}(\mathcal{B} \circ \mathcal{A})$ ,  $\exists x \in F^n$  such that  $\mathcal{B}(\mathcal{A}(x)) = y$ . Letting  $z = \mathcal{A}(x) \in F^m$  implies that  $\mathcal{B}(z) = y$  and  $y \in \text{RANGE}(\mathcal{B})$ . Thus,

$$\dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\text{RANGE}(\mathcal{B})).$$

Next, assume  $x \in \text{NULL}(\mathcal{A})$ , i.e.,  $\mathcal{A}(x) = 0$ . Then, we have  $x \in \text{NULL}(\mathcal{B} \circ \mathcal{A})$ , since  $\mathcal{B}(\mathcal{A}(x)) = 0$ . This implies that  $\text{NULL}(\mathcal{A}) \subseteq \text{NULL}(\mathcal{B} \circ \mathcal{A})$  and

$$\dim(\text{NULL}(\mathcal{A})) \leq \dim(\text{NULL}(\mathcal{B} \circ \mathcal{A})).$$

Subtracting  $n$  and changing sign, we obtain

$$n - \dim(\text{NULL}(\mathcal{A})) \geq n - \dim(\text{NULL}(\mathcal{B} \circ \mathcal{A})).$$

We can use the rank-nullity theorem and conclude

$$\dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\text{RANGE}(\mathcal{A})).$$

Finally, we have that:

$$\dim(\text{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \min\{\dim(\text{RANGE}(\mathcal{A})), \dim(\text{RANGE}(\mathcal{B}))\}.$$

**Solution 3. (Linear maps and matrix representations [20 points in total])**

1. [10 points in total] For  $i = 1, \dots, n$ , the representation of  $\nu_i$  in the basis  $\{\nu_1, \dots, \nu_n\}$  is  $e_i = [0, \dots, 0, 1, 0, \dots, 0]^T$ , where the “1” is in the  $i$ -th position.

Since  $\mathcal{A}(\nu_i) = \lambda\nu_i + \nu_{i+1}$ , the representation  $A$  of  $\mathcal{A}$  must satisfy  $Ae_i = \lambda e_i + e_{i+1} = [0, \dots, 0, \lambda, 1, 0, \dots, 0]^T$ , where the “ $\lambda$ ” and the “1” are in the  $i$ -th and  $(i + 1)$ -th

positions, respectively. Moreover,  $\mathcal{A}(\nu_n) = \lambda\nu_n$  implies that  $Ae_n = \lambda e_n$ . Finally, since  $Ae_i$  is the  $i$ -th column of  $A$ ,

$$A = \begin{bmatrix} \lambda & & & & \\ 1 & \lambda & & & \\ & \ddots & \ddots & & \\ & & 1 & \lambda & \end{bmatrix},$$

where the entries not shown are zeroes [10 points].

2. [10 points in total] For  $i = 1, \dots, n$ , let us define  $b_i = \mathcal{A}^{i-1}(b)$ , so that the basis becomes  $\{b_1, \dots, b_n\}$ . In vector form, the representation of  $b_i$  is given by  $e_i = [0, \dots, 0, 1, 0, \dots, 0]^T$ , where the “1” is in the  $i$ -th position.

For  $i = 1, \dots, n-1$ , it holds that  $\mathcal{A}(b_i) = \mathcal{A}(\mathcal{A}^{i-1}(b)) = \mathcal{A}^i(b) = b_{i+1}$ , hence the representation  $A$  of  $\mathcal{A}$  must satisfy  $Ae_i = e_{i+1}$ . Finally, since  $Ae_i$  is the  $i$ -th column of  $A$ ,

$$A = \begin{bmatrix} 0 & & & \beta_1 \\ 1 & 0 & & \beta_2 \\ & \ddots & \ddots & \vdots \\ & & 1 & 0 \\ & & & 1 & \beta_n \end{bmatrix},$$

where the entries not shown are zeroes and  $\beta = [\beta_1, \dots, \beta_n]^T$  is determined as follows: since  $\beta = Ae_n$  and  $e_n$  is the representation of  $b_n$ ,  $\beta$  is the representation of  $\mathcal{A}(b_n)$  with respect to the basis  $\{b_1, \dots, b_n\}$  [10 points].