Dynamic Programming

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Introduction

This is a replication of Adams, et al.(2015), mainly based on Chapter 7.

Overview

- 1. Replication
 - 1. Value Function Iteration
 - 2. Policy Function Iteration
 - 3. Finite Stochastic Dynamic Programming
- 2. Exercise

1. Replication

Setup

```
# initialize
rm(list = ls())

# package
if(!require(pacman)) install.packages("packman")
pacman::p_load(
  tidyverse,
  tictoc,
  RColorBrewer
)
```

1-1. Value Function Iteration

```
# one iteration of the value function
IterateVF <- function(V, maxK){
    # basic parameters
Alpha <- 0.65
Beta <- 0.9</pre>
```

```
Theta <- 1.2
  grid <- length(V)</pre>
  K <- seq(from = 1e-6, to = maxK, length.out = grid)</pre>
  TV <- rep(0, length(V))
  optK <- rep(0, length(V))</pre>
  # loop through and create new value function for each possible capital value
  for(k in 1:grid){
    c <- rep(Theta*(K[k]^Alpha), grid) - K</pre>
    c[c \le 0] \le rep(0, sum(c \le 0))
    u \leftarrow log(c)
    candid <- u + Beta*V
    TV[k] <- max(candid)
    optK[k] <- which(candid == max(candid))</pre>
  # time consuming method
  # candid <- rep(NA, 1000)
  \# c \leftarrow rep(NA, grid)
  # u \leftarrow rep(NA, grid)
  # for(k in 1:grid){
      for(k_tilde in 1:grid){
         c[k\_tilde] \leftarrow Theta*(K[k]^Alpha)-K[k\_tilde]
  #
         c[k\_tilde] \leftarrow ifelse(c[k\_tilde] > 0, c[k\_tilde], 0)
  #
        u[k\_tilde] \leftarrow log(c[k\_tilde])
  #
         candid[k\_tilde] \leftarrow u[k\_tilde] + Beta*V[k\_tilde]
     TV[k] \leftarrow max(candid)
      optK[k] <- K[which(candid == max(candid))]</pre>
  # }
  sol <- matrix(c(TV, optK), nrow = length(V), ncol = 2, byrow = FALSE)</pre>
  return(sol)
}
```

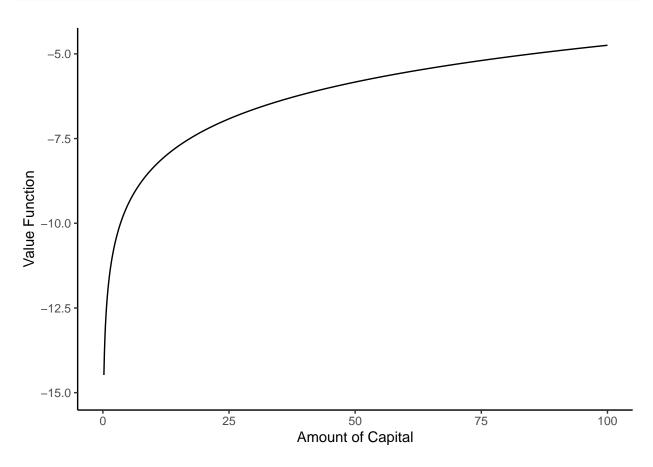
Analytical solution

```
# set parameters, plot analytical solution
Beta <- 0.9
Alpha <- 0.65
Theta <- 1.2
aB <- Alpha*Beta
K <- seq(from = 1e-6, to = 100, length.out = 1000)

E <- Alpha / (1 - aB)
f <- (1/(1-Beta))*(log(Theta*(1-aB))) + aB*log(aB*Theta)/((1-aB)*(1-Beta))
soln <- E*log(K) + f

ggplot() +
   geom_line(aes(x = K, y = soln)) +
   ylim(c(-15, NA)) +</pre>
```

```
xlab("Amount of Capital") + ylab("Value Function") +
theme_classic()
```



Iterated graph

```
tic()
n <- 15
# 10 iterations
TV <- matrix(rep(NA, 1000*n), ncol = n)
TV[, 1] <- rep(0, 1000)

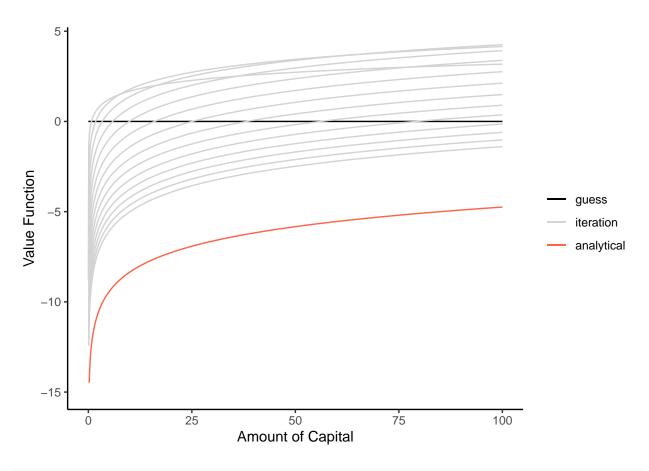
for(iter in 1:n){
   cat("Iteration number:", iter, "\n")
   if(iter < n) TV[, iter+1] <- IterateVF(TV[, iter], 100)[, 1]
}</pre>
```

```
## Iteration number: 1
## Iteration number: 2
## Iteration number: 3
## Iteration number: 4
## Iteration number: 5
## Iteration number: 6
## Iteration number: 7
## Iteration number: 8
## Iteration number: 9
```

```
## Iteration number: 10
## Iteration number: 11
## Iteration number: 12
## Iteration number: 13
## Iteration number: 14
## Iteration number: 15
toc()
```

0.419 sec elapsed

```
# plot
tic()
p1 <- ggplot()
for(i in 1:n){
 df <- data.frame(k = K, tv = TV[, i]) # store TV in a data.frame to layer plots
  if(i == 1){
   p1 \leftarrow p1 + geom\_line(\frac{data}{data} = df, aes(x = k, y = tv, color = 'guess'))
  } else{
    p1 <- p1 + geom_line(data = df, aes(x = k, y = tv, color = 'iteration'))
p1 <- p1 +
  geom_line(data = df, aes(x = k, y = soln, color = "analytical")) +
  scale_color_manual(
  name = NULL,
   values = c("guess" = "black", "iteration" = "lightgray", "analytical" = "tomato"),
   labels = c("guess", "iteration", "analytical")
  ) +
  ylim(c(-15, NA)) +
  labs(x = "Amount of Capital", y = "Value Function") +
  theme_classic()
p1
```



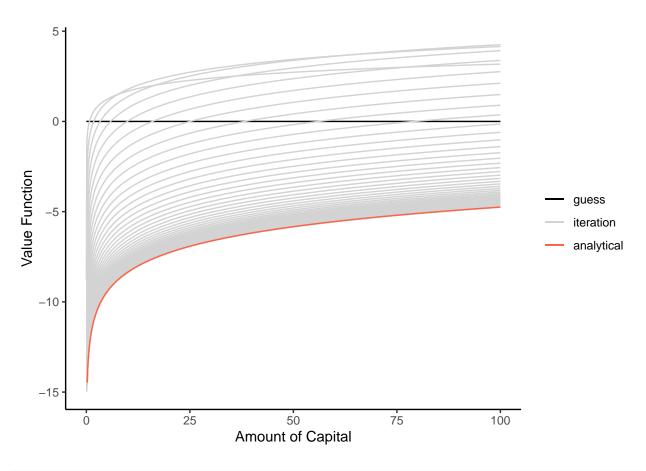
toc()

0.192 sec elapsed

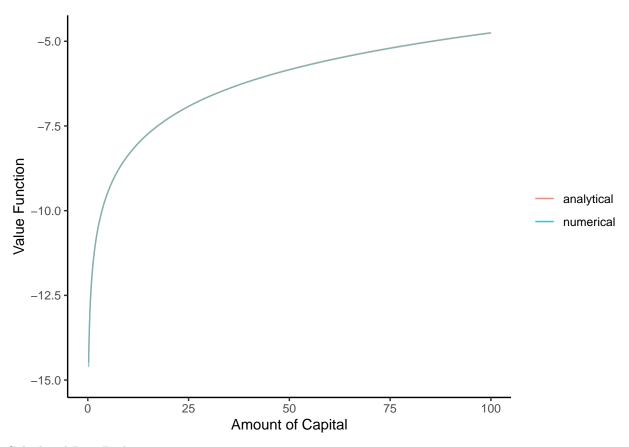
Convergence of Value Function

```
tic()
# setting
K <- seq(from = 1e-6, to = 100, length.out = 1000) # grid</pre>
V <- rep(0, 1000) # guess
conv <- 100 # criterion for convergence</pre>
crit <- 1e-2 # stopping threshold</pre>
Iter <- 0 # numbering iteration</pre>
# for plot
df \leftarrow data.frame(K = K, V = V)
p2 <- ggplot() +
  geom_line(data = df, aes(x = K, y = V, color = 'guess'))
# iteration
while(conv>crit && Iter<1000){</pre>
  Iter <- Iter + 1</pre>
  if(Iter %/% 10 == Iter/10) cat("Iteration number:", Iter, "\n")
  # mapping
```

```
sol <- IterateVF(V, 100)</pre>
  TV <- sol[, 1]
  # distance between TV and V
  conv <- max(abs(TV-V))</pre>
  # for plot
 df$TV <- TV # store TV in a data.frame to layer plots
 p2 \leftarrow p2 + geom\_line(data = df, aes(x = K, y = TV, color = 'iteration'))
  # pass TV to next iteration
  V <- TV
## Iteration number: 10
## Iteration number: 20
## Iteration number: 30
## Iteration number: 40
## Iteration number: 50
## Iteration number: 60
toc()
## 2.032 sec elapsed
cat("# of iterations:", Iter)
## # of iterations: 66
# plot
p2 <- p2 +
 geom_line(aes(x = K, y = soln, color = 'analytical')) +
 scale_color_manual(
   name = NULL,
   values = c("guess" = "black", "iteration" = "lightgray", "analytical" = "tomato"),
   labels = c("guess", "iteration", "analytical")
  ylim(c(-15, NA)) +
  labs(x = "Amount of Capital", y = "Value Function") +
  theme_classic()
p2
```

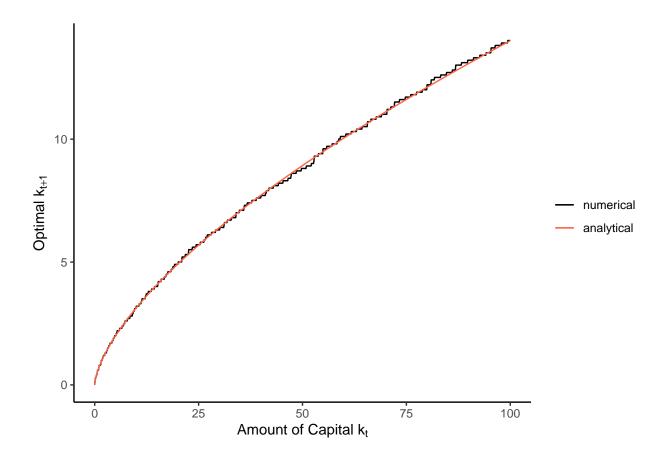


```
# another plot
p3 <-
ggplot() +
geom_line(aes(x = K, y = soln, color = 'soln'), alpha = 0.5) +
geom_line(aes(x = K, y = TV, color = 'TV'), alpha = 0.5) +
scale_color_manual(
    name = NULL,
    values = c("soln" = "tomato", "TV" = "#00AFBB"),
    labels = c("analytical", "numerical")
) +
ylim(c(-15, NA)) +
labs(x = "Amount of Capital", y = "Value Function") +
theme_classic()
p3 # seems overlapped!</pre>
```



Calculated Best Path

```
ggplot() +
  geom_line(aes(x = K, y = K[sol[, 2]], color = "numerical")) +
  geom_line(aes(x = K, y = Theta*(K^Alpha)*(aB), color = "analytical")) +
  scale_color_manual(
    name = NULL,
    values = c("numerical" = "black", "analytical" = "tomato"),
    labels = c("numerical", "analytical")
) +
  labs(x = expression(paste("Amount of Capital ", k[t])),
    y = expression(paste("Optimal ", k[t+1]))) +
  theme_classic()
```



1-2. Policy Function Iteration

We are to solve the following functional equation:

$$V(k) = \max_{\tilde{k}} \left\{ u(f(k) - \tilde{k}) + \beta V(\tilde{k}) \right\}.$$

Note that

$$V_j = U_j + \beta Q_j V_j,$$

where V_j denotes a vector by which a value function with respect to discretized k_t is expressed, and Q_j denotes the transition matrix whose binary entry takes 1 if it is the optimal \tilde{k} given k or not. U_j is a vactor whose each entry represents the maximized utility given today's capital k, i.e., $u(c_j(k))$. Solving this equation, we have

$$V_j = (I - \beta Q_j)^{-1} U_j.$$

This is the idea of the policy function iteration.

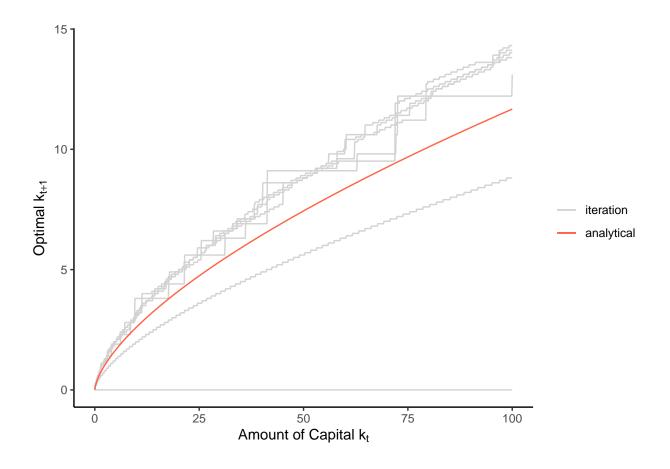
```
IteratePolicy <- function(V, maxK){
    # basic parameters
Alpha <- 0.65
Beta <- 0.9
Theta <- 1.2

grid <- length(V)
K <- seq(from = 1e-6, to = maxK, length.out = grid)
#TV <- rep(0, length(V))</pre>
```

```
opt <- rep(0, length(V))</pre>
  # loop through and create new value function for each possible capital value
  for(k in 1:grid){
    c <- rep(Theta*(K[k]^Alpha), grid) - K</pre>
    c[c \le 0] \le rep(0, sum(c \le 0))
    u <- log(c)
    candid <- u + Beta*V
    #TV[k] <- max(candid)</pre>
    opt[k] <- which(candid == max(candid))</pre>
  kopt <- K[opt]</pre>
  c <- Theta*K^Alpha - kopt
  u \leftarrow log(c)
  Q <- matrix(rep(0, grid*grid), ncol = grid)</pre>
  # create the transition matrix
  for(k in 1:grid){
    Q[k, opt[k]] \leftarrow 1
  TV <- solve(diag(grid)-Beta*Q)%*%u
  sol <- matrix(c(TV, opt), ncol = 2)</pre>
  V <- TV
  return(sol)
}
```

```
tic()
# setting
K <- seq(from = 1e-6, to = 100, length.out = 1000) # grid</pre>
V <- rep(0, 1000) # guess
conv <- 100 # criterion for convergence</pre>
crit <- 1e-2 # stopping threshold</pre>
Iter <- 0 # numbering iteration</pre>
# for plot
df \leftarrow data.frame(K = K, V = V)
p4 <- ggplot()
# iteration
while(conv>crit && Iter<1000){</pre>
  Iter <- Iter + 1</pre>
  if(Iter %/% 10 == Iter/10) cat("Iteration number:", Iter, "\n")
  # mapping
  sol <- IteratePolicy(V, 100)</pre>
  TV <- sol[, 1]
  opt <- sol[, 2]
  # distance between TV and V
  conv<- max(abs(TV-V))</pre>
```

```
# for plot
  df$K_opt <- K[opt]</pre>
  p4 <- p4 + geom_line(data = df, aes(x = K, y = K_opt, color = 'iteration'))
 # pass TV to next iteration
 V <- TV
}
toc()
## 1.379 sec elapsed
cat("# of outer iterations:", Iter)
## # of outer iterations: 7
# plot
p4 <- p4 +
  geom_line(aes(x = K, y = aB*(K^Alpha), color = 'analytical')) +
  scale_color_manual(
   name = NULL,
   values = c("iteration" = "lightgray", "analytical" = "tomato"),
   labels = c("iteration", "analytical")
  ) +
  labs(x = expression(paste("Amount of Capital ", k[t])),
     y = expression(paste("Optimal ", k[t+1]))) +
  theme_classic()
p4
```



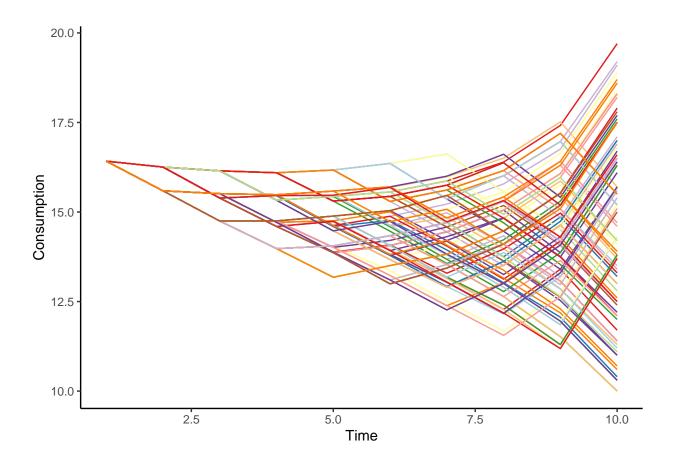
1-3. Finite Stochastic Dynamic Programming

This part is based on Chapter 6, "6.4 Stochastic Dynamic Programming".

```
tic()
# setup parameters
e < -c(-2, 2)
PI \leftarrow c(0.5, 0.5)
Beta <- 0.9
Theta <- 1.2
Alpha <- 0.98
Kl <- 100
grid <- 0.1
t <- 10
K \leftarrow seq(from = 0, to = Kl + max(e), by = grid)
V <- cbind(matrix(rep(NA, length(K)*t), ncol = t), matrix(rep(0, length(K)), ncol = 1))
aux <- array(rep(NA, length(K)*length(K)*t), dim = c(length(K), length(K), t))</pre>
# loop over preriods
for(t_iter in seq(from = t, to = 1, by = -1)){
  cat("Currently in period", t_iter, "\n")
  # loop over k_{t}
  for(inK in 1:length(K)){
  # for(inK in 1:length(seq(from = 0, to = Kl, by = grid))){ # seems mistaken
```

```
# loop over k_{t} + 1
    for(outK in 1:inK){
      c <- K[inK] - (K[outK]/Theta)^(1/Alpha) # note this is scaler</pre>
      nextKl <- Theta*(K[inK] - c)^Alpha + e[1]</pre>
      nextKh <- Theta*(K[inK] - c)^Alpha + e[2]</pre>
      nextKl[nextKl < 0] <- rep(0, sum(nextKl < 0))</pre>
      position_l <- ifelse((round(nextKl/grid) + 1) <= length(K),</pre>
                             (round(nextKl/grid) + 1),
                            length(K))
      position_h <- ifelse((round(nextKh/grid) + 1) <= length(K),</pre>
                             (round(nextKh/grid) + 1),
                            length(K))
      EnextV <-
        PI[1] * V[position_1, t_iter+1] + PI[2] * V[position_h, t_iter+1]
        #PI[1] * V[(round(nextKl/grid) + 1), t_iter+1] +
        \#PI[2] * V[(round(nextKh/grid) + 1), t_iter+1] \# seems mistaken
      \#c \leftarrow ifelse(c \leftarrow 0, 1e-100, c) \# if you want to avoid -Inf
      aux[inK, outK, t_iter] <- log(c) + Beta*EnextV</pre>
  V[, t_iter] <-</pre>
    apply(
      X = as.matrix(aux[, , t_iter]), MARGIN = 1, FUN = max, na.rm = TRUE
    )
## Currently in period 10
## Currently in period 9
## Currently in period 8
## Currently in period 7
## Currently in period 6
## Currently in period 5
## Currently in period 4
## Currently in period 3
## Currently in period 2
## Currently in period 1
toc()
## 15.993 sec elapsed
Simulation
tic()
# setup parameters and simulate shocks
set.seed(2022)
people <- 100
epsilon <-
  ifelse(purrr::rbernoulli(people*(t+1), 0.5), 2, -2) %>%
  matrix(ncol = t+1)
```

```
vf <-
  rep(NA, people*t) %>%
  matrix(ncol = t)
kap <- # capital</pre>
  cbind(
    Kl*(rep(1, people)), # k_{0}
    matrix(rep(NA, people*t), ncol = t)
con <- # consumption</pre>
  rep(NA, people*t) %>%
  matrix(ncol = t)
for(p in 1:people){
  for(t_iter in 1:t){
    position <- round(kap[p, t_iter]/grid + 1)</pre>
    vf[p, t_iter] <- V[position, t_iter]</pre>
    kap[p, t_iter + 1] <- K[which(aux[position, , t_iter] == vf[p, t_iter])]</pre>
    con[p, t_iter] \leftarrow kap[p, t_iter] - (kap[p, t_iter+1]/Theta)^(1/Alpha)
    kap[p, t_iter + 1] \leftarrow kap[p, t_iter + 1] + epsilon[p + t_iter + 1]
}
toc()
## 0.026 sec elapsed
plot
p_5 <- ggplot()</pre>
for(i in 1:people){
  df <- data.frame(time = 1:t, consumption = con[i, ])</pre>
  p_5 \leftarrow p_5 +
    geom_line(
      data = df, aes(x = time, y = consumption),
      color = sample(brewer.pal(12, "Paired"), 1)
    )
p_5 \leftarrow p_5 +
  labs(x = "Time", y = "Consumption") +
  theme_classic()
p_5
```



2. Exercise

(i)

We have

$$c_t = \theta k_t^{\alpha} - k_{t+1}.$$

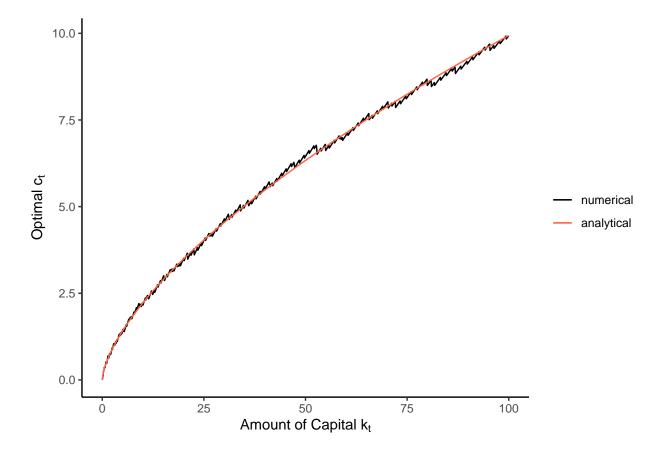
```
Beta <- 0.9
Alpha <- 0.65
Theta <- 1.2
aB <- Alpha*Beta

K <- seq(from = 1e-6, to = 100, length.out = 1000) # grid
V <- rep(0, 1000) # guess
conv <- 100 # criterion for convergence
crit <- 1e-2 # stopping threshold
Iter <- 0 # numbering iteration

# for plot
df <- data.frame(K = K, V = V)

# iteration
while(conv>crit && Iter<1000){</pre>
```

```
Iter <- Iter + 1</pre>
  if(Iter %/% 10 == Iter/10) cat("Iteration number:", Iter, "\n")
  # mapping
  sol <- IterateVF(V, 100)</pre>
  TV <- sol[, 1]
  # distance between TV and V
  conv <- max(abs(TV-V))</pre>
  # for plot
  df$TV <- TV # store TV in a data.frame to layer plots
  # pass TV to next iteration
  V <- TV
## Iteration number: 10
## Iteration number: 20
## Iteration number: 30
## Iteration number: 40
## Iteration number: 50
## Iteration number: 60
C_opt <- Theta*K^Alpha - K[sol[, 2]]</pre>
ggplot() +
  geom_line(aes(x = K, y = C_opt, color = "numerical")) +
  geom_line(aes(x = K, y = Theta*(K^Alpha)*(1-aB), color = "analytical")) +
  scale_color_manual(
    name = NULL,
    values = c("numerical" = "black", "analytical" = "tomato"),
   labels = c("numerical", "analytical")
  labs(x = expression(paste("Amount of Capital ", k[t])),
      y = expression(paste("Optimal ", c[t]))) +
  theme_classic()
```



(ii)

Note that the transition equation is

$$k_{t+1} = f(k_t) - c_t + \varepsilon_{t+1},$$

where the production function is set as $f(k_t) = \theta k^{\alpha}$. The value function is written as

$$V(k_t) = \max_{c_t \in (0, k_t]} \{ u(c_t) + \beta E_t [V(f(k_t) - c_t + \varepsilon_{t+1})] \}.$$

Here, discretization of consumption c_t is necessary to find the solution.

(ii)-(a)

```
# one iteration of the value function
IterateStochastic <- function(V, maxK){
    # basic parameters
Alpha <- 0.65
Beta <- 0.9
Theta <- 1.2
e <- c(-2, 2)
PI <- c(0.5, 0.5)

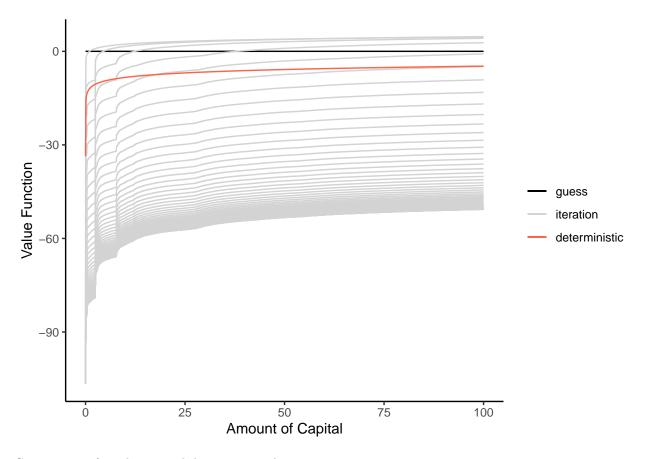
grid <- length(V)
K <- seq(from = 1e-6, to = maxK, length.out = grid)</pre>
```

```
TV <- rep(0, length(V))
optC <- rep(0, length(V))
# loop through and create new value function for each possible capital value
for(k in 1:grid){
  C \leftarrow seq(from = 1e-10, to = K[k], by = 0.1)
  #c <- rep(Theta*(K[k]^Alpha), grid) - K
  nextKl <- rep(Theta*K[k]^Alpha, length(C)) - C + e[1]</pre>
  nextKh <- rep(Theta*K[k]^Alpha, length(C)) - C + e[2]</pre>
  nextKl[nextKl < 0] <- rep(0, sum(nextKl < 0))</pre>
  EnextV <- rep(0, length(C))</pre>
  position_l <- rep(0, length(C))</pre>
  position_h <- rep(0, length(C))</pre>
  for(i in 1:length(C)){
    position_l[i] <- which(abs(K - nextKl[i]) == min(abs(K - nextKl[i])))[1]</pre>
    position_h[i] <- which(abs(K - nextKh[i]) == min(abs(K - nextKh[i])))[1]</pre>
    EnextV[i] <- PI[1] * V[position_1[i]] + PI[2] * V[position_h[i]]</pre>
  }
  u <- log(C)
  candid <- u + Beta*EnextV</pre>
  TV[k] <- max(candid)
  optC[k] <- which(candid == max(candid))</pre>
sol <- matrix(c(TV, optC), nrow = length(V), ncol = 2, byrow = FALSE)</pre>
return(sol)
```

Convergence of Value Function

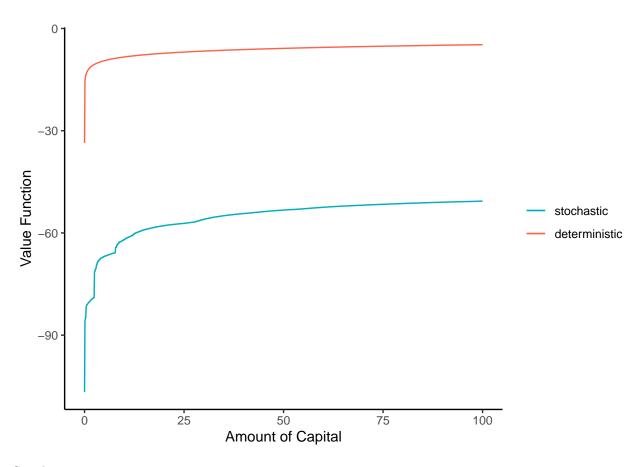
```
tic()
# setting
K <- seq(from = 1e-6, to = 100, length.out = 1000) # grid</pre>
V <- rep(0, 1000) # guess
conv <- 100 # criterion for convergence</pre>
crit <- 1e-2 # stopping threshold</pre>
Iter <- 0 # numbering iteration</pre>
# for plot
df \leftarrow data.frame(K = K, V = V)
p7 <- ggplot() +
  geom\_line(data = df, aes(x = K, y = V, color = 'guess'))
# iteration
while(conv>crit && Iter<1000){</pre>
  Iter <- Iter + 1</pre>
  if(Iter %/% 10 == Iter/10) cat("Iteration number:", Iter, "\n")
  # mapping
```

```
sol <- IterateStochastic(V, 100)</pre>
  TV <- sol[, 1]
  # distance between TV and V
  conv <- max(abs(TV-V))</pre>
  # for plot
  df$TV <- TV # store TV in a data.frame to layer plots
  p7 \leftarrow p7 + geom\_line(data = df, aes(x = K, y = TV, color = 'iteration'))
  # pass TV to next iteration
  V <- TV
## Iteration number: 10
## Iteration number: 20
## Iteration number: 30
## Iteration number: 40
## Iteration number: 50
## Iteration number: 60
V stoch <- V
optC_stoch <- sol[, 2]</pre>
toc()
## 776.204 sec elapsed
cat("# of iterations:", Iter)
## # of iterations: 66
# plot
p7 \leftarrow p7 +
  geom\_line(aes(x = K, y = soln, color = 'deterministic')) +
  scale_color_manual(
   name = NULL,
    values = c("guess" = "black", "iteration" = "lightgray", "deterministic" = "tomato"),
   labels = c("guess", "iteration", "deterministic")
  labs(x = "Amount of Capital", y = "Value Function") +
  theme_classic()
р7
```



Comparison of stochastic and deterministic dynamic programming

```
ggplot() +
  geom_line(aes(x = K, y = V_stoch, color = "stochastic")) +
  geom_line(aes(x = K, y = soln, color = 'deterministic')) +
  scale_color_manual(
    name = NULL,
    values = c("stochastic" = "#00AFBB", "deterministic" = "tomato"),
    labels = c("stochastic", "deterministic")
) +
  labs(x = "Amount of Capital", y = "Value Function") +
  theme_classic()
```



Simulation

```
tic()
# setup parameters and simulate shocks
set.seed(2022)
t <- 10
people <- 100
Kl <- 100
V <- cbind(matrix(rep(NA, length(K)*t), ncol = t), matrix(rep(0, length(K)), ncol = 1))</pre>
epsilon <-
  ifelse(purrr::rbernoulli(people*(t+1), 0.5), 2, -2) %>%
  matrix(ncol = t+1)
vf <-
 rep(NA, people*t) %>%
 matrix(ncol = t)
kap <- # capital
  cbind(
    Kl*(rep(1, people)), # k_{0}
    matrix(rep(NA, people*t), ncol = t)
  )
con <- # consumption</pre>
  rep(NA, people*t) %>%
  matrix(ncol = t)
for(p in 1:people){
  for(t_iter in 1:t){
```

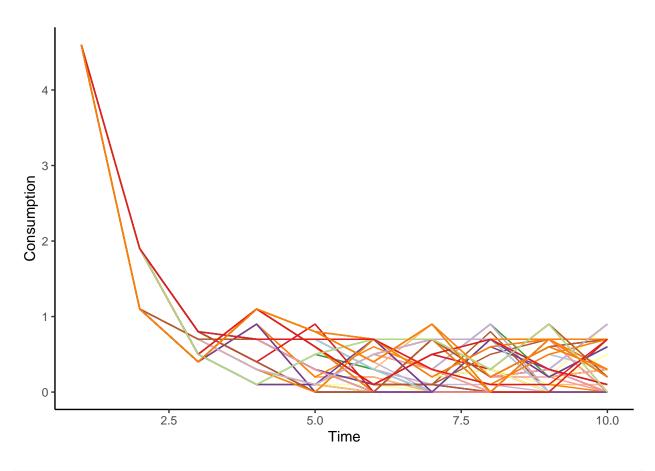
```
position <-
    which(abs(K - kap[p, t_iter]) == min(abs(K - kap[p, t_iter]), na.rm = TRUE))[1]
vf[p, t_iter] <- V_stoch[position]

con[p, t_iter] <-
    seq(from = 1e-10, to = K[position], by = 0.1)[optC_stoch[position]]
k_tmp <- Theta*kap[p, t_iter]^(Alpha) - con[p, t_iter] + epsilon[p + t_iter + 1]
kap[p, t_iter + 1] <- ifelse(k_tmp > 0, k_tmp, 0)
}
toc()
```

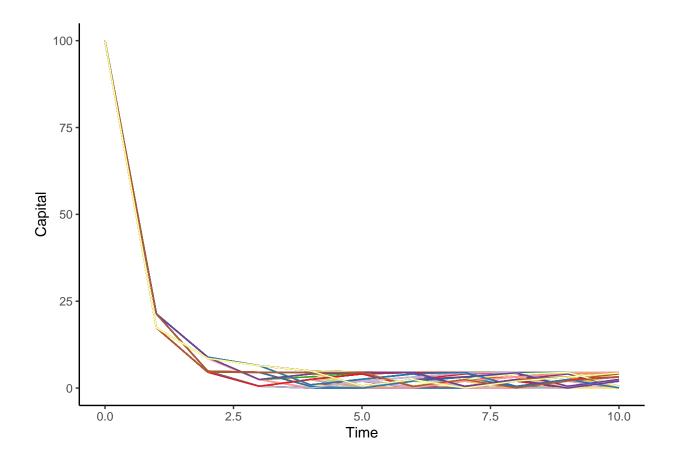
0.037 sec elapsed

plot consumption transition

```
p_8 <- ggplot()
for(i in 1:people){
    df <- data.frame(time = 1:t, consumption = con[i, ])
    p_8 <- p_8 +
        geom_line(
        data = df, aes(x = time, y = consumption),
        color = sample(brewer.pal(12, "Paired"), 1)
    )
}
p_8 <- p_8 +
    labs(x = "Time", y = "Consumption") +
    theme_classic()
p_8</pre>
```



```
p_9 <- ggplot()
for(i in 1:people){
    df <- data.frame(time = 0:t, capital = kap[i, ])
    p_9 <- p_9 +
        geom_line(
        data = df, aes(x = time, y = capital),
        color = sample(brewer.pal(12, "Paired"), 1)
    )
}
p_9 <- p_9 +
    labs(x = "Time", y = "Capital") +
    theme_classic()
p_9</pre>
```



(ii)-(b)

```
tic()
# setup parameters and simulate shocks
set.seed(2022)
t <- 10
people <- 100
Kl <- 100
V <- cbind(matrix(rep(NA, length(K)*t), ncol = t), matrix(rep(0, length(K)), ncol = 1))</pre>
epsilon <-
  ifelse(purrr::rbernoulli(people*(t+1), 0.5), 2, -2) %>%
  matrix(ncol = t+1)
vf <-
  rep(NA, people*t) %>%
  matrix(ncol = t)
kap <- # capital
    runif(people, \min = 50, \max = 100), # k_{0}
    matrix(rep(NA, people*t), ncol = t)
con <- # consumption</pre>
  rep(NA, people*t) %>%
  matrix(ncol = t)
```

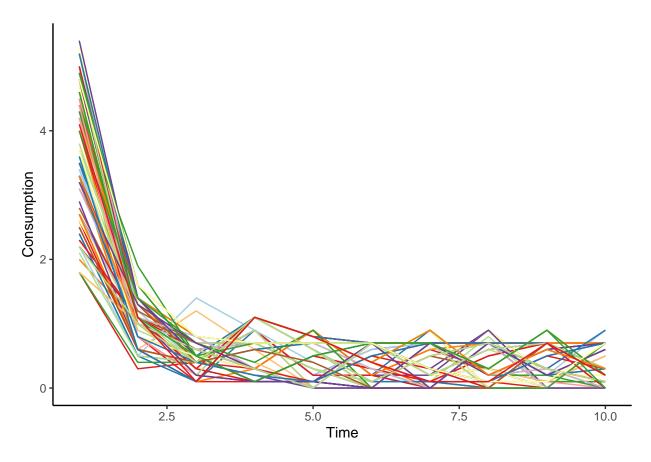
```
for(p in 1:people){
  for(t_iter in 1:t){
    position <-
        which(abs(K - kap[p, t_iter]) == min(abs(K - kap[p, t_iter]), na.rm = TRUE))[1]
    vf[p, t_iter] <- V_stoch[position]

    con[p, t_iter] <-
        seq(from = 1e-10, to = K[position], by = 0.1)[optC_stoch[position]]
    k_tmp <- Theta*kap[p, t_iter]^(Alpha) - con[p, t_iter] + epsilon[p + t_iter + 1]
    kap[p, t_iter + 1] <- ifelse(k_tmp > 0, k_tmp, 0)
    }
}
toc()
```

0.027 sec elapsed

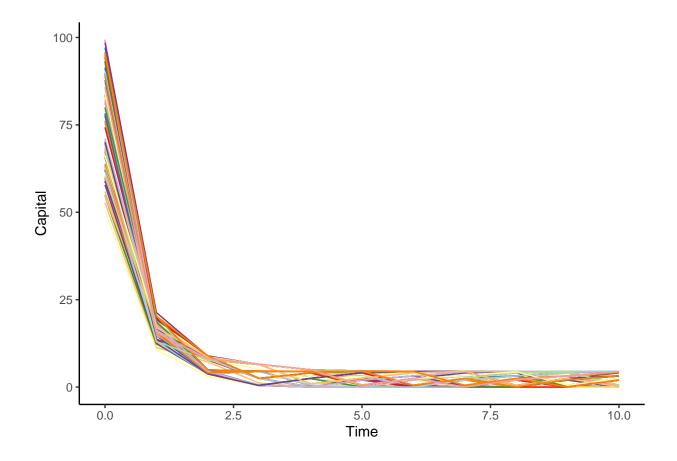
Transision of Consumption

```
p_10 <- ggplot()
for(i in 1:people){
    df <- data.frame(time = 1:t, consumption = con[i, ])
    p_10 <- p_10 +
        geom_line(
        data = df, aes(x = time, y = consumption),
        color = sample(brewer.pal(12, "Paired"), 1)
    )
}
p_10 <- p_10 +
    labs(x = "Time", y = "Consumption") +
    theme_classic()
p_10</pre>
```



Transision of Capital

```
p_11 <- ggplot()
for(i in 1:people){
    df <- data.frame(time = 0:t, capital = kap[i, ])
    p_11 <- p_11 +
        geom_line(
        data = df, aes(x = time, y = capital),
        color = sample(brewer.pal(12, "Paired"), 1)
    )
}
p_11 <- p_11 +
    labs(x = "Time", y = "Capital") +
    theme_classic()
p_11</pre>
```



(iii)

Reference

 \bullet Adams, A., D. Clarke, and S. Quinn. Microeconometrics and MATLAB. Oxford University Press, 2015.