Toyler expansion approximation examples

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\begin{split} f(x+\delta) &\approx f(x) + \nabla f(x)^T \delta + \frac{1}{2} \delta^T \nabla^2 f(x) \delta + O(\|\delta\|^3) \\ f(\delta) &\approx f(x_0) + \nabla f(x_0)^T (\delta - x_0) + \frac{1}{2} (\delta - x_0)^T \nabla^2 f(x) (\delta - x_0) + O(\|(\delta - x_0)\|^3) \end{split}
```

One-dimension approximation based on gradient and hessian.

```
% define function f = 0 (x) sqrt(x); % define gradient g = 0 (x) 1/2.*x.^{-1/2}; % define hessian h = 0 (x) -1/4.*x.^{-3/2}; % define first and second order approximation approl = 0 (x0, delta) f(x0) + g(x0)' * delta; appro2 = 0 (x0, delta) f(x0) + g(x0)' * delta + 1/2 .* delta' * h(x0) * delta; % define x0 and delta x0 = 4; delta = 0.1; actual_value = f(x0+delta)
```

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actual_value = 2.0248
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approximate_value_1st = appro1(x0, delta)
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```
approximate value 1st = 2.0250
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```
approximate_value_2nd = appro2(x0, delta)
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approximate_value_2nd = 2.0248

Two-dimension approximation based on gradient and hessian.

```
f = @(x) x(1).^2 - 2.*x(2).*cos(x(1)) + 9;
g1 = @(x) 2.*x(1) + 2.*x(2).*sin(x(1));
g2 = @(x) 2.*sin(x(1));
g = @(x) [g1(x); g2(x)];
h11 = @(x) 2+2.*x(2).*cos(x(1));
h12 = @(x) 2.*sin(x(1));
h21 = h12;
h22 = @(x) 0;
h = @(x) [h11(x), h12(x); h21(x), h22(x)];

x0 = [1;1];
delta = [0.1;0.1];
appro1 = @(x0, delta) f(x0) + g(x0)' * delta;
appro2 = @(x0, delta) f(x0) + g(x0)' * delta + 1/2 .* delta' * h(x0) * delta;
actual_value = f(x0+delta)
```

```
actual_value = 9.2121
```

```
approximate_value_1st = appro1(x0, delta)
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approximate_value_1st = 9.4560

approximate_value_2nd = appro2(x0, delta)

approximate_value_2nd = 9.4882