

Yongqi Dong

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Ph.D. Researcher | Delft University of Technology

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EDUCATIONAL BACKGROUND

Visiting Scholar, Department of Mechanical Engineering, **University of California, Berkeley** May.2023- Oct.2023
Socially Compliant Automated Driving via Integrating Deep Reinforcement Learning and Model-based Social-aware MPC

Ph.D. Researcher, Department of Transport and Planning, **Delft University of Technology (TU Delft)** Dec.2019-Present
Thesis: Expanding the Operational Design Domain of Automated Vehicles in Mixed Traffic with Artificial Intelligence
(*Safe, Efficient, and Socially Compliant Automated Driving: Sensing, Planning, and Control*)

Master of Control Science and Engineering, Department of Automation, **Tsinghua University** Sep.2014-Jul.2017
Minor: Master Project for Improving Ability in *Big Data*
Thesis: Data-Driven Analysis on Group Behaviors of Taxi Drivers and Ridesourcing Drivers
Nominated for Tsinghua University Outstanding Master Thesis Dissertation

Bachelor of Telecommunication Engineering Sep.2010-Jul.2014
School of Electronic and Information Engineering, **Beijing Jiaotong University**
GPA: 91.5/100 | Rank: 1/202 | Postgraduate Recommendation to Tsinghua University without Examination
Thesis: Design of vehicle-mounted data acquisition and communication unit for the WMN based locomotive remote control
Outstanding Undergraduate Thesis

PUBLICATIONS & PATENTS

- ✦ **Dong, Y.**, Patil, S., van Arem, B., & Farah, H. (2023). A Hybrid Spatial-temporal Deep Learning Architecture for Lane Detection. *Computer-Aided Civil and Infrastructure Engineering*, 38(1), 67-86. <https://doi.org/10.1111/mice.12829>
[Q1, IF:9.6, SJR:2.962]
- ✦ **Dong, Y.**, van Arem, B., & Farah, H. (2024). Safe and Socially-compliant Automated Driving through Integrating Deep Reinforcement Learning with SVO and MPCC (In preparation, to be submitted to *the Proceedings of the National Academy of Sciences, PNAS*)
- ✦ **Dong, Y.**, Farah, H., & van Arem, B. (2023). Towards Developing Socially-Compliant Automated Vehicles: State of the Practice, Experts Expectations, and a Conceptual Framework (**Accepted** by the *4th Symposium on Management of Future Motorway and Urban Traffic Systems 2022 (MFTS2022)*, to be submitted to *Journal of Transport Reviews*).
- ✦ Li, R.#, & **Dong, Y.#***(2023). Robust Lane Detection Through Self Pre-Training With Masked Sequential Autoencoders and Fine-Tuning With Customized PolyLoss. *IEEE Transactions on Intelligent Transportation Systems*, vol. 24, no. 12, pp. 14121-14132, doi: <https://doi.org/10.1109/TITS.2023.3305015>. (Joint first author and corresponding author)
- ✦ Patil, S.#, **Dong, Y.#***, Farah, H., & Hellendoorn, J. (2023). Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames (Joint first author and corresponding author, *Journal of Transportation Research Part C: Emerging Technologies, Under Review*), [Preprint](#)
- ✦ **Dong, Y.**, Liu, C., Wang, Y., & Fu, Zh. (2024). Towards Understanding Worldwide Cross-cultural Differences in Implicit Driving Cues: Review, Comparative Analysis, and Research Roadmap. Under review by 2024 *IEEE 27th International Conference on Intelligent Transportation Systems (ITSC)*, [Preprint](#)
- ✦ Huang, Y.#, **Dong, Y.#**, Tang, Y., & Li, L. (2024). Leverage Multi-source Traffic Demand Data Fusion with Transformer

Model for Urban Parking Prediction. Under review by 2024 IEEE 27th International Conference on Intelligent Transportation Systems (ITSC), [Preprint](#)

- Zhang, L.[#], **Dong, Y.**^{*,*}, Farah, H., & van Arem, B. (2023). Social-aware Planning and Control for Automated Vehicles based on Driving Risk Field and Model Predictive Contouring Control: Driving through Roundabouts as a Case Study. 2023 IEEE International Conference on Systems, Man, and Cybernetics (SMC), Honolulu, Oahu, HI, USA, 2023, pp. 3297-3304. <http://dx.doi.org/10.1109/SMC53992.2023.10394462>. (Co-first author and corresponding author, accepted and presented at *TRB's 2023 Automated Road Transportation Symposium*), [Demo video](#)
- **Dong, Y.**^{*,*}, Chen, K.[#], & Ma, Z. (2023). Comparative Study on Semi-Supervised Learning Applied for Anomaly Detection in Hydraulic Condition Monitoring System. 2023 IEEE International Conference on Systems, Man, and Cybernetics (SMC), Honolulu, Oahu, HI, USA, 2023, pp. 1702-1708, <http://dx.doi.org/10.1109/SMC53992.2023.10394193>.
- Lingam, N., de Winter, J., **Dong, Y.**, Tsapi, A., van Arem, B., & Farah, H. (2023). eHMI on the vehicle or just a traffic light? A driving simulator study (**Accepted** by *European Journal of Transport and Infrastructure Research*), [Preprint](#)
- **Dong, Y.**^{*,*}, Lu, X.[#], Li, R., Song, W., van Arem, B., & Farah, H. (2023). Intelligent Anomaly Detection for Lane Rendering Using Transformer with Self-Supervised Pre-Training and Customized Fine-Tuning (**Accepted** by the 2023 23rd COTA International Conference of Transportation Professionals, **accepted** by [TRB2024](#) and **under second-round review** by *Transportation Research Record: Journal of the Transportation Research Board*, **minor revision**), [Preprint](#)
- **Dong, Y.**^{*,*}, Li, R.[#], Farah, H. (2023). Robust Lane Detection through Self Pre-training with Masked Sequential Autoencoders and Fine-tuning with Customized PolyLoss (**Presented** at the *Transportation Research Board (TRB) 102nd annual meeting TRB 2023*). [TRBAM-23-02979 poster](#), [Preprint](#)
- Zhang, Y., **Dong, Y.**^{*} (2023). Optimization of coordinated flow restriction and skip-stopping schemes for urban rail stations considering platform carrying capacity (**Presented** at the *Transportation Research Board (TRB) 102nd annual meeting TRB 2023*, **under review** by *Transportation Research Record: Journal of the Transportation Research Board*). [TRBAM-23-04413 poster](#), [Preprint](#)
- **Dong, Y.**^{*,*}, Patil, S.[#], Farah, H., & Hellendoorn, J. (2023). Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames (**Presented** at the *Transportation Research Board (TRB) 102nd annual meeting TRB 2023*). [TRBAM-23-04409 poster](#)
- Liu, W., Zhang, X., **Dong, Y.**, Xu, L. (2023). A Unified Model Predictive Control Method of Automated Vehicles for Lane Changing and Lane Keeping Maneuvers (**Under Review** by *Journal of Intelligent Transportation Systems*)
- **Dong, Y.**, Detema, T., Wassenaar, V., van de Weg, J., Kopar, T., & Suleman, H. (2023). Comprehensive Comparison of Deep Reinforcement Learning for Automated Driving on Various Driving Maneuvers with Simulation. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 6165-6170, <http://dx.doi.org/10.1109/ITSC57777.2023.10422159>
- Yuan, H., Li, P., van Arem, B., Kang, L., Farah, H., & **Dong, Y.**^{*} (2023). Safe, Efficient, Comfort, and Energy-saving Automated Driving through Roundabout Based on Deep Reinforcement Learning. 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Spain, 2023, pp. 6074-6079, <http://dx.doi.org/10.1109/ITSC57777.2023.10422488> (Corresponding author and PI)
- Zhang, L.[#], **Dong, Y.**^{*,*}, Farah, H., Zgonnikov, A., & van Arem, B. (2023). Data-driven Semi-supervised Machine Learning with Surrogate Safety Measures for Abnormal Driving Behavior Detection, (**Accepted** & presented at the 35th annual meeting of *International Co-operation on Theories and Concepts in Traffic Safety*, **accepted** by [TRBAM2024](#), **under second-round review** by *Journal of Transportation Research Board*, **minor revision**), [Preprint](#)
- Berge, B., de Winter, J., Dodou, D., Pooyan Afghari, A., Papadimitriou, E., Reddy, N., **Dong, Y.**, Raju, N., & Farah, H., (2023). Understanding cyclists' perception of driverless vehicles through eye-tracking and interviews (**Accepted** for presentation at the 35th annual meeting of *International Co-operation on Theories and Concepts in Traffic safety*)

(ICTCT Catania 2023), under review by Journal of Safety Science), [Preprint](#)

- Xue, C.[#], **Dong, Y.[#]**, Liu, J.^{*}, Liao, Y., & Li, L. (2023). Design of the Reverse Logistics System for Medical Waste Recycling Part I: System Architecture and Disposal Site Selection Algorithm. *2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC)*, Bilbao, Spain, 2023, pp. 1741-1746, <http://dx.doi.org/10.1109/ITSC57777.2023.10422624> (Co-first author)
- Xue, C.[#], **Dong, Y.[#]**, Liu, J.^{*}, Liao, Y., & Li, L. (2023). Design of the Reverse Logistics System for Medical Waste Recycling Part II: Route Optimization with Case Study under COVID-19 Pandemic. *2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC)*, Bilbao, Spain, 2023, pp. 4011-4017. <http://dx.doi.org/10.1109/ITSC57777.2023.10422236> (Co-first author)
- Huang, Y., **Dong, Y.^{*}** (2024). Prediction of Parking Space Availability through Fusing Multi-source Heterogeneous Demanding Data with Transformer (Co-first author and corresponding author, in preparation for Journal of *IEEE Transactions on Intelligent Transportation Systems*)
- Yang, C., **Dong, Y.^{*}** (2024). Robust Lane Detection using Image Sequential Attention Based Transformer Model with Elaborated Positional Encoding (Corresponding author, in preparation for Journal of *IEEE Transactions on Intelligent Transportation Systems*)
- Wu, G., **Dong, Y.^{*}** (2024). Sequential Multimodal Deep Learning for Anomaly Detection in Weakly-Labeled Videos (Corresponding author, in preparation for Journal of *IEEE Transactions on Robotics*)
- **Dong, Y.^{*}**, Chen, K., Peng, Y., & Ma, Z. (2022). Comparative Study on Supervised versus Semi-supervised Machine Learning for Anomaly Detection of In-vehicle CAN Network. *2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC)*, 2022, pp. 2914-2919, <https://doi.org/10.1109/ITSC55140.2022.9922235>
- Farah, H., Postigo, I., Reddy, N., **Dong, Y.**, Rydergren, C., Raju, N., & Olstam, J. (2022). Modeling Automated Driving in Microscopic Traffic Simulations for Traffic Performance Evaluations: Aspects to Consider and State of the Practice. *IEEE Transactions on Intelligent Transportation Systems*, 2022, <https://doi.org/10.1109/TITS.2022.3200176>
- Raju, N., Schakel, W., Reddy, N., **Dong, Y.**, Farah, H. (2022). Car-Following Properties of a Commercial Adaptive Cruise Control System- A Pilot Field Test. *Transportation Research Record: Journal of the Transportation Research Board*, <https://doi.org/10.1177/03611981221077085>
- **Dong, Y.**, Wang, Sh., Li, L., Zhang, Z. (2018). An Empirical Study on Travel Patterns of Internet Based Ride-Sharing, *Transportation Research Part C: Emerging Technologies* 86: 1-22. <https://doi.org/10.1016/j.trc.2017.10.022>
[Highly cited; Q1, IF:8.3, SJR:2.882]
- **Dong, Y.**, Yang, Z., Yue, Y., Pei, X., & Zhang, Z. (2018). Revealing Travel Patterns of Sharing-bikes in a Spatial-temporal Manner using Non-negative Matrix Factorization Method. In *CICTP 2018: Intelligence, Connectivity, and Mobility* (pp. 1665-1674). Reston, VA: American Society of Civil Engineers.
<https://doi.org/10.1061/9780784481523.165>
- Yue, Y., Pei, X., Yang, Z., **Dong, Y.**, & Yao, D. (2018). A Trip Building and Chaining Methodology Using Traffic Surveillance Data. In *CICTP 2018: Intelligence, Connectivity, and Mobility* (pp. 2254-2262). Reston, VA: American Society of Civil Engineers. <https://doi.org/10.1061/9780784481523.224>
- **Dong, Y.**, Zhang, Z., Fu, R., Xie, N. (2016) Revealing New York Taxi Drivers' Operation Patterns Focusing on the Revenue Aspect. (2016) In *12th World Congress on Intelligent Control and Automation (WCICA)*, (pp. 1052-1057). IEEE. <https://doi.org/10.1109/WCICA.2016.7578771>
- **Dong, Y.**, Wang, Sh., Li, L., (2017) Uncovering Influence of On-Demand Ride Service on Emission Reduction and Energy Conservation through PHEM Model. [work paper]
- **Dong, Y.**, Ruan, H., Cai, T., Peng, J., and Wang, W. (2013). Using LED to Demonstrate the Composition of Simple Harmonic Motions and Five Polarization States of Light. *Physics Experimentation* 11:45-48
- [The Age of Smart Integrated Transportation: Practice in the Digital Transformation of Transportation Industry](#) [M].

- ✦ **Open resource repository:** [Datasets, Simulation Platforms, and Relevant Publications on Emerging Mixed Traffic of Automated Vehicles and Human-driven Vehicles](#)
- ✦ **Chinese Invention Patent:** Intelligent Demonstration Instrument of Simple Harmonic Oscillation Composition and Five Polarization States of Light, Application ID: 201310123700.5, Date: 2013.08.07, Publication Patent Number CN103236211B, Publication Patent Date: 2016.07.06
- ✦ **European Patent:**
 - ✦ Automated lane detection through self pre-training with masked sequential auto-encoders, fine-tuning with customised PolyLoss, and post-processing with clustering and curve fitting (IDF OCT-22-060, submitted & **filed**)
 - ✦ Socially compliant Planning and Control for Automated Vehicles using Model-backend Deep Reinforcement Learning with Driving Risk Field and Model Predictive Contouring Control (OCT-23-056, N2035943, Submitted & **filed**)
- ✦ **Software copyright:** Spatial-Temporal Attention Integrated Sequential Neural Network Model for Vision-based Robust Lane Detection Using Multi Continuous Image Frames (i-DEPOT 142731, Submitted & **filed**)

RESEARCH EXPERIENCE

Traffic and Transportation Safety Lab | Department of Transport and Planning | **TU Delft**

Dec.2019-Present

Advisors: Dr.ir. [Haneen Farah](#) and Prof.dr.ir. [Bart van Arem](#)

- ✦ **Data-driven research for expanding Automated Vehicles' Operational Design Domain in mixed traffic** (part of [SAMEN](#) project)
 - Developed a hybrid sequence-to-one model for lane detection in extremely-hard driving scenes
 - Incorporated spatial-temporal attention for automated vehicles' perception
 - Designed reliable data-driven algorithms for peculiarities identification, recognition, and prediction
 - Implemented Deep Reinforcement Learning (DRL) models for safe, reliable, and socially-compliant automated driving under challenging manoeuvres involving both longitudinal and lateral control
 - Gaze behaviour of road users when interacting with an automated vehicle at an intersection

Research outputs:

- A Hybrid Spatial-temporal Deep Learning Architecture for Lane Detection (Published in [CACIE](#))
- Robust Lane Detection through Self Pre-training with Masked Sequential Autoencoders and Fine-tuning with Customized PolyLoss (Published in [IEEE Transactions on ITS](#), Accepted by TRB 2023 for presentation)
- Aspects to Consider for Modeling Automated Driving in Microscopic Traffic Simulations: State of the Practice and Research Needs. (Published in [IEEE Transactions on ITS](#))
- Car-Following Properties of a Commercial Adaptive Cruise Control System- A Pilot Field Test. (Published on [Transportation Research Record: Journal of the Transportation Research Board](#))
- Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames (Under review by [TR C](#), Accepted by TRB 2023 for presentation)
- Towards Developing Socially-Compliant Automated Vehicles: State of the Practice, Experts Expectations, and a Conceptual Framework (Accepted by MFTS 2022, to be submitted to Journal of Transport Reviews)
- Social-aware Planning and Control for Automated Vehicles based on Driving Risk Field and Model Predictive Contouring Control: Driving through Roundabouts as a Case Study (accepted by IEEE-SMC 2023)
- Intelligent Anomaly Detection for Lane Rendering Using Transformer with Self-Supervised Pre-Training and Customized Fine-Tuning (accepted by CICTP 2023 and TRB 2024).
- Safe, Efficient, and Social Compliant Autonomous Driving based on Deep Reinforcement Learning (Accepted

by IEEE-ITSC 2023)

- European Patent: Robust lane detection method through self pre-training with masked sequential auto-encoders and fine-tuning with customised PolyLoss (OCT-22-060, N2033551, submitted & filed)
- European Patent: Socially compliant Planning and Control for Automated Vehicles using Model-backend Deep Reinforcement Learning with Driving Risk Field and Model Predictive Contouring Control (OCT-23-056, N2035943, submitted and filed)
- Software copyright: Spatial-Temporal Attention Integrated Sequential Neural Network Model for Vision-based Robust Lane Detection Using Multi Continuous Image Frames (i-DEPOT 142731, submitted and filed)

Waterloo Artificial Intelligence Institute | Faculty of Engineering | University of Waterloo

May.2018-Sep.2019

✦ **Applied Machine Learning, Artificial Intelligence, and Big Data Research**

- The 2018 Railroad Problem Solving Contest: Use CNN-LSTM-Dense Concatenated model to forecast train delays
- A Deep Learning Framework for Traffic Forecasting: Exploring GCN joint with LSTM to predict traffic flow
- Data-driven anomaly/fraud detection (Unsupervised): Auto-Encoder, Hierarchical Extreme Learning Machines
- Kaggle Competition: Employ LSTM, LightGBM and XGBoost models to predict stock movements with news data
- Deep reinforcement learning in traffic control: DQN, A3C, and PPO methods
- Real-time Road Surface Condition Monitoring: Adopt Convolutional Neural Network to RSC image classification
- Optimized dynamic dispatching and operation algorithm for on-demand shared mobility by deep learning

Singapore-MIT Alliance for Research and Technology (SMART)

Aug.2016-Sep.2016

Future Urban Mobility (FM) IRG | Project: *SimMobility* | Topic: Taxi Roaming

Advisors: Prof. [Moshe BEN-AKIVA](#), Postdoctoral Associate [Bat-hen NAHMIAS-BIRAN](#)

✦ **Constructing a model tackling the taxi roaming (taxi service) problem, to be embedded into the *SimMobility* platform**

- Proposed one advisable solution of cruising along hotspots through a cell-based logit-opportunity model improved by a data-driven method
- Participated in building the architecture of the final model embedded in *SimMobility*

Intelligent Transportation Laboratory, Tsinghua National Laboratory for Information Science

Sep.2014-May.2018

and Technology (TNList) | Advisors: Prof. [Zuo Zhang](#) and Prof. [Li Li](#) (*IEEE Fellow*)

Transportation Research based on machine learning and data-driven methods

✦ **Revealing New York taxi drivers' operation patterns focusing on revenue**

- Developed a method for classifying drivers into 3 groups based on their revenue: top, ordinary, low earner
- Excavated the population operation patterns of different taxi driver groups through big data analytics

✦ **Influence of on-demand ridesourcing versus traditional taxi based on machine learning and big data analytics**

- Uncovered the differences between taxi service and ridesourcing using big data analyzing and clustering methods
- Applied non-negative matrix factorization (NMF) to obtain basis patterns of Taxi, Hitch and Express service

✦ **Influence of on-demand ridesourcing on vehicle emissions**

- Applied big data analytics and *PHEM* model to demonstrate how ridesourcing reduced total vehicle emissions

✦ **Fundamental research on intelligent parking guidance and recommendations based on machine learning**

- Forecast models of travel time to parking lots (*Random Forest*); Guidance and optimization models for parking
- Personalized recommendation research on parking (Collaborative Filtering and Content-based algorithm)

✦ **Study on key technology in Intelligent Vehicle Infrastructure Cooperative Systems (IVICS) (863 Program)**

- Contributed to the design report of basic technical framework and the overall demonstration of IVICS in China

Design of vehicle-mounted data acquisition and communication unit for the WMN-based

Jun.2013-Jun.2014

locomotive remote control system

- Designed basic hardware circuits, software, and algorithms to accomplish the analog and digital signal acquisition
- Applied PID control algorithm to control the locomotive's movement
- Commissioned and implemented the CAN bus protocol and Wireless Mesh Network communication

The Freescale Cup College Students Intelligent Car Race: Intelligent car that can follow Jun.2012-Jun.2013

specific trajectories based on image acquisition and processing, pattern recognition, and PID controller

- **Hardware Aspect:** Designed the signal acquisition circuit as well as the core control circuit based on MC9S12XS256
- **Software Aspect:** Developed a specific control strategy and algorithm for the intelligent car to follow a given trajectory
- **Actuator:** Customized specific steering linkage and applied different PID algorithms to control diversion and speed

National Innovation Project for College Students: Design of a system to demonstrate May.2012- May.2013

the composition of the simple harmonic motions and five polarization states of light by using LEDs

- Designed a system, including the circuits hardware (*Altium Designer*) and control software (C), for the demonstration
- Participated in the "Challenge Cup" Entrepreneurship Design Contest in Beijing and won the Bronze award

HONORS & AWARDS

Erasmus + mobility Grants (Three times)	National Scholarship (Top 1%)
IEEE ITSS Young Professionals Fellowship (Twice)	Second-Class Merit Scholarship for Masters Tsinghua University
Outstanding College Graduates of Beijing (Top 1%)	First-Class Academic Fellowship (Top 1%, Twice)
First Class Tsinghua University RONG Scholarship	Second-Class Academic Fellowship (Top 3%, Once)
School-level Merit Student (Four times)	Second prize of Innovation Awards by the School of Science
Chinese Government Award for Outstanding Self-financed Students Abroad (6,000 \$)	
TU Delft-Transport Institute Interdisciplinary Research Award (10,500 €)	
2023 IEEE TAB Committee on Standards (TCoS) seed funding (6,000 \$)	
2024 IEEE ITSS New Initiatives Proposal Funding (5,000 \$)	

➤ **Selected Contest Awards (More than 10 awards are provincial level or above)**

- Honourable Mention in the Interdisciplinary Contest in Modeling
- Second Prize in the 2012 & 2013 Undergraduate Electronic Design Contest in Beijing
- Second Prize in the Physical Experiment Competition in Beijing
- Bronze award in "Challenge Cup" Entrepreneurship Design Contest in Beijing
- First Prize in Beijing Jiaotong University "Challenge Cup" Entrepreneurship Design Contest
- First Prize in Freescale Cup University Students Intelligent Car Race (Rank 2nd)
- 2019 Microsoft Discover AI Challenge: *Sustainable Life* Top (10%)

THESIS SUPERVISION

Yuteng Zhang Master of Science in Transport, Infrastructure & Logistics	Jan.2024- <i>ongoing</i>
Thesis title: Coordinated Planning and Control for Connected and Automated Vehicles' On-ramp Merging in Mixed Traffic Through Value Decomposition-based Multiagent Deep Reinforcement Learning	
Mathijs den Otter Master of Science in Civil Engineering–Transport and Planning	Sep.2022-Dec.2023
Thesis title: Impact of Improved Lane Marking Properties on the Performance of Lane Keeping Assistance Systems in Varying Circumstances	
Lanxin Zhang Master of Science in Civil Engineering–Transport and Planning	Oct.2022-Jun.2023
Thesis title: Semi-supervised Machine Learning for Abnormal Driving Behaviour Detection	
Henan Yuan Bachelor in Traffic and Transportation, BJTU&TUDelft TTE	Oct.2022-Jun.2023
Thesis title: Deep Reinforcement Learning for Driving through Roundabouts	

Shiva Nischal Lingam | Master of Science in Civil Engineering–Transport and Planning Jan.2021–Nov.2021
 Thesis title: [Effects of External Human Machine Interfaces on Automated Vehicles' Communicative Interactions With Human Drivers \(Cum Laude\)](#) | Won 2nd [Cuperusprijs prieze of KIVI](#)

Sandeep Patil | Master of Science in Mechanical Engineering (Vehicular Engineering) Oct.2020–Aug.2021
 Thesis title: [Lane Detection using SpatioTemporal Attention](#)

Eline van der Kooij | Master of Science in Transport, Infrastructure & Logistics Jul.2020–May.2021
 Thesis title: [Visibility of Lane Markings for Machine Vision](#)

Sanny Toonen | Bachelor of Science in Civil Engineering–Transport and Planning Jul.2020–May.2021
 Thesis title: [Lane Recognition for Automated Vehicles](#)

TEACHING ACTIVITIES

Project supervisor, Instructor | EEMCS, TU Delft Nov.2022–Feb.2024
 Courses: [Interdisciplinary Advanced AI Project \(IFEEMCS520200\)](#); [Capstone Applied AI Project \(T13150TU\)](#)
[Fundamentals of Artificial Intelligence Programme \(IFEEMCS520100\)](#)

Teaching Assistant, Instructor | TU Delft and BJTU joint bachelor program Mar.2022 & Mar.2023
 Course: Advanced Lecture "Trends in Transportation" 2022 & 2023

Lecturer | DakeOffer online Platform Mar.2020–Jun.2020 & Nov.2020–Jan.2021
 Course: Introduction to Big Data and Artificial Intelligence: Fundamental and Practice

Teaching Assistant | Transport and Planning, TU Delft Apr.2020–Aug.2020 & Apr.2021–Aug.2021
 Course: [CIE5805 – Intelligent Vehicles for Safe and Efficient Traffic](#)

Teaching Assistant | Department of Automation, Tsinghua University Sep.2016–Jan.2017
 Course: Data Ethics

Teaching and Lab Assistant | Electrical and Electronic Lab Center, Tsinghua University Mar.2016–Jul.2016
 Course: Advanced Labs in Electronic Technology

Teaching and Lab Assistant | Electrical and Electronic Lab Center, Tsinghua University Mar.2015–Jul.2015
 Course: Fundamentals of Electronics Power Technology

RSI Tutor | Center for Excellence in Education, USA Jul.2017–Aug.2017
 Research writing and presentation tutor for the 2017 Research Science Institute Program at Tsinghua University

Undergraduate Counselor (Class 2012) | School of EIE, Beijing Jiaotong University Jul.2012– Jul.2014

TALKS & PRESENTATIONS

Promoting Diversity and Leadership in ITS | IEEE WiE/YP Workshop & Forum, Cairo, Egypt Nov.21.2023
 Presentation topic: Resource Repository: Datasets, Simulation Platforms, and Relevant Publications for Emerging Mixed Traffic of Automated Vehicles and Human-driven Vehicles

Automated Round Transportation | TRB ARTS 2023, San Francisco, USA Jul.12.2023
 Presentation topic: Social-aware Planning and Control for Automated Vehicles Based on Driving Risk Field and Model Predictive Contouring Control: Driving through Roundabouts as a Case Study

AI Applications in Transportation Planning | TRB 2023, Washington D.C., USA Jan.11.2023
 Presentation topics: (1) Robust Lane Detection through Self Pre-training with Masked Sequential Autoencoders and Fine-tuning with Customized PolyLoss
 (2) Sequential Neural Network Model with Spatial-Temporal Attention Mechanism for Robust Lane Detection Using Multi Continuous Image Frames

Research into Urban Rail Transit Operations and Design | TRB 2023, Washington D.C., USA Jan.11.2023
 Presentation topic: Optimization of coordinated flow restriction and skip-stopping schemes for urban rail stations considering platform carrying capacity

Connected and Automated Vehicles | MFTS 2022, Dresden, Germany

Dec.01.2022

Presentation topic: Towards Developing Socially-Compliant Automated Vehicles: State of the Practice, Experts Expectations, and a Conceptual Framework

Automated mobility | IEEE ITSS Young Professionals Fellowship Symposium, Chania, Greece Nov.25.2022

Presentation topic: Multi-goal proactive traffic management for mixed traffic of automated vehicles (AVs) and human-driven vehicles (HDVs) using explainable physics-informed Artificial Intelligence

AI, Security, Privacy and Safety Systems in ITS Applications | ITSC2022, Macow, China Oct.08.2022

Presentation topic: Comparative Study on Supervised vs Semi-supervised ML for Anomaly Detection of CAN Network

Research on AI and Advancing Computing Applications | TRB 2022, Washington D.C., USA Jan.12.2022

Presentation topic: A Hybrid Spatial-temporal Sequence-to-one Neural Network Model for Lane Detection

Challenges of Automated Vehicles and Traffic | University of Győr, Hungary

May.28.2021

Talk topic: Deep learning for automated vehicles' operational design domain: problems, challenges, and case studies

SAMEN User Committee Annual Meeting | Dutch Research Council (NWO), Delft, Netherlands Jan.28.2021

Talk topic: Data-driven research for automated vehicles' operational design domain: a case study on perception

Intelligence, Connectivity, and Mobility | COTA CICTP 2018, Tsinghua University, China Jul.07.2018

Presentation topic: Revealing travel patterns of sharing-bikes in a spatial-temporal manner using the NFM method

World Congress on Intelligent Control and Automation | IEEE WCICA 2016, Guilin, China Jun.12.2016

Presentation topic: Revealing New York Taxi Drivers' Operation Patterns Focusing on the Revenue Aspect

PROFESSIONAL SERVICES & EXPERIENCE

Workshop Organizer (Main) | IEEE Intelligent Vehicles Symposium (IV 2023), Anchorage, USA, Jun.4, 2023

Workshop title: [Development of socially-compliant driving behaviour for automated vehicles to enhance safety and efficiency in mixed traffic](#)

Workshop Organizer (Vice) | IEEE International Conference on Intelligent Transportation Systems (ITSC), Bilbao, Bizkaia, Spain, Sep. 24, 2023

Workshop title: [Data-driven and Empirical Research for Emerging Mixed Traffic of Automated Vehicles and Human-driven Vehicles](#)

IEEE TCoS Seeding Project Leader (PI) | 2023 IEEE TAB Committee on Standards (TCoS) seed funding

Project title: Enhancing the deployment of socially-compliant automated vehicles in mixed traffic ([website](#))

Ad-hoc Reviewer Services

Journals

- International Journal of Computer Vision (**IF: 19.5**; Top AI journal)
- IEEE Transactions on Intelligent Transportation Systems
- IEEE Open Journal of Intelligent Transportation Systems
- Transportation Letters: the International Journal of Transportation Research
- Journal of Intelligent Transportation Systems: Technology, Planning, and Operations
- Journal of Transportation Research Record: Journal of the Transportation Research Board
- International Journal of Human-Computer Interaction
- Journal of Advanced Transportation
- Applied Ergonomics
- Journal of Internet Technology
- European Transport Research Review
- ASCE-ASME Journal of Risk and Uncertainty in Engineering Systems, Part A: Civil Engineering

Conferences and Proceedings

- IEEE Intelligent Vehicles Symposium (IV) | Associate editor
- IEEE Intelligent Transportation Systems Conference (ITSC)
- Transportation Research Board (TRB) Annual Meeting
- World Congress on Intelligent Control and Automation (WCICA)
- COTA International Conference of Transportation Professionals (CICTP)
- The International Symposium on Transport Network Resilience (INSTR)

Research Assistant | Transport Big Data Analytics | **ITS Lab, TNList@Tsinghua University** Aug.2017- May.2018

- Cross-domain data fusion for full-time trip chain reconstruction and anomaly detection;
- City Computing: Applying NMF methods to evaluate indicators describing urban function, land use, mobility, etc.
- Revealing collective travel patterns of *Shared Mobility* in a spatial-temporal manner

Carryout service data analysis Project Manager | Beijing Gooagoo Technical Service Co., Ltd. Jul.2016-Aug.2016

- Integral process of Big Data Analytics: Crawled carryout service data using Python crawler; executed data storage, data analysis, and data processing in a relational database (MySQL); visualization, clustering, and web application

System architect for control of shuttle machine | Beijing IBOSST for Logistics Co., Ltd. May.2016-Aug.2017

Data Analyst | Beijing Municipal Commission of Transport: TOCC Jun.2016- Jul.2016

Data Analysis Engineer | DiDi Chuxing Company May.2016-Jun.2016

- Determined the approximate trajectory of ride-sharing by transfer learning from private car trajectories
- Calculated the daily total vehicle emissions reductions by using the PHEM model

Commentator | China International Congress on Intelligent & Connected Vehicles (CICV) Oct.2015-Oct.2015

- Introduced the i-VICS systems to audiences; received executives from automobile manufacturers BMW, Volvo, VW

Test Engineer Assistant | China Unicom southern district IPv6 renovation project, MIIT CTTL Nov.2013-Dec.2013

- Tested all kinds of typical applications on the Internet under the IPv6 environment

Research Intern | Broadband Network & Digital Media: Qionghai Dai's Lab, Tsinghua University Jul.2013-Aug.2013

- Review of technical investigation for controlling waves in space and time for imaging and focusing in complex media

LEADERSHIP & VOLUNTEER EXPERIENCE

Webmaster | **Traffic and Transportation Safety (TTS) Lab Website, TU Delft** Mar.2020- Present

- Responsible and volunteering for the [TTS Lab website](#) development and maintenance

Project Leader | **Asian Youth Center:** Leadership Development Training Program for Masters Jul.2015-Aug.2016

- Responsible for activities and competitions between overseas and Chinese students in the Asian Youth Center project
- **Volunteer Leader** in the 5th Joint School Symposium for the Asian Youth Center Project

iTalk Group Leader | International Department, Tsinghua University Postgraduate Association Oct.2014-Oct.2015

- Committed to speech in English given by students or alumni stars, held a special performance for overseas students

Volunteer | National Doctor Forum on Traffic and Transportation Engineering, Beijing Jiaotong University Jun.2011

SKILLS & MISCELLANEOUS

- Programming: Python (Tensorflow, PyTorch, Keras), Matlab, R, C/C++, Java, VHDL | Database: MySQL
- [Deep Learning](#)
- [Deep Reinforcement Learning](#)
- Hardware circuit design: Altium Designer
- Software development on Linux and Windows
- Big data analytics and visualization methods | Cross-domain Data Fusion | Data-driven anomaly/fraud detection
- Languages: Chinese (Native); English (Professional); **Dutch** (Elementary)
- Hobbies: **Tai Chi, Meditation, Kung Fu**, Chess, Yoga, Reading, Mountain climbing