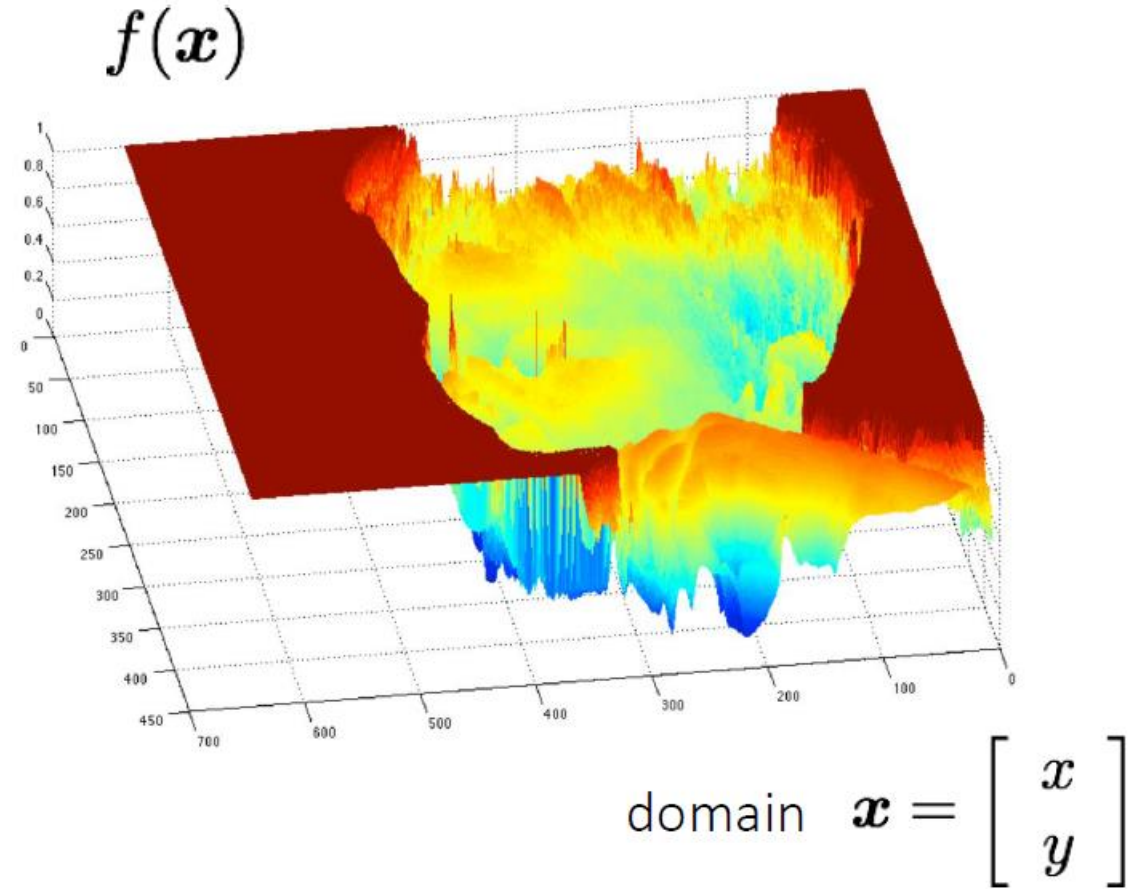


# Convolution as Smoothing



Sang-wook Lee(Yonsei)

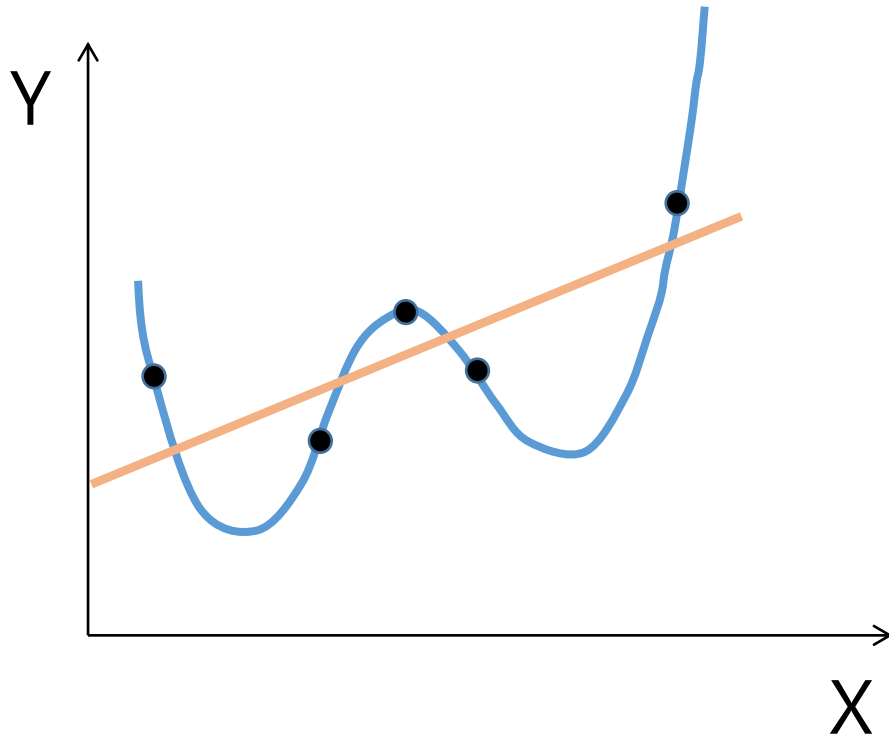
# Convolution as Smoothing

What is convolution? Averaging

What is averaging? Smoothing

# Smoothness

Smooth : Small  $f''$  or less wiggly



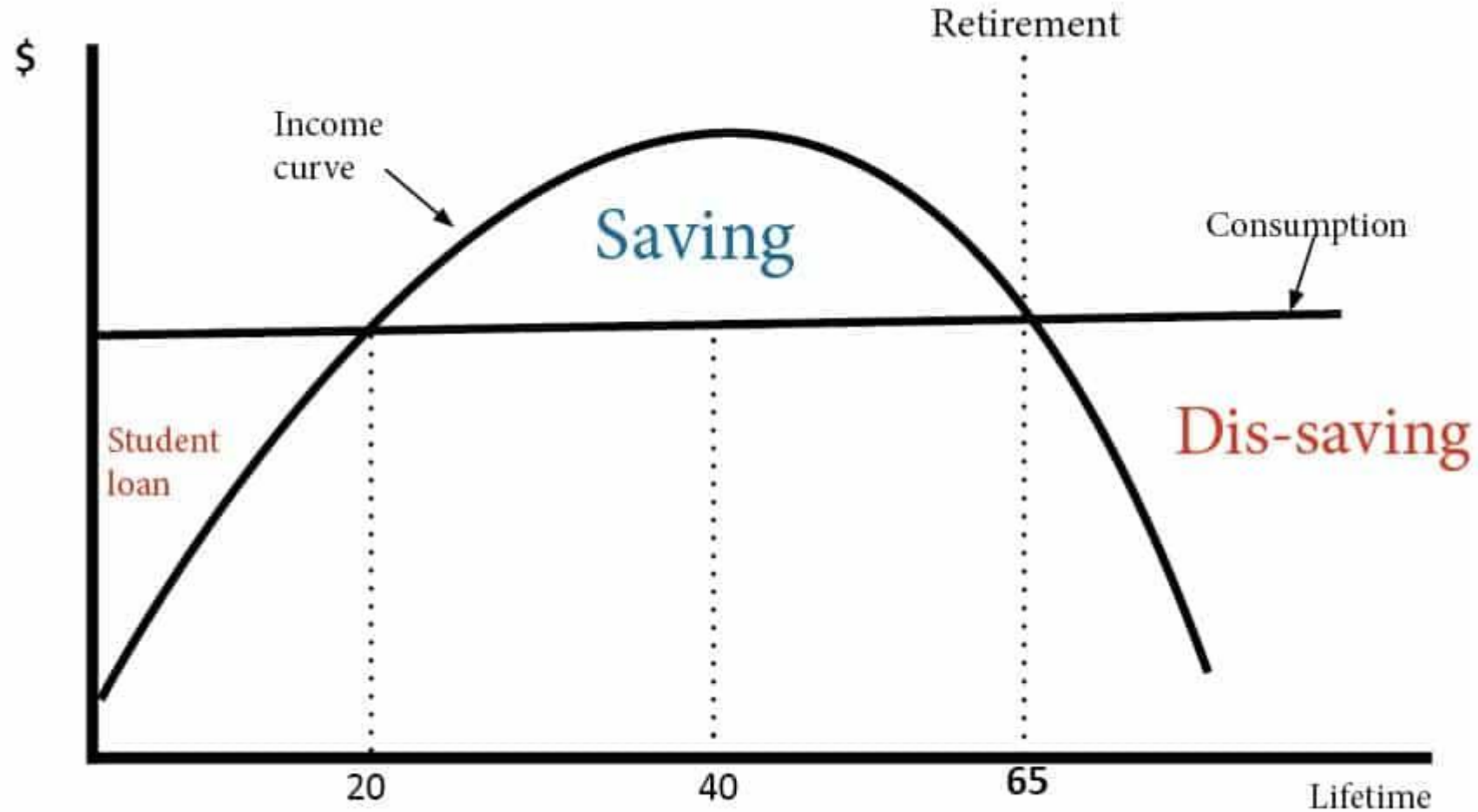
Small  $f''$  and less wiggly

Big  $f''$  and more wiggly

# Averaging is smoothing?

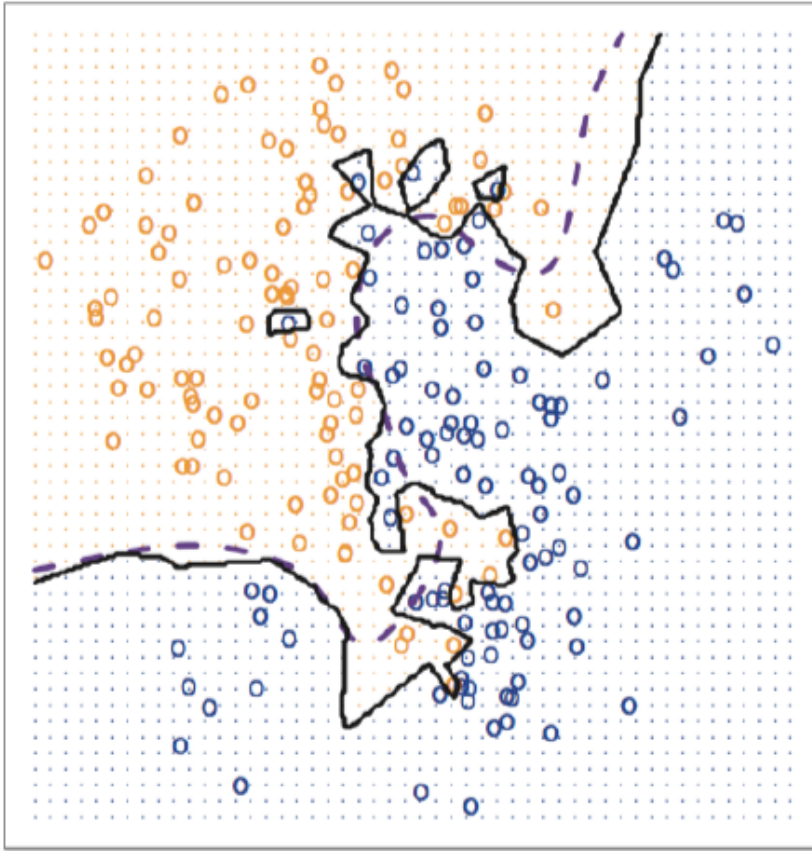
1. Consumption smoothing in Economics
2. KNN
3. CLT

# Consumption smoothing

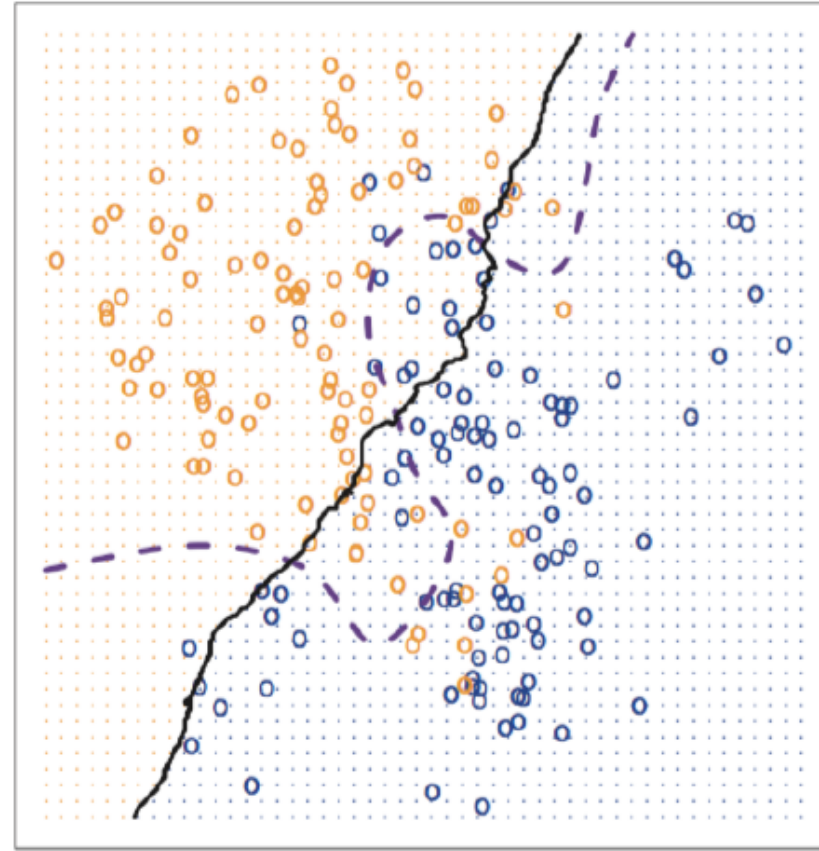


# KNN

KNN: K=1



KNN: K=100



# CLT

No matter how ugly the distribution is...

# Philosophy of Averaging

Local info vs. global info



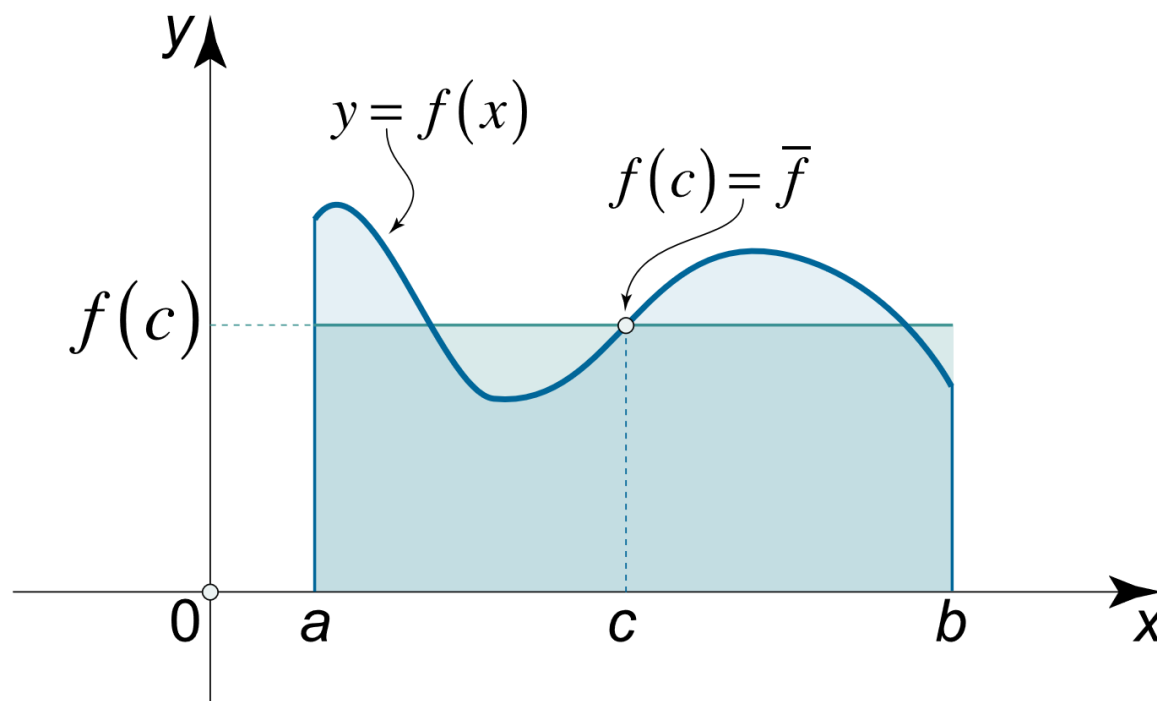
# Convex combination(weighted average)

$$\bar{X} = \sum_{i=1}^n \frac{1}{n} X_i \text{ s.t. } \sum_{i=1}^n \frac{1}{n} = 1$$

$$X^* = \sum_{i=1}^n w_i X_i \text{ s.t. } \sum_{i=1}^n w_i = 1, w_i \geq 0$$

# Integral as averaging

$$\bar{f} = \sum_{i=1}^n \frac{1}{n} f(x_i) \rightarrow \int_0^1 f(x) dx$$

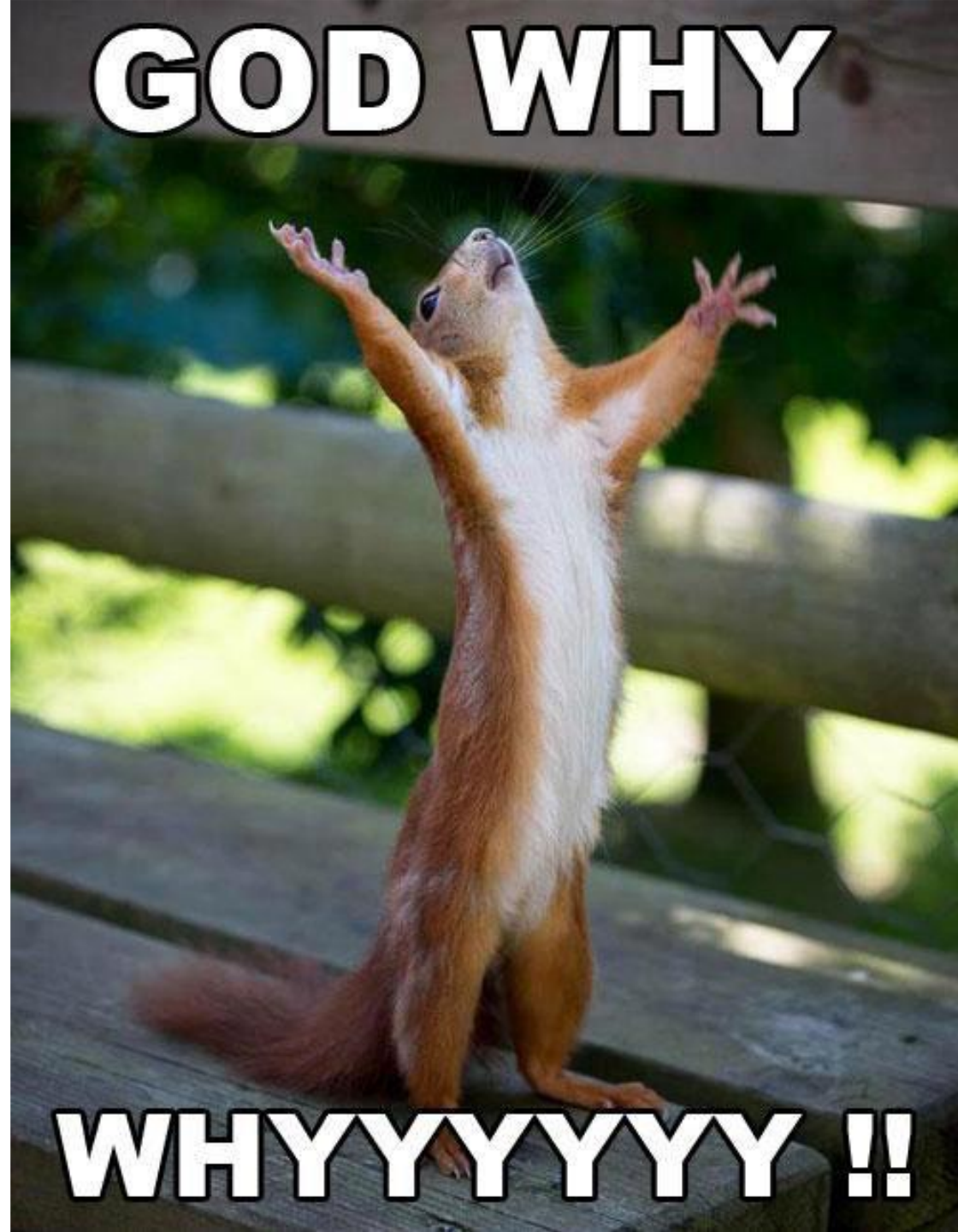


# Convolution as averaging

$$\sum_{i=1}^n \frac{1}{n} f(x_i) \rightarrow \int_0^1 f(t) dt = \int_0^1 1 \cdot f(t) dt$$

$$\sum_{i=1}^n w_i f(x_i) \rightarrow \int_0^1 g(x-t) \cdot f(t) dt = f * g(x)$$

**GOD WHY**



**WHYYYYYYY !!**

# Why need to use convolution?

1. Nice algebraic properties
2. Kernel smoothing
3. Image processing
4. Fourier transform

# Nice algebraic properties

## Commutativity

$$f * g = g * f$$

Proof: By definition

$$(f * g)(t) = \int_{-\infty}^{\infty} f(\tau)g(t - \tau) d\tau$$

Changing the variable of integration to  $u = t - \tau$  the result follows.

## Associativity

$$f * (g * h) = (f * g) * h$$

Proof: This follows from using [Fubini's theorem](#) (i.e., double integrals can be evaluated as i

## Distributivity

$$f * (g + h) = (f * g) + (f * h)$$

Proof: This follows from linearity of the integral.

## Associativity with scalar multiplication

$$a(f * g) = (af) * g$$

for any real (or complex) number  $a$ .

## Multiplicative identity

No algebra of functions possesses an identity for the convolution. The lack of identity is typically convolved with a [delta distribution](#) or, at the very least (as is the case of  $L^1$ ) admit [approximate](#) convolution. Specifically,

$$f * \delta = f$$

where  $\delta$  is the delta distribution.

## Inverse element

Some distributions have an [inverse element](#) for the convolution,  $S^{(-1)}$ , which is defined by

$$S^{(-1)} * S = \delta.$$

The set of invertible distributions forms an [abelian group](#) under the convolution.

## Complex conjugation

$$\overline{f * g} = \overline{f} * \overline{g}$$



...그만 알아보자

# Kernel Smoothing

## Idea

Suppose we use a bandwidth  $g(\neq h)$  and the kernel  $L$  to estimate  $\theta_2$ .

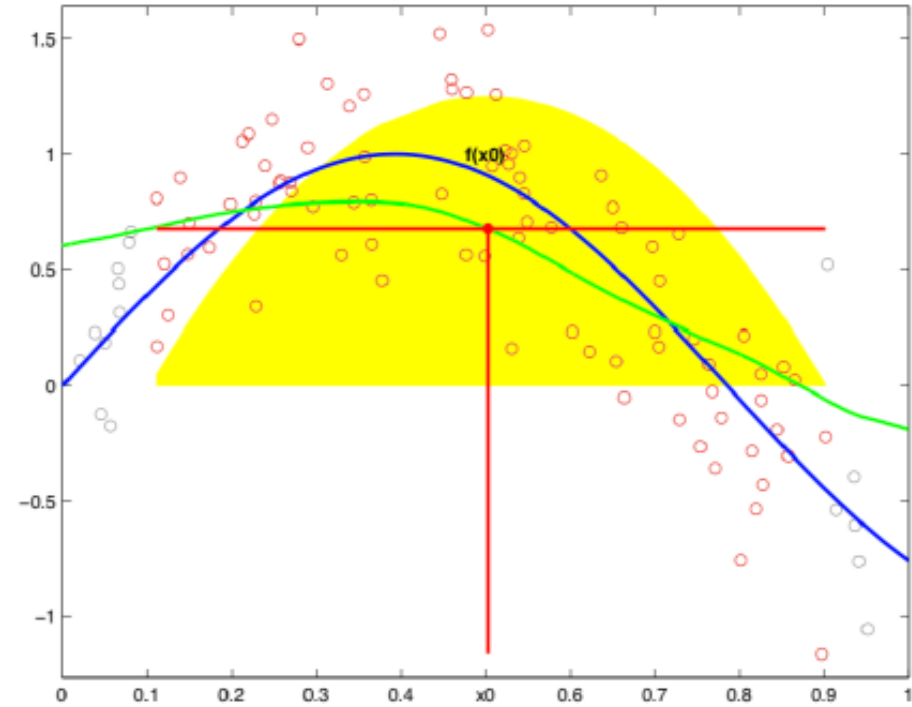
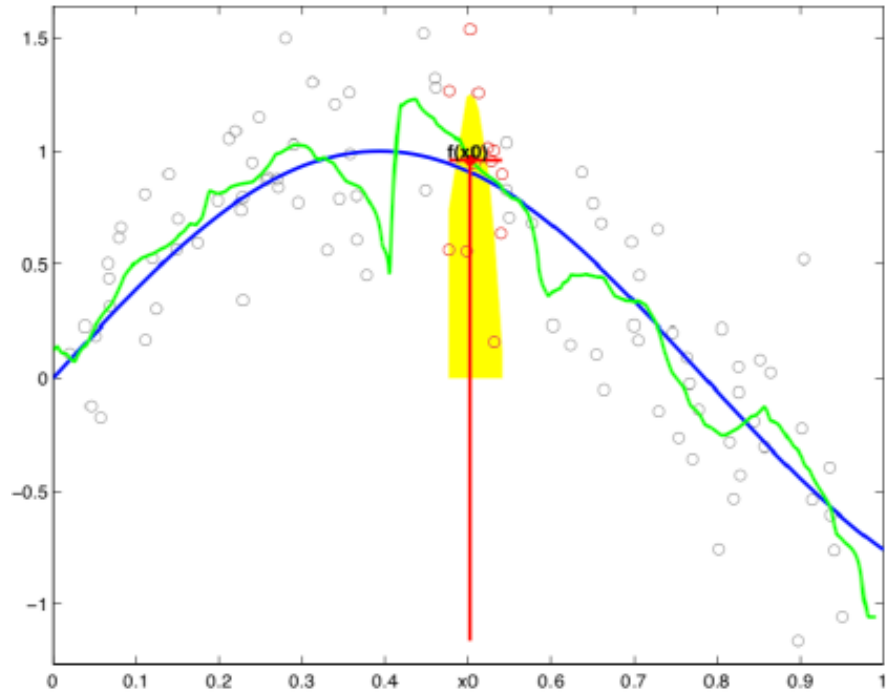
Then,

$$\text{Bias}(\tilde{\theta}_{2,0}(g)) = -\frac{1}{2} \mu_2(L * L) \theta_3 g^2 + o(n^{-1}g^{-5} + g^2)$$

$$\text{var}(\tilde{\theta}_{2,0}(g)) = 2n^{-2}g^{-9} \int (L'' * L'')^2 \theta_0 + O(n^{-1}) + o(n^{-2}g^{-9})$$

$$\begin{aligned} g_{\text{opt}} &= \underset{g>0}{\text{argmin}} \text{MSE}(\tilde{\theta}_{2,0}(g)) \\ &= \left[ \frac{18 \int (L'' * L'')^2}{\mu_2(L * L)^2} \right]^{1/13} \left( \frac{\theta_0}{\theta_3^2} \right)^{1/13} n^{-2/13} \end{aligned}$$

# Kernel Smoothing

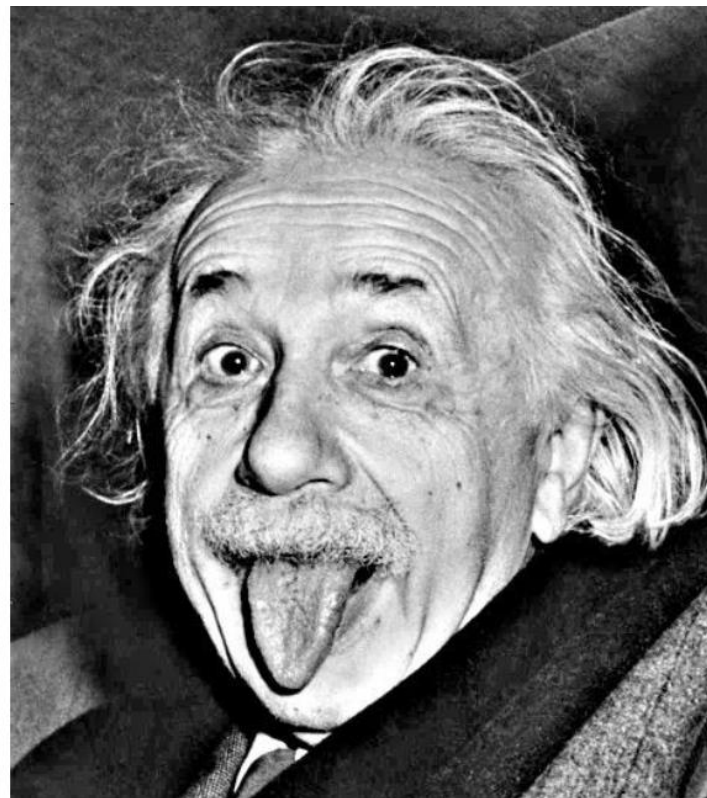
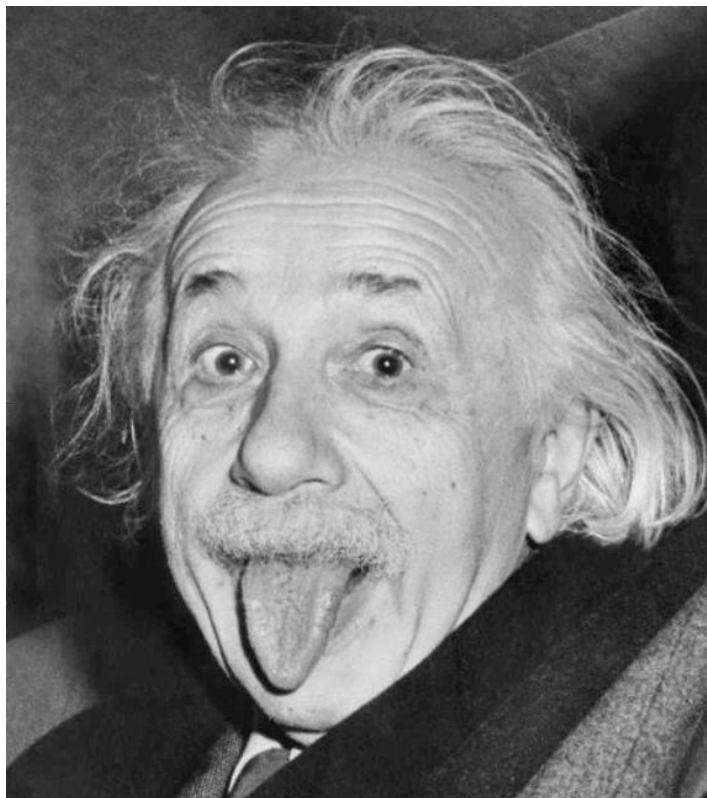




# Image processing

$$(f * g)(x) = \int_{-\infty}^{\infty} f(y)g(x - y)dy$$

filtered signal  $\nearrow$   $\nwarrow$  filter  $\nwarrow$  input signal



# Fourier Transform

$$\mathcal{F}\{g * h\} = \mathcal{F}\{g\}\mathcal{F}\{h\}$$

# What is Fourier transform?

$$\mathcal{L}(f) = \int_{-\infty}^{+\infty} e^{-xt} f(x) dx = F_1(t)$$

$$\mathcal{F}(f) = \int_{-\infty}^{+\infty} e^{-ixt} f(x) dx = F_2(t)$$

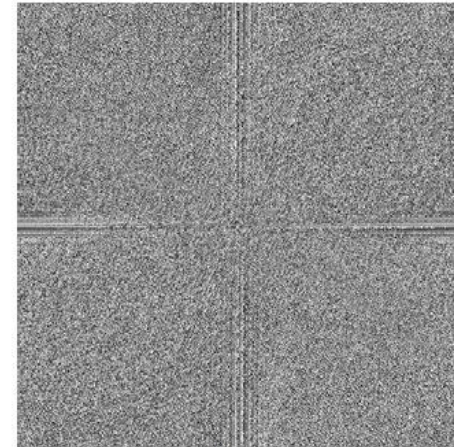
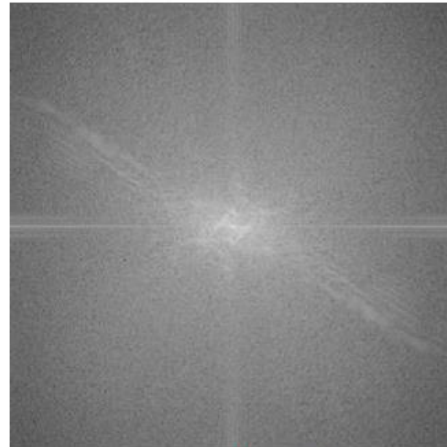
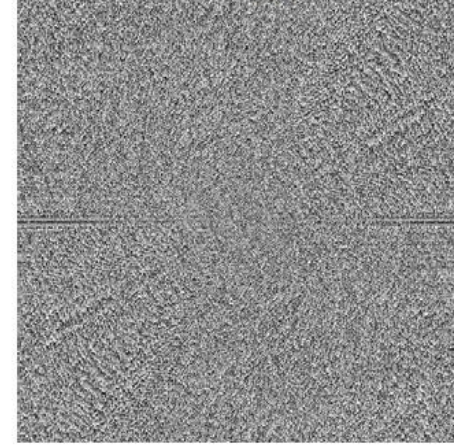
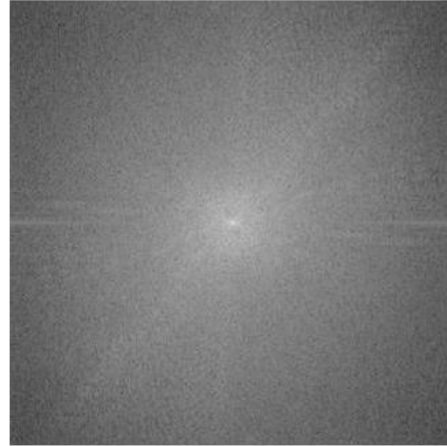
$$f(x) \rightarrow F(t)$$

# Why need to know Fourier transform?

1. Solving differential equation
2. Image process
3. Fourier series
4. MGF, characteristic function

# Image process

## Fourier transforms of natural images



original

amplitude

phase



# Example

Seolgwangeun.jpg

750x750 jpeg image

Thus the SVD of the image has 750 summands



rank 3



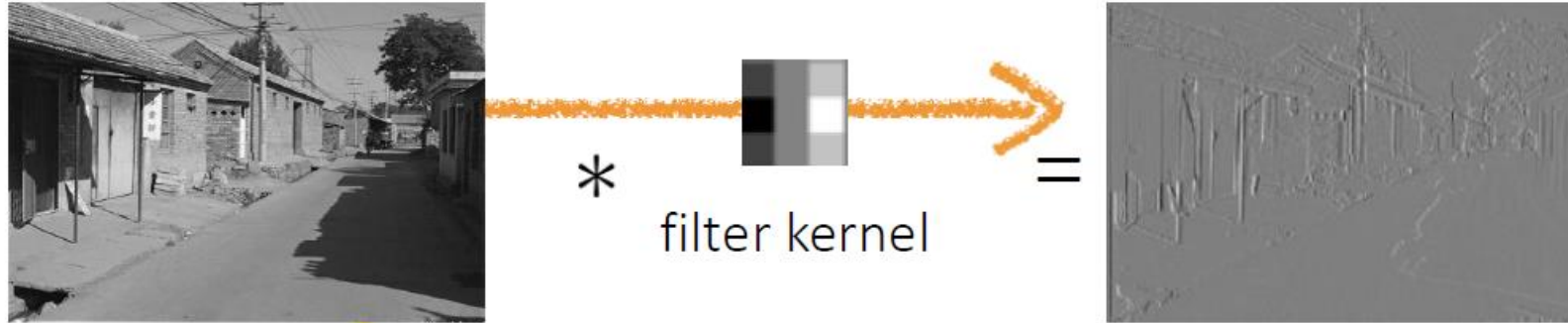
rank 45



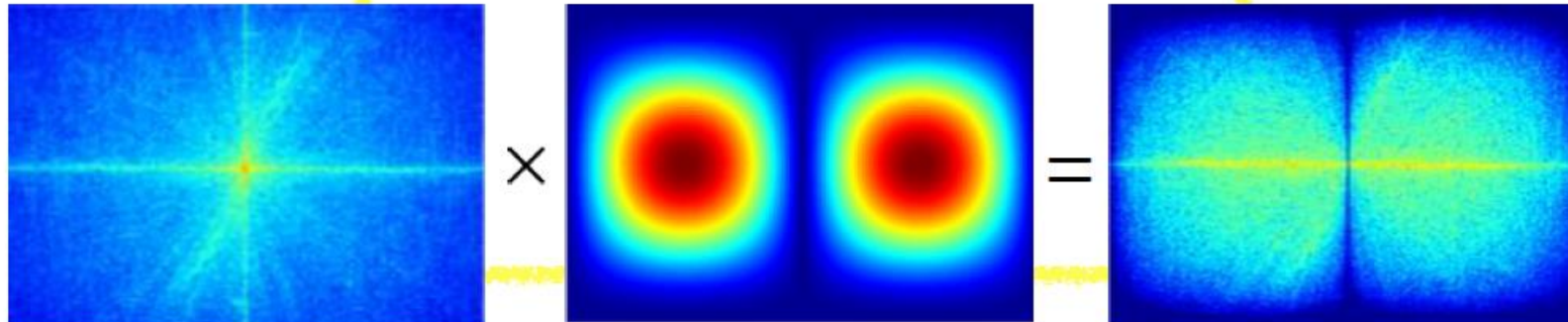
rank 297

# Image process

## Spatial domain filtering



Fourier transform



inverse Fourier transform

## Frequency domain filtering

# Taylor series vs. Fourier series

Taylor series:  $f(x) = \sum_{n=0}^{\infty} c_n x^n$

Fourier series:  $f(x) = \sum_{n=-\infty}^{\infty} c_n e^{inx}$

where  $c_n = \int_{-\infty}^{+\infty} e^{-int} f(t) dt$



???



# MGF, CF

$$M_X(t) = E(e^{Xt}) = \int_{-\infty}^{+\infty} e^{-xt} f(x) dx = \mathcal{L}(f)$$

$$\phi_X(t) = E(e^{iXt}) = \int_{-\infty}^{+\infty} e^{-ixt} f(x) dx = \mathcal{F}(f)$$

# Summary

What is convolution? Averaging

What is averaging? Smoothing

What is Fourier? Awesome thing

# Reference

- [1] Yongho Jeon(Yonsei), (2019) “*Nonparametric Function Estimation*” lecture note
- [2] Sunjoo Kim(Yonsei), (2019), “*Computer Vision*” lecture note
- [3] Bumsup Ham, (2018), “*Introductory Artificial Intelligence*” lecture note
- [4] Kwangeun Seol, (2018), “*Seoulkwangeun.jpg*” 존잘 사진

# 질문 받아요



감사합니다

