Task 1 – Breadth First Search (BFS):

(i) Create a graph with at least 10 nodes:

Let's create an example undirected graph with 10 nodes and 11 edges:



(ii) Write a program in Python to perform a Breadth First Search to find a specific node in the graph:

Python program to perform BFS on the given graph:

from collections import defaultdict, deque

```
class Graph:
       def __init__(self):
       self.graph = defaultdict(list)
       def add_edge(self, u, v):
       self.graph[u].append(v)
       self.graph[v].append(u)
       def bfs(self, start, target):
       visited = set()
       queue = deque([start])
       while queue:
       current = queue.popleft()
       if current == target:
               return True
       visited.add(current)
       for neighbor in self.graph[current]:
               if neighbor not in visited:
               queue.append(neighbor)
       return False
```

```
# Create the graph
graph = Graph()
graph.add edge(1, 2)
graph.add_edge(1, 4)
graph.add edge(2, 3)
graph.add_edge(2, 5)
graph.add_edge(2, 6)
graph.add_edge(3, 6)
graph.add_edge(3, 7)
graph.add edge(5, 6)
graph.add_edge(5, 8)
graph.add_edge(6, 9)
graph.add edge(9, 10)
# Perform BFS and search for node 10 starting from node 1
start node = 1
target node = 10
result = graph.bfs(start_node, target_node)
if result:
       print(f"Node {target node} is reachable from Node {start node} using BFS.")
else:
       print(f"Node {target_node} is NOT reachable from Node {start_node} using BFS.")
```

(iii) Description and Output:

In the given graph, each node represents a unique vertex, and each edge represents an undirected connection between two vertices. We created a graph with 10 nodes and used adjacency lists to represent the connections between the nodes.

The BFS algorithm starts from a given start node and explores its neighbors level by level. It uses a gueue data structure to keep track of the nodes to be visited.

In the Python code, we perform a BFS starting from node 1 and search for node 10. The output will indicate whether node 10 is reachable from node 1 using BFS.

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Task 2 – Depth First Search (DFS):
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To perform DFS on the same graph, we need to modify the Graph class to implement the DFS algorithm.

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Python code:
```

```
class Graph:

def __init __(self):
```

```
self.graph = defaultdict(list)
       def add_edge(self, u, v):
       self.graph[u].append(v)
       self.graph[v].append(u)
       def dfs(self, start, target, visited):
       if start == target:
       return True
       visited.add(start)
       for neighbor in self.graph[start]:
       if neighbor not in visited:
               if self.dfs(neighbor, target, visited):
               return True
       return False
# Create the graph (same as before)
# Perform DFS and search for node 10 starting from node 1
start_node = 1
target_node = 10
visited nodes = set()
result = graph.dfs(start_node, target_node, visited_nodes)
if result:
       print(f"Node {target_node} is reachable from Node {start_node} using DFS.")
else:
       print(f"Node {target_node} is NOT reachable from Node {start_node} using DFS.")
```

```
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     class Graph:
        def __init__(self):
    self.graph = defaultdict(list)
         def add_edge(self, u, v):
    self.graph[u].append(v)
            self.graph[v].append(u)
         def bfs(self, start, target):
            visited = set()
             queue = deque([start])
             while queue:
                 current = queue.popleft()
                 if current == target:
                 visited.add(current)
                 for neighbor in self.graph[current]:
                      if neighbor not in visited:
                        queue.append(neighbor)
    # Create the graph
    graph = Graph()
     graph.add_edge(1, 2)
    graph.add_edge(1, 4)
    graph.add_edge(2, 3)
     graph.add_edge(2, 5)
    graph.add_edge(2, 6)
    graph.add_edge(3, 6)
    graph.add_edge(3, 7)
    graph.add_edge(5, 6)
    graph.add_edge(5, 8)
     graph.add_edge(6, 9)
     graph.add_edge(9, 10)
    start_node = 1
     target_node = 10
     result = graph.bfs(start_node, target_node)
     if result:
       print(f"Node {target_node} is reachable from Node {start_node} using BFS.")
        print(f"Node {target_node} is NOT reachable from Node {start_node} using BFS.")
```

C:\Users\Yoann\Desktop>python tp4.py Node 10 is reachable from Node 1 using BFS.