

Actividad 8.1 (SLAM de Lidar)

Implementación de robótica inteligente

Grupo 501

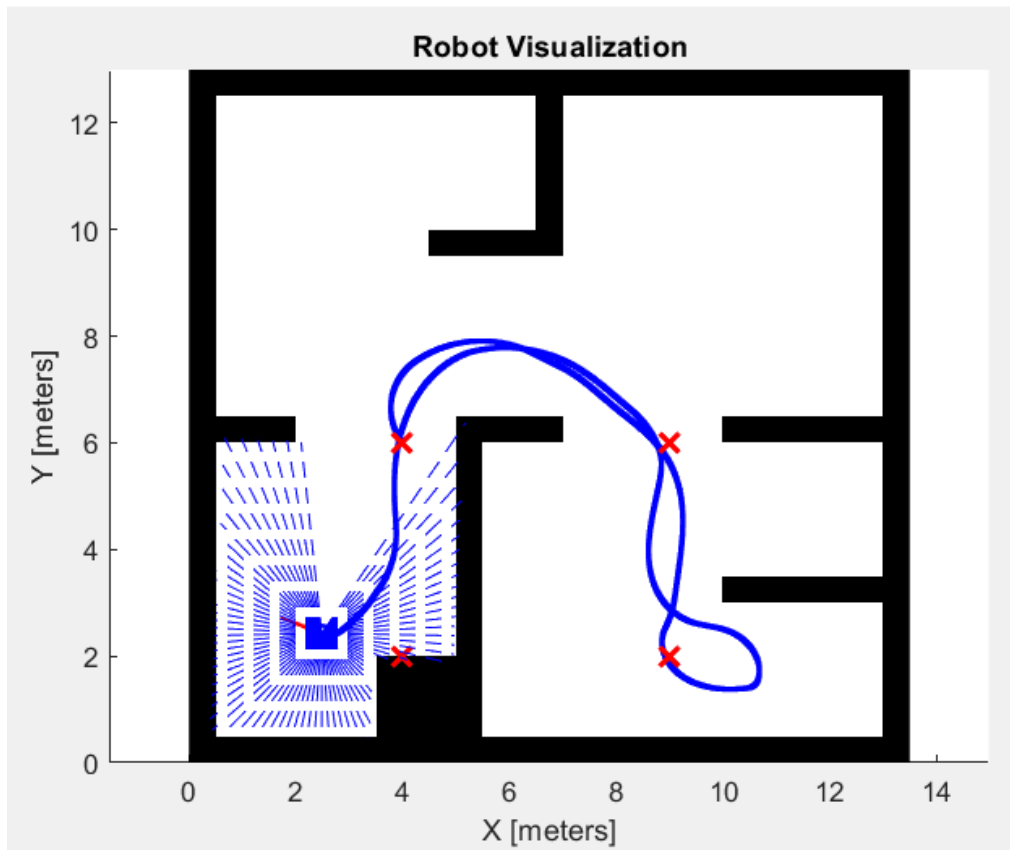
Yonathan Romero Amador

A01737244

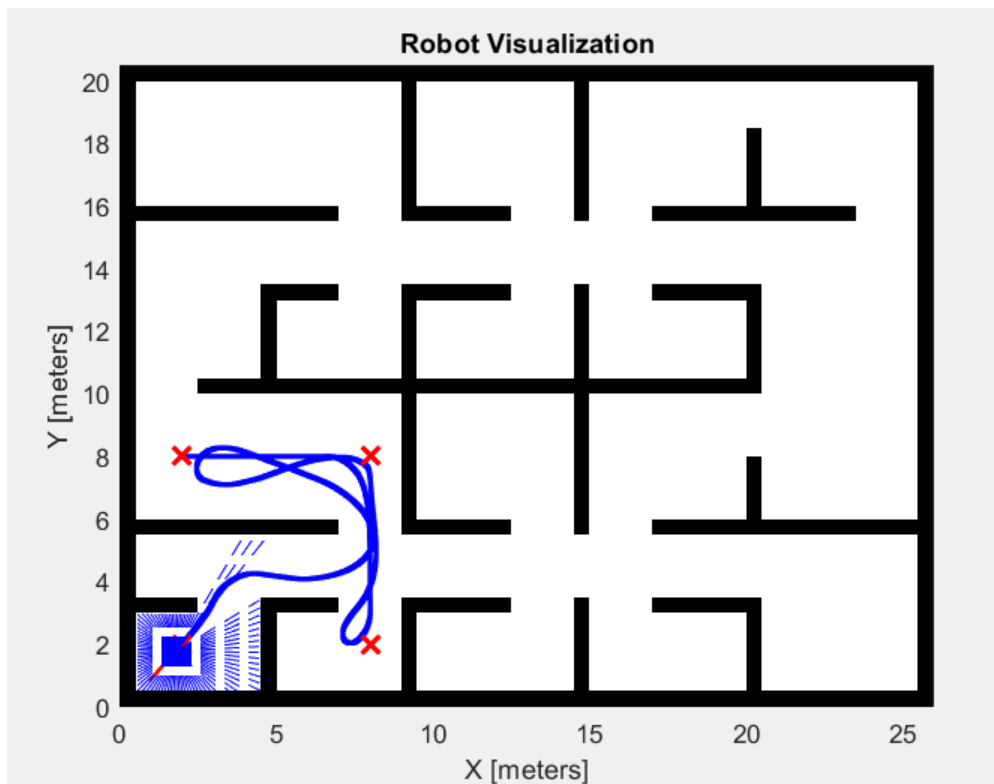
22 de Mayo del 2025

Patrón 1

- *exampleMap*

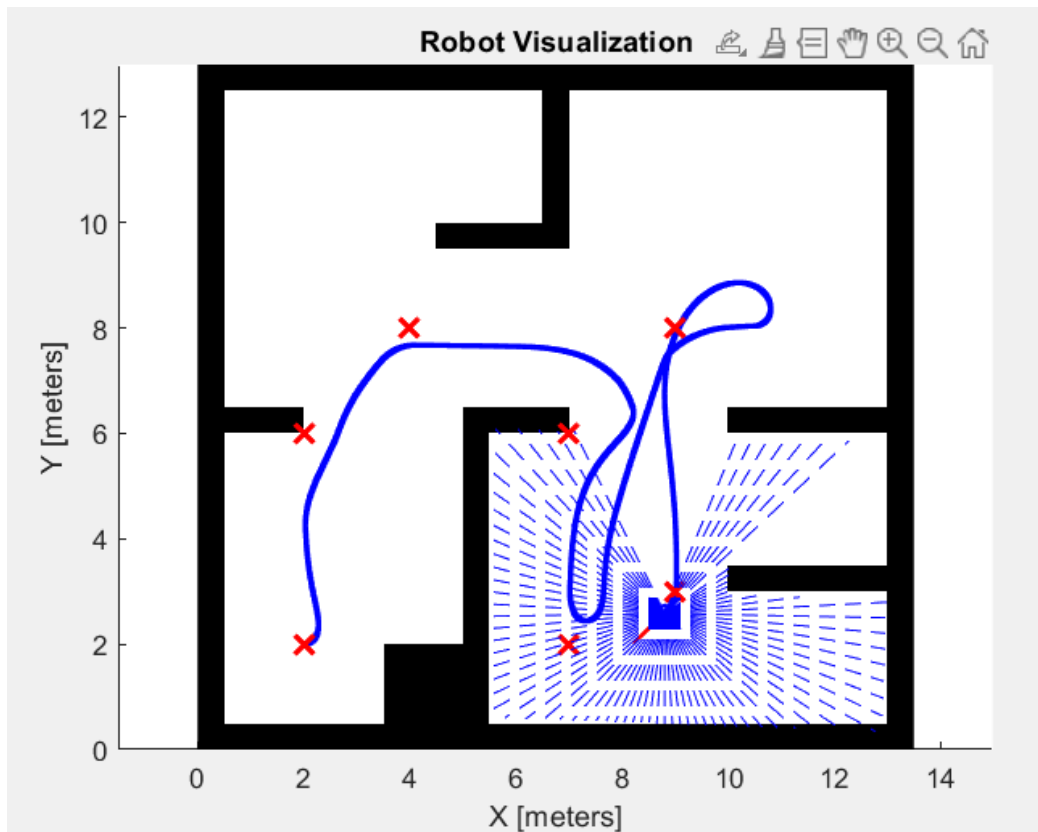


- *complexMap*

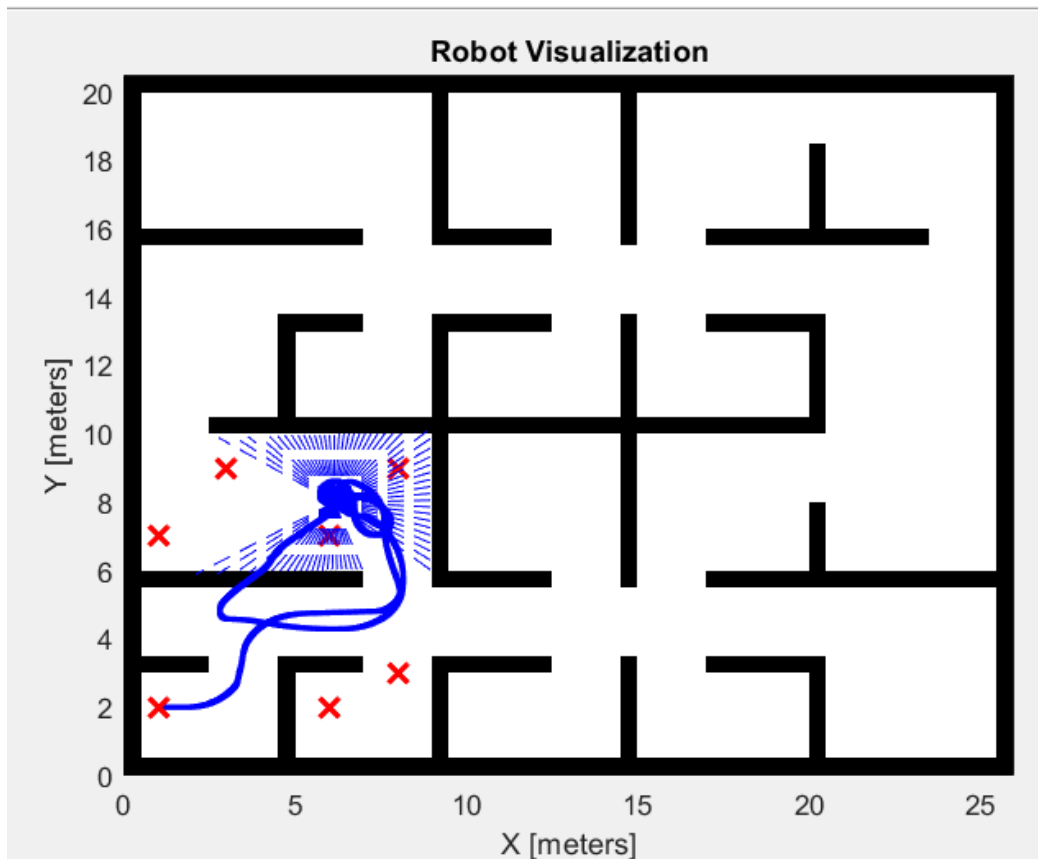


Patrón 2

- exampleMap

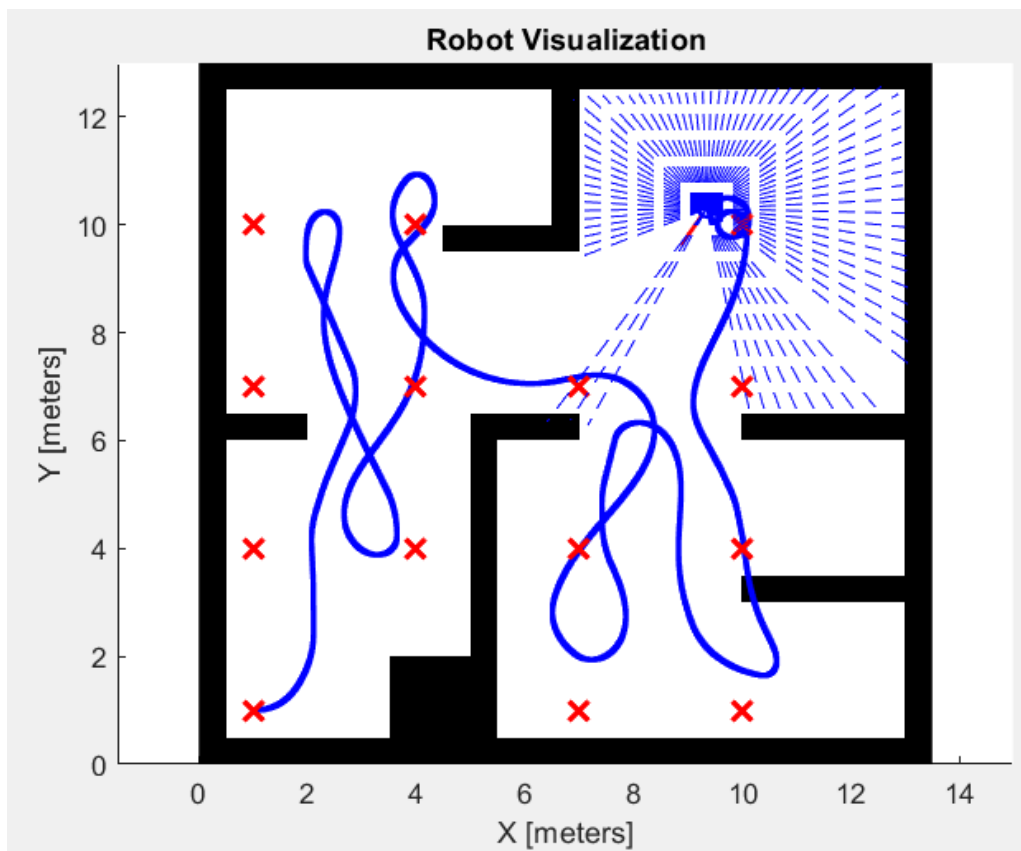


- complexMap



Patrón 3

- *exampleMap*



- *complexMap*

