Computing stuff tied to the physical world



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Fixing the Arduino's PWM #2

In AVR, Software on Nov 9, 2011 at 00:01

Yesterday's post identified a problem in the way different PWM pulses are generated in the ATmega.

It's all a matter of configuration, since evidently the timers used to generate the PWM signals all run off the same clock signal, and can therefore be made to cycle at *exactly* the same rate (they don't have to roll over at the same time for our purposes, but they *do* have to count equally fast).

The problem is caused by the fact than PWM pins D.5 and D.6 are based on timer 0, which is also used as millisecond timer, whereas PWM pin D.9 is based on timer 1. It's not a good idea to mess with timer 0, because that would affect the delay() and millis() code and affect all parts of a sketch which are timing-dependent.

Timer 0 is set in "Fast PWM" mode, which is not perfect. So the Wiring / Arduino team decided to use "Phase Correct PWM" mode for timers 1 and 2.

In *Fast PWM* mode, the timer just counts from 0 to 255, and the PWM output turns high when the counter is in a specific range. So far so good.

In *Phase Correct PWM* mode, the timer counts from 0 to 255 and then back to 0. Again, the PWM output turns high when the counter is in a specific range.

The phase correct mode counts up and down, and takes twice as long, so that explains why the green LED output runs at half the speed of the others.

Except that... it's not exactly twice!

Timer 0 wraps every 256 counts, and that should be kept as is to keep the millisecond code happy.

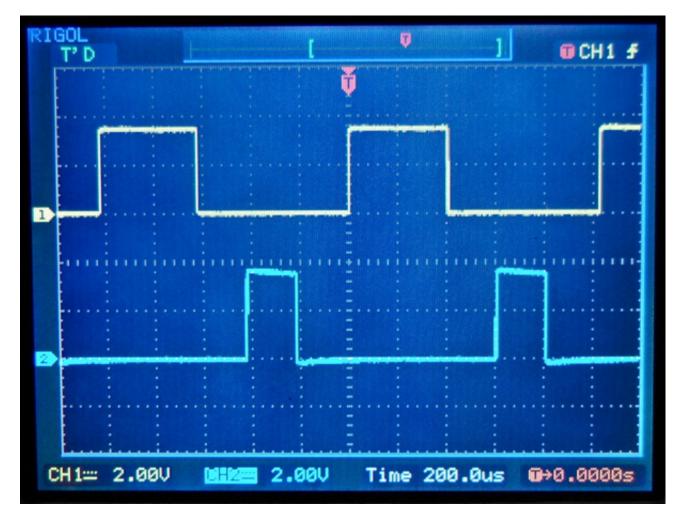
But timers 1 and 2 wrap every $0 \rightarrow 255 \rightarrow 0 = 511$ counts (I think – or is it 510?). Hence the out-of-sync effect which is causing so much trouble for the LED Node.

See also Ken Shirriff informative page titled <u>Secrets of Arduino PWM</u>, for the ins and outs of PWM.

The solution turns out to be ridiculously simple:

```
bitSet(TCCR1B, WGM12);
```

Just adding that single-bit change to setup() will force timer 1 into Fast PWM mode as well. The result:



This picture was taken with the scope running. The signals are in lock-step and rock solid. More importantly, the result is a perfectly smooth LED light – *yippie!*

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