

# 15. Clustering

## STA3142 Statistical Machine Learning

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# Announcement

- No class @ week 10 (May 7, 9)
- No class & no final exam @ week 16
  - Assignment 5 is the replacement
  - You should submit A5 for your attendance @ week 16

# Midterm Grading

- Ongoing; we are trying to release it this week
- If you don't agree with the Honor code – your midterm score is 0.
  - If you didn't write the pledge and your name on the first page properly, you receive 0 point.
  - If you did so, your submission will be graded after you complete it.
  - Your academic career is built on academic honesty.

# Post-Midterm

- Let's solve some questions that you felt difficult.
- A survey will be out together with midterm results.
  - To determine questions we are going to solve together
- If you feel you didn't do well,
  - You are not alone; other students would too.
  - Problem-solving skills can be improved by practice.
    - E.g., Derive ML algorithms we have learned from scratch
    - Don't just memorize them

# Assignment 3

- Due **Friday 5/3, 11:59pm**
- Topics
  - (Programming) K-Nearest Neighbors
  - (Math) MLE vs. MAP
  - (Math) Kernel Methods
  - (Math/Programming) SVM Primal
- Please read the instruction carefully!
  - Submit one pdf and one zip file separately
  - Write your code only in the designated spaces
  - Do not import additional libraries
  - ...
- If you feel difficult, consider to take **option 2**.

# Recap: Machine Learning Tasks

- Supervised Learning
  - Classification
  - Regression
- Unsupervised Learning
  - Clustering
  - Density estimation
  - Embedding / Dimensionality reduction
- Reinforcement Learning
  - Learning to act  
(e.g., robot control, decision making, etc.)

# Recap: Supervised Learning

- Given a dataset  $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$ , where
  - $x_i \in \mathcal{X}$ : input (feature)
  - $y_i \in \mathcal{Y}$ : output (label)
- A black box ML algorithm produces a prediction function  $h: \mathcal{X} \rightarrow \mathcal{Y}$ , such that  $h(x)$  can predict the  $y$  values for all  $x$ 
  - Not only for all training data  $x_i \in D$ , but also for unseen test data  $x^* \in \mathcal{X}$ .
- Labels could be discrete or continuous
  - Discrete labels: **classification**
  - Continuous labels: **regression**

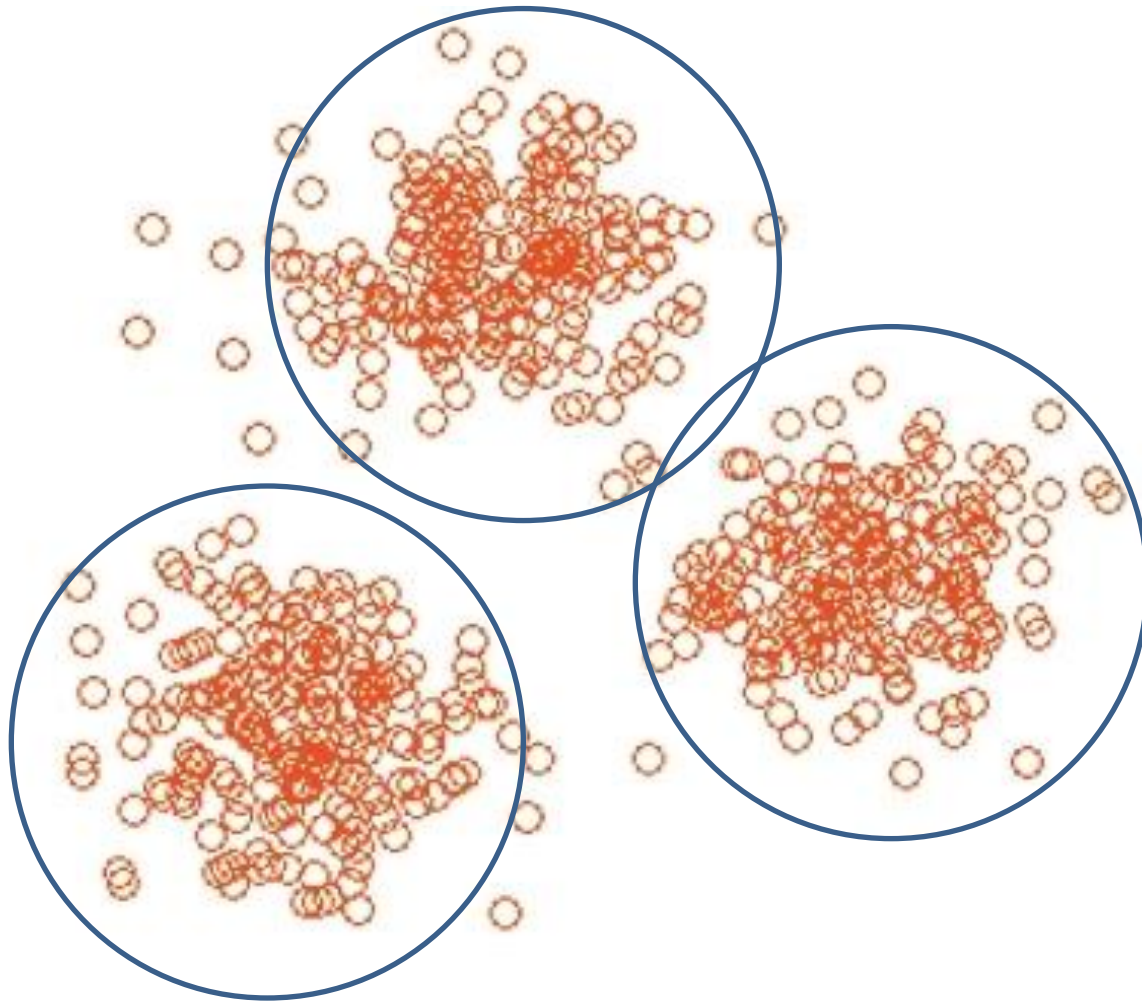
# Unsupervised Learning

- Given a dataset  $D = \{x_1, \dots, x_n\}$  without any labels, learning the underlying **structure** or **distribution** of the data
  - Clustering
  - Probability distribution (density)
  - Generating data
  - Embedding & neighborhood relations
- “Learning without teacher (supervision)”



# Unsupervised Learning: Clustering

- Grouping into similar examples



# Unsupervised Learning: Clustering

- Grouping into similar examples



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Slide Credit: Justin Johnson

# Outline

- Expectation Maximization (EM)
  - K-Means
  - Gaussian Mixture Models (GMM)
- General View of EM

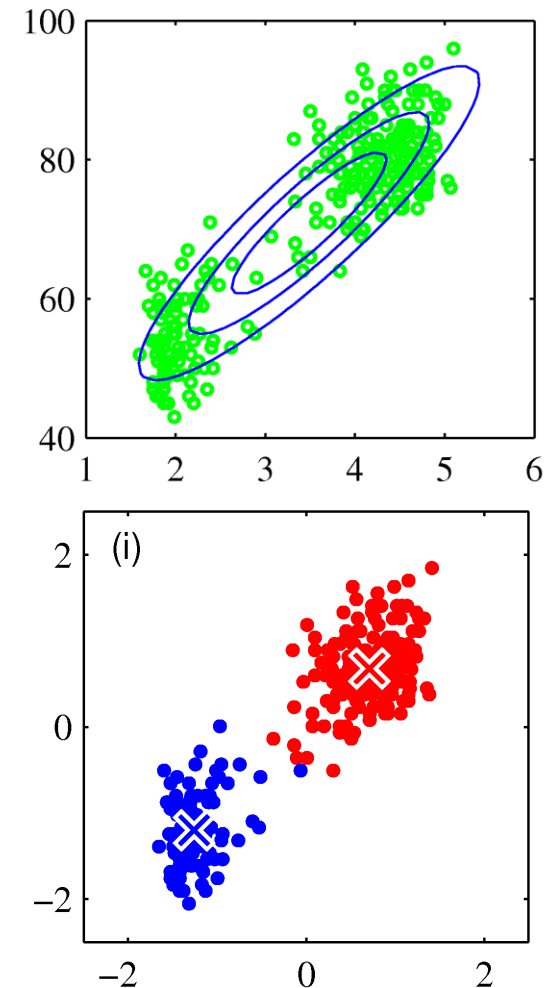
# Expectation Maximization (EM)

- Iteratively learning parameters when data is not fully observed
- Suppose we have observed variables  $X$  and latent (hidden) variables  $Z$ 
  - e.g., clustering:  $X$ : data,  $Z$ : cluster labels
- Iterate **E-steps** and **M-steps** until converged:
  - **E-step**: Inference about  $Z$  given  $X$ :  $Q = P(Z|X)$
  - **M-step**: Update parameters with  $Q$  found at E-step
- EM algorithms for clustering:
  - K-Means (a special case of GMM)
  - Gaussian Mixture Models (GMM)

# K-Means

# K-Means

- Given unlabeled data  $x^{(n)}$  for  $n = 1, \dots, N$ ,
- Assume that each data belongs to one of the  $K$  clusters,
- How do we find the cluster labels?



# K-Means: Formulation

- Cluster centers:  $\boldsymbol{\mu}_k, k = 1, \dots, K$
- Indicator variables:  $r_{nk} \in \{0,1\}, n = 1, \dots, N$ 
  - $r_{nk} = 1$  if  $\mathbf{x}^{(n)}$  is in cluster  $k$ .
  - $r_{nj} = 0$  for all  $j \neq k$ .
- Minimize  $J(r, \boldsymbol{\mu})$ : sum of squared distances of points from the center of its assigned cluster.

$$J(r, \boldsymbol{\mu}) = \sum_{k=1}^K \sum_{n=1}^N r_{nk} \|\mathbf{x}^{(n)} - \boldsymbol{\mu}_k\|^2$$

# K-Means Algorithm

- Initialize the cluster centers arbitrarily.
- Repeat the following updates until convergence:
  1. **E-Step:**

$$r := \operatorname{argmin}_r J(r, \boldsymbol{\mu})$$

2. **M-Step:**

$$\boldsymbol{\mu} := \operatorname{argmin}_{\boldsymbol{\mu}} J(r, \boldsymbol{\mu})$$



# K-Means Algorithm

- Initialize the cluster centers arbitrarily.
- Repeat the following updates until convergence:

- 1. E-Step:** Cluster assignment

- Assign each point to the closest center.

$$r_{nk} := \begin{cases} 1 & \text{if } k = \underset{j}{\operatorname{argmin}} \|\mathbf{x}^{(n)} - \boldsymbol{\mu}_k\|^2 \\ 0 & \text{otherwise} \end{cases}$$

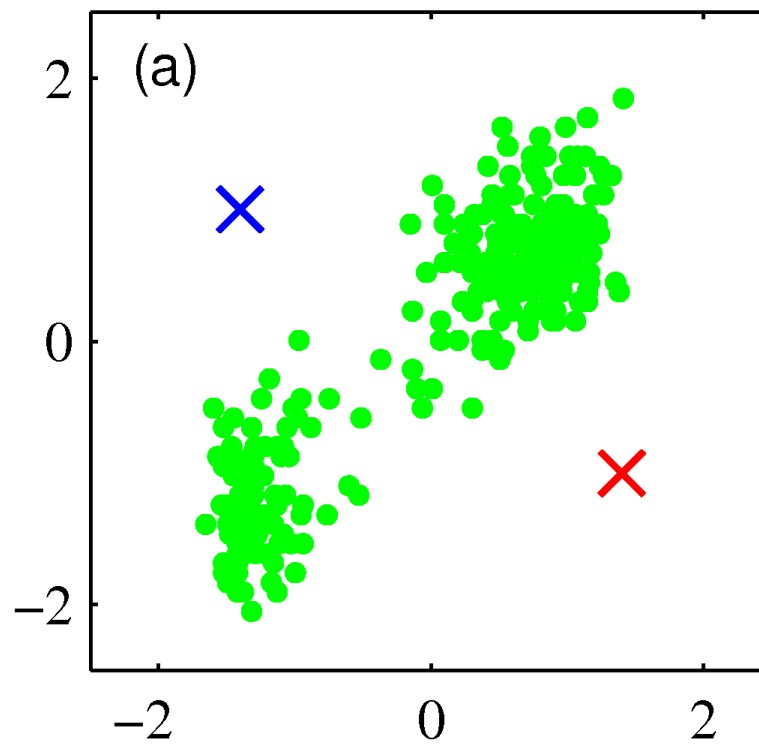
- 2. M-Step:** Parameter update

- Update cluster centers

$$\boldsymbol{\mu} := \frac{\sum_{n=1}^N r_{nk} \mathbf{x}^{(n)}}{\sum_{n=1}^N r_{nk}}$$

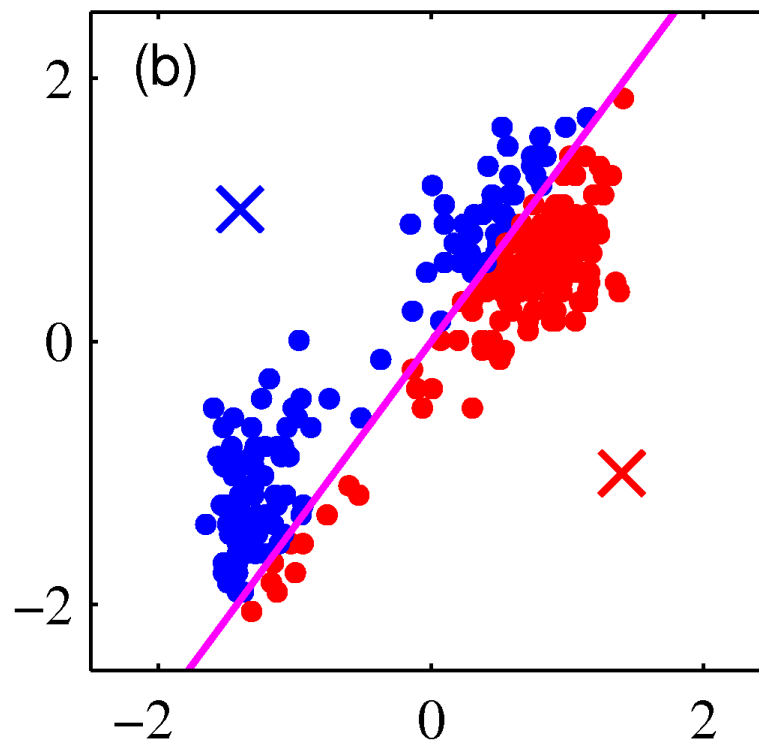
# K-Means Example: Initialization

- Choose  $K$  and pick random means.
- In this example,  $K = 2$ .



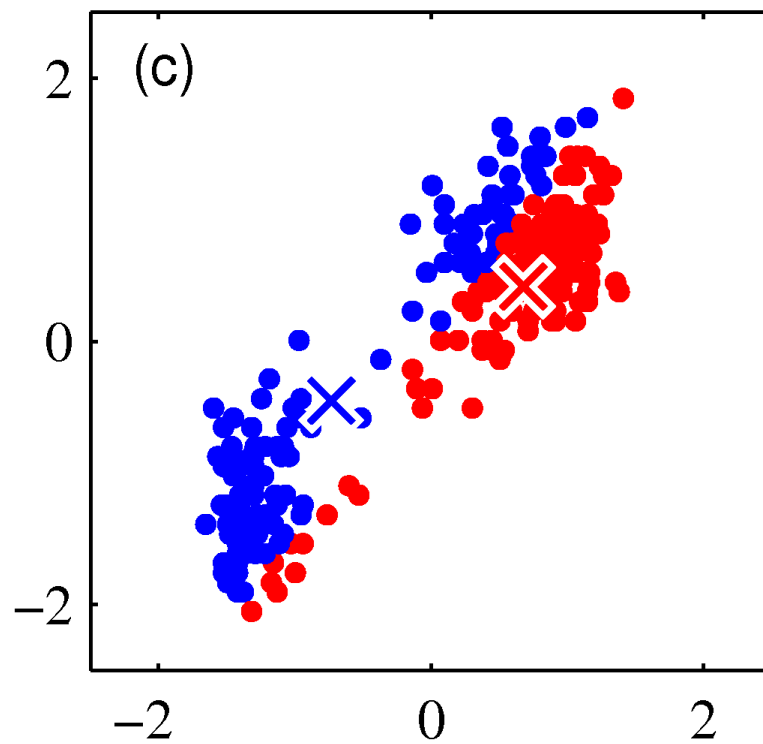
# K-Means Example: 1<sup>st</sup> E-Step

- Assign each data to the nearest center.



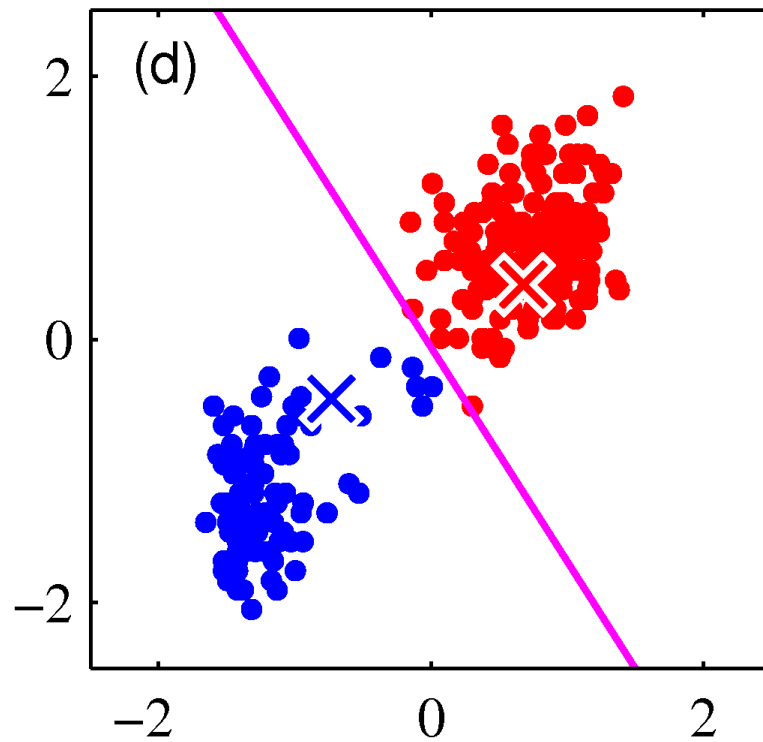
# K-Means Example: 1<sup>st</sup> M-Step

- Compute new centers for each cluster.



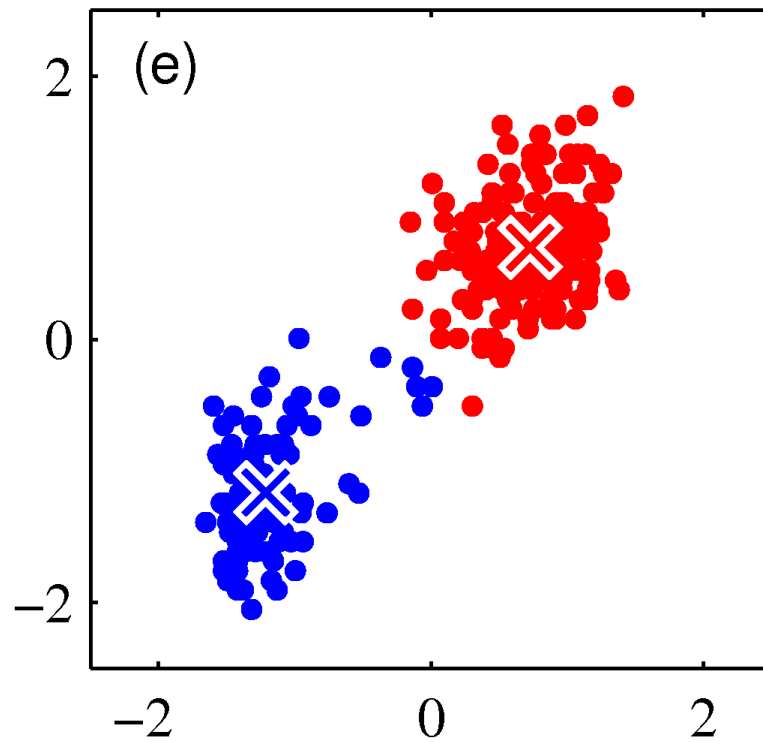
# K-Means Example: 2<sup>nd</sup> E-Step

- Reassign data to the nearest center.



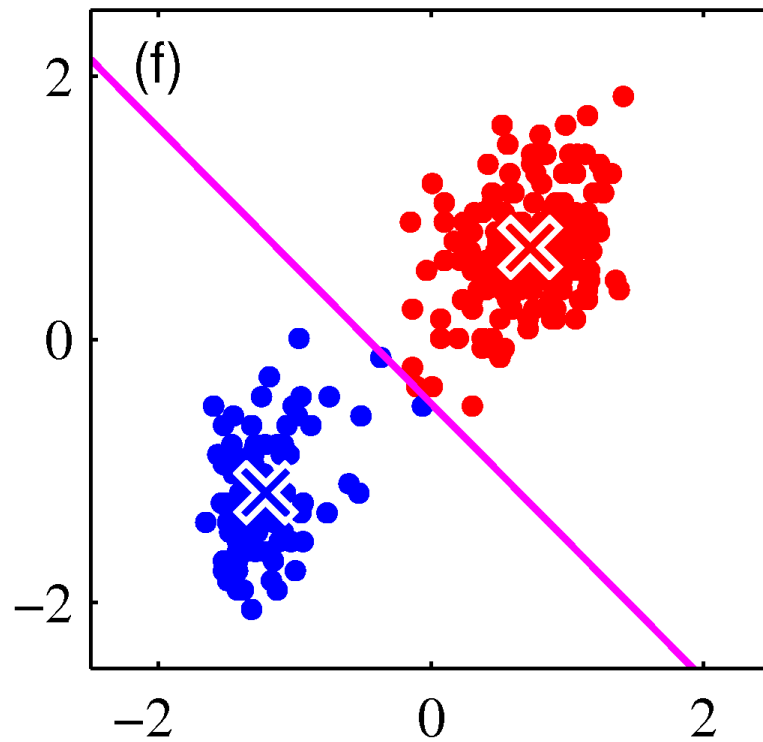
# K-Means Example: 2<sup>nd</sup> M-Step

- Compute new centers for each cluster.



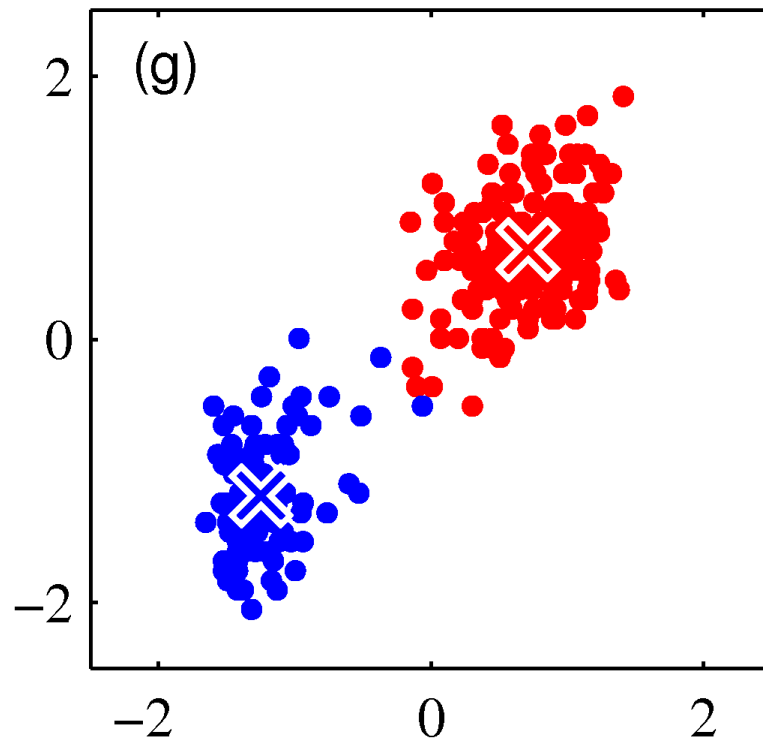
# K-Means Example: 3<sup>rd</sup> E-Step

- Reassign data to the nearest center.



# K-Means Example: 3<sup>rd</sup> M-Step

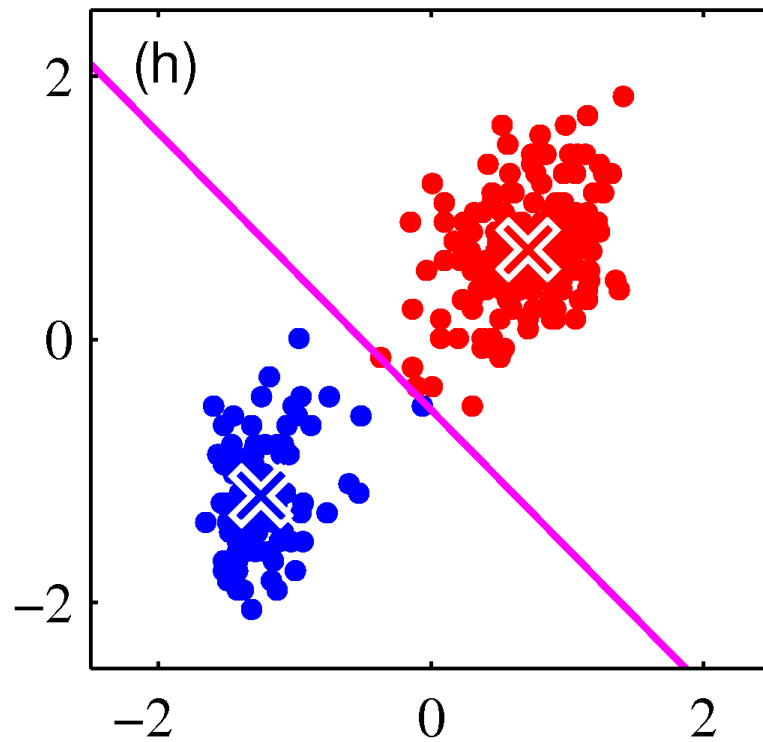
- Compute new centers for each cluster.





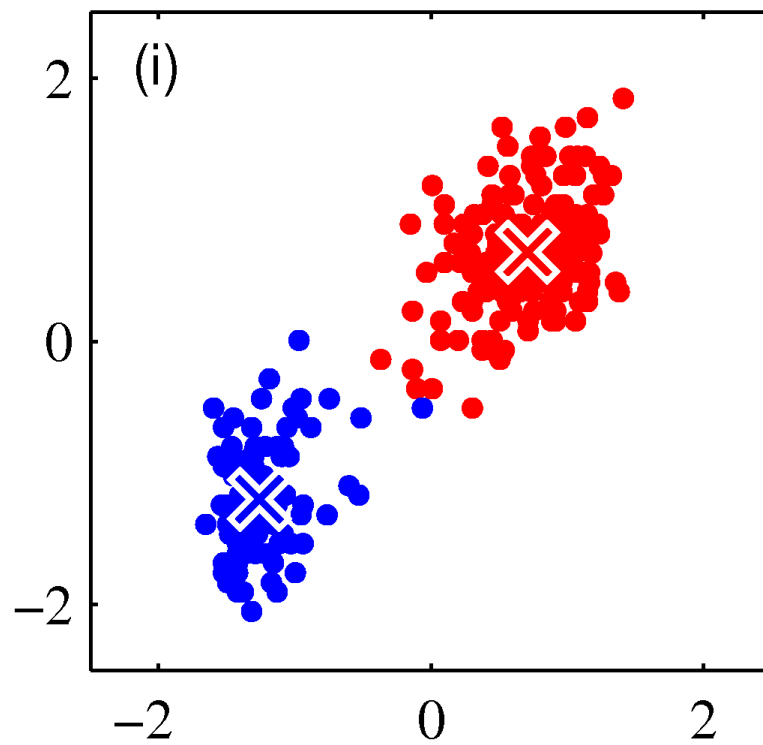
# K-Means Example: 4<sup>th</sup> E-Step

- Reassign data to the nearest center.



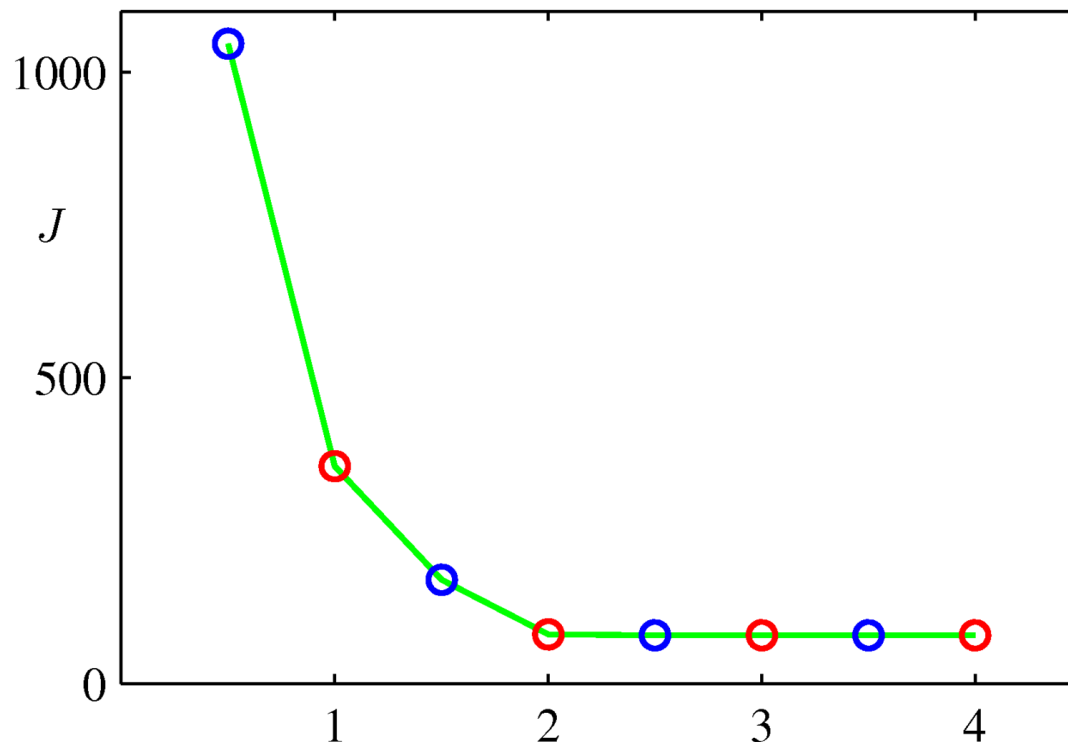
# K-Means Example: 4<sup>th</sup> M-Step

- Compute new centers for each cluster.
- Stop here; cluster centers have stopped changing.



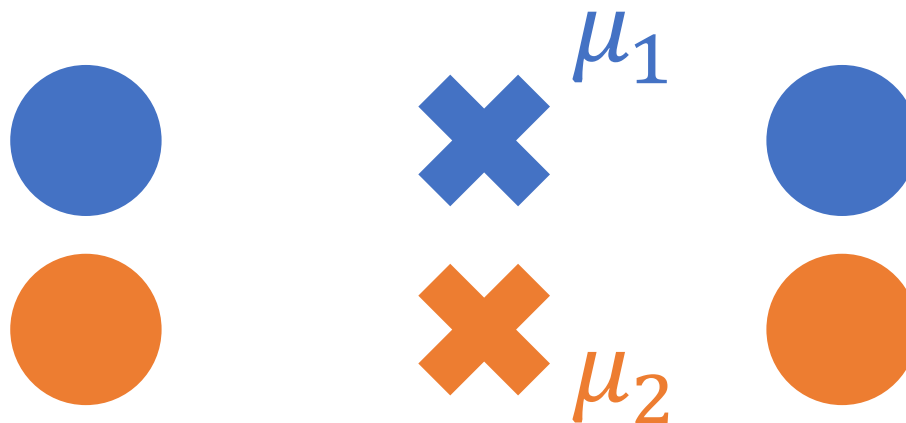
# K-Means: Convergence

- Convergence is relatively quick, in # of steps.
  - Blue circles after **E-step**: Assign each point to a cluster
  - Red circles after **M-step**: Recompute the cluster centers
  - However, all those distance computations are expensive.



# K-Means: Properties

- The objective function  $J(r, \mu)$  monotonically decreases over time.
  - It is a general property of the EM algorithm.
- No guarantee to find the **global optimum**.
  - Guaranteed to converge to **local optimum**.
  - Clustering result depends on the initial values.
  - e.g., the following clustering is a stable local optimum



# Gaussian Mixture Models

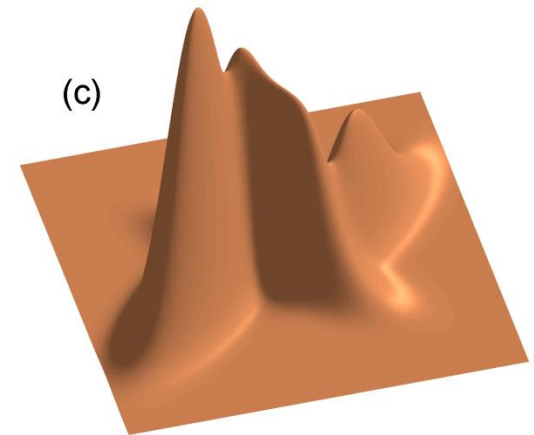
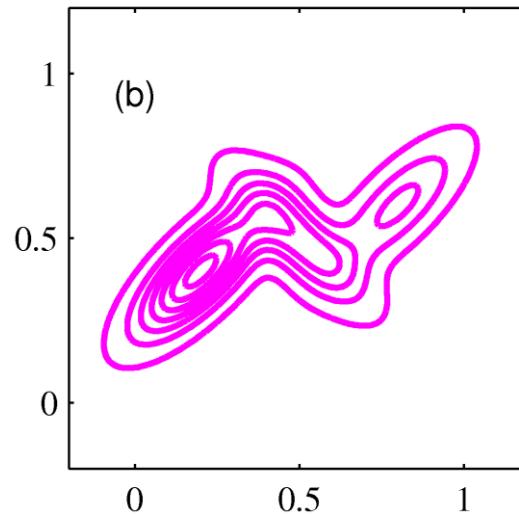
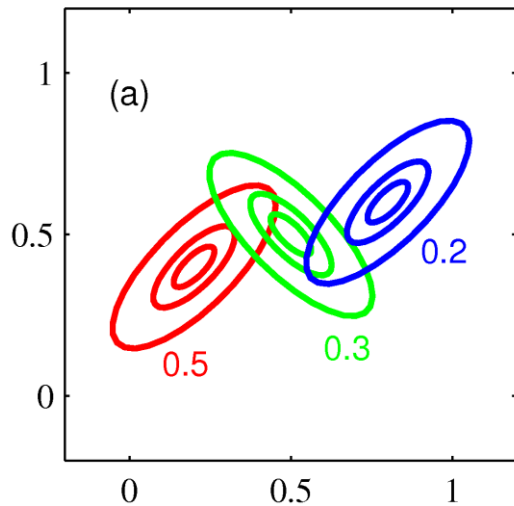
# Hard vs. Soft Clusters

- K-means uses hard clustering assignment.
  - Each data belongs to exactly one cluster.
- Gaussian mixture model (GMM) for soft clustering
  - Each data is assigned to more than one cluster.
  - Different clusters take different levels of responsibility (posterior probability) for each point.
    - Each data was generated by only one cluster, but we don't know which one.
  - Note that GMM itself is a probabilistic model, not a clustering method; **EM for GMM** is a clustering method on top of the probabilistic model.

# Gaussian Mixture Models

- GMMs make it possible to describe much richer distributions.

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \Sigma_k)$$



# GMM: Formulation

- Mixing coefficients:  $\pi_k$ , where  $\sum_{k=1}^K \pi_k = 1$
- Cluster assignments:  $\mathbf{z} \in \{0,1\}^K$  (1-of- $K$ )
- Marginal distribution of  $\mathbf{z}$ :

$$p(z_k = 1) = \pi_k, \quad p(\mathbf{z}) = \prod_{k=1}^K \pi_k^{z_k}$$

- Conditional distribution of  $\mathbf{x}$ :

$$p(\mathbf{x}|z_k = 1) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \Sigma_k)$$

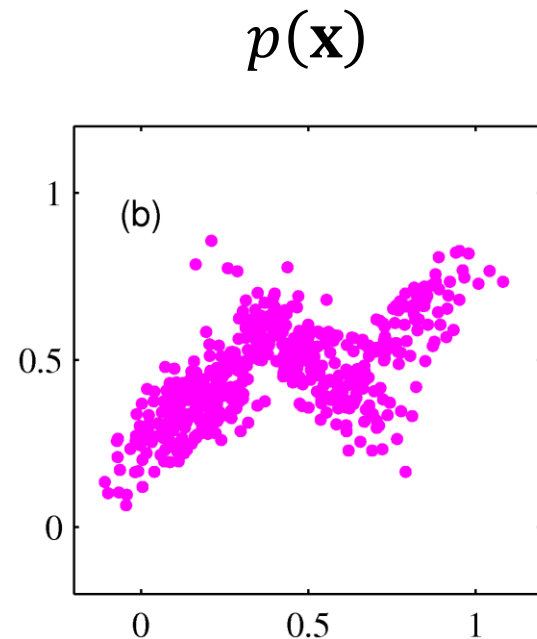
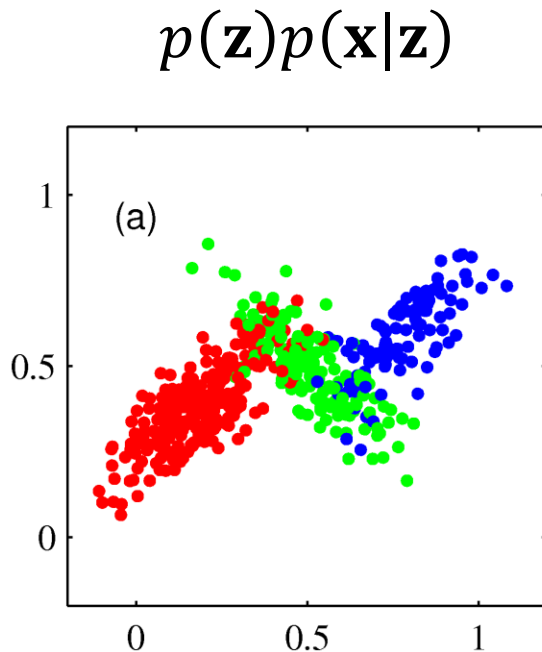
- Marginal distribution of  $\mathbf{x}$ :

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \Sigma_k)$$



# GMM: Formulation

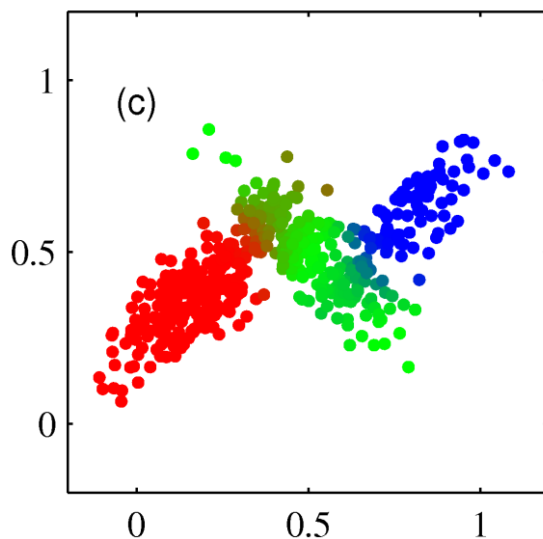
- To generate samples from a Gaussian mixture distribution  $p(\mathbf{x})$ , use  $p(\mathbf{x}, \mathbf{z})$ :
  - Select a value  $\mathbf{z}$  from the marginal  $p(\mathbf{z})$ ;
  - Then select a value  $\mathbf{x}$  from  $p(\mathbf{x}|\mathbf{z})$  for that  $\mathbf{z}$ .



# EM for GMM: E-Step

- Responsibility  $\gamma(z_k)$ : The degree (posterior prob.) to which each Gaussian explains an observation  $\mathbf{x}$ .

$$\begin{aligned}\gamma(z_k) &= p(z_k = 1 | \mathbf{x}) \\ &= \frac{\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_j, \Sigma_j)}\end{aligned}$$



# EM for GMM: M-Step Formulation

- Log-likelihood of observing the data  $\mathbf{x}$

$$\begin{aligned}\log p(\mathbf{x}) &= \sum_{k=1}^K \gamma(z_k) \log p(\mathbf{x}) \\ &= \sum_{k=1}^K \gamma(z_k) \log \frac{p(\mathbf{x}, z_k = 1)}{p(z_k = 1 | \mathbf{x})} \\ &= \sum_{k=1}^K \gamma(z_k) \log p(\mathbf{x}, z_k = 1) - \sum_{k=1}^K \gamma(z_k) \log \gamma(z_k)\end{aligned}$$

- Assume  $\gamma(z_k)$  is a constant

$$\log p(\mathbf{x}) = \sum_{k=1}^K \gamma(z_k) \log(\pi_k \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_k, \Sigma_k)) + C$$

# EM for GMM: M-Step Formulation

$$\begin{aligned}\log p(\mathbf{x}) &= \sum_{k=1}^K \gamma(z_k) \log(\pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \Sigma_k)) + \mathcal{C} \\&= \sum_{k=1}^K \gamma(z_k) \log \pi_k + \sum_{k=1}^K \gamma(z_k) \log \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \Sigma_k) + \mathcal{C} \\&= \sum_{k=1}^K \gamma(z_k) \log \pi_k + \frac{1}{2} \sum_{k=1}^K \gamma(z_k) \log |\Sigma_k^{-1}| \\&\quad - \frac{1}{2} \sum_{k=1}^K \gamma(z_k) (\mathbf{x} - \boldsymbol{\mu}_k)^T \Sigma_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k) + \mathcal{C}\end{aligned}$$

# EM for GMM: M-Step Formulation

- Log-likelihood:

$$\begin{aligned} L = \log p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(N)}) &= \sum_{n=1}^N \log p(\mathbf{x}^{(n)}) \\ &= \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k + \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log |\Sigma_k^{-1}| \\ &\quad - \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T \Sigma_k^{-1} (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k) + C \end{aligned}$$

# EM for GMM: M-Step Formulation

- Learning objective: maximum log-likelihood

$$\begin{aligned} & \max_{\{\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k, \pi_k\}_{k=1}^K} L \\ & \text{subject to } \sum_{k=1}^K \pi_k = 1 \end{aligned}$$

- where

$$\begin{aligned} L = & \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k + \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log |\boldsymbol{\Sigma}_k^{-1}| \\ & - \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k) \end{aligned}$$

# EM for GMM: M-Step Derivation

- MLE with respect to  $\boldsymbol{\mu}_k$ :

$$L = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k + \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log |\Sigma_k^{-1}| \\ - \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T \Sigma_k^{-1} (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)$$

$$\frac{\partial L}{\partial \boldsymbol{\mu}_k} = \frac{1}{2} \sum_{n=1}^N \gamma(z_{nk}) \Sigma_k^{-1} (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k) = 0 \\ \therefore \boldsymbol{\mu}_k = \frac{\sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}^{(n)}}{\sum_{n=1}^N \gamma(z_{nk})}$$

# EM for GMM: M-Step Derivation

- MLE with respect to  $M = \Sigma_k^{-1}$ :

$$L = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k + \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log |M|$$
$$- \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T M (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)$$

$$\frac{\partial \log |X|}{\partial X} = (X^{-1})^T \quad \frac{\partial \mathbf{a}^T X \mathbf{b}}{\partial X} = \mathbf{a} \mathbf{b}^T$$

$$\frac{\partial L}{\partial M} = \frac{1}{2} \sum_{n=1}^N \gamma(z_{nk}) M^{-1} - \frac{1}{2} \sum_{n=1}^N \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T = 0$$

$$\therefore M^{-1} = \Sigma_k = \frac{\sum_{n=1}^N \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T}{\sum_{n=1}^N \gamma(z_{nk})}$$



# EM for GMM: M-Step Derivation

- MLE with respect to  $\pi_k$ :

$$\begin{aligned} & \max_{\{\pi_k\}_{k=1}^K} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k \\ & \text{subject to } \sum_{k=1}^K \pi_k = 1 \end{aligned}$$

- Lagrangian function:

$$\mathcal{L}(\pi_1, \dots, \pi_K) = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k - \alpha \left( \sum_{k=1}^K \pi_k - 1 \right)$$

# EM for GMM: M-Step Derivation

- Lagrangian function:

$$\mathcal{L}(\pi_1, \dots, \pi_K) = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \log \pi_k - \alpha \left( \sum_{k=1}^K \pi_k - 1 \right)$$
$$\frac{\partial \mathcal{L}}{\partial \pi_k} = \sum_{n=1}^N \frac{\gamma(z_{nk})}{\pi_k} - \alpha = 0$$
$$\Rightarrow \pi_k = \frac{\sum_{n=1}^N \gamma(z_{nk})}{\alpha}$$

- From the constraint:

$$\sum_{k=1}^K \pi_k = \frac{1}{\alpha} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) = \frac{N}{\alpha} = 1$$
$$\therefore \pi_k = \frac{\sum_{n=1}^N \gamma(z_{nk})}{N}$$

# EM for GMM: M-Step

- The mean of a cluster is the weighted mean, weighted by the responsibilities  $\gamma(z_{nk})$ .

$$\boldsymbol{\mu}_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}^{(n)}$$

- where  $N_k = \sum_{n=1}^N \gamma(z_{nk})$  is the effective number of data in cluster  $k$

- Likewise for covariance:

$$\Sigma_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)(\mathbf{x}^{(n)} - \boldsymbol{\mu}_k)^T$$

- Mixing coefficients:  $\pi_k = \frac{N_k}{N}$

# EM for GMM: Summary

- Initialize means  $\boldsymbol{\mu}_k$ , covariances  $\Sigma_k$ , and mixing coefficients  $\pi_k$  for  $K$  Gaussians.
- **E-Step:** Given the parameters  $\{\boldsymbol{\mu}_k, \Sigma_k, \pi_k\}$ , evaluate the responsibilities  $\gamma(z_{nk})$ .

$$\gamma(z_{nk}) = p(z_k = 1 | \mathbf{x}^{(n)}) = \frac{\pi_k \mathcal{N}(\mathbf{x}^{(n)} | \boldsymbol{\mu}_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}^{(n)} | \boldsymbol{\mu}_j, \Sigma_j)}$$

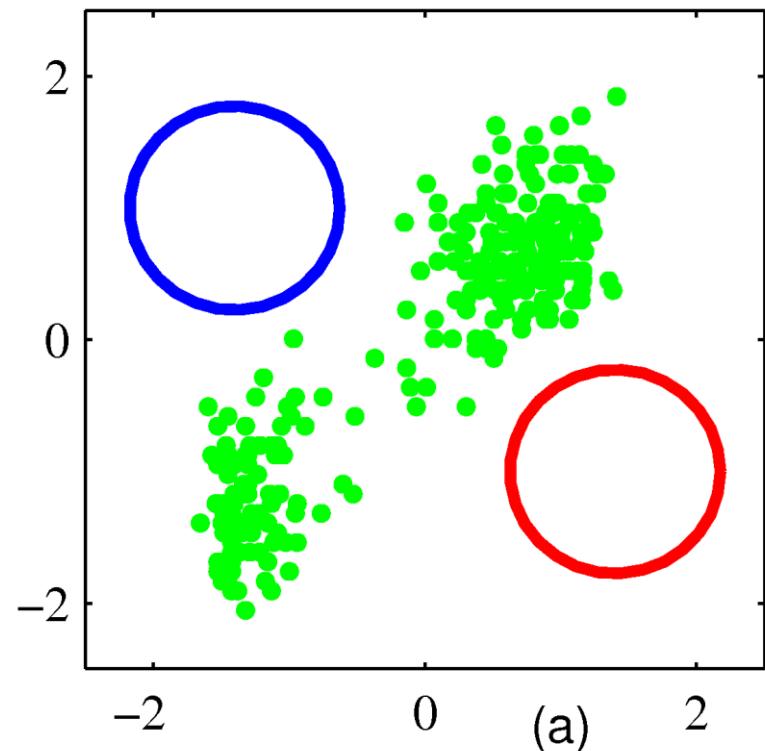
- **M-Step:** Given the responsibilities  $\gamma(z_{nk})$ , estimate the parameters  $\{\boldsymbol{\mu}_k, \Sigma_k, \pi_k\}$ .

$$\boldsymbol{\mu}_k^{\text{new}} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}^{(n)}, \pi_k^{\text{new}} = \frac{N_k}{N}, \text{ where } N_k = \sum_{n=1}^N \gamma(z_{nk})$$
$$\Sigma_k^{\text{new}} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (\mathbf{x}^{(n)} - \boldsymbol{\mu}_k^{\text{new}})(\mathbf{x}^{(n)} - \boldsymbol{\mu}_k^{\text{new}})^T$$

- Stop when the parameters or likelihood converges.

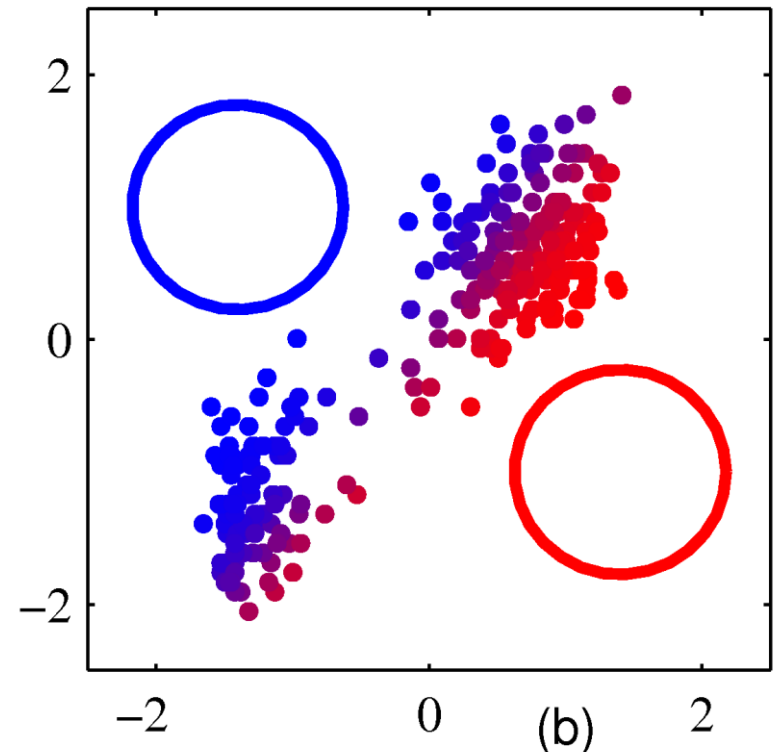
# EM for GMM Example

- Initialize parameters: means, covariances, and mixing coefficients.



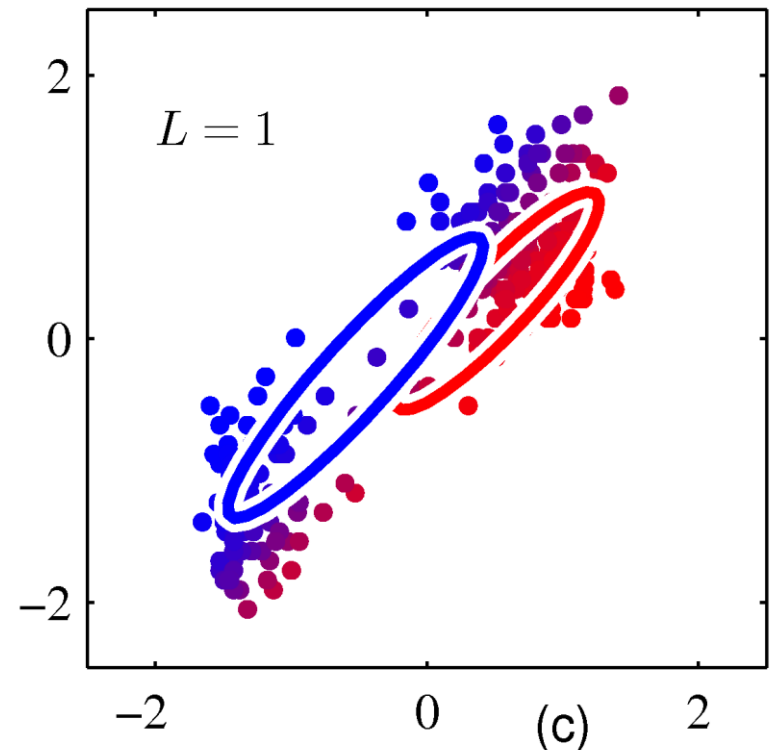
# EM for GMM Example: 1<sup>st</sup> E-Step

- Evaluate the responsibilities.



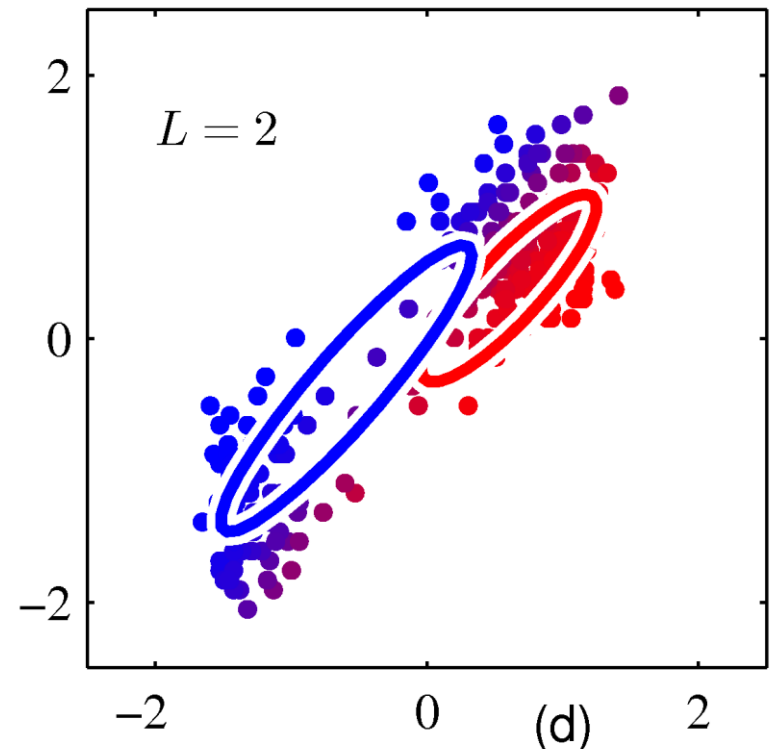
# EM for GMM Example: 1<sup>st</sup> M-Step

- Estimate the parameters.



# EM for GMM Example: 2<sup>nd</sup> Steps

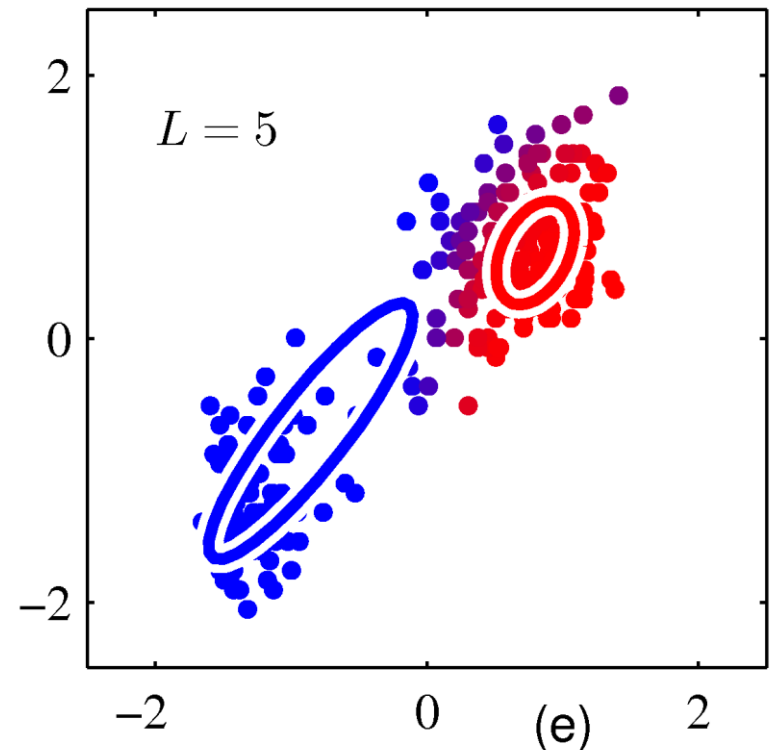
- Evaluate the responsibilities first, then estimate the parameters.





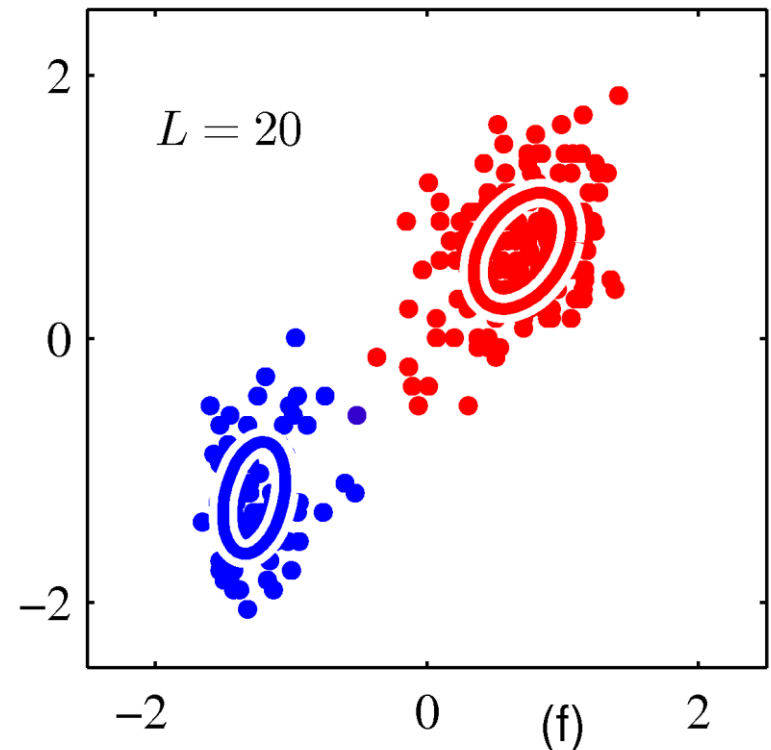
# EM for GMM Example: 5<sup>th</sup> Steps

- Evaluate the responsibilities first, then estimate the parameters.



# EM for GMM Example: 20<sup>th</sup> Steps

- Evaluate the responsibilities first, then estimate the parameters.



# EM for GMM vs. K-Means

- Fix the covariance matrix for each cluster as a diagonal matrix:

$$\Sigma_k = \sigma^2 I$$

- If we take  $\sigma^2 \rightarrow 0$ , then the update rules converge to K-means clustering.

# General View of EM

# EM: Motivation

- Suppose a system with **observed variables  $X$** .
- It may be easier to understand with additional **latent variables  $Z$** , which are not observed.
- E.g., in GMM, the latent variable  $Z$  specifies which Gaussian generated the sample  $X$ .
  - The responsibility is the posterior  $p(Z|X)$ .

# EM: Motivation

- In ML, we usually find model parameters  $\theta$  by maximizing log-likelihood of observed data.
- If we had complete data  $\{X, Z\}$ , we could easily maximize likelihood  $p(X, Z|\theta)$ .
- However, when not all variables are observed, we can marginalize over the **unobserved variables**:

$$\log p(X|\theta) = \log \left\{ \sum_Z p(X, Z|\theta) \right\}$$

- If  $Z$  is continuous, replace the sum with integral
- The summation over the **latent variables** is inside the logarithm, resulting in complicated expressions.

# EM: Formulation

- EM finds the local maximum likelihood of  $\log p(X)$  by alternating:
- **E-Step:** Given current parameters  $\theta^{\text{old}}$ , find the posterior distribution of  $Z$  given  $X$ :  $p(Z|X, \theta^{\text{old}})$
- Then, we find the **expectation** of the **complete-data log-likelihood** using the posterior:

$$Q(\theta, \theta^{\text{old}}) = \sum_Z \underbrace{p(Z|X, \theta^{\text{old}})}_{\text{Constant w.r.t. } \theta} \log p(X, Z|\theta)$$

- **M-Step:** Maximize the **expectation**:

$$\theta^{\text{new}} = \operatorname{argmax}_{\theta} Q(\theta, \theta^{\text{old}})$$

# EM: Derivation

- Goal: Maximize  $p(X|\theta) = \sum_Z p(X, Z|\theta)$
- For any distribution  $q(Z)$ , ( $q(Z) \geq 0, \sum_Z q(Z) = 1$ )

$$\log p(X|\theta) = \sum_Z q(Z) \log p(X|\theta)$$

- $\log p(X|\theta)$  is independent to  $Z$



# EM: Derivation

- Goal: Maximize  $p(X|\theta) = \sum_Z p(X, Z|\theta)$
- For any distribution  $q(Z)$ , ( $q(Z) \geq 0, \sum_Z q(Z) = 1$ )

$$\begin{aligned}\log p(X|\theta) &= \sum_Z q(Z) \log p(X|\theta) \\ &= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{p(Z|X, \theta)}\end{aligned}$$

- Conditional probability:  $p(X, Z|\theta) = p(X|\theta)p(Z|X, \theta)$

# EM: Derivation

- Goal: Maximize  $p(X|\theta) = \sum_Z p(X, Z|\theta)$
- For any distribution  $q(Z)$ , ( $q(Z) \geq 0, \sum_Z q(Z) = 1$ )

$$\begin{aligned}\log p(X|\theta) &= \sum_Z q(Z) \log p(X|\theta) \\ &= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{p(Z|X, \theta)} \\ &= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{q(Z)} \frac{q(Z)}{p(Z|X, \theta)}\end{aligned}$$

- Introduce auxiliary  $q(Z)$

# EM: Derivation

- Goal: Maximize  $p(X|\theta) = \sum_Z p(X, Z|\theta)$
- For any distribution  $q(Z)$ , ( $q(Z) \geq 0, \sum_Z q(Z) = 1$ )

$$\begin{aligned}\log p(X|\theta) &= \sum_Z q(Z) \log p(X|\theta) \\&= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{p(Z|X, \theta)} \\&= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{q(Z)} \frac{q(Z)}{p(Z|X, \theta)} \\&= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{q(Z)} + \sum_Z q(Z) \log \frac{q(Z)}{p(Z|X, \theta)} \\&= \mathcal{L}(q, \theta) + KL(q(Z) || p(Z|X))\end{aligned}$$

- $\mathcal{L}(q, \theta)$ : The lower bound we maximize
- $KL(q(Z) || p(Z|X))$ : Gap between  $q(Z)$  and  $p(Z|X)$

# EM: Derivation

- Goal: Maximize  $p(X|\theta) = \sum_Z p(X, Z|\theta)$
- For any distribution  $q(Z)$ , ( $q(Z) \geq 0, \sum_Z q(Z) = 1$ )

$$\begin{aligned}\log p(X|\theta) &= \sum_Z q(Z) \log p(X|\theta) \\&= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{p(Z|X, \theta)} \\&= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{q(Z)} \frac{q(Z)}{p(Z|X, \theta)} \\&= \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{q(Z)} + \sum_Z q(Z) \log \frac{q(Z)}{p(Z|X, \theta)} \\&= \mathcal{L}(q, \theta) + KL(q(Z) || p(Z|X)) \\&\geq \mathcal{L}(q, \theta)\end{aligned}$$

- KL divergence is nonnegative:  $KL(q(Z) || p(Z|X)) \geq 0$

# EM: Another Derivation

- Given the observed variables  $X$ , latent variables  $Z$ , and parameters  $\theta$ :

$$\log p(X|\theta) = \log \sum_Z p(X, Z|\theta)$$

- Introduce  $Z$

# EM: Another Derivation

- Given the observed variables  $X$ , latent variables  $Z$ , and parameters  $\theta$ :

$$\begin{aligned}\log p(X|\theta) &= \log \sum_Z p(X, Z|\theta) \\ &= \log \sum_Z q(Z) \frac{p(X, Z|\theta)}{q(Z)}\end{aligned}$$

- Introduce auxiliary  $q(Z)$  where  $q(Z) \geq 0, \sum_Z q(Z) = 1$

# EM: Another Derivation

- Given the observed variables  $X$ , latent variables  $Z$ , and parameters  $\theta$ :

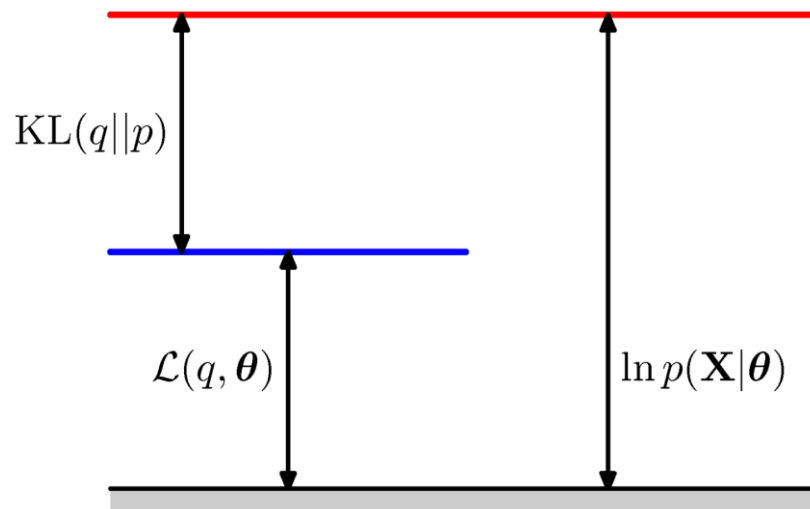
$$\begin{aligned}\log p(X|\theta) &= \log \sum_Z p(X, Z|\theta) \\ &= \log \sum_Z q(Z) \frac{p(X, Z|\theta)}{q(Z)} \\ &\geq \sum_Z q(Z) \log \frac{p(X, Z|\theta)}{q(Z)} = \mathcal{L}(q, \theta)\end{aligned}$$

- Jensen's inequality
- Equality holds when  $p(X, Z|\theta)/q(Z)$  is constant.

# EM: Visualizing Decompositions

$$\log p(X|\theta) = \mathcal{L}(q, \theta) + KL(q(Z)||p(Z|X))$$

- $KL(q||p) \geq 0$ ; equality holds only when  $q = p$ .
- Thus,  $\mathcal{L}(q, \theta)$  is the lower bound of  $\log p(X|\theta)$ , which EM maximizes.



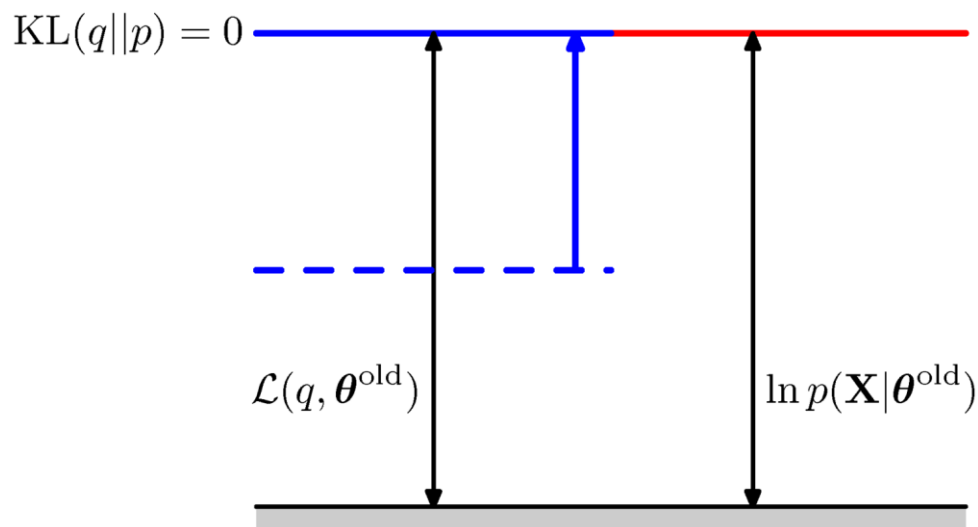


# EM: Visualizing Decompositions

$$\log p(X|\theta) = \mathcal{L}(q, \theta) + KL(q(Z)||p(Z|X))$$

- **E-Step** updates  $q(Z)$  to maximize  $\mathcal{L}(q, \theta)$ .
- $q(Z)$  is maximized when  $KL(q(Z)||p(Z|X)) = 0$

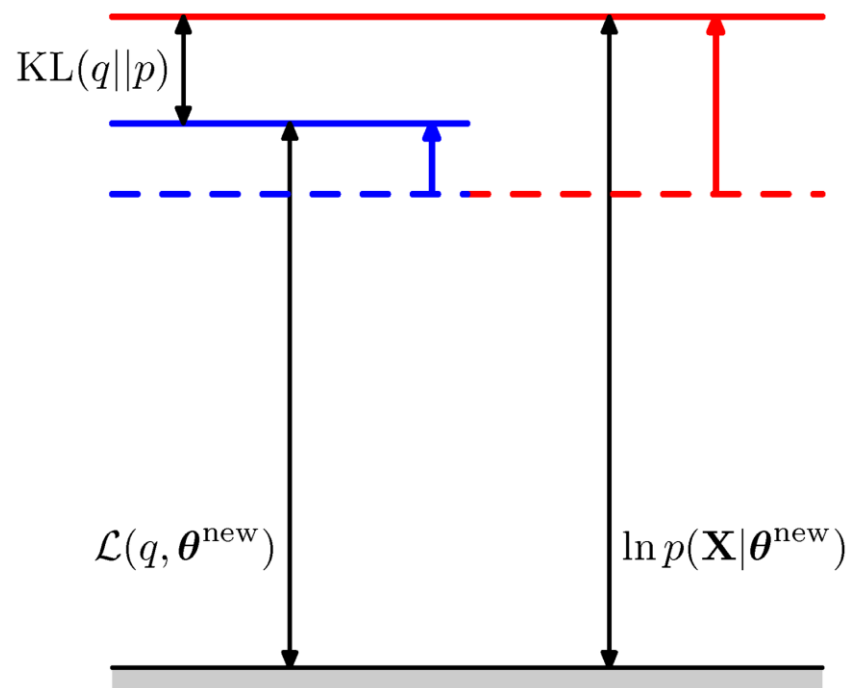
$$q(Z) = p(Z|X, \theta)$$



# EM: Visualizing Decompositions

$$\log p(X|\theta) = \mathcal{L}(q, \theta) + KL(q(Z)||p(Z|X))$$

- **M-Step:** Increase  $\mathcal{L}(q, \theta)$  with  $q(Z)$  as constant
  - This increases  $\log p(X|\theta)$ , but then  $q(Z) \neq p(Z|X, \theta)$
- Iterate EM until converged



# Next: Dimensionality Reduction