

# **VISVESVARAYA TECHNOLOGICAL UNIVERSITY**

**“JnanaSangama”, Belgaum -590014, Karnataka.**



## **LAB REPORT On**

### **ANALYSIS AND DESIGN OF ALGORITHMS (23CS4PCADA)**

**Submitted by**

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**in partial fulfillment for the award of the degree of  
BACHELOR OF ENGINEERING  
in  
COMPUTER SCIENCE AND ENGINEERING**



**B.M.S. COLLEGE OF ENGINEERING  
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This is to certify that the Lab work entitled “**ANALYSIS AND DESIGN OF ALGORITHMS**” carried out by Dama Yohitesh Naveen Sai (**IBM23CS085**), who is bonafide student of **B. M. S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum during the year 2024-25. The Lab report has been approved as it satisfies the academic requirements in respect of Analysis and Design of Algorithms Lab - (**23CS4PCADA**) work prescribed for the said degree.

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**Course outcomes:**

CO1	Analyze time complexity of Recursive and Non-recursive algorithms using asymptotic notations.
CO2	Apply various design techniques for the given problem.
CO3	Apply the knowledge of complexity classes P, NP, and NP-Complete and prove certain problems are NP-Complete
CO4	Design efficient algorithms and conduct practical experiments to solve problems.

# Lab program 1

**a. Write a program to obtain the Topological ordering of vertices in a given digraph.**

**Code :**

```
#include<stdio.h>

#include<stdlib.h>

#define SIZE 100

void topological_sort(int graph[SIZE][SIZE],int n){
    int indegree[n];

    for(int i = 0; i<n; i++) indegree[i]=0;

    for(int i = 0; i<n;i++){
        for(int j = 0; j<n;j++){
            if(graph[i][j]==1){
                indegree[j]++;
            }
        }
    }

    int source[n];
    int front = 0;
    int last = 0;

    for(int i = 0; i<n; i++){
        if(indegree[i]==0) source[last++]=i;
    }

    int sorted[n];
    int ind = 0;
```

```

while(front<last){
    int temp = source[front++];
    sorted[ind++]=temp;
    for(int i = 0; i<n; i++){
        if(graph[temp][i]==1){
            indegree[i]--;
            if(indegree[i]==0)source[last++]=i;
        }
    }
}

if(ind == n){
    printf("Topological Sorted Order is :");
    for(int i = 0; i<n;i++){
        printf(" %d ",sorted[i]);
    }
    printf("\n");
}
else{
    printf("Topological Sorting not possible.\n");
}

}

int main(){
    int graph[SIZE][SIZE];
    int n;

    printf("Enter Number of Vertices: ");

```

```

scanf("%d",&n);

printf("Enter adjacency matric:\n");

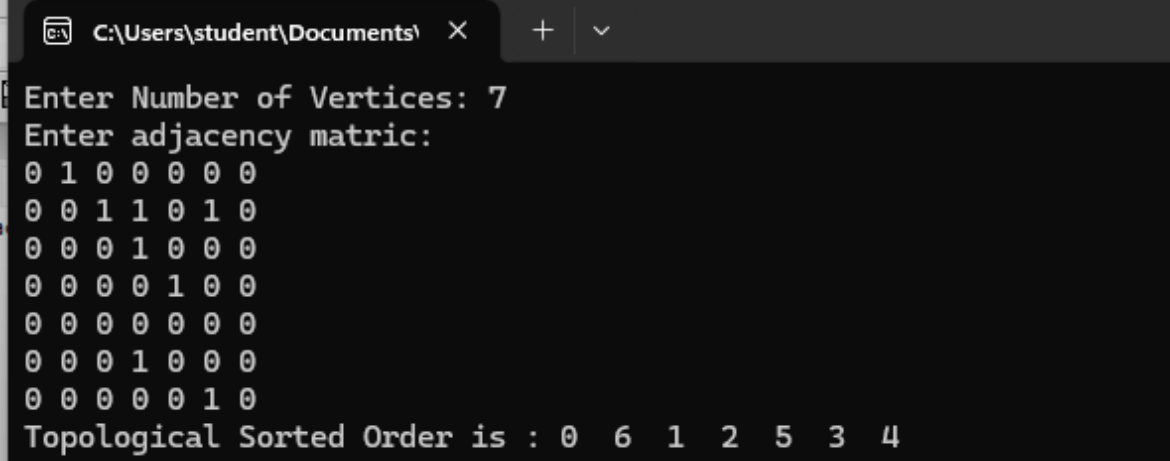
for(int i = 0;i<n;i++){
    for(int j = 0; j<n;j++){
        scanf("%d",&graph[i][j]);
    }
}

topological_sort(graph,n);

return 0;
}

```

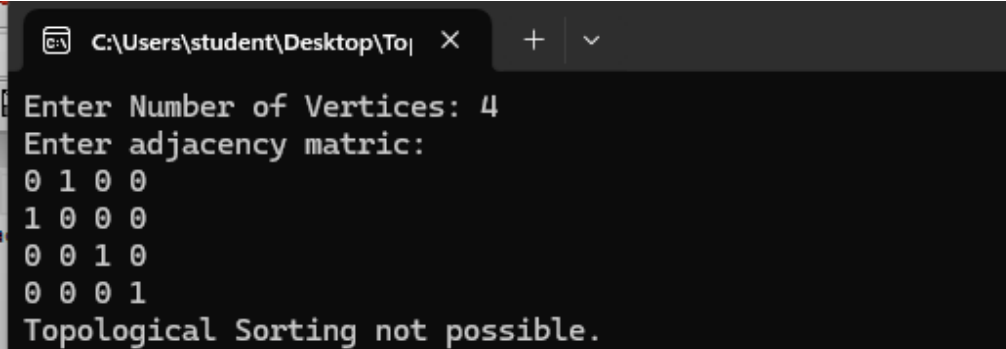
### Output:



```

C:\Users\student\Documents\ X + v
Enter Number of Vertices: 7
Enter adjacency matric:
0 1 0 0 0 0 0
0 0 1 1 0 1 0
0 0 0 1 0 0 0
0 0 0 0 1 0 0
0 0 0 0 0 0 0
0 0 0 1 0 0 0
0 0 0 0 0 1 0
Topological Sorted Order is : 0 6 1 2 5 3 4

```



```

C:\Users\student\Desktop\ToI X + v
Enter Number of Vertices: 4
Enter adjacency matric:
0 1 0 0
1 0 0 0
0 0 1 0
0 0 0 1
Topological Sorting not possible.

```

## b. LeetCode Program related to Topological sorting

### LeetCode 851. Loud and Rich

There is a group of  $n$  people labeled from 0 to  $n - 1$  where each person has a different amount of money and a different level of quietness.

You are given an array `richer` where `richer[i] = [ai, bi]` indicates that  $a_i$  has more money than  $b_i$  and an integer array `quiet` where `quiet[i]` is the quietness of the  $i$ th person. All the given data in `richer` are logically correct (i.e., the data will not lead you to a situation where  $x$  is richer than  $y$  and  $y$  is richer than  $x$  at the same time).

Return an integer array `answer` where `answer[x] = y` if  $y$  is the least quiet person (that is, the person  $y$  with the smallest value of `quiet[y]`) among all people who definitely have equal to or more money than the person  $x$ .

### Submission Code:

```
#define MAXN 510
```

```
int* loudAndRich(int** richer, int richerSize, int* richerColSize, int* quiet, int quietSize,
int* returnSize) {
    int n = quietSize;
    int graph[MAXN][MAXN] = {0};
    int indegree[MAXN] = {0};
    int answer[MAXN];
    int queue[MAXN], front = 0, rear = 0;

    for (int i = 0; i < richerSize; i++) {
        int a = richer[i][0], b = richer[i][1];
        if (!graph[a][b]) {
            graph[a][b] = 1;
            indegree[b]++;
        }
    }

    for (int i = 0; i < n; i++) {
        answer[i] = i;
        if (indegree[i] == 0) {
            queue[rear++] = i;
        }
    }

    while (front < rear) {
        int u = queue[front++];
```



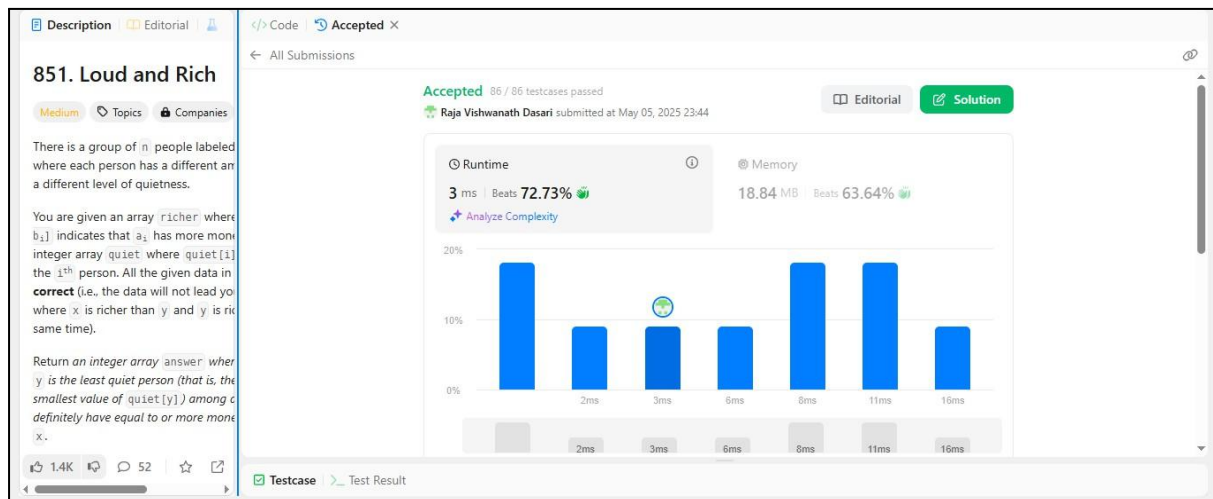
```

for (int v = 0; v < n; v++) {
    if (graph[u][v]) {
        if (quiet[answer[u]] < quiet[answer[v]]) {
            answer[v] = answer[u];
        }
        indegree[v]--;
        if (indegree[v] == 0) {
            queue[rear++] = v;
        }
    }
}

int* result = (int*)malloc(n * sizeof(int));
for (int i = 0; i < n; i++) {
    result[i] = answer[i];
}
*returnSize = n;
return result;
}

```

## Result:



## Lab Program 2

**Implement Johnson Trotter algorithm to generate permutations.**

### Code:

```
#include<stdio.h>
#include<stdlib.h>
void swap(int *a, int *b){
    int temp = *a;
    *a = *b;
    *b = temp;
}
void print_perm(int p[],int n){
    printf("Permutation: ");
    for(int i = 0;i<n; i++){
        printf("%d ",p[i]);
    }
    printf("\n");
}
void johnson_trotter(int n){
    int p[n];
    int d[n];
    for(int i = 0;i<n;i++){
        p[i] = i+1;
        d[i] = -1;
    }
    print_perm(p,n);

    while(1){
        int largest_mob = -1;
        int largest_ind = -1;

        for(int i=0; i<n;i++){
            if(d[i] == -1 && i>0 && p[i]>p[i-1]){
                if(p[i]>largest_mob){
                    largest_mob = p[i];
                    largest_ind = i;
                }
            }
        }
        else if(d[i] == 1 && i<n-1 && p[i]>p[i+1]){
            if(p[i]>largest_mob){
                largest_mob = p[i];
            }
        }
    }
}
```

```

        largest_ind = i;
    }
}
}
if(largest_mob == -1) break;
int ind = largest_ind;
if(d[ind]==-1){
    swap(&p[ind],&p[ind-1]);
    swap(&d[ind],&d[ind-1]);
}
else if(d[ind]==1){
    swap(&p[ind],&p[ind+1]);
    swap(&d[ind],&d[ind+1]);
}
for(int j = 0;j<n;j++){
    if(p[j]>largest_mob){
        d[j]= d[j]*-1;
    }
}
print_perm(p,n);
}
}

int main(){
    int n;
    printf("Enter number of elements to be permuted: ");
    scanf("%d",&n);
    johnson_trotter(n);
}

```

## **Output:**

```

C:\Users\student\Desktop\Jol >
Enter number of elements to be permuted: 3
Permutation: 1 2 3
Permutation: 1 3 2
Permutation: 3 1 2
Permutation: 3 2 1
Permutation: 2 3 1
Permutation: 2 1 3

Process returned 0 (0x0)   execution time : 1.497 s
Press any key to continue.

```

```
C:\Users\student\Desktop\Jol X + v
Enter number of elements to be permuted: 4
Permutation: 1 2 3 4
Permutation: 1 2 4 3
Permutation: 1 4 2 3
Permutation: 4 1 2 3
Permutation: 4 1 3 2
Permutation: 1 4 3 2
Permutation: 1 3 4 2
Permutation: 1 3 2 4
Permutation: 3 1 2 4
Permutation: 3 1 4 2
Permutation: 3 4 1 2
Permutation: 4 3 1 2
Permutation: 4 3 2 1
Permutation: 3 4 2 1
Permutation: 3 2 4 1
Permutation: 3 2 1 4
Permutation: 2 3 1 4
Permutation: 2 3 4 1
Permutation: 2 4 3 1
Permutation: 4 2 3 1
Permutation: 4 2 1 3
Permutation: 2 4 1 3
Permutation: 2 1 4 3
Permutation: 2 1 3 4

Process returned 0 (0x0)    execution time : 5.506 s
Press any key to continue.
|
```

## Lab Program 3

**a. Sort a given set of N integer elements using Merge Sort technique and compute its time taken. Run the program for different values of N and record the time taken to sort.**

### Code:

```
#include <stdio.h>
#include <stdlib.h>
#include <time.h>

// Merge function
void merge(int arr[], int left, int mid, int right) {
    int n1 = mid - left + 1;
    int n2 = right - mid;
    int *L = (int *)malloc(n1 * sizeof(int));
    int *R = (int *)malloc(n2 * sizeof(int));

    for (int i = 0; i < n1; i++) L[i] = arr[left + i];
    for (int i = 0; i < n2; i++) R[i] = arr[mid + 1 + i];

    int i = 0, j = 0, k = left;
    while (i < n1 && j < n2) {
        if (L[i] <= R[j]) arr[k++] = L[i++];
        else arr[k++] = R[j++];
    }

    while (i < n1) arr[k++] = L[i++];
    while (j < n2) arr[k++] = R[j++];

    free(L);
    free(R);
}

// Merge Sort function
void merge_sort(int arr[], int left, int right) {
    if (left < right) {
        int mid = left + (right - left) / 2;
        merge_sort(arr, left, mid);
        merge_sort(arr, mid + 1, right);
        merge(arr, left, mid, right);
    }
}
```

```

    }
}

int main() {
    int n_values[] =
{100000,200000,300000,400000,500000,600000,700000,800000,900000,1000000};
    int num_tests = sizeof(n_values) / sizeof(n_values[0]);

    for (int i = 0; i < num_tests; i++) {
        int n = n_values[i];
        int *array = (int *)malloc(n * sizeof(int));

        // Average Case: Randomized Input
        for (int j = 0; j < n; j++) array[j] = rand() % 1000000;
        clock_t start = clock();
        merge_sort(array, 0, n - 1);
        clock_t end = clock();
        printf("n = %d | Avg: %.6f\n", n, (double)(end - start) / CLOCKS_PER_SEC);

        free(array);
    }

    return 0;
}

```

## **Output:**

```

Merge Sort Time Complexity Analysis:
n = 100000 | Avg: 0.037664
n = 200000 | Avg: 0.079346
n = 300000 | Avg: 0.120634
n = 400000 | Avg: 0.164329
n = 500000 | Avg: 0.209077
n = 600000 | Avg: 0.251556
n = 700000 | Avg: 0.294781
n = 800000 | Avg: 0.339544
n = 900000 | Avg: 0.386991
n = 1000000 | Avg: 0.429733

```

## **b. LeetCode Program related to Binary Search Tree.**

### **LeetCode 230. Kth Smallest Element in a BST**

Given the root of a binary search tree, and an integer k, return the kth smallest value (1-indexed) of all the values of the nodes in the tree.

#### **Submission Code:**

```
/**
 * Definition for a binary tree node.
 * struct TreeNode {
 *     int val;
 *     struct TreeNode *left;
 *     struct TreeNode *right;
 * };
 */
#include <stdio.h>
#include <stdlib.h>

int kthSmallest(struct TreeNode* root, int k) {
    int findMin(struct TreeNode* root){
        while(root->left!=NULL){
            root = root->left;
        }
        return root->val;
    }
    struct TreeNode* delete_min(struct TreeNode* root){
        struct TreeNode* parent = root;
        struct TreeNode* child = root;
        if(root==NULL){
            return root;
        }
        while(child->left!=NULL){
            parent = child;
            child = child->left;
        }
        parent->left = child->right;
        return root;
    }
    for(int i = 0 ; i<k-1; i++){
        root = delete_min(root);
    }
}
```

```

    int r = findMin(root);
    return r;
}

```

## Result:

The screenshot shows the LeetCode interface for problem 230, "Kth Smallest Element in a BST". The problem description states: "Given the `root` of a binary search tree `k`, return the  $k^{\text{th}}$  smallest value (1-indexed values of the nodes in the tree)." An example tree is shown with root 3, left child 1, and right child 4.

The submission status is "Accepted" with 93 / 93 testcases passed. The submission was made by Raja Vishwanath Dasari on Mar 11, 2025 at 11:58. The runtime is 0 ms, beating 100.00% of submissions. The memory usage is 13.61 MB, beating 52.84% of submissions.

A bar chart shows the runtime distribution for the submission, with a single bar at 0 ms reaching 100%.



## Lab Program 4

**a. Sort a given set of N integer elements using Quick Sort technique and compute its time taken.**

### Code:

```
#include <stdio.h>

#include <stdlib.h>

#include <time.h>

// Swap function
void swap(int *a, int *b) {
    int temp = *a;
    *a = *b;
    *b = temp;
}

// Median-of-three pivot selection for best case
int median_of_three(int arr[], int low, int high) {
    int mid = low + (high - low) / 2;
    if (arr[low] > arr[mid]) swap(&arr[low], &arr[mid]);
    if (arr[low] > arr[high]) swap(&arr[low], &arr[high]);
    if (arr[mid] > arr[high]) swap(&arr[mid], &arr[high]);
    return mid; // Return index of the median element
}

// Partition function using last element as pivot
int partition(int arr[], int low, int high) {
    int pivot = arr[high]; // Worst and average case use last element as pivot
```

```

int i = low - 1;

for (int j = low; j < high; j++) {
    if (arr[j] <= pivot) {
        i++;
        swap(&arr[i], &arr[j]);
    }
}
swap(&arr[i + 1], &arr[high]);
return i + 1;
}

// Partition function using median-of-three pivot for best case
int partition_median(int arr[], int low, int high) {
    int median = median_of_three(arr, low, high);
    swap(&arr[median], &arr[high]); // Move median pivot to the end
    return partition(arr, low, high);
}

// Quick sort with normal partitioning
void quick_sort(int arr[], int low, int high) {
    if (low < high) {
        int pi = partition(arr, low, high);
        quick_sort(arr, low, pi - 1);
        quick_sort(arr, pi + 1, high);
    }
}

```

```

// Quick sort with median pivot for best case
void quick_sort_best(int arr[], int low, int high) {
    if (low < high) {
        int pi = partition_median(arr, low, high);
        quick_sort_best(arr, low, pi - 1);
        quick_sort_best(arr, pi + 1, high);
    }
}

int main() {
    int n_values[] = { 10000, 20000, 30000, 40000, 50000, 60000, 70000, 80000, 90000, 100000 };
    int num_tests = sizeof(n_values) / sizeof(n_values[0]);

    for (int i = 0; i < num_tests; i++) {
        int n = n_values[i];
        int *array = (int *)malloc(n * sizeof(int));

        // Best Case: Median Pivot (Balanced Partitioning)
        for (int j = 0; j < n; j++) array[j] = j;
        clock_t start = clock();
        quick_sort_best(array, 0, n - 1);
        clock_t end = clock();
        printf("n = %d | Best: %.6f | ", n, (double)(end - start) / CLOCKS_PER_SEC);

        // Average Case: Randomized Input
        for (int j = 0; j < n; j++) array[j] = rand() % 100000;
        start = clock();
        quick_sort(array, 0, n - 1);
        end = clock();
    }
}

```

```

printf("Avg: %.6f | ", (double)(end - start) / CLOCKS_PER_SEC);

// Worst Case: Already Sorted in Ascending Order (Last Element Pivot)
for (int j = 0; j < n; j++) array[j] = j;

start = clock();

quick_sort(array, 0, n - 1);

end = clock();

printf("Worst: %.6f\n", (double)(end - start) / CLOCKS_PER_SEC);

free(array);
}

return 0;
}

```

### **Output:**

n = 10000	Best: 0.000733	Avg: 0.001543	Worst: 0.349421
n = 20000	Best: 0.001842	Avg: 0.003396	Worst: 1.364989
n = 30000	Best: 0.002432	Avg: 0.005338	Worst: 3.761610
n = 40000	Best: 0.003336	Avg: 0.007314	Worst: 5.478223
n = 50000	Best: 0.004516	Avg: 0.009029	Worst: 9.220020
n = 60000	Best: 0.005158	Avg: 0.011119	Worst: 13.013741
n = 70000	Best: 0.005970	Avg: 0.013162	Worst: 17.445868
n = 80000	Best: 0.007140	Avg: 0.015433	Worst: 23.256661
n = 90000	Best: 0.008138	Avg: 0.018496	Worst: 29.237170
n = 100000	Best: 0.012229	Avg: 0.024076	Worst: 35.982174

## **b. LeetCode Program related to Binary Trees.**

### **LeetCode 124. Binary Tree Maximum Path Sum**

A path in a binary tree is a sequence of nodes where each pair of adjacent nodes in the sequence has an edge connecting them. A node can only appear in the sequence at most once.

Note that the path does not need to pass through the root.

The path sum of a path is the sum of the node's values in the path.

Given the root of a binary tree, return the maximum path sum of any non-empty path.

#### **Submission Code:**

```
struct TreeNode {
    int val;
    struct TreeNode *left;
    struct TreeNode *right;
};

int dfs(struct TreeNode* root, int* res) {
    if (root == NULL) {
        return 0;
    }

    int left = dfs(root->left, res);
    int right = dfs(root->right, res);

    left = (left > 0) ? left : 0;
    right = (right > 0) ? right : 0;

    *res = (*res > left + right + root->val) ? *res : (left + right + root->val);

    return root->val + ((left > right) ? left : right);
}

int maxPathSum(struct TreeNode* root) {
    int res = -999999999;
    dfs(root, &res);
    return res;
}
```

## Result:

DescriptionEditorialSolutions

### 124. Binary Tree Maximum Path Sum

HardTopicsCompanies

A **path** in a binary tree is a sequence of nodes where each pair of adjacent nodes in the sequence has an edge connecting them. A node can only appear in the sequence **at most once**. Note that the path does not need to pass through the root.

The **path sum** of a path is the sum of the node values in the path.

Given the `root` of a binary tree, return the **maximum path sum** of any **non-empty path**.

**Example 1:**

17.5K

254

☆

🔖

🕒

</> CodeAccepted X

← All Submissions

Accepted96 / 96 testcases passed

Raja Vishwanath Dasari submitted at Mar 17, 2025 21:18

EditorialSolution

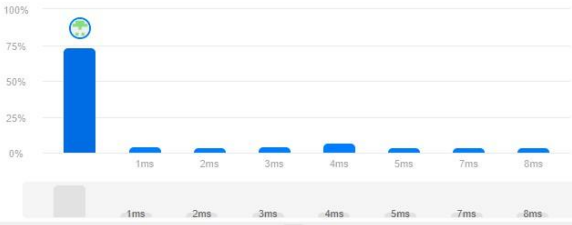
Runtime

0 ms | Beats 100.00%

Analyze Complexity

Memory

16.92 MB | Beats 63.57%



TestcaseTest Result

## Lab Program 5

**Sort a given set of N integer elements using Heap Sort technique and compute its time taken.**

### Code:

```
#include <stdio.h>
#include <stdlib.h>
#include <time.h>

void heapify(int arr[], int n, int i) {
    int l = 2 * i + 1, r = 2 * i + 2, m = i;
    if (l < n && arr[l] > arr[m]) m = l;
    if (r < n && arr[r] > arr[m]) m = r;
    if (m != i) {
        int t = arr[i];
        arr[i] = arr[m];
        arr[m] = t;
        heapify(arr, n, m);
    }
}

void heapsort(int arr[], int n) {
    for (int i = n / 2 - 1; i >= 0; i--) heapify(arr, n, i);
    for (int i = n - 1; i > 0; i--) {
        int t = arr[0];
        arr[0] = arr[i];
        arr[i] = t;
        heapify(arr, i, 0);
    }
}

int main() {
    int n_values[] =
{100000,200000,300000,400000,500000,600000,700000,800000,900000,1000000};
    int num_tests = sizeof(n_values) / sizeof(n_values[0]);
    printf("Heap Sort Time Complexity Analysis: \n");
    for (int i = 0; i < num_tests; i++) {
        int n = n_values[i];
        int *array = (int *)malloc(n * sizeof(int));
        for (int j = 0; j < n; j++) array[j] = rand() % 1000000;
```

```
clock_t start = clock();
heapsort(array, n);
clock_t end = clock();

printf("n = %d | Avg: %.6f sec\n", n, (double)(end - start) / CLOCKS_PER_SEC);
free(array);
}
return 0;
}
```

### **Output:**

```
Heap Sort Time Complexity Analysis:
n = 100000 | Avg: 0.032810 sec
n = 200000 | Avg: 0.076087 sec
n = 300000 | Avg: 0.109885 sec
n = 400000 | Avg: 0.151516 sec
n = 500000 | Avg: 0.198166 sec
n = 600000 | Avg: 0.235795 sec
n = 700000 | Avg: 0.294872 sec
n = 800000 | Avg: 0.331766 sec
n = 900000 | Avg: 0.369062 sec
n = 1000000 | Avg: 0.435496 sec
```



## Lab Program 6

### a. Implement 0/1 Knapsack problem using dynamic programming

#### Code:

```
#include<stdio.h>
#include<stdlib.h>

int max(int a,int b){
    int m = a>b?a:b;
    return m;
}

void knapsack(int v[], int w[], int n, int W){
    int dp[n+1][W+1];
    for(int i = 0;i<=n; i++){
        for(int j = 0;j<=W; j++){
            dp[i][j] = 0;
        }
    }

    for(int i = 1; i<=n; i++){
        for(int j = 1;j<=W; j++){
            if(w[i-1]<=j){
                dp[i][j] = max(dp[i-1][j], v[i-1]+dp[i-1][j-w[i-1]]);
            }
            else{
                dp[i][j]=dp[i-1][j];
            }
        }
    }

    printf("Maximum value: %d\n", dp[n][W]);

    printf("Selected item: ");
    int res = dp[n][W];
    int j = W;
    for (int i = n; i > 0 && res > 0; i--) {
        if (res != dp[i-1][j]) {
            printf("%d ", i);
            res -= v[i-1];
            j -= w[i-1];
        }
    }
}
```

```

    }
}
printf("\n");
}

int main() {
    int n, W;
    int values[100], weights[100];
    printf("Enter the number of items: ");
    scanf("%d", &n);
    printf("Enter the capacity of the knapsack: ");
    scanf("%d", &W);
    printf("Enter the values of the items:\n");
    for (int i = 0; i < n; i++) {
        scanf("%d", &values[i]);
    }
    printf("Enter the weights of the items:\n");
    for (int i = 0; i < n; i++) {
        scanf("%d", &weights[i]);
    }

    knapsack(values, weights, n, W);

    return 0;
}

```

### **Output:**

```

Enter the number of items: 5
Enter the capacity of the knapsack: 7
Enter the values of the items:
100 120 90 70 50
Enter the weights of the items:
2 3 6 1 4
Maximum value: 290
Selected item: 4 2 1

Process returned 0 (0x0)   execution time : 32.291 s
Press any key to continue.

```

## **b. LeetCode Program related to Knapsack problem or Dynamic Programming.**

### **LeetCode 474. Ones and Zeroes**

You are given an array of binary strings `strs` and two integers `m` and `n`.

Return the size of the largest subset of `strs` such that there are at most `m` 0's and `n` 1's in the subset.

A set `x` is a subset of a set `y` if all elements of `x` are also elements of `y`.

### **Submission Code:**

```
#include <string.h>

int findMaxForm(char** strs, int strsSize, int m, int n) {
    int dp[101][101] = {0};

    for (int k = 0; k < strsSize; ++k) {
        int zeros = 0, ones = 0;
        for (int i = 0; strs[k][i]; ++i) {
            if (strs[k][i] == '0') zeros++;
            else ones++;
        }
        for (int i = m; i >= zeros; --i) {
            for (int j = n; j >= ones; --j) {
                if (dp[i][j] < dp[i - zeros][j - ones] + 1) {
                    dp[i][j] = dp[i - zeros][j - ones] + 1;
                }
            }
        }
    }

    return dp[m][n];
}
```

## Result:

DescriptionEditorialSolution

### 474. Ones and Zeroes

MediumTopicsCompanies

You are given an array of binary strings `strs` and two integers `m` and `n`.

Return the size of the largest subset of `strs` such that there are **at most** `m` 0's and `n` 1's in the subset.

A set `x` is a **subset** of a set `y` if all elements of `x` are also elements of `y`.

**Example 1:**

**Input:** `strs = ["10", "0001", "111001", "1", "0"]`, `m = 3`

**Output:** 4

**Explanation:** The largest subset is `["10", "0001", "1", "0"]`.

5.6K41

</> CodeAccepted

← All Submissions

Accepted77 / 77 testcases passed

Raja Vishwanath Dasari submitted at May 13, 2025 09:13

EditorialSolution

Runtime49 msBeats: 86.21%

Memory9.22 MBBeats: 34.48%

Analyze Complexity

Runtime (ms)	Percentage (%)
43ms	~3.5%
47ms	~3.5%
49ms	~6.5%
52ms	~3.5%
56ms	~3.5%
59ms	~10.5%
64ms	~10.5%
71ms	~3.5%
76ms	~6.5%
82ms	~3.5%
159ms	~3.5%

TestcaseTest Result

## Lab Program 7

**a. Implement All Pair Shortest paths problem using Floyd's algorithm.**

### Code:

```
#include<stdio.h>
#include<stdlib.h>
#include<limits.h>

#define SIZE 100
int min(int a, int b){
    int m = a>b?b:a;
    return m;
}
void floyd_warshall(int graph[SIZE][SIZE],int n){
    int D[n][n];
    for(int i = 0 ; i<n;i++){
        for(int j = 0; j<n ;j++){
            D[i][j] = graph[i][j];
        }
    }

    for(int k = 0;k<n;k++){
        for(int i = 0 ; i<n;i++){
            for(int j = 0; j<n ;j++){
                if(D[i][k]!= INT_MAX && D[k][j]!=INT_MAX){
                    D[i][j]= min(D[i][j], D[i][k]+D[k][j]);
                }
            }
        }
    }

    printf("The final matrix D is:\n");
    for(int i = 0 ; i<n;i++){
        for(int j = 0; j<n ;j++){
            if(D[i][j]!=INT_MAX)printf("%d ",D[i][j]);
            else printf("INF ");
        }
        printf("\n");
    }
    for(int i = 0 ; i<n;i++){
        for(int j = 0; j<n ;j++){
```

```

        if(D[i][j]!=0 && D[i][j]!=INT_MAX){
            printf("Shortest Path from %d to %d : %d\n", i,j,D[i][j]);
        }
    }
}
}

int main(){
    int n;
    int graph[SIZE][SIZE];

    printf("Enter number of vertices :");
    scanf("%d",&n);
    printf("For no direct edge enter -1\n");
    for(int i =0;i<n;i++){
        for(int j =0; j<n;j++) scanf("%d",&graph[i][j]);
    }

    for(int i =0;i<n;i++){
        for(int j =0; j<n;j++){
            if(graph[i][j]==-1) graph[i][j]=INT_MAX;
        }
    }
    floyd_warshall(graph,n);
    return 0;
}

```

## Output:

```
Enter number of vertices :4
For no direct edge enter -1
0 -1 3 -1
2 0 -1 -1
-1 7 0 1
6 -1 -1 0
The final matrix D is:
0 10 3 4
2 0 5 6
7 7 0 1
6 16 9 0
Shortest Path from 0 to 1 : 10
Shortest Path from 0 to 2 : 3
Shortest Path from 0 to 3 : 4
Shortest Path from 1 to 0 : 2
Shortest Path from 1 to 2 : 5
Shortest Path from 1 to 3 : 6
Shortest Path from 2 to 0 : 7
Shortest Path from 2 to 1 : 7
Shortest Path from 2 to 3 : 1
Shortest Path from 3 to 0 : 6
Shortest Path from 3 to 1 : 16
Shortest Path from 3 to 2 : 9
```

```
Enter number of vertices :5
For no direct edge enter -1
0 6 2 4 -1
-1 0 -1 -1 -1
-1 3 0 -1 1
-1 1 -1 0 -1
-1 1 -1 -1 0
The final matrix D is:
0 4 2 4 3
INF 0 INF INF INF
INF 2 0 INF 1
INF 1 INF 0 INF
INF 1 INF INF 0
Shortest Path from 0 to 1 : 4
Shortest Path from 0 to 2 : 2
Shortest Path from 0 to 3 : 4
Shortest Path from 0 to 4 : 3
Shortest Path from 2 to 1 : 2
Shortest Path from 2 to 4 : 1
Shortest Path from 3 to 1 : 1
Shortest Path from 4 to 1 : 1
```

## **b. LeetCode Program related to shortest distance calculation.**

### **LeetCode 1334. Find the City With the Smallest Number of Neighbors at a Threshold Distance**

There are  $n$  cities numbered from 0 to  $n-1$ . Given the array `edges` where `edges[i] = [fromi, toi, weighti]` represents a bidirectional and weighted edge between cities `fromi` and `toi`, and given the integer `distanceThreshold`.

Return the city with the smallest number of cities that are reachable through some path and whose distance is at most `distanceThreshold`. If there are multiple such cities, return the city with the greatest number.

Notice that the distance of a path connecting cities  $i$  and  $j$  is equal to the sum of the edges' weights along that path.

### **Submission Code:**

```
#include <limits.h>
#include <stdlib.h>

#define INF 1000000000 // A large number representing infinity

int findTheCity(int n, int** edges, int edgesSize, int* edgesColSize, int distanceThreshold) {
    int dist[100][100]; // n <= 100

    // Initialize distances
    for (int i = 0; i < n; i++) {
        for (int j = 0; j < n; j++) {
            dist[i][j] = (i == j) ? 0 : INF;
        }
    }

    // Set initial edge weights
    for (int i = 0; i < edgesSize; i++) {
        int u = edges[i][0];
        int v = edges[i][1];
        int w = edges[i][2];
        dist[u][v] = w;
        dist[v][u] = w; // because it's bidirectional
    }

    // Floyd-Warshall algorithm
    for (int k = 0; k < n; k++) {
        for (int i = 0; i < n; i++) {
```



```

        for (int j = 0; j < n; j++) {
            if (dist[i][k] + dist[k][j] < dist[i][j]) {
                dist[i][j] = dist[i][k] + dist[k][j];
            }
        }
    }
}

int result = -1;
int minReachable = n + 1; // Start with max possible

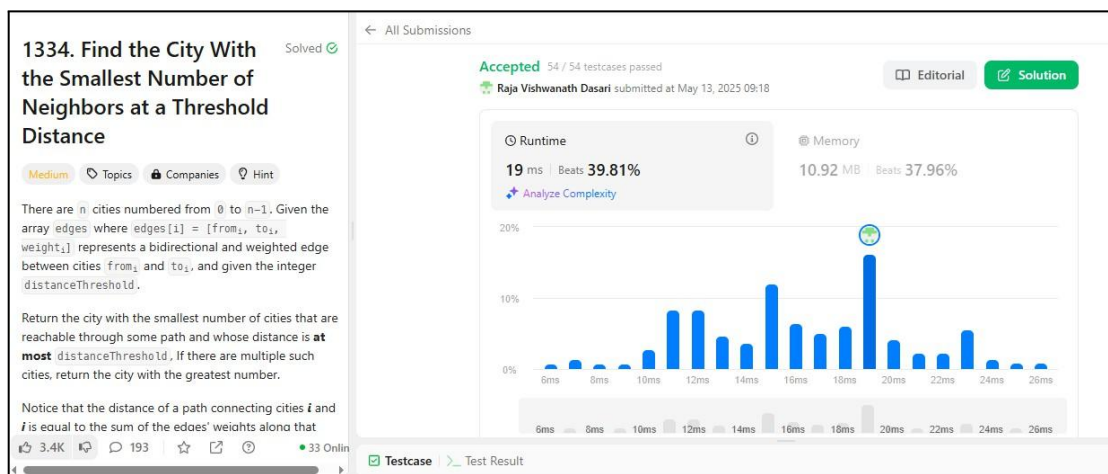
for (int i = 0; i < n; i++) {
    int count = 0;
    for (int j = 0; j < n; j++) {
        if (i != j && dist[i][j] <= distanceThreshold) {
            count++;
        }
    }

    // Choose the city with the smallest number of reachable cities.
    // If tied, choose the larger index.
    if (count <= minReachable) {
        minReachable = count;
        result = i;
    }
}

return result;
}

```

## Result:



## Lab Program 8

**a. Find Minimum Cost Spanning Tree of a given undirected graph using Prim's algorithm.**

### Code:

```
#include <stdio.h>
#include <limits.h>

#define MAX 100

int minKey(int key[], int mstSet[], int V) {
    int min = INT_MAX, min_index = -1;
    for (int v = 0; v < V; v++) {
        if (mstSet[v] == 0 && key[v] < min) {
            min = key[v];
            min_index = v;
        }
    }
    return min_index;
}

void printMST(int parent[], int graph[MAX][MAX], int V) {
    printf("Edge \tWeight\n");
    for (int i = 1; i < V; i++) {
        printf("%d - %d \t%d\n", parent[i], i, graph[i][parent[i]]);
    }
}

void primMST(int graph[MAX][MAX], int V) {
    int parent[MAX];
    int key[MAX];
    int mstSet[MAX];

    for (int i = 0; i < V; i++) {
        key[i] = INT_MAX;
        mstSet[i] = 0;
    }

    key[0] = 0;
    parent[0] = -1;
```

```

for (int count = 0; count < V - 1; count++) {
    int u = minKey(key, mstSet, V);
    mstSet[u] = 1;

    for (int v = 0; v < V; v++) {
        if (graph[u][v] && mstSet[v] == 0 && graph[u][v] < key[v]) {
            parent[v] = u;
            key[v] = graph[u][v];
        }
    }
}

printMST(parent, graph, V);
}

int main() {
    int V, graph[MAX][MAX];

    printf("Enter the number of vertices: ");
    scanf("%d", &V);

    printf("Enter the adjacency matrix (0 if no edge):\n");
    for (int i = 0; i < V; i++) {
        for (int j = 0; j < V; j++) {
            scanf("%d", &graph[i][j]);
        }
    }

    primMST(graph, V);

    return 0;
}

```

### Output:

```
Enter the number of vertices: 5
Enter the adjacency matrix (0 if no edge):
0 10 0 0 5
10 0 12 13 0
0 12 0 20 0
0 13 20 0 6
5 0 0 6 0
Edge      Weight
0 - 1     10
1 - 2     12
4 - 3      6
0 - 4      5

Process returned 0 (0x0)   execution time : 142.404 s
Press any key to continue.
```

### **b. Find Minimum Cost Spanning Tree of a given undirected graph using Kruskal's algorithm**

#### Code:

```
#include <stdio.h>

#define MAX 100

int parent[MAX];

int find(int i) {
    while (parent[i] != i)
        i = parent[i];
    return i;
}

void unionSet(int i, int j) {
    int a = find(i);
    int b = find(j);
    parent[b] = a;
}

int main() {
    int V;
    int graph[MAX][MAX];
```

```

printf("Enter number of vertices: ");
scanf("%d", &V);

printf("Enter the adjacency matrix (0 if no edge):\n");
for (int i = 0; i < V; i++) {
    for (int j = 0; j < V; j++) {
        scanf("%d", &graph[i][j]);
    }
}

for (int i = 0; i < V; i++)
    parent[i] = i;

int edgeCount = 0, minCost = 0;

printf("Edge \tWeight\n");

while (edgeCount < V - 1) {
    int min = 99999, a = -1, b = -1;

    for (int i = 0; i < V; i++) {
        for (int j = 0; j < V; j++) {
            if (graph[i][j] != 0 && graph[i][j] < min && find(i) != find(j)) {
                min = graph[i][j];
                a = i;
                b = j;
            }
        }
    }

    if (a != -1 && b != -1) {
        unionSet(a, b);
        printf("%d - %d \t%d\n", a, b, min);
        minCost += min;
        edgeCount++;
    } else {
        break;
    }
}

printf("Total weight of MST: %d\n", minCost);

return 0;
}

```

## Output:

```
Enter number of vertices: 5
Enter the adjacency matrix (0 if no edge):
0 10 0 0 5
10 0 12 13 0
0 12 0 20 0
0 13 20 0 6
5 0 0 6 0
Edge    Weight
0 - 4    5
3 - 4    6
0 - 1   10
1 - 2   12
Total weight of MST: 33

Process returned 0 (0x0)   execution time : 114.168 s
Press any key to continue.
```

## Lab Program 9

### a. Fractional Knapsack using Greedy technique.

#### Code:

```
#include<stdio.h>
#include<stdlib.h>

int partition(double arr[][3], int low, int high) {
    double pivot = arr[high][2];
    int i = (low - 1);
    for (int j = low; j < high; j++) {
        if (arr[j][2] > pivot) {
            i++;
            double temp0 = arr[i][0], temp1 = arr[i][1], temp2 = arr[i][2];
            arr[i][0] = arr[j][0];
            arr[i][1] = arr[j][1];
            arr[i][2] = arr[j][2];
            arr[j][0] = temp0;
            arr[j][1] = temp1;
            arr[j][2] = temp2;
        }
    }
    double temp0 = arr[i + 1][0], temp1 = arr[i + 1][1], temp2 = arr[i + 1][2];
    arr[i + 1][0] = arr[high][0];
    arr[i + 1][1] = arr[high][1];
    arr[i + 1][2] = arr[high][2];
    arr[high][0] = temp0;
    arr[high][1] = temp1;
    arr[high][2] = temp2;

    return i + 1;
}

void quick_sort(double arr[][3], int low, int high) {
    if (low < high) {
        int pi = partition(arr, low, high);
        quick_sort(arr, low, pi - 1);
        quick_sort(arr, pi + 1, high);
    }
}
```

```

void fractional_knapsack(int v[], int w[], int n, int W) {
    double items[n][3];
    for (int i = 0; i < n; i++) {
        items[i][0] = v[i];
        items[i][1] = w[i];
        items[i][2] = (double)v[i] / (double)w[i];
    }

    quick_sort(items, 0, n - 1);

    double K = W;
    double total_val = 0.0;
    double x[n];
    for (int i = 0; i < n; i++) {
        x[i] = 0.0;
    }
    for (int i = 0; i < n && K > 0; i++) {
        if (items[i][1] <= K) {
            total_val += items[i][0];
            K -= items[i][1];
            x[i] = 1.0;
        } else {
            total_val += K * items[i][2];
            x[i] = K / items[i][1];
            K = 0;
        }
    }

    printf("Total Value: %f\n", total_val);
    printf("Item fractions: ");
    for (int i = 0; i < n; i++) {
        printf("%f ", x[i]);
    }
    printf("\n");
}

int main(){
    int n, W;

    printf("Enter capacity of knapsack: ");
    scanf("%d", &W);

    printf("Enter number of items: ");

```



```

scanf("%d", &n);

if (n <= 0) {
    printf("Invalid number of items.\n");
    return 0;
}

int v[n];
int w[n];

printf("Enter weights of items: ");
for (int i = 0; i < n; i++) {
    scanf("%d", &w[i]);
}

printf("Enter values of items: ");
for (int i = 0; i < n; i++) {
    scanf("%d", &v[i]);
}

fractional_knapsack(v, w, n, W);

return 0;
}

```

### **Output:**

```

Enter capacity of knapsack: 50
Enter number of items: 3
Enter weights of items: 10 20 30
Enter values of items: 60 100 120
Total Value: 240.000000
Item fractions: 1.000000 1.000000 0.666667

Process returned 0 (0x0)   execution time : 18.795 s
Press any key to continue.
|

```

## **b. LeetCode Program related to Greedy Technique algorithms.**

### **LeetCode 1584. Min Cost to Connect All Points**

You are given an array points representing integer coordinates of some points on a 2D-plane, where  $\text{points}[i] = [x_i, y_i]$ .

The cost of connecting two points  $[x_i, y_i]$  and  $[x_j, y_j]$  is the manhattan distance between them:  $|x_i - x_j| + |y_i - y_j|$ , where  $|val|$  denotes the absolute value of  $val$ .

Return the minimum cost to make all points connected. All points are connected if there is exactly one simple path between any two points.

### **Submission Code:**

```
#include <stdio.h>
#include <stdlib.h>
#include <limits.h>

#define MAX_POINTS 1000

int visited[MAX_POINTS];
int minDist[MAX_POINTS];

int absVal(int x) {
    return x < 0 ? -x : x;
}

int manhattan_distance(int* a, int* b) {
    return absVal(a[0] - b[0]) + absVal(a[1] - b[1]);
}

int minCostConnectPoints(int** points, int pointsSize, int* pointsColSize) {
    for (int i = 0; i < pointsSize; i++) {
        visited[i] = 0;
        minDist[i] = INT_MAX;
    }

    int totalCost = 0;
    minDist[0] = 0;

    for (int i = 0; i < pointsSize; i++) {
        int u = -1;
        for (int j = 0; j < pointsSize; j++) {
            if (!visited[j] && (u == -1 || minDist[j] < minDist[u])) {
                u = j;
            }
        }
    }
}
```

```

    }
}

visited[u] = 1;
totalCost += minDist[u];

for (int v = 0; v < pointsSize; v++) {
    if (!visited[v]) {
        int dist = manhattan_distance(points[u], points[v]);
        if (dist < minDist[v]) {
            minDist[v] = dist;
        }
    }
}
}

return totalCost;
}

```

## Result:

Description
Editorial
Solutions
Submissions

### 1584. Min Cost to Connect All Points

Solved

Medium Topics Companies Hint

You are given an array `points` representing integer coordinates of some points on a 2D-plane, where `points[i] = [xi, yi]`.

The cost of connecting two points `[xi, yi]` and `[xj, yj]` is the **manhattan distance** between them:  $|x_i - x_j| + |y_i - y_j|$ , where  $|val|$  denotes the absolute value of `val`.

Return the *minimum cost to make all points connected*. All points are connected if there is **exactly one** simple path between any two points.

**Example 1:**

Code
Accepted

All Submissions

Accepted 72 / 72 testcases passed  
Raja Vishwanath Dasari submitted at Apr 16, 2025 23:47

Editorial
Solution

Runtime
27 ms | Beats 74.29%

Memory
9.98 MB | Beats 97.14%

Analyze Complexity

45 Online
Testcase
Test Result

## Lab Program 10

**From a given vertex in a weighted connected graph, find shortest paths to other vertices using Dijkstra's algorithm.**

### Code:

```
#include<stdio.h>
#include<stdlib.h>
#include<limits.h>

#define MAX 100

int findMin(int dist[], int visited[], int V){
    int min = INT_MAX;
    int min_ind;
    for(int i=0; i<V;i++){
        if(visited[i]==0 && dist[i]<min){
            min = dist[i];
            min_ind = i;
        }
    }
    return min_ind;
}

void printPath(int prev[], int j) {
    if (prev[j] == -1) {
        printf("%d ", j);
        return;
    }
    printPath(prev, prev[j]);
    printf("-> %d ", j);
}

void djikstra(int graph[MAX][MAX],int src,int V){
    int dist[V];
    int visited[V];
    int prev[V];

    for(int i = 0;i<V;i++){
        dist[i]=INT_MAX;
        visited[i]=0;
```

```

    prev[i] = -1;
}

dist[src] = 0;

for(int j = 0; j< V-1; j++){
    int u = findMin(dist, visited, V);
    visited[u] = 1;

    for(int v = 0; v<V ; v++){
        if(visited[v] == 0 && graph[u][v]!=0 && dist[u]!=INT_MAX){
            if(dist[u]+graph[u][v] < dist[v]){
                dist[v] = dist[u]+graph[u][v];
                prev[v] = u;
            }
        }
    }
}

printf("Vertex \t Shortest Distance\n");
for(int i = 0; i<V;i++){
    printf("%d \t %d\t\t",i,dist[i]);
    printf("Shortest Path: ");
    printPath(prev, i);
    printf("\n");
}

}

int main(){
    int V;
    int graph[MAX][MAX];
    int src;
    printf("Number of vertices: ");
    scanf("%d",&V);

    printf("Enter Weighted Adjacency Matrix ( 0 if no edge ):\n");
    for(int i = 0;i<V;i++){
        for(int j = 0; j<V; j++){
            scanf("%d",&graph[i][j]);
        }
    }
}

```

```

printf("\nSource Vertex: ");
scanf("%d",&src);

djikstra(graph,src,V);

return 0;

}

```

### Output:

```

Number of vertices: 9
Enter Weighted Adjacency Matrix ( 0 if no edge ):
0 4 0 0 0 0 0 8 0
4 0 8 0 0 0 0 0 11 0
0 8 0 7 0 4 0 0 2
0 0 7 0 0 14 0 0 0
0 0 0 9 0 10 0 0 0
0 0 4 14 10 0 2 0 0
0 0 0 0 0 2 0 1 6
8 11 0 0 0 0 1 0 7
0 0 2 0 0 0 6 7 0

Source Vertex: 0
Vertex    Shortest Distance    Shortest Path:
0          0              0
1          4              0 -> 1
2         12              0 -> 1 -> 2
3         19              0 -> 1 -> 2 -> 3
4         21              0 -> 7 -> 6 -> 5 -> 4
5         11              0 -> 7 -> 6 -> 5
6          9              0 -> 7 -> 6
7          8              0 -> 7
8         14              0 -> 1 -> 2 -> 8

Process returned 0 (0x0)    execution time : 5.754 s
Press any key to continue.

```

# Lab Program 11

**Implement “N-Queens Problem” using Backtracking.**

## Code:

```
#include <stdio.h>
#include <stdbool.h>
#define MAX_N 10
void printBoard(int board[MAX_N][MAX_N], int n) {
    for (int i = 0; i < n; i++) {
        for (int j = 0; j < n; j++) {
            printf("%d ", board[i][j]);
        }
        printf("\n");
    }
    printf("\n");
}
bool isSafe(int board[MAX_N][MAX_N], int row, int col, int n) {
    for (int i = 0; i < row; i++) {
        if (board[i][col] == 1) {
            return false;
        }
        if (col - (row - i) >= 0 && board[i][col - (row - i)] == 1) {
            return false;
        }
        if (col + (row - i) < n && board[i][col + (row - i)] == 1) {
            return false;
        }
    }
    return true;
}
void solveNQueens(int board[MAX_N][MAX_N], int row, int n, int* solutionCount) {
    if (row == n) {
        (*solutionCount)++;
        printBoard(board, n);
        return;
    }

    for (int col = 0; col < n; col++) {
        if (isSafe(board, row, col, n)) {
            board[row][col] = 1;
```

```

        solveNQueens(board, row + 1, n, solutionCount);
        board[row][col] = 0;
    }
}

int main() {
    int n;
    printf("Enter the size of the board (n): ");
    scanf("%d", &n);

    if (n < 1 || n > MAX_N) {
        printf("Please enter a number between 1 and %d.\n", MAX_N);
        return 1;
    }

    int board[MAX_N][MAX_N] = {0};
    int solutionCount = 0;

    solveNQueens(board, 0, n, &solutionCount);

    if (solutionCount == 0) {
        printf("No solution exists.\n");
    } else {
        printf("Total solutions found: %d\n", solutionCount);
    }

    return 0;
}

```

### **Output:**

```

Enter the size of the board (n): 4
0 1 0 0
0 0 0 1
1 0 0 0
0 0 1 0

0 0 1 0
1 0 0 0
0 0 0 1
0 1 0 0

Total solutions found: 2

```