Yongqi Dong







https://yongqidong.github.io/

Researcher and Research Group Leader @ RWTH Aachen University Ph.D. Researcher @ Delft University of Technology

Email: yongqi.dong@rwth-aachen.de | **TEL:** (+31) 0616619399 / (+1) 5109711107

EDUCATIONAL BACKGROUND

Doctor of Philosophy, Department of Transport & Planning, Delft University of Technology (TU Delft) Dec. 2019-May. 2025

Thesis: <u>Safe, Efficient, and Socially Compliant Automated Driving: Sensing, Anomaly Detection, Planning and Control</u> Advisors: Prof.dr.ir. Bart van Arem and Dr.ir. Haneen Farah

Visiting PhD Researcher, Department of Mechanical Engineering, University of California, Berkeley May.2023- Oct.2023 Topic: Socially Compliant Automated Driving via Deep Reinforcement Learning and Model-based Social-aware MPC

Master of Control Science and Engineering, Department of Automation, Tsinghua University

Sep.2014-Jul.2017

Minor: Master Project for Improving Ability in Big Data

Thesis: Data-Driven Analysis on Group Behaviors of Taxi Drivers and Ridesourcing Drivers

Nominated for Tsinghua University Outstanding Master Thesis Dissertation

Advisors: Prof. Li Li and Prof. Zuo Zhang

Bachelor of Telecommunication Engineering

Sep.2010-Jul.2014

School of Electronic and Information Engineering, Beijing Jiaotong University

GPA: 91.5/100 | Rank: 1/202 | Postgraduate Recommendation to Tsinghua University without Examination

Thesis: Design of vehicle-mounted data acquisition & communication unit for the WMN-based locomotive remote control Outstanding Undergraduate Thesis

PUBLICATIONS

(Google Scholar ID: L2kD-DwAAAAJ. The superscript # indicates equal contribution, * indicates corresponding authors.)

Key Journal Publications:

- 1. Dong, Y., Patil, S., Van Arem, B., & Farah, H. (2023). A Hybrid Spatial-temporal Deep Learning Architecture for Lane Detection. Computer-Aided Civil and Infrastructure Engineering, 38(1), 67-86. https://doi.org/10.1111/mice.12829 [Top Q1, IF: 8.5, SJR: 2.972, CiteScore: 17.6]
- → 2. Dong, Y., Wang, S., Li, L., Zhang, Z. (2018). An Empirical Study on Travel Patterns of Internet Based Ride-Sharing. Transportation Research Part C: Emerging Technologies, 86, 1-22. https://doi.org/10.1016/j.trc.2017.10.022 [Highly cited; Top Q1, IF: 7.6, SJR: 2.86, CiteScore: 15.8]
- → 3. Dong, Y., Farah, H., & Van Arem, B. (2025). Towards Developing Socially-Compliant Automated Vehicles: Advances, Experts Insights, and a Conceptual Framework. (Accepted by Communications in Transportation Research [Top Q1, IF: 12.5, SJR: 2.836, CiteScore: 15.2] and by 104th TRB Annual Meeting (TRB 2025) for presentation, and presented at the 4th Symposium on Management of Future Motorway and Urban Traffic Systems (MFTS)), Preprint
- → 4. Li, R.#, & **Dong, Y.**#,*(2023). Robust Lane Detection Through Self Pre-Training With Masked Sequential Autoencoders and Fine-Tuning With Customized PolyLoss. IEEE Transactions on Intelligent Transportation Systems, vol. 24, no. 12, pp. 14121-14132. https://doi.org/10.1109/TITS.2023.3305015 (Joint first author and corresponding author) [Top Q1, IF:7.9, SJR:2.58, CiteScore: 14.8]
- → 5. Dong, Y. ***, Zhang, L. **, Farah, H., Zgonnikov, A., & Van Arem, B. (2025). Data-driven Semi-supervised Machine Learning with Safety Indicators for Abnormal Driving Behavior Detection. Transportation Research Record: Journal of the Transportation Research Board, 1-16. https://doi.org/10.1177/03611981241306752
- ♦ 6. Dong, Y.**, Lu, X. *, Li, R., Song, W., Van Arem, B., & Farah, H. (2025). Intelligent Anomaly Detection for Lane

- Rendering Using Transformer with Self-Supervised Pre-Training and Customized Fine-Tuning. *Transportation Research Record: Journal of the Transportation Research Board*. https://doi.org/10.1177/03611981251333341 (accepted by and presented at TRB2024), Preprint
- → 7. Farah, H., Postigo, I., Reddy, N., Dong, Y., Rydergren, C., Raju, N., & Olstam, J. (2022). Modeling Automated Driving in Microscopic Traffic Simulations for Traffic Performance Evaluations: Aspects to Consider and State of the Practice. IEEE Transactions on Intelligent Transportation Systems, 24(6), 6558-6574. https://doi.org/10.1109/TITS.2022.3200176 [Top Q1, IF:7.9, SJR:2.58, CiteScore: 14.8]
- ▶ 8. Berge, S. H., De Winter, J., Dodou, D., Afghari, A. P., Papadimitriou, E., Reddy, N., **Dong, Y.**, Raju, N., & Farah, H. (2025). Understanding Cyclists' Perception of Driverless Vehicles through Eye-Tracking and Interviews. *Transportation Research Part F: Traffic Psychology and Behaviour*, 109, 399-420. https://doi.org/10.1016/j.trf.2024.11.015 [Top Q1, IF:3.5, SJR:1.262, CiteScore: 7.6]
- ▶ 9. Liu, W., Song, L., **Dong, Y.**, Zhang, X., & Xu, L. (2025). Unified Model Predictive Control Method of Automated Vehicles for Lane Changing and Lane Keeping Maneuvers. *Journal of Intelligent Transportation Systems*, 1-21. https://doi.org/10.1080/15472450.2025.2479235

Key Conference Proceeding Publications & Presentations:

- → 1. Zhang, L.#, Dong, Y. #,*, Farah, H., & Van Arem, B. (2023). Social-aware Planning and Control for Automated Vehicles based on Driving Risk Field and Model Predictive Contouring Control: Driving through Roundabouts as a Case Study. 2023 IEEE International Conference on Systems, Man, and Cybernetics (SMC), Honolulu, Oahu, HI, USA, 2023, pp. 3297-3304. http://dx.doi.org/10.1109/SMC53992.2023.10394462. (Co-first author and corresponding author, accepted and presented at TRB's 2023 Automated Road Transportation Symposium), Demo-video
- → 2. Dong, Y., Detema, T., Wassenaar, V., Van de Weg, J., Kopar, T., & Suleman, H. (2023). Comprehensive Comparison of Deep Reinforcement Learning for Automated Driving on Various Driving Maneuvers with Simulation. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 6165-6170, http://dx.doi.org/10.1109/ITSC57777.2023.10422159
- → 3. **Dong, Y.**^{#,*}, Patil, S.[#], Farah, H, & Hellendoorn, J. (2023). Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames (**Presented** at the Transportation Research Board (TRB) 102nd annual meeting TRB 2023). TRBAM-23-04409 poster
- ♣ 4. Yuan, H., Li, P., Van Arem, B., Kang, L., Farah, H., & Dong, Y.* (2023). Safe, Efficient, Comfort, and Energy-saving Automated Driving through Roundabout Based on Deep Reinforcement Learning. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 6074-6079, http://dx.doi.org/10.1109/ITSC57777.2023.10422488 (Corresponding author and PI)
- → 5. Xue, C.*, Dong, Y.*, Liu, J.*, Liao, Y., & Li, L. (2023). Design of the Reverse Logistics System for Medical Waste Recycling Part I: System Architecture and Disposal Site Selection Algorithm. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 1741-1746, http://dx.doi.org/10.1109/ITSC57777.2023.10422624 (Co-first author)
- ◆ 6. Xue, C.#, **Dong, Y.**#, Liu, J.*, Liao, Y., & Li, L. (2023). Design of the Reverse Logistics System for Medical Waste Recycling Part II: Route Optimization with Case Study under COVID-19 Pandemic. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 4011-4017. http://dx.doi.org/10.1109/ITSC57777.2023.10422236 (Co-first author)
- → 7. Dong, Y.*, Chen, K., Peng, Y., & Ma, Z. (2022). Comparative Study on Supervised versus Semi-supervised Machine Learning for Anomaly Detection of In-vehicle CAN Network. 2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC), 2022, pp. 2914-2919, https://doi.org/10.1109/ITSC55140.2022.9922235

Other Journal and Conference Publications:

▶ 1. Lingam, S. N., De Winter, J., Dong, Y., Tsapi, A., Van Arem, B., & Farah, H. (2024). eHMI on the Vehicle or on the

- Infrastructure? A Driving Simulator Study. European Journal of Transport and Infrastructure Research, 24(2), 1–24. https://doi.org/10.59490/ejtir.2024.24.2.7273 [Journal]
- ◆ 2. Dong, Y., Liu, C., Wang, Y., & Fu, Zh. (2024). Towards Understanding Worldwide Cross-cultural Differences in Implicit Driving Cues: Review, Comparative Analysis, and Research Roadmap. Accepted by and presented at the 2024 IEEE 27th International Conference on Intelligent Transportation Systems (ITSC), Preprint [Conference]
- → 3. Huang, Y.**, Dong, Y.**, Tang, Y., & Li, L. (2024). Leverage Multi-source Traffic Demand Data Fusion with Transformer Model for Urban Parking Prediction. Accepted by the 28th International Conference Of Hong Kong Society For Transportation Studies (HKSTS 2024) and the Conference in Emerging Technologies in Transportation Systems (TRC-30) for presentation, Preprint [Conference]
- → 4. **Dong, Y.****, Chen, K.*, & Ma, Z. (2023). Comparative Study on Semi-Supervised Learning Applied for Anomaly Detection in Hydraulic Condition Monitoring System. 2023 IEEE International Conference on Systems, Man, and Cybernetics (SMC), Honolulu, Oahu, HI, USA, 2023, pp. 1702-1708, http://dx.doi.org/10.1109/SMC53992.2023.10394193 [Conference]
- → 5. Raju, N., Schakel, W., Reddy, N., **Dong, Y.**, & Farah, H. (2022). Car-Following Properties of a Commercial Adaptive Cruise Control System: A Pilot Field Test. *Transportation Research Record: Journal of the Transportation Research Board*, 2676(7), 128-143. https://doi.org/10.1177/03611981221077085 [Journal]
- ♣ 6. Dong, Y., Yang, Z., Yue, Y., Pei, X., & Zhang, Z. (2018). Revealing Travel Patterns of Sharing-bikes in a Spatial-temporal Manner Using Non-negative Matrix Factorization Method. In CICTP 2018: Intelligence, Connectivity, and Mobility (pp. 1665-1674). Reston, VA: American Society of Civil Engineers. https://doi.org/10.1061/9780784481523.165 [Conference]
- → 7. Yue, Y., Pei, X., Yang, Z., **Dong, Y**., & Yao, D. (2018). A Trip Building and Chaining Methodology Using Traffic Surveillance Data. In *CICTP 2018: Intelligence, Connectivity, and Mobility* (pp. 2254-2262). Reston, VA: American Society of Civil Engineers. https://doi.org/10.1061/9780784481523.224 [Conference]
- → 8. **Dong, Y.**, Zhang, Z., Fu, R., Xie, N. (2016). Revealing New York Taxi Drivers' Operation Patterns Focusing on the Revenue Aspect. (2016) In *12th World Congress* on *Intelligent Control and Automation (WCICA)*, (pp. 1052-1057). IEEE. https://doi.org/10.1109/WCICA.2016.7578771 [Conference]
- → 9. **Dong, Y.**, Ruan, H., Cai, T., Peng, J, and Wang ,W. (2013). Using LED to Demonstrate the Composition of Simple Harmonic Motions and Five Polarization States of Light. *Physics Experimentation*, 11, 45-48 [Journal in Chinese]

Under Review and Working Papers:

- → 1. Dong, Y., Van Arem, B., & Farah, H. (2025). Safe and Socially-compliant Automated Driving through Integrating Multi-Agent Reinforcement Learning with SVO and MPCC (In preparation, to be submitted to the Proceedings of the National Academy of Sciences, PNAS)
- → 2. Patil, S.*, **Dong**, Y.*,*, Farah, H, & Hellendoorn, J. (2025). Efficient Sequential Neural Network based on Spatial-Temporal Attention and Linear LSTM for Robust Lane Detection Using Multi-frame Images, (Joint first author and corresponding author, *Under Review* by *IEEE Transactions on Intelligent Vehicles*), <u>Preprint</u>
- → 3. **Dong, Y.**^{#,*}, Reyna, C.F.[#], Klunder, G., Liao, F., & Rasouli, S. (2025). A Benchmarking Framework for Traffic Microsimulation Platforms: Case Study on Dutch Motorways with Dynamic Speed Limits. (Joint first author and corresponding author, *to be submitted* to *Transportation Research Part C: Emerging Technologies*)
- → 4. Ji, J., Lu, R., Belkessa, L., Dong, Y., Wang, L., Madadi, B., Varotto, S., Saunier, N., MacFarlane, G., & Wu, C. (2025).

 Exploring Artifacts Availability in Transportation Research Using Large Language Models, Accepted by the 2025

 International Symposium on Transportation Data & Modelling (ISTDM) and the 2025 Modelling Mobility Conference (MoMo) for presentation
- → 5. Lu, R., Ji, J., Belkessa, L., Dong, Y., Wang, L., Madadi, B., Varotto, S., Saunier, N., MacFarlane, G., & Wu, C. (2025).
 Measuring Availability Features for Reproducibility in Transportation Research, to be submitted to *Transportation*

- Research Part C: Emerging Technologies, Accepted by the 2025 Transportation Research Symposium for presentation
- ♦ 6. Zhang, Y., **Dong, Y.*** (2025). Optimization of coordinated flow restriction and skip-stopping schemes for urban rail stations considering platform carrying capacity (**Presented** at the Transportation Research Board (TRB) 102nd annual meeting TRB 2023, Under Review by Journal of Advanced Transportation). TRBAM-23-04413 poster, Preprint
- → 7. Zhang, Y., Dong, Y.*., Evans, C., Rinaldi, M., Shyrokau, B., & Farah, H. (2025). Coordinated Planning and Control for Connected and Automated Vehicles' On-ramp Merging in Mixed Traffic Through Value Decomposition-based Multiagent Deep Reinforcement Learning. (Corresponding author, to be submitted to Transportation Research Part C: Emerging Technologies)
- ▶ 8. The Age of Smart Integrated Transportation: Practice of in the Digital Transformation of Transportation Industry [M]. Publishing House of Electronics Industry. [Involved as reviewer and expert editor for Preface, Chapters 1 & 13]

Open resource repository:

- → <u>Datasets, Simulation Platforms, and Relevant Publications on Emerging Mixed Traffic of AVs and HDVs</u>
- → List of open datasets and codes: https://data.4tu.nl/search?search=Yongqi+Dong

PATENTS & SOFTWARE COPYRIGHTS

- **♦** European and Dutch Patent:
- → Dong, Y., Li, R. Automated lane detection (IDF OCT-22-060, granted on May 25, 2024, Patent number 2033551)
- → Socially compliant Planning and Control for Automated Vehicles using Model-backend Deep Reinforcement Learning with Driving Risk Field and Model Predictive Contouring Control (OCT-23-056, N2035943, Submitted & filed)
- **♦** Chinese Invention Patent:
- ▶ Intelligent Demonstration Instrument of Simple Harmonic Oscillation Composition and Five Polarization States of Light, Application ID: 201310123700.5, Date: 2013.08.07, Patent Number CN103236211B, Publication Date: 2016.07.06
- ♦ Software copyright:
- → Spatial-Temporal Attention Integrated Sequential Neural Network Model for Vision-based Robust Lane Detection Using Multi Continuous Image Frames (i-DEPOT 142731, approved & registered)
- → Vision-Based Lane Detection System With Self-supervised Pre-training Through Masked Sequential Auto-encoders (Computer Software Copyright Registration in China, 2024SR1350911, approved & registered)

ACADEMIC SERVICES

Technical Committee (Chair) | Automated Mobility in Mixed Traffic | IEEE ITSS Mar.2025-Present Establishing and chairing the interdisciplinary community: "Automated Mobility in Mixed Traffic"

IEEE ITSS New Initiatives Project Principal Investigator (PI) | IEEE ITSS Mar.2024-Present Project: Promoting interdisciplinary research toward the deployment of automated vehicles in mixed traffic

Workshop Organizer (Primary coordinator) | 27th IEEE ITSC 2024, Edmonton, Canada Sep.24, 2024
Workshop title: <u>Automated Mobility in Emerging Mixed Traffic</u>

Workshop Organizer (Second coordinator) | 26th IEEE ITSC 2023, Bilbao, Bizkaia, Spain Sep. 24, 2023

Workshop title: <u>Data-driven and Empirical Research for Emerging Mixed Traffic of Automated Vehicles</u>

and <u>Human-driven Vehicles</u>

IEEE TCoS Seeding Project Leader (PI) | 2023 IEEE TAB Committee on Standards (TCoS) seed funding Project title: Enhancing the deployment of socially-compliant automated vehicles in mixed traffic (website)

Ad-hoc Journal Reviewer Services

▶ International Journal of Computer Vision (IF: 19.5; Top AI journal)

- → IEEE Transactions on Intelligent Transportation Systems
- ▶ IEEE Open Journal of Intelligent Transportation Systems
- ▶ Transportation Letters: the International Journal of Transportation Research
- → Journal of Intelligent Transportation Systems: Technology, Planning, and Operations
- → Journal of Transportation Research Record: Journal of the Transportation Research Board
- ▶ International Journal of Human-Computer Interaction
- → Journal of Advanced Transportation
- → Scientific Reports
- ♣ Applied Ergonomics
- → European Transport Research Review
- ASCE-ASME Journal of Risk and Uncertainty in Engineering Systems, Part A: Civil Engineering

Ad-hoc Conference Reviewer Services

- → IEEE Intelligent Vehicles Symposium (IV) | Associate editor
- → IEEE Intelligent Transportation Systems Conference (ITSC)
- → Transportation Research Board (TRB) Annual Meeting
- ▶ World Congress on Intelligent Control and Automation (WCICA)
- → COTA International Conference of Transportation Professionals (CICTP)
- → The International Symposium on Transport Network Resilience (INSTR)

THESIS SUPERVISION

Yuteng Zhang | Master of Science in Transport, Infrastructure & Logistics

Jan.2024-Nov.2024

Thesis title: Coordinated Planning and Control for Connected and Automated Vehicles' On-ramp Merging in Mixed

Traffic Through Value Decomposition-based Multiagent Deep Reinforcement Learning

Cesar Flores Reyna | Master of Science in Sustainable Mobility Transitions, EIT, TU/e Jan. 2024-Nov. 2024

Thesis title: Investigating a Benchmarking Framework for the Large-Scale Micro Simulator (LSMS) Platform in Freeways under Dynamic Speed Limits

Mathijs den Otter | Master of Science in Civil Engineering-Transport and Planning Sep. 2022-Dec. 2023

Thesis title: <u>Impact of Improved Lane Marking Properties on the Performance of Lane Keeping Assistance Systems in Varying Circumstances</u>

Lanxin Zhang | Master of Science in Civil Engineering-Transport and Planning Oct.2022-Jun.2023

Thesis title: Semi-supervised Machine Learning for Abnormal Driving Behavior Detection

Henan Yuan | Bachelor in Traffic and Transportation, BJTU&TUDelft TTE Oct.2022-Jun.2023

Thesis title: Deep Reinforcement Learning for Driving through Roundabouts

Shiva Nischal Lingam | Master of Science in Civil Engineering-Transport and Planning Jan. 2021-Nov. 2021

Thesis title: Effects of External Human Machine Interfaces on Automated Vehicles' Communicative

Interactions With Human Drivers (Cum Laude) | Won 2nd Cuperusprijs prieze of KIVI

Sandeep Patil | Master of Science in Mechanical Engineering (Vehicular Engineering) Oct.2020-Aug.2021

Thesis title: Lane Detection using SpatioTemporal Attention

Eline van der Kooij | Master of Science in Transport, Infrastructure & Logistics Jul.2020-May.2021

Thesis title: Visibility of Lane Markings for Machine Vision

Sanny Toonen | Bachelor of Science in Civil Engineering-Transport and Planning Jul.2020-May.2021

Thesis title: Lane Recognition for Automated Vehicles

Project supervisor, Instructor | EEMCS, TU Delft

Nov.2022-Feb.2024

Courses: <u>Interdisciplinary Advanced AI Project (IFEEMCS520200)</u>; <u>Capstone Applied AI Project (T13150TU)</u>
Fundamentals of Artificial Intelligence Programme (IFEEMCS520100)

Teaching Assistant, Instructor | TU Delft and BJTU joint bachelor program

Mar.2022 & Mar.2023

Course: Advanced Lecture "Trends in Transportation" 2022 & 2023

Lecturer | DakeOffer online Platform

Mar.2020-Jun.2020 & Nov.2020-Jan.2021

Course: Introduction to Big Data and Artificial Intelligence: Fundamental and Practice

Teaching Assistant | Transport and Planning, TU Delft

Apr.2020-Aug.2020 & Apr.2021-Aug.2021

Course: CIE5805 - Intelligent Vehicles for Safe and Efficient Traffic

Teaching Assistant | Department of Automation, Tsinghua University

Sep.2016-Jan.2017

Course: Data Ethics

Teaching and Lab Assistant | Electrical and Electronic Lab Center, Tsinghua University Mar.2015-Jul.2016

Courses: Advanced Labs in Electronic Technology, Fundamentals of Electronics Power Technology

RSI Tutor | Center for Excellence in Education, USA

Jul.2017-Aug.2017

Research writing and presentation tutor for the 2017 Research Science Institute Program at Tsinghua University

Undergraduate Counselor (Class 2012) | School of EIE, Beijing Jiaotong University

Jul.2012- Jul.2014

TALKS & PRESENTATIONS

Promoting Diversity and Leadership in ITS | IEEE WiE/YP Workshop & Forum, Cairo, Egypt Nov.21.2023

Presentation topic: Resource Repository: Datasets, Simulation Platforms, and Relevant Publications for Emerging Mixed

Traffic of Automated Vehicles and Human-driven Vehicles

Automated Round Transportation | TRB ARTS 2023, San Francisco, USA

Jul.12.2023

Presentation topic: Social-aware Planning and Control for Automated Vehicles Based on Driving Risk Field and Model
Predictive Contouring Control: Driving through Roundabouts as a Case Study

AI Applications in Transportation Planning | TRB 2023, Washington D.C., USA

Jan.11.2023

Presentation topics: (1) Robust Lane Detection through Self Pre-training with Masked Sequential Autoencoders and Fine-tuning with Customized PolyLoss

(2) Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames

Research into Urban Rail Transit Operations and Design | TRB 2023, Washington D.C., USA Jan.11.2023

Presentation topic: Optimization of coordinated flow restriction and skip-stopping schemes for urban rail stations considering platform carrying capacity

Connected and Automated Vehicles | MFTS 2022, Dresden, Germany

Dec.01.2022

Presentation topic: Towards Developing Socially-Compliant Automated Vehicles: State of the Practice, Experts Expectations, and a Conceptual Framework

Automated mobility | IEEE ITSS Young Professionals Fellowship Symposium, Chania, Greece Nov.25.2022

Presentation topic: Multi-goal proactive traffic management for mixed traffic of automated vehicles (AVs) and human-driven vehicles (HDVs) using explainable physics-informed Artificial Intelligence

AI, Security, Privacy and Safety Systems in ITS Applications ITSC2022, Macow, China Oct.08.2022

Presentation topic: Comparative Study on Supervised vs Semi-supervised ML for Anomaly Detection of CAN Network

Research on AI and Advancing Computing Applications | TRB 2022, Washington D.C., USA Jan.12.2022

Presentation topic: A Hybrid Spatial-temporal Sequence-to-one Neural Network Model for Lane Detection

Challenges of Automated Vehicles and Traffic | University of Győr, Hungary

May.28.2021

Talk topic: Deep learning for automated vehicles' operational design domain: problems, challenges, and case studies

SAMEN User Committee Annual Meeting | Dutch Research Council (NWO), Delft, Netherlands Jan.28.2021

Talk topic: Data-driven research for automated vehicles' operational design domain: a case study on perception

Intelligence, Connectivity, and Mobility | COTA CICTP 2018, Tsinghua University, China Jul.07.2018

Presentation topic: Revealing travel patterns of sharing-bikes in a spatial-temporal manner using the NFM method

World Congress on Intelligent Control and Automation | IEEE WCICA 2016, Guilin, China Jun. 12.2016

Presentation topic: Revealing New York Taxi Drivers' Operation Patterns Focusing on the Revenue Aspect

HONORS & AWARDS

- **♦** Chinese CSC Award for Outstanding Self-financed Students Abroad (6,000 \$)
- **→** TU Delft-Transport Institute Interdisciplinary Research Award (10,500 €)
- **→** 2023 IEEE TAB Committee on Standards (TCoS) seed funding (6,000 \$)
- **→** 2024 IEEE ITSS New Initiatives Proposal Funding (5,000 \$)
- **▶** IEEE ITSS Young Professionals Fellowship (Twice)
- **▶** Erasmus + mobility Grants (Three times)
- Outstanding College Graduates of Beijing (Top 1‰)
- **▶** National Scholarship (Top 1%)
- → First Class Tsinghua University RONG Scholarship
- Second-Class Merit Scholarship for Masters Tsinghua University
- → Merit Student (Four times)
- → First-Class Academic Fellowship (Top 1%, Twice)
- Second Prize in the 2012 & 2013 Undergraduate Electronic Design Contest in Beijing
- ▶ Bronze award in "Challenge Cup" Entrepreneurship Design Contest in Beijing
- First Prize in Freescale Cup University Students Intelligent Car Race (Rank 2nd)
- Second Prize in the Physical Experiment Competition in Beijing
- 2019 Microsoft Discover AI Challenge: Sustainable Life | Data-Driven All-in-one Shared Mobility | Top (10%)

RESEARCH EXPERIENCE

- **→** AI-Enhanced Hierarchical Multi-objects Driving Risk Field Model Integrating Physics-Based and Human Perception-Based Approaches with Drivers' Distraction (PI, *Individual DFG*)
- **▶** Explainable Mathematics-Enhanced AI Model for Multi-Modal Urban Traffic Prediction and Simulation (Co-PI, <u>DFG Research Unit Proposal</u>)
- **▶** Realistic Modelling of Cycling Behavior and Interaction with Other Road Users in Mixed Traffic (PI, <u>DFG Package</u> Proposal)
- ▶ Parameter-Efficient Fine-Tuning of Pretrained Multimodal Large Vision Model (LVM) for Privacy-preserving Traffic Anomaly Detection with Thermal Imaging

Traffic and Transportation Safety Lab | Department of Transport and Planning | TU Delft Dec. 2019-Jun. 2024

- ▶ Data-driven and AI-based research for expanding Automated Vehicles' Operational Design Domain in mixed traffic (part of <u>SAMEN</u> project)
 - > Developed a hybrid sequence-to-one model for lane detection in extremely hard driving scenes
 - > Incorporated spatial-temporal attention for automated vehicles' perception
 - > Designed reliable data-driven algorithms for anomalies and abnormal behaviors prediction
 - > Implemented Deep Reinforcement Learning (DRL) models for safe, reliable, and socially compliant automated driving under challenging maneuvers involving both longitudinal and lateral control

> Gaze behavior of road users when interacting with an automated vehicle at an intersection: Understanding cyclists' perception of driverless vehicles through eye-tracking and interviews

Mechanical Systems Control (MSC) Lab | Department of Mechanical Engineering | UC Berkeley May.2023-Oct.2023 Advisor: Prof. Masayoshi Tomizuka

- Socially Compliant Automated Driving through DRL and Model-based Social-aware MPC
 - > Reviewed State-of-the-art Socially Compliant Automated Driving Methods in Literature
 - > Developed Model-enhance Multi-agent Deep Reinforcement Learning with Social-aware MPC

Waterloo Artificial Intelligence Institute | Faculty of Engineering | University of Waterloo

May.2018-Sep.2019

- ♣ Applied Machine Learning, Artificial Intelligence, and Big Data Research
 - > 2018 Railroad Problem Solving Contest: Use CNN-LSTM-Dense Concatenated model to forecast train delays
 - > A Deep Learning Framework for Traffic Forecasting: Exploring GCN joint with LSTM to predict traffic flow
 - > Data-driven anomaly detection (unsupervised): Auto-Encoder, Hierarchical Extreme Learning Machines
 - > Kaggle competition: Employ LSTM, LightGBM, XGBoost models to predict stock movements with news data
 - > Deep reinforcement learning in traffic control: DQN, A3C, and PPO methods
 - > Real-time Road Surface Condition (RSC) Monitoring: Adopt CNN to RSC image classification

Singapore-MIT Alliance for Research and Technology (SMART)

Aug.2016-Sep.2016

Future Urban Mobility (FM) IRG | Project: SimMobility | Topic: Taxi Roaming

Advisors: Prof. Moshe BEN-AKIVA, Postdoctoral Associate Bat-hen NAHMIAS-BIRAN

- Constructing a model tackling the taxi roaming (taxi service) problem, to be embedded into the SimMobility platform
 - > Proposed one advisable solution of cruising along hotspots through a cell-based logit-opportunity model improved by a data-driven method
 - > Participated in building the architecture of the final model embedded in SimMobility

$Intelligent\ Transportation\ Laboratory, Tsinghua\ National\ Laboratory\ for\ Information\ Science\ and\ Technology$

(TNList) | Advisors: Prof. Zuo Zhang and Prof. Li Li (IEEE Fellow)

Sep.2014-May.2018

Transportation Research based on machine learning and data-driven methods

- ▶ Revealing New York taxi drivers' operation patterns focusing on revenue
 - > Developed a method for classifying drivers into 3 groups based on their revenue: top, ordinary, low earner
 - > Excavated the population operation patterns of different taxi driver groups through big data analytics
- → Influence of on-demand ridesourcing vs. traditional taxi based on machine learning and big data analytics
 - > Uncovered the differences between taxi service and ridesourcing using big data analysis and clustering
 - > Applied non-negative matrix factorization (NMF) to obtain basis patterns of Taxi, Hitch and Express service
- ▶ Influence of on-demand ridesourcing on vehicle emissions with big data analytics and PHEM model
- ▶ Fundamental research on intelligent parking guidance and recommendations based on machine learning
 - Forecast models of travel time to parking lots (Random Forest); Guidance & optimization models for parking
 - > Personalized recommendation research on parking (Collaborative Filtering and Content-based algorithm)
- → Study on key technology in Intelligent Vehicle Infrastructure Cooperative Systems (IVICS) (863 Program)
 - > Contributed to the design report of basic technical framework and the overall demonstration of IVICS

The Freescale Cup College Students Intelligent Car Race: Intelligent car that can follow

Jun.2012-Jun.2013

specific trajectories based on image processing, pattern recognition, and PID controller

→ Hardware Aspect: Designed the signal acquisition circuit and the core control circuit based on MC9S12XS256

- → Software Aspect: Developed specific control strategies/algorithms for intelligent cars to follow given trajectories
- → Actuator: Customized specific steering linkage, applied and tuned PID algorithms to control diversion and speed

WORKING EXPERIENCE

Junior Research Group Leader | AI & Automated Mobility Group | RWTH Aachen University Jun.2024-Present

- Research proposal initialization, preparation, and writing: German Research Foundation (<u>DFG</u>) and <u>mFUND</u>
- **▶** Co-PI: main responder and drafter for three DFG research proposals
- ▶ Lead the group and supervise the PhD/MSc students
- → Teaching support for Road Planning II and Machine Learning in Civil Engineering (master's level)

PhD Researcher | TTS Lab | Department of Transport & Planning | TU Delft

Dec.2019-Jun.2024

- ◆ Carried out PhD research work under the NWO funded <u>SAMEN</u> project
- ▶ Provided teaching assistance and evaluation support for various courses and supervised seven MSc students
- ▶ Published scientific papers and patents, presented research works in conferences and organized workshops

Visiting PhD Researcher | MSC Lab | Department of Mechanical Engineering | UC Berkeley

May.2023-Oct.2023

Carried out literature review and research work related to Socially Compliant Automated Driving

Research Assistant | Waterloo Artificial Intelligence Institute | University of Waterloo

May.2018-Sep.2019

→ Carried out research works related to applied Machine Learning, Artificial Intelligence, and Big Data in Transportation

Research Assistant | Transport Big Data Analytics | ITS Lab, TNList@Tsinghua University Aug.2017- May.2018

- → Cross-domain data fusion for full-time trip chain reconstruction and anomaly detection;
- → City Computing: Applying NMF methods to evaluate indicators describing urban function, land use, mobility, etc.
- → Revealing collective travel patterns of *Shared Mobility* in a spatial-temporal manner

Commentator | China International Congress on Intelligent & Connected Vehicles (CICV)

Carryout service data analysis Project Manager | Beijing Gooagoo Technical Service Co., Ltd. Jul. 2016-Aug. 2016

→ Integral process of Big Data Analytics: Crawled carryout service data using Python crawler; executed data storage, data analysis, and data processing in a relational database (MySQL); visualization, clustering, and web application

→ Introduced the i-VICS systems to audiences; received executives from automobile manufacturers BMW, Volvo, VW

LEADERSHIP & VOLUNTEER EXPERIENCE

Webmaster | Traffic and Transportation Safety (TTS) Lab Website, TU Delft

Mar.2020-June.2024

Oct.2015-Oct.2015

→ Responsible and volunteering for the <u>TTS Lab website</u> development and maintenance

Project Leader | Asian Youth Center: Leadership Development Training Program for Masters

Jul.2015-Aug.2016

- → Responsible for activities and competitions between overseas and Chinese students in the Asian Youth Center project
- ▶ Volunteer Leader in the 5th Joint School Symposium for the Asian Youth Center Project

iTalk Group Leader | International Department, Tsinghua University Postgraduate Association

Oct.2014-Oct .2015

→ Committed to speech in English given by students or alumni stars, held a special performance for overseas students

Volunteer | National Doctor Forum on Traffic and Transportation Engineering, Beijing Jiaotong University

Jun.2011

SKILLS & MISCELLANEOUS

- → Programming: Python (Tensorflow, PyTorch, Keras), Matlab, R, C/C++, Java, VHDL | Database: MySQL
- AI Certificates: Deep Learning, Deep Reinforcement Learning, TRAIL Research School Diploma
- ▶ Hardware circuit design: Altium Designer | Software development on Linux and Windows
- → Big data analytics and visualization methods | Cross-domain Data Fusion | Data-driven anomaly/fraud detection
- → Languages: Chinese (Native); English (Professional); Dutch (Elementary)
- Hobbies: Tai Chi, Kung Fu, Meditation, Yoga, Chess, Reading, Mountain Hiking