

Lecture 3 Fisher Discriminant

Outline

- ► Recap:
 - Bayes Optimal Classifier
 - Parameter Estimation
- ► Classification without Learning Distributions
 - ► Mean Separation
 - Fisher Discriminant
 - Perceptron
 - Large Margin Classifiers

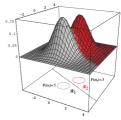


Recap: Bayes Optimal Classifier

Recap:

Assume our data is generated for each class ω_j according to the multivariate Gaussian distribution $p(\mathbf{x}|\omega_j) = \mathcal{N}(\boldsymbol{\mu}_j, \boldsymbol{\Sigma})$ and with class priors $P(\omega_j)$. The Bayes optimal classifier is derived as

$$\begin{split} & \arg\max_{j} \{P(\omega_{j}|\mathbf{x})\} \\ & = \arg\max_{j} \{\log p(\mathbf{x}|\omega_{j}) + \log P(\omega_{j})\} \\ & = \arg\max_{j} \left\{\mathbf{x}^{\top} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_{j}^{\top} - \frac{1}{2} \boldsymbol{\mu}_{j} \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_{j} + \log P(\omega_{j})\right\} \end{split}$$



- Given our generative assumptions, there is no better classifier than the one above.
- ► However, in practice, we don't know these distributions and only have the data.



Recap: Parameter Estimation

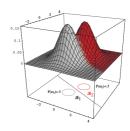
Example of estimator:

Maximum likelihood estimator:

$$\mu = \frac{1}{N} \sum_{k=1}^{N} \mathbf{x}_{k}$$

$$\widehat{\Sigma} = \frac{1}{N} \sum_{k=1}^{N} (\mathbf{x}_{k} - \mu)$$

$$\widehat{\pmb{\Sigma}} = rac{1}{N} \sum_{k=1}^N (\mathbf{x}_k - oldsymbol{\mu}) (\mathbf{x}_k - oldsymbol{\mu})^ op$$



Problem:

- The covariance matrix (and its inverse) may be difficult to estimate.
- We make an assumption about the data (e.g. Gaussian-distributed) which may not correspond to reality.

Distribution-Free Approaches

"When solving a problem of interest, do not solve a more general problem as an intermediate step." (V. Vapnik)

Interpretation in our setting:

- Don't take the intermediate step of learning distributions to build the classifier. Build the classifier directly.
- ▶ That is, rather than assuming a set of distributions (e.g. Gaussian), assume a set of models (e.g. linear), and find the parameters of the model that optimize some classification objective (e.g. based on the statistics of the data in projected space).



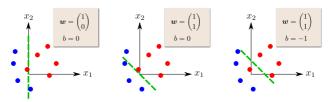
Linear Classifiers

Functions of the type

$$f(\mathbf{x}; \mathbf{w}, b) = \mathbf{w}^{\mathsf{T}} \mathbf{x} + b$$

where $\mathbf{w} \in \mathbb{R}^d$ and $b \in \mathbb{R}$ are parameters to learn. We decide for class ω_1 if $f(\mathbf{x}) > 0$ and for class ω_2 if $f(\mathbf{x}) < 0$.

Examples of linear classifiers on a simple 2d exmaple:



Question: Based on what criterion do we choose the parameters **w**, *b*?



Mean Separation Criterion

Idea:

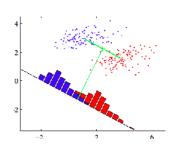
▶ Build a projection the data z = w^Tx with ||w|| = 1 such that the means of classes in projected space are as distant as possible.

Approach:

First, we compute the means in projected space for the two classes

$$\mu_1 = \frac{1}{N_1} \sum_{k \in C_1} z_k \qquad \mu_2 = \frac{1}{N_2} \sum_{k \in C_2} z_k$$

► Then we would like to find w that maximizes the difference of means, i.e. we express the means as a function of w and pose the optimization problem:





$$\arg\max_{\mathbf{w}}|\underline{\mu_2}(\mathbf{w})-\underline{\mu_1}(\mathbf{w})|\qquad \text{with}\quad \|\mathbf{w}\|=1$$

Derivation of Mean Separation

► The constrained optimization problem (subject to the constraint ||w|| = 1) can be developed as:

$$\begin{aligned} & \arg\max_{\mathbf{w}} |\mu_{2}(\mathbf{w}) - \mu_{1}(\mathbf{w})| \\ & = \arg\max_{\mathbf{w}} \left| \frac{1}{N_{2}} \sum_{k \in \mathcal{C}_{2}} z_{k}(\mathbf{w}) - \frac{1}{N_{1}} \sum_{k \in \mathcal{C}_{1}} z_{k}(\mathbf{w}) \right| \\ & = \arg\max_{\mathbf{w}} \left| \frac{1}{N_{2}} \sum_{k \in \mathcal{C}_{2}} \mathbf{w}^{\top} \mathbf{x}_{k} - \frac{1}{N_{1}} \sum_{k \in \mathcal{C}_{1}} \mathbf{w}^{\top} \mathbf{x}_{k} \right| \\ & = \arg\max_{\mathbf{w}} \left| \mathbf{w}^{\top} \left(\frac{1}{N_{2}} \sum_{k \in \mathcal{C}_{2}} \mathbf{x}_{k} \right) - \mathbf{w}^{\top} \left(\frac{1}{N_{1}} \sum_{k \in \mathcal{C}_{1}} \mathbf{x}_{k} \right) \right|^{\frac{1}{2}} \end{aligned}$$

$$= \arg\max_{\mathbf{w}} \left| \mathbf{w}^{\top} \left(\mu_{2} - \mu_{1} \right) \right|$$

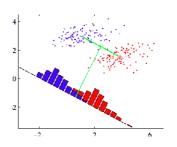
where μ_2 and μ_1 are the means in *input space*.

The best vector **w** is the one that aligns with $(\mu_2 - \mu_1)$, i.e. $\mathbf{w} = (\mu_2 - \mu_1)/||\mu_2 - \mu_1||$.



Limitations of Mean Separation

- ► There is a significant class overlap in projected space.
- A better classifier seems achievable if we rotate the projection a few degrees clockwise.
- Making means distant may not be sufficient to induce class separability in projected space.





Fisher Discriminant



R.A. Fisher (1890 - 1962)

Idea:

In addition to maximizing the separation between class means in projected space, also consider to reduce the within-class variance.

$$\mu_{1} = \frac{1}{|\mathcal{C}_{1}|} \sum_{k \in \mathcal{C}_{1}} z_{k} \qquad \mu_{2} = \frac{1}{|\mathcal{C}_{2}|} \sum_{k \in \mathcal{C}_{2}} z_{k}$$

$$s_{1} = \sum_{k \in \mathcal{C}_{1}} (z_{k} - \mu_{1})^{2} \qquad s_{2} = \sum_{k \in \mathcal{C}_{2}} (z_{k} - \mu_{2})^{2}$$

 Maximizing distance between means while minimizing within-class variance can be formulated as:

$$\arg\max_{w} \frac{(\mu_2(\mathbf{w}) - \mu_1(\mathbf{w}))^2}{s_1(\mathbf{w}) + s_2(\mathbf{w})}$$



Deriving the Fisher Discriminant (1)

The within-class variance can be expanded as:

$$s_{j}(\mathbf{w}) = \sum_{k \in C_{j}} (z_{k} - \mu_{j})^{2}$$

$$= \sum_{k \in C_{j}} (\mathbf{w}^{\top} \mathbf{x}_{k} - \mathbf{w}^{\top} \mu_{j})^{2}$$

$$= \mathbf{w}^{\top} \sum_{k \in C_{j}} (\mathbf{x}_{k} - \mu_{j}) (\mathbf{x}_{k} - \mu_{j})^{\top} \mathbf{w}$$

$$S_{j}$$

where S_j is a scatter matrix (unnormalized covariance matrix) for the data of class j.

Observations:

- Similar structure as the PCA objective (but for each class separately)
- ▶ Unlike PCA, we want to *minimize* the variance rather than maximize it.



Deriving the Fisher Discriminant (2)

Making use of the results of Slide 7 and 10, we can rewrite the Fisher objective

$$J(\mathbf{w}) = \frac{(\mu_2(\mathbf{w}) - \mu_1(\mathbf{w}))^2}{s_1(\mathbf{w}) + s_2(\mathbf{w})}$$

as

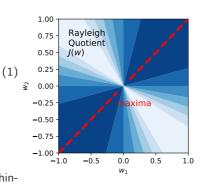
$$J(\mathbf{w}) = \frac{\mathbf{w}^{\mathsf{T}} \mathbf{S}_{B} \mathbf{w}}{\mathbf{w}^{\mathsf{T}} \mathbf{S}_{W} \mathbf{w}}$$

where

$$\mathbf{S}_{B} = (\boldsymbol{\mu}_{2} - \boldsymbol{\mu}_{1})(\boldsymbol{\mu}_{2} - \boldsymbol{\mu}_{1})^{\mathsf{T}}$$

 $\mathbf{S}_{W} = S_{1} + S_{2}$

are the 'Between-Class' and 'Within-Class' scatter matrices respectively. The form of Eq. (1) is known as *Rayleigh Coefficient*.

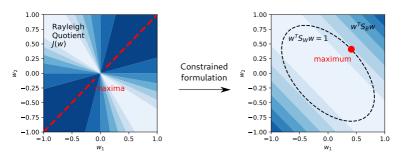




Deriving the Fisher Discriminant (3)

A solution that maximizes the Rayleigh quotient $J(\mathbf{w})$ can be obtained by first observing that $\forall_{\alpha\neq 0}: J(\alpha\mathbf{w}) = J(\mathbf{w})$ and searching for the particular solution for which the denominator is exactly one. This can be stated as the constrained optimization problem

$$\arg\max_{\mathbf{w}} \mathbf{w}^{\mathsf{T}} \mathbf{S}_{B} \mathbf{w} \quad \text{s.t.} \quad \mathbf{w}^{\mathsf{T}} \mathbf{S}_{W} \mathbf{w} = 1$$





Deriving the Fisher Discriminant (4)

We start with the constrained optimization problem:

$$\underset{\mathbf{w}}{\operatorname{arg}} \underset{\mathbf{w}}{\operatorname{max}} \mathbf{w}^{\mathsf{T}} \mathbf{S}_{\mathcal{B}} \mathbf{w} \quad \text{s.t.} \quad \mathbf{w}^{\mathsf{T}} \mathbf{S}_{\mathcal{W}} \mathbf{w} = 1$$

Method of Lagrange Multipliers

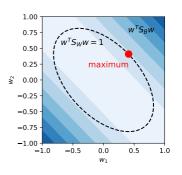
Step 1: We build the Lagrangian

$$\mathcal{L}(\mathbf{w}, \lambda) = \mathbf{w}^{\top} \mathbf{S}_{B} \mathbf{w} + \lambda \cdot (1 - \mathbf{w}^{\top} \mathbf{S}_{W} \mathbf{w})$$

Step 2: We look for potential solutions by posing $\nabla \mathcal{L}(\mathbf{w}, \lambda) = \mathbf{0}$, which leads to the equation:

$$\mathsf{S}_{\mathcal{B}}\,\mathsf{w}=\lambda\mathsf{S}_{\mathcal{W}}\,\mathsf{w}$$

This is a generalized eigenvalue problem.



Deriving the Fisher Discriminant (5)

Further steps:

If S_W is invertible, it can be restated as the standard eigenvalue problem

$$(\mathbf{S}_W^{-1}\mathbf{S}_B)\mathbf{w} = \lambda\mathbf{w}$$

 \triangleright Expanding the term S_B , we get:

$$\mathbf{S}_{W}^{-1}(\boldsymbol{\mu}_{2} - \boldsymbol{\mu}_{1}) \underbrace{(\boldsymbol{\mu}_{2} - \boldsymbol{\mu}_{1})^{\mathsf{T}} \mathbf{w}}_{\text{scalar!}} = \lambda \mathbf{w}$$

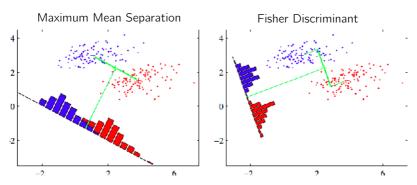
▶ Therefore, one possible solution for **w** is given by

$$\mathbf{w} = \mathbf{S}_W^{-1}(\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)$$

(Reminder, in our original Rayleigh quotient formulation, $J(\alpha \mathbf{w}) = J(\mathbf{w})$, i.e. the optimum is defined up to a scaling factor.)



Mean Separation vs. Fisher Discriminant



- Fisher Discriminant leads (in general) to better class separability, and therefore, better classification accuracy.
- ► Fisher Discriminant requires inversion of a covariance matrix (only tractable for low-dimensional data).



Decision Theory vs. Fisher Discriminant

Bayes decision theory (Lecture 1)

Discriminant has the form

$$\mathbf{w} = \mathbf{\Sigma}^{-1}(\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)$$

- ...under the assumption that the data-generating distributions are *Gaussian* (with means μ_1, μ_2 for each class, and *same* covariance Σ).
- Bias is also given by the analysis (cf. Slide 2).

Fisher discriminant (today)

Discriminant has the form

$$\mathbf{w} = \mathbf{S}_W^{-1}(\boldsymbol{\mu}_2 - \boldsymbol{\mu}_1)$$

- No generative assumption. Classifier only derived from a criterion on mean and dispersion of data in projected space.
- Bias is not provided by the analysis but it can be fitted in a second step.



Application: P300 BCI Speller

```
A B C D E F
G H I J K L
M N O P Q R
S T U V W X
Y Z 1 2 3 4
5 6 7 8 9 _
```



BCI with ML: Calibration and Feedback

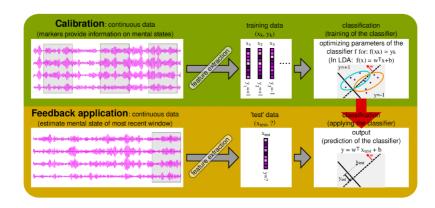
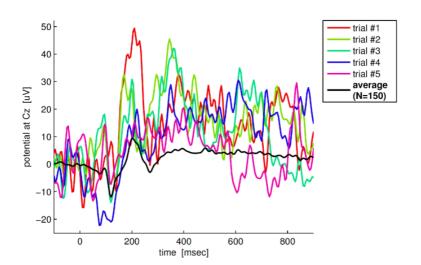


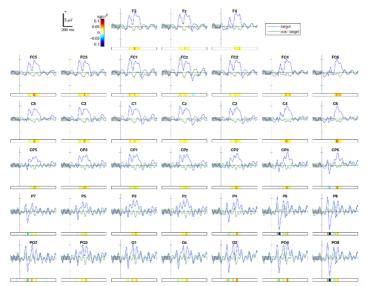


Illustration: Single-Trials and ERPs



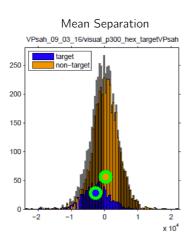


Scalp Potentials In Response to (Non-)Targets

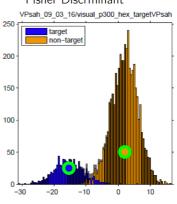




A BCI example: P300 speller



Fisher Discrminant





Fisher Discriminant (Strengths/Limitations)

Strengths:

- ► Accurate when the means/covariances describe well the data, and close to optimal when the data is Gaussian of fixed covariance.
- ▶ The Fisher discriminant is given in closed form and is fast to compute.

Limitations:

- Although applicable to non-Gaussian distributions, the resulting decision boundary can become in that case strongly suboptimal.
- In particular, like principal component analysis, Fisher Discriminant is not robust to outliers.

Idea:

➤ To overcome these limitations, we will discuss other learning algorithms that more specifically focus on modeling the decision boundary between the two classes.



The Perceptron



F. Rosenblatt (1928-1971)

- Proposed by F. Rosenblatt in 1958.
- Classifier that prefectly separates training data (if the data is linearly separable).
- Trained using an simple and cheap iterative procedure.
- The perceptron gave rise to artificial neural networks.

The Perceptron Algorithm

Consider our linear model

$$z_k = \mathbf{w}^{\mathsf{T}} \mathbf{x}_k + b$$
 $y_k = \operatorname{sign}(z_k)$

and let t_k be 1 and -1 when the true class of \mathbf{x}_k is ω_1 and ω_2 respectively.

Algorithm

- lterate over all examples k = 1..., N (multiple times).
 - If example \mathbf{x}_k is correctly classified $(y_k = t_k)$, continue.
 - If example \mathbf{x}_k is wrongly classified $(y_k \neq t_k)$, apply:

$$\mathbf{w} \leftarrow \mathbf{w} + \eta \cdot \mathbf{x}_k t_k \tag{2}$$

$$b \leftarrow b + \eta \cdot t_k \tag{3}$$

where η is a learning rate.

▶ The algorithm stops once all examples are correctly classified.



The Perceptron: Optimization View

▶ The perceptron can be seen as the minimization of the error function

$$\mathcal{E}(\mathbf{w},b) = \frac{1}{N} \sum_{k=1}^{N} \underbrace{\max(0, -z_k t_k)}_{\mathcal{E}_k(\mathbf{w}, b)}$$

Proof: Computing the gradient of \mathcal{E}_k gives

$$\nabla_{\mathbf{w}} \mathcal{E}_{k}(\mathbf{w}, b) = 1_{-z_{k}t_{k}>0} \cdot (-\mathbf{x}_{k}t_{k})$$

$$= 1_{y_{k}\neq t_{k}} \cdot (-\mathbf{x}_{k}t_{k})$$

$$= \begin{cases} 0 & y_{k} = t_{k} \\ -\mathbf{x}_{k}t_{k} & y_{k} \neq t_{k} \end{cases}$$

And we observe that the update rule $\mathbf{w} \leftarrow \mathbf{w} - \eta \cdot \nabla_{\mathbf{w}} \mathcal{E}_{k}(\mathbf{w}, b)$ is equivalent to that of Eq. (2)

Similar result can be obtained for the bias.



The Perceptron: Optimization View

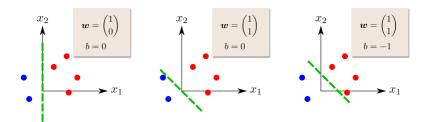
Recall: The objective function corresponding to the perceptron algorithm is given by:

$$\mathcal{E}(\mathbf{w},b) = \frac{1}{N} \sum_{k=1}^{N} \underbrace{\max(0, -z_k t_k)}_{\mathcal{E}_k(\mathbf{w}, b)}$$

- This objective can be interpreted as measuring for each wrongly classified data point how far the data point is from the decision boundary, and penalizing accordingly.
- In practice various strategies can be implemented to optimize this objective (e.g. gradient descent on $\mathcal{E}(\mathbf{w}, b)$ directly, or adding momentum to the gradient descent).
- Optimization of the objective also works for data that is not linearly separable.



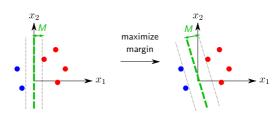
A Problem of the Perceptron



- All these solutions have an error $\mathcal{E}(\mathbf{w}, b) = 0$.
- Some solutions are obviously better than other, e.g. those where the decision boundary is separated from the data with a large margin.



Large Margin Classifiers



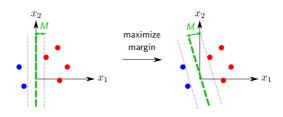
Idea: Induce large margin M by redefining the optimization problem as:

$$\underbrace{\arg\min_{\mathbf{w},b,M}}_{(1)} \left[\underbrace{\frac{1}{M}}_{(2)} + \frac{1}{N} \sum_{k=1}^{N} \underbrace{\max(0, M - (\mathbf{w}^{\top} \mathbf{x}_k + b)t_k)}_{(3)} \right] \quad \text{s.t.} \quad \underbrace{\|\mathbf{w}\| = 1}_{(4)} \quad (4)$$

- ▶ (1) actively optimize the margin
- ▶ (2) apply a penalty if the margin is too large
- (3) apply a penalty if some points violate the margin and
- \triangleright (4) constrain the projection so that M is interpretable as a margin.



Large Margin Classifiers



► An equivalent (and more standard) formulation of the optimization problem is given by:

$$\arg\min_{\mathbf{w},b} \frac{1}{N} \sum_{k=1}^{N} \max(0, 1 - (\mathbf{w}^{\top} \mathbf{x}_k + b) t_k) + \|\mathbf{w}\|^2$$
 (5)

(proof in next slide).

- Large Margin Classifiers are typically solved using (stochastic) gradient descent or quadratic programming.
- More will be said about these model during the lecture on support vector machines.

Derivation of Eq. (5) from Eq. (4)

$$\arg\min_{\mathbf{w},b,M}\frac{1}{N}\sum_{k=1}^{N}\max(0,M-(\mathbf{w}^{\top}\mathbf{x}_{k}+b)t_{k})+\frac{1}{M}\quad\text{s.t.}\quad\|\mathbf{w}\|=1$$

The same objective can be rewritten as:

$$=\arg\min_{\mathbf{w},b,M}\frac{1}{N}\sum_{k=1}^{N}\max(0,M-(\mathbf{w}^{\top}\mathbf{x}_{k}+b)t_{k})+\frac{\|\mathbf{w}\|^{2}}{M}\quad\text{s.t.}\quad\|\mathbf{w}\|=1$$

Dividing by M does not change the argmin nor the constraint

$$=\arg\min_{\mathbf{w},b,M}\frac{1}{N}\sum_{k=1}^{N}\max(0,1-(\frac{\mathbf{w}^{\top}}{M}\mathbf{x}_{k}+\frac{b}{M})\mathbf{t}_{k})+\frac{\|\mathbf{w}\|^{2}}{M^{2}}\quad\text{s.t.}\quad\frac{\|\mathbf{w}\|}{M}=\frac{1}{M}$$

and redefining $w \leftarrow w/M$ and $b \leftarrow b/M$, we get:

$$=\arg\min_{\mathbf{w},b,M}\frac{1}{N}\sum_{k=1}^{N}\max(0,1-(\mathbf{w}^{\mathsf{T}}\mathbf{x}_{k}+b)t_{k})+\|\mathbf{w}\|^{2}\quad\text{s.t.}\quad\|\mathbf{w}\|=\frac{1}{M}$$

Because optimizing w.r.t. M is now trivial, we can further simplify to

 $= \arg\min_{\mathbf{w},b} \frac{1}{N} \sum_{k=1}^{N} \max(0, 1 - (\mathbf{w}^{\top} \mathbf{x}_{k} + b) t_{k}) + \|\mathbf{w}\|^{2}$





Advanced Classification Topics

- ▶ Nonlinear Classification (Kernel SVM, Artificial Neural Networks, Decision Trees, Random Forests, Boosting). (Covered in ML1)
- ► Incorporating **prior knowledge** such as invariances into a classifier. Example: the convolutional neural network. (Covered in ML2)
- Classification in high dimensions: Unintuitively, methods that actually promote within-class variance instead of reducing it tend to perform better in this setting.



Summary

- ▶ In practice, it is preferable to **train a classifier directly** rather than learning the class distributions in the first place.
- ► The maximum mean separation and Fisher discriminant are two such instances, where one only needs to estimate the mean and the covariance of the data, without having to estimate full distributions.
- ► The **perceptron** (and its **large-margin** extension) more specifically focus on the decision boundary, which typically leads to higher classification accuracy on general tasks.

