

AM5630 - Foundations of CFD

Assignment -3

Lid Driven Cavity using Stream Function vorticity approach



Vijay S (AM16D025)
Yogeshwaran R (AM16D028)
Department of Applied Mechanics
IIT Madras, Chennai

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1. Problem Statement

- Using stream function vorticity approach, solve the lid driven cavity problem where the upper plate is moving with velocity of 1.0 m/s in positive x direction as shown below.

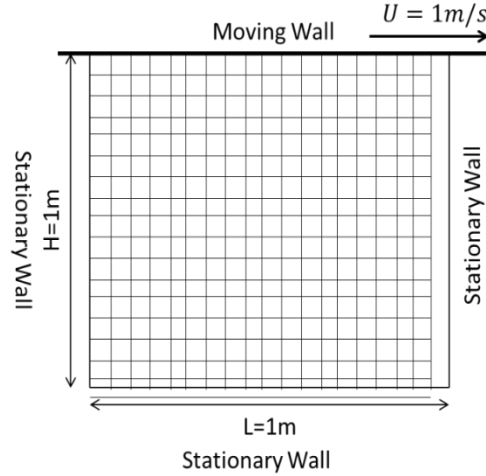


Figure 1 Lid Driven closed cavity

- The cavity is of size 1m x 1m. Take the convergence criteria for the stream function equation as $\text{CONGS} = 0.001$; and to achieve a steady state solution, CONSS is set to 0.002.
- Compare/Validate the numerical results with Ghia et al., “*High-Re Solutions for Incompressible Flow Using the Navier-Stokes Equations and a Multigrid Method*”, *Journal Of Computational Physics*, Vol. 48, pp387-411.
- Plot streamlines, vorticity, velocity vector & centerline velocity profile for the Reynold’s number (Re) = 400 and 1000.
- Extend the above problem to lid driven cavity with open flow channel as shown below.

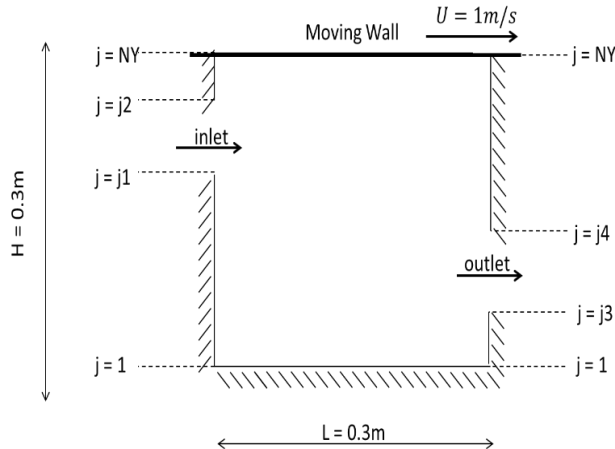


Figure 2 Lid Driven cavity with inlet & outlet ports

2. Governing Equation:

$$\text{(Continuity Equation)} \quad \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = -\omega \quad (1)$$

$$\text{(Vorticity transport Equation)} \quad \frac{\partial \omega}{\partial t} + u \frac{\partial \omega}{\partial x} + v \frac{\partial \omega}{\partial y} = \frac{1}{\text{Re}} \left(\frac{\partial^2 \omega}{\partial x^2} + \frac{\partial^2 \omega}{\partial y^2} \right) \quad (2)$$

$$\text{(Velocity Components)} \quad u = \frac{\partial \varphi}{\partial y}, \quad v = -\frac{\partial \varphi}{\partial x} \quad (3)$$

$$\text{(Pressure poisson Equation)} \quad \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} = 2\rho \left[\left(\frac{\partial^2 \omega}{\partial x^2} \right) \left(\frac{\partial^2 \omega}{\partial y^2} \right) - \left(\frac{\partial^2 \omega}{\partial x \partial y} \right)^2 \right] \quad (4)$$

3. Discretization of Governing Equation:

$$-\omega_{i,j} = \frac{\varphi_{i+1,j} - 2\varphi_{i,j} + \varphi_{i-1,j}}{\Delta x^2} + \frac{\varphi_{i,j+1} - 2\varphi_{i,j} + \varphi_{i,j-1}}{\Delta y^2} + O(\Delta x^2, \Delta y^2) \quad (5)$$

$$\omega_{i,j}^{n+1} = \omega_{i,j}^n + \Delta t * \left[\frac{1}{\text{Re}} \left(\frac{\omega_{i+1,j} - 2\omega_{i,j} + \omega_{i-1,j}}{\Delta x^2} + \frac{\omega_{i,j+1} - 2\omega_{i,j} + \omega_{i,j-1}}{\Delta y^2} \right) - \left(u_{i,j} \frac{\omega_{i+1,j} - \omega_{i-1,j}}{2\Delta x} + v_{i,j} \frac{\omega_{i,j+1} - \omega_{i,j-1}}{2\Delta y} \right) \right] + O(\Delta x^2, \Delta y^2, \Delta t) \quad (6)$$

$$u = \frac{\varphi_{i,j+1} - \varphi_{i,j-1}}{2\Delta y} + O(\Delta y^2), \quad v = \frac{\varphi_{i+1,j} - \varphi_{i-1,j}}{2\Delta x} + O(\Delta x^2) \quad (7)$$

$$p_{i,j} = 0.25 [p_{i+1,j} + p_{i-1,j} + p_{i,j+1} + p_{i,j-1}] - 0.5\rho \Delta x^2 \Delta y^2 \left[\left(\frac{\omega_{i+1,j} - 2\omega_{i,j} + \omega_{i-1,j}}{\Delta x^2} \right) \left(\frac{\omega_{i,j+1} - 2\omega_{i,j} + \omega_{i,j-1}}{\Delta y^2} \right) - \left(\frac{\omega_{i+1,j+1} + \omega_{i-1,j-1} - \omega_{i+1,j-1} + \omega_{i-1,j+1}}{4\Delta x \Delta y} \right)^2 \right] \quad (8)$$

4. Boundary condition

4.1 Lid Driven Closed Cavity Problem

4.1.1 Vorticity Boundary Condition

4.1.1.1 Left wall

Consider Equation (1) along the surface, the stream function is constant, and its value may be specified arbitrarily; for example, $\varphi_{i,j} = \varphi_1$. Then, along left wall,

$$\left(\frac{\partial^2 \varphi}{\partial y^2} \right)_{1,j} = 0, \text{ and Equation (1) is then reduced to } \left(\frac{\partial^2 \varphi}{\partial x^2} \right)_{1,j} = -\omega_{1,j} \quad (9)$$

Using Taylor's series, the second order derivative in the equation above is obtained as

$$\left(\frac{\partial^2 \varphi}{\partial x^2} \right)_{1,j} = \frac{2(\varphi_{2,j} - \varphi_{1,j})}{\Delta x^2} + O(\Delta x) \quad (10)$$

Substitution of Equation (10) into Equation (9) yields

$$\omega_{1,j} = \frac{2(\varphi_{1,j} - \varphi_{2,j})}{\Delta x^2} + O(\Delta x) \quad (11)$$

4.1.1.2 Right wall

A similar procedure is used to derive the boundary conditions at right boundary; the appropriate expression is given by,

$$\omega_{IM,j} = - \left(\frac{\partial^2 \varphi}{\partial x^2} \right)_{IM,j} = \frac{2(\varphi_{IM,j} - \varphi_{IMM1,j})}{\Delta x^2} + O(\Delta x) \quad (12)$$

4.1.1.3 Bottom wall

Since the bottom wall is fixed, the above procedure is followed for the bottom boundary also. The appropriate expression is given by,

$$\omega_{i,1} = - \left(\frac{\partial^2 \varphi}{\partial y^2} \right)_{i,1} = \frac{2(\varphi_{i,1} - \varphi_{i,2})}{\Delta y^2} + O(\Delta y) \quad (13)$$

4.1.1.4 Top wall

The upper surface is moving to the right with a constant velocity $u_0 = \left(\frac{\partial \varphi}{\partial y} \right)_{i,JM} = 1 \text{ m/s}$. Following the procedure described previously, the Taylor's series expansion at point (1, JMM1) yields,

$$\begin{aligned} \varphi_{i,JMM1} &= \varphi_{i,JM} - \left(\frac{\partial \varphi}{\partial y} \right)_{i,JM} \Delta y + \left(\frac{\partial^2 \varphi}{\partial y^2} \right)_{i,JM} \frac{\Delta y^2}{2} + O(\Delta y^3), \text{ from which} \\ \omega_{i,JM} &= \frac{2(\varphi_{i,JM} - \varphi_{i,JMM1})}{\Delta y^2} - \frac{2u_0}{\Delta y} + O(\Delta y) \end{aligned} \quad (14)$$

4.1.2 Stream Function Boundary Condition

4.1.2.1 Left wall

Consider Equation (3), using Taylor's series, the first order x-derivative in the equation is obtained as

$$\left(\frac{\partial \varphi}{\partial x} \right)_{1,j} = \frac{4\varphi_{2,j} - \varphi_{3,j} - 3\varphi_{1,j}}{2\Delta x} + O(\Delta x^2), \text{ Since the wall is fixed, } \left(\frac{\partial \varphi}{\partial y} \right)_{1,JM} = 0 \text{ and } \varphi_{i,j} \text{ at wall can be arbitrarily specified as mentioned earlier. Therefore, the above equation can be rewritten as}$$

$$\varphi_{2,j} = \frac{1}{4} (\varphi_{3,j} - \varphi_{1,j}) + O(\Delta x^2), \quad (15)$$

4.1.2.2 Right wall

Similarly, using Taylor's series backward differencing for the right fixed wall, the equation obtained as,

$$\varphi_{IMM1,j} = \frac{1}{4} (\varphi_{IMM2,j} - \varphi_{1,j}) + O(\Delta x^2) \quad (16)$$

4.1.2.3 Bottom wall

Consider Equation (3), using Taylor's series, the first order y-derivative in the equation is obtained as

$$\left(\frac{\partial \varphi}{\partial y} \right)_{i,1} = \frac{\varphi_{i,2} - \varphi_{i,1}}{\Delta y} + O(\Delta y), \text{ Since } \left(\frac{\partial \varphi}{\partial y} \right)_{i,1} = 0 \text{ and } \varphi_{i,1} \text{ can be any arbitrary value, the above equation becomes } \varphi_{i,2} = \varphi_{i,1} \quad (17)$$

The arbitrary constant φ is set to zero for all four walls as there were no flow rate across the boundaries

4.1.2.4 Top wall

Similarly, for top wall, the Taylor's series for the first order y-derivative is obtained as

$\left(\frac{\partial \phi}{\partial y}\right)_{i,JM} = \frac{\phi_{i,JMM1} - \phi_{i,JM}}{\Delta y} + O(\Delta y)$, Since the upper boundary is moving, $\left(\frac{\partial \phi}{\partial y}\right)_{i,JM} = u_0$, the above equation becomes

$$\phi_{i,JM} = u_0 \Delta y + \phi_{i,JM-1} + O(\Delta y), \quad (18)$$

4.2 Lid Driven Cavity with inlet & outlet ports

The procedure followed in this case is as same as the closed lid driven cavity problem at all fixed regions. The boundary conditions for vorticity and stream function at inlet and outlet port are described in the following sections.

4.2.1 Vorticity Boundary condition

4.2.1.1 Inlet port

Utilizing approximation (Equation (10)) and a second-order central difference expression for the y-derivative and substituting in Equation (1),

$$\omega_{i,J} = \frac{2(\phi_{1,j} - \phi_{2,j})}{\Delta x^2} - \frac{\phi_{1,j+1} - 2\phi_{1,j} + \phi_{1,j-1}}{\Delta y^2} + O(\Delta x, \Delta y^2), \quad J1 < J < J2 \quad (19)$$

4.2.1.2 Outlet port

Similarly, at the outlet, a simple extrapolation may be used for which one sets $\frac{\partial \phi}{\partial x} = 0$ to provide

$$\omega_{i,J} = \frac{1}{3} (4\phi_{IMM1,j} - \phi_{IMM2,j}) + O(\Delta x^2) \quad J3 < J < J4 \quad (20)$$

4.2.2 Stream Function Boundary Condition

4.2.2.1 Inlet Port

The stream function at inlet is determined from the interior as provided below,

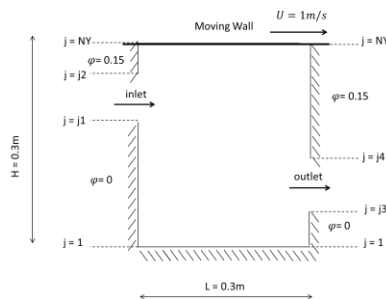
$$\phi_{1,j} = \frac{1}{3} (4\phi_{2,j} - \phi_{3,j}) + O(\Delta x^2) \quad J1 < J < J2 \quad (21)$$

4.2.2.2 Outlet Port

Similarly, the stream function at outlet is determined as given below,

$$\phi_{IM,j} = \frac{1}{3} (4\phi_{IMM1,j} - \phi_{IMM2,j}) + O(\Delta x^2) \quad J3 < J < J4 \quad (22)$$

4.2.2.3 Stationary Walls



5. Algorithm:

5.1 Pseudo Code

Step 1. Initialize ϕ, ω, u, v, p

Step 2. Compute the boundary conditions for vorticity & Stream function.

Step 3. Obtain ϕ by solving Poisson equation (Eqn. (5)) for the initial guess $\omega_{i,j}^k = 0$, using Point successive over relaxation scheme with Convergence criteria of $\text{CONSF} = 0.001$

Step 4. Calculate $u_{i,j}$ and $v_{i,j}$ from equation (7)

Step 5. Calculate $\omega_{i,j}^{k+1}$ from Vorticity equation (Eqn. (6))

Step 6. Update $\omega_{i,j}^k = \omega_{i,j}^{k+1}$

Step 7. Repeat the above steps ω reached convergence ($\text{CONSS} = 0.002$)

Step 8. Calculate Pressure using equation (8)

5.2 Flowchart

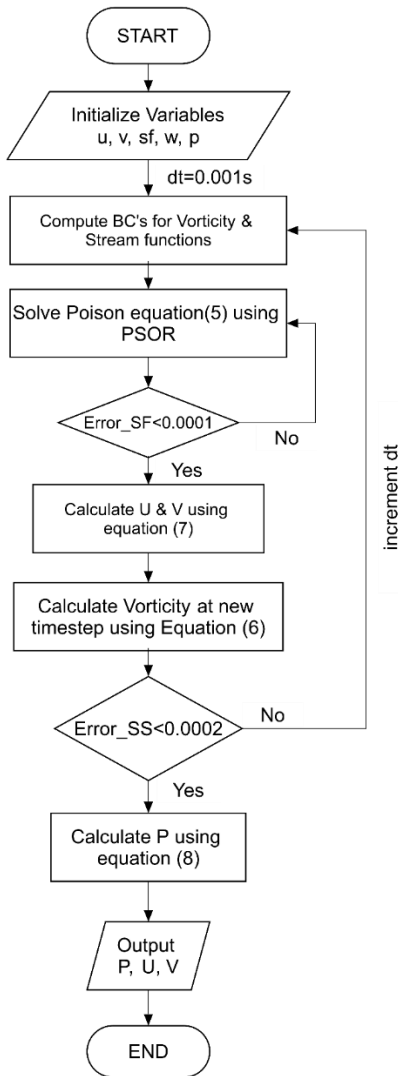


Figure 3 Flowchart of Stream Function Vorticity approach

6. Results and Discussion

6.1 Lid Driven Cavity:

6.1.1 Case 1- (Re = 1000)

Figure 4 and Figure 9 represents the variation of U-component velocity profile w.r.t 'y' along the centerline for Re=1000 and Re=400 respectively. The numerical results obtained using stream function vorticity approach has been compared/validated with results from Ghia et al and CFD analysis using FLUENT. The results are in excellent agreement with each other as shown in the figure below.

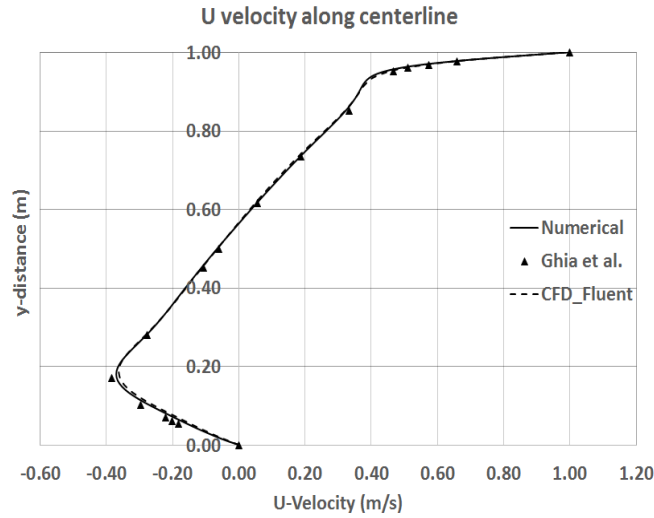


Figure 4 Comparison of U Velocity profile along x-centerline for RE=1000 (Numerical Code vs Ghia et al. vs CFD analysis)

Similar comparison for V-component velocity profile w.r.t 'x' along the centerline is compared in Figure 5 and 10 for Re=1000 and Re=400 respectively. The numerical code results are in excellent agreement with CFD solution and Ghia et al results.

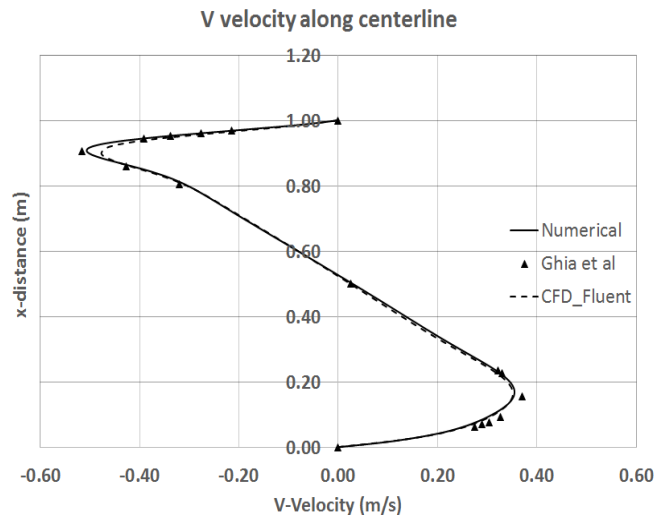


Figure 5 Comparison of V Velocity profile along y-centerline for RE=1000 (Numerical Code vs Ghia et al. vs CFD analysis)

CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach

The stream lines pattern, u and v component velocity contour, vorticity contours for Re=1000 and Re=400 are compared with Ghia et al and CFD in the figure 6,7,8,11,12,13 respectively. The stream patterns and velocity contours are in good qualitative and quantitate agreement with each other.

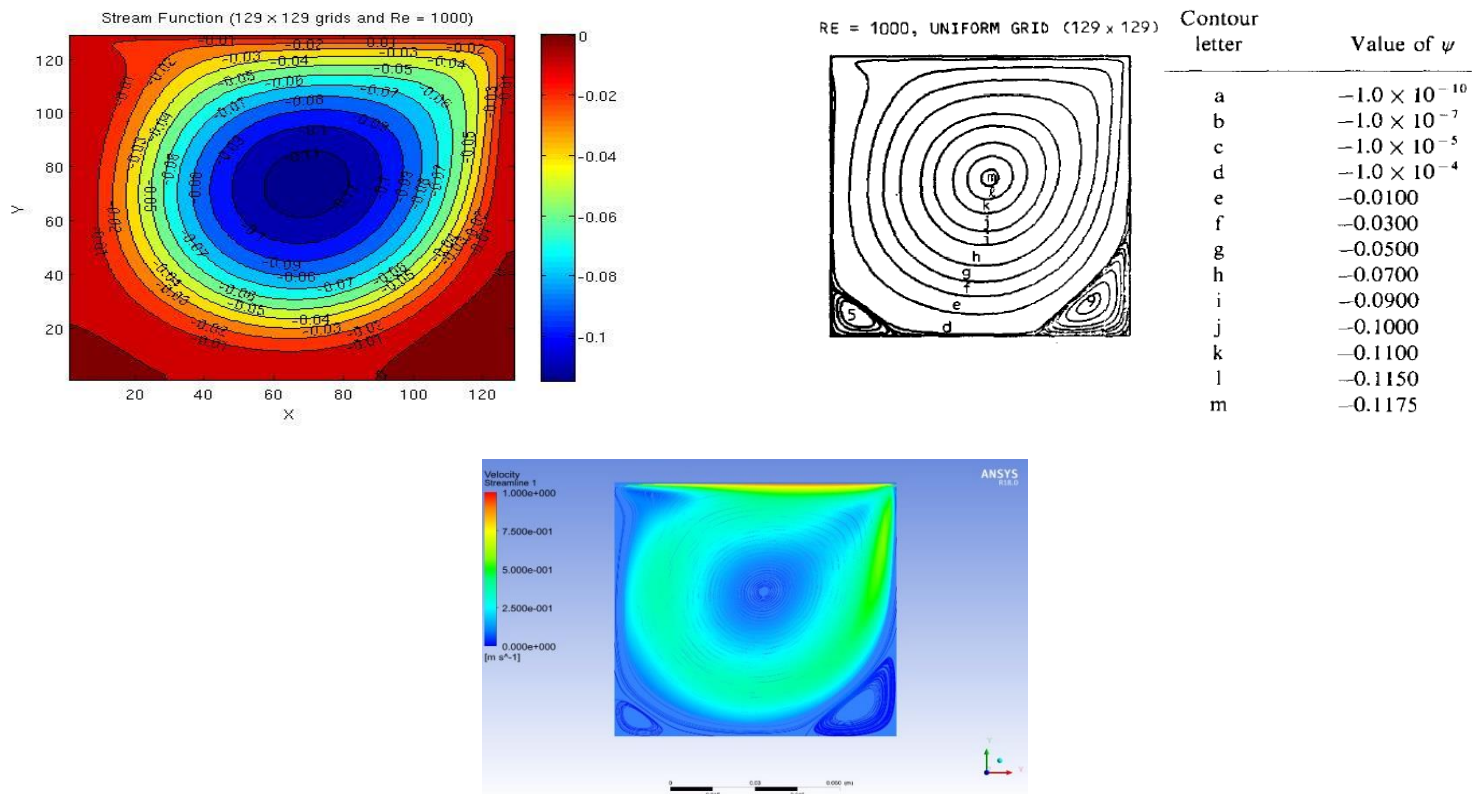


Figure 6 Comparison of Streamlines pattern for RE=1000 (Numerical Code vs Ghia et al. vs CFD analysis)

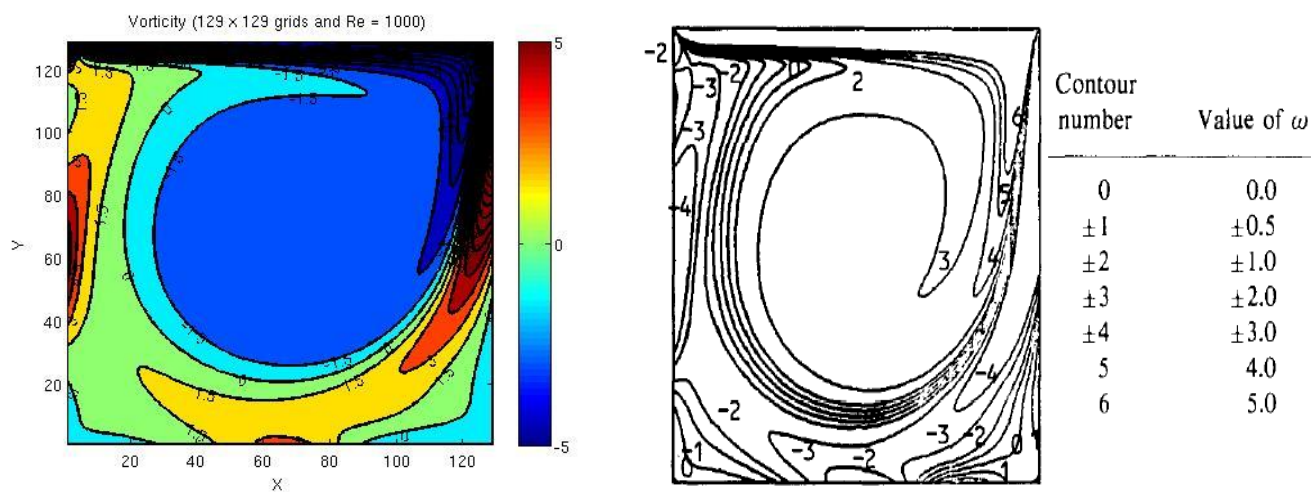


Figure 7 Comparison of Vorticity contours for RE=1000 (Numerical Code vs Ghia et al)

CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach

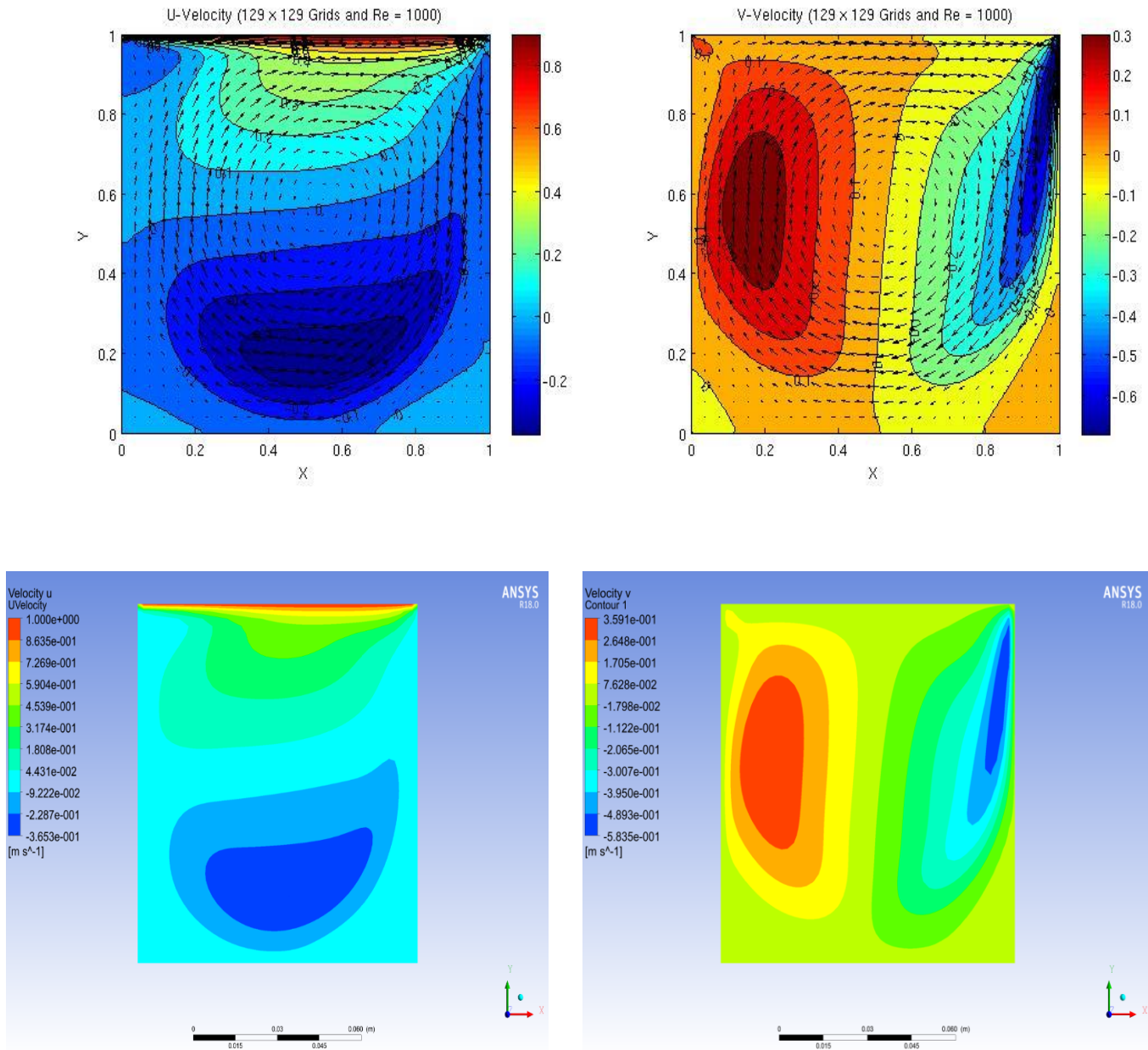


Figure 8 Comparison of U & V velocity contours for RE=1000 (Numerical Code vs CFD analysis)

6.1.2 Case 2- (Re = 400)

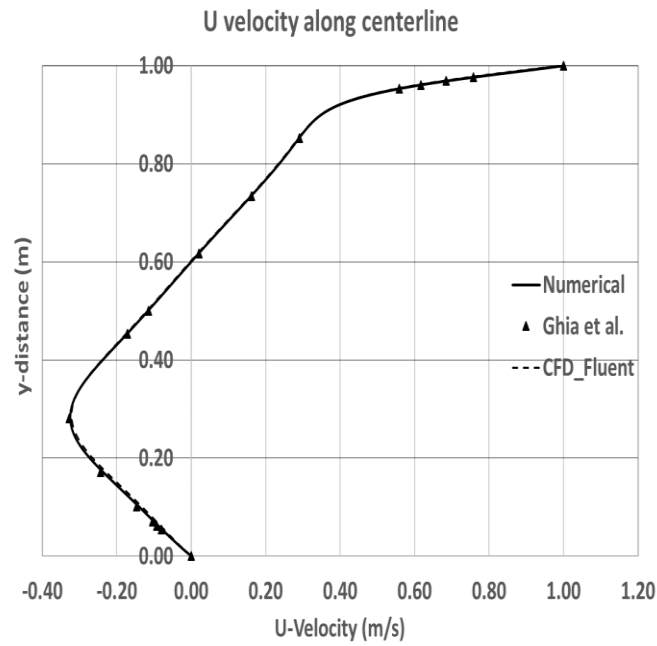


Figure 9 Comparison of U Velocity profile along x-centerline for RE =400 (Numerical Code vs Ghia et al. vs CFD analysis)

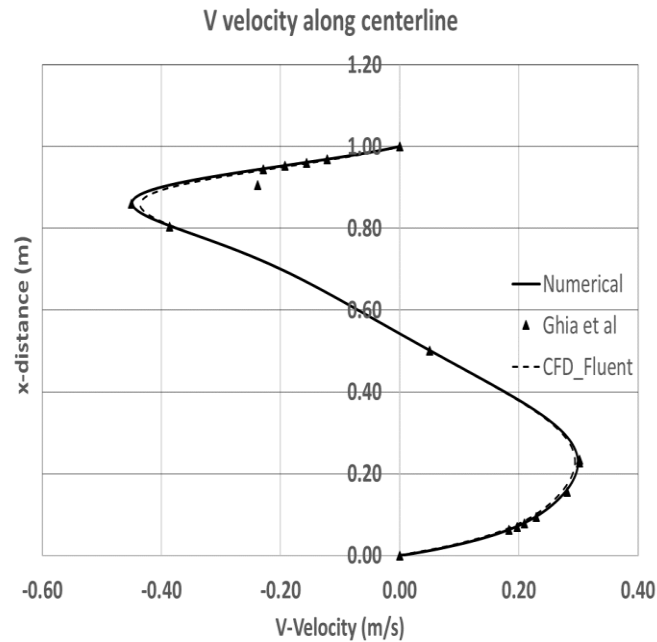


Figure 10 Comparison of V Velocity profile along y-centerline for RE=400 (Numerical Code vs Ghia et al. vs CFD analysis)

CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach

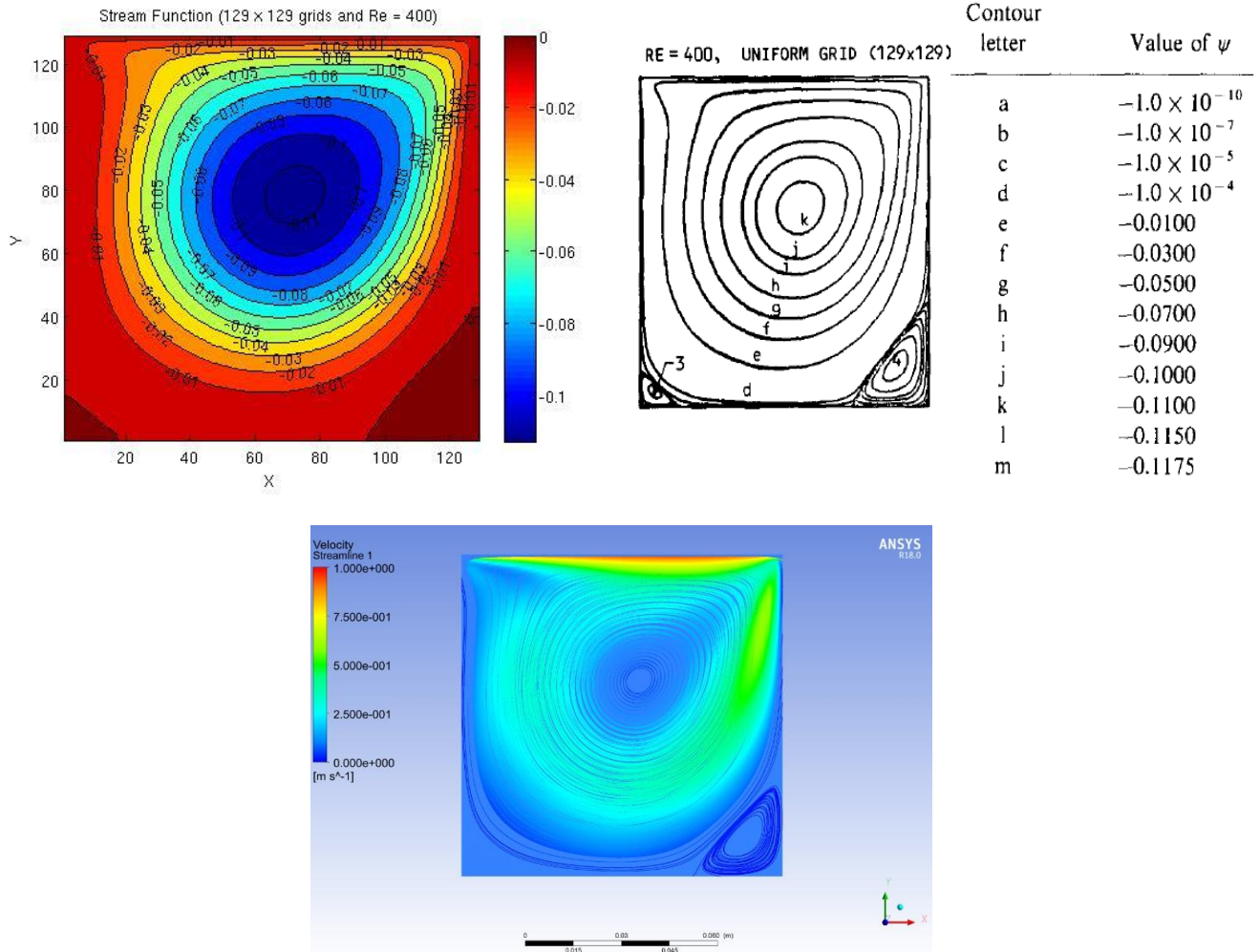


Figure 11 Comparison of Streamlines pattern for RE=400 (Numerical Code vs Ghia et al. vs CFD analysis)

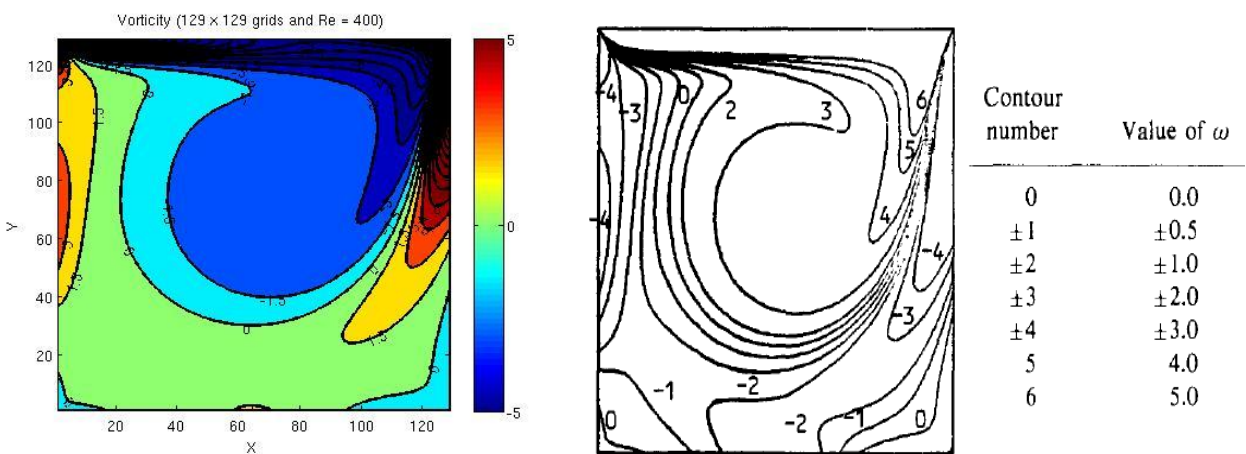


Figure 12 Comparison of Vorticity contours for RE=400 (Numerical Code vs Ghia et al)

CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach

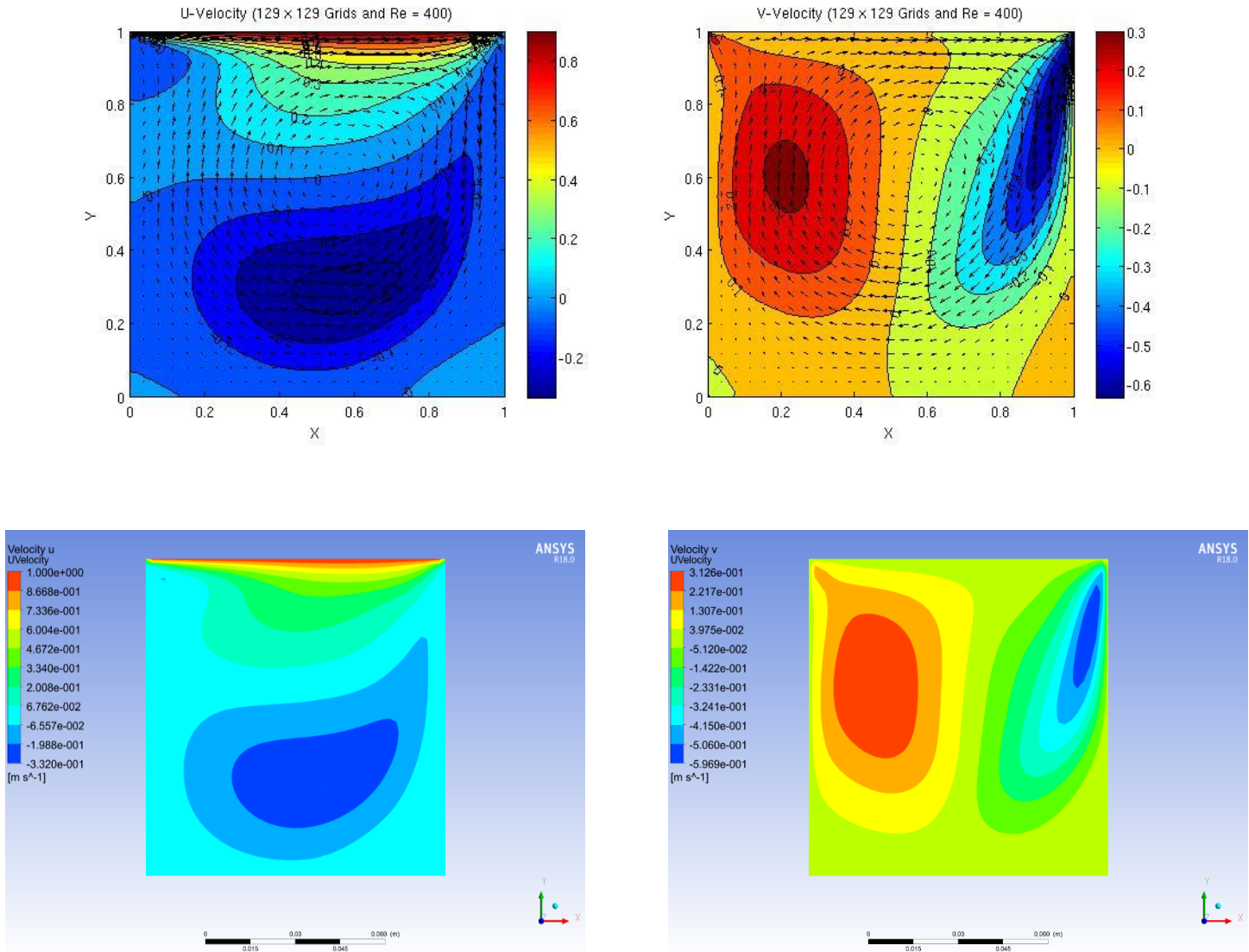
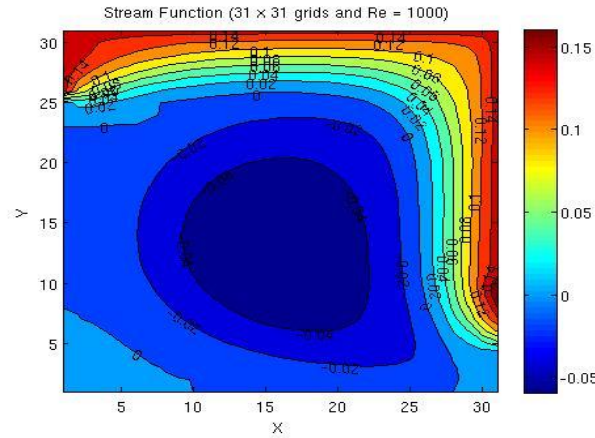


Figure 13 Comparison of U & V velocity contours for RE=400 (Numerical Code vs CFD analysis)

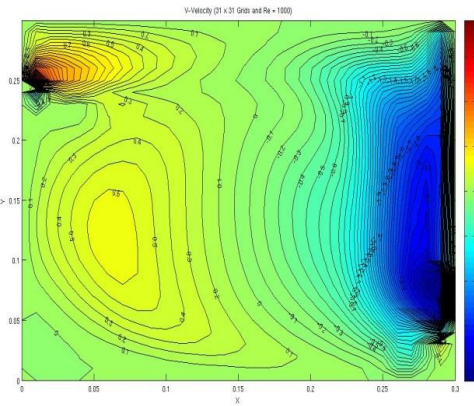
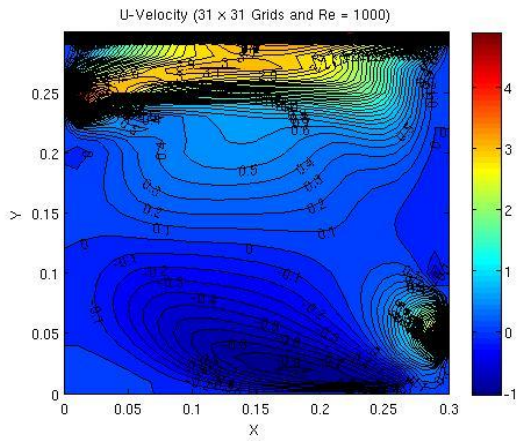
6.2 Lid Driven Cavity with inlet & outlet ports (Results for RE=1000):

The results for Lid driven cavity with inlet and outlet ports are presented in Figure 14 and 15. The streamline patterns in the Figure 14 (a) are in good qualitative agreement in comparison stream lines pattern presented in *Computational Fluid Dynamics Vol I* by Klaus A. Hoffmann and Steve T. Chiang in pg.no 351. Figure 15 represents U and V component velocities along centerline for Re =1000.

CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach



(a)



(b)

Figure 14 Stream Function, U and V Contours for Lid Driven with Open flow channel for $Re = 1000$

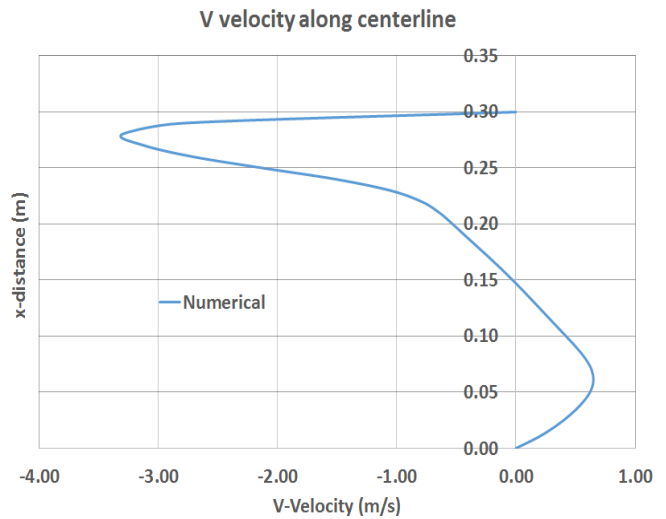
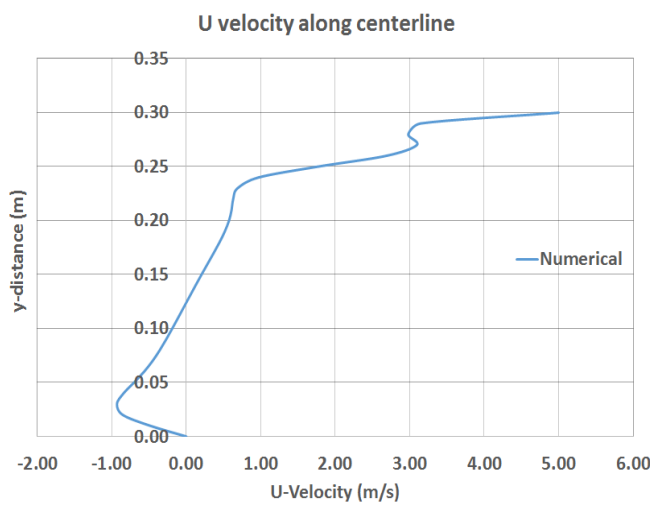


Figure 15 U & V velocities along centerline for $Re=1000$ (Numerical Code)

7 Appendix

7.1 Fortran Code (Lid driven closed cavity)

```

!*****
SUBROUTINE READ_INPUTS (L, H, NX, NY, J1, J2, J3, J4, DT, T, UP, RE, DX, DY, X, Y, U, V, SF, W, P, RSF, RW, PRHS)
IMPLICIT NONE
DOUBLE PRECISION :: L, H, DT, T, UP, RE
INTEGER :: NX, NY, J1, J2, J3, J4
DOUBLE PRECISION :: DX,DY
DOUBLE PRECISION, ALLOCATABLE :: X(:),Y(:)
DOUBLE PRECISION, ALLOCATABLE :: U(:,,:), V(:,,:), SF(:,,:), W(:,,:), RSF(:,,:), RW(:,,:), P(:,,:), PRHS(:,,:)
INTEGER :: I,J

CHARACTER*1000 :: DUMMYLINE

OPEN (UNIT=01,FILE='AM16D025.In',STATUS='OLD')

READ (01,*) DUMMYLINE, L
READ (01,*) DUMMYLINE, H
READ (01,*) DUMMYLINE, NX
READ (01,*) DUMMYLINE, NY
READ (01,*) DUMMYLINE, J1
READ (01,*) DUMMYLINE, J2
READ (01,*) DUMMYLINE, J3
READ (01,*) DUMMYLINE, J4
READ (01,*) DUMMYLINE, DT
READ (01,*) DUMMYLINE, T
READ (01,*) DUMMYLINE, UP
READ (01,*) DUMMYLINE, RE

ALLOCATE (X(NX))
ALLOCATE (Y(NY))
ALLOCATE (U(NX,NY))
ALLOCATE (V(NX,NY))
ALLOCATE (SF(NX,NY))
ALLOCATE (W(NX,NY))
ALLOCATE (RSF(NX,NY))
ALLOCATE (RW(NX,NY))
ALLOCATE (P(NX,NY))
ALLOCATE (PRHS(NX,NY))

DX = L/(NX-1)
DY = H/(NY-1)
DO I=1,NX
    X(I) = (I-1)*DX
ENDDO
DO J=1,NY
    Y(J) = (J-1)*DY
ENDDO
U = 0.0d0
V = 0.0d0
SF = 0.0d0
W = 0.0d0
RW = 0.0d0
RSF = 0.0d0
PRHS = 0.0d0
P = 0.0d0
DO I=1,NX
    U(I,NY) = UP
ENDDO

END SUBROUTINE
!*****
PROGRAM LID_DRIVEN_CAVITY_STREAM_FUNCTION_VORTICITY_APPROACH
IMPLICIT NONE

DOUBLE PRECISION :: L, H, DT, T, UP, RE
INTEGER :: NX, NY, J1, J2, J3, J4, K
DOUBLE PRECISION :: DX,DY

```


CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach

```

DOUBLE PRECISION, ALLOCATABLE :: X(:),Y(:)
DOUBLE PRECISION, ALLOCATABLE :: U(:,,:), V(:,,:), SF(:,,:), W(:,,:), P(:,,:), RSF(:,,:), RW(:,,:), SF_OLD(:,,:), PRHS(:,,:), PNEW(:,,:), W_OLD(:,,:)
INTEGER :: I,J, NUM_TIMESTEPS, ITER, B, A, C
DOUBLE PRECISION :: ERROR, ITC, ERR, ERR1
DOUBLE PRECISION, PARAMETER :: ESF = 1E-5
DOUBLE PRECISION, PARAMETER :: RF = 1.5
DOUBLE PRECISION :: TERM1, TERM2, TERM3, TERM4, SF_CONST,ERRW, ERRSF
CHARACTER*1000 :: XX,Z
character(len=8) :: fmt ! format descriptor

REAL :: START, FINISH
SF_CONST = 0;

CALL READ_INPUTS (L, H, NX, NY, J1, J2, J3, J4, DT, T, UP, RE, DX, DY, X, Y, U, V, SF, W, P, RSF, RW, PRHS)

ALLOCATE (SF_OLD(NX,NY))
ALLOCATE (W_OLD(NX,NY))
ALLOCATE (PNEW(NX,NY))

NUM_TIMESTEPS = T/DT
ERROR = 100.0d0
ITC = 0
CALL CPU_TIME(START)
DO WHILE((ITC.LT.NUM_TIMESTEPS))
    W_OLD = W
    DO I=2,NX-1
        DO J=2,NY-1
            TERM1 = (W(I+1,J)-2.0D0*W(I,J)+W(I-1,J))/(DX*DX)
            TERM2 = (W(I,J+1)-2.0D0*W(I,J)+W(I,J-1))/(DY*DY)
            TERM3 = (U(I+1,J)*W(I+1,J)-U(I-1,J)*W(I-1,J))/(2.0D0*DX)
            TERM4 = (V(I,J+1)*W(I,J+1)-V(I,J-1)*W(I,J-1))/(2.0D0*DY)
            RW(I,J) = (TERM1+TERM2)/RE-TERM3-TERM4
            W(I,J) = W(I,J)+DT*RW(I,J)
        ENDDO
    ENDDO
    DO ITER = 1, 1000
        SF_OLD=SF
        DO I = 2 , NX-1
            DO J = 2 , NY-1
                SF (I,J) = (RF/4)*((W(I,J)*(DX*DX))+SF(I+1,J)+SF(I,J+1)+SF(I-1,J)+SF(I,J-1))+(1-RF)*SF(I,J)
            ENDDO
        ENDDO
        ERR = 0.0
        DO I = 1 , NX
            DO J = 1 , NY
                ERR = ERR+ABS(SF_OLD(I,J)-SF(I,J))
            ENDDO
        ENDDO
        IF (ERR .LE. 0.001) THEN
            EXIT
        ENDIF
    ENDDO

    DO J=2,NY-1
        SF(2,J) = 0.25d0*SF(3,J)
        SF(NX-1,J) = 0.25d0*SF(NX-2,J)
    ENDDO
    DO I=2,NX-1
        SF(I,2) = 0.25d0*SF(I,3)
        SF(I,NY-1) = 0.25d0*(SF(I,NY-2)-2.0d0*DY)
    ENDDO

    DO I = 1 , NX
        W (I,1) = (SF_CONST-2*SF(I,2))/(DY*DY) !BOTTOMWALL
        W (I,NY) = -2*((SF(I,NY-1)-SF_CONST)/(DY*DY)+(UP/DY)) !TOPWALL
    ENDDO

    DO J = 2 , J1
        W (1,J) = 2*(SF_CONST-SF(2,J))/(DX*DX)
    ENDDO
    DO J = J1+1 , J2
        W (1,J) = 2*(SF_CONST-SF(2,J))/(DX*DX)
    ENDDO

```

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```

DO J = J2+1 , NY-1
  W (1,J) = 2*(SF_CONST-SF(2,J))/(DX*DX)
ENDDO
!RIGHTWALL
DO J = 2 , J3
  W (NX,J) = 2*(SF_CONST-SF(NX-1,J))/(DX*DX)
ENDDO
DO J = J3+1 , J4
  W (NX,J) = 2*(SF_CONST-SF(NX-1,J))/(DX*DX)
ENDDO
DO J = J4+1 , NY-1
  W (NX,J) = 2*(SF_CONST-SF(NX-1,J))/(DX*DX)
ENDDO

DO J=1,NY
  U(1,J) = 0.0d0
  U(NX,J) = 0.0d0
  V(1,J) = 0.0d0
  V(NX,J) = 0.0d0
ENDDO
DO I=2,NX-1
  U(I,1) = 0.0d0
  V(I,1) = 0.0d0
  U(I,NY) = UP
  V(I,NY) = 0.0d0
ENDDO

DO I=2,NX-1
  DO J=2,NY-1
    U(I,J) = 0.5d0*(SF(I,J+1)-SF(I,J-1))/DY
    V(I,J) = -0.5d0*(SF(I+1,J)-SF(I-1,J))/DX
  ENDDO
ENDDO

DO I=2,NX-1
  PNEW = P
  DO J=2,NY-1
    PRHS(I,J) = (((SF(I-1,J)-2*SF(I,J)+SF(I+1,J))/(DX*DX))*((SF(I,J-1)-2*SF(I,J)+SF(I,J+1))/(DY*DY)))- (SF(I+1,J+1)-SF(I+1,J-1)-SF(I-1,J+1)+SF(I-1,J-1))/(4*(DX*DY))
    P(I,J) = (0.25*(PNEW(I+1,J)+PNEW(I-1,J) + PNEW(I,J+1)+PNEW(I,J-1))- 0.5*((PRHS(I,J)*DX**2*DY**2)));
  ENDDO
ENDDO

ITC = ITC+1
ERR1 = 0.0
DO I = 1 , NX
  DO J = 1 , NY
    ERR1 = ERR1+ABS(W_OLD(I,J)-W(I,J))
  ENDDO
ENDDO
IF ((ERR1 .LE. 0.002) .AND. (ITC .GE. 5) )THEN
  EXIT
ENDIF

ENDDO

CALL CPU_TIME(FINISH)
OPEN (UNIT=10,FILE='TIME.DAT',STATUS='UNKNOWN')
OPEN (UNIT=2,FILE='VX.DAT',STATUS='UNKNOWN')
OPEN (UNIT=3,FILE='UY.DAT',STATUS='UNKNOWN')
OPEN (UNIT=4,FILE='SF.DAT',STATUS='UNKNOWN')
OPEN (UNIT=5,FILE='W.DAT',STATUS='UNKNOWN')
OPEN (UNIT=6,FILE='U.DAT',STATUS='UNKNOWN')
OPEN (UNIT=7,FILE='V.DAT',STATUS='UNKNOWN')
OPEN (UNIT=8,FILE='P.DAT',STATUS='UNKNOWN')
OPEN (UNIT=9,FILE='T.DAT',STATUS='UNKNOWN')
DO I = 1 , NX
  WRITE (2,*) X(I), V(I,(NY+1)/2)
END DO
DO J = 1 , NY
  WRITE (3,*) Y(J), U((NX+1)/2,J)
END DO
DO I=1,NX

```

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```

DO J=1,NY
  WRITE (4,*) X(I), X(J), SF(I,J)
  WRITE (5,*) X(I), X(J), W(I,J)
  WRITE (6,*) X(I), X(J), U(I,J)
  WRITE (7,*) X(I), X(J), V(I,J)
  WRITE (8,*) X(I), X(J), P(I,J)
ENDDO
ENDDO
WRITE (10, '(A, 5X, E13.3)') 'TIME.TXT', FINISH-START

DO I = 1, 560
  CLOSE (I)
ENDDO

END PROGRAM LID_DRIVEN_CAVITY_STREAM_FUNCTION_VORTICITY_APPROACH

```

7.2 Fortran Code (lid driven cavity with inlet & outlet ports)

```

! *****
SUBROUTINE READ_INPUTS (L, H, NX, NY, J1, J2, J3, J4, DT, T, UP, RE, DX, DY, X, Y, U, V, SF, W, P, RSF,
RW, PRHS)
IMPLICIT NONE
DOUBLE PRECISION :: L, H, DT, T, UP, RE
INTEGER :: NX, NY, J1, J2, J3, J4
DOUBLE PRECISION :: DX, DY
DOUBLE PRECISION, ALLOCATABLE :: X(:), Y(:)
DOUBLE PRECISION, ALLOCATABLE :: U(:, :), V(:, :), SF(:, :), W(:, :), RSF(:, :), RW(:, :), P(:, :), PRHS(:, :)
INTEGER :: I, J

CHARACTER*1000 :: DUMMYLINE

OPEN (UNIT=999, FILE='AM16D025.In', STATUS='OLD')

READ (999, *) DUMMYLINE, L
READ (999, *) DUMMYLINE, H
READ (999, *) DUMMYLINE, NX
READ (999, *) DUMMYLINE, NY
READ (999, *) DUMMYLINE, J1
READ (999, *) DUMMYLINE, J2
READ (999, *) DUMMYLINE, J3
READ (999, *) DUMMYLINE, J4
READ (999, *) DUMMYLINE, DT
READ (999, *) DUMMYLINE, T
READ (999, *) DUMMYLINE, UP
READ (999, *) DUMMYLINE, RE

ALLOCATE (X (NX))
ALLOCATE (Y (NY))
ALLOCATE (U (NX, NY))
ALLOCATE (V (NX, NY))
ALLOCATE (SF (NX, NY))
ALLOCATE (W (NX, NY))
ALLOCATE (RSF (NX, NY))
ALLOCATE (RW (NX, NY))
ALLOCATE (P (NX, NY))
ALLOCATE (PRHS (NX, NY))

DX = L / (NX-1)
DY = H / (NY-1)
DO I=1, NX
  X(I) = (I-1) * DX
ENDDO
DO J=1, NY
  Y(J) = (J-1) * DY
ENDDO
U = 0.0d0
V = 0.0d0
SF = 0.0d0
W = 0.0d0
RW = 0.0d0
RSF = 0.0d0
PRHS = 0.0d0

```

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```

P = 0.0d0
DO I=1,NX
    U(I,NY) = UP
ENDDO

END SUBROUTINE
!*****
*****
PROGRAM LID_DRIVEN_CAVITY_STREAM_FUNCTION_VORTICITY_APPROACH
IMPLICIT NONE

DOUBLE PRECISION :: L, H, DT, T, UP, RE
INTEGER :: NX, NY, J1, J2, J3, J4, K
DOUBLE PRECISION :: DX,DY, SF1, SF2
DOUBLE PRECISION, ALLOCATABLE :: X(:),Y(:)
DOUBLE PRECISION, ALLOCATABLE :: U(:, :), V(:, :), SF(:, :), W(:, :), P(:, :), RSF(:, :), RW(:, :), SF_OLD(:, :),
PRHS(:, :), PNEW(:, :), W_OLD(:, :)
INTEGER :: I,J, NUM_TIMESTEPS, ITER, B, A, C
DOUBLE PRECISION :: ERROR, ITC, ERR, ERR1
DOUBLE PRECISION, PARAMETER :: ESF = 1E-5
DOUBLE PRECISION, PARAMETER :: RF = 1.5
DOUBLE PRECISION :: TERM1, TERM2, TERM3, TERM4, SF_CONST,ERRW, ERRSF
CHARACTER*1000 :: XX,Z
character(len=8) :: fmt ! format descriptor

REAL :: START, FINISH
SF_CONST = 0;

SF1 = 0.0;
SF2 = 0.15;

CALL READ_INPUTS (L, H, NX, NY, J1, J2, J3, J4, DT, T, UP, RE, DX, DY, X, Y, U, V, SF, W, P, RSF, RW, PRHS)

ALLOCATE (SF_OLD(NX,NY))
ALLOCATE (W_OLD(NX,NY))
ALLOCATE (PNEW(NX,NY))

DO I=1,NX
    U(I,NY) = UP
ENDDO

NUM_TIMESTEPS = T/DT
ITC = 0
CALL CPU_TIME(START)
DO WHILE ((ITC.LT.NUM_TIMESTEPS))
    W_OLD = W
    !-----START:STREAM FUNCTION BC's-----
    ---
    !LEFTWALL
    DO J = 1 , J1-1
        !SF(2,J) = 0.25d0*(SF(3,J) + 3*SF1)
        !SF(1,J) = 1/3 * (4*SF(2,J)-SF(3,J))
        SF(1,J) = SF1
    ENDDO
    DO J = J1 , J2
        SF(1,J) = 1/3 * (4*SF(2,J)-SF(3,J))
    ENDDO
    DO J = J2+1 , NY
        !SF(2,J) = 0.25d0*(SF(3,J) + 3*SF2)
        SF(1,J) = SF2
    ENDDO

    !RIGHTWALL
    DO J = 1 , J3-1
        !SF(NX-1,J) = 0.25d0*(SF(NX-2,J)+3*SF1)
        SF(NX,J) = SF1
    ENDDO
    DO J = J3 , J4
        SF(NX,J) = - SF(NX-2,J) + 2*SF(NX-1,J)
    ENDDO
    DO J = J4+1 , NY
        !SF(NX-1,J) = 0.25d0*(SF(NX-2,J)+3*SF2)
        SF(NX,J) = SF2
    ENDDO

```

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```

DO I=2,NX-1
    SF(I,1) = SF1 !BOTTOM WALL
    SF(I,NY) = SF2 !TOP WALL
ENDDO
!-----END:STREAM FUNCTION BC's-----

DO ITER = 1, 1000
    SF_OLD=SF
    DO I = 2, NX-1
        DO J = 2, NY-1
            SF(I,J) = (RF/4) * ((W(I,J) * (DX*DX)) + SF(I+1,J) + SF(I,J+1) + SF(I-1,J) + SF(I,J-1)) + (1-RF) * SF(I,J)
        ENDDO
    ENDDO
    ERR = 0.0
    DO I = 1, NX
        DO J = 1, NY
            ERR = ERR + ABS(SF_OLD(I,J) - SF(I,J))
        ENDDO
    ENDDO
    IF (ERR .LE. 0.001) THEN
        EXIT
    ENDIF
ENDDO

!-----START:VORTICITY BC's-----

DO I = 2, NX-1
    W(I,1) = 2 * (SF(I,1) - SF(I,2)) / (DY*DY) !BOTTOMWALL
    W(I,NY) = -2 * ((SF(I,NY-1) - SF(I,NY)) / (DY*DY) + (UP/DY)) !TOPWALL
ENDDO

DO J = 1, J1-1
    W(1,J) = 2 * (SF(1,J) - SF(2,J)) / (DX*DX)
ENDDO
DO J = J1, J2
    W(1,J) = (2 * (SF(1,J) - SF(2,J)) / (DX*DX)) - (SF(1,J+1) - 2 * SF(1,J) + SF(1,J-1)) / (DY*DY)
ENDDO
DO J = J2+1, NY
    W(1,J) = 2 * (SF(1,J) - SF(2,J)) / (DX*DX)
ENDDO
!RIGHTWALL
DO J = 1, J3
    W(NX,J) = 2 * (SF(NX,J) - SF(NX-1,J)) / (DX*DX)
ENDDO
DO J = J3, J4
    W(NX,J) = 1/3 * (4 * SF(NX-1,J) - SF(NX-2,J))
ENDDO
DO J = J4+1, NY
    W(NX,J) = 2 * (SF(NX,J) - SF(NX-1,J)) / (DX*DX)
ENDDO
!-----END:VORTICITY BC's-----

DO I=2,NX-1
    DO J=2,NY-1
        U(I,J) = 0.5d0 * (SF(I,J+1) - SF(I,J-1)) / DY
        V(I,J) = -0.5d0 * (SF(I+1,J) - SF(I-1,J)) / DX
    ENDDO
ENDDO

DO I=2,NX-1
    DO J=2,NY-1
        TERM1 = (W(I+1,J) - 2.0D0 * W(I,J) + W(I-1,J)) / (DX*DX)
        TERM2 = (W(I,J+1) - 2.0D0 * W(I,J) + W(I,J-1)) / (DY*DY)
        TERM3 = (U(I+1,J) * W(I+1,J) - U(I-1,J) * W(I-1,J)) / (2.0D0 * DX)
        TERM4 = (V(I,J+1) * W(I,J+1) - V(I,J-1) * W(I,J-1)) / (2.0D0 * DY)
        RW(I,J) = (TERM1 + TERM2) / RE - TERM3 - TERM4
        W(I,J) = W(I,J) + DT * RW(I,J)
    ENDDO
ENDDO

DO I=2,NX-1
    PNEW = P
    DO J=2,NY-1

```

CFD Assignment – Lid Driven Cavity – Stream Function Vorticity Approach

```

      PRHS(I,J) = ((SF(I-1,J)-2*SF(I,J)+SF(I+1,J))/(DX*DX))*((SF(I,J-1)-
2*SF(I,J)+SF(I,J+1))/(DY*DY))- (SF(I+1,J+1)-SF(I+1,J-1)-SF(I-1,J+1)+SF(I-1,J-1))/(4*(DX*DY))
      P(I,J) = (0.25*(PNEW(I+1,J)+PNEW(I-1,J) + PNEW(I,J+1)+PNEW(I,J-1))-
0.5*((PRHS(I,J)*DX**2*DY**2)));
      ENDDO
    ENDDO

    ITC = ITC+1
    ERR1 = 0.0
    DO I = 1 , NX
      DO J = 1 , NY
        ERR1 = ERR1+ABS(W_OLD(I,J)-W(I,J))
      ENDDO
    ENDDO
    IF ((ERR1 .LE. 0.002) .AND. (ITC .GE. 5) ) THEN
      EXIT
    ENDIF
  ENDDO

  CALL CPU_TIME(FINISH)
  OPEN (UNIT=10,FILE='TIME.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=2,FILE='VX.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=3,FILE='UY.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=4,FILE='SF.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=5,FILE='W.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=6,FILE='U.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=7,FILE='V.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=8,FILE='P.DAT',STATUS='UNKNOWN')
  OPEN (UNIT=9,FILE='T.DAT',STATUS='UNKNOWN')
  DO I = 1 , NX
    WRITE (2,*) X(I), V(I,(NY+1)/2)
  END DO
  DO J = 1 , NY
    WRITE (3,*) Y(J), U((NX+1)/2,J)
  END DO
  DO I=1,NX
    DO J=1,NY
      WRITE (4,*) X(I), X(J), SF(I,J)
      WRITE (5,*) X(I), X(J), W(I,J)
      WRITE (6,*) X(I), X(J), U(I,J)
      WRITE (7,*) X(I), X(J), V(I,J)
      WRITE (8,*) X(I), X(J), P(I,J)
    ENDDO
  ENDDO
  WRITE (10,'(A, 5X, E13.3)') 'TIME.TXT', FINISH-START

  DO I= 1 , 10
    CLOSE (I)
  ENDDO

END PROGRAM LID_DRIVEN_CAVITY_STREAM_FUNCTION_VORTICITY_APPROACH

```