Yongqi Dong







Junior Research Group Leader @ RWTH Aachen University Ph.D. Researcher @ Delft University of Technology

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EDUCATIONAL BACKGROUND

PhD in Transportation, Department of Transport & Planning, **Delft University of Technology** (**TU Delft**) Dec.2019-May.2025 **Thesis:** *Safe, Efficient, and Socially Compliant Automated Driving: Sensing, Anomaly Detection, Planning and Control* **Advisors:** Prof.dr.ir. <u>Bart van Arem</u> and Dr.ir. <u>Haneen Farah</u>

Visiting PhD Researcher, Department of Mechanical Engineering, **University of California, Berkeley** May.2023- Oct.2023

Topic: Socially Compliant Automated Driving via Deep Reinforcement Learning and Model-based Social-aware MPC

Master of Control Science and Engineering, Department of Automation, Tsinghua University

Sep.2014-Jul.2017

Minor: Master Project for Improving Ability in Big Data

Thesis: Data-Driven Analysis on Group Behaviors of Taxi Drivers and Ridesourcing Drivers

Nominated for Tsinghua University Outstanding Master Thesis Dissertation

Advisors: Prof. Li Li and Prof. Zuo Zhang

Bachelor of Telecommunication Engineering

Sep.2010-Jul.2014

School of Electronic and Information Engineering, Beijing Jiaotong University

GPA: 91.5/100 | Rank: 1/202 | Postgraduate Recommendation to Tsinghua University without Examination

Thesis: Design of vehicle-mounted data acquisition & communication unit for the WMN-based locomotive remote control **Outstanding Undergraduate Thesis**

PUBLICATIONS

(Google Scholar ID: L2kD-DwAAAAJ. The superscript # indicates equal contribution, * indicates corresponding authors.)

Key Journal Publications:

- → 1. Dong, Y., Patil, S., van Arem, B., & Farah, H. (2023). A Hybrid Spatial-temporal Deep Learning Architecture for Lane Detection. Computer-Aided Civil and Infrastructure Engineering, 38(1), 67-86. https://doi.org/10.1111/mice.12829 [Top Q1, IF:8.5, SJR:2.972, CiteScore: 17.6]
- ◆ 2. Dong, Y., Wang, Sh., Li, L., Zhang, Z. (2018). An Empirical Study on Travel Patterns of Internet Based Ride-Sharing, Transportation Research Part C: Emerging Technologies, 86, 1-22. https://doi.org/10.1016/j.trc.2017.10.022 [Highly cited; Top Q1, IF:7.6, SJR:2.86, CiteScore: 15.8]
- → 3. Li, R.*, & **Dong, Y.****,*(2023). Robust Lane Detection Through Self Pre-Training With Masked Sequential Autoencoders and Fine-Tuning With Customized PolyLoss. *IEEE Transactions on Intelligent Transportation Systems*, vol. 24, no. 12, pp. 14121-14132, doi: https://doi.org/10.1109/TITS.2023.3305015. (Joint first author and corresponding author) [**Top Q1**, *IF*:7.9, *SJR*:2.58, *CiteScore*: 14.8]
- ◆ 4. Dong, Y. ***, Zhang, L. **, Farah, H., Zgonnikov, A., & van Arem, B. (2025). Data-driven Semi-supervised Machine Learning with Safety Indicators for Abnormal Driving Behavior Detection, (accepted by Transportation Research Record: Journal of the Transportation Research Board; accepted by and presented at TRBAM2024 and the 35th annual meeting of International Co-operation on Theories and Concepts in Traffic Safety (ICTCT 2023)), Preprint
- ▶ 5. Farah, H., Postigo, I., Reddy, N., **Dong, Y.**, Rydergren, C., Raju, N., & Olstam, J. (2022). Modelling Automated Driving in Microscopic Traffic Simulations for Traffic Performance Evaluations: Aspects to Consider and State of the Practice. *IEEE Transactions on Intelligent Transportation Systems*, 24(6), 6558-6574. https://doi.org/10.1109/TITS.2022.3200176 [Top Q1, IF:7.9, SJR:2.58, CiteScore: 14.8]

★ 6. Berge, S.H., de Winter, J., Dodou, D., Afghari, A. P., Papadimitriou, E., Reddy, N., Dong, Y., Raju, N., & Farah, H. (2025). Understanding Cyclists' Perception of Driverless Vehicles through Eye-Tracking and Interviews. Transportation Research Part F: Traffic Psychology and Behaviour, 109, 399-420. https://doi.org/10.1016/j.trf.2024.11.015 [Top Q1, IF:3.5, SJR:1.262, CiteScore: 7.6]

Key Conference Proceeding Publications & Presentations:

- ◆ 1. Zhang, L.*, Dong, Y. **, Farah, H., & van Arem, B. (2023). Social-aware Planning and Control for Automated Vehicles based on Driving Risk Field and Model Predictive Contouring Control: Driving through Roundabouts as a Case Study. 2023 IEEE International Conference on Systems, Man, and Cybernetics (SMC), Honolulu, Oahu, HI, USA, 2023, pp. 3297-3304. http://dx.doi.org/10.1109/SMC53992.2023.10394462. (Co-first author and corresponding author, accepted and presented at TRB's 2023 Automated Road Transportation Symposium), Demovideo
- ▶ 2. **Dong, Y.**^{#,*}, Lu, X. [#], Li, R., Song, W., van Arem, B., & Farah, H. (2023). Intelligent Anomaly Detection for Lane Rendering Using Transformer with Self-Supervised Pre-Training and Customized Fine-Tuning (**Accepted** and presented at <u>TRB2024</u> and *under second-round review* by *Transportation Research Record: Journal of the Transportation Research Board*, minor revision), <u>Preprint</u>
- → 3. Dong, Y., Detema, T., Wassenaar, V., van de Weg, J., Kopar, T., & Suleman, H. (2023). Comprehensive Comparison of Deep Reinforcement Learning for Automated Driving on Various Driving Maneuvers with Simulation. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 6165-6170, http://dx.doi.org/10.1109/ITSC57777.2023.10422159
- ◆ 4. **Dong, Y.**^{#,*}, Patil, S.[#], Farah, H, & Hellendoorn, J. (2023). Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames (**Presented** at *the Transportation Research Board (TRB) 102nd annual meeting TRB 2023*). TRBAM-23-04409 poster
- → 5. Yuan, H., Li, P., van Arem, B., Kang, L., Farah, H., & **Dong, Y.*** (2023). Safe, Efficient, Comfort, and Energy-saving Automated Driving through Roundabout Based on Deep Reinforcement Learning. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 6074-6079, http://dx.doi.org/10.1109/ITSC57777.2023.10422488 (Corresponding author and PI)
- ◆ 6. Xue, C.*, **Dong, Y.***, Liu, J.*, Liao, Y., & Li, L. (2023). Design of the Reverse Logistics System for Medical Waste Recycling Part I: System Architecture and Disposal Site Selection Algorithm. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 1741-1746, http://dx.doi.org/10.1109/ITSC57777.2023.10422624 (Co-first author)
- → 7. Xue, C.*, Dong, Y.*, Liu, J.*, Liao, Y., & Li, L. (2023). Design of the Reverse Logistics System for Medical Waste Recycling Part II: Route Optimization with Case Study under COVID-19 Pandemic. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 4011-4017. http://dx.doi.org/10.1109/ITSC57777.2023.10422236 (Co-first author)
- ▶ 8. **Dong, Y.***, Chen, K., Peng, Y., & Ma, Z. (2022). Comparative Study on Supervised versus Semi-supervised Machine Learning for Anomaly Detection of In-vehicle CAN Network. 2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC), 2022, pp. 2914-2919, https://doi.org/10.1109/ITSC55140.2022.9922235

Other Journal and Conference Publications:

- → 1. Lingam, S. N., De Winter, J., Dong, Y., Tsapi, A., Van Arem, B., & Farah, H. (2024). eHMI on the Vehicle or on the Infrastructure? A Driving Simulator Study. European Journal of Transport and Infrastructure Research, 24(2), 1–24. https://doi.org/10.59490/ejtir.2024.24.2.7273 [Journal]
- → 2. Dong, Y., Liu, C., Wang, Y., & Fu, Zh. (2024). Towards Understanding Worldwide Cross-cultural Differences in Implicit Driving Cues: Review, Comparative Analysis, and Research Roadmap. Accepted by and presented at the 2024 IEEE 27th International Conference on Intelligent Transportation Systems (ITSC), Preprint [Conference]
- → 3. Huang, Y.*, Dong, Y.**, Tang, Y., & Li, L. (2024). Leverage Multi-source Traffic Demand Data Fusion with

- Transformer Model for Urban Parking Prediction. Accepted by <u>the 28th International Conference Of Hong Kong</u>
 <u>Society For Transportation Studies (HKSTS 2024)</u> and the <u>Conference in Emerging Technologies in Transportation</u>
 <u>Systems (TRC-30)</u> for presentation, <u>Preprint [Conference]</u>
- → 4. **Dong, Y.*****, Chen, K.**, & Ma, Z. (2023). Comparative Study on Semi-Supervised Learning Applied for Anomaly Detection in Hydraulic Condition Monitoring System. 2023 IEEE International Conference on Systems, Man, and Cybernetics (SMC), Honolulu, Oahu, HI, USA, 2023, pp. 1702-1708, http://dx.doi.org/10.1109/SMC53992.2023.10394193 [Conference]
- → 5. Raju, N., Schakel, W., Reddy, N., Dong, Y., Farah, H. (2022). Car-Following Properties of a Commercial Adaptive Cruise Control System- A Pilot Field Test. Transportation Research Record: Journal of the Transportation Research Board, 2676(7), 128-143. https://doi.org/10.1177/03611981221077085 [Journal]
- → 7. Dong, Y., Yang, Z., Yue, Y., Pei, X., & Zhang, Z. (2018). Revealing Travel Patterns of Sharing-bikes in a Spatial-temporal Manner Using Non-negative Matrix Factorization Method. In CICTP 2018: Intelligence, Connectivity, and Mobility (pp. 1665-1674). Reston, VA: American Society of Civil Engineers. https://doi.org/10.1061/9780784481523.165 [Conference]
- → 7. Yue, Y., Pei, X., Yang, Z., **Dong, Y**., & Yao, D. (2018). A Trip Building and Chaining Methodology Using Traffic Surveillance Data. In *CICTP 2018: Intelligence, Connectivity, and Mobility* (pp. 2254-2262). Reston, VA: American Society of Civil Engineers. https://doi.org/10.1061/9780784481523.224 [Conference]
- ▶ 8. **Dong, Y.**, Zhang, Z., Fu, R., Xie, N. (2016). Revealing New York Taxi Drivers' Operation Patterns Focusing on the Revenue Aspect. (2016) In *12th World Congress* on *Intelligent Control and Automation (WCICA)*, (pp. 1052-1057). IEEE. https://doi.org/10.1109/WCICA.2016.7578771 [Conference]
- → 9. **Dong, Y.**, Ruan, H., Cai, T., Peng, J, and Wang ,W. (2013). Using LED to Demonstrate the Composition of Simple Harmonic Motions and Five Polarization States of Light. *Physics Experimentation*, 11, 45-48 [Journal in Chinese]

Under Review and Working Papers:

- → 1. Dong, Y., van Arem, B., & Farah, H. (2025). Safe and Socially-compliant Automated Driving through Integrating Multi-Agent Reinforcement Learning with SVO and MPCC (In preparation, to be submitted to the Proceedings of the National Academy of Sciences, PNAS)
- ▶ 2. Dong, Y., Farah, H., & van Arem, B. (2025). Towards Developing Socially-Compliant Automated Vehicles: State of the Art, Experts Expectations, and a Conceptual Framework (Accepted by the 104th TRB Annual Meeting (TRB 2025) for poster presentation, and presented at the 4th Symposium on Management of Future Motorway and Urban Traffic Systems (MFTS); Under Review by Communications in Transportation Research), Preprint
- → 3. Patil, S.*, **Dong, Y.****, Farah, H, & Hellendoorn, J. (2025). Efficient Sequential Neural Network based on Spatial-Temporal Attention and Linear LSTM for Robust Lane Detection Using Multi-Frame Images, (Joint first author and corresponding author, *Under Review* by IEEE Transactions on Intelligent Vehicles (T-IV)), <u>Preprint</u>
- → 4. Ji, J., Lu, R., Belkessa, L., Dong, Y., Wang, L., Madadi, B., Varotto, S., Saunier, N., MacFarlane, G., & Wu, C., (2025). Exploring Artifacts Availability in Transportation Research Using Large Language Models, *Under Review* by *International Symposium on Transportation Data & Modelling (ISTDM)* 2025
- → 5. Wu, C., Ji, J., Lu, R., Madadi, B., **Dong, Y.**, Varotto, S., Belkessa, L., Saunier, N., MacFarlane, G., Wang, L., Ghosh, B. (2025). Measuring Availability Features for Reproducibility in Transportation Research, to be submitted to *Transportation Research Part C: Emerging Technologies*, *Under Review* by *Transportation Research Symposium*
- ♦ 6. Zhang, Y., Dong, Y.* (2025). Optimization of coordinated flow restriction and skip-stopping schemes for urban rail stations considering platform carrying capacity (Presented at the Transportation Research Board (TRB) 102nd annual meeting TRB 2023, Under Review by Journal of Advanced Transportation). TRBAM-23-04413 poster, Preprint
- → 7. Liu, W., Zhang, X., **Dong, Y.**, Xu, L. (2025). A Unified Model Predictive Control Method of Automated Vehicles for Lane Changing and Lane Keeping Maneuvers (*Under review* by *Journal of Intelligent Transportation Systems, Minor*)
- ▶ 8. Dong, Y.#,*, Reyna, C.F.#, Klunder, G., Liao, F., & Rasouli, S. (2025). A Benchmarking Framework for Traffic

- Microsimulation Platforms: Case Study on Dutch Motorways with Dynamic Speed Limits. (Joint first author and corresponding author, to be submitted to Transportation Research Part C: Emerging Technologies)
- → 9. Zhang, Y., Dong, Y.*., Evans, C., Rinaldi, M., Shyrokau, B., & Farah, H. (2025). Coordinated Planning and Control for Connected and Automated Vehicles' On-ramp Merging in Mixed Traffic Through Value Decomposition-based Multiagent Deep Reinforcement Learning. (Corresponding author, to be submitted to Transportation Research Part C: Emerging Technologies)
- → 10. The Age of Smart Integrated Transportation: Practice of in the Digital Transformation of Transportation Industry [M]. Publishing House of Electronics Industry. [Involved as reviewer and expert editor for Preface, Chapters 1 & 13]
 Open resource repository:
 - Datasets, Simulation Platforms, and Relevant Publications on Emerging Mixed Traffic of AVs and HDVs

PATENTS & SOFTWARE COPYRIGHTS

- **♦** European and Dutch Patent:
- → Dong, Y., Li, R. Automated lane detection (IDF OCT-22-060, granted on May 25, 2024, Patent number 2033551)
- → Socially compliant Planning and Control for Automated Vehicles using Model-backend Deep Reinforcement Learning with Driving Risk Field and Model Predictive Contouring Control (OCT-23-056, N2035943, Submitted & filed)
- **♦** Chinese Invention Patent:
- ▶ Intelligent Demonstration Instrument of Simple Harmonic Oscillation Composition and Five Polarization States of Light, Application ID: 201310123700.5, Date: 2013.08.07, Patent Number CN103236211B, Publication Date: 2016.07.06
- **♦** Software copyright:
- → Spatial-Temporal Attention Integrated Sequential Neural Network Model for Vision-based Robust Lane Detection Using Multi Continuous Image Frames (i-DEPOT 142731, approved & registered)
- → Vision-Based Lane Detection System With Self-supervised Pre-training Through Masked Sequential Auto-encoders (Computer Software Copyright Registration in China, 2024SR1350911, approved & registered)

ACADEMIC SERVICES

Technical Committee (Chair) | Automated Mobility in Mixed Traffic | IEEE ITSS Mar.2025-Present Establishing and chairing the interdisciplinary community: "Automated Mobility in Mixed Traffic"

IEEE ITSS New Initiatives Project Principal Investigator (PI) | IEEE ITSS Mar.2024-Present

Project: Promoting interdisciplinary research toward the deployment of automated vehicles in mixed traffic

Workshop Organizer (Primary coordinator) | 27th IEEE ITSC 2024, Edmonton, Canada Sep.24, 2024 Workshop title: <u>Automated Mobility in Emerging Mixed Traffic</u>

Workshop Organizer (Second coordinator) | 26th IEEE ITSC 2023, Bilbao, Bizkaia, Spain Sep. 24, 2023

Workshop title: Data-driven and Empirical Research for Emerging Mixed Traffic of Automated Vehicles

and Human-driven Vehicles

Workshop Organizer (Primary coordinator) | IEEE IV 2023, Anchorage, USA Jun.4, 2023

Workshop title: <u>Development of Socially-compliant Driving Behaviour for Automated Vehicles to Enhance</u>
<u>Safety and Efficiency in Mixed Traffic</u>

IEEE TCoS Seeding Project Leader (PI) | 2023 IEEE TAB Committee on Standards (TCoS) seed funding Project title: *Enhancing the deployment of socially-compliant automated vehicles in mixed traffic* (website)

Ad-hoc Journal Reviewer Services

- ▶ International Journal of Computer Vision (**IF: 19.5**; Top AI journal)
- → IEEE Transactions on Intelligent Transportation Systems
- ▶ IEEE Open Journal of Intelligent Transportation Systems

- → Transportation Letters: the International Journal of Transportation Research
- → Journal of Intelligent Transportation Systems: Technology, Planning, and Operations
- ▶ Journal of Transportation Research Record: Journal of the Transportation Research Board
- ▶ International Journal of Human-Computer Interaction
- Journal of Advanced Transportation
- → Scientific Reports
- → Applied Ergonomics
- → European Transport Research Review
- ▶ ASCE-ASME Journal of Risk and Uncertainty in Engineering Systems, Part A: Civil Engineering

Ad-hoc Conference Reviewer Services

- → IEEE Intelligent Vehicles Symposium (IV) | Associate editor
- → IEEE Intelligent Transportation Systems Conference (ITSC)
- → Transportation Research Board (TRB) Annual Meeting
- → World Congress on Intelligent Control and Automation (WCICA)
- **♦** COTA International Conference of Transportation Professionals (CICTP)
- → The International Symposium on Transport Network Resilience (INSTR)

THESIS SUPERVISION

Yuteng Zhang | Master of Science in Transport, Infrastructure & Logistics

Jan.2024-Nov.2024

Thesis title: Coordinated Planning and Control for Connected and Automated Vehicles' On-ramp Merging in Mixed

Traffic Through Value Decomposition-based Multiagent Deep Reinforcement Learning

Cesar Flores Reyna | Master of Science in Sustainable Mobility Transitions, EIT, TU/e Jan.2024-Nov.2024

Thesis title: Investigating a Benchmarking Framework for the Large-Scale Micro Simulator (LSMS) Platform in Freeways under Dynamic Speed Limits

Mathijs den Otter | Master of Science in Civil Engineering-Transport and Planning Sep. 2022-Dec. 2023

Thesis title: <u>Impact of Improved Lane Marking Properties on the Performance of Lane Keeping Assistance Systems in Varying Circumstances</u>

Lanxin Zhang | Master of Science in Civil Engineering-Transport and Planning Oct.2022-Jun.2023

Thesis title: Semi-supervised Machine Learning for Abnormal Driving Behaviour Detection

Henan Yuan | Bachelor in Traffic and Transportation, BJTU&TUDelft TTE Oct.2022-Jun.2023

Thesis title: Deep Reinforcement Learning for Driving through Roundabouts

Shiva Nischal Lingam | Master of Science in Civil Engineering-Transport and Planning Jan. 2021-Nov. 2021

Thesis title: Effects of External Human Machine Interfaces on Automated Vehicles' Communicative

Interactions With Human Drivers (Cum Laude) | Won 2nd Cuperusprijs prieze of KIVI

Sandeep Patil | Master of Science in Mechanical Engineering (Vehicular Engineering) Oct.2020-Aug.2021

Thesis title: Lane Detection using SpatioTemporal Attention

Eline van der Kooij | Master of Science in Transport, Infrastructure & Logistics Jul.2020-May.2021

Thesis title: Visibility of Lane Markings for Machine Vision

Sanny Toonen | Bachelor of Science in Civil Engineering-Transport and Planning Jul.2020-May.2021

Thesis title: Lane Recognition for Automated Vehicles

TEACHING ACTIVITIES

Project supervisor, Instructor | EEMCS, TU Delft

Nov.2022-Feb.2024

Courses: Interdisciplinary Advanced AI Project (IFEEMCS520200); Capstone Applied AI Project (T13150TU)

Fundamentals of Artificial Intelligence Programme (IFEEMCS520100)

Teaching Assistant, Instructor | TU Delft and BJTU joint bachelor program Mar.2022 & Mar.2023

Course: Advanced Lecture "Trends in Transportation" 2022 & 2023

Lecturer | DakeOffer online Platform Mar.2020-Jun.2020 & Nov.2020-Jan.2021

Course: Introduction to Big Data and Artificial Intelligence: Fundamental and Practice

Teaching Assistant | Transport and Planning, TU Delft Apr.2020-Aug.2020 & Apr.2021-Aug.2021

Course: CIE5805 – Intelligent Vehicles for Safe and Efficient Traffic

Teaching Assistant | Department of Automation, Tsinghua University Sep.2016-Jan.2017

Course: Data Ethics

Teaching and Lab Assistant | Electrical and Electronic Lab Center, Tsinghua University Mar. 2015-Jul. 2016

Courses: Advanced Labs in Electronic Technology, Fundamentals of Electronics Power Technology

RSI Tutor | Center for Excellence in Education, USA

Jul.2017-Aug.2017

Research writing and presentation tutor for the 2017 Research Science Institute Program at Tsinghua University

Undergraduate Counselor (Class 2012) | School of EIE, Beijing Jiaotong University Jul. 2012 - Jul. 2014

TALKS & PRESENTATIONS

Promoting Diversity and Leadership in ITS | IEEE WiE/YP Workshop & Forum, Cairo, Egypt Nov.21.2023

Presentation topic: Resource Repository: Datasets, Simulation Platforms, and Relevant Publications for Emerging Mixed

Traffic of Automated Vehicles and Human-driven Vehicles

Automated Round Transportation | TRB ARTS 2023, San Francisco, USA

Jul.12.2023

Presentation topic: Social-aware Planning and Control for Automated Vehicles Based on Driving Risk Field and Model
Predictive Contouring Control: Driving through Roundabouts as a Case Study

AI Applications in Transportation Planning | TRB 2023, Washington D.C., USA

Jan.11.2023

Presentation topics: (1) Robust Lane Detection through Self Pre-training with Masked Sequential Autoencoders and Fine-tuning with Customized PolyLoss

(2) Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames

Research into Urban Rail Transit Operations and Design | TRB 2023, Washington D.C., USA Jan.11.2023

Presentation topic: Optimization of coordinated flow restriction and skip-stopping schemes for urban rail stations considering platform carrying capacity

Connected and Automated Vehicles | MFTS 2022, Dresden, Germany

Dec.01.2022

Presentation topic: Towards Developing Socially-Compliant Automated Vehicles: State of the Practice, Experts

Expectations, and a Conceptual Framework

Automated mobility | IEEE ITSS Young Professionals Fellowship Symposium, Chania, Greece Nov.25.2022

Presentation topic: Multi-goal proactive traffic management for mixed traffic of automated vehicles (AVs) and human-driven vehicles (HDVs) using explainable physics-informed Artificial Intelligence

AI, Security, Privacy and Safety Systems in ITS Applications ITSC2022, Macow, China Oct.08.2022

Presentation topic: Comparative Study on Supervised vs Semi-supervised ML for Anomaly Detection of CAN Network

Research on AI and Advancing Computing Applications | TRB 2022, Washington D.C., USA Jan.12.2022

Presentation topic: A Hybrid Spatial-temporal Sequence-to-one Neural Network Model for Lane Detection

Challenges of Automated Vehicles and Traffic | University of Győr, Hungary

May.28.2021

Talk topic: Deep learning for automated vehicles' operational design domain: problems, challenges, and case studies

SAMEN User Committee Annual Meeting | Dutch Research Council (NWO), Delft, Netherlands Jan. 28.2021

Talk topic: Data-driven research for automated vehicles' operational design domain: a case study on perception

Intelligence, Connectivity, and Mobility | COTA CICTP 2018, Tsinghua University, China Jul.07.2018

Presentation topic: Revealing travel patterns of sharing-bikes in a spatial-temporal manner using the NFM method

World Congress on Intelligent Control and Automation | IEEE WCICA 2016, Guilin, China Jun.12.2016

Presentation topic: Revealing New York Taxi Drivers' Operation Patterns Focusing on the Revenue Aspect

HONORS & AWARDS

- **→** Chinese CSC Award for Outstanding Self-financed Students Abroad (6,000 \$)
- **▶** TU Delft-Transport Institute Interdisciplinary Research Award (10,500 €)
- **→** 2023 IEEE TAB Committee on Standards (TCoS) seed funding (6,000 \$)
- **→** 2024 IEEE ITSS New Initiatives Proposal Funding (5,000 \$)
- **▶** IEEE ITSS Young Professionals Fellowship (Twice)
- Erasmus + mobility Grants (Three times)
- Outstanding College Graduates of Beijing (Top 1‰)
- → National Scholarship (Top 1%)
- First Class Tsinghua University RONG Scholarship
- Second-Class Merit Scholarship for Masters Tsinghua University
- Merit Student (Four times)
- → First-Class Academic Fellowship (Top 1%, Twice)
- Second Prize in the 2012 & 2013 Undergraduate Electronic Design Contest in Beijing
- Bronze award in "Challenge Cup" Entrepreneurship Design Contest in Beijing
- First Prize in Freescale Cup University Students Intelligent Car Race (Rank 2nd)
- Second Prize in the Physical Experiment Competition in Beijing
- 2019 Microsoft Discover AI Challenge: Sustainable Life | Data-Driven All-in-one Shared Mobility | Top (10%)

RESEARCH EXPERIENCE

- → AI-Enhanced Hierarchical Multi-objects Driving Risk Field Model Integrating Physics-Based and Human Perception-Based Approaches with Drivers' Distraction (PI, <u>Individual DFG</u>)
- **▶** Explainable Mathematics-Enhanced AI Model for Multi-Modal Urban Traffic Prediction and Simulation (Co-PI, <u>DFG Research Unit Proposal</u>)
- → Realistic Modelling of Cycling Behaviour and Interaction with Other Road Users in Mixed Traffic (PI, <u>DFG Package Proposal</u>)
- → Parameter-Efficient Fine-Tuning of Pretrained Multimodal Large Vision Model (LVM) for Privacy-preserving Traffic Anomaly Detection with Thermal Imaging

Traffic and Transportation Safety Lab | Department of Transport and Planning | TU Delft Dec. 2019-Jun. 2024

- Data-driven and AI-based research for expanding Automated Vehicles' Operational Design Domain in mixed traffic (part of <u>SAMEN</u> project)
 - > Developed a hybrid sequence-to-one model for lane detection in extremely hard driving scenes
 - > Incorporated spatial-temporal attention for automated vehicles' perception
 - > Designed reliable data-driven algorithms for anomalies and abnormal behaviors prediction
 - > Implemented Deep Reinforcement Learning (DRL) models for safe, reliable, and socially compliant automated driving under challenging manoeuvres involving both longitudinal and lateral control
 - > Gaze behaviour of road users when interacting with an automated vehicle at an intersection: Understanding

cyclists' perception of driverless vehicles through eye-tracking and interviews

Mechanical Systems Control (MSC) Lab | Department of Mechanical Engineering | UC Berkeley May.2023-Oct.2023 Advisor: Prof. Masayoshi Tomizuka

- Socially Compliant Automated Driving through DRL and Model-based Social-aware MPC
 - > Reviewed State-of-the-art Socially Compliant Automated Driving Methods in Literature
 - > Developed Model-enhance Multi-agent Deep Reinforcement Learning with Social-aware MPC

Waterloo Artificial Intelligence Institute | Faculty of Engineering | University of Waterloo

May.2018-Sep.2019

- **▶** Applied Machine Learning, Artificial Intelligence, and Big Data Research
 - > 2018 Railroad Problem Solving Contest: Use CNN-LSTM-Dense Concatenated model to forecast train delays
 - > A Deep Learning Framework for Traffic Forecasting: Exploring GCN joint with LSTM to predict traffic flow
 - > Data-driven anomaly detection (unsupervised): Auto-Encoder, Hierarchical Extreme Learning Machines
 - > Kaggle competition: Employ LSTM, LightGBM, XGBoost models to predict stock movements with news data
 - > Deep reinforcement learning in traffic control: DQN, A3C, and PPO methods
 - Real-time Road Surface Condition (RSC) Monitoring: Adopt CNN to RSC image classification

Singapore-MIT Alliance for Research and Technology (SMART)

Aug.2016-Sep.2016

Future Urban Mobility (FM) IRG | Project: SimMobility | Topic: Taxi Roaming

Advisors: Prof. Moshe BEN-AKIVA, Postdoctoral Associate Bat-hen NAHMIAS-BIRAN

- → Constructing a model tackling the taxi roaming (taxi service) problem, to be embedded into the SimMobility platform
 - > Proposed one advisable solution of cruising along hotspots through a cell-based logit-opportunity model improved by a data-driven method
 - > Participated in building the architecture of the final model embedded in SimMobility

Intelligent Transportation Laboratory, Tsinghua National Laboratory for Information Science and Technology

(TNList) | Advisors: Prof. Zuo Zhang and Prof. Li Li (IEEE Fellow)

Sep.2014-May.2018

Transportation Research based on machine learning and data-driven methods

- ▶ Revealing New York taxi drivers' operation patterns focusing on revenue
 - > Developed a method for classifying drivers into 3 groups based on their revenue: top, ordinary, low earner
 - > Excavated the population operation patterns of different taxi driver groups through big data analytics
- → Influence of on-demand ridesourcing vs. traditional taxi based on machine learning and big data analytics
 - > Uncovered the differences between taxi service and ridesourcing using big data analysis and clustering
 - > Applied non-negative matrix factorization (NMF) to obtain basis patterns of Taxi, Hitch and Express service
- → Influence of on-demand ridesourcing on vehicle emissions with big data analytics and PHEM model
- → Fundamental research on intelligent parking guidance and recommendations based on machine learning
 - Forecast models of travel time to parking lots (Random Forest); Guidance & optimization models for parking
 - > Personalized recommendation research on parking (Collaborative Filtering and Content-based algorithm)
- Study on key technology in Intelligent Vehicle Infrastructure Cooperative Systems (IVICS) (863 Program)
 - > Contributed to the design report of basic technical framework and the overall demonstration of IVICS

The Freescale Cup College Students Intelligent Car Race: Intelligent car that can follow

Jun.2012-Jun.2013

specific trajectories based on image processing, pattern recognition, and PID controller

- → Hardware Aspect: Designed the signal acquisition circuit and the core control circuit based on MC9S12XS256
- → Software Aspect: Developed specific control strategies/algorithms for intelligent cars to follow given trajectories
- Actuator: Customized specific steering linkage, applied and tuned PID algorithms to control diversion and speed

WORKING EXPERIENCE

Junior Research Group Leader | AI & Automated Mobility Group | RWTH Aachen University Jun. 2024-Present

- ▶ Research proposal initialization, preparation, and writing: German Research Foundation (DFG) and mFUND
- **▶** Co-PI: main responder and drafter for three DFG research proposals
- → Lead the group and supervise the PhD/MSc students
- → Teaching support for Road Planning II and Machine Learning in Civil Engineering (master's level)

PhD Researcher | TTS Lab | Department of Transport & Planning | TU Delft

Dec.2019-Jun.2024

- ▶ Carried out PhD research work under the NWO funded SAMEN project
- → Provided teaching assistance and evaluation support for various courses and supervised seven MSc students
- ▶ Published scientific papers and patents, presented research works in conferences and organized workshops

Visiting PhD Researcher | MSC Lab | Department of Mechanical Engineering | UC Berkeley

May.2023-Oct.2023

→ Carried out literature review and research work related to Socially Compliant Automated Driving

Research Assistant | Waterloo Artificial Intelligence Institute | University of Waterloo

May.2018-Sep.2019

→ Carried out research works related to applied Machine Learning, Artificial Intelligence, and Big Data in Transportation

Research Assistant | Transport Big Data Analytics | ITS Lab, TNList@Tsinghua University Aug.2017- May.2018

- → Cross-domain data fusion for full-time trip chain reconstruction and anomaly detection;
- → City Computing: Applying NMF methods to evaluate indicators describing urban function, land use, mobility, etc.
- ▶ Revealing collective travel patterns of Shared Mobility in a spatial-temporal manner

Carryout service data analysis Project Manager | Beijing Gooagoo Technical Service Co., Ltd. Jul.2016-Aug.2016

→ Integral process of Big Data Analytics: Crawled carryout service data using Python crawler; executed data storage,
data analysis, and data processing in a relational database (MySQL); visualization, clustering, and web application

Commentator | China International Congress on Intelligent & Connected Vehicles (CICV)

Oct.2015-Oct.2015

→ Introduced the i-VICS systems to audiences; received executives from automobile manufacturers BMW, Volvo, VW

LEADERSHIP & VOLUNTEER EXPERIENCE

Webmaster | Traffic and Transportation Safety (TTS) Lab Website, TU Delft

Mar.2020-June.2024

Responsible and volunteering for the TTS Lab website development and maintenance

Project Leader | Asian Youth Center: Leadership Development Training Program for Masters

Jul.2015-Aug.2016

- → Responsible for activities and competitions between overseas and Chinese students in the Asian Youth Center project
- ♦ Volunteer Leader in the 5th Joint School Symposium for the Asian Youth Center Project

iTalk Group Leader | International Department, Tsinghua University Postgraduate Association

Oct.2014-Oct .2015

→ Committed to speech in English given by students or alumni stars, held a special performance for overseas students

Volunteer | National Doctor Forum on Traffic and Transportation Engineering, Beijing Jiaotong University

Jun.2011

SKILLS & MISCELLANEOUS

- → Programming: Python (Tensorflow, PyTorch, Keras), Matlab, R, C/C++, Java, VHDL | Database: MySQL
- ♦ Deep Learning, Deep Reinforcement Learning, TRAIL Research School Diploma
- ▶ Hardware circuit design: Altium Designer | Software development on Linux and Windows
- ▶ Big data analytics and visualization methods | Cross-domain Data Fusion | Data-driven anomaly/fraud detection
- ▶ Languages: Chinese (Native); English (Professional); **Dutch** (Elementary)
- 🖊 Hobbies: Tai Chi, Kung Fu, Meditation, Yoga, Chess, Reading, Mountain Hiking