Adaptive sparse grids and quasi Monte Carlo for option pricing under the rough Bergomi model

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Outline

① Option Pricing under the Rough Bergomi Model: Motivation & Challenges

2 Our Hierarchical Deterministic Quadrature Methods

3 Numerical Experiments and Results

4 Conclusions

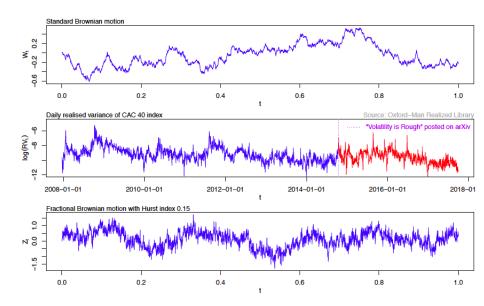
① Option Pricing under the Rough Bergomi Model: Motivation & Challenges

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Rough volatility [Gatheral et al., 2018]



The rough Bergomi model Bayer et al., 2016 This model, under a pricing measure, is given by

$$\begin{cases} dS_t &= \sqrt{v_t} S_t dZ_t, \\ v_t &= \xi_0(t) \exp\left(\eta \widetilde{W}_t^H - \frac{1}{2} \eta^2 t^{2H}\right), \\ Z_t &:= \rho W_t^1 + \bar{\rho} W_t^{\perp} \equiv \rho W^1 + \sqrt{1 - \rho^2} W^{\perp}, \end{cases}$$
(1)

- \bullet $(W^1,W^\perp):$ two independent standard Brownian motions
- \bullet \widetilde{W}^H is Riemann-Liouville process, defined by

$$\widetilde{W}_t^H = \int_0^t K^H(t-s)dW_s^1, \quad t \ge 0,$$

$$K^H(t-s) = \sqrt{2H}(t-s)^{H-1/2}, \quad \forall \ 0 \le s \le t.$$

- $H \in (0, 1/2]$ (H = 1/2 for Brownian motion): controls the roughness of paths, $\rho \in [-1, 1]$ and $\eta > 0$.
- $t \mapsto \xi_0(t)$: forward variance curve, known at time 0.



Model challenges

• Numerically:

- ► The model is non-affine and non-Markovian ⇒ Standard numerical methods (PDEs, characteristic functions) seem inapplicable.
- ► The only prevalent pricing method for mere vanilla options is Monte Carlo (MC) [Bayer et al., 2016, McCrickerd and Pakkanen, 2018]: still a time consuming task.
- ▶ Discretization methods have poor behavior of the strong error, that is the convergence rate is of order of $H \in [0, 1/2]$ [Neuenkirch and Shalaiko, 2016] ⇒ Variance reduction methods, such as multilevel Monte Carlo (MLMC), are inefficient for very small values of H.

• Theoretically:

▶ No proper weak error analysis done in the rough volatility context.

Option pricing challenges

The integration problem is challenging

- Issue 1: Time-discretization of the rough Bergomi process (large N (number of time steps)) $\Rightarrow S$ takes values in a high-dimensional space \Rightarrow Curse of dimensionality when using numerical integration methods.
- Issue 2: The payoff function g is typically not smooth ⇒ low regularity ⇒ slow convergence of deterministic quadrature methods.

<u>A</u> Curse of dimensionality: An exponential growth of the work (number of function evaluations) in terms of the dimension of the integration problem.

Methodology [Bayer et al., 2018]

We design a hierarchical efficient pricing method based on

- Analytic smoothing to uncover available regularity (inspired by [Romano and Touzi, 1997] in the context of stochastic volatility models).
- Approximating the option price using deterministic quadrature methods
 - ▶ Adaptive sparse grids quadrature (ASGQ).
 - Quasi Monte Carlo (QMC).
- 3 Coupling our methods with hierarchical representations \Rightarrow Reduce the dimension of the problem.
 - **Brownian bridges** as a Wiener path generation method.
 - ► Richardson Extrapolation (Condition: weak error of order 1)

 ⇒ Faster convergence of the weak error ⇒ \(\sqrt{number of time steps (smaller dimension)}. \)

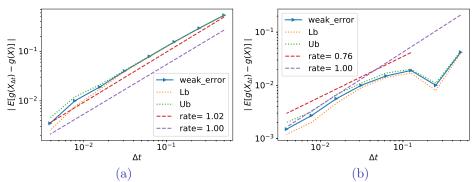
Simulation of the rough Bergomi dynamics

Goal: Simulate jointly $(W_t^1, \widetilde{W}_t^H : 0 \le t \le T)$, resulting in $W_{t_1}^1, \ldots, W_{t_N}$ and $\widetilde{W}_{t_1}^H, \ldots, \widetilde{W}_{t_N}^H$ along a given grid $t_1 < \cdots < t_N$

- Covariance based approach [Bayer et al., 2016]
 - ▶ Based on Cholesky decomposition of the covariance matrix of the (2N)-dimensional Gaussian random vector $W_{t_1}^1, \dots, W_{t_N}^1, \widetilde{W}_{t_1}^H, \dots, \widetilde{W}_{t_N}^H.$
 - Exact method but slow
 - ▶ At least $\mathcal{O}(N^2)$.
- 2 The hybrid scheme [Bennedsen et al., 2017]
 - ▶ Based on Euler discretization but crucially improved by moment matching for the singular term in the left point rule.
 - ▶ Accurate scheme that is much faster than the Covariance based approach.
 - $ightharpoonup \mathcal{O}(N)$ up to logarithmic factors that depend on the desired error.

On the choice of the simulation scheme

Figure 1.1: The convergence of the weak error \mathcal{E}_B , using MC with 6×10^6 samples, for example parameters: H = 0.07, $K = 1, S_0 = 1$, T = 1, $\rho = -0.9$, $\eta = 1.9$, $\xi_0 = 0.0552$. The upper and lower bounds are 95% confidence intervals. a) With the hybrid scheme b) With the exact scheme.



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Conditional expectation for analytic smoothing

$$C_{RB}(T,K) = E\left[\left(S_T - K\right)^+\right]$$

$$= E\left[E\left[\left(S_T - K\right)^+ \mid \sigma(W^1(t), t \leq T)\right]\right]$$

$$= E\left[C_{BS}\left(S_0 = \exp\left(\rho \int_0^T \sqrt{v_t} dW_t^1 - \frac{1}{2}\rho^2 \int_0^T v_t dt\right), \left(k = K, \sigma^2 = (1 - \rho^2) \int_0^T v_t dt\right)\right]$$

$$\approx \int_{\mathbb{R}^{2N}} C_{BS}\left(G(\mathbf{w}^{(1)}, \mathbf{w}^{(2)})\right) \rho_N(\mathbf{w}^{(1)}) \rho_N(\mathbf{w}^{(2)}) d\mathbf{w}^{(1)} d\mathbf{w}^{(2)}$$

$$= C_{RB}^N. \tag{2}$$

- $C_{\text{BS}}(S_0, k, \sigma^2)$: the Black-Scholes call price, for initial spot price S_0 , strike price k, and volatility σ^2 .
- ullet G maps 2N independent standard Gaussian random inputs to the parameters fed to Black-Scholes formula.
- ρ_N : the multivariate Gaussian density, N: number of time steps.



Numerical integration methods

- Plain Monte Carlo (MC)
 - $\triangleright \ \varepsilon(M) = \mathcal{O}\left(M^{-1/2}\right)$
 - \blacktriangleright (+) insensitive to d, (-) slow convergence, no profit from regularity.
- Classical Quasi-Monte Carlo (QMC)

 - \blacktriangleright (+) better convergence, (-) sensitive to d, no profit from regularity.
- Quadrature based on product approaches
 - $\triangleright \ \varepsilon(M) = \mathcal{O}\left(M^{-r/d}\right)$
 - \blacktriangleright (+) profits from regularity, (-) highly sensitive to d.
- Sparse grids quadrature (SGQ)

 - \blacktriangleright (+) profits from regularity, less sensitive to d.

 ε : prescribed accuracy, M: the amount of work, d: dimension of problem, r, s: smoothness indices.

 \wedge In our context, d=2N where N is the number of time steps used for simulating the rough Bergomi dynamics.

Sparse grids I [Bungartz and Griebel, 2004]

Goal: Given $F: \mathbb{R}^d \to \mathbb{R}$ and a multi-index $\beta \in \mathbb{N}_+^d$, approximate

$$E[F] \approx Q^{m(\beta)}[F],$$

where $Q^{m(\beta)}$ a Cartesian quadrature grid with $m(\beta_n)$ points along y_n . **Idea:** Denote $Q^{m(\beta)}[F] = F_{\beta}$ and introduce the first difference operator

$$\Delta_i F_{\beta} \left\{ \begin{array}{ll} F_{\beta} - F_{\beta - e_i}, & \text{if } \beta_i > 1 \\ F_{\beta} & \text{if } \beta_i = 1 \end{array} \right.$$

where e_i denotes the *i*th *d*-dimensional unit vector, and mixed difference operators

$$\Delta[F_{\beta}] = \otimes_{i=1}^{d} \Delta_{i} F_{\beta}$$

Sparse grids II [Bungartz and Griebel, 2004]

A quadrature estimate of E[F] is

$$\mathcal{M}_{\mathcal{I}_{\ell}}[F] = \sum_{\beta \in \mathcal{I}_{\ell}} \Delta[F_{\beta}],\tag{3}$$

- Product approach: $\mathcal{I}_{\ell} = \{\max\{\beta_1, \dots, \beta_d\} \leq \ell; \beta \in \mathbb{N}_+^d\}$
- Regular SG: $\mathcal{I}_{\ell} = \{ |\beta|_{1} \leq \ell + d 1; \beta \in \mathbb{N}_{+}^{d} \}$

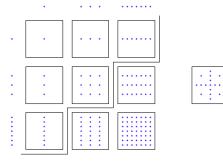


Figure 2.1: Left are product grids $\Delta_{\beta_1} \otimes \Delta_{\beta_2}$ for $1 \leq \beta_1, \beta_2 \leq 3$. Right is the corresponding SG construction.

• ASGQ: $\mathcal{I}_{\ell} = \mathcal{I}^{ASGQ}$.

• The construction of \mathcal{I}^{ASGQ} is done by profit thresholding

$$\mathcal{I}^{\text{ASGQ}} = \{ \boldsymbol{\beta} \in \mathbb{N}_+^d : P_{\boldsymbol{\beta}} \ge \overline{T} \}.$$

- Profit of a hierarchical surplus $P_{\beta} = \frac{|\Delta E_{\beta}|}{\Delta W_{\beta}}$.
- Error contribution: $\Delta E_{\beta} = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} \mathcal{M}^{\mathcal{I}}|$.
- Work contribution: $\Delta W_{\beta} = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] \text{Work}[\mathcal{M}^{\mathcal{I}}].$

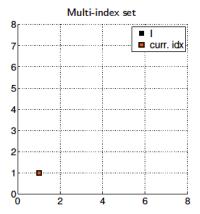


Figure 2.2: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

• The construction of \mathcal{I}^{ASGQ} is done by profit thresholding

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- Work contribution: $\Delta W_{\beta} = \text{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] \text{Work}[\mathcal{M}^{\mathcal{I}}].$

Multi-index set reduced margin curr. idx

Figure 2.3: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

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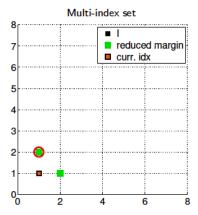


Figure 2.4: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

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- Work contribution: $\Delta W_{\beta} = \text{Work}[\mathcal{M}^{\mathcal{I} \cup {\{\beta\}}}] \text{Work}[\mathcal{M}^{\mathcal{I}}].$

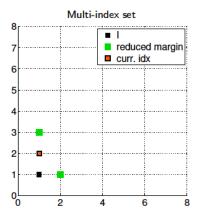


Figure 2.5: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

• The construction of \mathcal{I}^{ASGQ} is done by profit thresholding

$$\mathcal{I}^{\text{ASGQ}} = \{ \boldsymbol{\beta} \in \mathbb{N}_+^d : P_{\boldsymbol{\beta}} \ge \overline{T} \}.$$

- Profit of a hierarchical surplus $P_{\beta} = \frac{|\Delta E_{\beta}|}{\Delta W_{\beta}}$.
- Error contribution: $\Delta E_{\beta} = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} \mathcal{M}^{\mathcal{I}}|$.
- Work contribution: $\Delta W_{\beta} = \operatorname{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] \operatorname{Work}[\mathcal{M}^{\mathcal{I}}].$

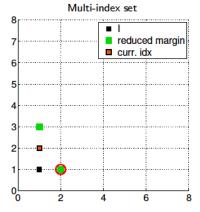


Figure 2.6: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

• The construction of \mathcal{I}^{ASGQ} is done by profit thresholding

$$\mathcal{I}^{\text{ASGQ}} = \{ \boldsymbol{\beta} \in \mathbb{N}_+^d : P_{\boldsymbol{\beta}} \ge \overline{T} \}.$$

- Profit of a hierarchical surplus $P_{\beta} = \frac{|\Delta E_{\beta}|}{\Delta W_{\beta}}$.
- Error contribution: $\Delta E_{\beta} = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} \mathcal{M}^{\mathcal{I}}|$.
- Work contribution: $\Delta W_{\beta} = \operatorname{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] \operatorname{Work}[\mathcal{M}^{\mathcal{I}}].$

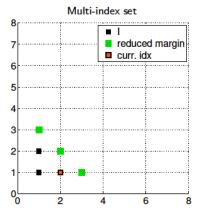


Figure 2.7: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

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$$\mathcal{I}^{\text{ASGQ}} = \{ \boldsymbol{\beta} \in \mathbb{N}_+^d : P_{\boldsymbol{\beta}} \ge \overline{T} \}.$$

- Profit of a hierarchical surplus $P_{\beta} = \frac{|\Delta E_{\beta}|}{\Delta W_{\beta}}$.
- Error contribution: $\Delta E_{\beta} = |\mathcal{M}^{\mathcal{I} \cup \{\beta\}} \mathcal{M}^{\mathcal{I}}|$.
- Work contribution: $\Delta W_{\beta} = \operatorname{Work}[\mathcal{M}^{\mathcal{I} \cup \{\beta\}}] \operatorname{Work}[\mathcal{M}^{\mathcal{I}}].$

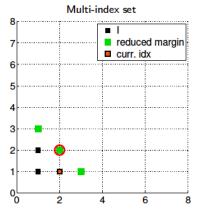


Figure 2.8: A posteriori, adaptive construction as in [Haji-Ali et al., 2016]: Given an index set \mathcal{I}_k , compute the profits of the neighbor indices and select the most profitable one

Randomized QMC

• A (rank-1) lattice rule [Sloan, 1985, Nuyens, 2014] with n points

$$Q_n(f) := \frac{1}{n} \sum_{k=0}^{n-1} f\left(\frac{kz \bmod n}{n}\right),$$

where $z = (z_1, \ldots, z_d) \in \mathbb{N}^d$.

• A randomly shifted lattice rule

$$\overline{Q}_{n,q}(f) = \frac{1}{q} \sum_{i=0}^{q-1} Q_n^{(i)}(f) = \frac{1}{q} \sum_{i=0}^{q-1} \left(\frac{1}{n} \sum_{k=0}^{n-1} f\left(\frac{kz + \Delta^{(i)} \bmod n}{n}\right) \right), (4)$$

where $\{\Delta^{(i)}\}_{i=1}^q$: independent random shifts, and $M^{\text{QMC}} = q \times n$.

- Unbiased approximation of the integral.
- Practical error estimate.
- \bullet We use a pre-made point generators using lattice seq_b2.py from https:

//people.cs.kuleuven.be/~dirk.nuyens/qmc-generators/.



Wiener path generation methods

 $\{t_i\}_{i=0}^N$: Grid of time steps, $\{B_{t_i}\}_{i=0}^N$: Brownian motion increments

• Random Walk

▶ Proceeds incrementally, given B_{t_i} ,

$$B_{t_{i+1}} = B_{t_i} + \sqrt{\Delta t} z_i, \ z_i \sim \mathcal{N}(0, 1).$$

All components of $\mathbf{z} = (z_1, \dots, z_N)$ have the same scale of importance: isotropic.

• Hierarchical Brownian Bridge

▶ Given a past value B_{t_i} and a future value B_{t_k} , the value B_{t_j} (with $t_i < t_j < t_k$) can be generated according to $(\rho = \frac{j-i}{k-i})$

$$B_{t_j} = (1 - \rho)B_{t_i} + \rho B_{t_k} + \sqrt{\rho(1 - \rho)(k - i)\Delta t} z_j, \ z_j \sim \mathcal{N}(0, 1).$$

- ▶ The most important values (determine the large scale structure of Brownian motion) are the first components of $\mathbf{z} = (z_1, \dots, z_N)$.
- ▶ \(\) the effective dimension (# important dimensions) and \(\) anisotropy between different directions \(\) Faster ASGQ and QMC convergence.

Error comparison

 \mathcal{E}_{tot} : the total error of approximating the expectation in (2).

• When using ASGQ estimator, Q_N

$$\mathbf{\mathcal{E}_{tot}} \leq \left| C_{\mathrm{RB}} - C_{\mathrm{RB}}^{N} \right| + \left| C_{\mathrm{RB}}^{N} - Q_{N} \right| \leq \mathcal{E}_{B}(N) + \mathcal{E}_{Q}(\mathrm{TOL}_{\mathrm{ASGQ}}, N),$$

where \mathcal{E}_Q is the quadrature error, \mathcal{E}_B is the bias, TOL_{ASGQ} is a user selected tolerance for ASGQ method.

 \bullet When using randomized QMC or MC estimator, $Q_N^{\rm MC~(QMC)}$

$$\mathcal{E}_{\text{tot}} \leq \left| C_{\text{RB}} - C_{\text{RB}}^{N} \right| + \left| C_{\text{RB}}^{N} - Q_{N}^{\text{MC (QMC)}} \right| \leq \mathcal{E}_{B}(N) + \mathcal{E}_{S}(M, N),$$

where \mathcal{E}_S is the statistical error, M is the number of samples used for MC or randomized QMC method.

• M^{QMC} and M^{MC} , are chosen so that $\mathcal{E}_{S,\text{QMC}}(M^{\text{QMC}})$ and $\mathcal{E}_{S,\text{MC}}(M^{\text{MC}})$ satisfy

$$\mathcal{E}_{S,\mathrm{QMC}}(M^{\mathrm{QMC}}) = \mathcal{E}_{S,\mathrm{MC}}(M^{\mathrm{MC}}) = \mathcal{E}_{B}(N) = \frac{\mathcal{E}_{\mathsf{tot}}}{2}.$$

2 Our Hierarchical Deterministic Quadrature Methods

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Numerical experiments

Table 1: Reference solution (using MC with 500 time steps and number of samples, $M = 8 \times 10^6$) of call option price under the rough Bergomi model, for different parameter constellations. The numbers between parentheses correspond to the statistical errors estimates.

Parameters	Reference solution
$H = 0.07, K = 1, S_0 = 1, T = 1, \rho = -0.9, \eta = 1.9, \xi_0 = 0.0552$	$0.0791 \ (5.6e-05)$
$H = 0.02, K = 1, S_0 = 1, T = 1, \rho = -0.7, \eta = 0.4, \xi_0 = 0.1$	0.1246 $(9.0e-05)$
$H = 0.02, K = 0.8, S_0 = 1, T = 1, \rho = -0.7, \eta = 0.4, \xi_0 = 0.1$	0.2412 $(5.4e-05)$
$H = 0.02, K = 1.2, S_0 = 1, T = 1, \rho = -0.7, \eta = 0.4, \xi_0 = 0.1$	$0.0570 \\ (8.0e-05)$

- Set 1 is the closest to the empirical findings [Gatheral et al., 2018], suggesting that $H \approx 0.1$. The choice $\nu = 1.9$ and $\rho = -0.9$ is justified by [Bayer et al., 2016].
- For the remaining three sets, we test the potential of our method for a very rough case, where variance reduction methods are inefficient.

Relative errors and computational gains

Table 2: In this table, we highlight the computational gains achieved by ASGQ and QMC over MC method to meet a certain error tolerance. We note that the ratios are computed for the best configuration with Richardson extrapolation for each method. The ratios (MC/ASGQ) and (MC/QMC) are referred to CPU time ratios.

Parameters	Relative error	(MC/ASGQ)	$(\mathbf{MC}/\mathbf{QMC})$
Set 1	1%	15	10
Set 2	0.2%	21.5	73.2
Set 3	0.4%	26.7	21.3
Set 4	2%	5	10

Computational work of the MC method with different configurations

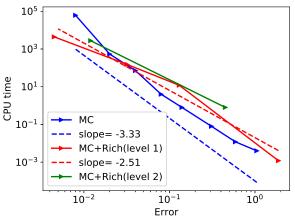


Figure 3.1: Computational work of the MC method with the different configurations in terms of Richardson extrapolation 's level. Case of parameter set 1 in Table 1.

Computational work of the QMC method with different configurations

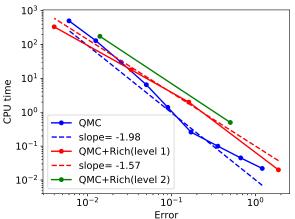


Figure 3.2: Computational work of the QMC method with the different configurations in terms of Richardson extrapolation 's level. Case of parameter set 1 in Table 1.

Computational work of the ASGQ method with different configurations

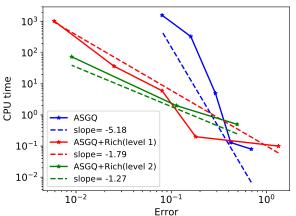


Figure 3.3: Computational work of the ASGQ method with the different configurations in terms of Richardson extrapolation 's level. Case of parameter set 1 in Table 1.

Computational work of the different methods with their best configurations

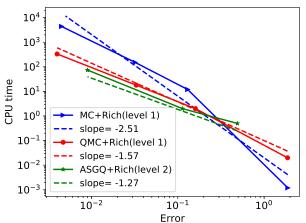


Figure 3.4: Computational work comparison of the different methods with the best configurations, for the case of parameter set 1 in Table 1.

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Conclusions

- Proposed novel fast option pricers, for options whose underlyings follow the rough Bergomi model, based on
 - ► Conditional expectations for numerical smoothing.
 - ▶ hierarchical deterministic quadrature methods.
- Given a sufficiently small relative error tolerance, our proposed methods demonstrate substantial computational gains over the standard MC method, for different parameter constellations.
- Accelerating our novel methods can be achieved by using better QMC or ASGQ methods.

Thank you for your attention

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