An Image Is Worth 393 Areas:

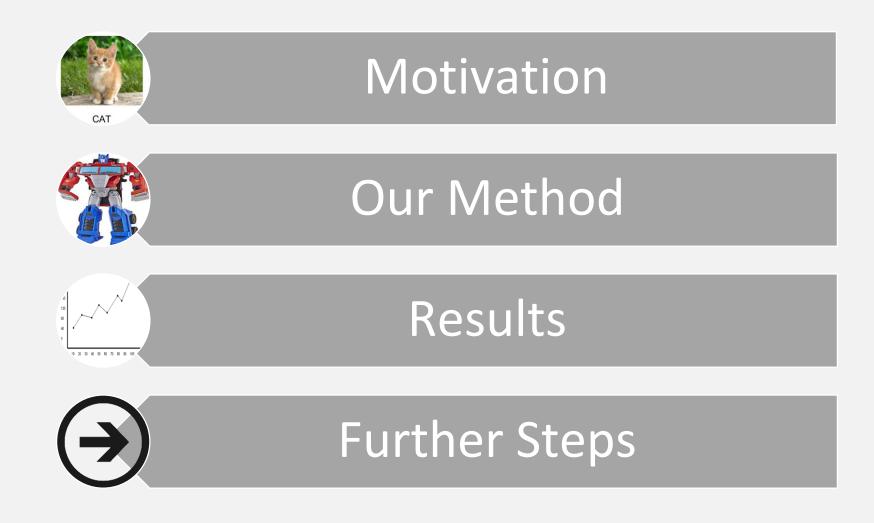
Training image Transformers with Area-Attention

Osher Tidhar

Yoav Kurtz



Agenda



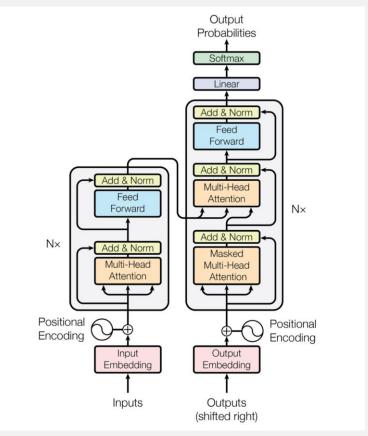
Model of choice for NLP problems.





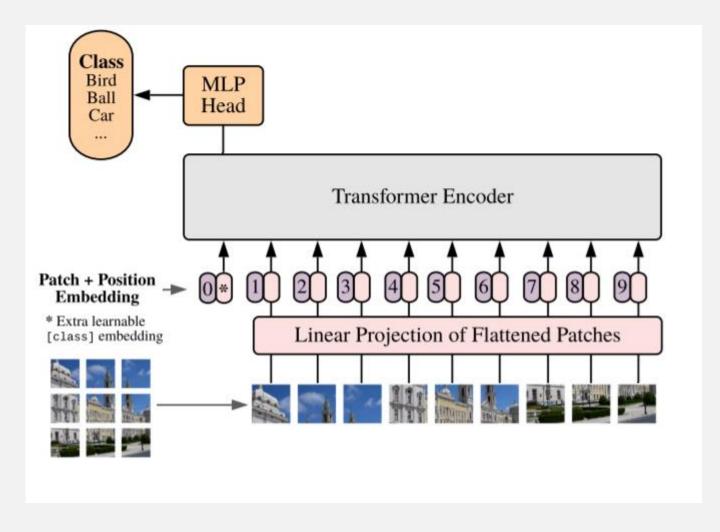
Recently migrated to computer vision.

- Motivation
- Our Method
- Results
- Further Steps



Transformer Overview

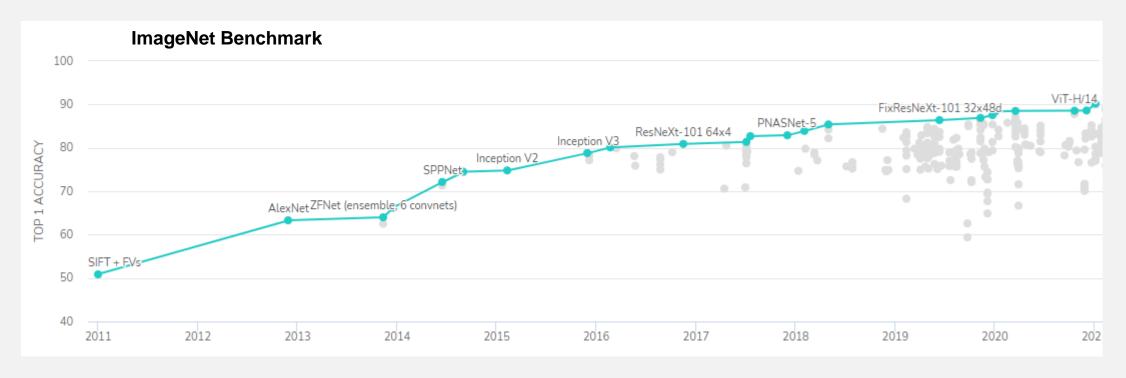
Vision Transformer¹



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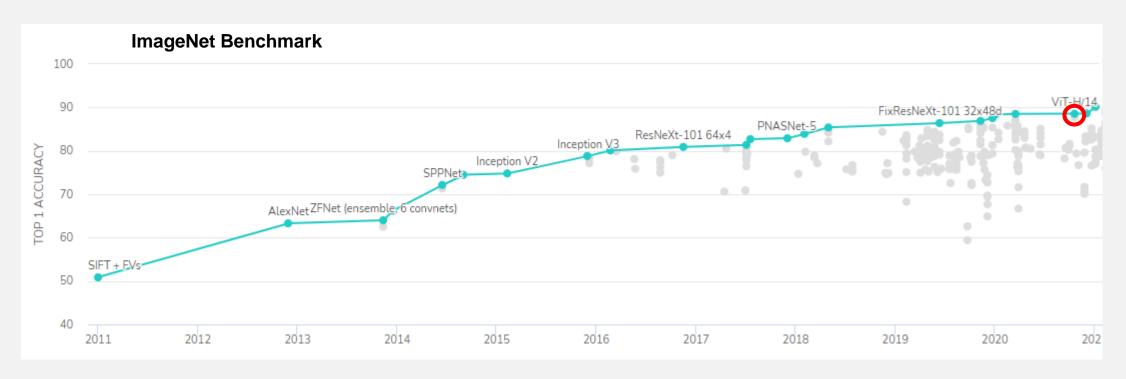
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- Model of choice for NLP problems.
- Recently migrated to vision, showing competitive^{1,2} results.



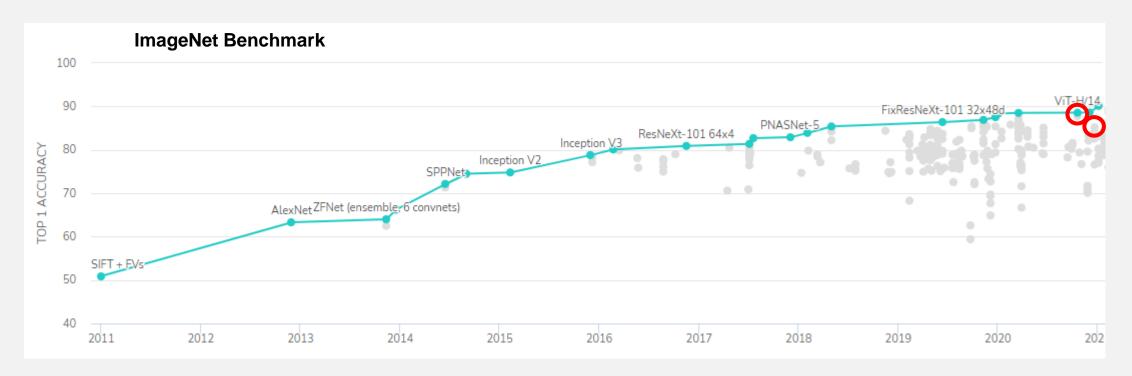
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- Model of choice for NLP problems.
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- Model of choice for NLP problems.
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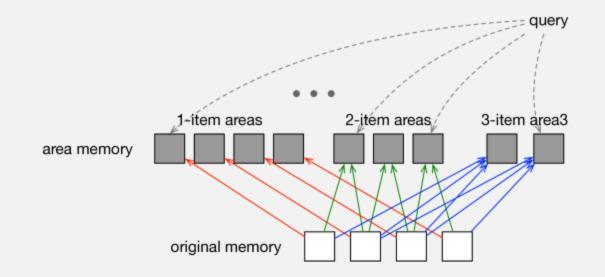
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Recently migrated to vision, showing com



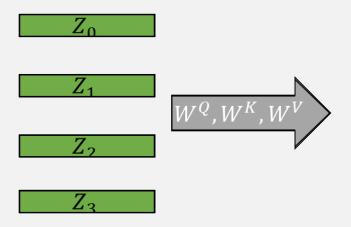
Motivation

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- Attending group of items in the memory that are structurally adjacent.
- Model can attend to combinations of items.

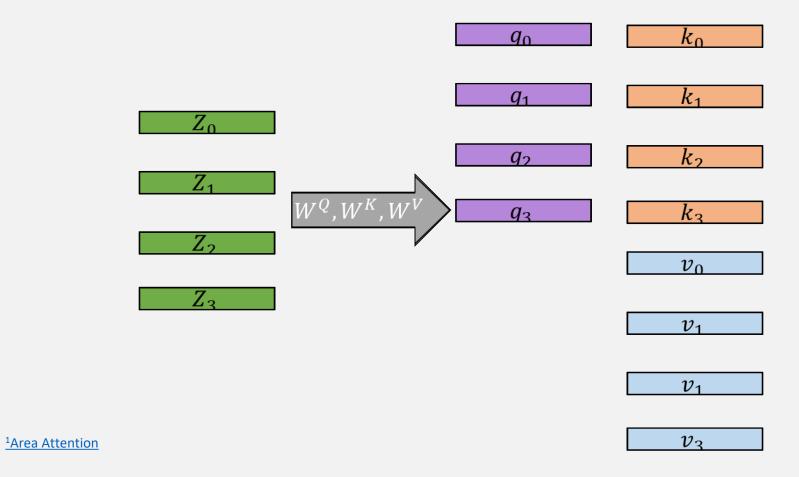


- Z_0
- Z_1
- Z_{\cdot}
- Z_3

- Motivation
- Our Method
- Result:
- Further Steps

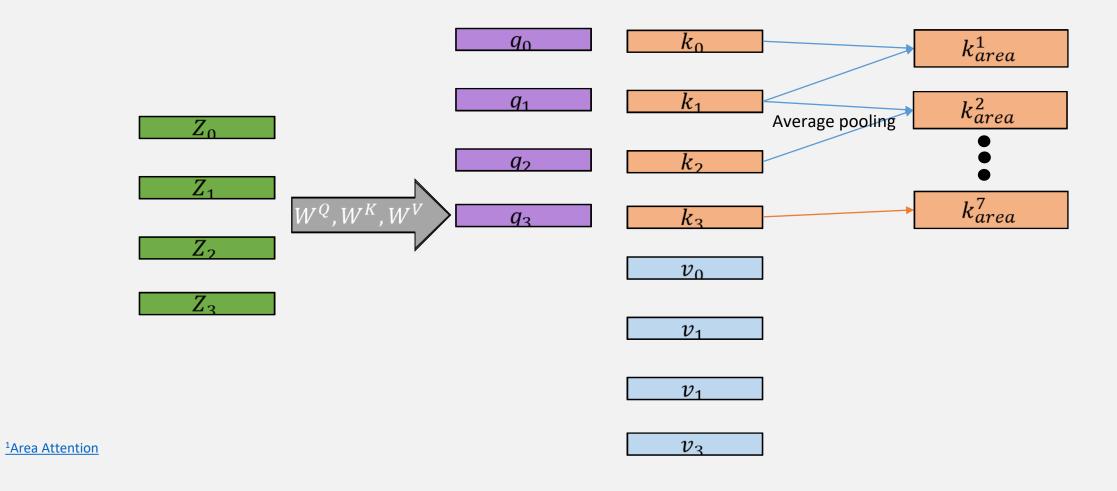


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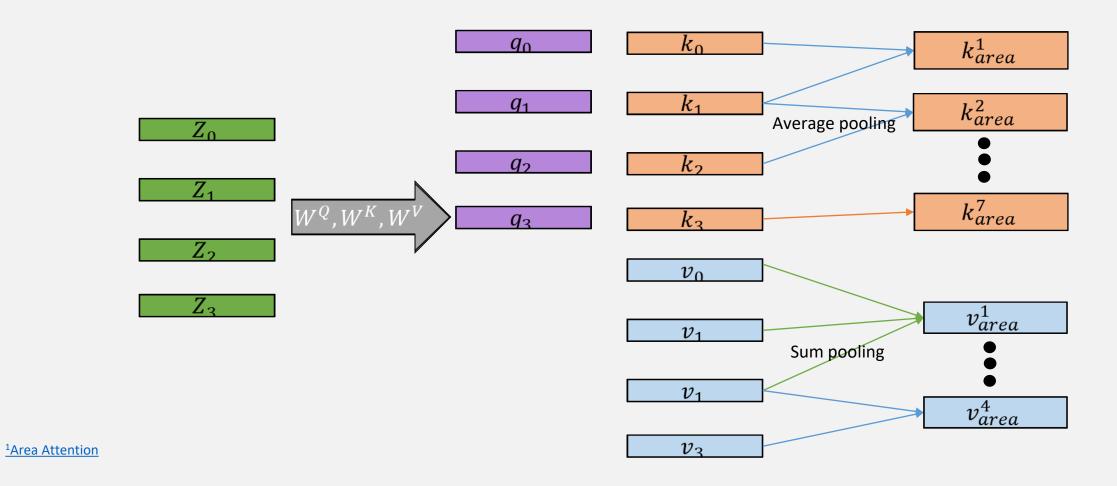


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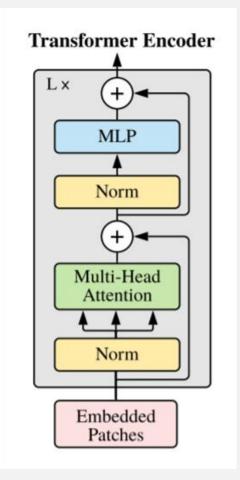


- Motivation
- Our Method
- Result:
- Further Steps



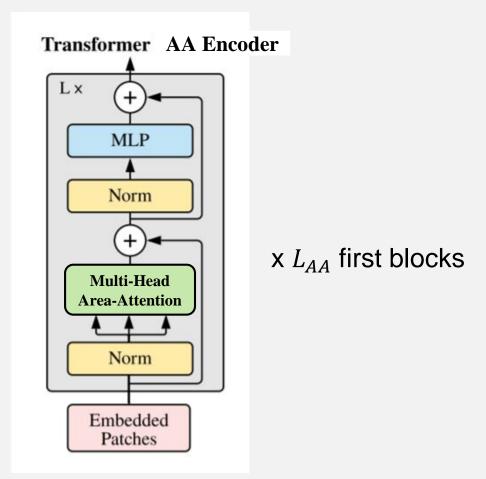
Vision Transformer + Area Attention

- Motivation
- Our Method
- Results
- Further Steps
- Multi-head self-attention replaced with multi-head area-attention.
- Different AA configurations are tested.



Vision Transformer + Area Attention

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Number of areas in ViT + AA

- Motivation
- Our Method
- Results
- In ViT, each image is represented by patches of 16x16 pixels.
 - Further Steps
- In our model, what is the total number of areas that can be generated?
- → For the following configurations:

(H, W)	(P, P)	max area size
224x224	16x16	2

we got a sequence of length 197:

14x14 patch images + 1 token class.

which corresponds to 393 areas:

197 areas built of 1 element + 196 areas built of a combination of 2 adjacent elements.

Choosing a dataset for our experiments:

Motivation

Results

Our Method

Further Sten

Dataset - CIFAR-10

	Train size	Test size	#classes
CIFAR-10	50,000	10,000	10

Choosing models for our experiments

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Original architecture of the Vision-Transformer model:

	Embedding	#heads	#layers	#params	Training resolution
ViT Base	768	12	12	86M	224

Models we used: Vision-Transformers small¹ and tiny²

	Embedding	#heads	#layers	#params	Training resolution
ViT Small	384	6	12	22M	224
ViT Small + AA	384	6	12	22M	224
ViT Tiny	192	3	12	5M	224
ViT Tiny + AA	192	3	12	5M	224

Choosing models for our experiments

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Accuracy achieved with ViT + AA

- Motivation
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- Accuracy of our pretrained weights on CIFAR-10 Testset:

o ViT-Small model:

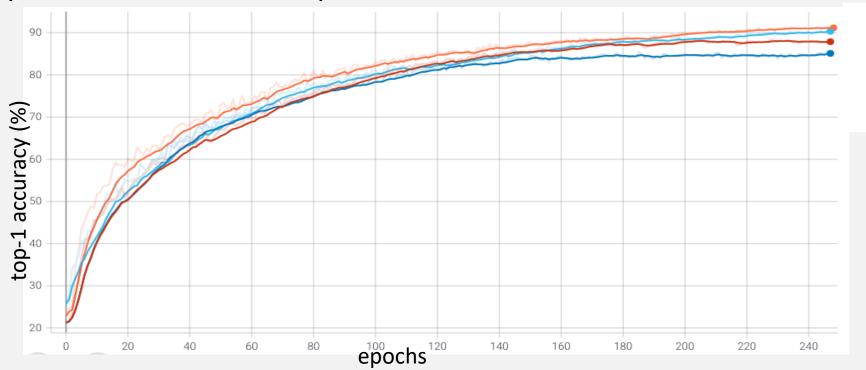
	top-1 acc	top-5 acc	loss
ViT-small + AA with max_size=2	91.44	99.6	0.408
ViT-small + AA with max_size=3	87.77	98.69	0.526
ViT-small + AA with max_size=4	84.61	98.17	0.602
Only ViT-small	90.02	99.6	0.432

o ViT-Tiny model:

	top-1 acc	top-5 acc	loss
ViT-tiny + AA with max_size=2	86.14	99.52	0.557
Only ViT-tiny	85.49	99.49	0.576

Accuracy achieved with ViT + AA

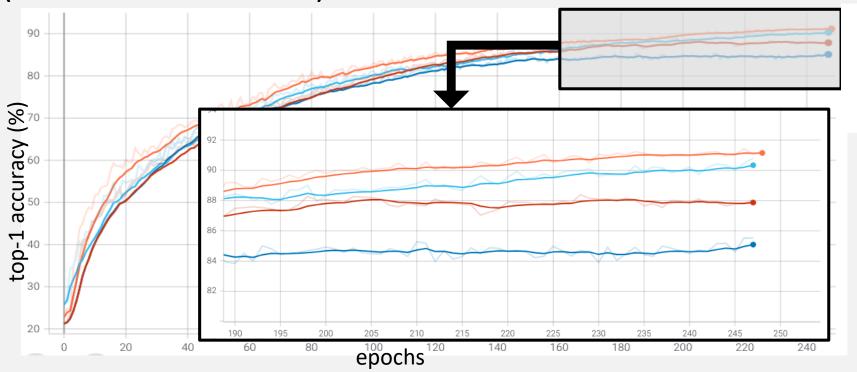
- Motivation
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- Further Steps
- Only AA2 configuration achieves better accuracy than only ViT-S.
- Accuracy improves as we decrease the maximum size of an area (for the first 2 blocks).



- ViT-S + AA with max size = 2
- Only ViT-S
- ViT-S + AA with max size = 3
- ViT-S + AA with max size = 4

Accuracy achieved with ViT + AA

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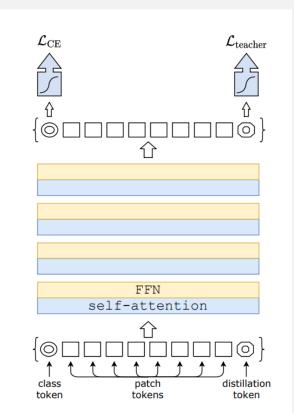


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- Only ViT-S
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- ViT-S + AA with max size = 4

Further steps

- Training AA-ViT using network distillation.
- Plays the same role as the class token, except that it aims at reproducing the label estimated by the teacher.
- Both tokens interact in the transformer through attention
- Achieved results that were competitive with the results of convnets for Imagenet.

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Questions?