Introduction

Deep Learning

Deep Neural Networks

Deep Structural Learning

Deep Belief Networks

DL is providing breakthrough results in speech recognition and image classification …

From this Hinton et al 2012 paper:
http://static.googleusercontent.com/media/research.google.com/en//pubs/archive/38131.pdf

modeling technique	#params [10^6]	WER Hub5'00-SWB	WER RT03S-FSH
GMM, 40 mix DT 309h SI	29.4	23.6	27.4
NN 1 hidden-layer×4634 units	43.6	26.0	29.4
+ 2×5 neighboring frames	45.1	22.4	25.7
DBN-DNN 7 hidden layers×2048 units	45.1	17.1	19.6
+ updated state alignment	45.1	16.4	18.6
+ sparsification	15.2 nz	16.1	18.5
GMM 72 mix DT 2000h SA	102.4	17.1	18.6

task	hours of training data	DNN-HMM	GMM-HMM with same data	GMM-HMM with more data
Switchboard (test set 1)	309	18.5	27.4	18.6 (2000 hrs)
Switchboard (test set 2)	309	16.1	23.6	17.1 (2000 hrs)
English Broadcast News	50	17.5	18.8	
Bing Voice Search (Sentence error rates)	24	30.4	36.2	
Google Voice Input	5,870	12.3		16.0 (>>5,870hrs)
Youtube	1,400	47.6	52.3	

go here: http://yann.lecun.com/exdb/mnist/

From here:
http://people.idsia.ch/~juergen/cvpr2012.pdf

Dataset	Best result of others [%]	MCDNN [%]	Relative improv. [%]
MNIST	0.39	0.23	41
NIST SD 19	see Table 4	see Table 4	30-80
HWDB1.0 on.	7.61	5.61	26
HWDB1.0 off.	10.01	6.5	35
CIFAR10	18.50	11.21	39
traffic signs	1.69	0.54	72
NORB	5.00	2.70	46

So, 1. **what exactly is deep learning** ?

And, 2. **why is it generally better** than other methods on image, speech and certain other types of data?

So, 1. **what exactly is deep learning** ?

And, 2. **why is it generally better** than other methods on image, speech and certain other types of data?

The short answers

1. **'Deep Learning' means** using a **neural network** with **several layers of nodes** between input and output

2. **the series of layers between input & output do feature identification and processing in a series of stages, just as our brains seem to.**

hmmm… OK, but:

3. **multilayer neural networks have been around for 25 years. What's actually new?**

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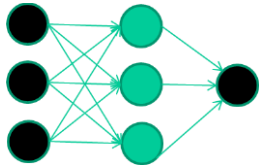
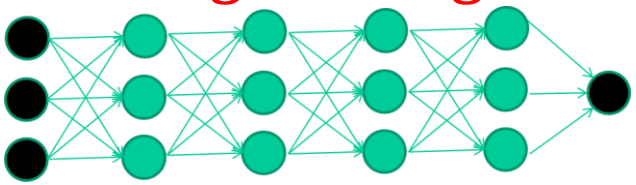
3. **multilayer neural networks have been around for 25 years. What's actually new?**

we have always had good algorithms for learning the weights in networks with 1 hidden layer



but these algorithms are not good at learning the weights for networks with more hidden layers

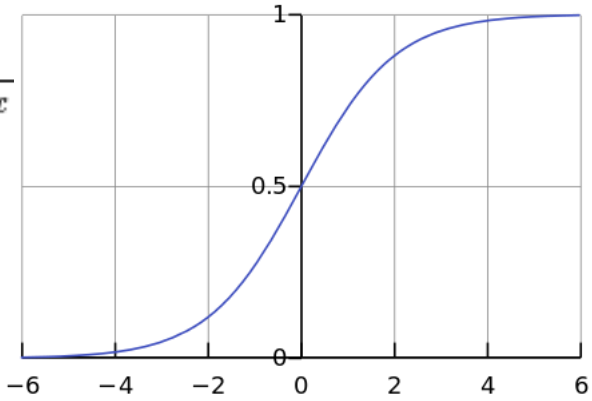


what's new is: **<u>algorithms for training many-later networks</u>**

longer answers

1. reminder/quick-explanation of how neural network weights are learned;
2. the idea of **unsupervised feature learning** (why 'intermediate features' are important for difficult classification tasks, and how NNs seem to naturally learn them)
3. The 'breakthrough' – the simple trick for training Deep neural networks

$$f(x) = \frac{1}{1 + e^{-x}}$$



-0.06

W1

-2.5

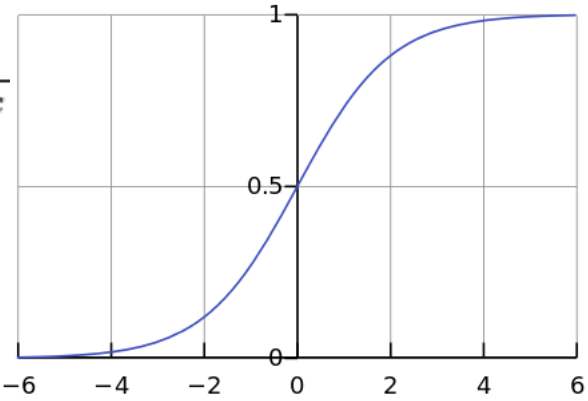
W2

W3

1.4

***f*(x)**

$$f(x) = \frac{1}{1 + e^{-x}}$$



-0.06

2.7

-2.5

-8.6

0.002

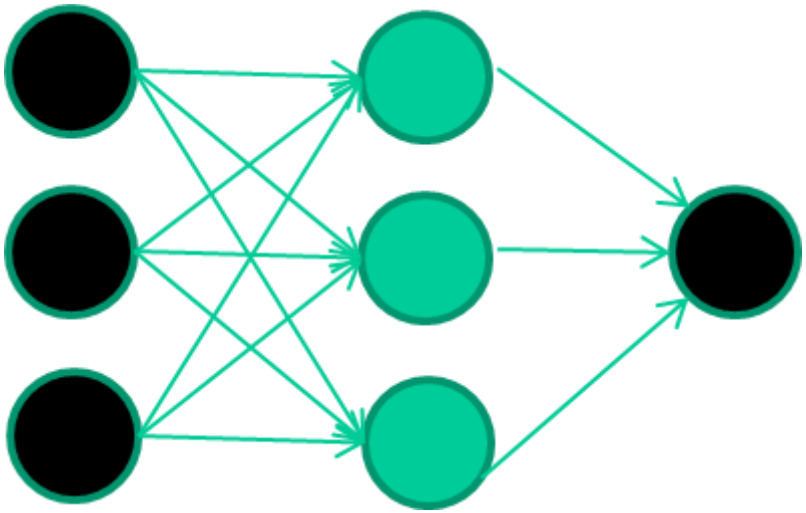
1.4

$f(x)$

x = -0.06×2.7 + 2.5×8.6 + 1.4×0.002 = 21.34

A dataset

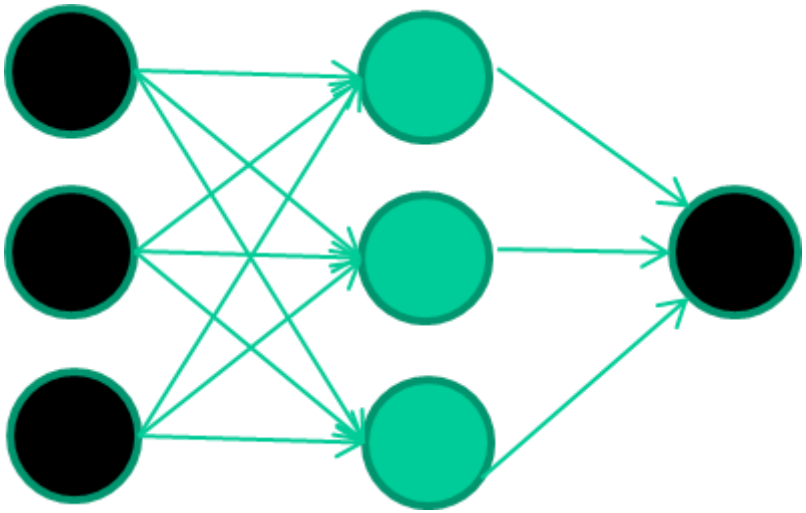
Fields			***class***
1.4	2.7	1.9	0
3.8	3.4	3.2	0
6.4	2.8	1.7	1
4.1	0.1	0.2	0
etc …			



Training the neural network

Fields			***class***
1.4	2.7	1.9	0
3.8	3.4	3.2	0
6.4	2.8	1.7	1
4.1	0.1	0.2	0

etc …



Training data

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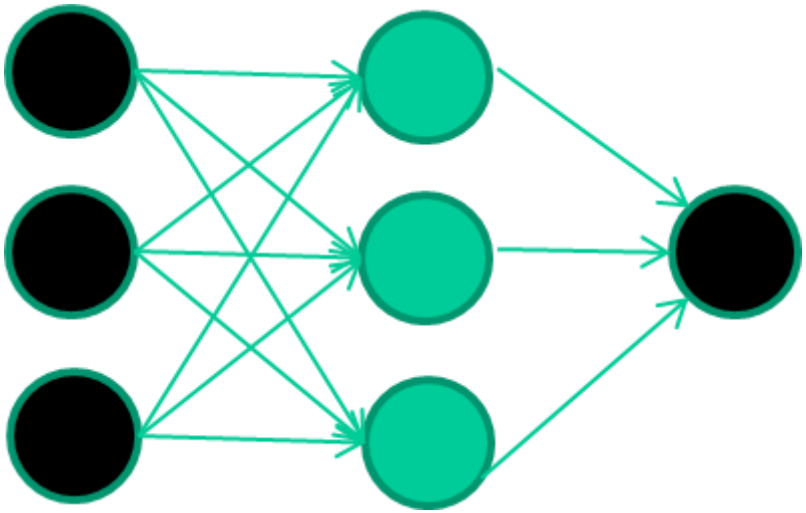
3.8	3.4	3.2	0
6.4	2.8	1.7	1
4.1	0.1	0.2	0
etc …			

Initialise with random weights



Training data

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3.8	3.4	3.2	0
6.4	2.8	1.7	1
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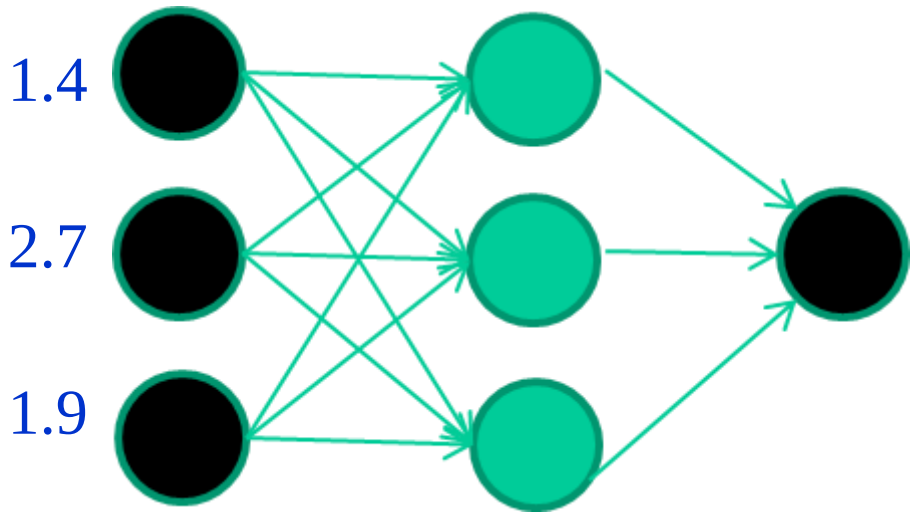
etc …			

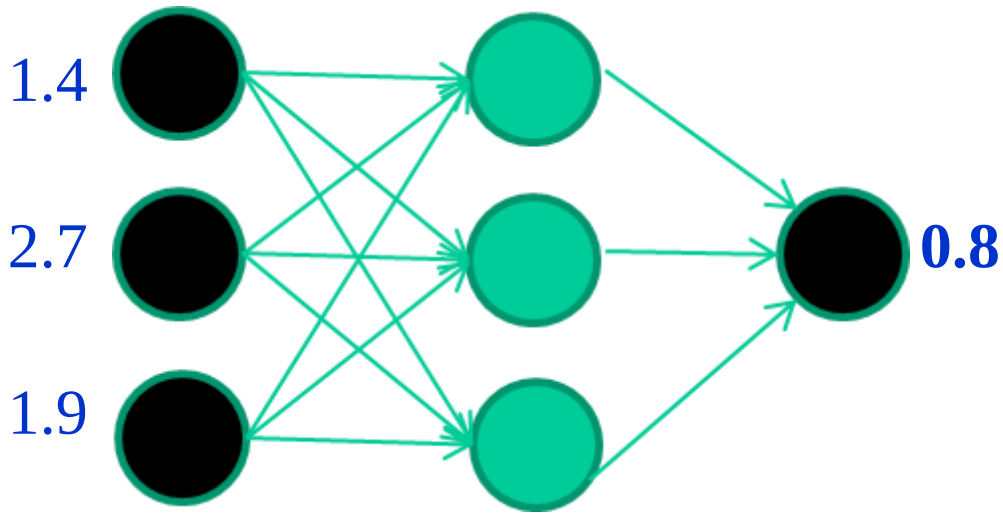
Present a training pattern



Training data

Fields			***class***
1.4	2.7	1.9	0
3.8	3.4	3.2	0
6.4	2.8	1.7	1
4.1	0.1	0.2	0
etc …			

Feed it through to get output



Training data

Fields			***class***
1.4	2.7	1.9	0
3.8	3.4	3.2	0
6.4	2.8	1.7	1
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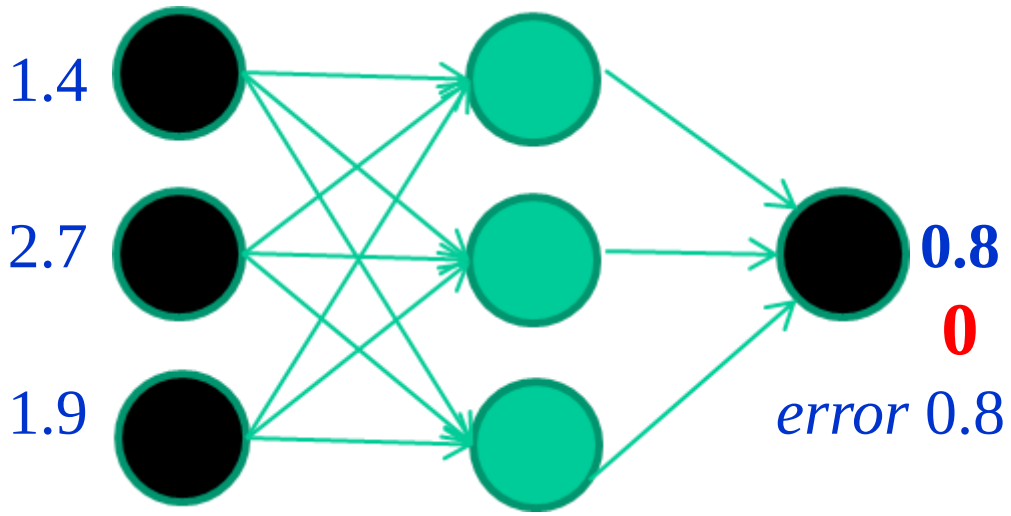
etc …

Compare with target output



Training data

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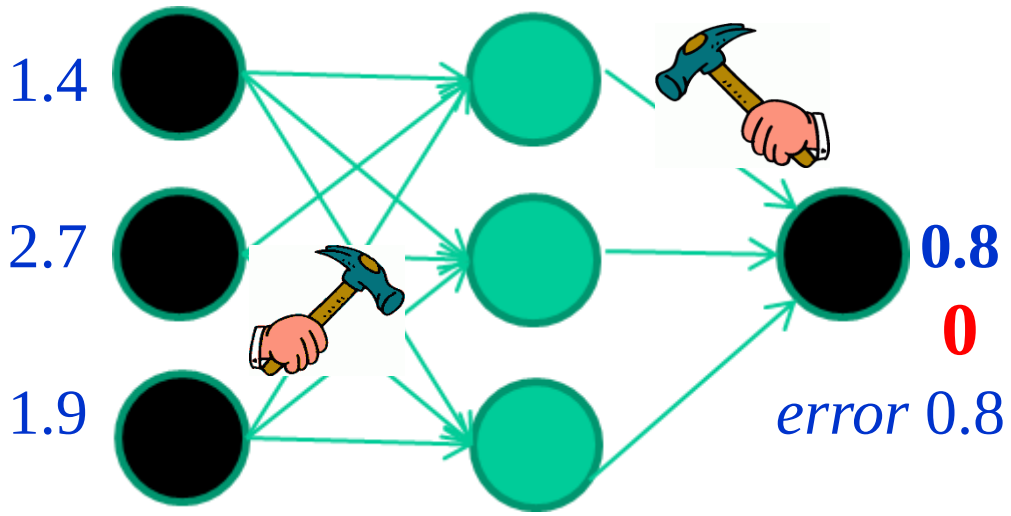
etc …			

Adjust weights based on error



Training data

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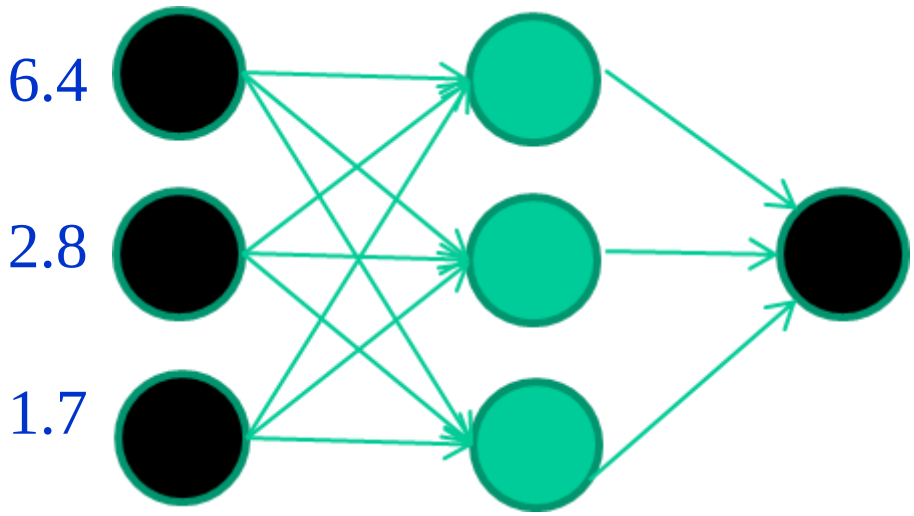
Present a training pattern



Training data

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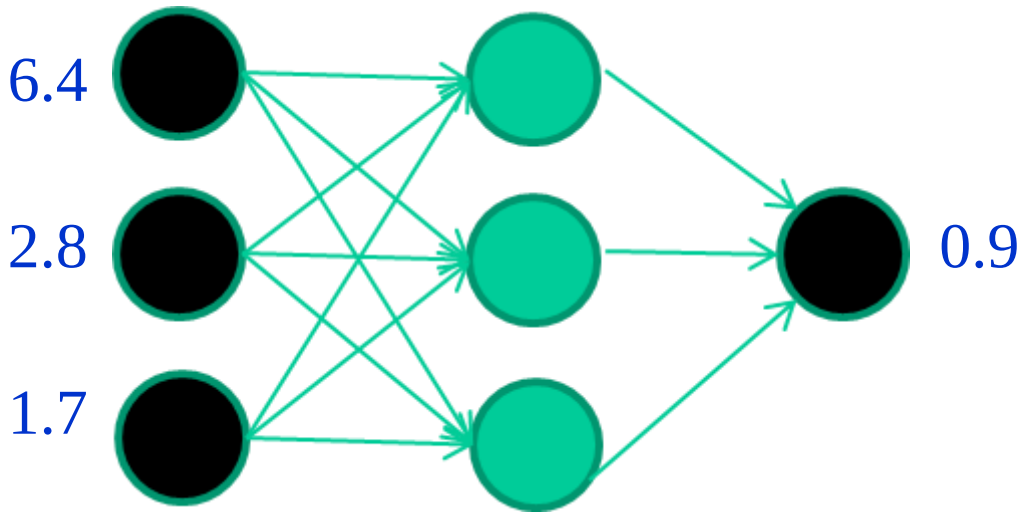
Feed it through to get output



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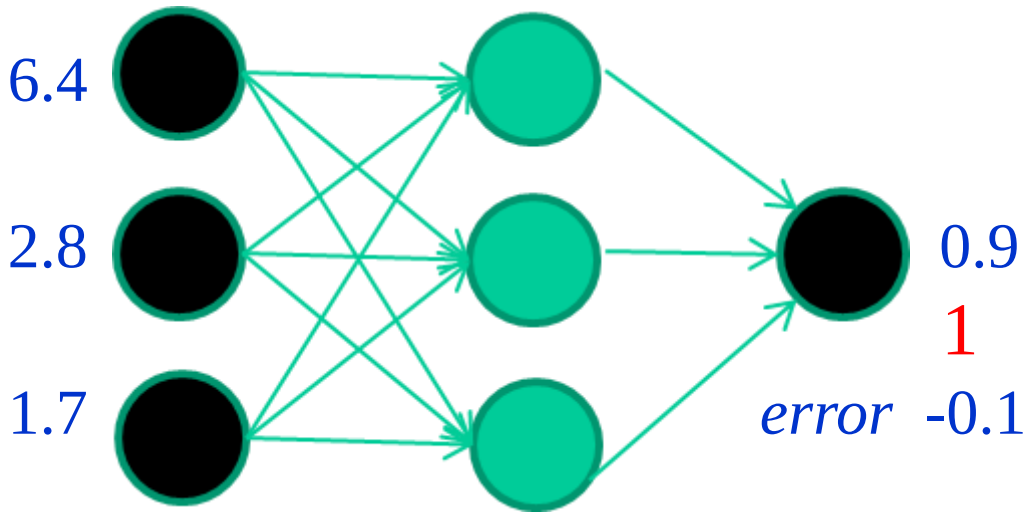
Compare with target output



Training data

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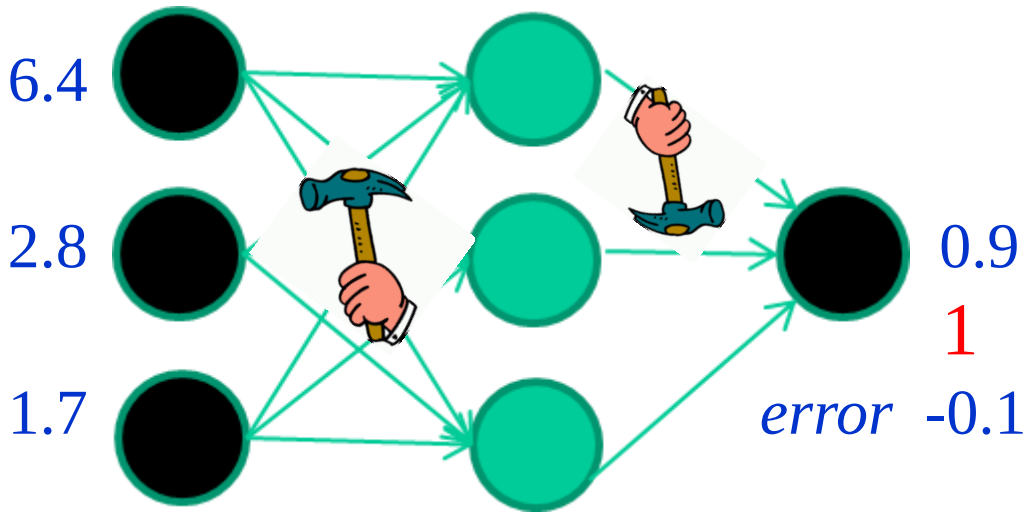

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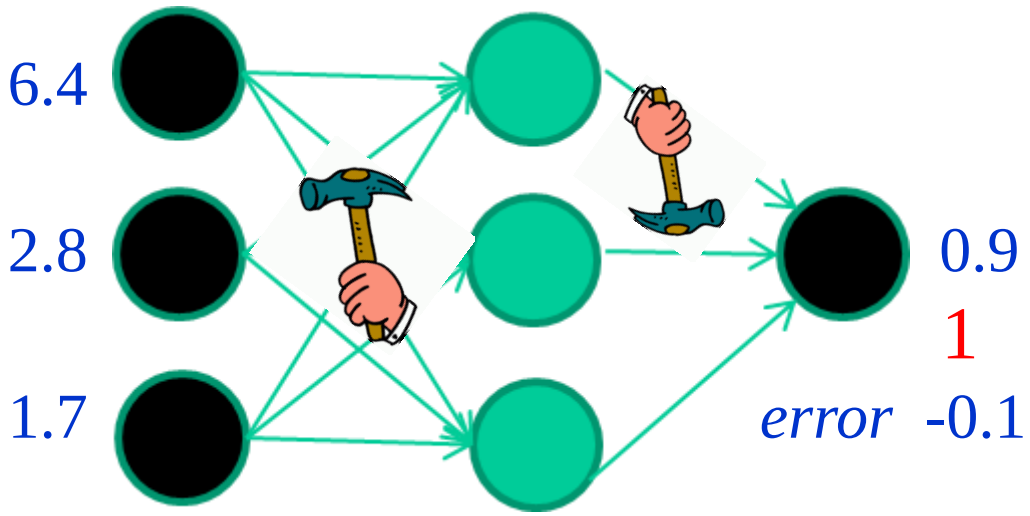
6.4	2.8	1.7	1
4.1	0.1	0.2	0

etc …

And so on ….

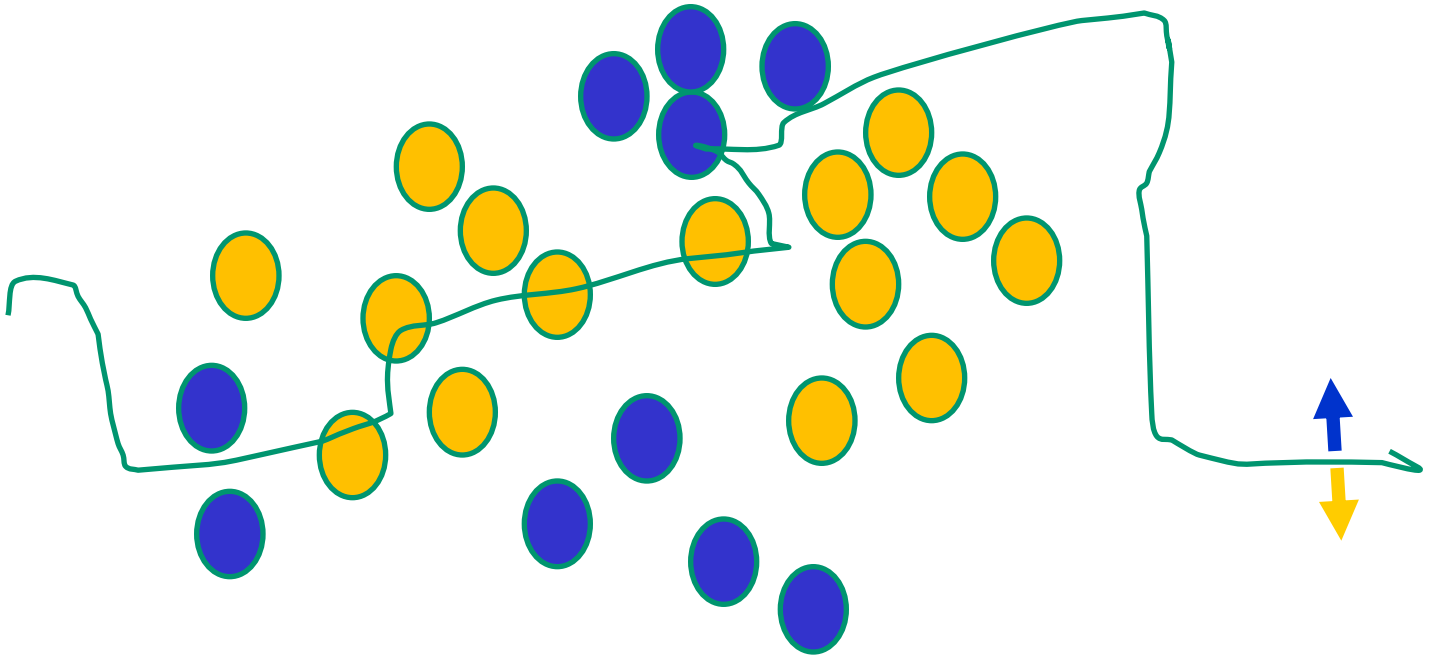


Repeat this thousands, maybe millions of times – each time taking a random training instance, and making slight weight adjustments

Algorithms for weight adjustment are designed to make changes that will reduce the error

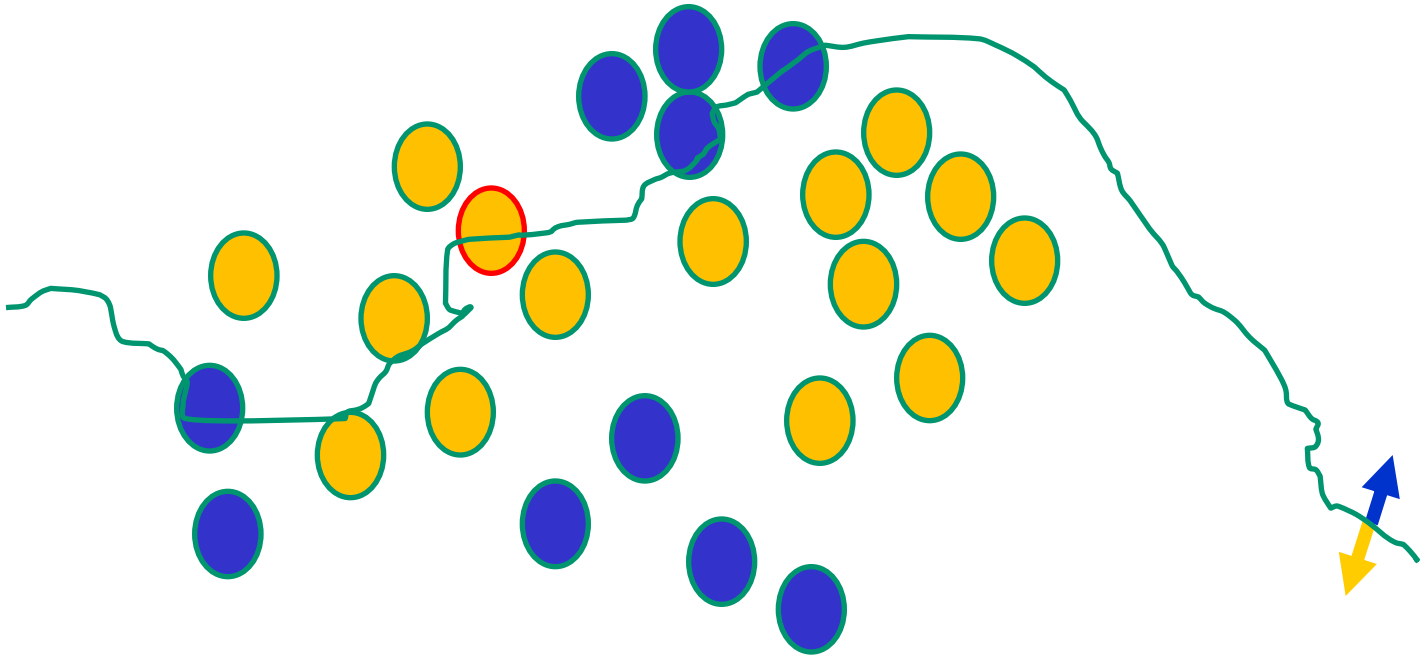
The decision boundary perspective…

Initial random weights



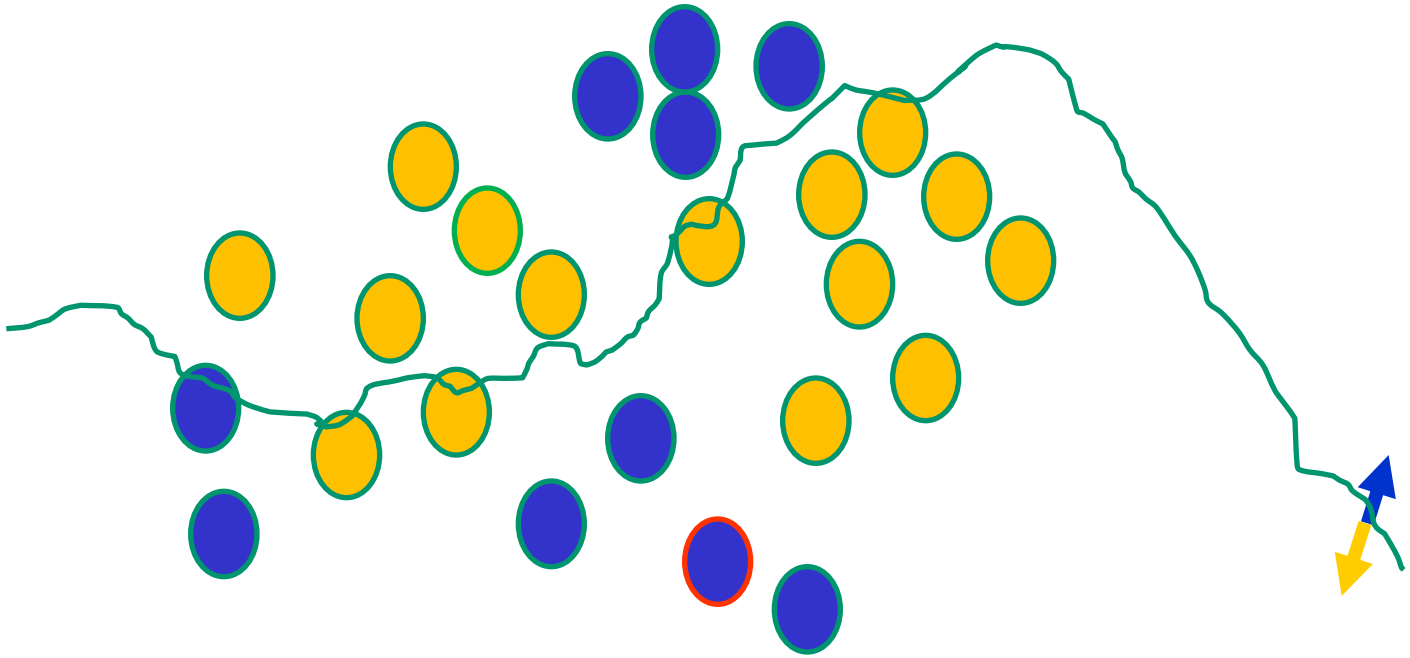
The decision boundary perspective…

Present a training instance / adjust the weights



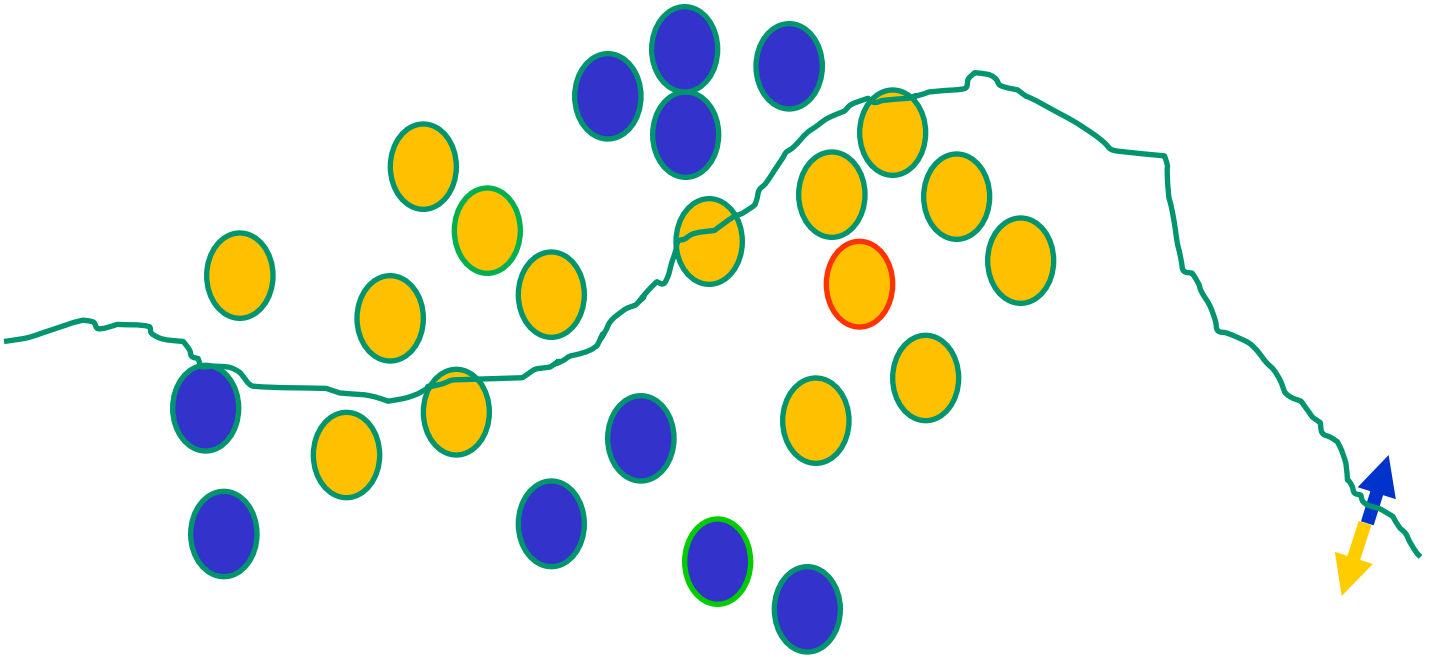
The decision boundary perspective…

Present a training instance / adjust the weights



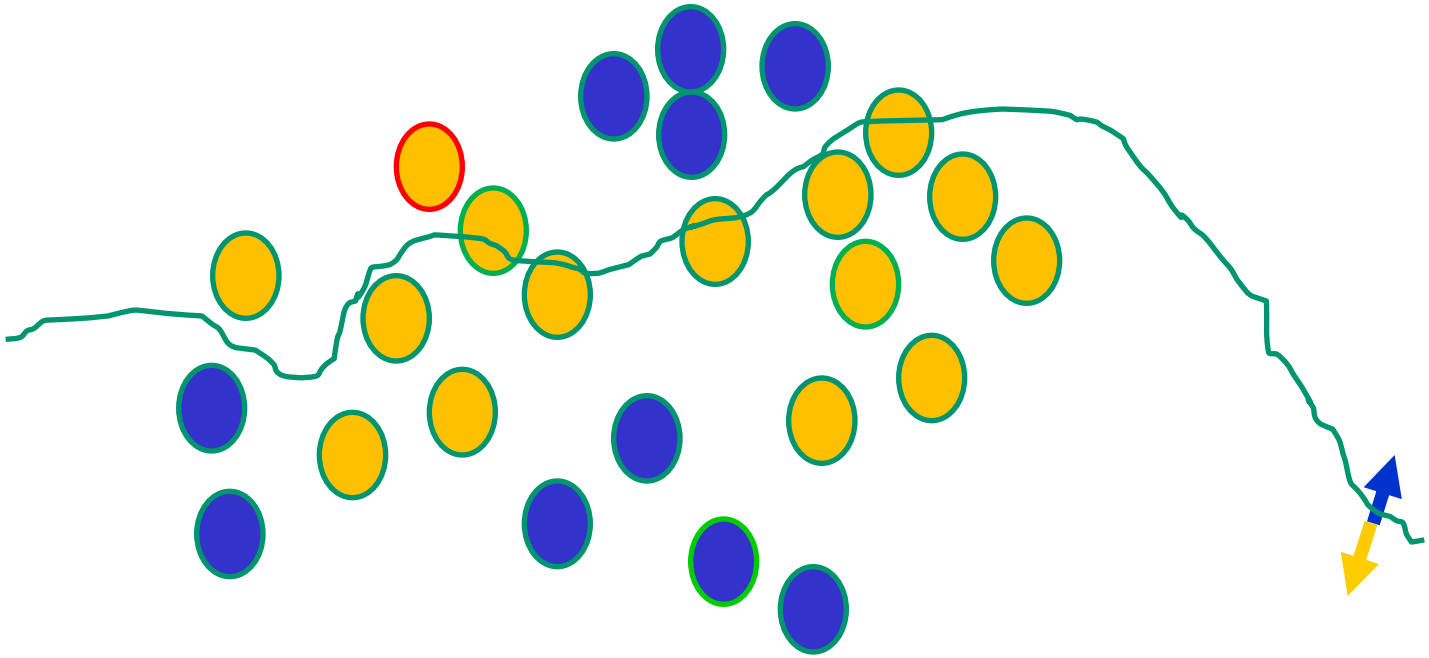
The decision boundary perspective…

Present a training instance / adjust the weights



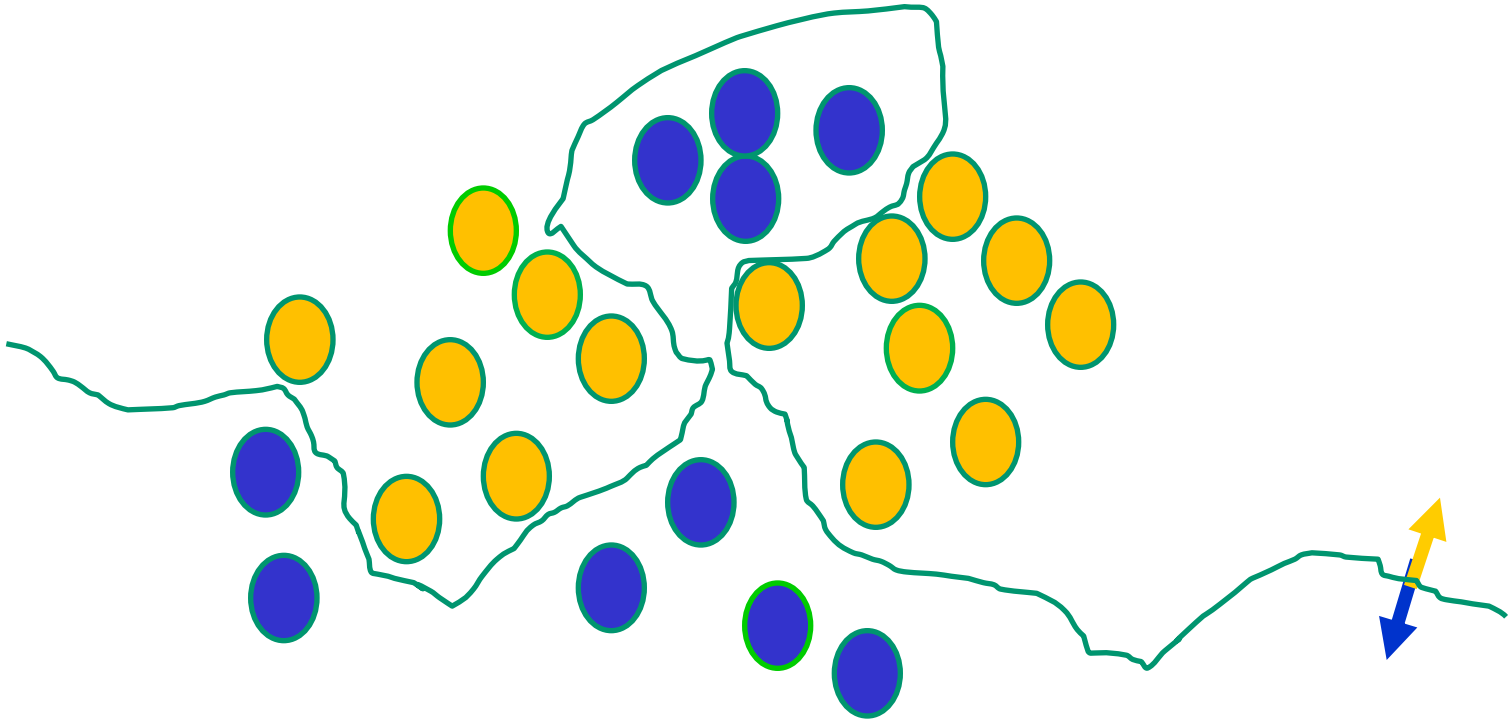
The decision boundary perspective…

Present a training instance / adjust the weights



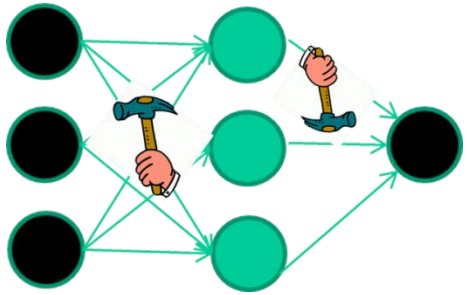
The decision boundary perspective…

Eventually ….



The point is that

- weight-learning algorithms for NNs are dumb
- they work by making thousands and thousands of tiny adjustments, each making the network do better at the most recent pattern, but perhaps a little worse on many others
- but, by dumb luck, eventually this tends to be good enough to learn effective classifiers for many real applications



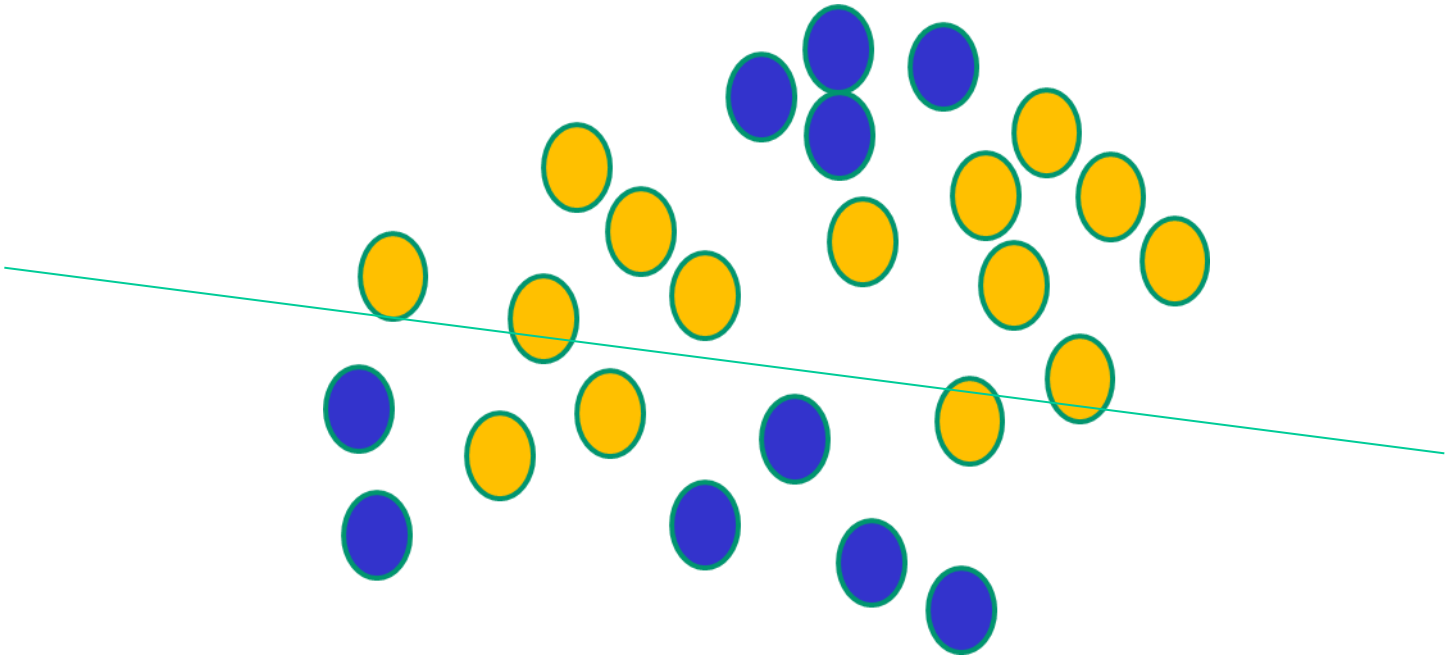
Some other points

Detail of a standard NN weight learning algorithm – **previously introduced**

If $f(x)$ is non-linear, a network with 1 hidden layer can, in theory, learn perfectly any classification problem. A set of weights exists that can produce the targets from the inputs. The problem is finding them.

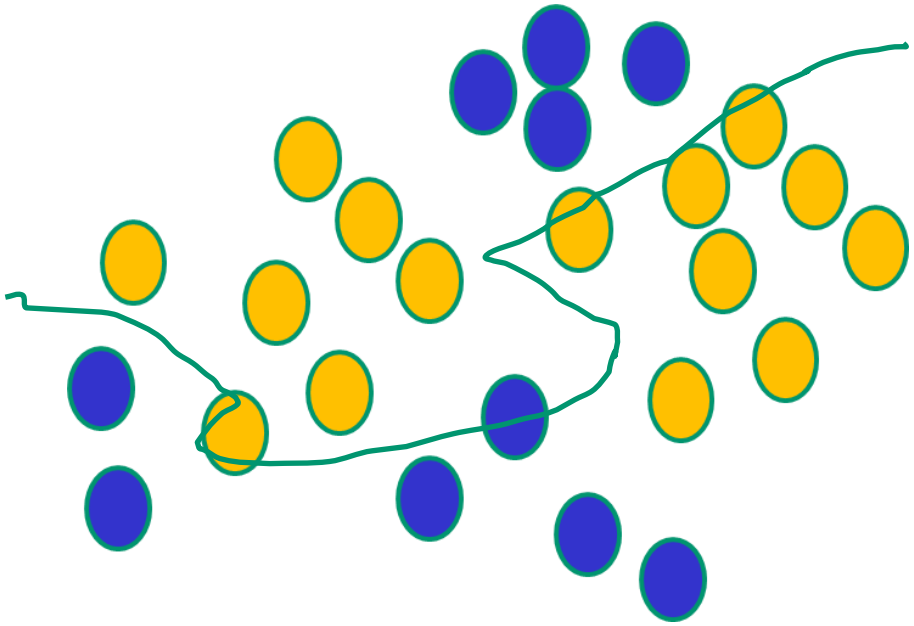
Some other ‘by the way’ points

If $f(x)$ is linear, the NN can **only** draw straight decision boundaries (even if there are many layers of units)



Some other ‘by the way’ points

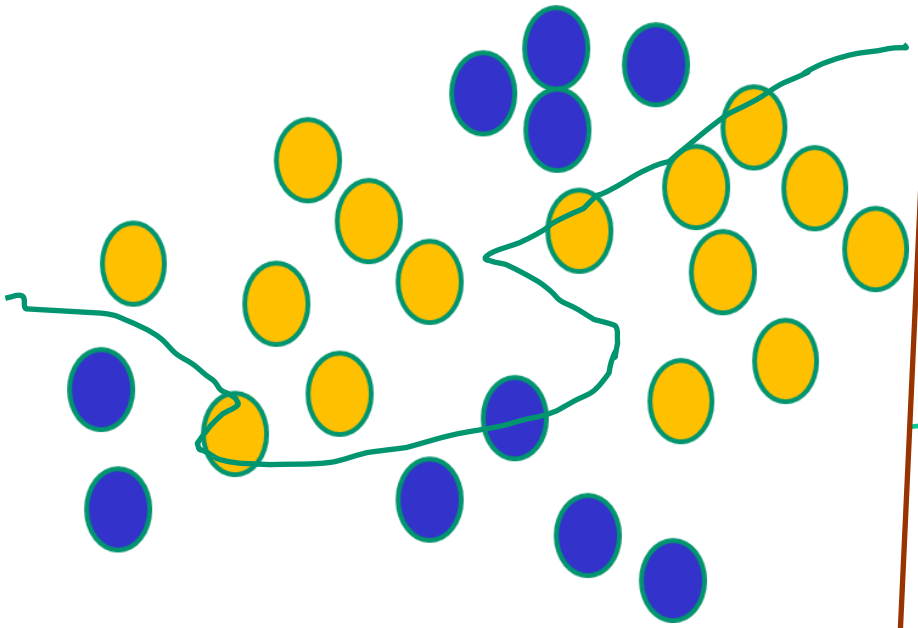
NNs use nonlinear *f*(x) so they can draw complex boundaries, but keep the data unchanged

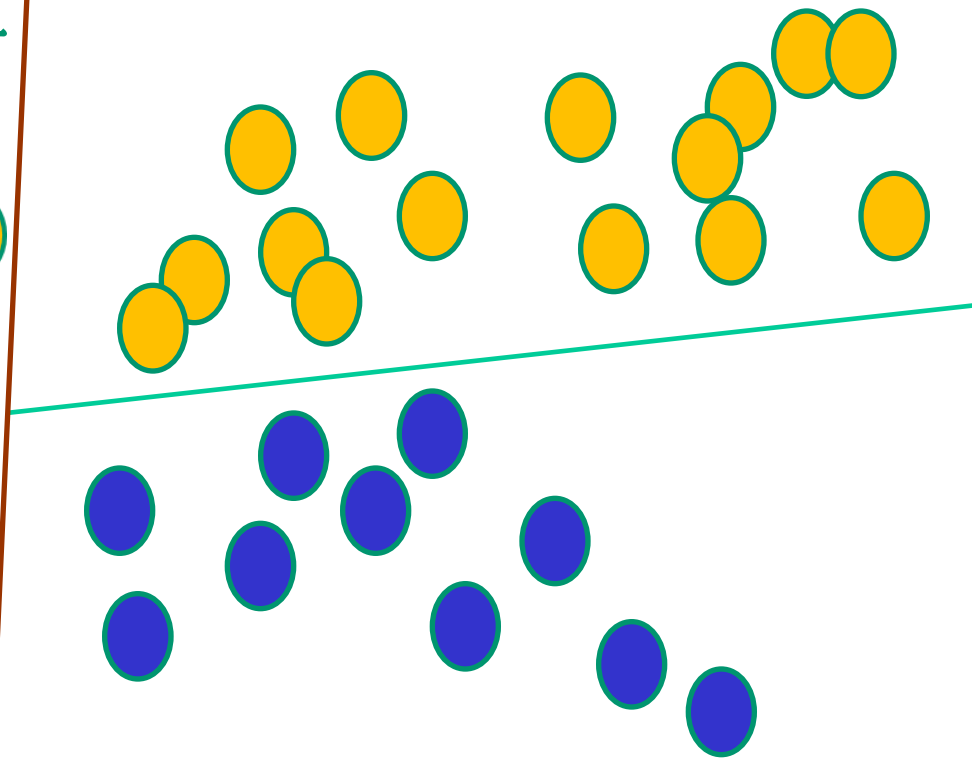


Some other ‘by the way’ points

NNs use nonlinear *f*(x) so they can draw complex boundaries, but keep the data unchanged

SVMs only draw straight lines, but they transform the data first in a way that makes that OK





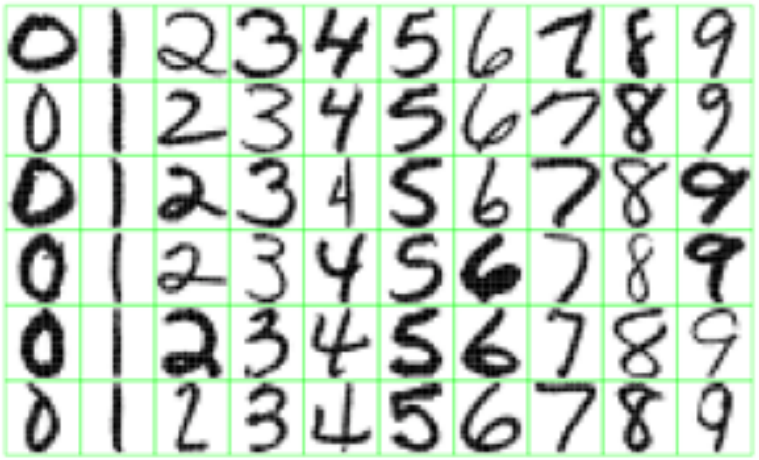
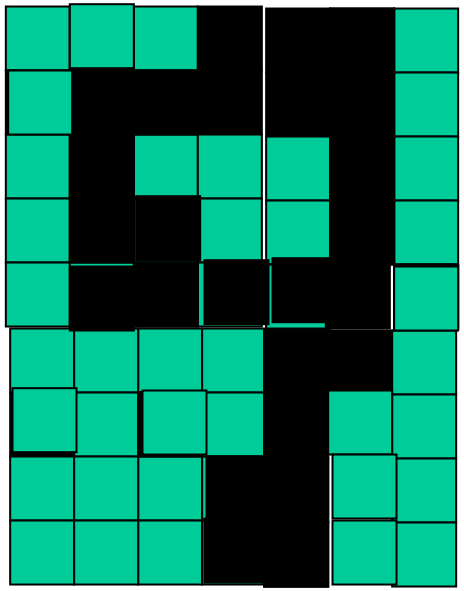
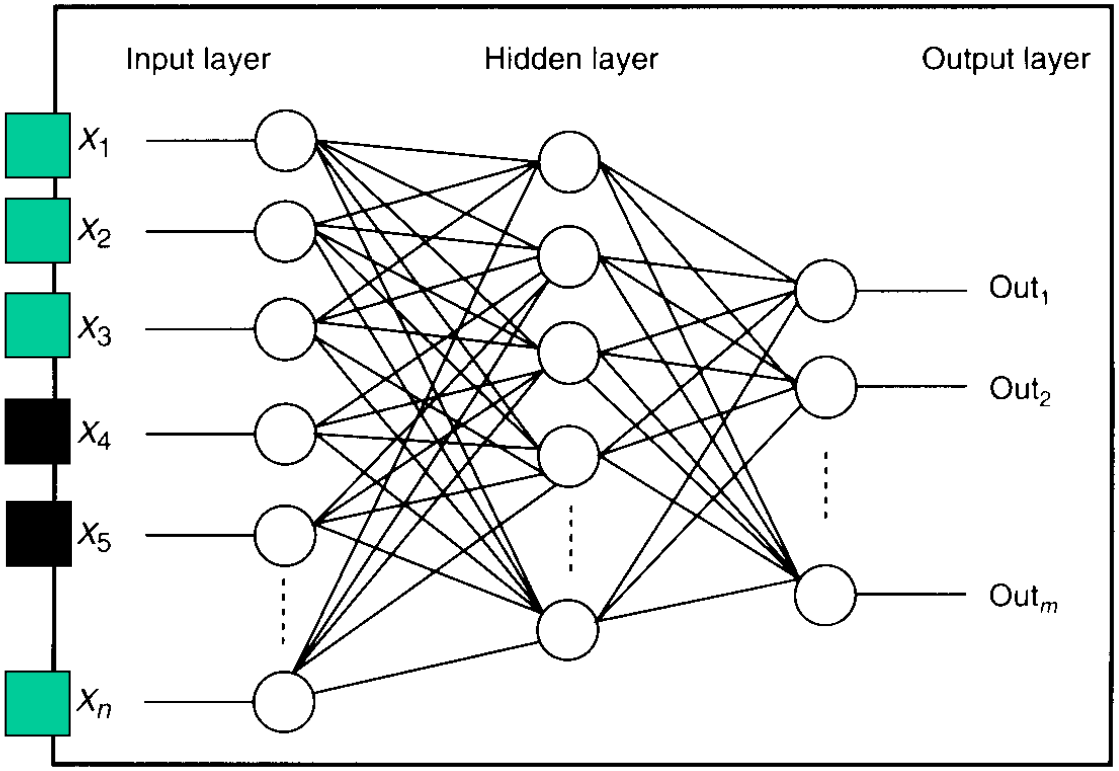


Figure 1.2: *Examples of handwritten digits from U.S. postal envelopes.*

Feature detectors





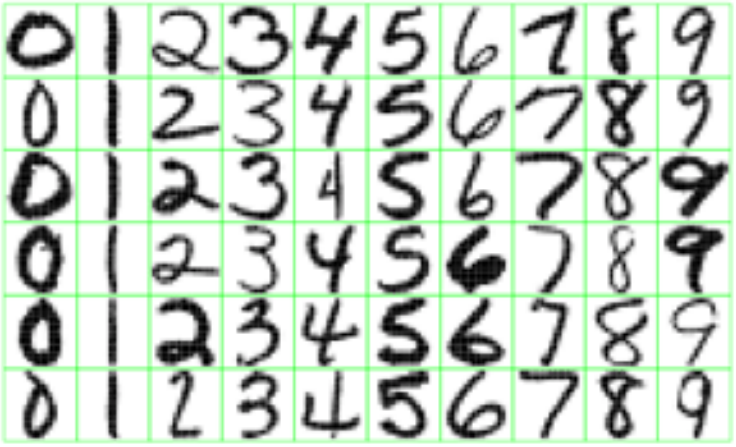
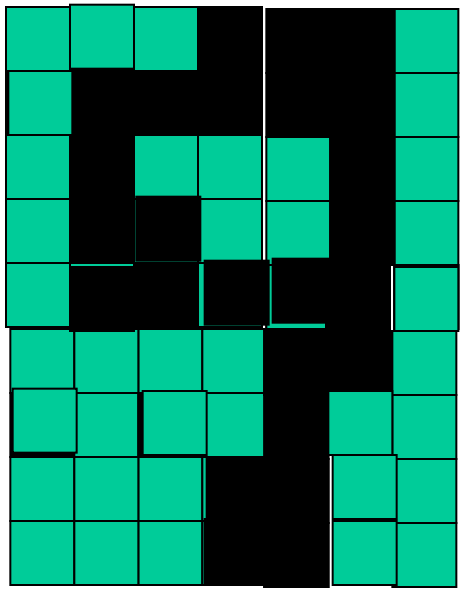
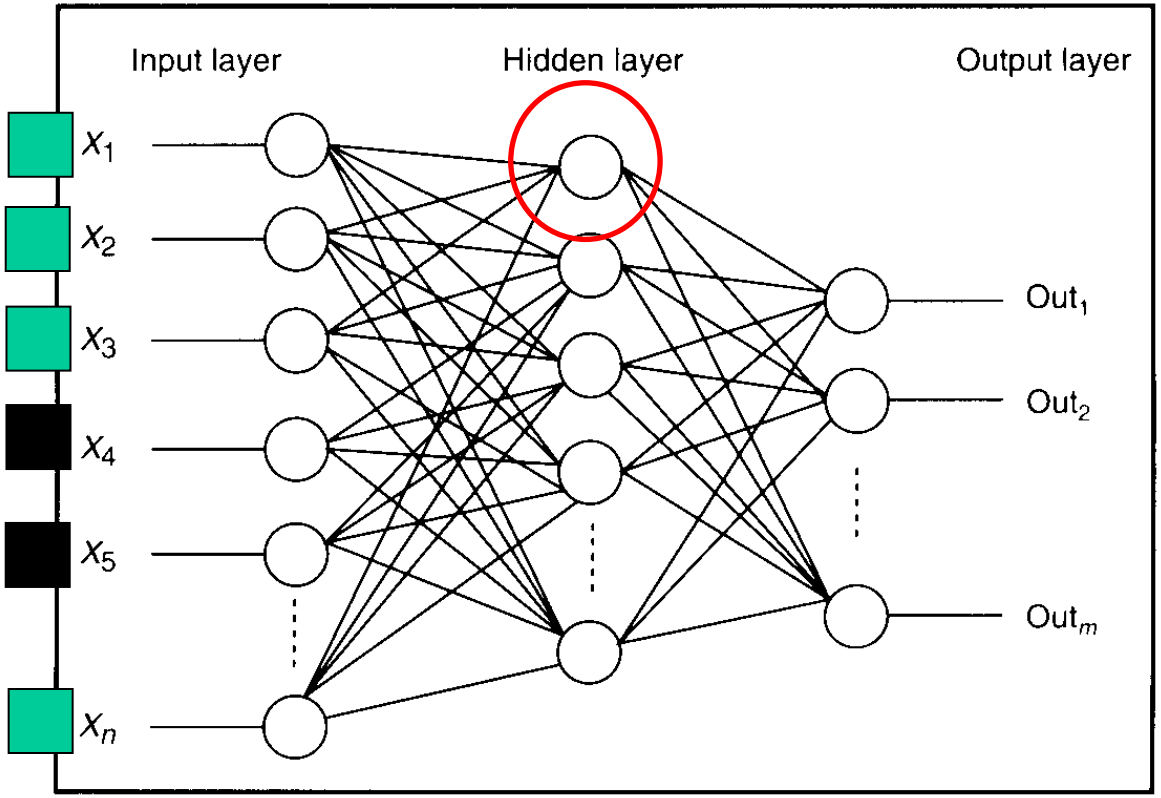


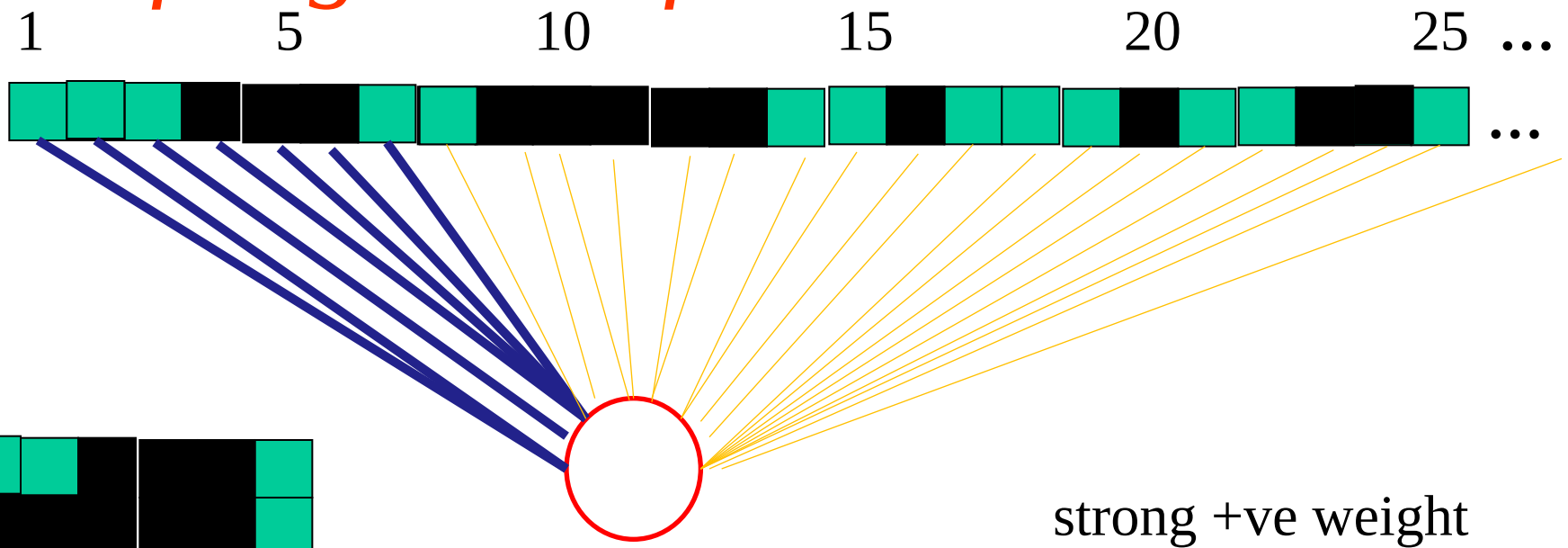
Figure 1.2: *Examples of handwritten digits from U.S. postal envelopes.*

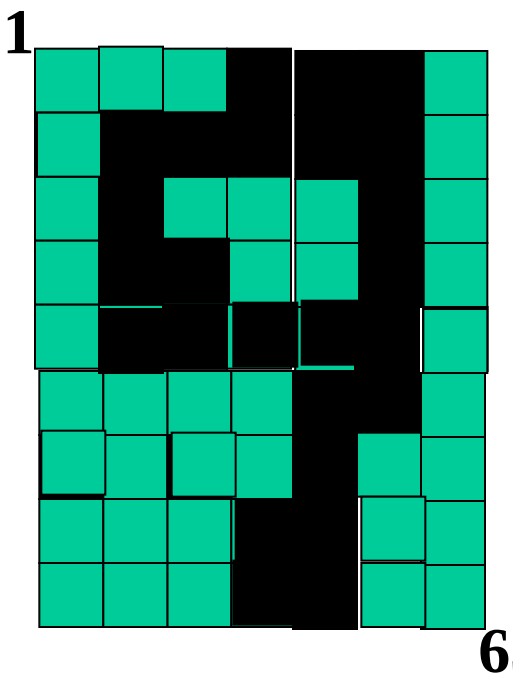
what is this unit doing?





Hidden layer units become *self-organised feature detectors*

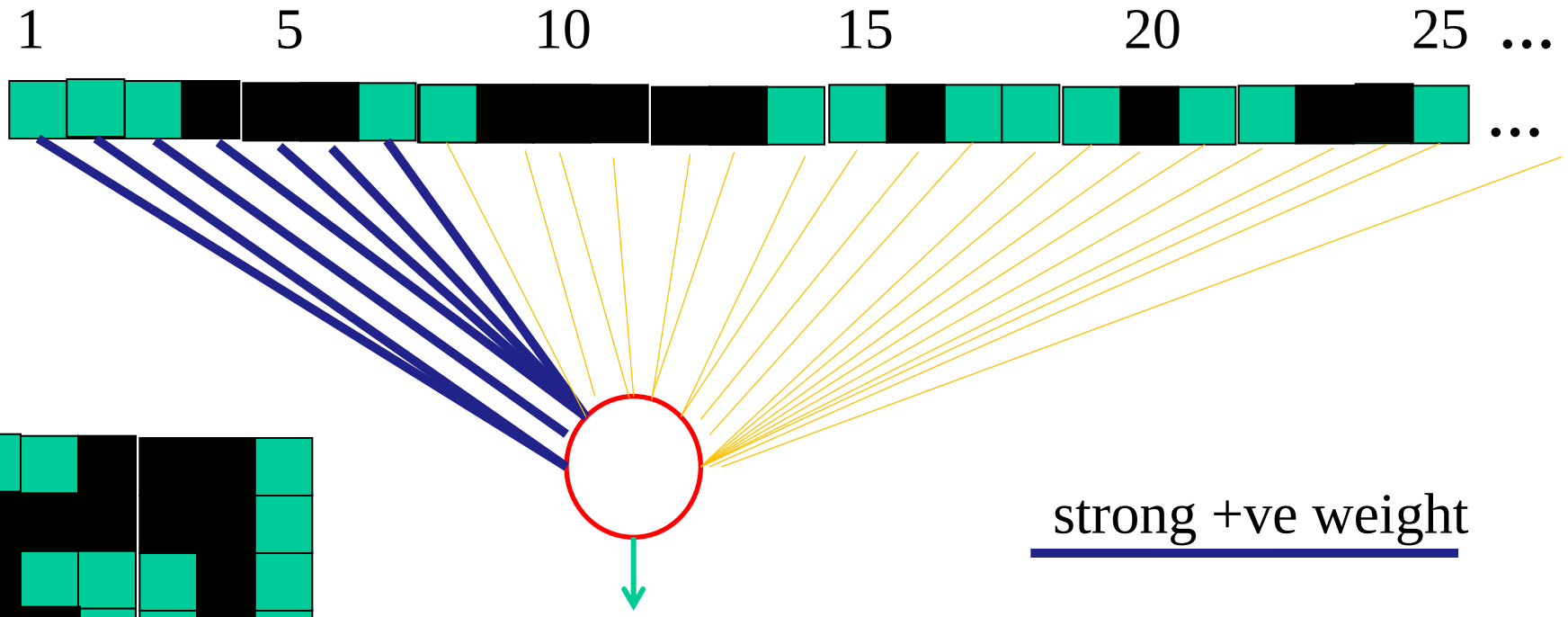


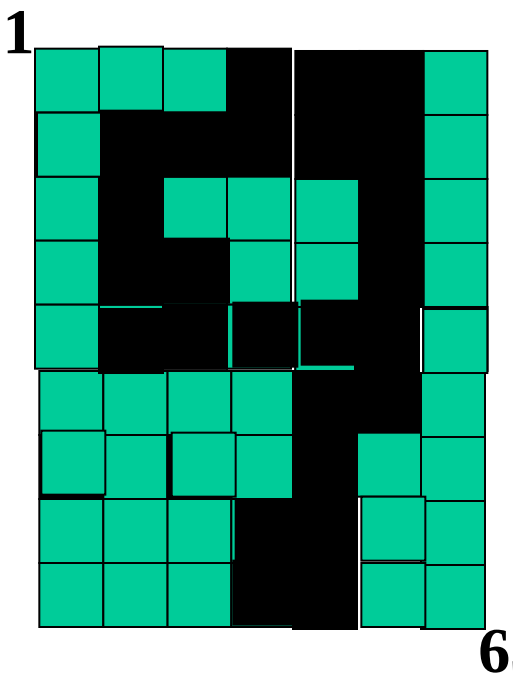


strong +ve weight

low/zero weight

What does this unit detect?

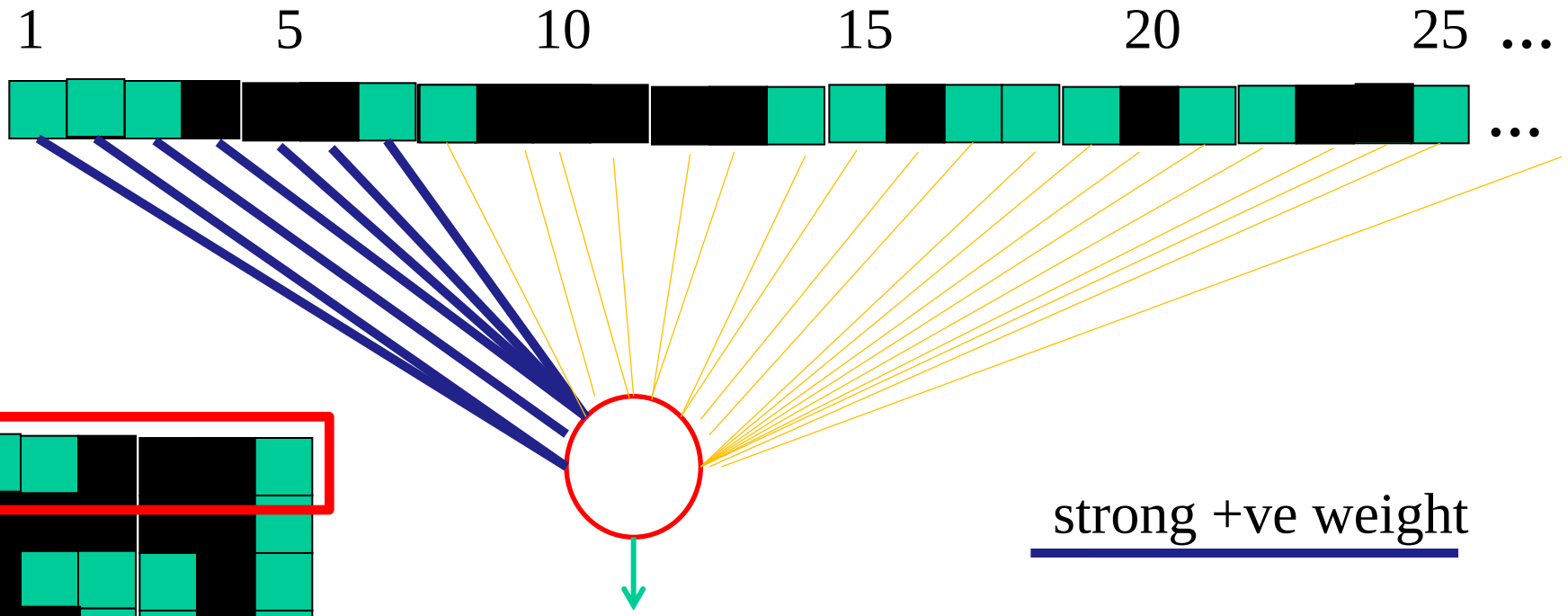


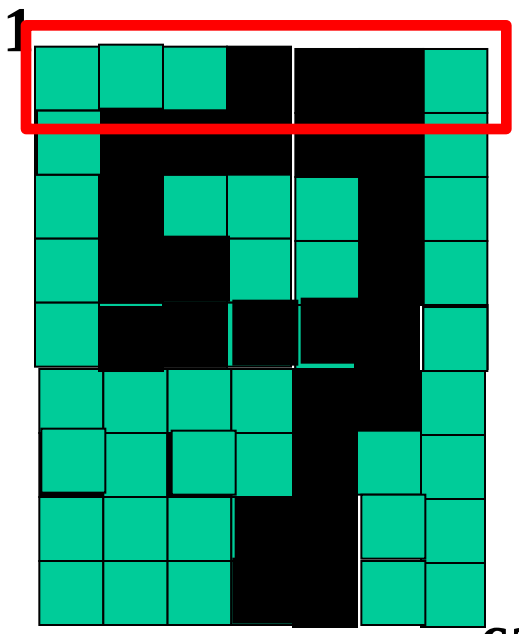


strong +ve weight

low/zero weight

What does this unit detect?



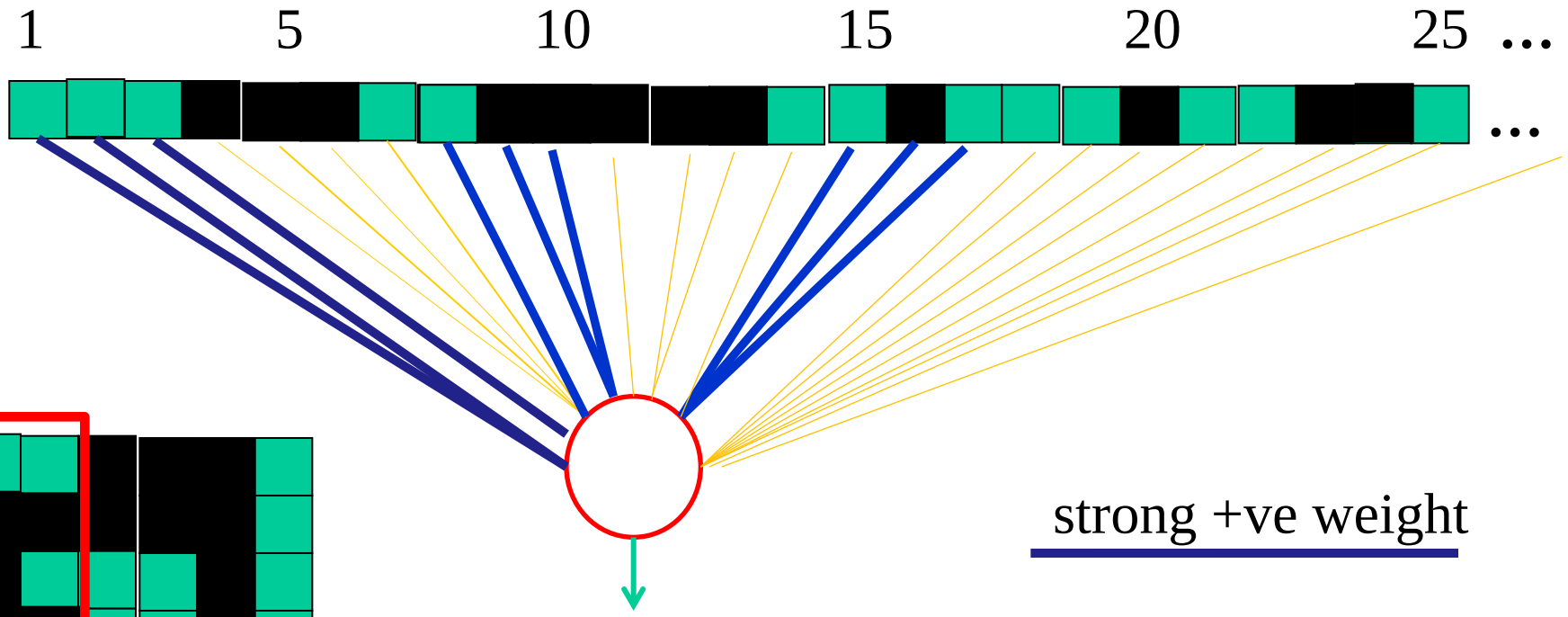


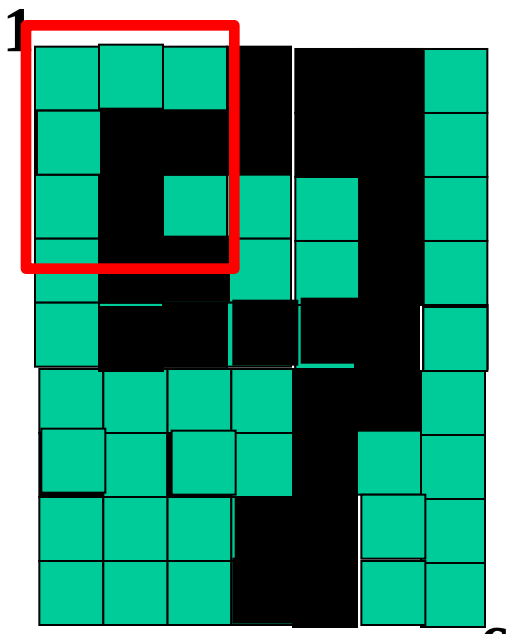
strong +ve weight

low/zero weight

it will send strong signal for a horizontal line in the top row, ignoring everywhere else

What does this unit detect?

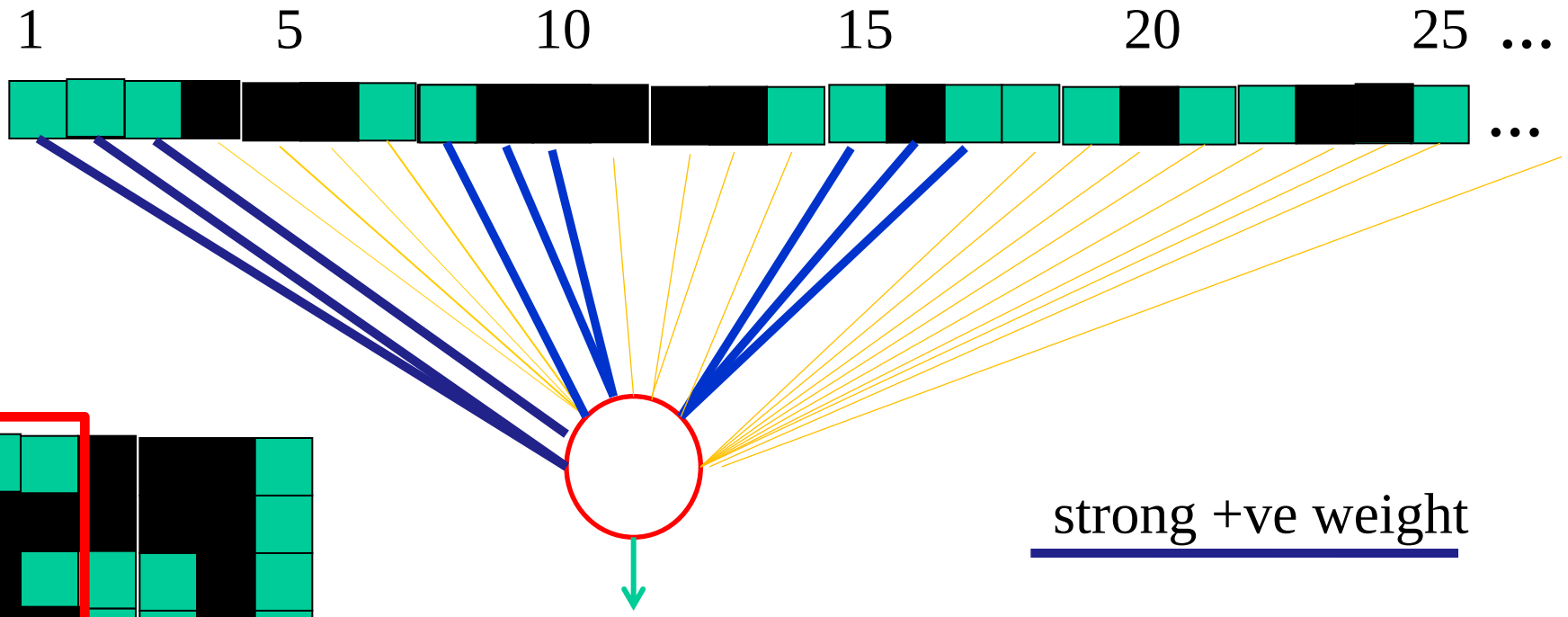


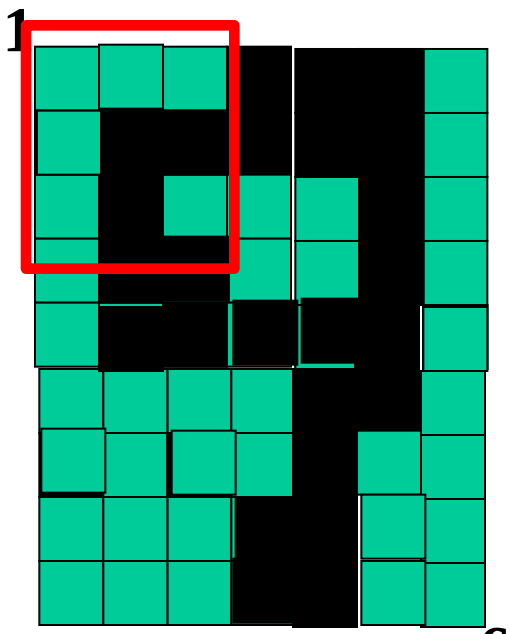


strong +ve weight

low/zero weight

What does this unit detect?





strong +ve weight

low/zero weight

Strong signal for a dark area in the top left corner

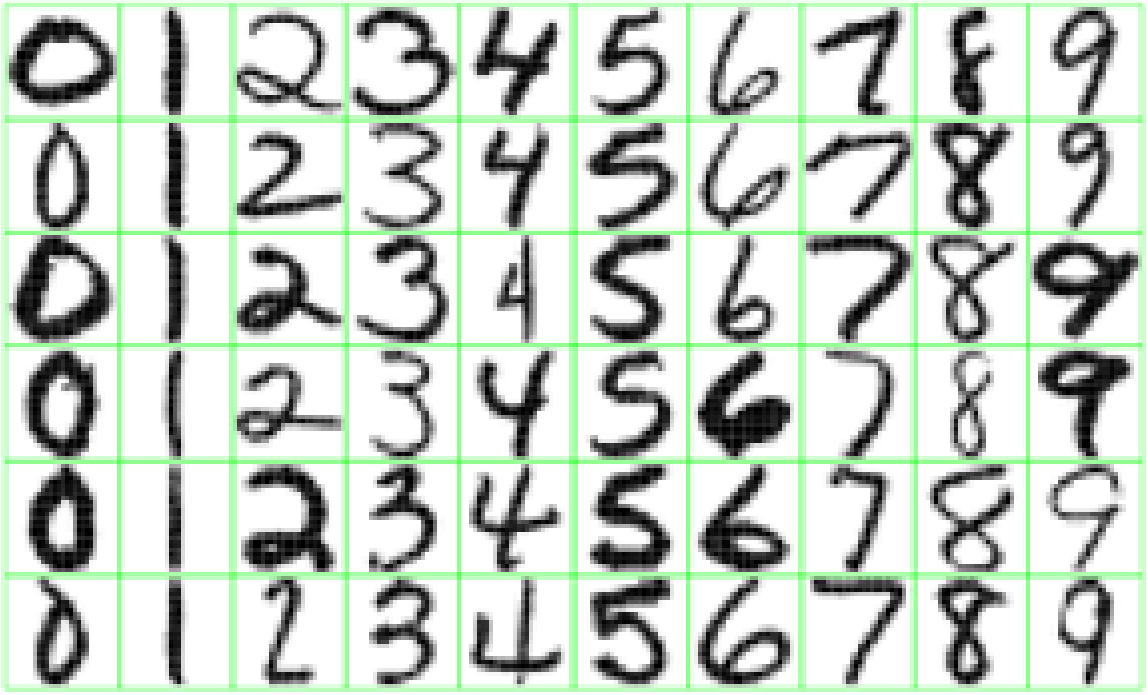
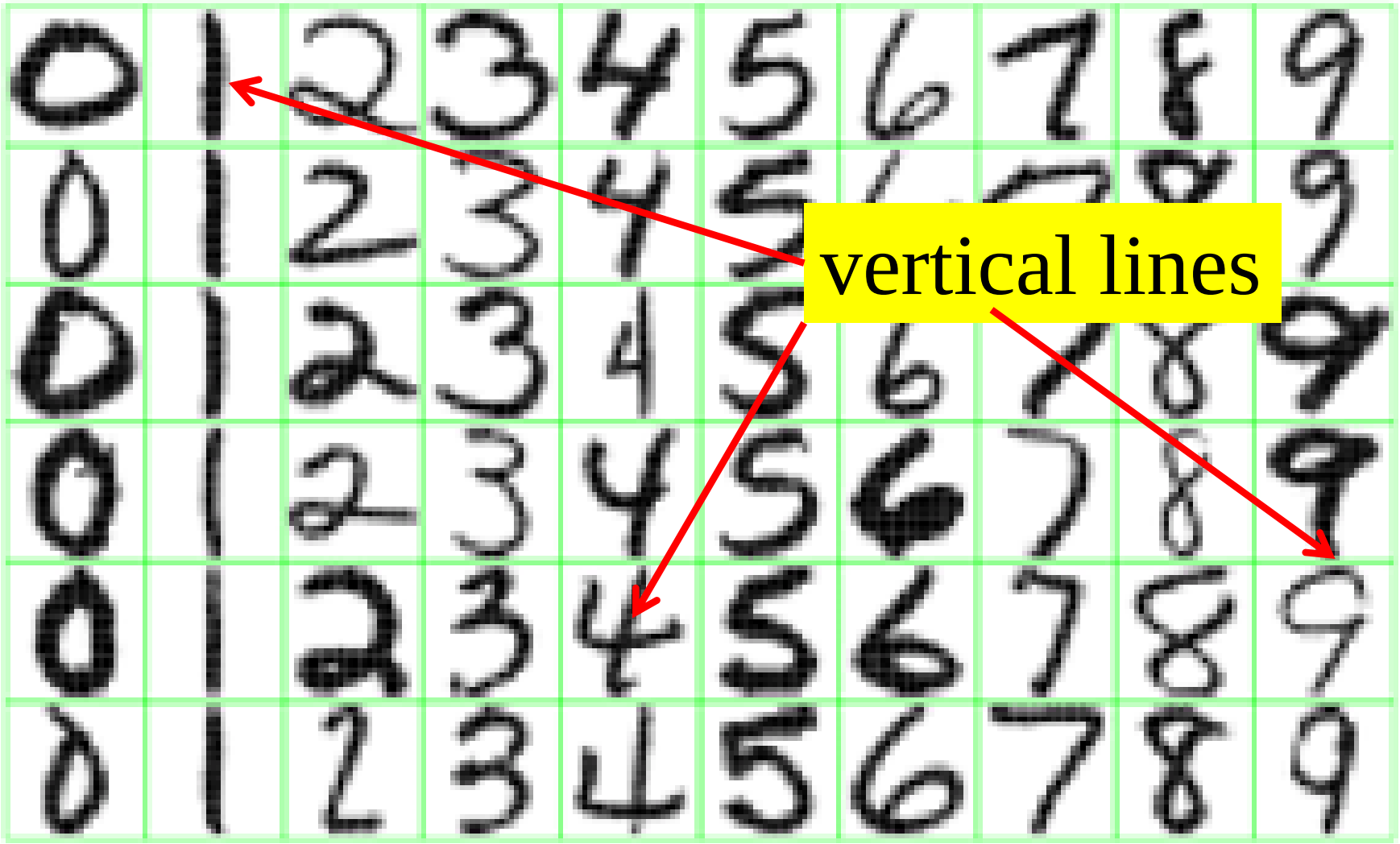


Figure 1.2: *Examples of handwritten digits from U.S. postal envelopes.*

What features might you expect a good NN to learn, when trained with data like this?



1

Figure 1.2: *Examples of handwritten digits from U.S. postal envelopes.*

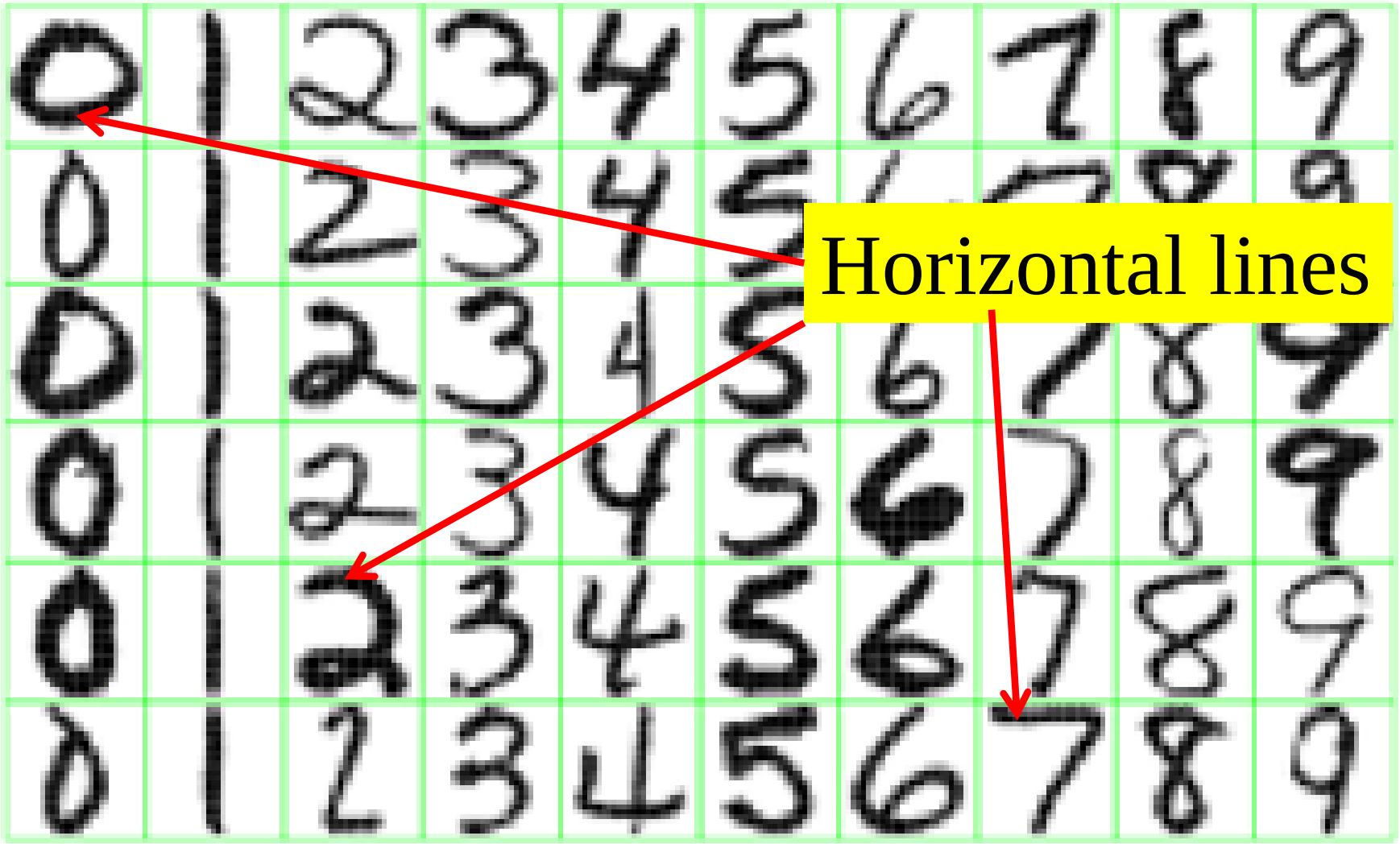
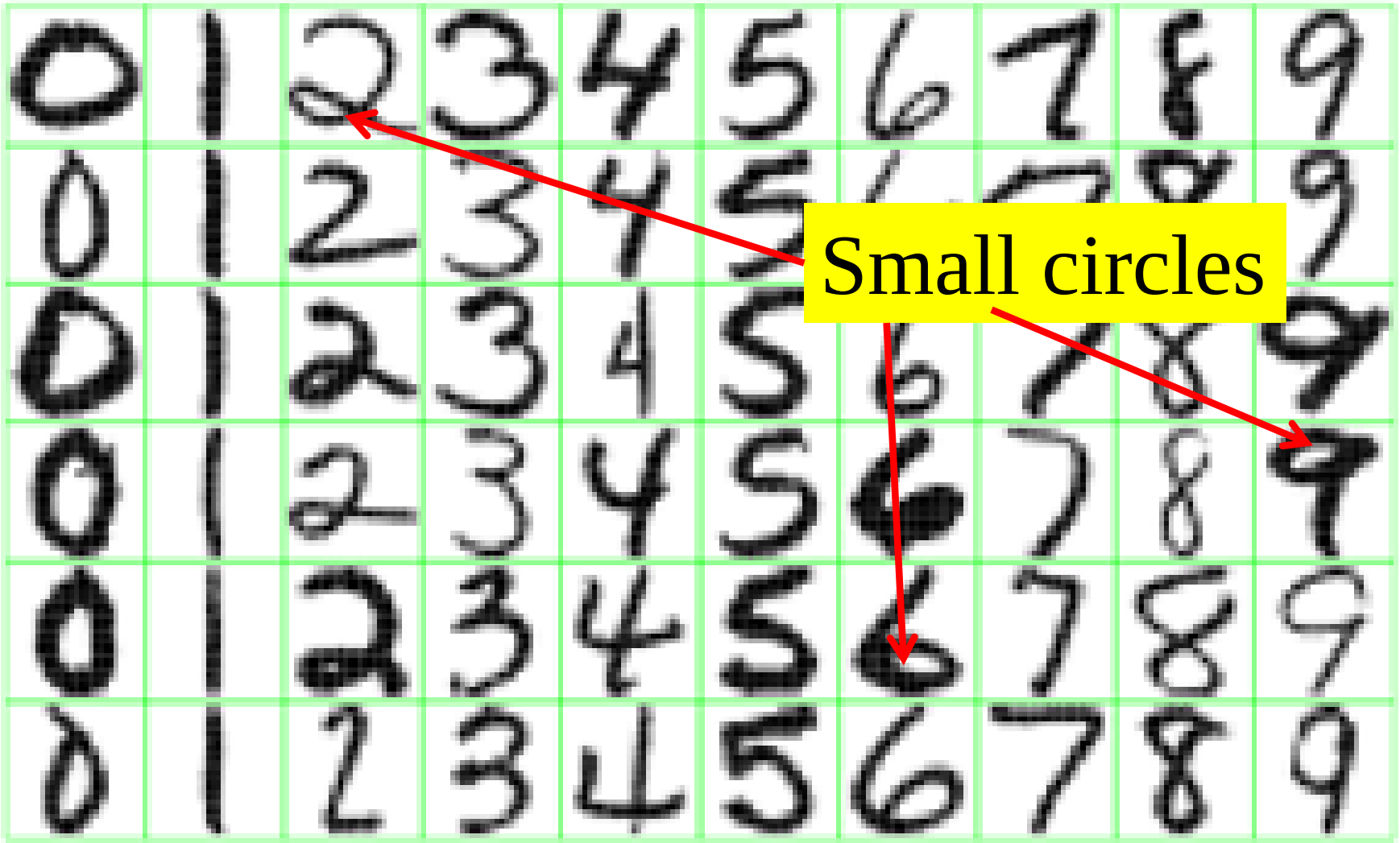
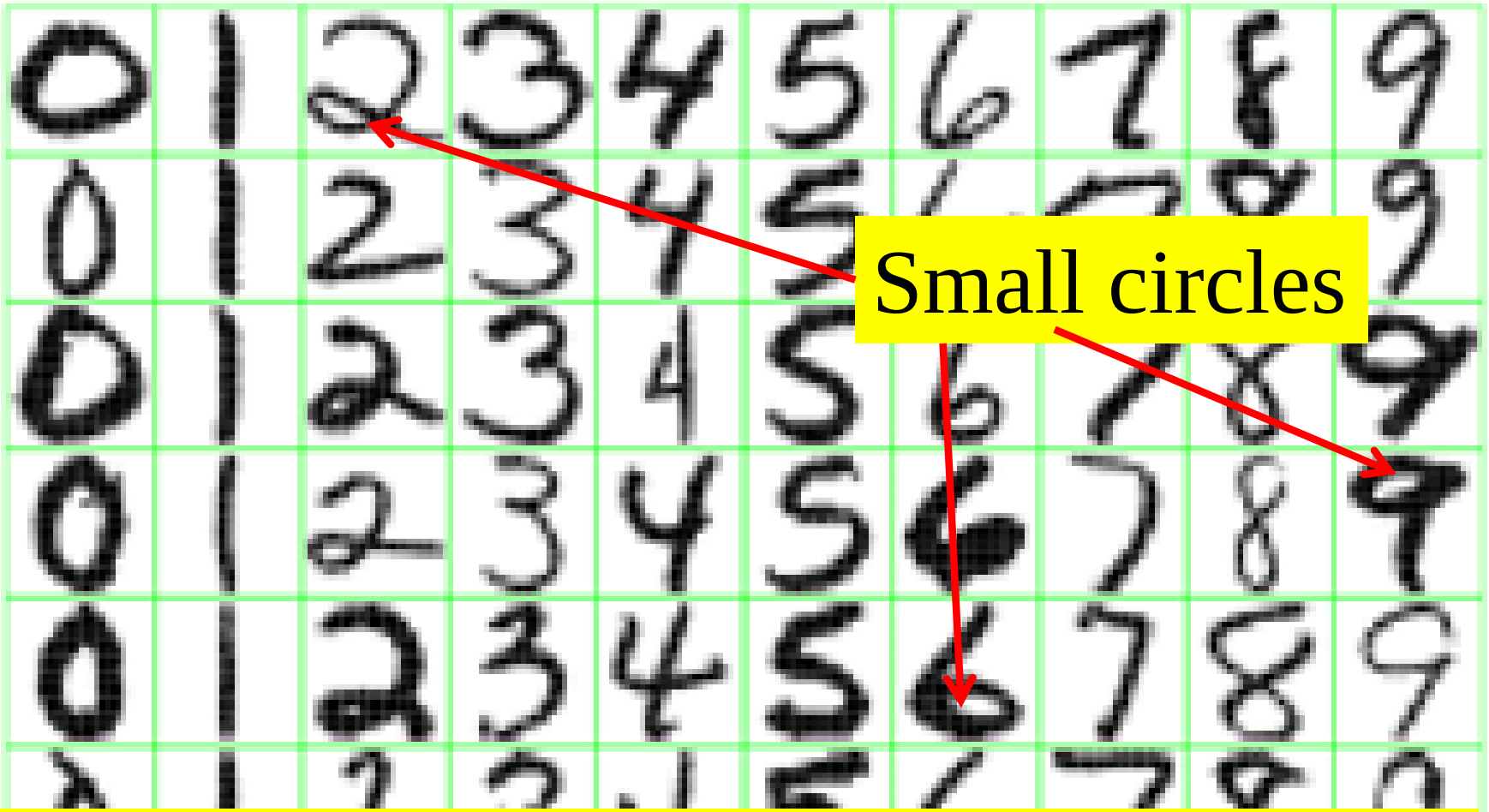


Figure 1.2: *Examples of handwritten digits from U.S. postal envelopes.*



1

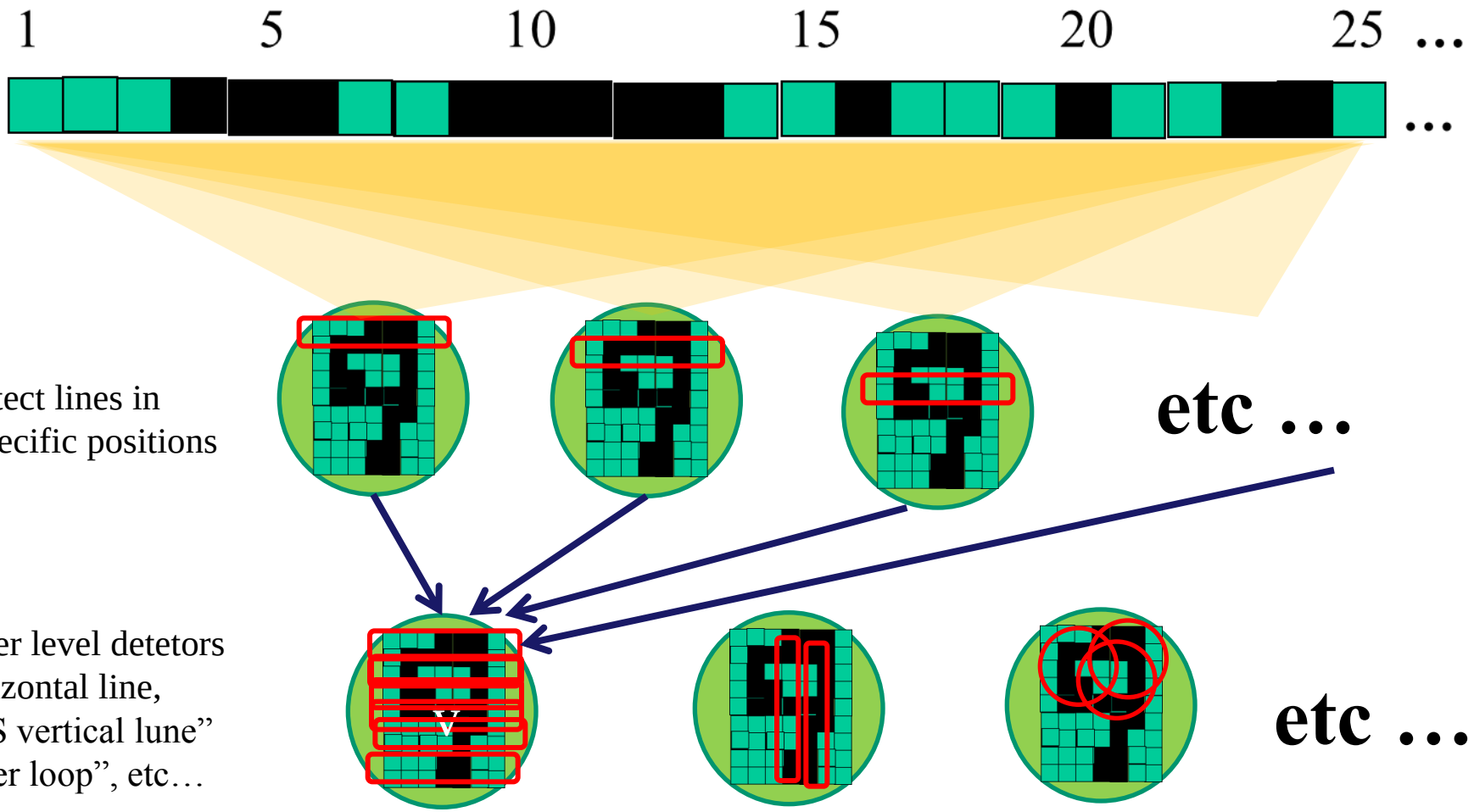
Figure 1.2: *Examples of handwritten digits from U.S. postal envelopes.*



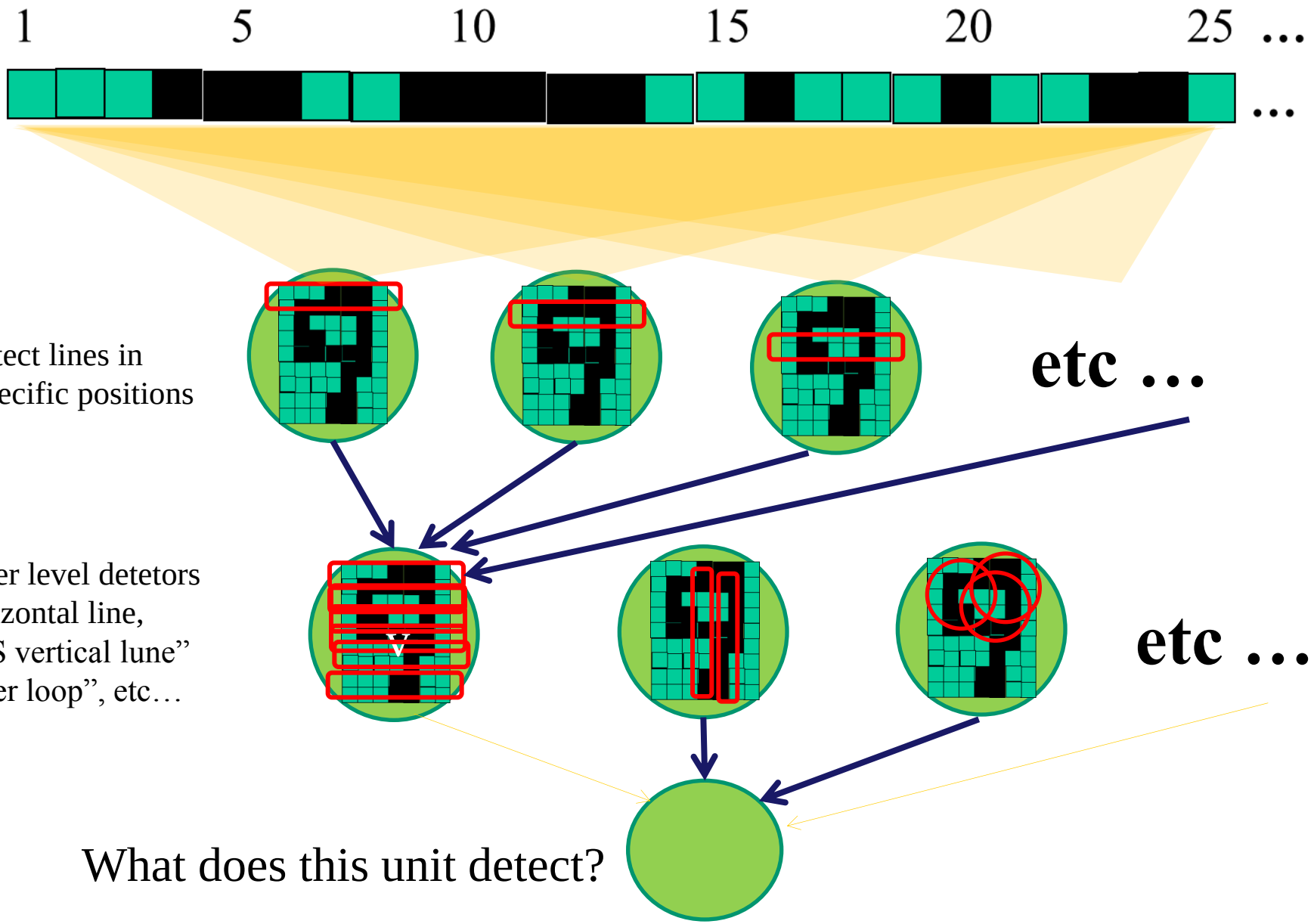
1

But what about position invariance ???
our example unit detectors were tied to specific parts of the image

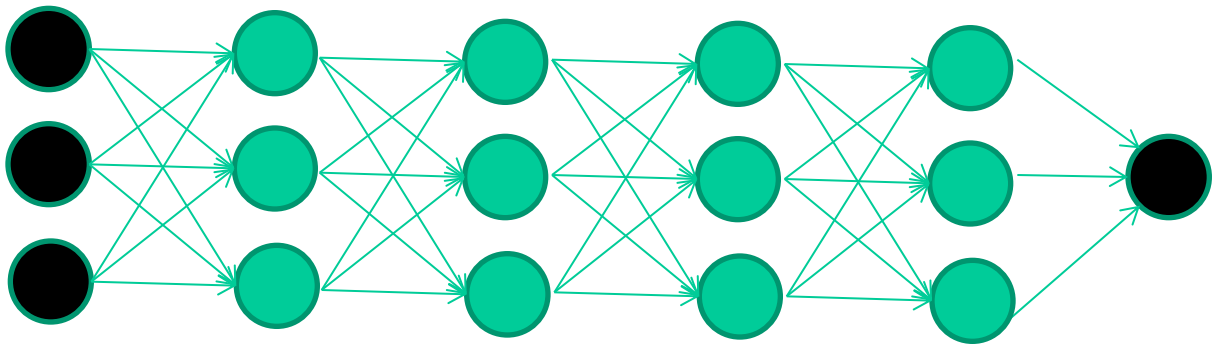
successive layers can learn higher-level features …



successive layers can learn higher-level features …

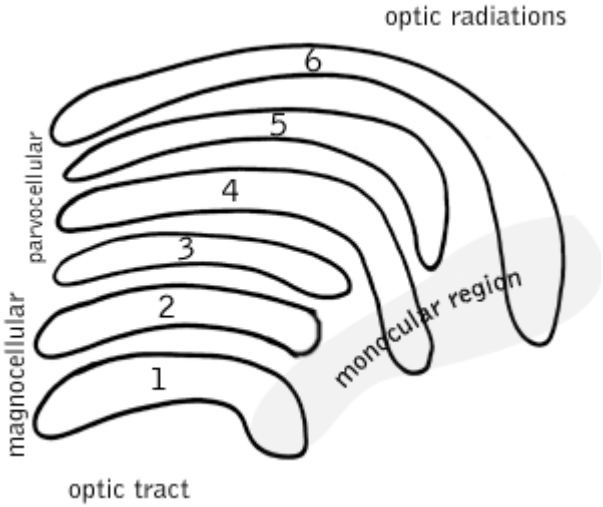


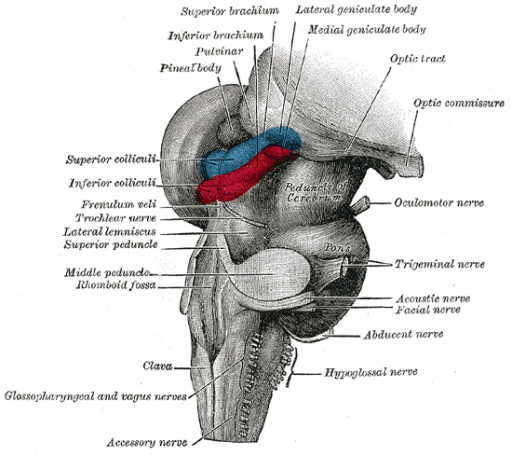
So: *multiple layers make sense*



So: *multiple layers make sense*

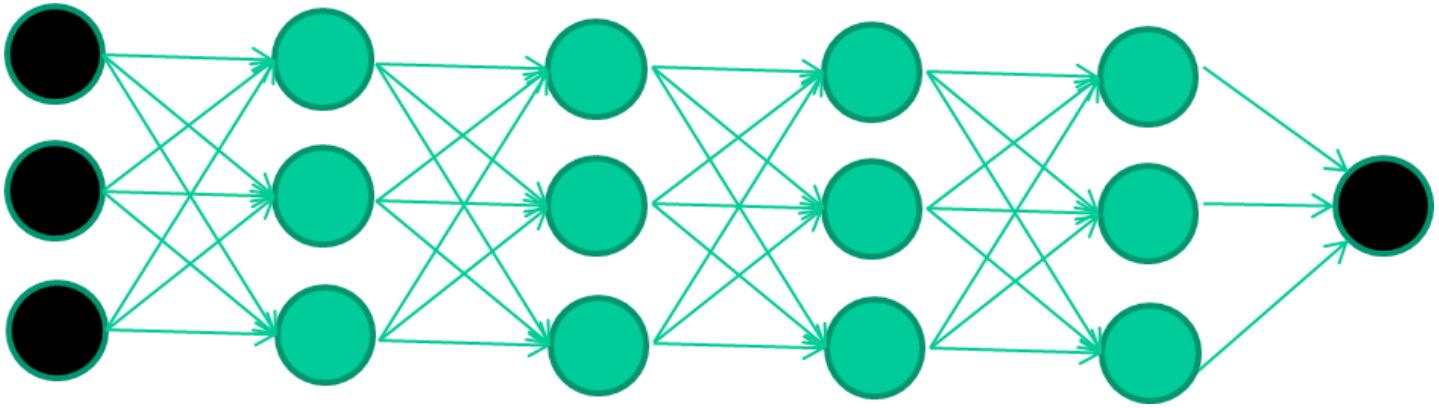
Your brain works that way



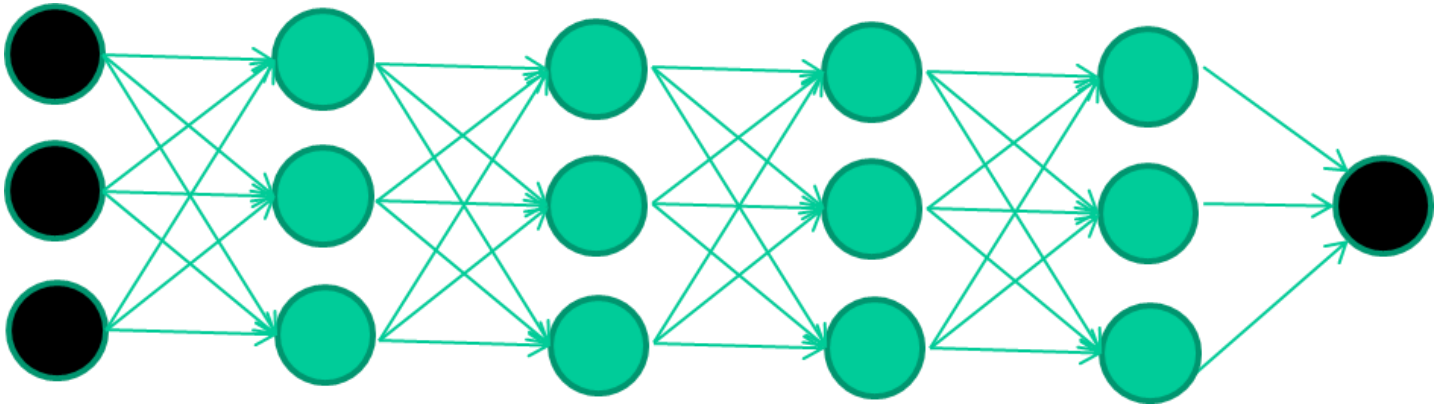


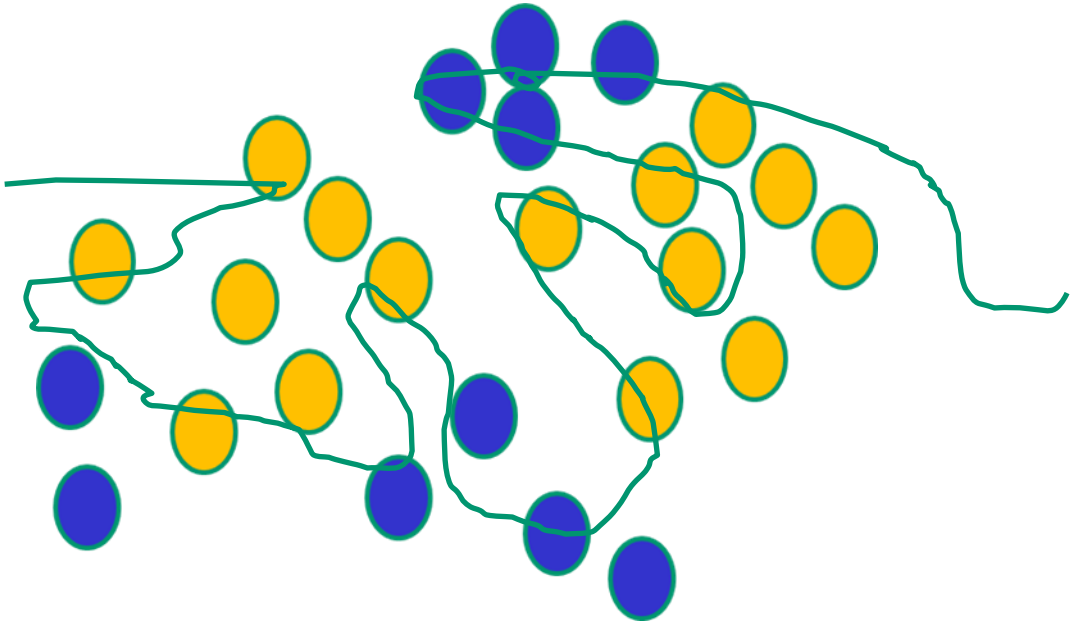
So: *multiple layers make sense*

Many-layer neural network architectures should be capable of learning the true underlying features and 'feature logic', and therefore generalise very well …



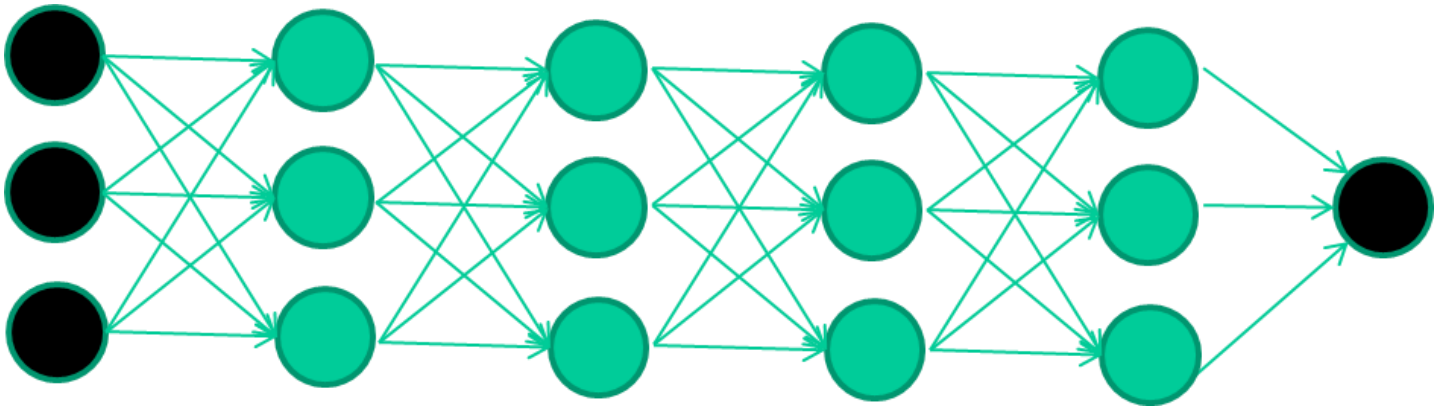
But, until very recently, our weight-learning algorithms simply did not work on multi-layer architectures



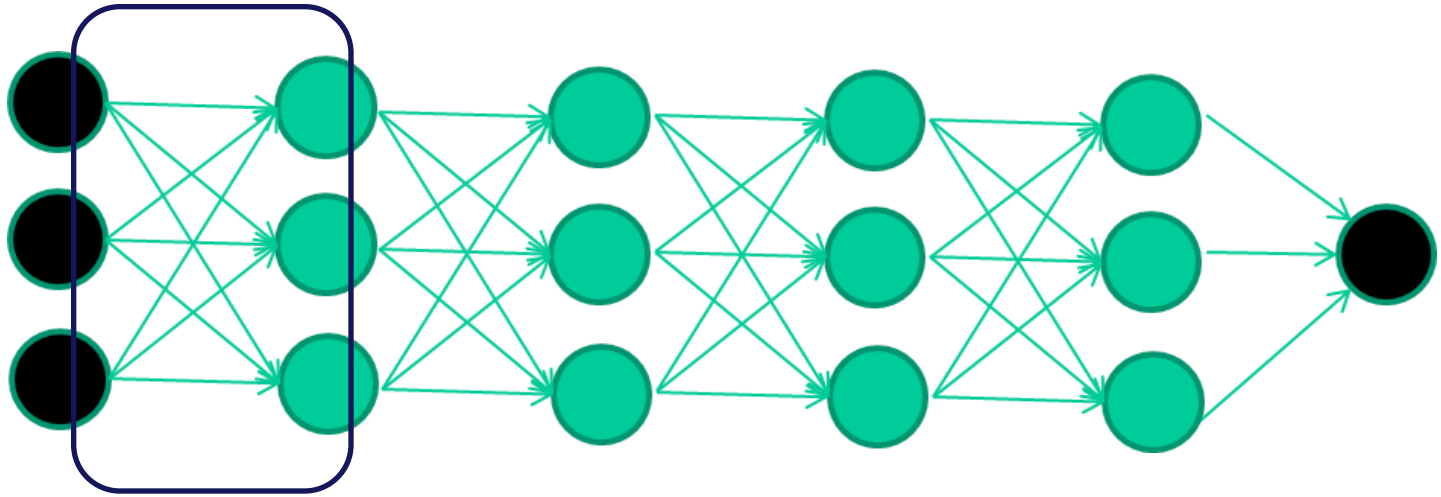


Along came deep learning …

The new way to train multi-layer NNs…

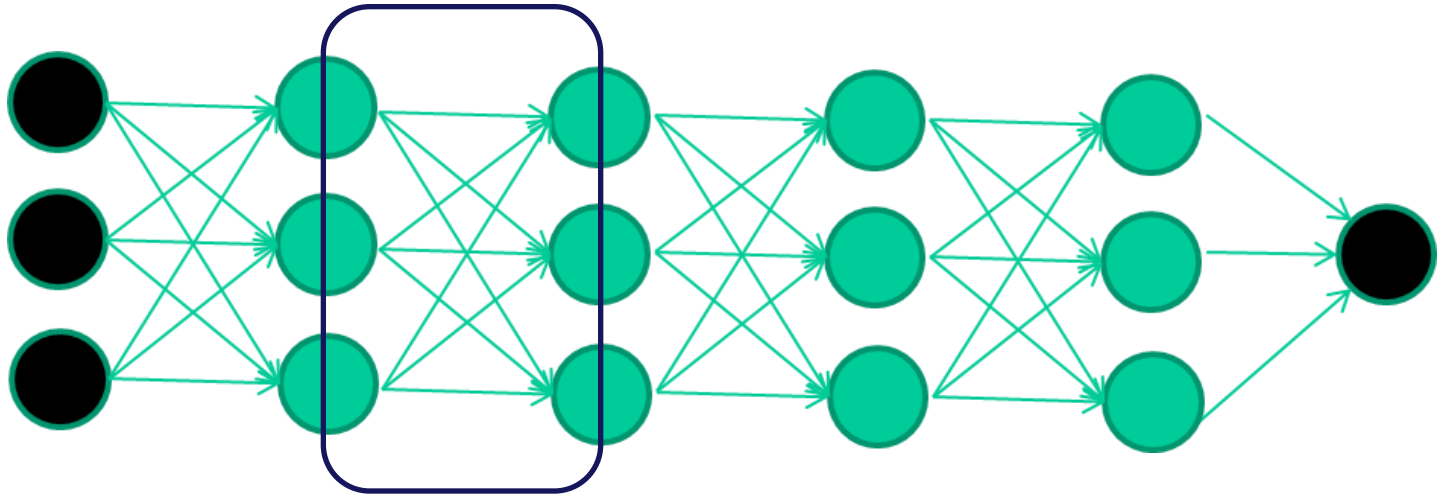


The new way to train multi-layer NNs…



Train **this** layer first

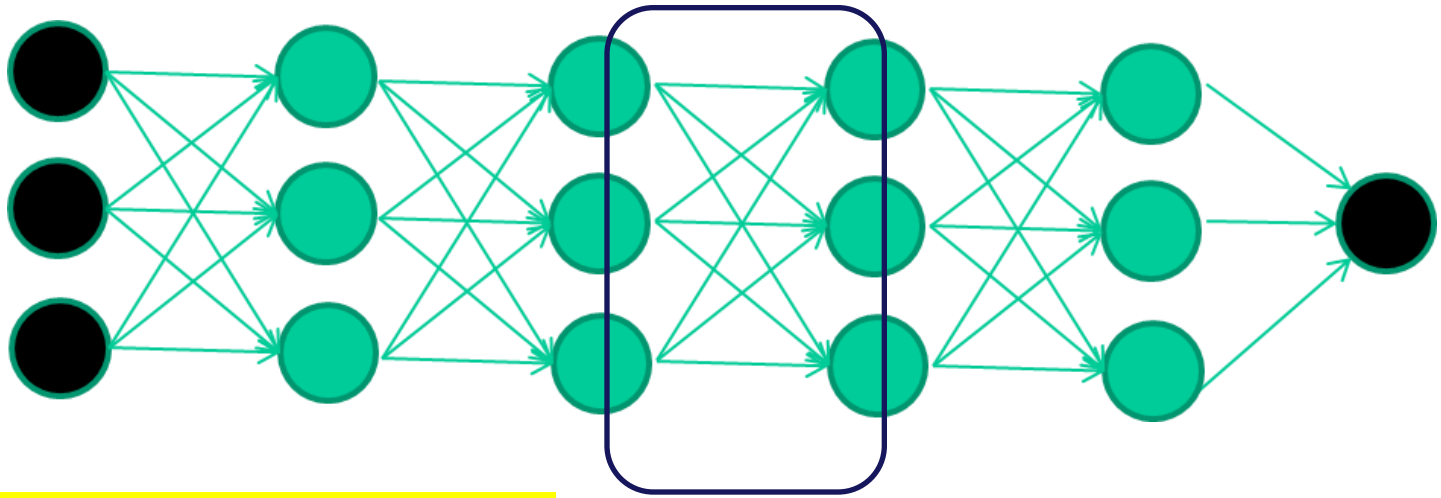
The new way to train multi-layer NNs…



Train **this** layer first

then **this** layer

The new way to train multi-layer NNs…

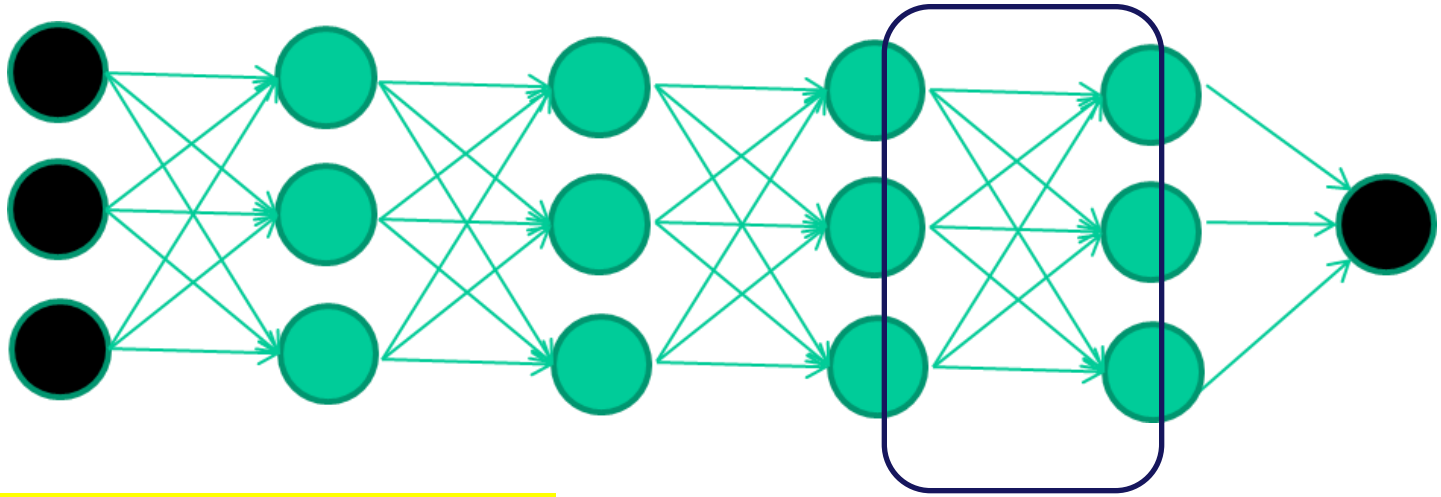


Train **this** layer first

then **this** layer

then **this** layer

The new way to train multi-layer NNs…



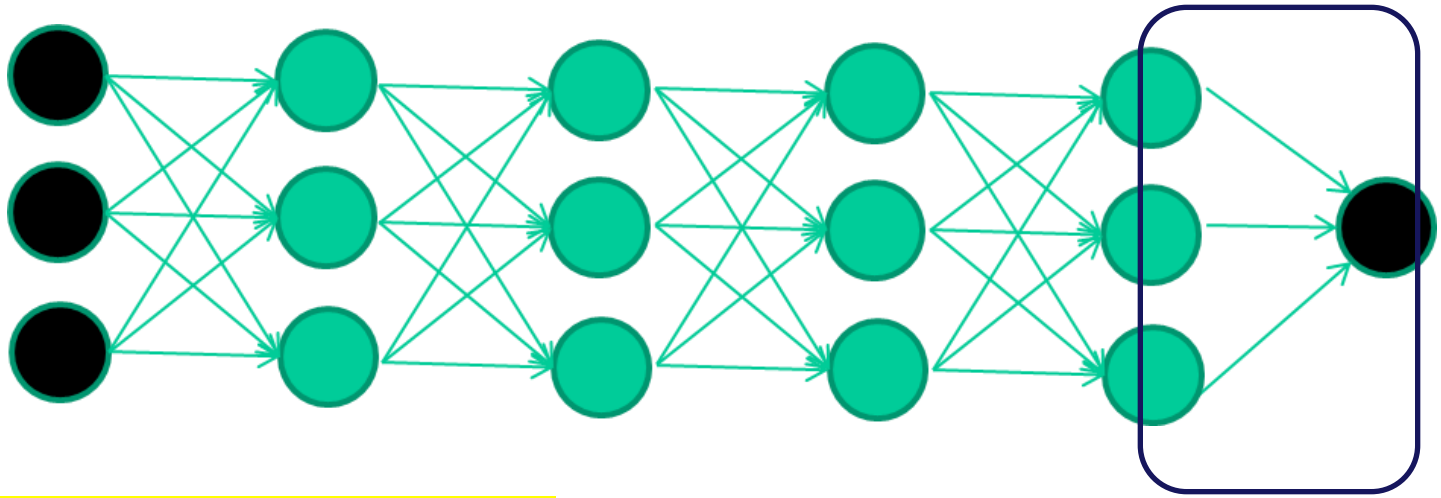
Train **this** layer first

then **this** layer

then **this** laver

then **this** layer

The new way to train multi-layer NNs…



Train **this** layer first

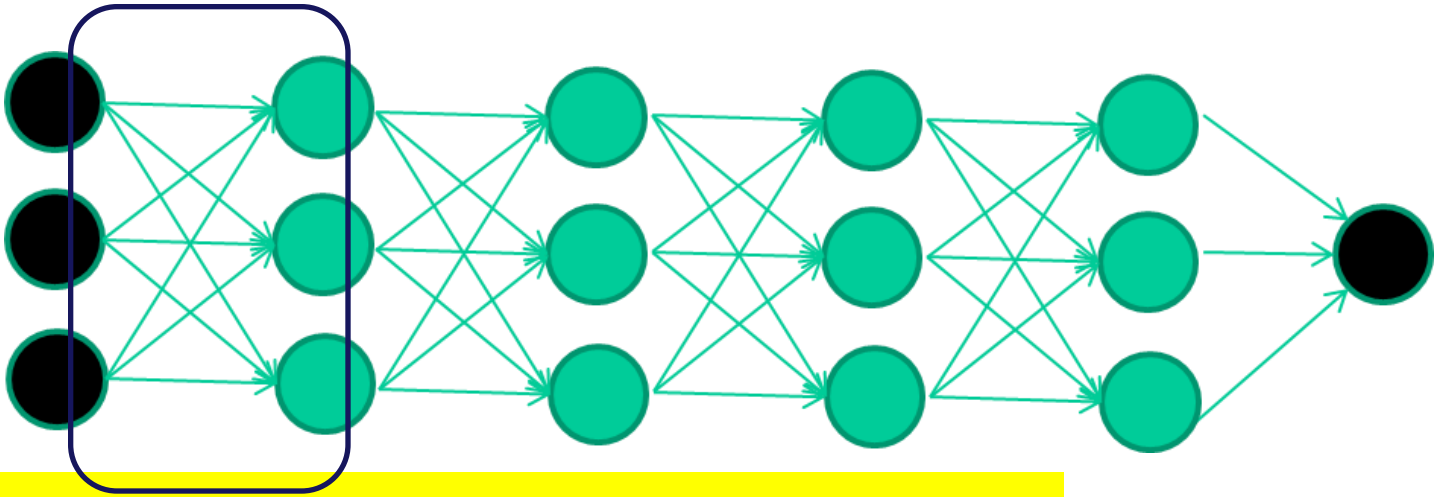
then **this** layer

then **this** laver

then **this** laver

finally **this** layer

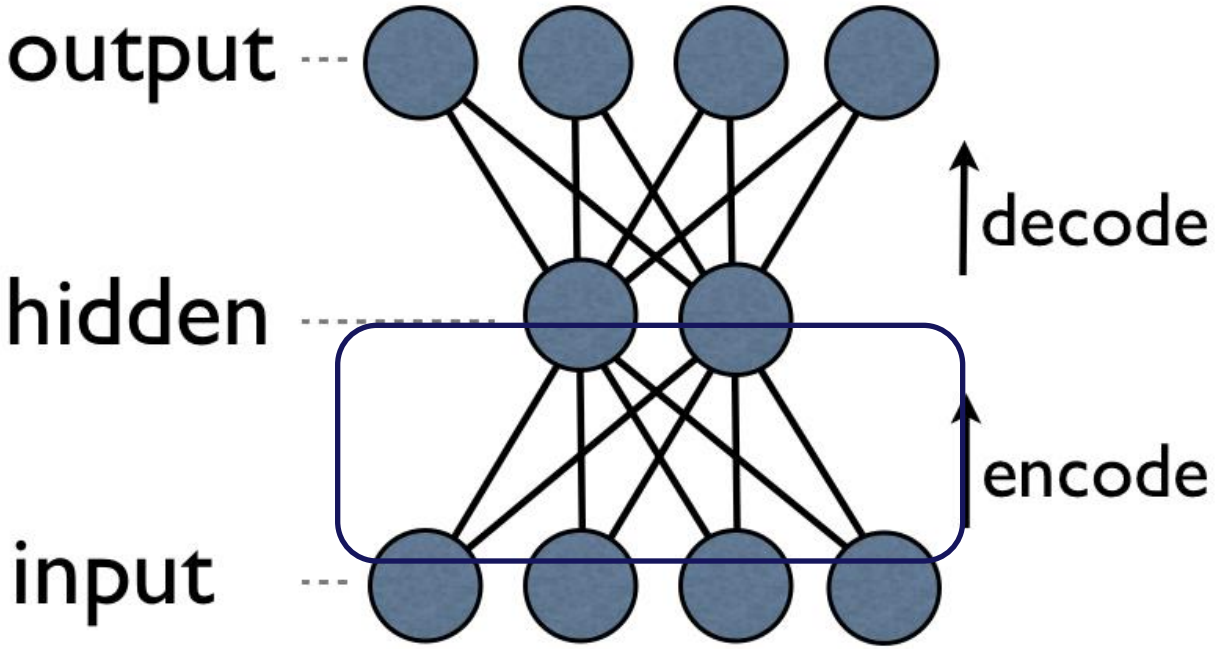
The new way to train multi-layer NNs…



EACH of the (non-output) layers is trained to be an ***auto-encoder***

Basically, it is forced to learn good features that describe what comes from the previous layer

an auto-encoder is trained, with an absolutely standard weight-adjustment algorithm to reproduce the input



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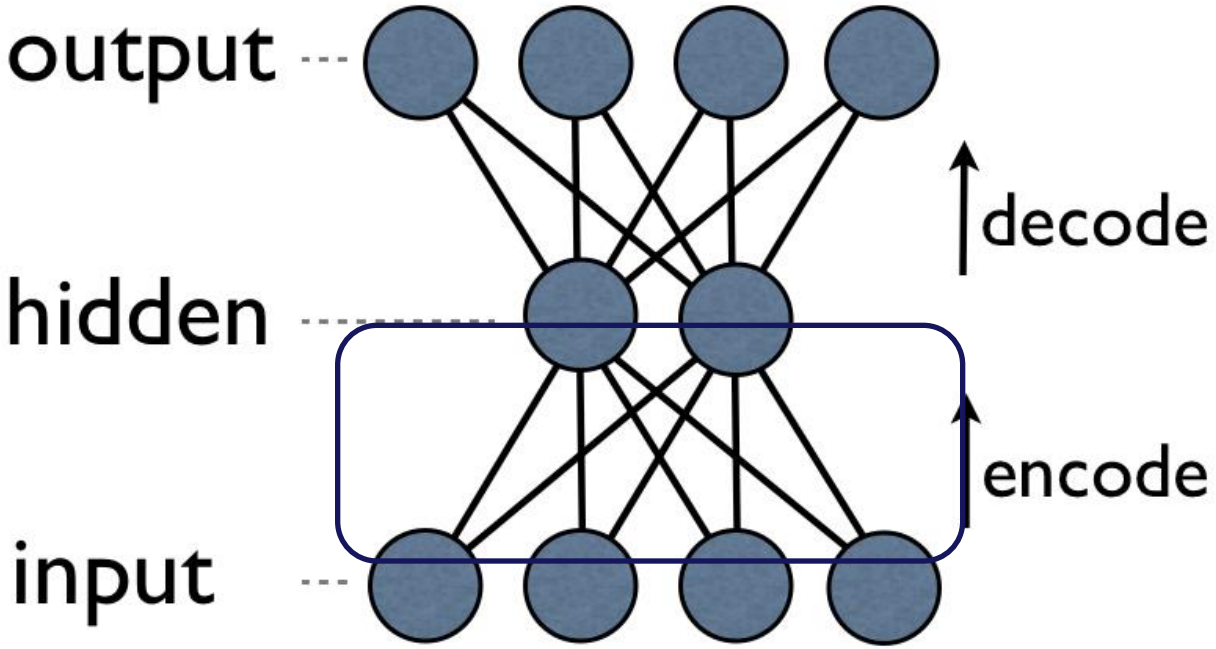
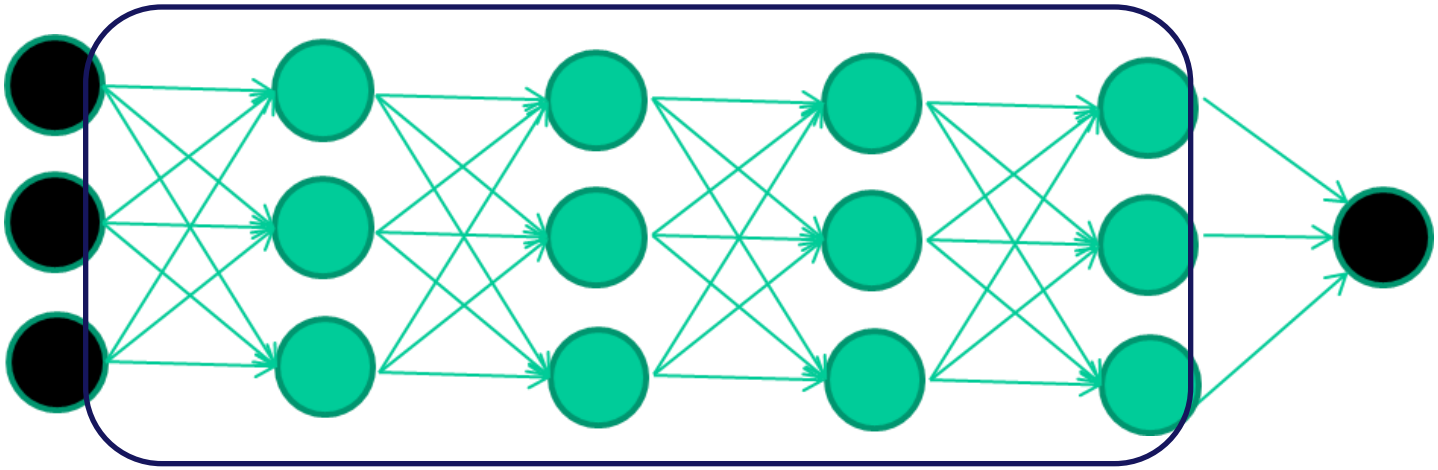
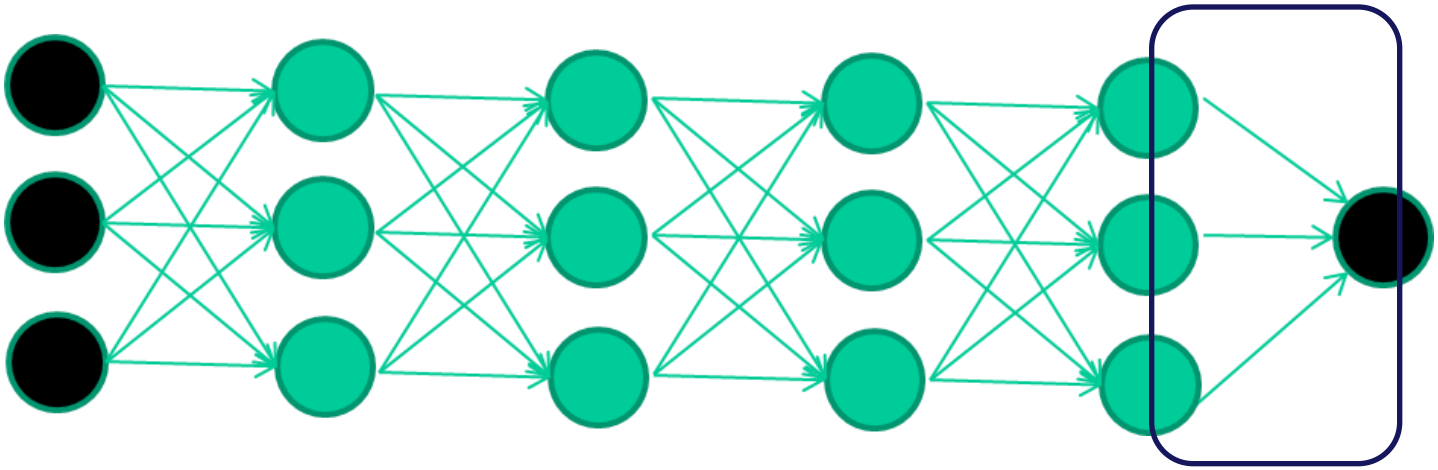


By making this happen with (many) fewer units than the inputs, this forces the 'hidden layer' units to become good feature detectors

intermediate layers are each trained to be auto encoders (or similar)



Final layer trained to predict class based on outputs from previous layers



And that's that

- That's the basic idea
- There are many many types of deep learning,
- different kinds of autoencoder, variations on architectures and training algorithms, etc…
- Very fast growing area …