Linear System Theory

Problem Set 1 Linear Spaces, Linear Maps, and Representations

Issue date: September 19, 2019 Due date: October 7, 2019

Exercise 1. (Linear spaces [40 points])

1. [18 **points**] Let S be a set, and $F = \{f : S \to \mathbb{R}_+\}$ be the space of functions from S to the (strictly) positive reals. Let the operations $\oplus : F \times F \to F$, $\odot : \mathbb{R} \times F \to F$ be defined as follows:

$$[f_1 \oplus f_2](x) = f_1(x)f_2(x) \qquad \forall f_1, f_2 \in F, \forall x \in S$$
$$[\alpha \odot f](x) = f(x)^{\alpha} \qquad \forall \alpha \in \mathbb{R}, \forall f \in F, \forall x \in S$$

- Show that $(F, \mathbb{R}, \oplus, \odot)$ is a linear space.
- Identify the zero-vector.
- 2. $[12 \mathbf{points}]$ Let $S = \{a, b\}$, and let

$$f_1(a) = 2, \ f_1(b) = 1$$

 $f_2(a) = 1, \ f_2(b) = 3$
 $f_3(a) = 4, \ f_3(b) = 1$

Show that $\{f_1, f_2\}$ are linearly independent and that $\{f_1, f_3\}$ are linearly dependent.

3. [10 **points**] Let $\varphi : F \to F$ be defined as follows:

$$[\varphi(f)](x) = \sqrt{f(x)} \qquad \forall f \in F, \forall x \in S$$

Show that φ is a linear map over the space F on $(F, \mathbb{R}, \oplus, \odot)$.

Solution 1.1

• vector addition

- associative: $\forall f_1, f_2, f_3 \in F, f_1 \oplus (f_2 \oplus f_3) = f_1 \oplus (f_2 f_3) = f_1(f_2 f_3) = f_1 f_2 f_3 = (f_1 f_2) f_3 = (f_1 \oplus f_2) \oplus f_3$

- commutative:

$$\forall f_1, f_2 \in F, f_1 \oplus f_2 = f_1 f_2 = f_2 f_1 = f_2 \oplus f_1$$
- identity:

Define $f_0(x) = 1, \forall x \in S.$ $F = \{f : S \to \mathbb{R}_+\} \Rightarrow f_0 \in F.$ $\forall f \in F, f \oplus f_0 = f \cdot 1 = f.$

- inverse: $\forall f \in F, f(x) \in \mathbb{R}_+, f(x) > 0, \frac{1}{f} > 0, \frac{1}{f} \in F, f \oplus \frac{1}{f} = f(x) \cdot \frac{1}{f(x)} = 1$

• scalar multiplication

- associative: $\forall a,b \in \mathbb{R}, \forall f \in F, a \odot (b \odot f) = a \odot f^b = (f^b)^a = f^{ab} = (a \cdot b) \odot f$ - identity: $\forall f \in F, 1 \odot f = f^1 = f$

• distributive scalar multiplication

$$- \forall a, b \in \mathbb{R}, \forall f \in F, (a+b) \odot f = f^{a+b} = f^a f^b = (f^a)(f^b) = (a \odot f) \oplus (b \odot f) \\
- \forall a \in \mathbb{R}, \forall f_1, f_2 \in F, a \odot (f_1 \oplus f_2) = a \odot (f_1 f_2) = (f_1 f_2)^a = f_1^a f_2^a = (a \odot f_1) \oplus (a \odot f_2)$$

Therefore, $(F, \mathbb{R}, \oplus, \odot)$ is a linear space and the zero-vector is 1.

Solution 1.2

• $\{f_1, f_2\}$

For the sake of contradiction, we assume $\{f_1, f_2\}$ are linearly dependent so that $\exists c_1, c_2 \in \mathbb{R}$ which are not both 0 such that $(c_1 \odot f_1(x)) \oplus (c_2 \odot f_2(x)) = 1$ x = a: $(c_1 \odot 2) \oplus (c_2 \odot 1) = 1 \Rightarrow 2^{c_1} \cdot 1^{c_2} = 2^{c_1} = 1 \Rightarrow c_1 = 0$ x = b: $(0 \odot 1) \oplus (c_2 \odot 3) = 1 \Rightarrow 2^0 \cdot 3^{c_2} = 3^{c_2} = 1 \Rightarrow c_2 = 0$ $c_1 = c_2 = 0$ contradict our assumption $\Rightarrow \{f_1, f_2\}$ must be linearly independent.

• $\{f_1, f_3\}$

 $\{f_1, f_3\}$ are linearly dependent, if we can find $c_1, c_2 \in \mathbb{R}$ that are not both 0 such that $(c_1 \odot f_1(x)) \oplus (c_2 \odot f_3(x)) = 1$

$$x = a: (c_1 \odot 2) \oplus (c_2 \odot 4) = 1 \Rightarrow 2^{c_1} \cdot 4^{c_2} = 2^{c_1 + 2c_2} = 1$$

$$x = b: (c_1 \odot 1) \oplus (c_2 \odot 1) = 1 \Rightarrow 1^{c_1} \cdot 1^{c_2} = 1^{c_1 + c_2} = 1$$

 $1^{c_1+c_2}=1$ implies c_1,c_2 can be any real number. We can choose $c_1=2,c_2=-1$ to satisfy the two conditions above. Therefore, $\{f_1,f_3\}$ are linearly dependent.

Solution 1.3

 $\forall a_1, a_2 \in \mathbb{R}, \forall f_1, f_2 \in F,$

$$\varphi((a_1 \odot f_1) \oplus (a_2 \odot f_2)) = \varphi(f_1^{a_1} f_2^{a_2}) = \sqrt{f_1^{a_1} f_2^{a_2}} = \sqrt{f_1^{a_1}} \sqrt{f_2^{a_2}}$$

$$= \sqrt{f_1^{a_1}} \sqrt{f_2^{a_2}} = \left(a_1 \odot \sqrt{f_1}\right) \left(a_2 \odot \sqrt{f_2}\right)$$

$$= (a_1 \odot \varphi(f_1)) (a_2 \odot \varphi f_2) = (a_1 \odot \varphi(f_1)) \oplus (a_2 \odot \varphi(f_2))$$

Therefore, φ is a linear map over the space F on $(F, \mathbb{R}, \oplus, \odot)$.

Exercise 2. (Range and null space [40 points])

Let $(F, +, \cdot)$ be a field and consider the linear maps $\mathcal{A}: (F^n, F) \to (F^m, F)$ and $\mathcal{B}: (F^m, F) \to (F^p, F)$. Show, without using the matrix representation of linear maps, that:

- 1. $[10 \text{ points}] 0 \le dim(\text{Range}(A)) \le \min\{m, n\}.$
- 2. [15 points] $dim(RANGE(\mathcal{A})) + dim(RANGE(\mathcal{B})) m \le dim(RANGE(\mathcal{B} \circ \mathcal{A}))$
- 3. $[15 \, \mathbf{points}] \, dim(\mathrm{Range}(\mathcal{B} \circ \mathcal{A})) \leq \min\{dim(\mathrm{Range}(\mathcal{A})), dim(\mathrm{Range}(\mathcal{B}))\}.$

Solution 2.1

The first inequality is trivial since the number of vectors of a basis should definitely non-negative, i.e., $0 \le dim(RANGE(A))$. For the second inequality, we first prove a lemma.

Lemma 1 If (V, F) has dimension n then any set of n + 1 or more vectors is linearly dependent.

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Proof 1 For the sake of contradiction, we assume that there exists a set of n + k \, (k > 0, k \in \mathbb{N}) linearly independent vectors \{v_1, \ldots, v_{n+k}\}, then \dim(\operatorname{span}(\{v_1, \ldots, v_{n+k}\})) = n + k. Since \{v_1, \ldots, v_{n+k}\} \subseteq (V, F), \operatorname{span}(\{v_1, \ldots, v_{n+k}\}) \subseteq (V, F), n + k = \dim(\operatorname{span}(\{v_1, \ldots, v_{n+k}\})) \leq \dim((V, F)) = n, which leads to contradiction.
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Next, we prove $dim(RANGE(\mathcal{A})) \leq m$. For the sake of contradiction, assume $dim(RANGE(\mathcal{A})) = p > m$, and a basis of $RANGE(\mathcal{A})$ is $\{v_1, \ldots, v_p\}$, which are linearly independent.

The fact that linearly independent vectors $\{v_1, \ldots, v_p\} \subseteq \text{RANGE}(\mathcal{A}) \subseteq (V, F)$ and the dimension of (V, F) is m < p contradict the lemma. Therefore $\text{RANGE}(\mathcal{A}) \leq m$.

Finally, we prove $dim(RANGE(\mathcal{A})) \leq n$. $\forall v \in V, \exists u \in U, \mathcal{A}(u) = v$. Let $\{e_1, \dots, e_n\}$ be a basis of U. $\forall u \in U, \exists a_1, \dots, a_n, u = a_1e_1 + \dots + a_ne_n$, where a_i are not all 0.

Therefore, $\forall v \in V, v = \mathcal{A}(u) = \mathcal{A}(a_1e_1 + \dots + a_ne_n) = a_1\mathcal{A}(e_1) + \dots + a_n\mathcal{A}(e_n)$. If $\{\mathcal{A}(e_1), \dots, \mathcal{A}(e_n)\}$ are linearly independent, then $\dim(\text{RANGE}(\mathcal{A})) = n$, otherwise $\dim(\text{RANGE}(\mathcal{A})) < n$.

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\begin{cases} dim(\text{Range}(\mathcal{A})) \leq n \\ dim(\text{Range}(\mathcal{A})) \leq m \end{cases} \Rightarrow dim(\text{Range}(\mathcal{A})) \leq \min\{m,n\}, \text{ which completes the proof.}
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Solution 2.2

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\begin{aligned} \operatorname{RANGE}(\mathcal{A}) \cap \operatorname{Null}(\mathcal{B}) &\subseteq \operatorname{Null}(\mathcal{B}) \\ \Leftrightarrow \dim\left(\operatorname{RANGE}(\mathcal{A}) \cap \operatorname{Null}(\mathcal{B})\right) &\leq \dim(\operatorname{Null}(\mathcal{B})) \\ \Leftrightarrow \dim\left(\operatorname{RANGE}(\mathcal{A}) \cap \operatorname{Null}(\mathcal{B})\right) &\leq \dim(\operatorname{Null}(\mathcal{B})) + \dim(\operatorname{Null}(\mathcal{A})) \\ \Leftrightarrow \dim\left(\operatorname{Null}(\mathcal{B} \circ \mathcal{A})\right) &\leq \dim(\operatorname{Null}(\mathcal{B})) + \dim(\operatorname{Null}(\mathcal{A})) \\ \Leftrightarrow n - \dim\left(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})\right) &\leq m - \dim(\operatorname{RANGE}(\mathcal{B})) + n - \dim(\operatorname{RANGE}(\mathcal{A})) \\ \Leftrightarrow \dim(\operatorname{RANGE}(\mathcal{A})) + \dim(\operatorname{RANGE}(\mathcal{B})) - m &\leq \dim\left(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})\right) \end{aligned}
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Solution 2.3

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\begin{aligned} &\operatorname{RANGE}(\mathcal{A}) \in F^m \Rightarrow \operatorname{RANGE}(\mathcal{B} \circ \mathcal{A}) \subseteq \operatorname{RANGE}(\mathcal{B}) \Rightarrow \dim(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\operatorname{RANGE}(\mathcal{B})) \\ &\operatorname{Let} \left\{ v_1, \dots, v_r \right\} \text{ be a set of basis of } \operatorname{RANGE}(\mathcal{A}). \\ &\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A}) = \left\{ l \in F^p | \exists w \in \operatorname{RANGE}(\mathcal{A}), \mathcal{B}(w) = l \right\}. \\ &\operatorname{Since } \operatorname{RANGE}(\mathcal{A}) = \operatorname{span}(\left\{ v_1, \dots, v_r \right\}), \ \forall w \in \operatorname{RANGE}(\mathcal{A}), \exists c_1, \dots, c_r \in F, w = c_1 v_1 + \dots + c_r v_r. \\ &\operatorname{Due to the linear map } \mathcal{B}, \mathcal{B}(w) = c_1 \mathcal{B}(v_1) + \dots + c_r \mathcal{B}(v_r). \\ &\forall l \in F^p, \exists w \in \operatorname{RANGE}(\mathcal{A}), \exists c_1, \dots, c_r, l = \mathcal{B}(w) = \mathcal{B}(c_1 v_1 + \dots + c_r v_r) = c_1 \mathcal{B}(v_1) + \dots + c_r \mathcal{B}(v_r). \\ &\operatorname{If} \left\{ \mathcal{B}(v_1), \dots, \mathcal{B}(v_r) \right\} \text{ are linearly independent, } \dim(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})) = r = \dim(\operatorname{RANGE}(\mathcal{A})), \\ &\operatorname{otherwise } \dim(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\operatorname{RANGE}(\mathcal{A})) \\ &\operatorname{dim}(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\operatorname{RANGE}(\mathcal{A})) \\ &\operatorname{dim}(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \dim(\operatorname{RANGE}(\mathcal{B})) \end{aligned} \Rightarrow \dim(\operatorname{RANGE}(\mathcal{B} \circ \mathcal{A})) \leq \min\left\{ \dim(\operatorname{RANGE}(\mathcal{A})), \dim(\operatorname{RANGE}(\mathcal{B})) \right\}
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Exercise 3. (Linear maps and matrix representations [20 points])

Consider a linear map $\mathcal{A}:(U,F)\to(U,F)$ where U has finite dimension n.

- 1. [10 **points**] Assume there exists a basis ν_i , i = 1, ..., n for U such that $\mathcal{A}(\nu_n) = \lambda \nu_n$ and $\mathcal{A}(\nu_i) = \lambda \nu_i + \nu_{i+1}$, i = 1, ..., n-1. Derive the representation of \mathcal{A} with respect to this basis.
- 2. [10 **points**] Assume there exists a vector $b \in U$ such that the set $\{b, \mathcal{A}(b), \mathcal{A} \circ \mathcal{A}(b), \dots, \mathcal{A}^{n-1}(b)\}$ is linearly independent. Derive the representation of \mathcal{A} with respect to this basis.

Solution 3.1

$$\mathcal{A}(\nu_1) = \lambda \nu_1 + \nu_2$$

$$\mathcal{A}(\nu_2) = \lambda \nu_2 + \nu_3$$

$$\vdots$$

$$\mathcal{A}(\nu_{n-1}) = \lambda \nu_{n-1} + \nu_n$$

$$\mathcal{A}(\nu_n) = \lambda \nu_n$$

$$a_{ij} = \begin{cases} \lambda & i = j \\ 1 & i = j+1 \\ 0 & otherwise \end{cases} \Rightarrow A = \begin{bmatrix} \lambda & & & \\ 1 & \lambda & & & \\ & 1 & \ddots & & \\ & & \ddots & \lambda & \\ & & & 1 & \lambda \end{bmatrix}$$

Solution 3.2

 $\mathcal{A}: (U,F) \to (U,F) \Rightarrow \mathcal{A}^n(b) \in U.$

Since the set $\{b, \mathcal{A}(b), \mathcal{A} \circ \mathcal{A}(b), \dots, \mathcal{A}^{n-1}(b)\}$ is linearly independent and dim(U) = n, $\exists c_1, \dots, c_n \in F$, which are not all zero, such that $\mathcal{A}^n(b) = c_1b + \dots + c_n\mathcal{A}^{n-1}(b)$.

$$a_{ij} = \begin{cases} 1 & i = j+1 \\ c_j & j = n \\ 0 & otherwise \end{cases} \Rightarrow A = \begin{bmatrix} 1 & & c_1 \\ & 1 & & \vdots \\ & & \ddots & \vdots \\ & & 1 & c_n \end{bmatrix}$$