DIGITAL IMAGE PROCESSING

IN

MATLAB

Presented By:

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- Grayscale digital image: Matrix of integers from 0 to L-1
- Color digital image: Three matrices of integers from 0 to L-1 each
- ➡ Digital image processing means applying sequence of operations on digital images using digital computer.
- Major Applications :
 - Improvement of pictorial information for better human perception
 - For autonomous machine applications
 - **■** Efficient storage and transmission.

- ♣ A digital image will be obtained from analog image by sampling and quantization.
- Sampling:
 - Representation of an image by 2-D matrix
- Quantization:
 - ■Each matrix element represented by one of the finite set of discrete values.

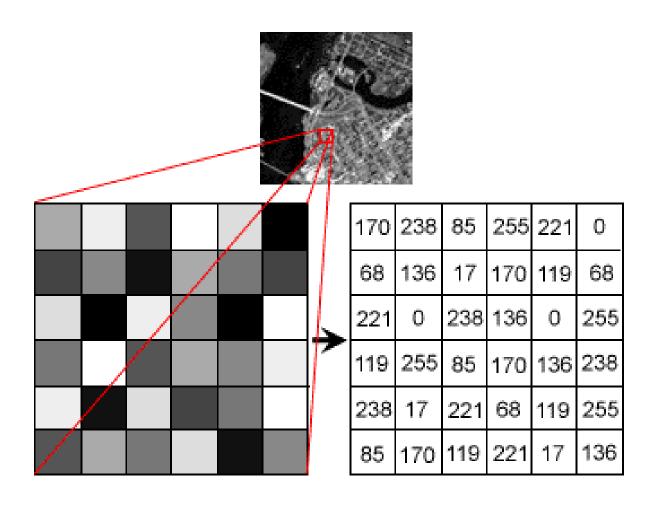


Figure 1. Example of a digital image

- → A pixel is the smallest unit of a digital image or graphic that can be displayed and represented on a digital display device.
- ▶ Pixels are combined to form a complete image or video.
- → Major type of digital images
 - Binary image: pixel values of a binary image will be either 0 or 1.
 - Grayscale image: pixels values will be depends on the number of bits used to represent one pixel. In general 8-bit grayscale representation is used, where the pixel values will fall into [0, 255].
 - Color image: color images will be represented using 3 different primary color planes, say R, G, and B. In general each pixel will be represented using 24 bits.



(a) Binary image



(b) Grayscale image

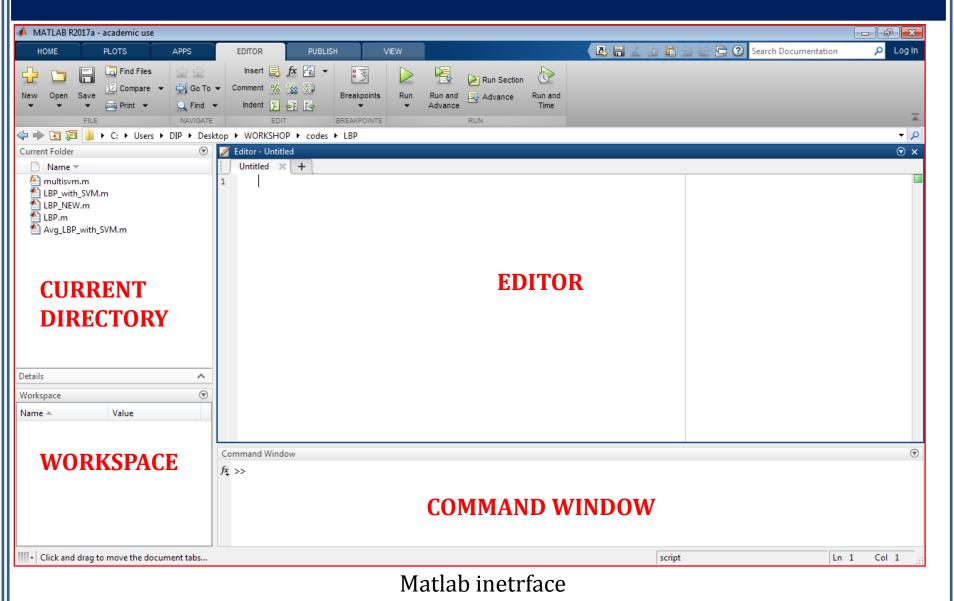


(c) Color image

Introduction to Matlab

- Matlab stands for Matrix Laboratory
- → MATLAB features a family of application-specific solutions called toolboxes
- ➡ Most of the digital image processing solutions are available in image processing toolbox (IPT) and computer vision toolbox(CVT) of Matlab.
- ➡ IPT and CVT in Matlab provides operations like
 - Image enhancement
 - Noise reduction
 - Geometric transformations (rotation, scaling, etc.)
 - Image segmentation

Introduction to Matlab



Introduction to Matlab

- Matlab stands for Matrix Laboratory
- ➡ All data is represented in the form of matrix.
- → MATLAB features a family of application-specific solutions called toolboxes
- → Most of the digital image processing solutions are available in image processing toolbox of Matlab.
- ➡ Image processing toolbox in Matlab provides operations like
 - Image enhancement
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 - Geometric transformations (rotation, scaling, etc.)
 - Image segmentation

Matrix Initilialization

Matrix representation in matlab

To initialize a matrix of size 5X10 with all 0's.

To initialize a matrix of size 5X10 with all 1's.

$$>> a=ones(5, 10)$$

➡ To initialize a matrix of size 5X5 with the integer 150

$$>> a=ones(5, 5).*150$$

To linearize a matrix

>> b=reshape(a, [1 (r*c)]);

Loop Statements in Matlab

```
for
Eg:-
       sum=0;
       for i=1:10
               sum=sum+i; % Finding sum of first 10 natural numbers
       end
⇒ while
Eg:-
       fact=1;
       i=1;
       while i<5
               fact=fact*i; % Finding factorial 5
        i=i+1;
```

end

Conditional Statements in Matlab

```
if 🗰
```

```
Check given number is odd or even
Example 1:
                  x=input('Enter a number \n');
                  if mod(x,2)==0
                            disp("Even No");
                  else
                            disp("Odd No");
                  end
Check given number is negative or positive
Example 2:
                  x=input('Enter a number\n');
                  if x>0
                            disp("Positive")
                  elseif x==0
                            disp("Zero")
                  else
                            disp("Negative");
                  end
```

Basic Statistics

```
→Mean
    for 1-D case M = mean(A)
    for 2-D case M = mean2(B)
→Median
    M = median(A)
▶Mode
    M = mode(A)
▶Variance
    V = var(A)
▶Standard Deviation
    Column-wise std- y = std(A,0)
    Row-wise std -
                     y=std(A,1)
▶Skewness
    Column-wise skewness-
                                 y = skewness(A,0)
    Row-wise skewness
                                 y= skewness(A,1)
→Kurtosis
    k = kurtosis(X)
```

Displaying an Image in Matlab

imshow

syntax : imshow(filename/matrix_name)

example : imshow('cameraman.tif');

imshow(A);

⇒ figure

figure creates new figure window to open multiple images at a time

```
example : figure; imshow(A); title('First image');
figure; imshow(B); title('Second image');
```

Displaying an Image in Matlab

→ imread

syntax : Variable_Name=imread(filename);

example : A=imread('cameraman.tif');

imshow(A);

Writing an Image in Matlab

imwrite

syntax : imwrite(variable_name, filename, format)

example : I=uint8(ones([100 100]).*150);

imwrite(I, 'writeimage.tif','tif');

R=imread('writeimage.tif');

imshow(R);

Image Formats in Matlab

BMP Windows Bitmap

GIF Graphics Interchange Format

HDF Hierarchical Data Format

JPEG Joint Photographic Experts Group

JPG

JPF

JPX

J2C

J2K

PBM Portable Bitmap

PCX Paintbrush

PGM Portable Graymap

PNG Portable Network Graphics

PNM Portable Any Map

PPM Portable Pixmap

RAS Sun™ Raster

TIFF Tagged Image File Format

TIF

XWD X Window Dump

CUR Windows Cursor resources

→ imresize

syntax : imresize(variable_name, Scale)

example : I=imread('cameraman.tif');

B=imresize(I,0.5);

C=imresize(I,2);

figure; imshow(I);

figure; imshow(B);

figure;imshow(C);







(a) Original image

(b) scaled down

(b) scaled up

→ imresize

syntax : imresize(variable_name, Size)

example : I=imread('cameraman.tif');

B=imresize(I, [200 200]);

figure;imshow(I);
figure;imshow(B);







(b) Resized image

⇒ imresize

- The interpolation techniques need to consider during scaling operation can also mention during usage of imresize function. Three interpolation techniques are available.
 - o nearest
 - o bilinear
 - o bicubic
- syntax : imresize(variable_name, size, method)
- example : I=imread('cameraman.tif');

B=imresize(I, [200 200], 'nearest');

figure; imshow(B);

imcrop

■ We can crop unwanted regions from image using imcrop function

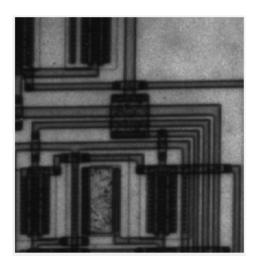
■ Syntax : imcrop(variable_name, rectangle_postion)

■ Example : I = imread('circuit.tif');

I2 = imcrop(I, [60 40 100 90]);

figure, imshow(I);

figure, imshow(I2);



(a) Original image



(b) Cropped image

Display Images Using imtool

▶ imtool

■ imtool function can also used to display an image, where we can see the range of pixel values in the image, pixel value at each location, etc.

■ syntax : imtool(variable_name);

or

imtool(file_name);

example : imtool('coins.png');



Color Image Processing

➡ We can extract each color component of a given RGB image Example I=imread('D:\images\peppers.jpg'); R=I(:,:,1);G=I(:,:,2);B=I(:,:,3);figure; imshow(R); title('R Color Plane'); figure; imshow(G);title('G Color Plane'); figure; imshow(B); title('B Color Plane'); To convert and RGB image to grayscale use rgb2gray and to convert grayscale image to binary use im2bw I=imread('D:\images\peppers.jpg'); G=rgb2gray(I); B=im2bw(G); figure; imshow(G);title('Grayscale Version');

figure; imshow(B);title('Binary Image');

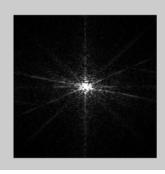
Frequency Domain

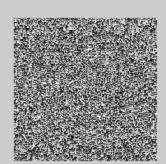
fft2

```
Im = imread('cameraman.tif');
F = fft2(double(Im));
figure;
subplot(2,2,1);
imshow(Im);
subplot(2,2,2);
imshow(abs(F),[24 100000]);
subplot(2,2,3);
imshow(abs(fftshift(F)),[24 100000]);
subplot(2,2,4);
imshow(angle(fftshift(F)),[-pi pi]);
```









Frequency Domain

Swapping of phase and magnitude two images

```
I1 = imresize(imread('cameraman.tif'),[512 512]);
I2 = imresize(imread('pout.tif'),[512 512]);
F1 = fftshift(fft2(I1));
F2 = fftshift(fft2(I2));
R1 = abs(ifft2(ifftshift(abs(F1).*exp(j*angle(F2)))));
R2 = abs(ifft2(ifftshift(abs(F2).*exp(j*angle(F1)))));
figure;
subplot(2,2,1); imshow(I1);
subplot(2,2,2); imshow(I2);
subplot(2,2,3); imshow(R1,[]);
subplot(2,2,4); imshow(R2,[]);
```

Frequency Domain

Swapping of phase and magnitude two images









Discrete Cosine Transform

ightharpoonup B = dct2(A) returns the two-dimensional discrete cosine transform of A. The matrix B is the same size as A and contains the discrete cosine transform coefficients.

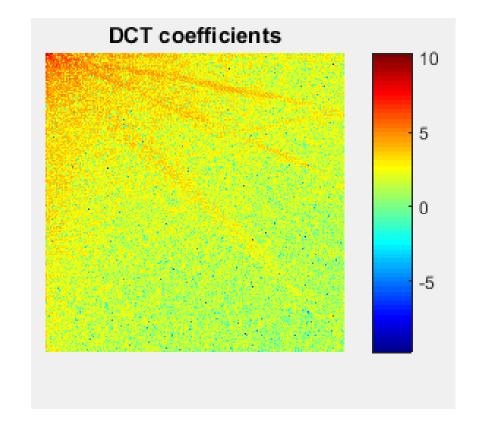
Example

```
I = imread('cameraman.tif');
figure;imshow(I);title('Original Image');

J = dct2(I);
figure; imshow(log(abs(J)),[]); title('DCT coefficients');
colormap(gca, jet(64)); % gca handle for image shown in the last figure colorbar;
```

Discrete Cosine Transform





Singular Value Decomposition (SVD)



Example:

```
A=[ 5, 6,2;4,7,2;5,5,6;6,4,8;] [U S V]=svd(A);
```

```
U =
                                        S =
                    0.7442
  -0.4351
           0.4753
                               -0.1757
                                           17.5073
                                                                          -0.5751 0.0105
                                                                                              0.8180
  -0.4370
           0.5976
                     -0.5438
                               0.3953
                                                     5.3428
                                                                          -0.6078 0.6638
                                                                                             -0.4358
  -0.5255
           -0.2088
                    -0.3501
                               -0.7468
                                                               0.9735
                                                                          -0.5476
                                                                                    -0.7479
                                                                                             -0.3753
  -0.5862
            -0.6111
                    0.1668
                              0.5052
```

Histogram Processing

To find histogram of an image use imhist()

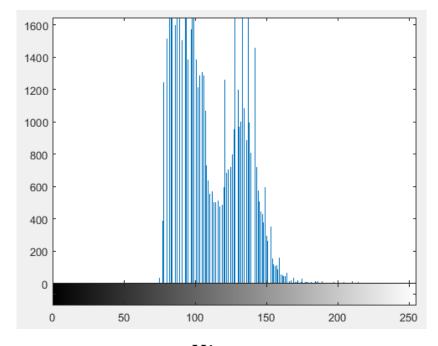
Example : I=imread('pout.tif');

figure; imshow(I);

figure; imhist(I);



Image



Histogram

Image Enhancement

- **→ imadjust** increases the contrast of the image by mapping the values of the input intensity image to new values such that, by default, 1% of the data is saturated at low and high intensities of the input data.
- **▶ histeq** performs histogram equalization. It enhances the contrast of images by transforming the values in an intensity image so that the histogram of the output image approximately matches a specified histogram (uniform distribution by default).
- → adapthisteq performs contrast-limited adaptive histogram equalization. Unlike histeq, it operates on small data regions (tiles) rather than the entire image. Each tile's contrast is enhanced so that the histogram of each output region approximately matches the specified histogram (uniform distribution by default). The contrast enhancement can be limited in order to avoid amplifying the noise which might be present in the image.

Image Enhancement

➡imadjust, histeq, adapthisteq

```
pout=imread('pout.tif');
pout_imadjust=imadjust(pout);
pout_histeq=histeq(pout);
pout_adapthisteq=adapthisteq(pout);
figure;
subplot(2,2,1);imshow(pout);title('Original');
subplot(2,2,2);imshow(pout_imadjust);title('Imadjust');
subplot(2,2,3);imshow(pout_histeq);title('Histeq');
subplot(2,2,4);imshow(pout_adapthisteq);title('AdaptHisteq');
```

Image Enhancement

Original



lmadjust



Histeq



AdaptHisteq



Addition of Noise

imnoise: Adding noise to image.

J = imnoise(I,TYPE,PARAMETERS) Add noise of a given TYPE to the intensity image I. TYPE is a string that can have one of these values:

■ 'gaussian' Gaussian white noise with constant mean and variance

■ 'localvar' Zero-mean Gaussian white noise with an intensity-dependent variance

- 'poisson' Poisson noise
- 'salt & pepper' "On and Off" pixels
- 'speckle' Multiplicative noise

Addition of Noise

salt & pepper

```
I=imread('cameraman.tif');
N=imnoise(I,'salt & pepper', 0.01);
figure;
subplot(1,2,1);imshow(I);title('Original image');
subplot(1,2,2);imshow(N);title('Salt & Pepper Noise');
```

Original image



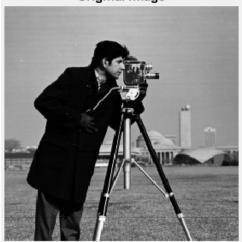
Salt & Pepper Noise



Image Filtering

medfilt2: for median filtering
 I=imread('cameraman.tif');
 N=imnoise(I,'salt & pepper', 0.01);
 F=medfilt2(N, [5 5]);
 figure;
 subplot(1,3,1);imshow(I,[]);title('Original image');
 subplot(1,3,2);imshow(N,[]);title('Salt & Pepper Noise');
 subplot(1,3,3);imshow(F,[]);title('Filtered Image');

Original image



Salt & Pepper Noise



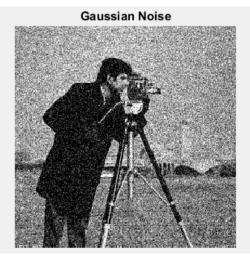
Filtered Image



➡ wiener2 : for wiener filtering

```
I=imread('cameraman.tif');
N=imnoise(I,'gaussian',0,0.025);
F=wiener2(N, [5 5]);
figure;
subplot(1,3,1);imshow(I,[]);title('Original Image');
subplot(1,3,2);imshow(N,[]);title('Gaussian Noise');
subplot(1,3,3);imshow(F,[]);title('Filtered Image');
```







fspecial: To define new filter

■ syntax : fspecial(Type, Size)

■ Types :

'average' : averaging filter

'disk' : circular averaging filter

'gaussian' : Gaussian lowpass filter

'laplacian' : filter approximating the 2-D Laplacian operator

'log' : Laplacian of Gaussian filter

'motion' : motion filter

'prewitt' : Prewitt horizontal edge-emphasizing filter

'sobel' : Sobel horizontal edge-emphasizing filter

fspecial: To define new filter

```
■ Example 1 : H=fspecial('average',[3 3]);
```

This will create a filter H as follows:

```
0.1111 0.1111 0.1111

H= 0.1111 0.1111 0.1111

0.1111 0.1111
```

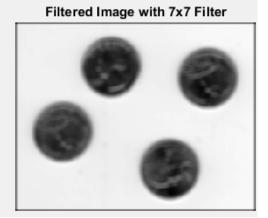
■ Example : **G=fspecial('gaussian',[5,5])**;

```
0.0000
       0.0000
               0.0002
                       0.0000
                               0.0000
0.0000
        0.0113
                0.0837 0.0113
                                0.0000
0.0002
       0.0837
                0.6187 0.0837
                                0.0002
0.0000
       0.0113
                0.0837 0.0113
                                0.0000
0.0000
        0.0000
                0.0002
                        0.0000
                                0.000
```

imfilter: To perform filtering operation with a specific filter







Edge Detection

- **▶ Edge detection** is an image processing technique for finding the boundaries of objects within images.
- ▶ It works by detecting discontinuities in brightness.
- ➡ Edge detection is used for image segmentation and data extraction in areas such as image processing, computer vision, and machine vision.
- **edge** Function finds edges in intensity image.
 - edge takes an image I as input, and returns a binary image BW of the same size as I, with 1's where the function finds edges in I and 0's elsewhere.

Edge Detection

```
I=imread('coins.png');
E1=edge(I, 'canny');
E2=edge(I, 'prewitt');
E3=edge(I, 'sobel');
E4=edge(I, 'roberts');
E5=edge(I, 'log');
subplot(3,2,1);imshow(I,[]);title('Original Image');
subplot(3,2,2);imshow(E1,[]);title('Canny');
subplot(3,2,3);imshow(E2,[]);title('Prewitt');
subplot(3,2,4);imshow(E3,[]);title('Sobel');
subplot(3,2,5);imshow(E4,[]);title('Roberts');
subplot(3,2,6);imshow(E5,[]);title('Log');
```

Edge Detection

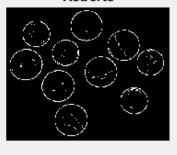
Original Image



Prewitt



Roberts



Canny



Sobel



Log



- Morphology means study of structure
- Finding structures, completing incomplete structure to be addressed
- →Morphological operation will involve a small image called structuring element.

- **▶ imdilate** and **imerode** are two commonly used morphological operators
- **▶IM2** = **imerode(IM,SE)** erodes image IM with structuring element SE.
- → The argument SE will be obtained by **strel** function.

```
se1 = strel('square',11)  % 11-by-11 square
se2 = strel('line',10,45)  % line, length 10, angle 45 degrees
se3 = strel('disk',15)  % disk, radius 15
se4 = strel('ball',15,5)  % ball, radius 15, height 5
```

Imerode and imdilate

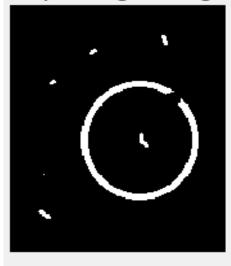
```
I1=rgb2gray(imread('D:\images\morph1.bmp'));
I=im2bw(I1);
se=strel('square',10);
I2=imdilate(I,se);
I3=imerode(I2,se);
figure;
subplot(1,3,1);imshow(I);title('Step 1 : Original Image');
subplot(1,3,2);imshow(I2);title('Step 2 : Dilated Image');
subplot(1,3,3);imshow(I3);title('Step 3 : Eroded Image');
```

Imerode and imdilate

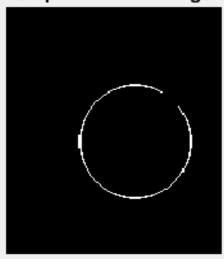
```
I1=rgb2gray(imread('D:\images\morph.bmp'));
I=im2bw(I1);
se=strel('square',4);
I2=imerode(I,se);
I3=imdilate(I2,se);
figure;
subplot(1,3,1);imshow(I);title('Step 1 : Original Image');
subplot(1,3,2);imshow(I2);title('Step 2: Eroded Image');
subplot(1,3,3);imshow(I3);title('Step 3: Dilated Image');
```

imerode and imdilate

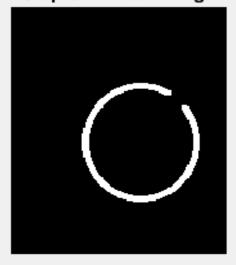
Step 1 : Original Image



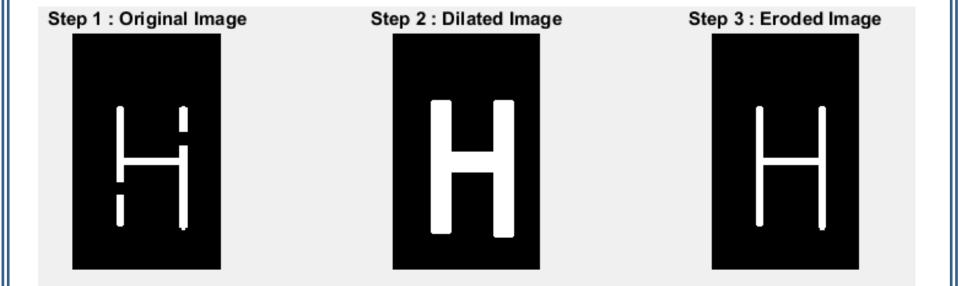
Step 2: Eroded Image



Step 3: Dilated Image



imerode and imdilate



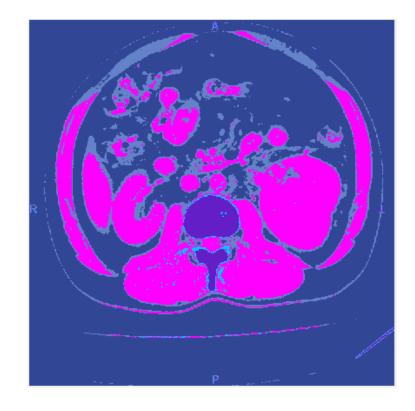
Gray to RGB Conversion for Better Visualization

```
I=imresize(imread('D:\images\brain.tif'),[512 512]);
R=uint8(zeros(512,512));
G=uint8(zeros(512,512));
B=uint8(zeros(512,512));
[R1 C1]=size(I);
for i=1:R1
  for j=1: C1
    if I(i,j) > 230
      R(i,j)=100;
                 G(i,j)=30; B(i,j)=200;
    elseif I(i,j)>150
      R(i,j)=0; G(i,j)=200;
                                    B(i,j)=255;
   elseif I(i,j)>100
      R(i,j)=255;
                      G(i,j)=0;
                                    B(i,j)=255;
    elseif I(i,j)>50
      R(i,j)=100;
                      G(i,j)=130; B(i,j)=200;
    else
      R(i,j)=50;
                G(i,j)=70; B(i,j)=150;
    end
  end
end
ColorImage = cat(3,R,G,B);
figure; imshow(ColorImage);
```

Gray to RGB Conversion for Better Visualization



Original grascale image



Corresponding color image

Frame Extraction From Video

```
filename = 'rhinos.avi';
mov = VideoReader(filename);
opFolder = fullfile(cd, 'snaps');
if ~exist(opFolder, 'dir')
  mkdir(opFolder);
end
numFrames = mov.NumberOfFrames;
numFramesWritten = 0;
for t = 1 : 5: numFrames
currFrame = read(mov, t);
opBaseFileName = sprintf('%d.png', t);
opFullFileName = fullfile(opFolder, opBaseFileName);
imwrite(currFrame, opFullFileName, 'png'); progIndication = sprintf('Wrote
frame %d of %d.', t, numFrames);
disp(progIndication);
numFramesWritten = numFramesWritten + 1;
end
progIndication = sprintf('Wrote %d frames to folder "%s"',numFramesWritten,
opFolder);
disp(progIndication);
```

Frame Extraction From Video













Step 1: Read Image

Step 2: Detect Entire Cell

Step 3: Dilate the Image

Step 4: Fill Interior Gaps

Step 5: Remove Connected Objects on Border

Step 6: Smoothen the Object

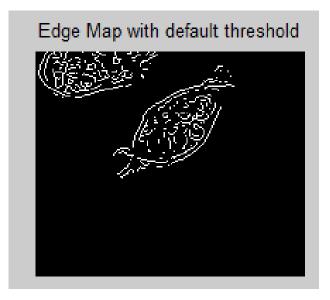
Step 1: Read Image

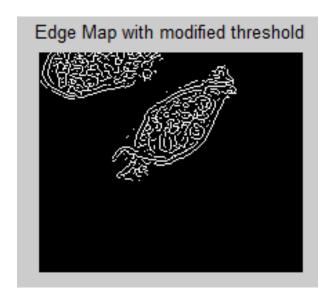
```
I = imread('cell.tif');
figure, imshow(I), title('original image');
```



Step 2: Detect Entire Cell

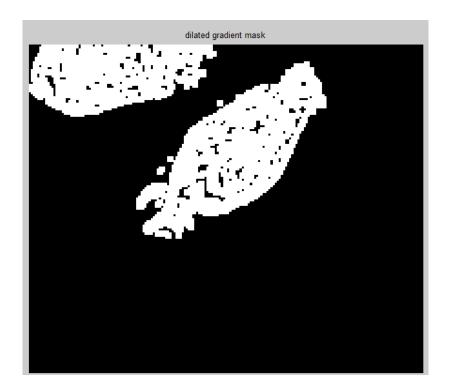
```
[BW, threshold] = edge(I, 'sobel');
fudgeFactor = .5;
BWs = edge(I,'sobel', threshold * fudgeFactor);
figure, imshow(BW), title('Edge Map with default threshold');
figure, imshow(BWs), title('Edge Map with modified threshold');
```





Step 3: Dilate the Image

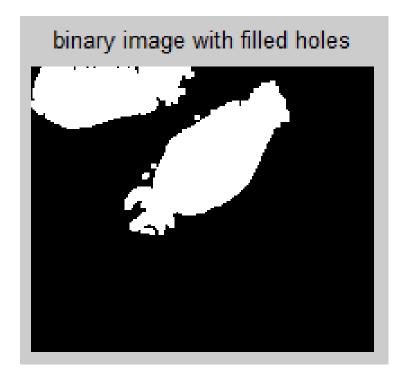
```
se=strel('square',3);
BWsdil = imdilate(BWs, se);
figure, imshow(BWsdil), title('dilated gradient mask');
```



Step 4: Fill Interior Gaps

```
BWdfill = imfill(BWsdil, 'holes');
```

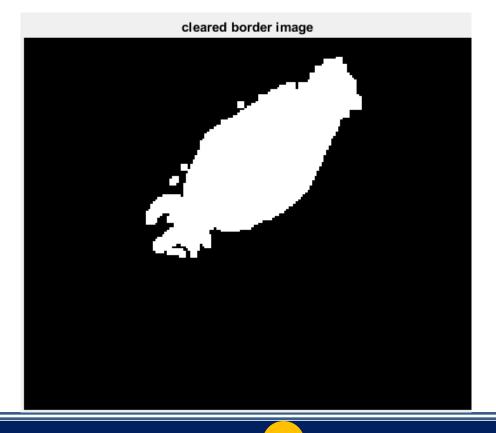
figure, imshow(BWdfill); title('binary image with filled holes');



Step 5: Remove Connected Objects on Border

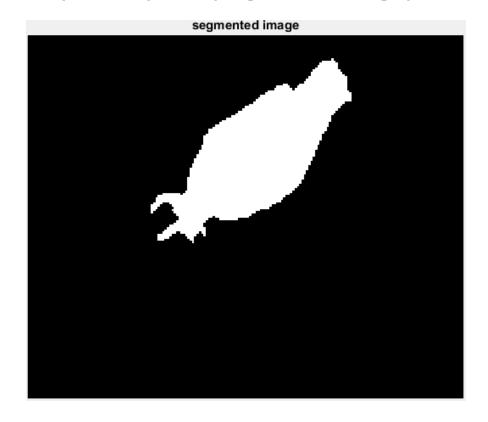
BWnobord = imclearborder(BWdfill, 4);

figure, imshow(BWnobord), title('cleared border image');



Step 6: Smoothen the Object

```
seD = strel('disk',1);
BWfinal = imerode(BWnobord,seD);
BWfinal = imerode(BWfinal,seD);
figure, imshow(BWfinal), title('segmented image');
```



Step 1: Detect Candidate Text Regions Using MSER

Step 2: Remove Non-Text Regions Based On Basic Geometric

Properties

Step 3: Remove Non-Text Regions Based On Stroke Width Variation

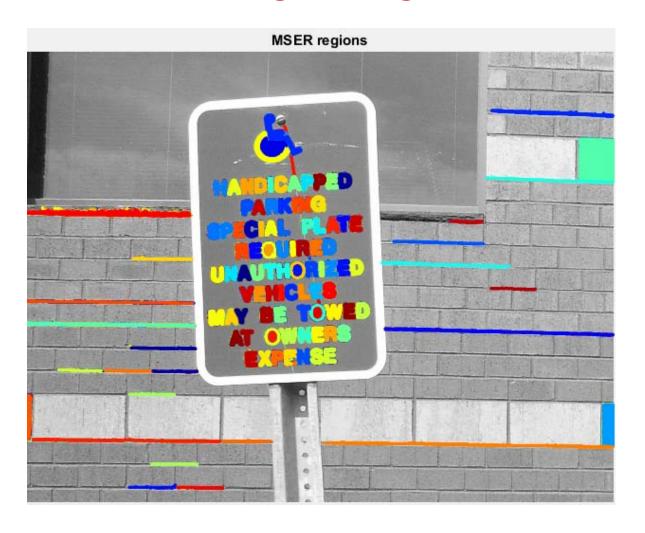
Step 4: Merge Text Regions For Final Detection Result

Step 5: Recognize Detected Text Using OCR

Step 1: Detect Candidate Text Regions Using MSER

```
colorImage = imread('handicapSign.jpg');
I = rgb2gray(colorImage);
% Detect MSER regions.
[mserRegions, mserConnComp] = detectMSERFeatures(I, ...
  'RegionAreaRange',[200 8000],'ThresholdDelta',4); % ThresholdDelta
Threshold of the stability value
figure
imshow(I)
hold on
plot(mserRegions, 'showPixelList', true, 'showEllipses', false)
title('MSER regions')
```

Step 1: Detect Candidate Text Regions Using MSER



```
% Use regionprops to measure MSER properties
mserStats = regionprops(mserConnComp, 'BoundingBox', 'Eccentricity', ...
  'Solidity', 'Extent', 'Euler', 'Image');
% Extent – The ratio between number of pixels in the bounding box and in the region
% Euler- number of objects in the region minus the number of holes in those objects
%Image – binary image corresponds to pixel index list of the connected component
% Solidity - the proportion of the pixels in the convex hull that are also in the region
% Compute the aspect ratio using bounding box data.
bbox = vertcat(mserStats.BoundingBox);
w = bbox(:,3);
h = bbox(:,4);
aspectRatio = w./h;
```

```
% Threshold the data to determine which regions to remove. These thresholds % may need to be tuned for other images.

filterIdx = aspectRatio' > 3;

filterIdx = filterIdx | [mserStats.Eccentricity] > .995;

filterIdx = filterIdx | [mserStats.Solidity] < .3;

filterIdx = filterIdx | [mserStats.Extent] < 0.2 | [mserStats.Extent] > 0.9;

filterIdx = filterIdx | [mserStats.EulerNumber] < -4;
```

```
% Remove regions
mserStats(filterIdx) = [];
mserRegions(filterIdx) = [];

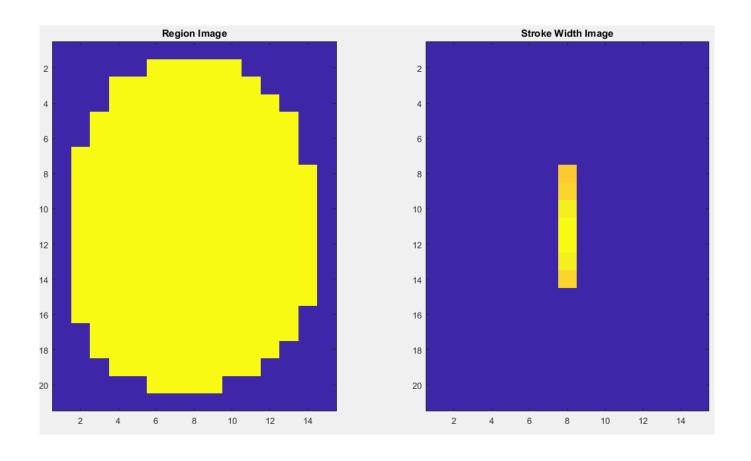
% Show remaining regions
figure
imshow(I)
hold on
plot(mserRegions, 'showPixelList', true,'showEllipses',false)
title('After Removing Non-Text Regions Based On Geometric Properties')
hold off
```

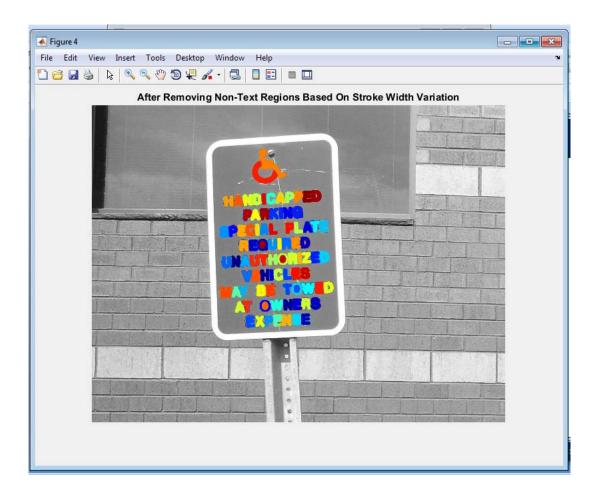


```
% Get a binary image of the a region, and pad it to avoid boundary effects
% during the stroke width computation.
regionImage = mserStats(6).Image;
regionImage = padarray(regionImage, [1 1]);
% Compute the stroke width image.
distanceImage = bwdist(~regionImage);
skeletonImage = bwmorph(regionImage, 'thin', inf);
strokeWidthImage = distanceImage;
strokeWidthImage(\sim skeletonImage) = 0; % Show the region image
alongside the stroke width image.
figure; subplot(1,2,1);
imagesc(regionImage);
title('Region Image');
subplot(1,2,2);
imagesc(strokeWidthImage); title('Stroke Width Image')
```

```
% Compute the stroke width variation metric strokeWidthValues = distanceImage(skeletonImage); strokeWidthMetric = std(strokeWidthValues)/mean(strokeWidthValues); % Threshold the stroke width variation metric strokeWidthThreshold = 0.4; strokeWidthFilterIdx = strokeWidthMetric > strokeWidthThreshold; % Threshold the stroke width variation metric strokeWidthThreshold = 0.4; strokeWidthFilterIdx = strokeWidthMetric > strokeWidthThreshold;
```

```
% Process the remaining regions
for j = 1:numel(mserStats)
 regionImage = mserStats(j).Image;
  regionImage = padarray(regionImage, [1 1], 0);
  distanceImage = bwdist(~regionImage);
  skeletonImage = bwmorph(regionImage, 'thin', inf);
  strokeWidthValues = distanceImage(skeletonImage);
  strokeWidthMetric = std(strokeWidthValues)/mean(strokeWidthValues);
 strokeWidthFilterIdx(j) = strokeWidthMetric > strokeWidthThreshold;
end
% Remove regions based on the stroke width variation
mserRegions(strokeWidthFilterIdx) = [];
mserStats(strokeWidthFilterIdx) = [];
% Show remaining regions
Figure; imshow(I); hold on
plot(mserRegions, 'showPixelList', true,'showEllipses',false)
title('After Removing Non-Text Regions Based On Stroke Width Variation')
hold off
```





Step 4: Merge Text Regions For Final Detection Result

```
% Get bounding boxes for all the regions
bboxes = vertcat(mserStats.BoundingBox);
% Convert from the [x y width height] bounding box format to the [xmin ymin]
% xmax ymax] format for convenience.
xmin = bboxes(:,1);
ymin = bboxes(:,2);
xmax = xmin + bboxes(:,3) - 1;
ymax = ymin + bboxes(:,4) - 1;
% Expand the bounding boxes by a small amount.
expansionAmount = 0.02;
xmin = (1-expansionAmount) * xmin;
ymin = (1-expansionAmount) * ymin;
xmax = (1+expansionAmount) * xmax;
ymax = (1+expansionAmount) * ymax;
```

% Clip the bounding boxes to be within the image bounds

Step 4: Merge Text Regions For Final Detection Result

```
% Clip the bounding boxes to be within the image bounds
xmin = max(xmin, 1);
ymin = max(ymin, 1);
xmax = min(xmax, size(I,2));
ymax = min(ymax, size(I,1));
% Show the expanded bounding boxes
expandedBBoxes = [xmin ymin xmax-xmin+1 ymax-ymin+1];
IExpandedBBoxes =
insertShape(colorImage,'Rectangle',expandedBBoxes,'LineWidth',3);
figure
imshow(IExpandedBBoxes)
title('Expanded Bounding Boxes Text')
% Compute the overlap ratio
overlapRatio = bboxOverlapRatio(expandedBBoxes, expandedBBoxes);
% Set the overlap ratio between a bounding box and itself to zero to
```

We simplify the graph representation

Step 4: Merge Text Regions For Final Detection Result

```
% Set the overlap ratio between a bounding box and itself to zero to
% simplify the graph representation.
n = size(overlapRatio,1);
overlapRatio(1:n+1:n^2) = 0;
% Create the graph
g = graph(overlapRatio);
% Find the connected text regions within the graph
componentIndices = conncomp(g);
% Merge the boxes based on the minimum and maximum dimensions.
xmin = accumarray(componentIndices', xmin, [], @min);
ymin = accumarray(componentIndices', ymin, [], @min);
xmax = accumarray(componentIndices', xmax, [], @max);
ymax = accumarray(componentIndices', ymax, [], @max);
% Compose the merged bounding boxes using the [x y width height] format.
textBBoxes = [xmin ymin xmax-xmin+1 ymax-ymin+1];
```

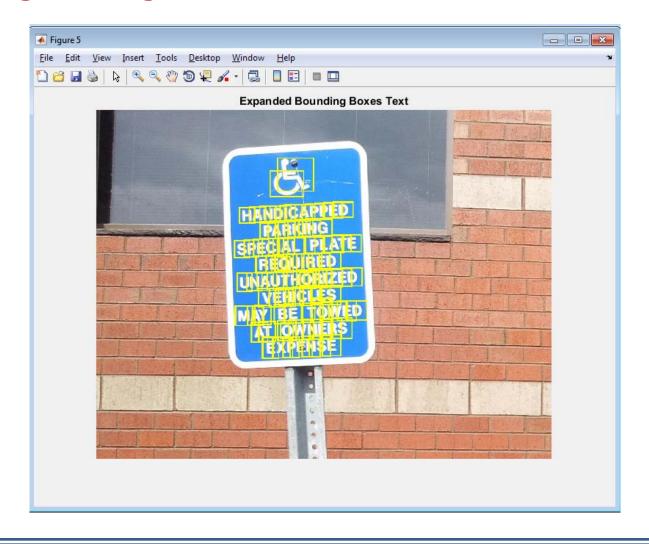
Step 4: Merge Text Regions For Final Detection Result

```
% Remove bounding boxes that only contain one text region
numRegionsInGroup = histcounts(componentIndices);
textBBoxes(numRegionsInGroup == 1, :) = [];

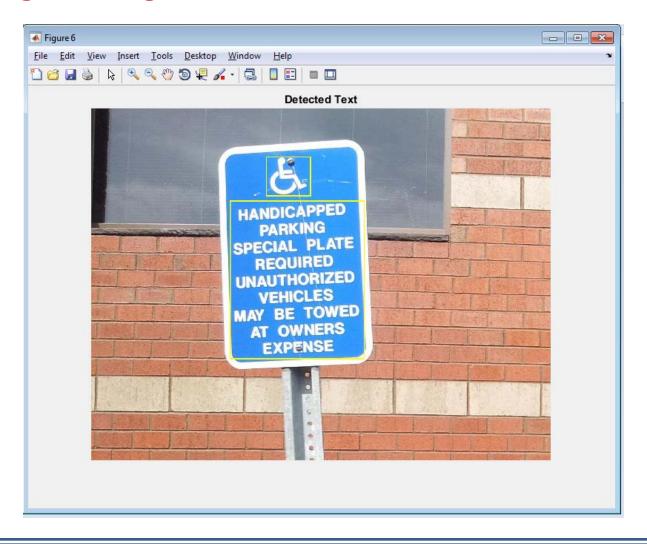
% Show the final text detection result.
ITextRegion = insertShape(colorImage, 'Rectangle', textBBoxes,'LineWidth',3);
figure
imshow(ITextRegion)
title('Detected Text')
```

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Step 4: Merge Text Regions For Final Detection Result



Step 4: Merge Text Regions For Final Detection Result



Step 5: Recognize Detected Text Using OCR

```
ocrtxt = ocr(I, textBBoxes);
[ocrtxt.Text]
```

THANK YOU...