

CIVL 4210 - Advanced Construction with Al and Robotics

Guidebook: Data Visualization

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Background

THE HONG KONG UNIVERSITY OF SCHOOL OF ENGINEERING AND TECHNOLOGY

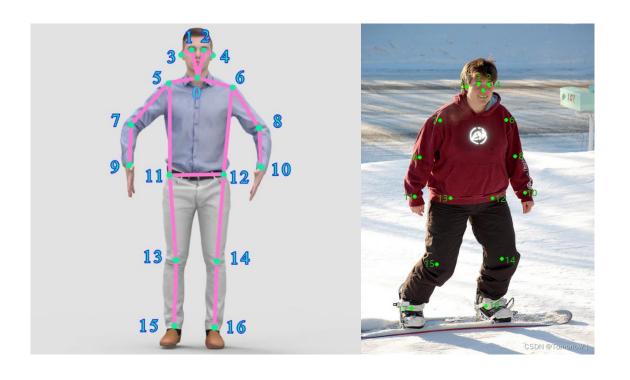
1. Human Pose Estimation - keypoint

In order to represent the human pose, the human body is usually divided into different keypoints, such as the COCO dataset with 17 keypoint types. The body parts 17 key points include:

0: nose, 1: left eye, 2: right eye, 3: left ear, 4: right ear, 5: left shoulder, 6: right shoulder, 7: left elbow, 8: right elbow, 9: left wrist, 10: right wrist, 11: left crotch, 12: right crotch, 13: left knee, 14: right knee, 15: left ankle, 16: right ankle.

2.Matplotlib

Matplotlib is a drawing library for the Python language and its numerical computation library NumPy. It can draw 2D and 3D pictures.



Step 1: Plot a curve



Step 1: Import model

Step 2: Creat array

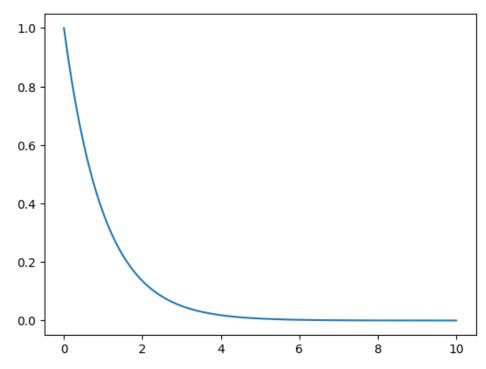
Step 3: Draw the squares of array

import matplotlib.pyplot as plt

import numpy as np a=np.linspace(0,10,100) b=np.exp(-a) plt.plot(a,b)



See the difference when you change "a" and "b".



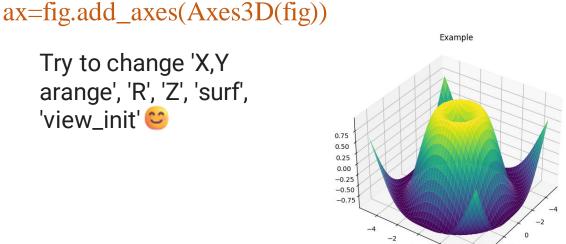
Step 2: Draw a surface

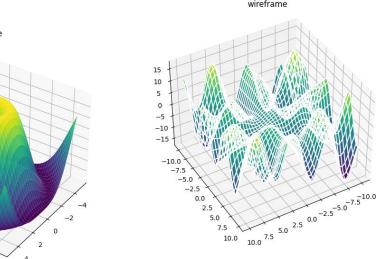


Step 1: Import model

import matplotlib.pyplot as plt from mpl_toolkits.mplot3dimport Axes3D import numpy as np from matplotlib.pyplot import MultipleLocator fig=plt.figure()

Try to change 'X,Y arange', 'R', 'Z', 'surf', 'view init'





X = np.arange(-5,5,0.25)

Y = np.arange(-5,5,0.25)

X,Y=np.meshgrid(X,Y)

Step 2: Creat array Step 3: Draw the squares of array

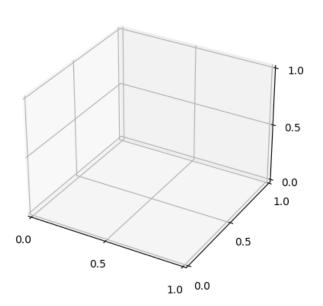
R=np.sqrt(X**2+Y**2)Z=np.sin(R)surf=ax.plot_surface(X,Y,Z,cm ap='viridis') ax.set_title('Example') ax.view_init(35,35,0) plt.show()

Step 3: Drawing of human posture



Step 1: Fire up matplotlib create

from mpl_toolkits.mplot3d import Axes3D import matplotlib.pyplot as plt import numpy as np from matplotlib.pyplot import MultipleLocator



Step 2: Establish connections between keypoints

```
def renderBones(): # define a function
 link = [[0,2],[0,3],[2,5],[3,6],[1,5],[1,6]
        ,[5,11],[11,15],[6,12],[12,16]
,[3,8],[8,14],[14,17],[2,7],[7,13],[13,18]
        ,[1,4],[4,9],[4,10]]
 for 1 in link:
    index1, index2 = [0], [1]
    ax.plot([xs[index1],xs[index2]],
[ys[index1],ys[index2]],
[zs[index1],zs[index2]], linewidth=1,
label=r'$z=y=x$')
```

Step 3: Build 3D image with Matplotlib. pyplot module

```
x_major_locator = MultipleLocator(0.5)
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
ax.xaxis.set_major_locator(x_major_locator)
ax.yaxis.set_major_locator(x_major_locator)
ax.zaxis.set_major_locator(x_major_locator)
x_major_locator = MultipleLocator(0.5)
```

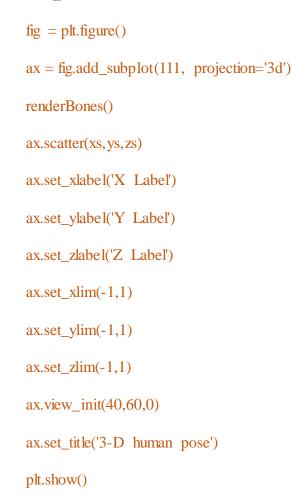
Step 3: Drawing of human posture



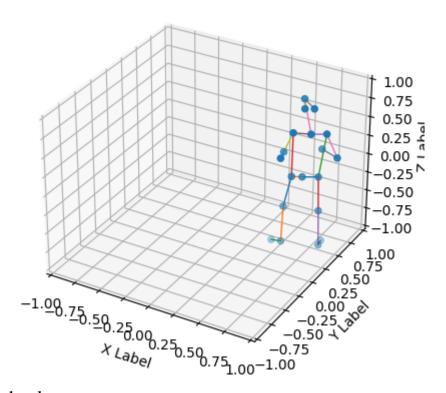
Step 4: Read the data

```
import urllib.request
url='https://raw.githubusercontent.com/Yokhong/CIVL4210/main/H2_human_pose_in
_3D_space/humanpose_data.txt'
urllib.request.urlretrieve(url, "/content/humanpose_data.txt")
file="humanpose_data.txt" # relative address (computing)
nl=[]
with open (file) as f:
for line in f:
nl.extend([float(i) for i in line.split()])
xs = n1[0:19]
print(xs)
ys=n1[19:38]
print(ys)
zs=n1[38:57]
```

Step 5: Draw 3-D human pose

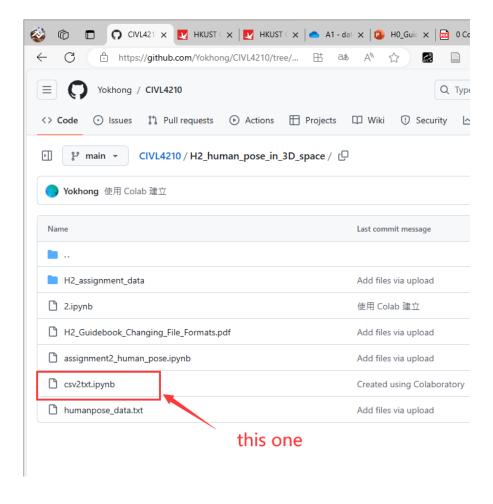


3-D human pose

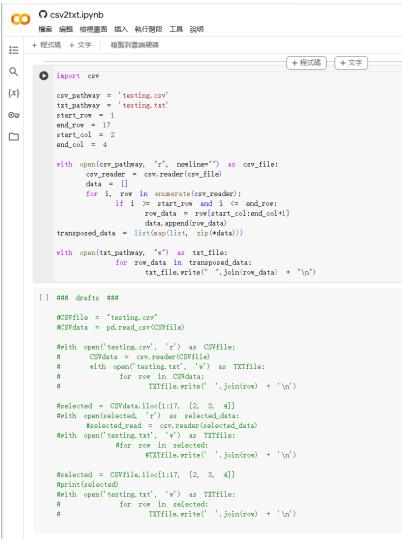


Changing File Formats

Convert .csv format to .txt format.







Assignment requirement



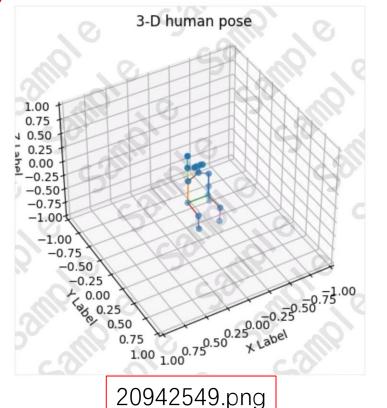
- 1. Change the raw data into the format that your code can read.
- 2. Define a function in which you can join the key points together.
- 3. Load the files you changed and print out XS, YS, and ZS.
- 4. Change the view to elevation angles of 40, azimuth angles of 60, and rotation angles of 0.
- 5. Plot the 3D human pose and save the picture on your computer.
- 6. Please use the last digit of your school number to select the corresponding data number. (For example, your student ID is 20942549, so you need to select the data numbered nine.)



Assignment requirement



What you need to submit to Canvas are an ipynb file and a picture of the 3D human pose named as your student ID.





Appendix

NUMBER	NAME
0	neck
1	L-eye
1 2 3	R-eye
	L-ear
4	R-ear
5	L-shoulder
6	R-shoulder
7	L-elbow
8	R-elbow
9	L-wrist
10	R-wrist
11	L-hip
12	R-hip
13	L-knee
14	R-knee
15	L-ankle
16	R-ankle



