Bayesian neural nets

Estimating a predictive distribution

Why to care about uncertainty

- Cat / dog classifier, classify an hippopotamus
- Reliability in steering control
- Physics simulator prediction
- Minimising action randomness when connected to a reward

NN with dropout

$$\boldsymbol{h} = f(\boldsymbol{W}_h \boldsymbol{x} \odot \boldsymbol{\delta}_x + \boldsymbol{b}_h)$$

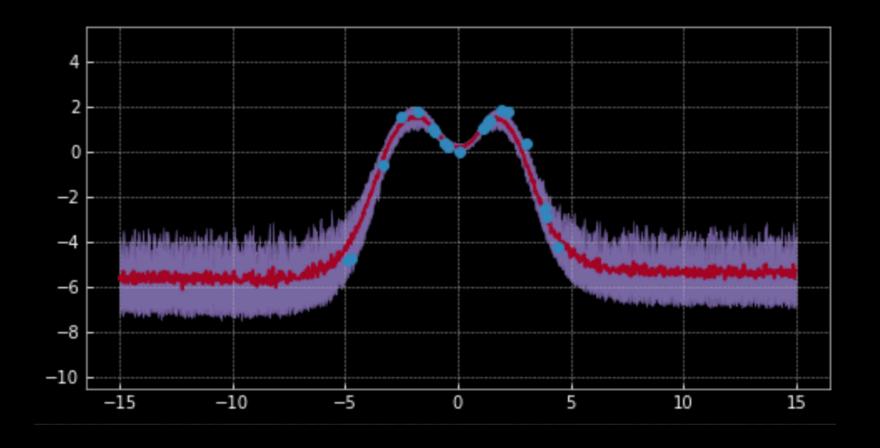
$$\hat{\boldsymbol{y}} = g(\boldsymbol{W}_y \boldsymbol{h} \odot \boldsymbol{\delta}_h + \boldsymbol{b}_y)$$

$$\hat{m{y}}$$
 $\hat{m{y}}$ $\hat{m{y}}$ $\hat{m{y}}$ $\hat{m{y}}$ $\hat{m{x}}$ $\hat{m{\delta}}_{x} \in \mathbb{R}^{n}$ $\hat{m{h}}, \pmb{\delta}_{h} \in \mathbb{R}^{d}$ $\hat{m{h}}, \pmb{\delta}_{h} \in \mathbb{R}^{d}$ $\hat{m{y}} \in \mathbb{R}^{K}$ $\hat{m{w}}_{h} \in \mathbb{R}^{d \times n}$ $\hat{m{w}}_{h} \in \mathbb{R}^{d \times n}$ $\hat{m{w}}_{h} \in \mathbb{R}^{d \times n}$ $\hat{m{w}}_{y} \in \mathbb{R}^{K \times d}$ $\hat{m{w}}_{y} \in \mathbb{R}^{K \times d}$

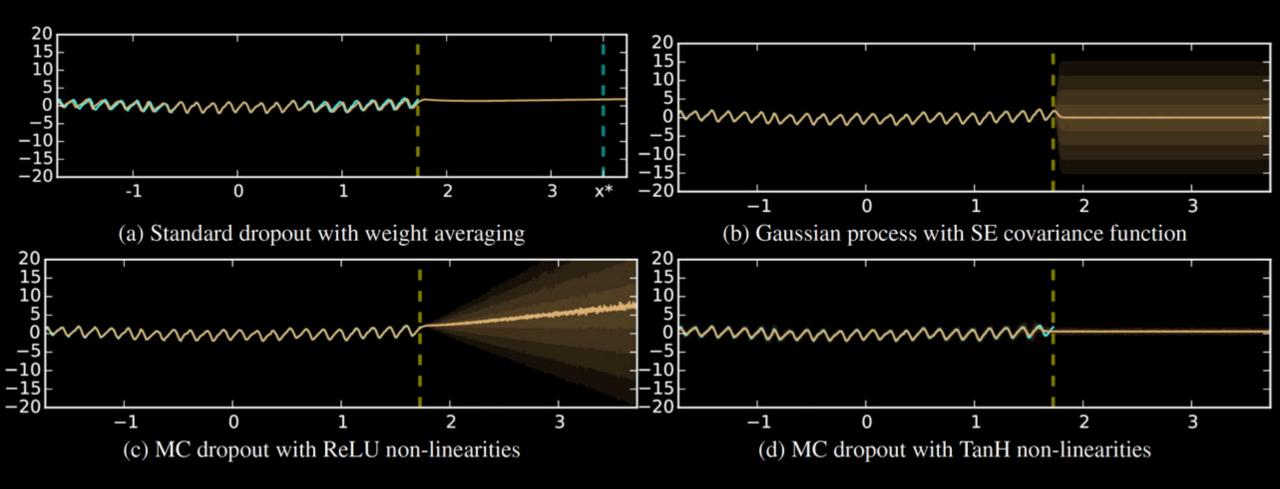
 $f(\cdot), g(\cdot): (\cdot)^+, \sigma(\cdot), \tanh(\cdot), \operatorname{softmax}(\cdot)$

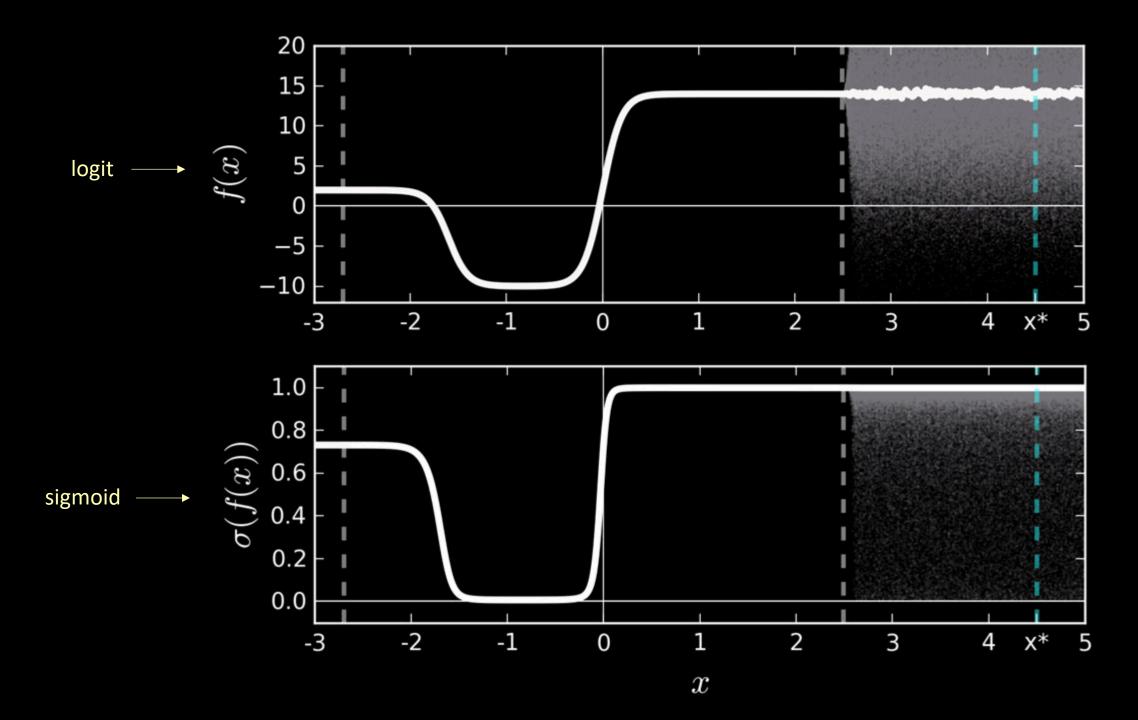
Regression (I)

See notebook demo



Regression (II)





classification Multi-class

