

Adaptive sparse grids and quasi Monte Carlo for option pricing under the rough Bergomi model

Chiheb Ben Hammouda



Christian Bayer



Raúl Tempone



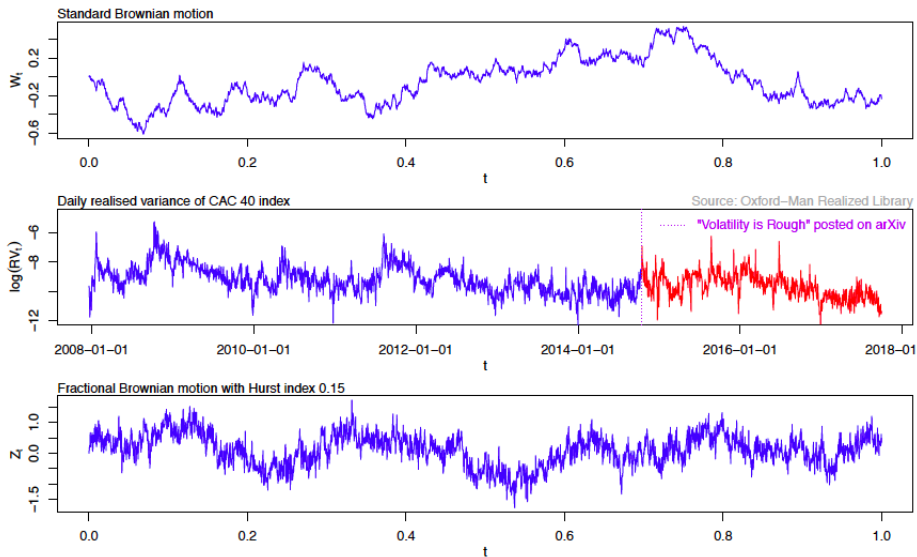
3rd International Conference on Computational Finance
(ICCF2019), A Coruña
8-12 July, 2019

Outline

- ➊ Option Pricing under the Rough Bergomi Model: Motivation & Challenges
- ➋ Our Hierarchical Deterministic Quadrature Methods
- ➌ Numerical Experiments and Results
- ➍ Conclusions

- 1 Option Pricing under the Rough Bergomi Model: Motivation & Challenges
- 2 Our Hierarchical Deterministic Quadrature Methods
- 3 Numerical Experiments and Results
- 4 Conclusions

Rough volatility [Gatheral et al., 2018]



The rough Bergomi model [Bayer et al., 2016]

This model, under a pricing measure, is given by

$$\begin{cases} dS_t &= \sqrt{v_t} S_t dZ_t, \\ v_t &= \xi_0(t) \exp \left(\eta \widetilde{W}_t^H - \frac{1}{2} \eta^2 t^{2H} \right), \\ Z_t &:= \rho W_t^1 + \bar{\rho} W_t^\perp \equiv \rho W^1 + \sqrt{1 - \rho^2} W^\perp, \end{cases} \quad (1)$$

- (W^1, W^\perp) : two independent standard Brownian motions
- \widetilde{W}^H is **Riemann-Liouville process**, defined by

$$\begin{aligned} \widetilde{W}_t^H &= \int_0^t K^H(t-s) dW_s^1, \quad t \geq 0, \\ K^H(t-s) &= \sqrt{2H}(t-s)^{H-1/2}, \quad \forall 0 \leq s \leq t. \end{aligned}$$

- $H \in (0, 1/2]$ ($H = 1/2$ for Brownian motion): controls the **roughness** of paths, $\rho \in [-1, 1]$ and $\eta > 0$.
- $t \mapsto \xi_0(t)$: forward variance curve, known at time 0.

Model challenges

- **Numerically:**

- ▶ The model is **non-affine** and **non-Markovian** \Rightarrow Standard numerical methods (PDEs, characteristic functions) seem **inapplicable**.
- ▶ The only prevalent pricing method for mere **vanilla options** is **Monte Carlo (MC)** [Bayer et al., 2016, Bayer et al., 2017, McCrickerd and Pakkanen, 2018]: still a **time consuming task**.
- ▶ Discretization methods have **poor behavior of the strong error**, that is the convergence rate is of order of $H \in [0, 1/2]$ [Neuenkirch and Shalaiko, 2016] \Rightarrow Variance reduction methods, such as **multilevel Monte Carlo (MLMC)**, are inefficient for **very small values** of H .

- **Theoretically:**

- ▶ No proper weak error analysis done in the rough volatility context.

Option pricing challenges

The integration problem is **challenging**

- **Issue 1:** Time-discretization of the rough Bergomi process (large N (number of time steps)) $\Rightarrow S$ takes values in a high-dimensional space \Rightarrow **Curse of dimensionality** when using numerical integration methods.
- **Issue 2:** The payoff function g is typically **not smooth** \Rightarrow **low regularity** \Rightarrow slow convergence of deterministic quadrature methods.

⚠ Curse of dimensionality: An exponential growth of the work (number of function evaluations) in terms of the dimension of the integration problem.

Methodology [Bayer et al., 2018]

We design a **hierarchical efficient pricing method** based on

- ① **Analytic smoothing** to uncover available regularity (inspired by [Romano and Touzi, 1997] in the context of stochastic volatility models).
- ② Approximating the option price using **deterministic quadrature methods**
 - ▶ **Adaptive sparse grids quadrature (ASGQ).**
 - ▶ **Quasi Monte Carlo (QMC).**
- ③ Coupling our methods with **hierarchical representations** \Rightarrow **Reduce the dimension** of the problem.
 - ▶ **Brownian bridges** as a Wiener path generation method.
 - ▶ **Richardson Extrapolation** (**Condition: weak error of order 1**)
 \Rightarrow Faster convergence of the weak error $\Rightarrow \searrow$ number of time steps (smaller dimension).

Simulation of the rough Bergomi dynamics

Goal: Simulate jointly $(W_t^1, \widetilde{W}_t^H : 0 \leq t \leq T)$, resulting in $W_{t_1}^1, \dots, W_{t_N}^1$ and $\widetilde{W}_{t_1}^H, \dots, \widetilde{W}_{t_N}^H$ along a given grid $t_1 < \dots < t_N$

① Covariance based approach [Bayer et al., 2016]

- ▶ Based on Cholesky decomposition of the covariance matrix of the $(2N)$ -dimensional Gaussian random vector

$$W_{t_1}^1, \dots, W_{t_N}^1, \widetilde{W}_{t_1}^H, \dots, \widetilde{W}_{t_N}^H.$$

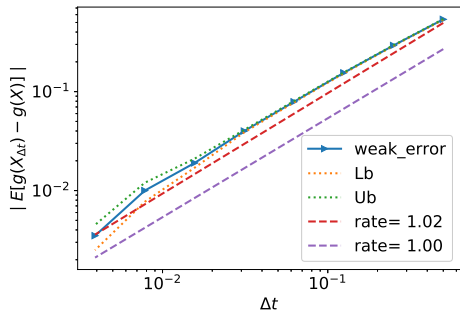
- ▶ Exact method but slow
- ▶ At least $\mathcal{O}(N^2)$.

② The hybrid scheme [Bennedsen et al., 2017]

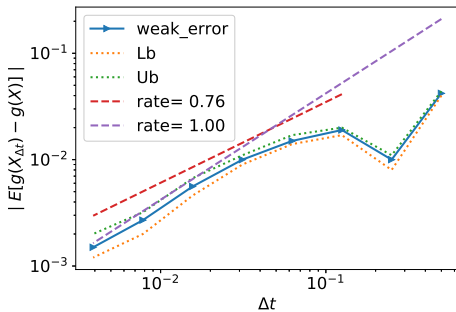
- ▶ Based on Euler discretization but crucially improved by moment matching for the singular term in the left point rule.
- ▶ Accurate scheme that is much faster than the Covariance based approach.
- ▶ $\mathcal{O}(N)$ up to logarithmic factors that depend on the desired error.

On the choice of the simulation scheme

Figure 1.1: The convergence of the weak error \mathcal{E}_B , using MC with 6×10^6 samples, for example parameters: $H = 0.07$, $K = 1$, $S_0 = 1$, $T = 1$, $\rho = -0.9$, $\eta = 1.9$, $\xi_0 = 0.0552$. The upper and lower bounds are 95% confidence intervals. a) With the hybrid scheme b) With the exact scheme.



(a)



(b)

- 1 Option Pricing under the Rough Bergomi Model: Motivation & Challenges
- 2 Our Hierarchical Deterministic Quadrature Methods
- 3 Numerical Experiments and Results
- 4 Conclusions

Conditional expectation for analytic smoothing

$$\begin{aligned}C_{RB}(T, K) &= E \left[(S_T - K)^+ \right] \\&= E \left[E \left[(S_T - K)^+ \mid \sigma(W^1(t), t \leq T) \right] \right] \\&= E \left[C_{BS} \left(S_0 = \exp \left(\rho \int_0^T \sqrt{v_t} dW_t^1 - \frac{1}{2} \rho^2 \int_0^T v_t dt \right), \right. \right. \\&\quad \left. \left. k = K, \sigma^2 = (1 - \rho^2) \int_0^T v_t dt \right) \right] \\&\approx \int_{\mathbb{R}^{2N}} C_{BS} \left(G(\mathbf{w}^{(1)}, \mathbf{w}^{(2)}) \right) \rho_N(\mathbf{w}^{(1)}) \rho_N(\mathbf{w}^{(2)}) d\mathbf{w}^{(1)} d\mathbf{w}^{(2)} \\&= C_{RB}^N.\end{aligned}\tag{2}$$

- $C_{BS}(S_0, k, \sigma^2)$: the Black-Scholes call price, for initial spot price S_0 , strike price k , and volatility σ^2 .
- G maps $2N$ independent standard Gaussian random inputs to the parameters fed to Black-Scholes formula.
- ρ_N : the multivariate Gaussian density, N : number of time steps.

Numerical integration methods

- **Plain Monte Carlo (MC)**

- ▶ $\varepsilon(M) = \mathcal{O}(M^{-1/2})$
- ▶ (+) insensitive to d , (−) slow convergence, no profit from regularity.

- **Classical Quasi-Monte Carlo (QMC)**

- ▶ $\varepsilon(M) = \mathcal{O}(M^{-1} \log(M)^{d-1})$
- ▶ (+) better convergence, (−) sensitive to d , no profit from regularity.

- **Quadrature based on product approaches**

- ▶ $\varepsilon(M) = \mathcal{O}(M^{-r/d})$
- ▶ (+) profits from regularity, (−) highly sensitive to d .

- **Sparse grids quadrature (SGQ)**

- ▶ $\varepsilon(M) = \mathcal{O}(M^{-s} \log(M)^{(d-1)(s+1)})$
- ▶ (+) profits from regularity, less sensitive to d .

ε : prescribed accuracy, M : the amount of work, d : dimension of problem, r, s : smoothness indices.

⚠ In our context, $d = 2N$ where N is the number of time steps used for simulating the rough Bergomi dynamics.

Sparse grids I [Bungartz and Griebel, 2004]

Goal: Given $F : \mathbb{R}^d \rightarrow \mathbb{R}$ and a multi-index $\beta \in \mathbb{N}_+^d$, **approximate**

$$\mathbb{E}[F] \approx Q^{m(\beta)}[F],$$

where $Q^{m(\beta)}$ a Cartesian quadrature grid with $m(\beta_n)$ points along y_n .

Idea: Denote $Q^{m(\beta)}[F] = F_\beta$ and introduce the **first difference operator**

$$\Delta_i F_\beta \begin{cases} F_\beta - F_{\beta - e_i}, & \text{if } \beta_i > 1 \\ F_\beta & \text{if } \beta_i = 1 \end{cases}$$

where e_i denotes the i th d -dimensional unit vector, and **mixed difference operators**

$$\Delta[F_\beta] = \otimes_{i=1}^d \Delta_i F_\beta$$

Sparse grids II [Bungartz and Griebel, 2004]

A quadrature estimate of $E[F]$ is

$$\mathcal{M}_{\mathcal{I}_\ell}[F] = \sum_{\beta \in \mathcal{I}_\ell} \Delta[F_\beta], \quad (3)$$

- **Product approach:** $\mathcal{I}_\ell = \{\max\{\beta_1, \dots, \beta_d\} \leq \ell; \beta \in \mathbb{N}_+^d\}$
- **Regular SG:** $\mathcal{I}_\ell = \{|\beta|_1 \leq \ell + d - 1; \beta \in \mathbb{N}_+^d\}$

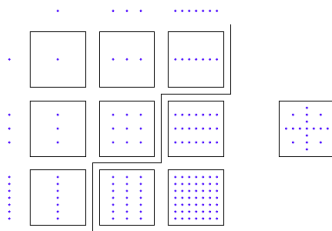


Figure 2.1: Left are product grids $\Delta_{\beta_1} \otimes \Delta_{\beta_2}$ for $1 \leq \beta_1, \beta_2 \leq 3$. Right is the corresponding SG construction.

- **ASGQ:** $\mathcal{I}_\ell = \mathcal{I}^{\text{ASGQ}}$.

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- **Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- **Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- **Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

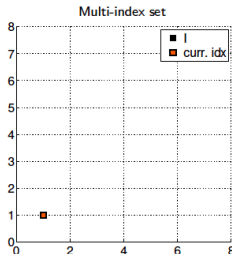


Figure 2.2: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- **Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- **Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- **Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

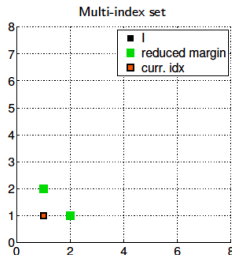


Figure 2.3: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one.

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

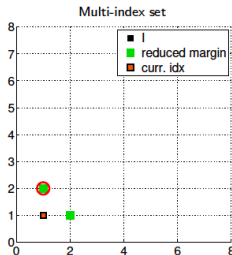


Figure 2.4: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one.

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- **Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- **Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- **Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

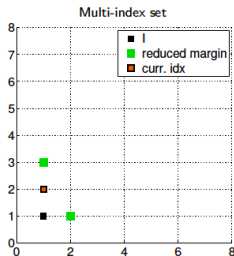


Figure 2.5: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one.

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

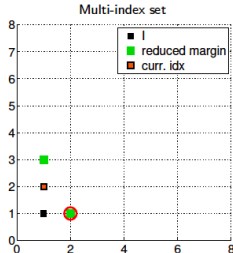


Figure 2.6: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one.

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- **Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- **Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- **Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

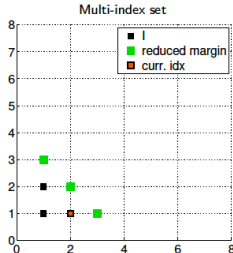


Figure 2.7: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one.

ASGQ in practice

- The construction of $\mathcal{I}^{\text{ASGQ}}$ is done by **profit thresholding**

$$\mathcal{I}^{\text{ASGQ}} = \{\beta \in \mathbb{N}_+^d : P_\beta \geq \bar{T}\}.$$

- Profit of a hierarchical surplus** $P_\beta = \frac{|\Delta E_\beta|}{\Delta \mathcal{W}_\beta}$.
- Error contribution:** $\Delta E_\beta = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} - \mathcal{M}^{\mathcal{I}}|$.
- Work contribution:** $\Delta \mathcal{W}_\beta = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] - \text{Work}[\mathcal{M}^{\mathcal{I}}]$.

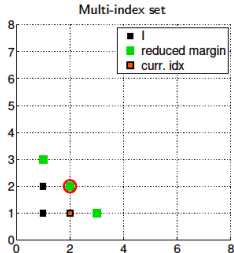


Figure 2.8: **A posteriori, adaptive construction** as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one.

Randomized QMC

- A (rank-1) lattice rule [Sloan, 1985, Nuyens, 2014] with n points

$$Q_n(f) := \frac{1}{n} \sum_{k=0}^{n-1} f\left(\frac{kz \bmod n}{n}\right),$$

where $z = (z_1, \dots, z_d) \in \mathbb{N}^d$.

- A randomly shifted lattice rule

$$\overline{Q}_{n,q}(f) = \frac{1}{q} \sum_{i=0}^{q-1} Q_n^{(i)}(f) = \frac{1}{q} \sum_{i=0}^{q-1} \left(\frac{1}{n} \sum_{k=0}^{n-1} f\left(\frac{kz + \Delta^{(i)} \bmod n}{n}\right) \right), \quad (4)$$

where $\{\Delta^{(i)}\}_{i=1}^q$: independent random shifts, and $M^{\text{QMC}} = q \times n$.

- ▶ Unbiased approximation of the integral.
- ▶ Practical error estimate.
- We use a pre-made point generators using latticeseq_b2.py from <https://people.cs.kuleuven.be/~dirk.nuyens/qmc-generators/>.

Wiener path generation methods

$\{t_i\}_{i=0}^N$: Grid of time steps, $\{B_{t_i}\}_{i=0}^N$: Brownian motion increments

- **Random Walk**

- ▶ Proceeds incrementally, given B_{t_i} ,

$$B_{t_{i+1}} = B_{t_i} + \sqrt{\Delta t} z_i, \quad z_i \sim \mathcal{N}(0, 1).$$

- ▶ All components of $\mathbf{z} = (z_1, \dots, z_N)$ have the same scale of importance: **isotropic**.

- **Hierarchical Brownian Bridge** [Glasserman, 2004]

- ▶ Given a past value B_{t_i} and a future value B_{t_k} , the value B_{t_j} (with $t_i < t_j < t_k$) can be generated according to ($\rho = \frac{j-i}{k-i}$)

$$B_{t_j} = (1 - \rho)B_{t_i} + \rho B_{t_k} + \sqrt{\rho(1 - \rho)(k - i)\Delta t} z_j, \quad z_j \sim \mathcal{N}(0, 1).$$

- ▶ The most important values (determine the large scale structure of Brownian motion) are the first components of $\mathbf{z} = (z_1, \dots, z_N)$.
- ▶ \searrow the **effective dimension** (# important dimensions) and \nearrow **anisotropy** between different directions \Rightarrow **Faster** ASGQ and QMC convergence.

Error comparison

\mathcal{E}_{tot} : the total error of approximating the expectation in (2).

- When using ASGQ estimator, Q_N

$$\mathcal{E}_{\text{tot}} \leq |C_{\text{RB}} - C_{\text{RB}}^N| + |C_{\text{RB}}^N - Q_N| \leq \mathcal{E}_B(N) + \mathcal{E}_Q(\text{TOL}_{\text{ASGQ}}, N),$$

where \mathcal{E}_Q is the quadrature error, \mathcal{E}_B is the bias, TOL_{ASGQ} is a user selected tolerance for ASGQ method.

- When using randomized QMC or MC estimator, $Q_N^{\text{MC (QMC)}}$

$$\mathcal{E}_{\text{tot}} \leq |C_{\text{RB}} - C_{\text{RB}}^N| + |C_{\text{RB}}^N - Q_N^{\text{MC (QMC)}}| \leq \mathcal{E}_B(N) + \mathcal{E}_S(M, N),$$

where \mathcal{E}_S is the statistical error, M is the number of samples used for MC or randomized QMC method.

- M^{QMC} and M^{MC} , are chosen so that $\mathcal{E}_{S, \text{QMC}}(M^{\text{QMC}})$ and $\mathcal{E}_{S, \text{MC}}(M^{\text{MC}})$ satisfy

$$\mathcal{E}_{S, \text{QMC}}(M^{\text{QMC}}) = \mathcal{E}_{S, \text{MC}}(M^{\text{MC}}) = \mathcal{E}_B(N) = \frac{\mathcal{E}_{\text{tot}}}{2}.$$

- 1 Option Pricing under the Rough Bergomi Model: Motivation & Challenges
- 2 Our Hierarchical Deterministic Quadrature Methods
- 3 Numerical Experiments and Results**
- 4 Conclusions

Numerical experiments

Table 1: Reference solution (using MC with 500 time steps and number of samples, $M = 8 \times 10^6$) of call option price under the rough Bergomi model, for different parameter constellations. The numbers between parentheses correspond to the statistical errors estimates.

Parameters	Reference solution
Set 1: $H = 0.07, K = 1, S_0 = 1, T = 1, \rho = -0.9, \eta = 1.9, \xi_0 = 0.0552$	0.0791 ($5.6e-05$)
Set 2: $H = 0.02, K = 1, S_0 = 1, T = 1, \rho = -0.7, \eta = 0.4, \xi_0 = 0.1$	0.1246 ($9.0e-05$)
Set 3: $H = 0.02, K = 0.8, S_0 = 1, T = 1, \rho = -0.7, \eta = 0.4, \xi_0 = 0.1$	0.2412 ($5.4e-05$)
Set 4: $H = 0.02, K = 1.2, S_0 = 1, T = 1, \rho = -0.7, \eta = 0.4, \xi_0 = 0.1$	0.0570 ($8.0e-05$)

- Set 1 is the **closest to the empirical findings** [Gatheral et al., 2018, Bennedsen et al., 2016], suggesting that $H \approx 0.1$. The choice of values $\nu = 1.9$ and $\rho = -0.9$ is justified by [Bayer et al., 2016].
- For the remaining three sets, we wanted to test the potential of our method for a **very rough case**, where variance reduction methods are inefficient.

Relative errors and computational gains

Table 2: In this table, we highlight the computational gains achieved by ASGQ and QMC over MC method to meet a certain error tolerance. We note that the ratios are computed **for the best configuration with Richardson extrapolation for each method.**

Parameters	Relative error	CPU time ratio (MC/ASGQ)	CPU time ratio (MC/QMC)
Set 1	1%	15	10
Set 2	0.2%	21.5	73.2
Set 3	0.4%	26.7	21.3
Set 4	2%	5	10

Computational work of the MC method with different configurations

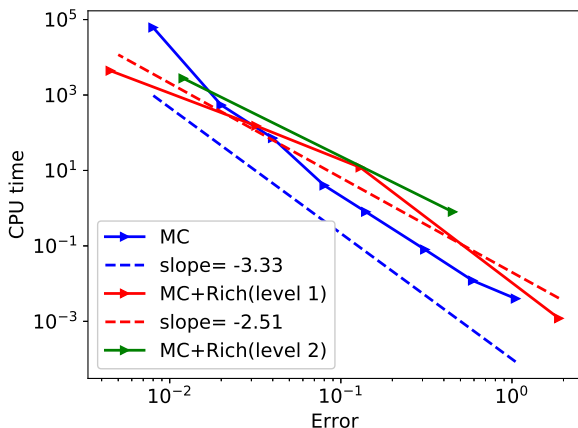


Figure 3.1: Computational work of the MC method with the different configurations in terms of Richardson extrapolation 's level. Case of parameter set 1 in Table 1.

Computational work of the QMC method with different configurations

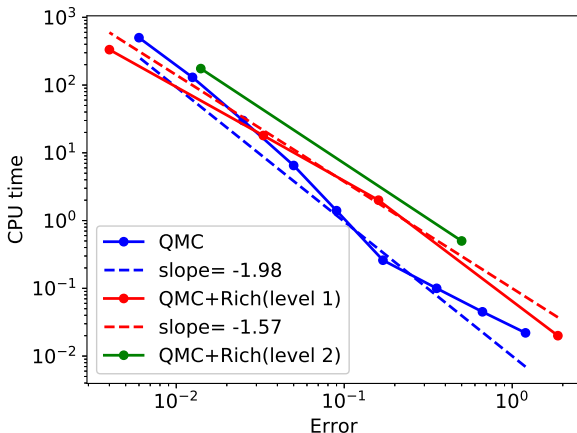


Figure 3.2: Computational work of the QMC method with the different configurations in terms of Richardson extrapolation 's level. Case of parameter set 1 in Table 1.

Computational work of the ASGQ method with different configurations

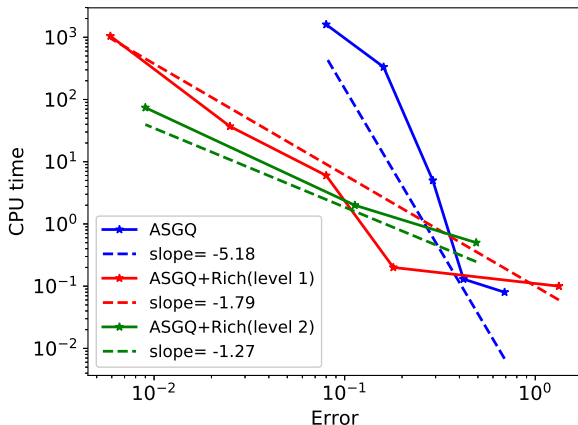


Figure 3.3: Computational work of the ASGQ method with the different configurations in terms of Richardson extrapolation 's level. Case of parameter set 1 in Table 1.

Computational work of the different methods with their best configurations

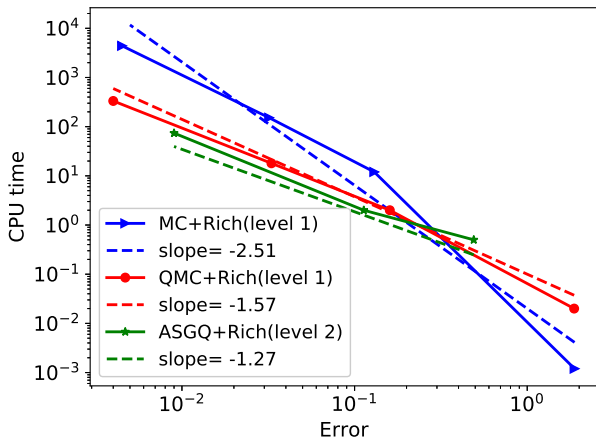


Figure 3.4: Computational work comparison of the different methods with the best configurations, for the case of parameter set 1 in Table 1.

- 1 Option Pricing under the Rough Bergomi Model: Motivation & Challenges
- 2 Our Hierarchical Deterministic Quadrature Methods
- 3 Numerical Experiments and Results
- 4 Conclusions

Conclusions

- Proposed novel **fast option pricers**, for options whose underlyings follow **the rBergomi model**, based on
 - ▶ Conditional expectations for **numerical smoothing**.
 - ▶ **hierarchical deterministic quadrature methods**.
- Given a sufficiently small relative error tolerance, our proposed methods demonstrate **substantial computational gains over the standard MC method**, for different parameter constellations.
- Accelerating our novel methods can be achieved by using better QMC or ASGQ methods.

Thank you for your attention

References I



Bayer, C., Friz, P., and Gatheral, J. (2016).

Pricing under rough volatility.

Quantitative Finance, 16(6):887–904.



Bayer, C., Friz, P. K., Gassiat, P., Martin, J., and Stemper, B. (2017).

A regularity structure for rough volatility.

arXiv preprint arXiv:1710.07481.



Bayer, C., Hammouda, C. B., and Tempone, R. (2018).

Hierarchical adaptive sparse grids and quasi monte carlo for option pricing under the rough bergomi model.

arXiv preprint arXiv:1812.08533.



Bennedsen, M., Lunde, A., and Pakkanen, M. S. (2016).

Decoupling the short-and long-term behavior of stochastic volatility.

arXiv preprint arXiv:1610.00332.



Bennedsen, M., Lunde, A., and Pakkanen, M. S. (2017).

Hybrid scheme for Brownian semistationary processes.

Finance and Stochastics, 21(4):931–965.



Bungartz, H.-J. and Griebel, M. (2004).

Sparse grids.

Acta numerica, 13:147–269.



Gatheral, J., Jaisson, T., and Rosenbaum, M. (2018).

Volatility is rough.

Quantitative Finance, 18(6):933–949.

References II



Glasserman, P. (2004).
Monte Carlo methods in financial engineering.
Springer, New York.



Haji-Ali, A.-L., Nobile, F., Tamellini, L., and Tempone, R. (2016).
Multi-index stochastic collocation for random pdes.
Computer Methods in Applied Mechanics and Engineering, 306:95–122.



McCrickerd, R. and Pakkanen, M. S. (2018).
Turbocharging Monte Carlo pricing for the rough Bergomi model.
Quantitative Finance, pages 1–10.



Neuenkirch, A. and Shalaiko, T. (2016).
The order barrier for strong approximation of rough volatility models.
arXiv preprint arXiv:1606.03854.



Nuyens, D. (2014).
The construction of good lattice rules and polynomial lattice rules.



Romano, M. and Touzi, N. (1997).
Contingent claims and market completeness in a stochastic volatility model.
Mathematical Finance, 7(4):399–412.



Sloan, I. H. (1985).
Lattice methods for multiple integration.
Journal of Computational and Applied Mathematics, 12:131–143.