

Matrix Properties

Yashas.N

yn37git.github.io/blog/2025/Short-Notes

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Symbols used:

iff	→	if and only if
Capital letters	→	Matrices $\mathbf{A}_{m \times n} = [a_{ij}]_{m \times n}$
\mathbf{A}^T or \mathbf{A}'	→	Transpose of Matrix
$\bar{\mathbf{A}}$	→	Conjugate of Matrix
\mathbf{AB}	→	Matrix product
$ \mathbf{A} $ or $\det(\mathbf{A})$	→	Determinant of Matrix
$\text{tr}(\mathbf{A})$ or $\text{trace}(\mathbf{A})$	→	trace of Matrix
\mathbf{A}^*	→	Conjugate transpose of Matrix
\mathbf{A}^{-1}	→	Inverse of Matrix
\mathbf{I}	→	Identity
$\text{Im}(\mathbf{A})$	→	Image or range space of \mathbf{A}
$\text{rank}(\mathbf{A})$ or $r(\mathbf{A})$	→	Dimension of Range space of \mathbf{A}
$\ker(\mathbf{A})$	→	Null space of \mathbf{A}
$\text{null}(\mathbf{A})$	→	Dimension of Null space of \mathbf{A}
\mathbb{F}	→	Field

1 Basic properties

- 1 • $\mathbf{A}(\mathbf{BC}) = (\mathbf{AB})\mathbf{C}$
- 4 • $\text{tr}(\mathbf{AB}) = \text{tr}(\mathbf{BA})$
- 4 • $(\mathbf{AB})' = \mathbf{B}'\mathbf{A}'$
- 4 • $(\mathbf{AB})^* = \mathbf{B}^*\mathbf{A}^*$
- 5 • if \mathbf{A} is Hermitian then $i\mathbf{A}$ is skew-Hermitian and vise-versa.
- 6 • if \mathbf{A}, \mathbf{B} are symmetric, \mathbf{AB} is symmetric iff $\mathbf{AB} = \mathbf{BA}$.
- 7 • $\mathbf{AA}', \mathbf{A}'\mathbf{A}$ are always symmetric.
- 8 • For any Square Matrix \mathbf{A} :
 - $\mathbf{A} + \mathbf{A}'$ is symmetric.
 - $\mathbf{A} - \mathbf{A}'$ is skew- symmetric.
 - $\mathbf{A} + \mathbf{A}^*$ is Hermitian.
 - $\mathbf{A} - \mathbf{A}^*$ is skew-Hermitian .
- 8 • By preceding point any Square matrix can be decomposed (by +) into symmetric - skew-symmetric or Hermitian- skew-Hermitian pair.
- $\mathbf{B}'\mathbf{AB}$ is symmetric or skew as is \mathbf{A}
- $\mathbf{B}^*\mathbf{AB}$ is hermitian or skew as is \mathbf{A}
- Determinant is a Multilinear (row), Alternating and Normalized Function on Matrices.
- Determinant of upper or lower triangle or diagonal matrix is equal to product of diagonal elements.
- $|\mathbf{AB}| = |\mathbf{A}||\mathbf{B}| = |\mathbf{BA}|$
- $|\mathbf{A}'| = |\mathbf{A}|$
- $|\mathbf{A}^*| = |\bar{\mathbf{A}}|$
- \mathbf{A} is invertible iff $|\mathbf{A}| \neq 0$.

- $A^{-1} = \frac{\text{adj}(A)}{|A|}$ where $\text{adj}(A)$ is the transpose of co-factor matrix.
- $B^{-1} - A^{-1} = B^{-1}(A - B)A^{-1}$
- Cramer's rule for a system of linear equations $Ax = b$ where A is square and for $x = [x_1, x_2, \dots, x_n]^T$ we have $x_i = \frac{|A \leftarrow_i b|}{|A|}$ where $A \leftarrow_i b$ is obtained by replacing i^{th} column of A by b .
- $|\text{adj}(A)| = |A|^{n-1}$ where A is an $n \times n$ matrix
- $\text{adj}(A^*) = \text{Adj}(A)^*$
- $\text{adj}(A^{-1}) = \text{adj}(A)^{-1} = A/|A|$
- $\text{adj}(\text{adj}(A)) = |A|^{n-2}A$
- $\text{adj}(AB) = \text{adj}(B)\text{adj}(A)$ for non-singular matrices A, B .
- A is orthogonal if $A'A = I$
- A is orthogonal $\implies |A| = \pm 1 \implies$ invertible.
- A is unitary if $A^*A = I$
- if A, B are orthogonal then so are AB, BA . Similar result follows in unitary case also.
- $\text{rank}(A) = r$ iff all the $r+1$ order minors are zero i.e. if any one of r^{th} order minor is non zero then $\text{rank}(A) \geq r$.
- $\text{rank}(A) = \text{rank}(A') = \text{rank}(A^*)$
- Elementary transformation: exchange of rows, multiplication of row by non zero constant, addition of k multiple of a row to another row.
- Elementary transformations doesn't change the rank of a matrix.
- Every elementary transformation has a corresponding non singular matrix which when pre-multiplied to a given matrix gives the respective operation.
- Normal form of a matrix : (Echelon form) A matrix which can be partitioned into identity and null matrices where the identity is present in upper-left part.
- $\exists P, Q$ non-singular square matrices such that $N = PAQ$ where A is any matrix and N is its

normal or Echelon form.

- $\text{rank}(AB) \leq \min(\{\text{rank}(A), \text{rank}(B)\})$.

- $\text{rank}(A + B) \leq \text{rank}(A) + \text{rank}(B)$.

- **Sylvester inequality :**

for any matrices $A_{m \times k}, B_{k \times n}$

$$\begin{aligned} \text{rank}(AB) &= \text{rank}(B) - \dim(\text{Im}(B) \cap \ker(A)) \\ \text{so } \text{rank}(A) + \text{Rank}(B) - k &\leq \text{rank}(AB) \\ &\leq \min(\{\text{rank}(A), \text{Rank}(B)\}). \end{aligned}$$

(use: for $Bx \neq 0$, $ABx = A(Bx) = 0$ iff $x \in \text{Im}(B) \cap \ker(A)$ and that $\dim(\text{Im}(B) \cap \ker(A)) \leq \text{null}(A) = k - r(A)$ so $-\dim(\text{Im}(B) \cap \ker(A)) \geq r(A) - k$.)

- **Frobenius Inequality :**

for $A_{m \times k}, B_{k \times p}, C_{p \times n}$

$$\text{rank}(AB) + \text{rank}(BC) \leq \text{rank}(B) + \text{rank}(ABC).$$

- $\text{rank}(A) = \text{rank}(A^*A)$

- if all entries of A are real then $\text{rank}(A'A) = \text{rank}(A)$.

- if A is n -squared then :

- $\text{rank}(A) = n \implies \text{rank}(\text{adj}(A)) = n$.

- $\text{rank}(A) = n - 1 \implies \text{rank}(\text{adj}(A)) = 1$.

- $\text{rank}(A) < n - 1 \implies \text{rank}(\text{adj}(A)) = 0$

i.e. $\text{adj}(A) \equiv 0$. (use minors and cofactor definition of $\text{Adj}(A)$.)

- $\text{rank}(A) \geq \text{rank}(A^2) \geq \dots \geq \text{rank}(A^n) \geq \dots$

- $\text{null}(A) \leq \text{null}(A^2) \leq \dots \leq \text{null}(A^n) \leq \dots$

- if $\text{rank}(A^m) = \text{rank}(A^{m+1})$ then

- $\text{rank}(A^k) = \text{rank}(A^m) \quad \forall k \geq m$

- $\text{null}(A^k) = \text{null}(A^m) \quad \forall k \geq m$

- Eigenvalues of Hermitian matrices are real.

(if λ is eigenvalue then $(Ax)^* = x^*A^* = x^*A = (\lambda x)^* = \bar{\lambda}x^*$ so $x^*A^*x = \lambda x^*x = \bar{\lambda}x^*x \implies \bar{\lambda} = \lambda$)

- Eigenvalues of Skew-Hermitian are purely imaginary or zero.

- If λ is Eigenvalue of Unitary matrix A then $|\lambda| = 1$

(if $Ux = \lambda x$ then $x^*U^*Ux = x^*Ix = x^*x$ but $(x^*U^*)(Ux) = \bar{\lambda}\lambda x^*x$.)

- Real Eigenvalues of Orthogonal Matrices are $1, -1$ only.

- Eigenvalues of A and A' are same.

- Eigenvalues of triangular, diagonal matrices are its diagonal elements.

- if λ is an eigenvalue of non-singular matrix A then

- $\lambda \neq 0$
- $\frac{1}{\lambda}$ is the eigenvalue of A^{-1} .
- λ^k is the eigenvalue of A^k .
- $\frac{|A|}{\lambda}$ is the eigenvalue of $\text{adj}(A)$.

- if $\{\lambda_i\}$ are eigenvalues of A then eigenvalues of $B = p(A)$ are of form $p(\lambda_i)$ only.

- For A_n with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ $\text{trace}(A) = \sum_{i=1}^n \lambda_i$, $\det(A) = \prod_{i=1}^n \lambda_i$ and $\text{trace}(\text{adj}(A)) = \sum_{i=1}^n \prod_{j \neq i} \lambda_j$.

- If $A = P^{-1}BP$ then A and B have same eigenvalues

- for square Matrices A, B eigenvalues of AB and BA are same.

(use if $ABx = \lambda x$ then $BA(Bx) = B(ABx) = \lambda Bx$ so λ is eigenvalue of BA also and vis-a-viz.)

- Geometric multiplicity (no of eigenvectors for an eigenvalue) \leq Algebraic multiplicity (order of eigenvalue in characteristic polynomial).

- $A = P^{-1}BP$ this Relation ARB (similarity) is equivalence, determinant invariant, eigenvalue invariant, trace invariant.

- A matrix is diagonalizable if it is similar to a diagonal matrix

- A matrix is diagonalizable iff for each of its eigenvalue Geometric multiplicity = Algebraic multiplicity.

- square matrix A is diagonalizable iff minimal polynomial of A splits into distinct linear factors in the given field i.e. minimal polynomial of A is separable and has only linear irreducible factors.

- A non-zero Nil-potent ($A^m = 0$) matrix has eigenvalues as zero only.

- A non-zero Nil-potent matrix is never Diagonalizable.

(if A is diagonalizable then $P^{-1}AP = D$ so $(P^{-1}AP)^m = P^{-1}A^mP = 0 = D^m \implies D \equiv 0$ thus $A \equiv 0$)

- **Schurs theorems:**

- Every Square matrix A is Unitarily similar to Upper triangular matrix whose diagonals are

eigenvalues of A (complex values included).

- If $A \in M_n(\mathbb{R})$ and has only real eigenvalues then it is real orthogonally similar to real upper triangular matrix.

(say $\lambda_1, \lambda_2, \dots, \lambda_n$ are eigenvalues of $A_{n \times n}$ (with repeats) let x be normalised eigenvector of A to eigenvalue λ_1 then $x^*x = 1$ and $Ax = \lambda_1 x$, now from an orthonormal basis with x and let this matrix be $U_1 = [x \ u_2 \dots u_n]$ thus we have $U_1^*AU_1 = [\lambda_1, *; 0, A_1]$ for $A_{1 \times 1 \times n-1}$ and as U_1 is unitary we have eigenvalues of A_1 are $\lambda_2, \dots, \lambda_n$ only so lets commence the same procedure for $A_{1 \times 1 \times n-1}$ we get U_2 join this to form $V_2 = [1, 0; 0, U_2]$ then we get $(U_1V_2)^*AU_1V_2 = [\lambda_1, *, *; 0, \lambda_2, *; 0, 0, A_2]$ clearly U_1V_2 was unitary so proceeding similarly we get the theorem)

- If $A \in M_n(\mathbb{R})$ has complex eigenvalues then it is similar to a matrix with diagonal blocks of 1-by-1 and 2-by-2 only (has upper triangular entries). Where 1-by-1 blocks are real eigenvalue of A and 2-by-2 blocks are $\begin{bmatrix} a & b \\ -b & a \end{bmatrix}$ for $a + ib$ eigenvalue.

(for $A_{n \times n}$ let $\lambda = a + ib$ and its eigenvector is $x = u + iv$ then prove $\bar{\lambda}, \bar{x}$ are eigenpairs so x, \bar{x} are linearly independent so are u, v and as $Au = au - bv, Av = bu + av$ and if $S = [u, v, S_1]_{n \times n}$ be made non singular thus $S^{-1}AS = [B, *; 0, A_1]$ for $B = \begin{bmatrix} a & b \\ -b & a \end{bmatrix}$.)

- Every Symmetric matrix ($A \in M_n(\mathbb{R})$) is orthogonally similar to diagonal matrix (D) i.e. $D = P^TAP$, $P^TP = I$.

- Every Hermitian matrix (A) is unitarily similar to diagonal matrix (D) i.e. $D = P^*AP$, $P^*P = I$.

- A matrix A is normal iff $A^*A = AA^*$

- A matrix is Unitarily similar to diagonal matrix iff it is Normal.

- A triangular normal matrix is Diagonal also a block diagonal normal matrix has off diagonal blocks = 0.

- if A is normal then $p(A)$ (specially $A + aI$, $a \in \mathbb{C}$) is normal. In other words if A is diagonalisable then so is $P(A)$ (note: even zero matrix is considered as a diagonal matrix).

2 Quadratic Form

- $Q : \mathbb{F}^n \times \mathbb{F}^n \rightarrow \mathbb{F}$ given by $\sum_{i=0}^n \sum_{j=0}^n a_{ij} x_i x_j$

where $a_{ij} \in \mathbb{F}$ a field.

- It can be represented as $X'AX$ for $X = [x_1, x_2, \dots, x_n]^T$ and **Symmetric** matrix $A = [A]_{ij} = \frac{1}{2}(a_{ij} + a_{ji})$

- Congruence relation (**ARB**) : if $A = P^T B P$ for some non-singular P, A, B square.

- Matrices congruent to Symmetric matrices are Symmetric.

- Quadratic forms are equivalent if the corresponding matrices are congruent.

- Congruent matrices or equivalent Forms have same Range.

- Every Symmetric matrix is congruent to a diagonal matrix. (same as orthogonally diagonalizable)

- Every n -rowed real Symmetric matrix with rank r is congruent to a Diagonal matrix with diagonal $[1, \dots, 1, -1, \dots, -1, 0, \dots, 0]$ with 1 appearing p times -1 appearing $r - p$ times and 0 $n - r$ times.

- Canonical Form of real Quadratic Form: for Q has matrix A and if $P'AP = \text{diag}[1, \dots, 1, -1, \dots, -1, 0, \dots, 0]$ then $X = PY$ which transforms Q to $y_1^2 + \dots + y_p^2 - y_{p+1}^2 - \dots - y_r^2$ for Real non singular matrix P .

- Number of positive terms in canonical form is **Index**, difference of positive and negative terms is **Signature**.

- Index and Signature are congruence invariant.

- Two real Quadratic forms (symmetric matrices) are orthogonally equivalent iff their matrices have same eigenvalues and multiplicities.

- A Quadratic Form Q is:

- positive definite if $Q(X) \geq 0$ and $Q(X) = 0 \iff X = 0$
- negative definite if $Q(X) \leq 0$ and $Q(X) = 0 \iff X = 0$
- positive semi-definite if $Q(X) \geq 0$

- negative semi-definite if $Q(X) \leq 0$
- or is indefinite

- if for a n dimensional Quadratic form Rank= r and Signature= s then it is :

- positive definite iff $s = r = n$.
- negative definite iff $-s = r = n$.
- positive semi-definite iff $s = r < n$.
- negative semi-definite iff $-s = r < n$.
- indefinite iff $|s| \neq r$

- Now as real Symmetric matrices are diagonalizable and have a canonical form we have:

- Index = number of positive eigenvalues.
- Rank = number of non zero eigenvalues.
- Signature = no of +ve - no of -ve eigenvalues.

- from above we have for a real Quadratic form Q with matrix A then Q is:

- positive definite iff all eigenvalues are positive or > 0 .

- negative definite iff all eigenvalues are negative or < 0 .

- positive semi-definite iff at-least one eigenvalues is 0 and others > 0 .

- negative semi-definite iff at-least one eigenvalues is 0 and others < 0 .

- indefinite iff eigenvalues are -ve as well as +ve.

- every real non-singular matrix $A = PS$ for P orthogonal S positive definite

$(S = Q'D_1Q, D_1 = \sqrt{\text{diagonalization}(A'A)}, P = AS')$

- Q with matrix A is positive definite iff all leading principal minors of A are positive.

- A matrix A is positive definite $\implies |A| > 0$

- A complex Quadratic form is hermitian if its corresponding matrix is hermitian.

- A Hermitian Form assumes only real values.

- if $\text{norm}(A) = \sum_{i,j} |[A]_{ij}|^2$ then $\text{norm}(A) = \text{trace}(A^*A)$.

3 Jordan Form

- **Canonical Form** : Given a equivalence relation on set of matrices, the main problem is to

find whether A and B belong to same equivalence class. One classical way of doing this is choosing a set of representative matrices such that each matrix belong to only one class and distinct members are of different classes. Such a set of representatives is the Canonical Form of such relation.

- Jordan form is the canonical form for relation of Similarity.
- A matrix in Jordan form Consist of Jordan blocks $J_k(\lambda)$ which is a upper triangular matrix of size k -by- k with diagonal entries λ and super diagonal 1 and others 0 i.e.

$$J_k(\lambda) = \begin{bmatrix} \lambda & 1 & & & \\ & \lambda & 1 & & \\ & & \ddots & \ddots & \\ & & & \lambda & 1 \\ & & & & \lambda \end{bmatrix}_{k \times k}$$

- $J_k(0)^{k+n} = 0$ for $n \geq 0$ i.e. $J_k(0)$ is nilpotent matrix such that $J_k(0)^k = 0$.
- $\text{rank}(J_k(0)^l) = \max(k-l, 0)$
- Convention: $\text{rank}(J_k(0)^0) = k$
- if $r_k(A, \lambda) = \text{rank}(A - \lambda I)^k$ and $w_k(A, \lambda) = r_{k-1}(A, \lambda) - r_k(A, \lambda)$ then in Jordan Form of A :
 - $w_k(A, \lambda)$ = number of blocks with eigenvalue λ that has size at least k (use the fact for every Jordan block of λ , $A - \lambda I$ is Similar to Jordan form consisting of $J_k(0)$ Jordan block instead of λ so as we measure ranks each power decreases the rank of the block by one if the block size is greater than the power.)
 - so $w_1(A, \lambda) = n - r_1(A, \lambda)$ = number of Jordan Blocks with eigenvalue λ = Geometric multiplicity of λ as eigenvalue of A
 - $w_k(A, \lambda) - w_{k+1}(A, \lambda)$ = number of blocks of Size k
 - q : index of λ in A = smallest integer such that $\text{rank}(A - \lambda I)^{q+1} = \text{rank}(A - \lambda I)^q = r_{q+1}(A, \lambda) = r_q(A, \lambda)$
 - $w_1(A, \lambda) + w_2(A, \lambda) + \dots + w_q(A, \lambda)$ = Sum of dimensions all Jordan blocks in λ = Algebraic Multiplicity of λ as eigenvalue of A
 - Weyr characteristic of $A \in M_n$ associated

with $\lambda \in \mathbb{C}$ is

$$w(A, \lambda) = (w_1(A, \lambda), w_2(A, \lambda), \dots, w_q(A, \lambda))$$

- Segre characteristic of $A \in M_n$ associated with $\lambda \in \mathbb{C}$ is

$$s(A, \lambda) = s_1(A, \lambda) \geq s_2(A, \lambda) \geq \dots \geq s_{w_1(A, \lambda)} > 0$$

where s is sizes of Jordan Blocks in λ as they occur in Jordan form (non-increasing order)

- for a given A, λ eigenvalue, If we arrange $w(A, \lambda)$ in dot form as rows (partitions: Ferrers diagram) then its columns are $s(A, \lambda)$ and Vice-versa.

- for A_n upper diagonal with $[A]_{ii} = 1$, $[A]_{i,i+1} \neq 0$ then A is similar to $J_n(1)$

- if $\lambda = 1$ is the only eigenvalue of A then A is similar to A^k

- in J Jordan form of A :

- Total No of Jordan blocks = Total no of independent eigenvectors.

- No of Jordan blocks in λ = Dimension of eigenspace of λ

- Sum of sizes of Jordan blocks in λ = Algebraic Multiplicity.

- If A_n is non singular then A is similar to A^T . (use : for Jordan block $J_n = J_n(\lambda)$ and $B_n = B_n \times n$ reversal matrix (upside down identity) we have $J_n = B_n J_n' B_n$ as $B_n^{-1} = B_n$ we have $J_n R J_n'$)

- If minimal polynomial of $A = \prod_{i=1}^k (t - \lambda_i)^{r_i}$ then largest Jordan block of λ_i in JCF of A is of size r_i .

4 Rational Form

- Jordan form of A_n is possible iff The characteristics polynomial of A splits completely to linear factors over \mathbb{F} (i.e. $(x - a_i)^{n_i}$, $a_i \in \mathbb{F}$), which may not be possible if there are irreducible polynomials of degree more than 1 in $\mathbb{F}[x]$, so to make canonical form under consideration of these Matrices we arrive at Rational form which uses the concept of Invariant subspaces, Cyclic subspaces and Primary Decomposition theorem.

- For given monic polynomial (characteristic/minimal) $p(x) = x^n + a_{n-1}x^{n-1} + \dots +$

$a_1x + a_0$ a_i 's $\in \mathbb{F}$ of linear transform $T : V \rightarrow V$ if there exist x such that $T_x = \{x, T(x), T^2(x), \dots, T^{n-1}(x)\}$ is a linear independent set then The matrix of T with respect to T -cyclic basis T_x is Companion matrix which has same characteristic and minimal polynomial = $p(x)$ and is given by

$$C_A = \begin{bmatrix} 0 & \dots & \dots & 0 & -a_0 \\ 1 & 0 & \dots & 0 & -a_1 \\ 0 & 1 & \dots & 0 & -a_2 \\ \vdots & \ddots & \ddots & \vdots & \vdots \\ 0 & \dots & 0 & 1 & -a_{n-1} \end{bmatrix}$$

• If $p(x) = (p_1(x))^{n_1}(p_2(x))^{n_2}\dots(p_k(x))^{n_k}$ and $m(x) = (p_1(x))^{m_1}(p_2(x))^{m_2}\dots(p_k(x))^{m_k}$ are characteristics and minimal polynomial of linear transform $T : V \rightarrow V$ where p_i 's are irreducible in \mathbb{F} of degree d_i respectively then :

■ $K_{p_i} = \{x : (p_i(T))^k(x) = 0\}$ is T invariant Subspace of V

■ $K_{p_i} = \ker((p_i(T))^{m_i})$ (Null space) , $K_{p_i} \cap K_{p_j} = \{0\}$ for $i \neq j$

■ Every K_{p_i} has a union T -cyclic basis as a basis.

• From above and Primary decomposition theorem we have: for a linear transformation $T : V \rightarrow V$ with matrix A has a basis in which A is similar to

$$\begin{bmatrix} C_1 & \dots & 0 \\ 0 & C_2 & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \dots & \dots & C_k \end{bmatrix}$$

where C_i 's are companion matrices related to minimal polynomial's irreducible terms.

• Dimension of $K_{p_i} = d_i n_i$ (d_i = degree of p_i , n_i = power of p_i in characteristic polynomial)

• $\dim(K_{p_i})$ = dimension of total blocks associated with p_i

• number of blocks associated with $p_i = r_i = \frac{1}{d_i}[\dim(V) - \text{rank}(p_i(A))]$

• number of blocks of size atleast i — by — $i = r_i = \frac{1}{d_i}[\text{rank}(p_i(A)^{i-1}) - \text{rank}(p_i(A)^i)]$

5 Mics Properties

• A has a block B_n in its block form iff it has an n dimensional invariant space associated.

• Λ_n is a block matrix in which $[\Lambda]_{i,j} = 0$ if $i \neq j$, $\Lambda_{ii} = \lambda_i I_{n_i}$ blocks and commutes with B iff B is a block Diagonal conformal with Λ i.e. iff

$$\Lambda = \begin{bmatrix} \lambda_1 I_{n_1} & & & 0 \\ & \lambda_2 I_{n_2} & & \\ & & \ddots & \\ 0 & & & \lambda_d I_{n_d} \end{bmatrix},$$

$$B = \begin{bmatrix} B_{n_1} & & 0 \\ & B_{n_2} & \\ & & \ddots \\ 0 & & & B_{n_d} \end{bmatrix}$$

• Extremum of $X^T A X$ for constraint $X^T X = 1$ occurs in eigenvalues of A .

• From above Extremum of real Quadratic Form $X^T A X$ with constraints $X^T X = 1$ is the largest eigenvalue of A vise-versa $\text{Max}\{X^T A X | A \text{ is symmetric, } X^T X = 1\}$ = largest eigenvalue of A .

• μ is a eigenvalue of $p(A)$ iff $\mu = p(\lambda)$ for an eigenvalue λ of A (where $p(\cdot)$ is a polynomial over \mathbb{F}).

• if λ is an eigenvalue of A then corresponding eigenvector are non-zero columns of $\text{adj}(A - \lambda I)$ (use full only if $\text{rank}(A - \lambda I) = n - 1$).

• Coefficients of Characteristic polynomial of A of degree n : $n \rightarrow 1, n-1 \rightarrow -\text{trace}(A), \text{constant} \rightarrow (-1)^n \det(A)$.

• A, B are simultaneously Diagonalizable iff A, B commute i.e. if $D_1 = S^{-1} A S, D_2 = S^{-1} B S$ for same $S \iff AB = BA$. This even holds for a family of Diagonalizable matrices.

• for $A_{m \times n}$

$$\begin{bmatrix} I_m & A \\ 0 & I_n \end{bmatrix}^{-1} = \begin{bmatrix} I_m & -A \\ 0 & I_n \end{bmatrix}$$

• For $A_{m \times n} B_{n \times m}$ Eigenvalues of $AB =$ Eigenvalues of BA (including zero).

• Cauchy's Determinant Identity : $\det(A +$

$$\mathbf{xy}^T = \det(\mathbf{A}) + \mathbf{y}^T \text{adj}(\mathbf{A})\mathbf{x}$$

(so $|\mathbf{I} + \mathbf{xy}^*| = 1 + \mathbf{y}^*\mathbf{x}$)

- if $\mathbf{S} = \mathbf{A} + i\mathbf{B}$ and non-singular then $\exists \tau \in \mathbb{R}$ such that $\mathbf{T} = \mathbf{A} + \tau\mathbf{B}$ is non-singular.

(use that $p(t) = \det(\mathbf{A} + t\mathbf{B})$ has at most n zeroes in complex plane so there is $\tau \in \mathbb{R}$ such that $p(\tau) \neq 0$)

- Every real Matrix \mathbf{A} similar over \mathbb{C} to real matrix \mathbf{B} is similar over \mathbb{R} . i.e. $\mathbf{0} \neq \mathbf{A}, \mathbf{B} \in \mathbf{M}_n(\mathbb{R})$ if $\mathbf{S} \in \mathbf{M}_n(\mathbb{C})$ and $\mathbf{B} = \mathbf{S}^{-1}\mathbf{A}\mathbf{S}$ then $\exists \mathbf{T} \in \mathbf{M}_n(\mathbb{R})$ such that $\mathbf{B} = \mathbf{T}^{-1}\mathbf{A}\mathbf{T}$

- If \mathbf{A} is diagonalizable i.e. $\mathbf{A} = \mathbf{S}^{-1}\mathbf{D}\mathbf{S}$ then $p(\mathbf{A}) = \mathbf{S}^{-1}p(\mathbf{D})\mathbf{S}$ which makes evaluation of $p(\mathbf{A})$ easier.

- If \mathbf{A}_n has distinct eigenvalues (diagonalizable) and Commutes with \mathbf{B} then \mathbf{B} is Diagonalizable (more precisely \mathbf{A}_n, \mathbf{B} are simultaneously diagonalizable) and $\mathbf{B} = p(\mathbf{A})$

(use similarity, partition arguments and Lagrange interpolation poly which provides a polynomial map of n distinct reals to any n reals) for some polynomial $p(t)$ of degree at most $n - 1$

- If \mathbf{B} is Diagonalizable then \mathbf{B} has a square-root i.e. $\exists \mathbf{A} | \mathbf{A}^2 = \mathbf{B}$.

- If $\mathbf{A}_n, \mathbf{B}_n$ are similar so are $\text{adj}(\mathbf{A}), \text{adj}(\mathbf{B})$.

- All Unitary Matrices Form a group in $\text{GL}(n, \mathbb{C})$ and compact in \mathbb{C}^{n^2} .

- Singular Value Decomposition: Every matrix $\mathbf{A}_{m,n}$ can be written as $\mathbf{A} = \mathbf{U}_m \mathbf{S} \mathbf{V}_n$ where \mathbf{U}, \mathbf{V} are Unitary and \mathbf{S} is the diagonal (with zero) entries that are eigenvalue of $\mathbf{A}^* \mathbf{A}$ or $\mathbf{A} \mathbf{A}^*$.

- Reversal Matrix \mathbf{B} is matrix that is up-side-down of Identity and $\mathbf{B}\mathbf{A}$ reverses row order of \mathbf{A} , $\mathbf{A}\mathbf{B}$ reverses column order of \mathbf{A} And $\mathbf{B} = \mathbf{B}^* = \mathbf{B}^{-1}$

- By Jordan Canonical form Every non-singular matrix is similar to its Transpose

- \mathbf{A} is similar to $\bar{\mathbf{A}}$ iff \mathbf{A} is Similar to a real matrix (Same condition for $\mathbf{A} \sim \mathbf{A}^*$)

- \mathbf{A} is hermitian iff $\text{tr}(\mathbf{A}^2) = \text{tr}(\mathbf{A}^* \mathbf{A})$

- if \mathbf{A} is hermitian then, $\forall \mathbf{x} \in \mathbb{C}^n$:

- $\mathbf{x}^* \mathbf{A} \mathbf{x}$ is positive iff all eigenvalues are positive

- $\mathbf{x}^* \mathbf{A} \mathbf{x}$ is negative iff all eigenvalues are negative

- if eigenvalues are $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$ and subspaces $\{\mathbf{S}\}$ of \mathbb{C}^n then $\lambda_1 = \min(\frac{\mathbf{x}^* \mathbf{A} \mathbf{x}}{\mathbf{x}^* \mathbf{x}}), \lambda_n = \max(\frac{\mathbf{x}^* \mathbf{A} \mathbf{x}}{\mathbf{x}^* \mathbf{x}})$,

$$\lambda_k = \min_{\{\dim(\mathbf{S})=k\}} \max_{\mathbf{0} \neq \mathbf{x} \in \mathbf{S}} \frac{\mathbf{x}^* \mathbf{A} \mathbf{x}}{\mathbf{x}^* \mathbf{x}}$$

$$= \max_{\{\dim(\mathbf{S})=n-(k+1)\}} \min_{\mathbf{0} \neq \mathbf{x} \in \mathbf{S}} \frac{\mathbf{x}^* \mathbf{A} \mathbf{x}}{\mathbf{x}^* \mathbf{x}}$$

- In general even if $\mathbf{A} \in \mathbf{M}_n$ is not hermitian with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ then

$$\min_{\mathbf{x} \neq \mathbf{0}} \left| \frac{\mathbf{x}^* \mathbf{A} \mathbf{x}}{\mathbf{x}^* \mathbf{x}} \right| \leq |\lambda_i| \leq \max_{\mathbf{x} \neq \mathbf{0}} \left| \frac{\mathbf{x}^* \mathbf{A} \mathbf{x}}{\mathbf{x}^* \mathbf{x}} \right|$$

(can be pure inequality also)

- Every Jordan matrix is similar to a complex symmetric matrix so **Every matrix is similar to a complex symmetric matrix**

6 Properties based on Matrix Norm

- A function $||| \cdot ||| : \mathbf{M}_n \rightarrow \mathbb{R}$ is a matrix norm if:

$$1. |||\mathbf{A}||| \geq 0 \quad \text{Non-negative}$$

$$1a. |||\mathbf{A}||| = 0 \iff \mathbf{A} = \mathbf{0} \quad \text{Positive}$$

$$2. |||c\mathbf{A}||| = |c| |||\mathbf{A}||| \quad \forall c \in \mathbb{C} \quad \text{Homogeneous}$$

$$3. |||\mathbf{A} + \mathbf{B}||| \leq |||\mathbf{A}||| + |||\mathbf{B}||| \quad \text{Triangular Inequality}$$

$$4. |||\mathbf{A}\mathbf{B}||| \leq |||\mathbf{A}||| |||\mathbf{B}||| \quad \text{Sub-multiplicativity}$$

- Clearly $|||\mathbf{A}^k||| \leq |||\mathbf{A}|||^k$ now If $\mathbf{A}^2 = \mathbf{A} \implies |||\mathbf{A}||| \geq 1$ in particular $|||\mathbf{I}||| \geq 1$

- Some Matrix norms:

$$\text{■ } l_1 \text{ norm : } \|\mathbf{A}\|_1 = \sum_{i,j=1}^n |a_{ij}|$$

$$\text{■ } l_2 \text{ norm : } \|\mathbf{A}\|_2 = |\text{tr}(\mathbf{A}^* \mathbf{A})|^{1/2}$$

$$= \sqrt{\sigma_1(\mathbf{A})^2 + \dots + \sigma_n(\mathbf{A})^2} = \left(\sum_{i,j=1}^n |a_{ij}|^2 \right)^{1/2}$$

- l_∞ norm : $\|A\|_\infty = \max_{1 \leq i, j \leq n} |a_{ij}|$
- max Column sum norm
- $\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{ij}|$
- max Row sum norm
- $\|A\|_\infty = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$
- Spectral norm $\|A\|_2 = \sigma_1(A) = \text{Largest Singular Value of } A$
- **Matrix norm induced by vector norm** : if $\|\cdot\|$ is norm in \mathbb{C}^n then:

$$\|A\| = \max_{\|x\|=1} \|Ax\| = \max_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

$$= \max_{\|x\| \leq 1} \|Ax\| = \max_{\|x\|_\alpha = 1} \frac{\|Ax\|}{\|x\|}$$
 (for any other norm $\|\cdot\|_\alpha$ in \mathbb{C}^n) is a Matrix norm with additional properties:
 - $\|I\| = 1$
 - $\|Ay\| \leq \|A\| \|y\|$
- For Any Matrix $A \in M_n(\mathbb{C})$ we have $|\lambda| \leq \rho(A) = \max(|\lambda_i|) \leq \|A\|$ and if A is non-singular then $\rho(A) \geq |\lambda| \geq 1/\|A\|$
- if there is Matrix norm such that $\|A\| < 1$ then $\lim_{k \rightarrow \infty} A^k = 0$
- from above we have $\lim_{k \rightarrow \infty} A^k = 0$ iff $\rho(A) < 1$
- For any given Matrix norm $\|\cdot\|$ we have $\rho(A) = \lim_{k \rightarrow \infty} \|A^k\|^{1/k}$
- Matrix power series $\sum_{k=0}^{\infty} a_k A^k$ converges if $\rho(A) \leq R$ where R is the radius of convergence of complex power series $\sum_{k=0}^{\infty} a_k z^k$ i.e. if $\exists \|\cdot\| : \|A\| < R$
- Matrix A is nonsingular if $\exists \|\cdot\| : \|I - A\| < 1$ and $A^{-1} = \sum_{k=0}^{\infty} (I - A)^k$
- From above we have if $A_n = [a_{ij}]$ and $|a_{ii}| > \sum_{j \neq i} |a_{ij}|$ i.e. absolute value of diagonal elements are greater than sum of absolute values of elements in corresponding rows (or columns) then A is non singular

7 Properties associated to Quadratic forms

- A_n is Hermitian iff :
 - $x^* A x$ is real for all $x \in \mathbb{C}^n$
 - A is normal and all its eigenvalues are real
 - $S^* A S$ is Hermitian $\forall S \in M_n$
- from above A is +ve (-ve) semi-definite ($x^* A x \geq 0$ or ≤ 0) $\implies A$ is hermitian
- if A is +ve definite (-ve) then $A^*, A^{-1}, A^T, \bar{A}$ are all +ve definite (-ve).
- every Diagonal entry of +ve (-ve) definite (semi) Matrix are +ve (non -ve, -ve) only.
- A positive semi-definite matrix is positive definite iff it is non-singular
- for $A_n = [a_{ij}]$ a +ve (-ve) semi-definite matrix if $a_{kk} = 0$ then $a_{ik} = a_{ki} = 0 \forall i \in \{1, 2, \dots, n\}$ i.e. if diagonal entry is 0 then that row and column are 0.
- A is positive semi definite iff $A = B^* B$ for some B
- A_n is positive definite iff $\det(p_k) > 0 \forall 1 \leq k \leq n$ where p_k is the $k \times k$ principle matrix partitioned in A (along the diagonal).

8 Other Important Theorems

- Gersgorin Theorem: for a matrix $A_n = [a_{ij}]$
 - A Gersgorin Disk of $A = \{z \in \mathbb{C} : |z - a_{ii}| \leq R'_i(A) = \sum_{j \neq i} |a_{ij}|\}$ for $i = 1, 2, \dots, n$
 - Eigenvalues of A are all in the union of Gersgorin Discs of A i.e. $\{\lambda_i\} \in G(A) = \bigcup_{i=1}^n \{z \in \mathbb{C} : |z - a_{ii}| \leq R'_i(A)\}$
 - if $G(A)$ forms a disjoint set $G_k(A)$ which is union of k discs then $G_k(A)$ contains exactly k eigenvalues (counted according to algebraic multiplicity).
 - The above statements remain true even if radius of the discs are $C'_j = \sum_{i \neq j} |a_{ij}|$ as A^T has same eigenvalues.
 - from above we have $\rho(A) \leq \min \left\{ \max_i \sum_{j=1}^n |a_{ij}|, \max_j \sum_{i=1}^n |a_{ij}| \right\}$

■ if p_1, p_2, \dots, p_n are positive real numbers then

$\{\lambda_i\} \in \bigcup_{i=1}^n \{z \in \mathbb{C} : |z - a_{ii}| \leq \frac{1}{p_i} \sum_{j \neq i} p_j |a_{ij}|\}$
or

$\{\lambda_i\} \in \bigcup_{i=1}^n \{z \in \mathbb{C} : |z - a_{jj}| \leq p_j \sum_{i \neq j} \frac{1}{p_i} |a_{ij}|\}$
as similar matrices have same eigenvalues

● A is Diagonally dominant if $|a_{ii}| \geq \sum_{j \neq i} |a_{ij}|$ and strictly diagonally dominant if $|a_{ii}| > \sum_{j \neq i} |a_{ij}|$

● if A is strictly diagonally dominant then : A is non-singular, if $a_{ii} > 0 \forall i = 1, 2, \dots, n$ then every eigenvalue of A has a positive real part, and if A is hermitian and $a_{ii} > 0 \forall i = 1, 2, \dots, n$ then A is positive definite.

● A_n has nonzero diagonal entries, is diagonally dominant and $|a_{ii}| > R'_i$ for atleast $n - 1$ values of i then A is non singular.

● If every entry of A is non zero, A is diagonally dominant and $|a_{kk}| > R'_k$ for any k then A is non singular

● if A_n has the property that $\forall p, q \in \{1, 2, \dots, n\} \exists$ sequence of distinct integers $p = k_1, k_2, \dots, k_m = q$ such that

$a_{k_1 k_2}, a_{k_2 k_3}, \dots, a_{k_{m-1} k_m}$ are non zero, A is diagonally dominant and $|a_{kk}| > R'_k$ for any k then A is non singular

● The above property states that if A is a probability/stochastic matrix then for each node in directed graph of A is strongly connected (for each pair of nodes there is a finite length directed path to them or the stochastic matrix has only one class and all states are communicating)

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