# **Yogev Ofir - Software Engineer**

053-531-0520 | yogev282000@gmail.com | LinkedIn | GitHub | Website

#### **Profile**

I am a recent CS and Mathematics graduate, skilled in Java, C++, Python, and React Native, with strengths in full-stack development, problem-solving, and learning new technologies. Eager to tackle challenging projects, I have excellent communication skills, strong technical skills, attention to detail, and a self-driven approach to continuous improvement.

### **Skills**

- . Java, Python, C++, C, PHP, Windows, Linux
- React Native, TypeScript, Flutter, Node.js, React.js, JavaScript
- . Firebase, MongoDB, MySQL, SQL, Git

#### **Education**

### B.Sc Computer Science & Mathematics - Ariel University (GPA-85)

Sep 2022 - March 2025

- Relevant Coursework:
  - Data Structures, Algorithms, Software Engineering, Deep Learning
  - Communication Networks, Computability and Complexity, OOP

## Coursera - Deep Learning (GPA-96)

Sep 2023 - Oct 2023

Coursera - Meta React Specialization (GPA-100)

June 2023 - July 2023

## **Projects**

### (Mobile Application) - TechNaim - Real-Time Technician Tracking & Scheduling: link - TechNaim

- Created a full-stack end-to-end application aimed at enhancing field service operations.
- Developed a Node.js/Express, JavaScript backend paired with a React-Native frontend utilizing TypeScript.
- · Automated technician routing, dynamic schedule adjustments, and real-time location tracking using WebSockets.
- Integrated Google APIs to provide directions and traffic information.
- Designed an optimization algorithm for calculating precise ETAs and the quickest routes across various customer locations.

### Semantic Template Matching for UAV Localization: link - <u>UAV</u>

- Developed a hybrid framework combining deep semantic segmentation with classical template matching.
- Used a UNetFormer-based network to convert raw UAV images into semantic maps highlighting key features like roads and buildings.
- Leveraged UAV metadata for pre-alignment with a reference map.
- Applied a correlation-based template matching algorithm to accurately localize the UAV, even in GNSS-denied areas.

### (Mobile Application) - Secunity - Team Leader: link - Secunity

- Developed a cross-platform full-stack end-to-end application (iOS, Android, Web) for settlement security teams as part of Software Engineering course.
- Built the system using Flutter for the frontend and Firebase for the backend.
- Implemented authentication, real-time alerts, scheduling, and status updates within a modular, scalable architecture.

## **Military Service**

#### **Deputy Class Commander**

2018 - 2021

- Gained skills in managing classified equipment in an artillery battery.
- Streamlined communication between different command levels.
- Worked on the SHEDER HAM system.
- Demonstrated leadership by substituting for the team commander while operate in high-pressure environments.

#### **Additional**

Languages: English (fluent), Hebrew (native)