

# Multivariate Normal model

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# I. Outline

# Outline

- Up until now all of our models have been univariate. However, we are now going to deal with multivariate models.
- This allows us to jointly estimate population means, variances and correlations of a collection of variables.
- We will focus on calculating posterior distributions under semiconjugate prior distributions which works well with Gibbs sampler.

## II. Multivariate normal density

# Bivariate normal

- $\mathbf{Y}_i = \begin{pmatrix} Y_{i,1} \\ Y_{i,2} \end{pmatrix} = \begin{pmatrix} \text{score on first test} \\ \text{score on second test} \end{pmatrix}$
- Things we might be interested in include the population mean  $\theta$ ,

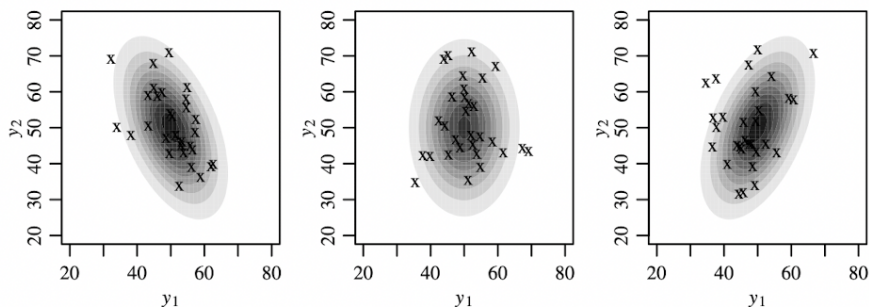
$$E[\mathbf{Y}_i] = \begin{pmatrix} E[Y_{i,1}] \\ E[Y_{i,2}] \end{pmatrix} = \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix}$$

- and population covariance matrix  $\Sigma$

$$\Sigma = Cov[\mathbf{Y}] = \begin{pmatrix} \sigma_1^2 & \sigma_{1,2} \\ \sigma_{1,2} & \sigma_2^2 \end{pmatrix}$$

# Bivariate normal

Figure below gives contour plots each one  $\boldsymbol{\theta} = (50, 50)^T$ ,  $\sigma_1^2 = 64$ ,  $\sigma_2^2 = 144$ , but value of  $\sigma_{1,2}$  varying from -48, 0, 48 from left to right. This implies that each has correlations of -.5, 0, +.5 respectively.



**Fig. 7.1.** Multivariate normal samples and densities.

Interesting part is that the marginal distribution of each  $\mathbf{Y}_j$  is a univariate normal w/ mean  $\theta_j$  and variance  $\sigma_j^2$

# Multivariate normal model

- p-dimensional data vector  $\mathbf{Y}$

$$p(\mathbf{y} \mid \boldsymbol{\mu}, \Sigma) = (2\pi)^{-p/2} |\Sigma|^{-1/2} \exp \left\{ -(\mathbf{y} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{y} - \boldsymbol{\mu}) / 2 \right\}$$

where

$$\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_p \end{pmatrix} \quad \boldsymbol{\mu} = \begin{pmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_p \end{pmatrix} \quad \Sigma = \begin{pmatrix} \sigma_1^2 & \sigma_{1,2} & \cdots & \sigma_{1,p} \\ \sigma_{1,2} & \sigma_2^2 & \cdots & \sigma_{2,p} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{1,p} & \cdots & \cdots & \sigma_p^2 \end{pmatrix}$$



# Some knowledge about matrix

**matrix algebra** For a matrix  $\mathbf{A}$

- $|\mathbf{A}|$  called determinant, measures how "big"  $\mathbf{A}$  is
- inverse of  $\mathbf{A}$  is the matrix  $\mathbf{A}^{-1}$  s.t.  $\mathbf{A}\mathbf{A}^{-1}$  is  $\mathbf{I}_p$
- $\mathbf{b}^T \mathbf{A}$  is  $1 \times p$  vector  $(\sum_{j=1}^p b_j a_{j,1}, \dots, \sum_{j=1}^p b_j a_{j,p})$
- $\mathbf{b}^T \mathbf{A} \mathbf{b}$  is a single number  $\sum_{j=1}^p \sum_{k=1}^p b_j b_k a_{j,k}$ .

### III. Semiconjugate prior distribution for mean $\mu$

# Semiconjugate prior for $\mu$ (known $\Sigma$ )

As in the previous chapters of univariate normal models, we put multivariate normal model for prior  $\mu$

- prior  $\mu \sim MVN(\mu_0, \Lambda_0)$

$$\begin{aligned}
 p(\mu) &= (2\pi)^{-p/2} |\Lambda_0|^{-1/2} \exp \left\{ -\frac{1}{2} (\mu - \mu_0)^T \Lambda_0^{-1} (\mu - \mu_0) \right\} \\
 &= (2\pi)^{-p/2} |\Lambda_0|^{-1/2} \exp \left\{ -\frac{1}{2} \mu^T \Lambda_0^{-1} \mu + \mu^T \Lambda_0^{-1} \mu_0 - \frac{1}{2} \mu_0^T \Lambda_0^{-1} \mu_0 \right\} \\
 &\propto \exp \left\{ -\frac{1}{2} \mu^T \Lambda_0^{-1} \mu + \mu^T \Lambda_0^{-1} \mu_0 \right\} \\
 &= \exp \left\{ -\frac{1}{2} \mu^T \mathbf{A}_0 \mu + \mu^T \mathbf{b}_0 \right\}
 \end{aligned}$$

where  $\mathbf{A}_0 = \Lambda_0^{-1}$  and  $\mathbf{b}_0 = \Lambda_0^{-1} \mu_0$

# Likelihood for multivariate normal

- Our sampling model is  $\mathbf{Y}_1, \dots, \mathbf{Y}_n | \mu, \Sigma \stackrel{\text{i.i.d.}}{\sim} \text{MVN}(\mu, \Sigma)$

$$\begin{aligned}
 p(\mathbf{y}_1, \dots, \mathbf{y}_n | \mu, \Sigma) &= \prod_{i=1}^n (2\pi)^{-p/2} |\Sigma|^{-1/2} \exp \left\{ -(\mathbf{y}_i - \mu)^T \Sigma^{-1} (\mathbf{y}_i - \mu) / 2 \right\} \\
 &= (2\pi)^{-np/2} |\Sigma|^{-n/2} \exp \left\{ -\frac{1}{2} \sum_{i=1}^n (\mathbf{y}_i - \mu)^T \Sigma^{-1} (\mathbf{y}_i - \mu) \right\} \\
 &\propto \exp \left\{ -\frac{1}{2} \mu^T \mathbf{A}_1 \mu + \mu^T \mathbf{b}_1 \right\}
 \end{aligned}$$

where  $\mathbf{A}_1 = n\Sigma^{-1}$  and  $\mathbf{b}_1 = n\Sigma^{-1}\bar{\mathbf{y}}$

$$\bar{\mathbf{y}} = \left( \frac{1}{n} \sum_{i=1}^n y_{i,1}, \dots, \frac{1}{n} \sum_{i=1}^n y_{i,p} \right)$$

# Posterior for multivariate model

- By combining the two functions of prior and likelihood, we obtain the following posterior

$$\begin{aligned} p(\mu \mid \mathbf{y}_1, \dots, \mathbf{y}_n, \Sigma) &\propto \exp \left\{ -\frac{1}{2} \mu^T \mathbf{A}_0 \mu + \mu^T \mathbf{b}_0 \right\} \times \exp \left\{ -\frac{1}{2} \mu^T \mathbf{A}_1 \mu + \mu^T \mathbf{b}_1 \right\} \\ &= \exp \left\{ -\frac{1}{2} \mu^T \mathbf{A}_n \mu + \mu^T \mathbf{b}_n \right\}, \text{ where} \\ \mathbf{A}_n &= \mathbf{A}_0 + \mathbf{A}_1 = \Lambda_0^{-1} + n\Sigma^{-1} \text{ and} \\ \mathbf{b}_n &= \mathbf{b}_0 + \mathbf{b}_1 = \Lambda_0^{-1} \mu_0 + n\Sigma^{-1} \bar{\mathbf{y}} \end{aligned}$$

- This implies that the conditional distribution of  $\mu$  therefore must be multivariate normal distribution with covariance  $\mathbf{A}_n^{-1}$  and mean  $\mathbf{A}_n^{-1} \mathbf{b}_n$

# Posterior inference

- As we summarize the result from the previous slide,

$$\text{Cov}[\mu \mid \mathbf{y}_1, \dots, \mathbf{y}_n, \Sigma] = \Lambda_n = (\Lambda_0^{-1} + n\Sigma^{-1})^{-1}$$

$$\text{E}[\mu \mid \mathbf{y}_1, \dots, \mathbf{y}_n, \Sigma] = \mu_n = (\Lambda_0^{-1} + n\Sigma^{-1})^{-1} (\Lambda_0^{-1}\mu_0 + n\Sigma^{-1}\bar{\mathbf{y}})$$

$$p(\mu \mid \mathbf{y}_1, \dots, \mathbf{y}_n, \Sigma) = \text{MVN}(\mu_n, \Lambda_n)$$

- Looks a bit complicated, but these are interpretable by the same analogy we learned before.
  - 1) Posterior precision(inverse variance) is the sum of prior precision and the data precision
  - 2) Posterior expectation is a weighted average of the prior expectation and the sample mean

## IV. Inverse-Wishart distribution

# The design of variance-covariance matrix

- Just as variance  $\sigma^2$  must be positive, variance-covariance matrix  $\Sigma$  must be positive definite.

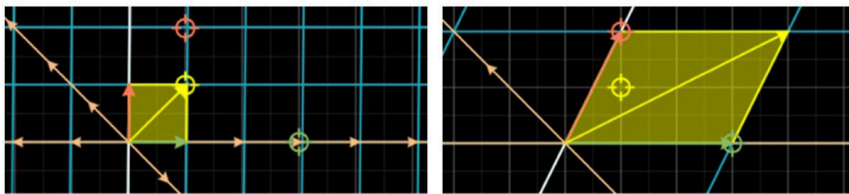
$$\mathbf{x}'\Sigma\mathbf{x} > 0 \text{ for all vectors } \mathbf{x}.$$

- Positive definiteness guarantees that all  $\sigma_j^2 > 0$  for all  $j$  and correlations are between -1 and 1
- Also, covariance matrix should be symmetric so that  $\sigma_{j,k} = \sigma_{k,j}$
- Thus, any valid prior distribution should be set of **symmetric, positive definite matrices**. How?



# Why positive definite?

- covariance matrix  $\Sigma$ 의 positive definite 조건은 그냥  $\sigma^2$ 가 양수여야 한다는 조건의 multivariate 버전인 것!
- Positive definite는 symmetric matrix의 특수한 형태이며, "모든 eigenvalue들이 0보다 크다"와 동치인 조건  $\rightarrow$  eigenvalue들이 0보다 크다는 것이 왜 중요할까?



[Interactive Matrix Visualization \(shad.io\)](https://shad.io/Interactive-Matrix-Visualization)

$$A = VDV^{-1}$$

$$A(p \times p) = \begin{bmatrix} a_1 & \cdots & a_p \end{bmatrix} = \begin{bmatrix} v_1 & \cdots & v_p \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_p \end{bmatrix} \begin{bmatrix} v_1 & \cdots & v_p \end{bmatrix}^{-1}$$

A라는 행렬에 대응하는 선형연산  $T$ 는,

- 좌표평면을  $v_1, \dots, v_p$ 를 축으로 하여  $\lambda_1, \dots, \lambda_p$ 만큼 늘려/줄여주는데,
- 표준기저  $S$ 의 관점에서 보면  $e_i$  기저벡터가  $a_i$ 로 가는 것으로 볼 수 있고,
- 고유벡터의 기저  $V$ 에서 보면, 그냥 기저벡터에  $\lambda_i$ 만큼 곱해주는 것이다.

# Empirical covariance matrices

- Sum of squares matrix of a collection of multivariate vectors  $z_1, \dots, z_n$  given by

$$\sum_{i=1}^n z_i z_i^T = \mathbf{Z}^T \mathbf{Z}$$

- $\mathbf{Z}$  is  $n \times p$  matrix where  $i$ th row is  $z_i^T$ ,  $z_i z_i^T$  is the following  $p \times p$  matrix

$$z_i z_i^T = \begin{pmatrix} z_{i,1}^2 & z_{i,1}z_{i,2} & \cdots & z_{i,1}z_{i,p} \\ z_{i,2}z_{i,1} & z_{i,2}^2 & \cdots & z_{i,2}z_{i,p} \\ \vdots & \vdots & \ddots & \vdots \\ z_{i,p}z_{i,1} & z_{i,p}z_{i,2} & \cdots & z_{i,p}^2 \end{pmatrix}$$

- If  $z_i$ s are samples from a population with zero mean,  $\mathbf{Z}^T \mathbf{Z} / n$  can be thought as sample covariance matrix

$$\begin{aligned} \frac{1}{n} [\mathbf{Z}^T \mathbf{Z}]_{j,j} &= \frac{1}{n} \sum_{i=1}^n z_{i,j}^2 = s_{j,j} = s_j^2 \\ \frac{1}{n} [\mathbf{Z}^T \mathbf{Z}]_{j,k} &= \frac{1}{n} \sum_{i=1}^n z_{i,j} z_{i,k} = s_{j,k} \end{aligned}$$

# Empirical covariance matrices

- If  $n > p$  and  $\mathbf{z}_i$ s are linearly independent, then  $\mathbf{Z}^T \mathbf{Z}$  will be positive definite and symmetric.
- Now suggest a given integer  $\nu_0$  and a  $p * p$  covariance matrix  $\Phi_0$ 
  1. sample  $\mathbf{z}_i, \dots, \sim i.i.d. MVN(\mathbf{0}, \Phi_0)$
  2. calculate  $\mathbf{Z}^T \mathbf{Z} = \sum_{i=1}^{\nu_0} \mathbf{z}_i \mathbf{z}_i^T$
  3. repeat the procedure generating  $\mathbf{Z}_i^T \mathbf{Z}_i$
- $\mathbf{Z}_i^T \mathbf{Z}_i \sim Wis(\nu_0, \Phi_0)$

## Properties

- If  $\nu_0 > p$ ,  $\mathbf{Z}^T \mathbf{Z}$  is positive definite with prob. 1
- $\mathbf{Z}^T \mathbf{Z}$  is symmetric with prob. 1
- $E[\mathbf{Z}^T \mathbf{Z}] = \nu_0 \Phi_0$

# Wishart distribution

- Wishart distribution is a multivariate analogue of the gamma distribution

$$\frac{(n-1)S^2}{\sigma^2} \sim X^2(n-1) = \Gamma\left(\frac{n-1}{2}, \frac{1}{2}\right)$$
$$\Leftrightarrow (n-1)s^2 \sim \Gamma\left(\frac{n-1}{2}, \frac{1}{2\sigma^2}\right)$$

- Our prior distribution for the precision  $1/\sigma^2$  is a gamma distribution and prior distribution for variance is inverse-gamma distribution
- Similarly, Wishart distribution is a semi-conjugate prior distribution for the precision matrix  $\Sigma^{-1}$  and so, the inverse-Wishart distribution is our semi-conjugate prior for covariance matrix  $\Sigma$

# Inverse Wishart distribution as semi-conjugate prior for $\Sigma$

- Let's revisit the procedure of creating Wishart distribution

1. Sample  $z_1, \dots, z_{\nu_0} \sim i.i.d. MVN(\mathbf{0}, S_0^{-1})$
2. Calculate  $\mathbf{Z}^T \mathbf{Z} = \sum_{i=1}^{\nu_0} z_i z_i^T$
3. Set  $\Sigma = (\mathbf{Z}^T \mathbf{Z})^{-1}$

$$\Sigma^{-1} \sim \text{Wis}(\nu_0, S_0^{-1}), E[\Sigma^{-1}] = \nu_0 S_0^{-1}$$

$$\Sigma \sim \text{Wis}^{-1}(\nu_0, S_0^{-1}), E[\Sigma] = \frac{1}{\nu_0 - p - 1} S_0$$

- prior 모수 설정 방법!

1.  $\Sigma = \Sigma_0$ 라는 믿음이 강한 경우:  $\nu_0 \uparrow$ ,  $S_0 = (\nu_0 - p - 1)\Sigma_0$ 로 설정
  2. 믿음이 약하면  $\nu_0 = p + 2$ 로 설정
- 두 경우 모두  $\Sigma$ 가  $\Sigma_0$ 를 중심으로 근처에 설정되도록 함

# Full conditional distribution of covariance matrix

- Prior:  $\Sigma \sim \text{inv-Wis}(\nu_0, \mathbf{S}_0^{-1})$

$$p(\Sigma) = \left[ 2^{\nu_0 p/2} \pi^{(p)/2} |\mathbf{S}_0|^{-\nu_0/2} \prod_{j=1}^p \Gamma([\nu_0 + 1 - j]/2) \right]^{-1} \times \\ |\Sigma|^{-(\nu_0 + p + 1)/2} \times \exp \left\{ -\text{tr}(\mathbf{S}_0 \Sigma^{-1}) / 2 \right\}.$$

- Likelihood:  $\mathbf{y} | \boldsymbol{\mu}, \Sigma \sim \text{MVN}(\boldsymbol{\mu}, \Sigma)$

$$p(\mathbf{y}_1, \dots, \mathbf{y}_n | \boldsymbol{\mu}, \Sigma) = (2\pi)^{-np/2} |\Sigma|^{-n/2} \exp \left\{ -\sum_{i=1}^n (\mathbf{y}_i - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{y}_i - \boldsymbol{\mu}) / 2 \right\} \\ \propto |\Sigma|^{-n/2} \exp \frac{1}{2} \text{tr}(S_\mu \Sigma^{-1}) \\ \text{where } S_\mu = \sum_{i=1}^n (\mathbf{y}_i - \boldsymbol{\mu})(\mathbf{y}_i - \boldsymbol{\mu})^T$$

# Full conditional distribution of covariance matrix

- Full conditional posterior distribution of  $\Sigma$ :  $\Sigma \mid y \sim \text{inv-Wis}(\nu_n + n, [\mathbf{S}_0 + \mathbf{S}_\mu]^{-1})$

$$\begin{aligned} p(\Sigma \mid y_1, \dots, y_n, \mu) &\propto p(\Sigma) p(y_1, \dots, y_n \mid \mu, \Sigma) \\ &\propto |\Sigma|^{-(V_0+p+1)/2} \times \exp \left\{ -\text{tr} (S_0 \Sigma^{-1}) / 2 \right\} \times |\Sigma|^{-n/2} \exp \left( -\frac{1}{2} \text{tr} (S_\mu \Sigma^{-1}) \right) \\ &= |\Sigma|^{-(v_0+p+n+1)/2} \exp \left( -\frac{1}{2} \text{tr} ([S_0 + S_\mu] \Sigma^{-1}) \right) \end{aligned}$$

- Interpretation of the expectation as weighted average

$$\begin{aligned} E[\Sigma \mid y_1, \dots, y_n, \mu] &= \frac{1}{\nu_0 + n - p - 1} (S_0 + S_\mu) \\ &= \frac{\nu_0 - p - 1}{\nu_0 + n - p - 1} \underbrace{\frac{1}{\nu_0 - p - 1} S_0}_{\text{weighted average}} + \frac{n}{\nu_0 + n - p - 1} \underbrace{\frac{1}{n} S_\mu}_{\text{weighted average}} \end{aligned}$$

# Summary

- ① Semiconjugate prior for  $\mu$  (given  $\Sigma$ )

$$\mu \sim \text{MVN}(\mu_0, \Lambda_0)$$

$$\mu \mid y \sim \text{MVN}(\mu_n, \Lambda_n)$$

$$\text{where } \begin{cases} \mu_n = (\Lambda_0^{-1} + n\Sigma^{-1}) (\Lambda_0^{-1}\mu_0 + n\Sigma^{-1}\bar{y}) \\ \Lambda_n = \Lambda_0^{-1} + n\Sigma^{-1} \end{cases}$$

- ② Semiconjugate prior for  $\Sigma$  (given  $\mu$ )

$$\Sigma \sim \text{Wis}^{-1}(\nu_0, S_0^{-1}) \quad (S_0 = (\nu_0 - p - 1) \Sigma_0)$$

$$\Sigma \mid y \sim \text{Wis}^{-1}(\nu_0 + n, (S_0 + S_\mu)^{-1})$$

$$E[\Sigma \mid y] = \frac{\nu_0 - p - 1}{\nu_0 + n - p - 1} \Sigma_0 + \frac{n}{\nu_0 + n - p - 1} \left( \frac{1}{n} S_\mu \right)$$

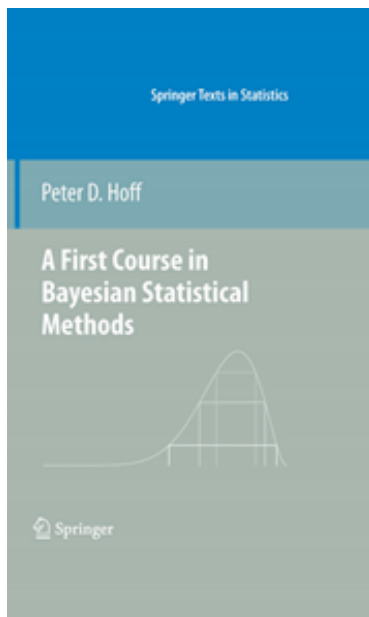


# Bayesian Statistics

## Ch.7 Multivariate Normal model

이규민

March 25, 2021



- **A First Course in Bayesian Statistical Methods**

- 목차:

- 1 Intro
- 2 Belief, probability, and exchangeability
- 3 One parameter models
- 4 Monte Carlo approximation
- 5 Normal model
- 6 Gibbs sampler
- 7 Multivariate normal model
- 8 Hierarchical model
- 9 Linear regression
- 10 Metropolis-Hastings algorithm

# What we did so far...

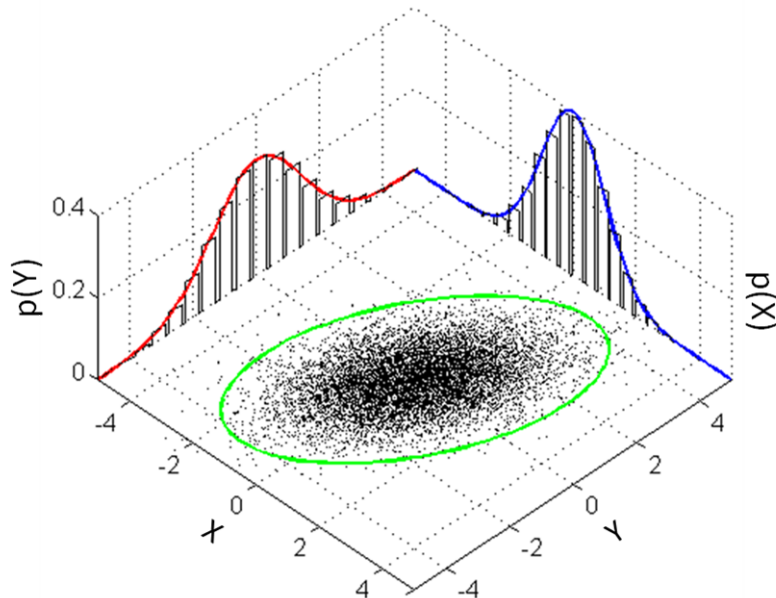
## Full conditional distribution

- $\theta | y_1, \dots, y_n, \Sigma \sim MVN(\mu_n, \Lambda_n)$
- $\Sigma | y_1, \dots, y_n, \theta \sim inv - Wish(\nu_n, S_n^{-1})$

→ with these, we approximate joint posterior distribution,  $\theta, \Sigma | y_1, \dots, y_n$

# Gibbs Sampling

sampling joint distribution by generating dependent sequence of parameters



# Gibbs Sampling

**sampling joint distribution by generating dependent sequence of parameters**

$$\theta_1^{(0)} \rightarrow \theta_2^{(1)} \rightarrow \theta_1^{(1)} \rightarrow \dots \theta_2^{(s)} \rightarrow \theta_1^{(s)} \rightarrow \dots$$

- 1. Choose a starting value  $\theta_1^{(0)}$
- 2. Sample  $\theta_2^{(1)}$  from  $p(\theta_2 | \theta_1^{(0)}, y_1, \dots, y_n)$
- 3. Sample  $\theta_1^{(1)}$  from  $p(\theta_1 | \theta_2^{(1)}, y_1, \dots, y_n)$
- 4. So on ...

# Gibbs Sampling

sampling joint distribution by generating dependent sequence of parameters

$$\Sigma^{(0)} \rightarrow \mu^{(1)} \rightarrow \Sigma^{(1)} \rightarrow \dots \mu^{(s)} \rightarrow \Sigma^{(s)} \rightarrow \dots$$

- 1. Choose a starting value  $\Sigma^{(0)}$
- 2. Sample  $\mu^{(1)}$  from  $MVN(\mu_n, \Lambda_n)$  computed from  $y_1, \dots, y_n$  and  $\Sigma^{(0)}$ 
  - $\Lambda_n^{-1} = \Lambda_0^{-1} + n\Sigma^{-1}$
  - $\mu_n = \Lambda_n(\Lambda_0^{-1}\mu_0 + n\Sigma^{-1}\bar{y})$
- 3. Sample  $\Sigma^{(1)}$  from  $inv - Wish(\nu_n, S_n^{-1})$  computed from  $y_1, \dots, y_n$  and  $\theta^{(1)}$ 
  - $\nu_n = \nu_0 + n$
  - $S_0 = (\nu_0 - d - 1)\Sigma_0$
  - $S_\mu = \sum_{i=1}^n (y_i - \mu)(y_i - \mu)^T$
  - $S_n = S_0 + S_\mu$
- 4. So on ...

# Gibbs Sampling

Listing 1: Bivariate normal distribution: true model

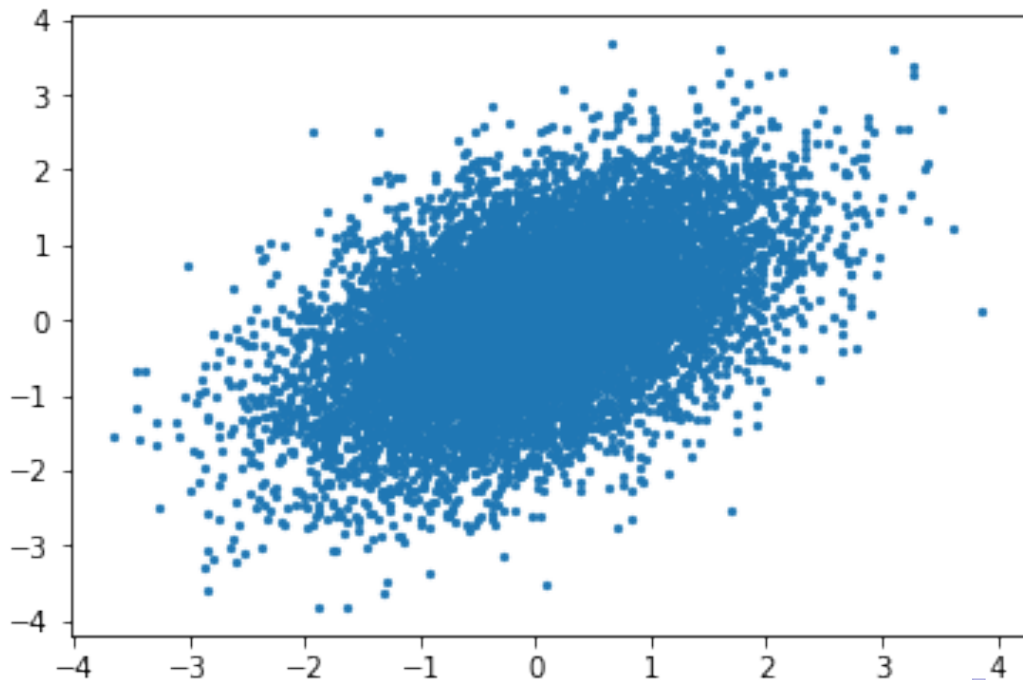
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```
import numpy as np
import matplotlib.pyplot as plt
from scipy.stats import pearsonr

automatic_samples = np.random.multivariate_normal([0,0], [[1, 0.5], [0.5,1]], 10000)
plt.scatter(automatic_samples[:,0], automatic_samples[:,1], s=5)
```

---

# Gibbs Sampling





# Gibbs Sampling

## Gibbs sampling by yourself Again bivariate normal model

$$\begin{bmatrix} x_0 \\ x_1 \end{bmatrix} \sim N \left[ \begin{bmatrix} \mu_0 \\ \mu_1 \end{bmatrix}, \begin{bmatrix} \Sigma_{00} & \Sigma_{01} \\ \Sigma_{10} & \Sigma_{11} \end{bmatrix} \right]$$

$$p(x_0|x_1) \sim N(\mu_0 + \Sigma_{01}\Sigma_{11}^{-1}(x_1 - \mu_1), \Sigma_{00} - \frac{\Sigma_{01}^2}{\Sigma_{11}})$$

# Gibbs Sampling

Listing 2: Bivariate normal distribution: generated by Gibbs sampling

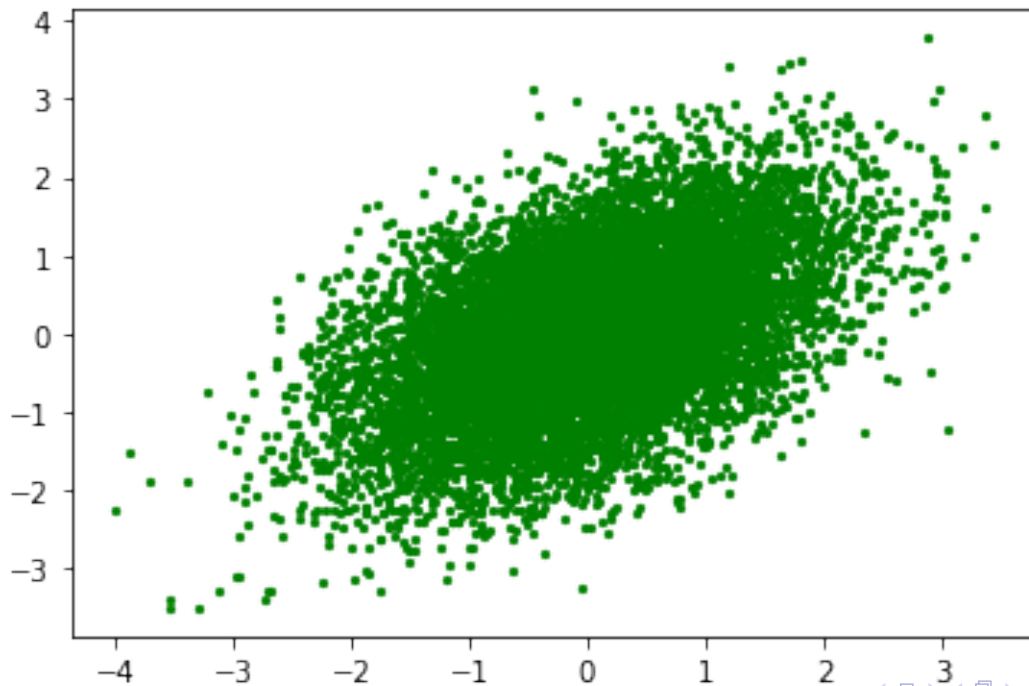
```
samples = {'x': [1], 'y': [-1]}

num_samples = 10000

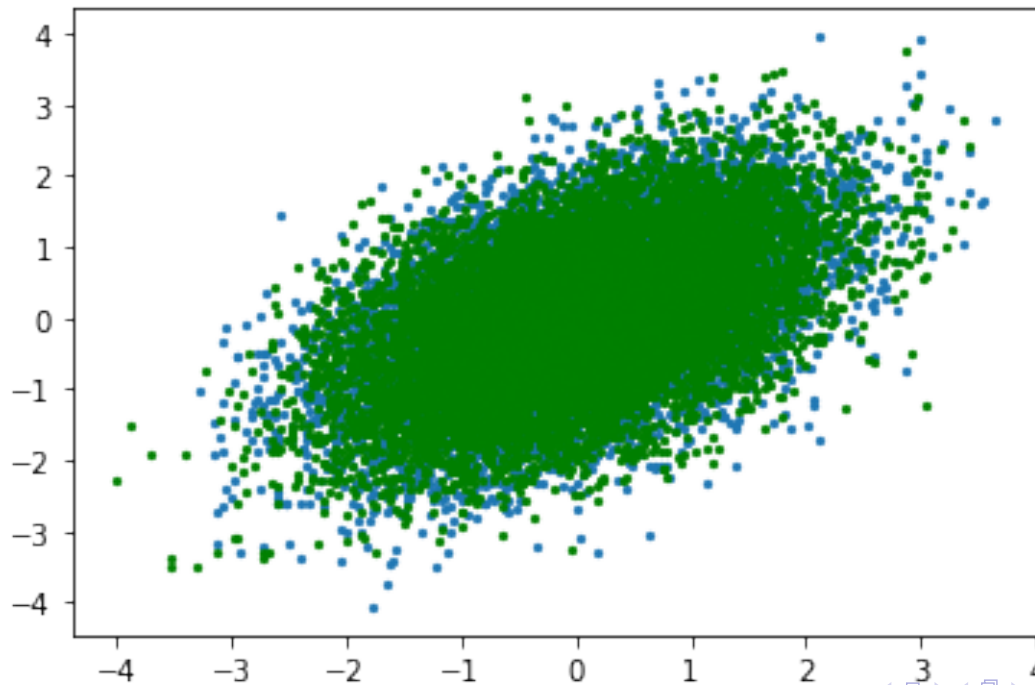
for _ in range(num_samples):
    curr_y = samples['y'][-1]
    new_x = np.random.normal(curr_y/2, np.sqrt(3/4))
    new_y = np.random.normal(new_x/2, np.sqrt(3/4))
    samples['x'].append(new_x)
    samples['y'].append(new_y)

plt.scatter(samples['x'], samples['y'], s=5)
```

# Gibbs Sampling



# Gibbs Sampling



# Gibbs Sampling

## Listing 3: Bivariate normal distribution: comparing histograms

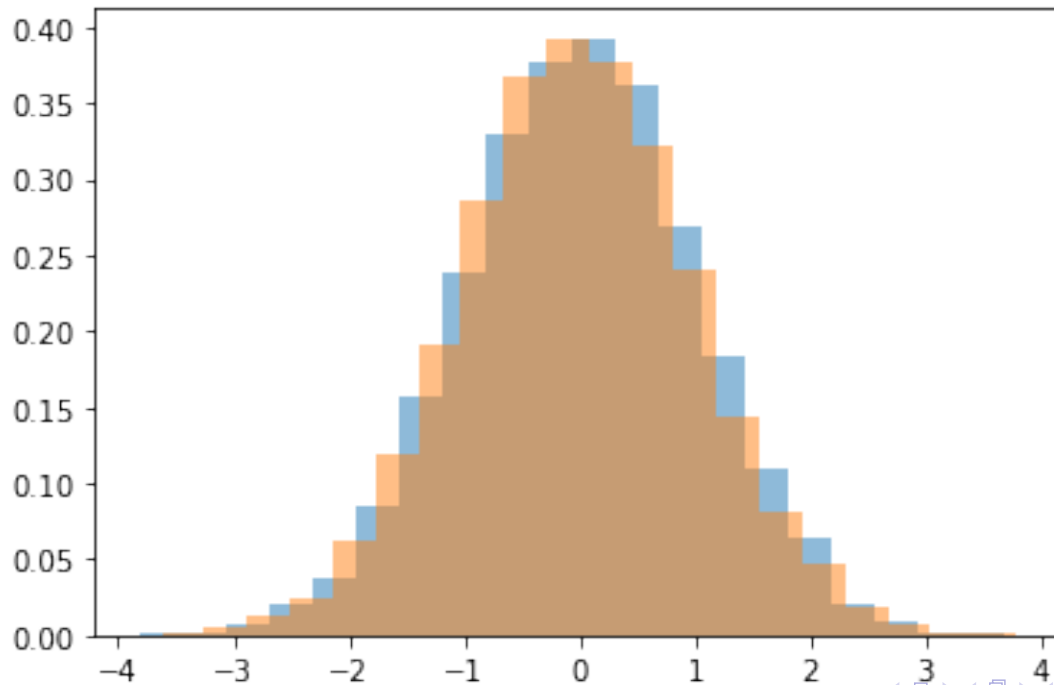
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```
plt.hist(automatic_samples[:,0], bins=20, density=True, alpha=0.5)
plt.hist(samples['x'], bins=20, density=True, alpha=0.5)

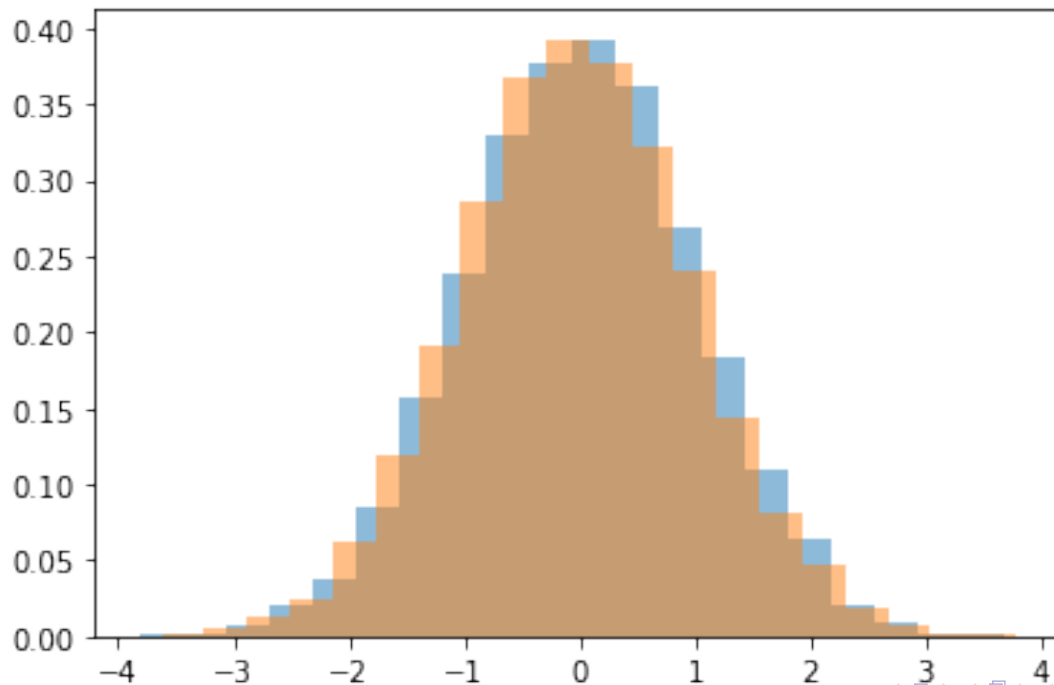
plt.hist(automatic_samples[:,1], bins=20, density=True, alpha=0.5)
plt.hist(samples['y'], bins=20, density=True, alpha=0.5)
```

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# Gibbs Sampling



# Gibbs Sampling



# Gibbs Sampling

## Gibbs sampling: data analysis

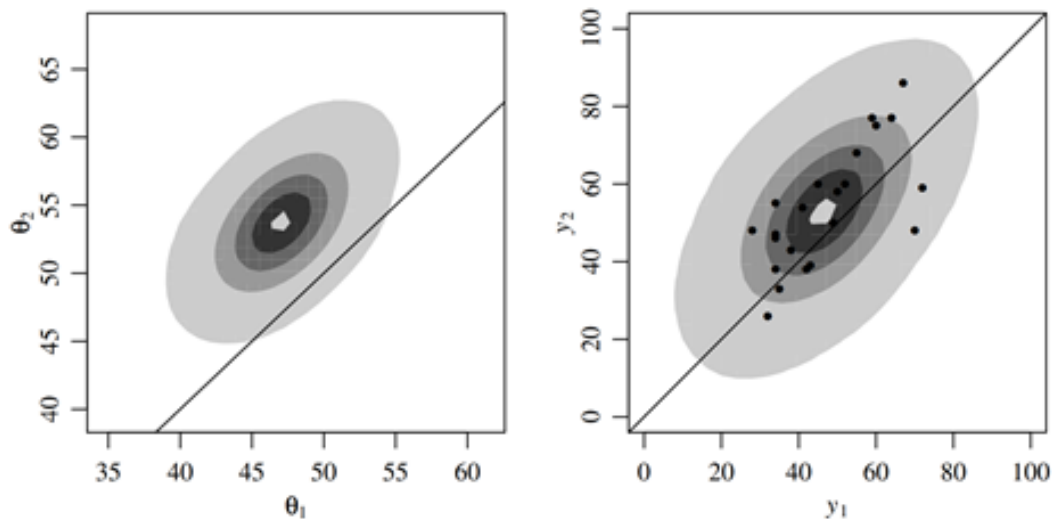


Fig. 7.2. Reading comprehension data and posterior distributions



# Gibbs Sampling

**Gibbs sampling: look at the whole process!**

# Gibbs Sampling

Listing 4: Bivariate normal distribution: by yourself!

```
def conditional_sampler(sampling_index, current_x, mean, cov):
    conditioned_index = 1 - sampling_index # 두 r.v. 중 고르기
    a = cov[sampling_index, sampling_index] # Sigma00
    b = cov[sampling_index, conditioned_index] # Sigma01
    c = cov[conditioned_index, conditioned_index] # Sigma11

    mu = #채워보세요 "!"
    sigma = #채워보세요 "!"
    new_x = np.copy(current_x)
    new_x[sampling_index] = np.random.randn()*sigma + mu
    # [x_0, x_1] 꼴의 1x2 np.array return
    return new_x
```

# Gibbs Sampling

Listing 5: Bivariate normal distribution: by yourself!

```
def gibbs_sampler(initial_point, num_samples, mean, cov, create_gif=True):  
    """  
    [input 형태]  
    initial_point = [x_0, x_1] = [-9.0, -9.0]  
    num_samples = 100  
    mean = np.array([0, 0])  
    cov = np.array([[10, 3],  
                    [3, 5]])  
    """  
  
    frames = [] # for GIF  
    point = np.array(initial_point)  
    samples = np.empty([num_samples+1, 2]) # sampled points  
    samples[0] = # 채워보세요!  
    tmp_points = np.empty([num_samples, 2]) # inbetween points 중간저장소()
```

# Gibbs Sampling

Listing 6: Bivariate normal distribution: by yourself!

```
for i in range(num_samples):
    # 0| for 0|loop gibbs sampler 의전부 !
    # point = [x_0, x_1]
    # Sample from  $p(x_0|x_1)$ 
    point = conditional_sampler(0, point, mean, cov)
    tmp_points[i] = point
    if(create_gif):
        frames.append(plot_samples(samples, i+1, tmp_points, i+1,
            title="Num_Samples:_" + str(i)))

# Sample from  $p(x_1|x_0)$ 
point = conditional_sampler(1, point, mean, cov)
samples[i+1] = point
if(create_gif):
    frames.append(plot_samples(samples, i+2, tmp_points, i+1,
        title="Num_Samples:_" + str(i+1)))
```

# NA imputation

## NA imputation

	glu	bp	skin	bmi
1	86	68	28	30.2
2	195	70	33	NA
3	77	82	NA	35.8
4	NA	76	43	47.9
5	107	60	NA	NA
6	97	76	27	NA
7	NA	58	31	34.3
8	193	50	16	25.9
9	142	80	15	NA
10	128	78	NA	43.3

# NA imputation

## Types of missing data

- MCAR: Missing completely at random
- MAR: Missing at random
- MNAR: Missing not at random

# NA imputation

## NA imputation

- $O_i = (O_1, \dots, O_p)^T$  where  $O_{i,j} = 1$  for observed data, 0 for o.w.
- Assume "Missing at random" :  $O_i$  and  $Y_i$  are independent
- So  $O_i$  doesn't depend on  $\theta$  or  $\Sigma$

$$p(o_i, y_{i,j} : o_{i,j} = 1 | \theta, \Sigma) = p(o_i) \times p(y_{i,j} : o_{i,j} = 1 | \theta, \Sigma) \quad (1)$$

$$= p(o_i) \times \int p(y_{i,j} | \theta, \Sigma) \prod_{y_{i,j} : o_{i,j}=0} dy_{i,j} \quad (2)$$

# NA imputation

## Again Gibbs sampling

이제는 NA로 몰랐던 자료도 sampling!

$$Y_{obs} = y_{i,j} : o_{i,j} = 1$$

$$Y_{miss} = y_{i,j} : o_{i,j} = 0$$

$$\Sigma^{(0)}, Y_{miss}^{(0)} \rightarrow \theta^{(1)} \rightarrow \Sigma^{(1)} \rightarrow Y_{miss}^{(1)} \rightarrow \dots \rightarrow \theta^{(s)} \rightarrow \Sigma^{(s)} \rightarrow Y_{miss}^{(s)} \rightarrow \dots$$

- 1. Choose a starting value  $\Sigma^{(0)}, Y_{miss}^{(0)}$
- 2. Sample  $\theta^{(1)}$  from  $p(\theta | \Sigma^{(0)}, Y_{miss}^{(0)}, Y_{obs})$
- 3. Sample  $\Sigma^{(1)}$  from  $p(\Sigma | \theta^{(1)}, Y_{miss}^{(0)}, Y_{obs})$
- 4. Sample  $Y_{miss}^{(1)}$  from  $p(Y_{miss} | \theta^{(1)}, \Sigma^{(1)}, Y_{obs})$
- 5. So on ...