

a). 같은  $y_{i,j}$  에 대한 variability는 비/차는 것인데

첫번째 것에는  $\theta_1, \theta^2$  을 condition 하여  $\mu, \tau^2$  와  $\tau$  이 주어짐 (조건이다)

condition 은 것이라  $\text{Var}[y_{i,j} | \theta_1, \theta^2]$  이  $\tau$  이 주는 것이다.

b)  $\circ \text{Cov}[y_{i,j}, y_{i,j} | \theta_1, \theta^2]$

$y_{i,j} \sim y_{i,j} | \theta_1, \theta^2 \sim \mathcal{N}(\theta_1, \theta^2)$  이다. zero 일 것.

$\circ \text{Cov}[y_{i,j}, y_{i,j} | \mu, \tau^2]$

$\theta_1$  가 unknown 이지만,  $y_{i,j}$  는 알게 되면  $\theta_1$  에 대한 belief는 update 되어

따라서,  $y_{i,j}$  는 알 수 있게 되면 positive 일 것.

c)  $\circ V[y_{i,j} | \theta_1, \theta^2] = \theta^2$

$\circ V[\bar{y}_{i,j} | \theta_1, \theta^2] = \theta^2 / n_{i,j}$

$$\begin{aligned} \circ V[y_{i,j} | \mu, \tau^2] &= V[E[y_{i,j} | \theta_1, \theta^2] | \mu, \tau^2] + E[V[y_{i,j} | \theta_1, \theta^2] | \mu, \tau^2] \\ &= V[\theta_1 | \mu, \tau^2] + E[\theta^2 | \mu, \tau^2] \\ &= \tau^2 + \theta^2 \end{aligned}$$

$$\begin{aligned} \circ V[\bar{y}_{i,j} | \mu, \tau^2] &= V[E[\bar{y}_{i,j} | \theta_1, \theta^2] | \mu, \tau^2] + E[V[\bar{y}_{i,j} | \theta_1, \theta^2] | \mu, \tau^2] \\ &= V[\theta_1 | \mu, \tau^2] + E[\theta^2 / n_{i,j} | \mu, \tau^2] \\ &= \tau^2 + \theta^2 / n_{i,j} \end{aligned}$$

$$\circ \text{Cov}[y_{i,j}, y_{i,j} | \theta_1, \theta^2] = E[y_{i,j} \times y_{i,j} | \theta_1, \theta^2] - E[y_{i,j} | \theta_1, \theta^2] \times E[y_{i,j} | \theta_1, \theta^2] = 0$$

$$\begin{aligned} \circ \text{Cov}[y_{i,j}, y_{i,j} | \mu, \tau^2] &= \text{Cov}[E[y_{i,j}, y_{i,j} | \theta_1, \theta^2] | \mu, \tau^2] \\ &= E[\text{Cov}[y_{i,j}, y_{i,j} | \theta_1, \theta^2] | \mu, \tau^2] \\ &\quad + \text{Cov}[E[y_{i,j} | \theta_1, \theta^2], E[y_{i,j} | \theta_1, \theta^2]] \\ &= 0 + \text{Cov}[\theta_1, \theta_1] = \tau^2 \end{aligned}$$

$$p(\mu | \theta, \sigma^2, \tau^2, Y) = p(\mu, \theta, \sigma^2, \tau^2, Y) / \int p(\mu, Y, \theta, \sigma^2, \tau^2) d\mu.$$

$$= \frac{p(Y | \theta, \sigma^2, \tau^2, \mu) \times p(\theta | \sigma^2, \tau^2, \mu) \times p(\sigma^2, \tau^2, \mu)}{\int p(Y | \theta, \sigma^2, \tau^2, \mu) \times p(\theta | \sigma^2, \tau^2, \mu) \times p(\sigma^2, \tau^2, \mu) d\mu}$$

$$= \frac{p(Y | \theta, \sigma^2) \times p(\theta | \mu, \tau^2) \times p(\sigma^2) \times p(\tau^2) \times p(\mu)}{\int p(Y | \theta, \sigma^2) \times p(\theta | \mu, \tau^2) \times p(\sigma^2) \times p(\tau^2) \times p(\mu) d\mu}$$

$$= \frac{p(\mu) \cdot p(\theta | \mu, \tau^2)}{\int p(\mu) \cdot p(\theta | \mu, \tau^2) d\mu}.$$

$$= \frac{\cancel{p(\mu)} \cdot \cancel{p(\theta)} p(\mu | \theta, \tau^2)}{\int \cancel{p(\mu)} \cdot \cancel{p(\theta)} p(\mu | \theta, \tau^2) d\mu} = p(\mu | \theta, \tau^2).$$

∴  $\mu$ 는  $\sigma^2, Y$ 와 독립. ( $\theta$ 가 알려져 있다면).