

Automated Reasoning

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Fall 2024

Lecture 6: SMT for Linear Arithmetic

Slides inspired by:
Erika Abraham, RWTH,
Ashutosh Gupta, IITB,
Kroening & Strichman, Decision Procedures

Today's Lecture

- SMT with linear arithmetic & linear programming
- Generalized Simplex
- SMT-compliant Simplex
- Branch & Bound
- Difference logic

Goal:

Learn methods for automated reasoning about linear constraints in SMT

Linear Programming

An optimization problem

- Classic example with integer valued variables

A factory makes two products: Doors (D) and Frames (F).

- Constructing a D yields 70 euro profit
- Constructing a F yields 50 euro profit
- Building a D requires 2 units of wood, a F requires 1 unit of wood
- Building a D requires 4 hours, a F requires 3 hours
- We have 240 hours and 100 units of wood
- How to maximize profit?

Linear Programming

An optimization problem

- Classic example with real-valued variables

A factory makes two products: Beer (B) and Soda (S).

- Brewing B yields 70 euro profit
- Brewing HL of S yields 50 euro profit
- Brewing B requires 2 units of water, S requires 1 unit of water
- Brewing B requires 4 hours, S requires 3 hours
- We have 240 hours and 100 units of water
- How to maximize profit?

Encoding

maximize $70b + 50s$ s.t.

$$4 \cdot b + 3 \cdot s \leq 240$$

$$2 \cdot b + 1 \cdot s \leq 100$$

$$b \geq 0$$

$$s \geq 0$$

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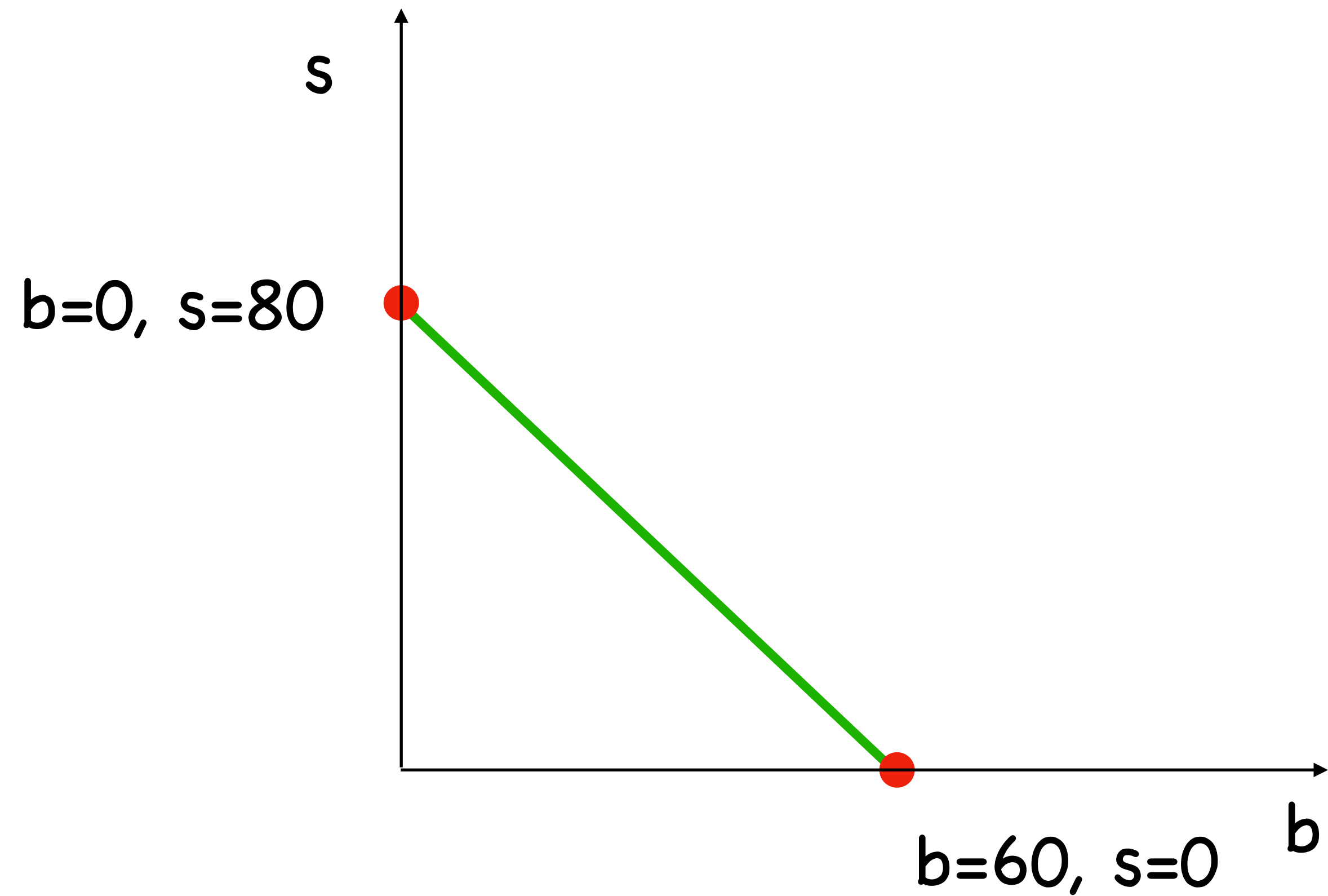
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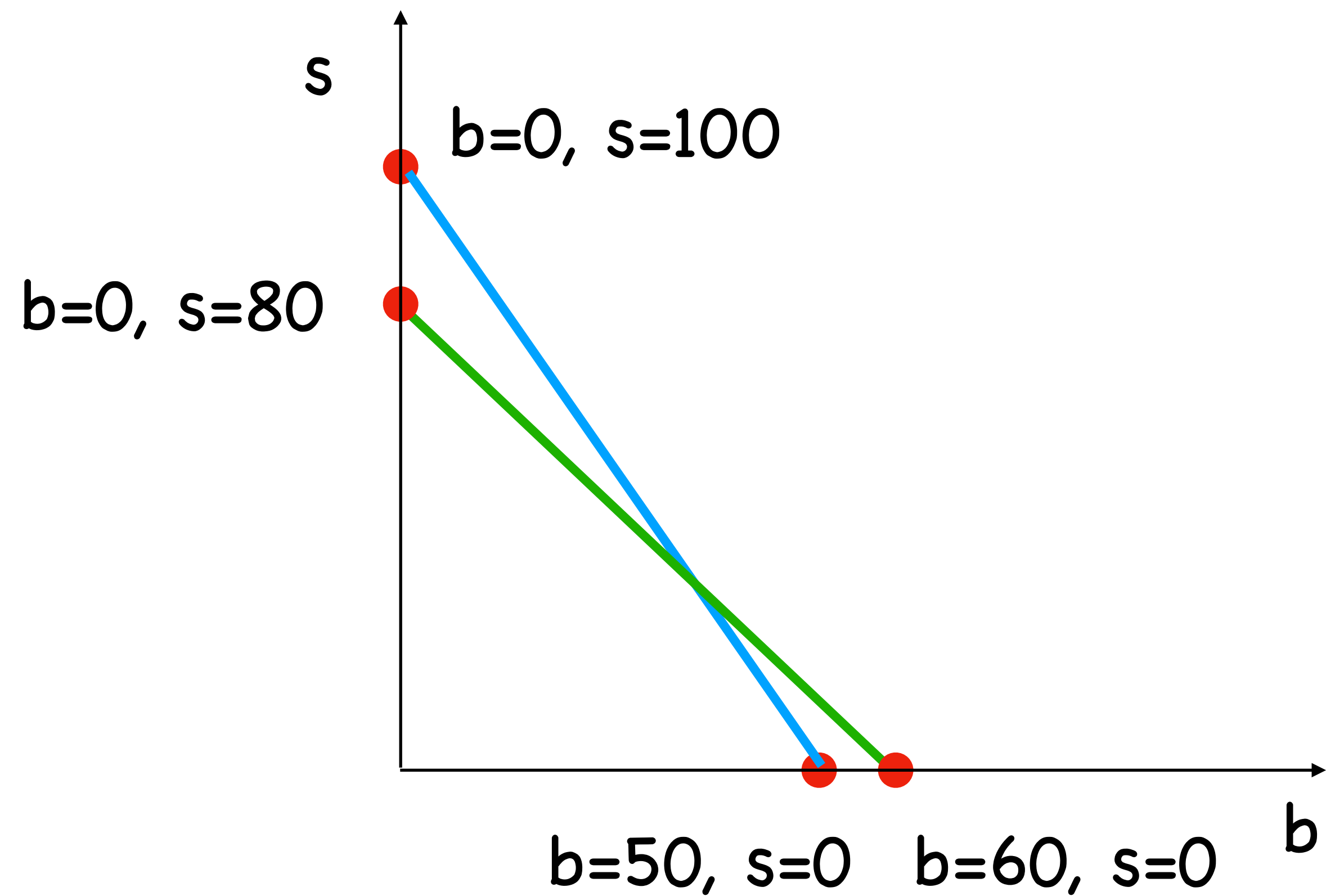
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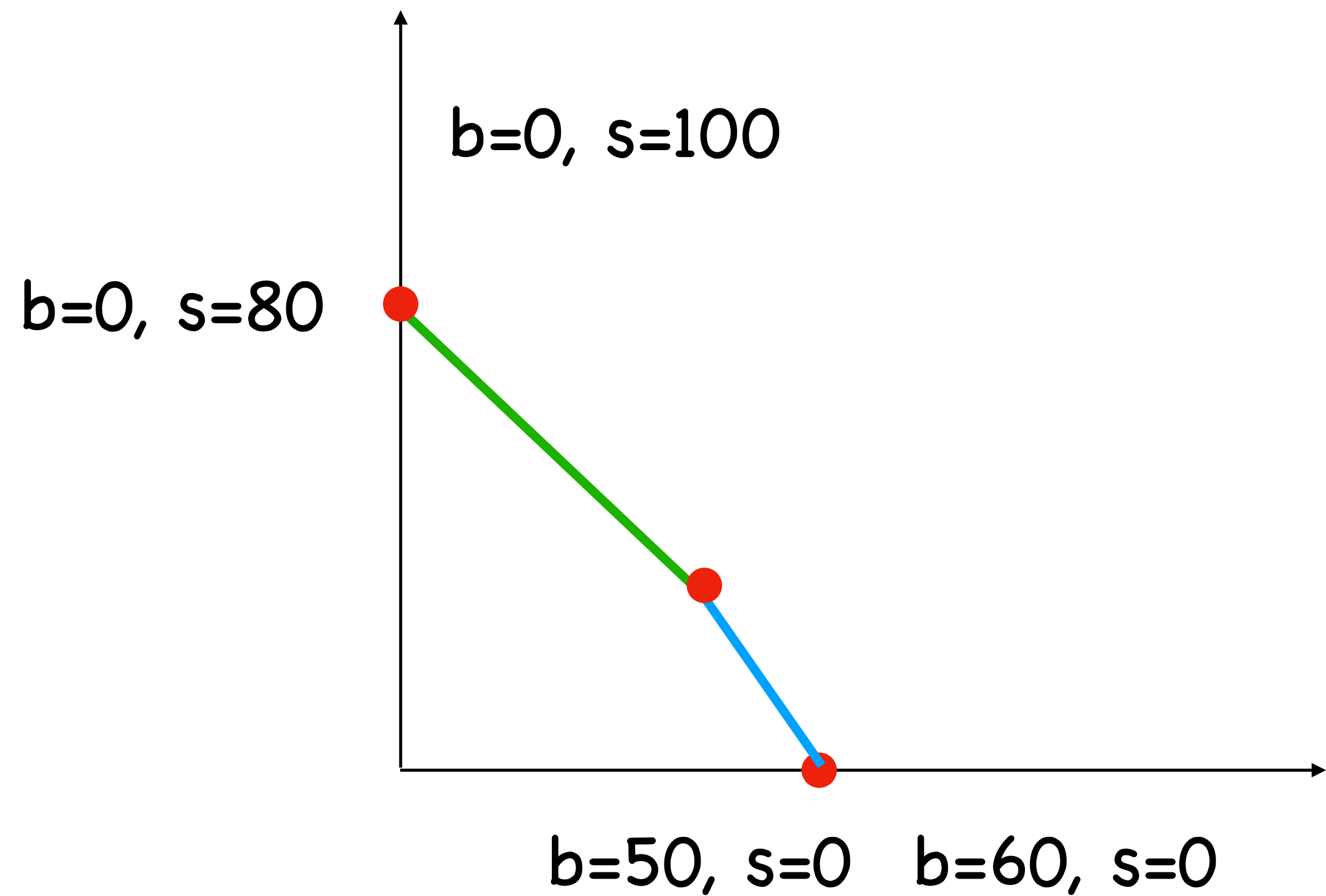
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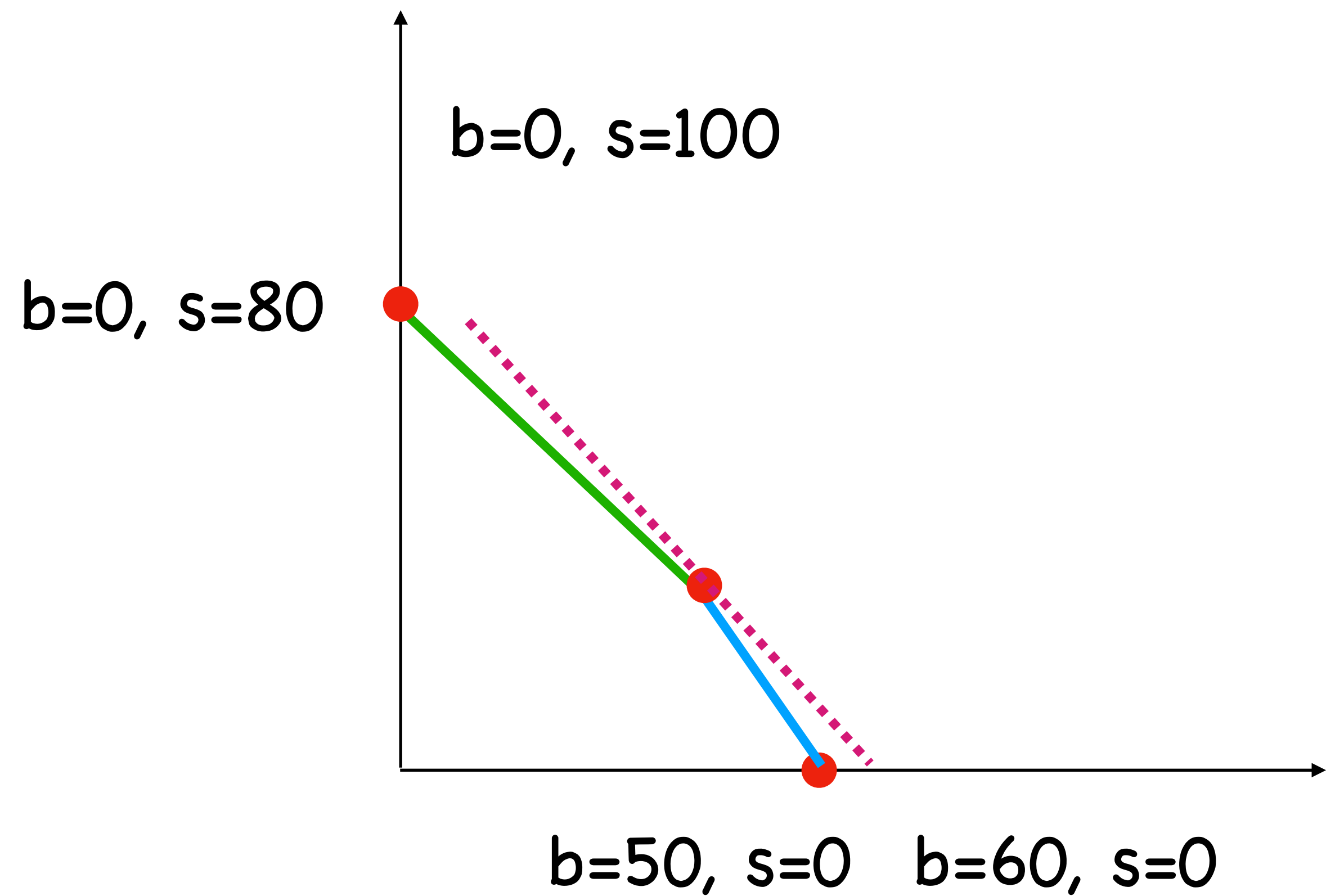
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Matrix Normal Form

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$$\begin{bmatrix} -4 & -3 \\ -2 & -1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} b \\ s \end{bmatrix} \geq \begin{bmatrix} -240 \\ -100 \\ 0 \\ 0 \end{bmatrix}$$

Quantifier-Free Linear Real Arithmetic

QF_LRA

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- Real valued variables, Constants

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Multiplication only with constants as syntactic sugar for addition...

Quantifier-Free Linear Real Arithmetic

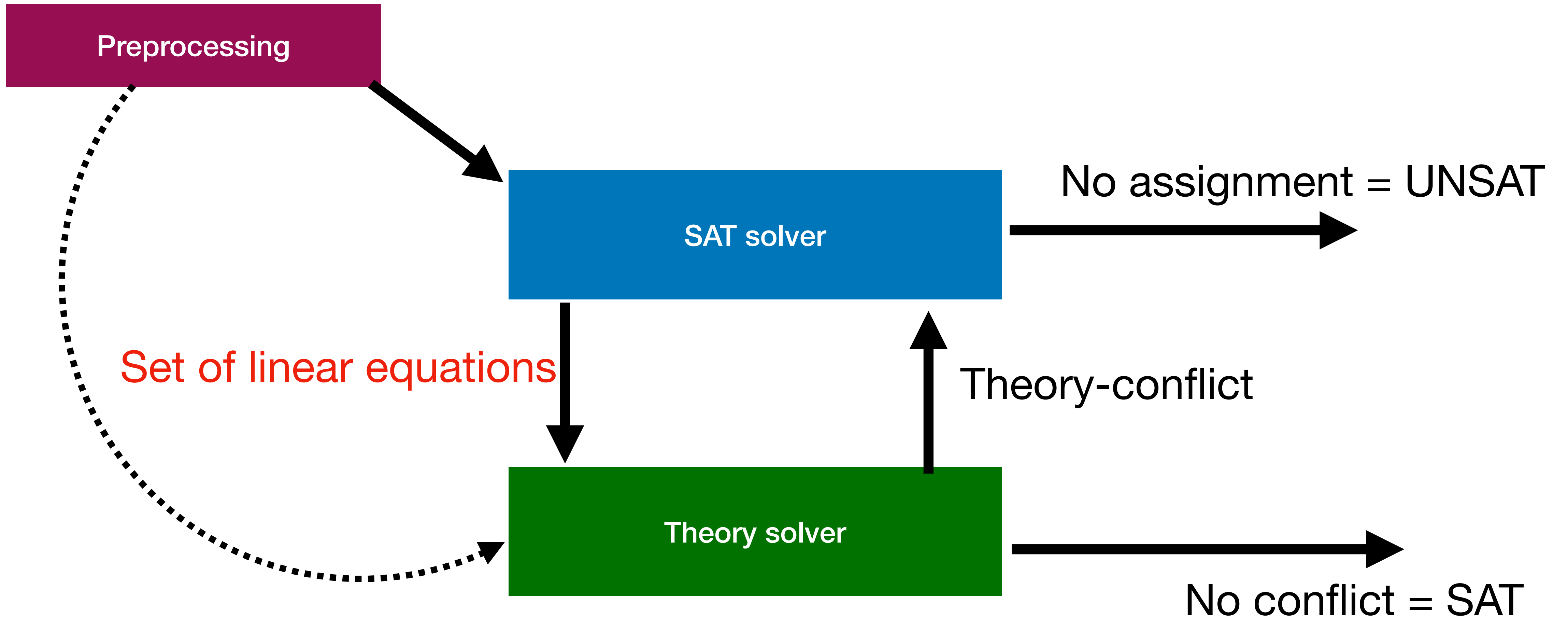
QF_LRA

- Real valued variables, Constants
- Addition between them
- Inequalities (focus on \leq , \geq)
- and their Boolean combination

Multiplication only with constants as syntactic sugar for addition...

Adds arbitrary Boolean combination of constraints to linear programming, but removes the objective (requires a constant objective)

DPLL(T) for QF_LRA



How to solve Linear Programs

How to solve Linear Programs

- Using an off-the-shelf LP solver:
GLPK, GLOP, LPsolve, Soplex, Gurobi, Mosek, CPLEX, Cardinal Opt,

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- Simplex algorithm (1920s); worst-case exponential runtime
- Interior point or barrier methods (1979); polynomial runtime
- (Variations of) simplex still practically superior in many cases
- For precise arithmetic and SMT-compliant theory solving, simplex is standard

Summary

- Linear programming & QF_LRA
- Generalized Simplex
- Incrementality & Backtracking for Generalized Simplex
- Branch & Bound for QF_LIA
- Difference logic

Generalized Simplex

- Consider the **feasibility** of linear equations of the following form

$$A \cdot \begin{bmatrix} x_1 \\ \dots \\ x_n \\ s_1 \\ \dots \\ s_m \end{bmatrix} = 0, \quad \bigwedge_{1 \leq i \leq m} l_i \leq s_i \leq u_i$$

i.e.,

variables x_1, \dots, x_n , **unbounded**, and additional variables s_1, \dots, s_m **bounded**

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Simplex for optimization starts with a feasible point while our goal is to find a feasible point
(but is similar in almost all other aspects)

i.e.,

variables x_1, \dots, x_n , **unbounded**, and additional variables s_1, \dots, s_m **bounded**

Quiztime

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Bring $x + y \geq 2$ into generalized form

Example

$$x_1 + x_2 \geq 2$$

$$2x_1 - x_2 \geq 0$$

$$-x_1 - 2x_2 \geq 1$$

Example

$$\begin{array}{l} x_1 + x_2 \geq 2 \\ 2x_1 - x_2 \geq 0 \\ -x_1 - 2x_2 \geq 1 \end{array} \quad \Rightarrow \quad \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \geq \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$$

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Tableaux-Notation

$$\begin{bmatrix} 1 & 1 & -1 & 0 & 0 \\ 2 & -1 & 0 & -1 & 0 \\ -1 & 2 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ s_1 \\ s_2 \\ s_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

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 \hline
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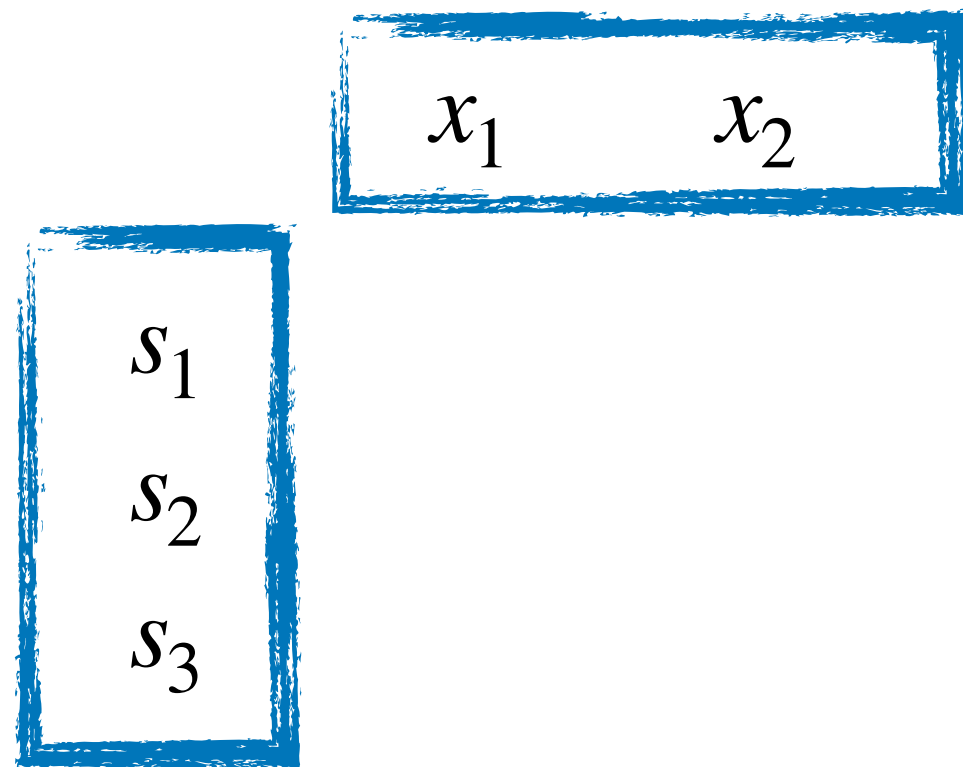
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Tableaux-Notation



Nonbasic variables \mathcal{N}

Basic variables \mathcal{B}

$$s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1$$

Tableaux-Notation

	x_1	x_2
s_1	1	1
s_2	2	-1
s_3	-1	2

Nonbasic variables \mathcal{N}

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	x_1	x_2	Nonbasic variables \mathcal{N}
s_1	1	1	
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s_3	-1	2	

Basic variables \mathcal{B}

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The tableaux represents the following system of linear equations:

$$\bigwedge_{x_i \in \mathcal{B}} \left(x_i = \sum_{x_j \in \mathcal{N}} a_{ij} x_j \right)$$

We call them the **Tableaux-Equations**

The Simplex Algorithm

- Search for a satisfying assignment
- Series of pivot operations guide towards that assignment
- Pivots preserve inequalities

The Simplex Datastructures

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- The bounds on the variables remain constant

$$\forall x \in \mathcal{B} \cup \mathcal{N} : l_i \leq x_i \leq u_i$$

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The Simplex Datastructures

- The bounds on the variables remain constant

$$\forall x \in \mathcal{B} \cup \mathcal{N} : l_i \leq x_i \leq u_i$$

- Maintain a tableaux
- Maintain an assignment $\alpha: x \rightarrow \mathbb{Q}$

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Simplex Datastructures

Initialization

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Simplex Datastructures

Initialization

$$\begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} \begin{array}{cc} x_1 & x_2 \\ \left[\begin{array}{cc} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{array} \right] \end{array}$$

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$$\forall x \in \mathcal{B} \cup \mathcal{N} : l_i \leq x_i \leq u_i$$

- Construct a tableaux as outlined before:
 - The basic variables are the additional variables
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$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

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- Construct a tableaux as outlined before:
 - The basic variables are the additional variables
 - The nonbasic variables are the problem variables
- Construct an assignment $\alpha: x \rightarrow \mathbb{Q}$ with $\alpha(x) = 0$

The Simplex Invariants

- Simplex maintains two invariants
 1. $A\vec{x} = \vec{0}$ (i.e., the tableaux equalities do hold)
 2. For each nonbasic variable $x_j \in \mathcal{N}$, it holds that $l_j \leq \alpha(x_j) \leq u_j$

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Initially, simplex satisfies its invariants!

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The bounds on the basic variables may be violated

If simplex finds an assignment α that respects the bounds on the basic variables, α is a satisfying solution to the LP

Simplex

With a violated bound

$$\begin{array}{cc} & x_1 & x_2 \\ s_1 & \left[\begin{array}{cc} 1 & 1 \end{array} \right] \\ s_2 & \left[\begin{array}{cc} 2 & -1 \end{array} \right] \\ s_3 & \left[\begin{array}{cc} -1 & 2 \end{array} \right] \end{array} \quad s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1$$
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- To increase $\alpha(x_i)$ we must either:

- increase some x_j with $a_{i,j} > 0$ and $\alpha(x_j) < u_j$
- decrease some x_j with $a_{i,j} < 0$ and $\alpha(x_j) > l_j$

Simplex

With a violated bound

$$\begin{array}{cc}
 & x_1 & x_2 \\
 s_1 & \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} & s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1 \\
 s_2 & & \\
 s_3 & &
 \end{array}
 \alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

- Let x_i violate it's lower bound (the upper bound case is symmetrical)
- Thus, $\alpha(x_i) < l_i$
- Recall that x_i must be basic (why?)

• Thus, use the tableaux equality $x_i = \sum_{x_j \in \mathcal{N}} a_{ij} x_j$ is satisfied by $\alpha(x_i) = \sum a_{ij} \cdot \alpha(x_j)$

- To increase $\alpha(x_i)$ we must either:
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Such x_j is suitable

Simplex

Update with a violated bound

Simplex

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- How much: Just enough to ensure the bound
- We increase $\alpha(x_j)$ by $\theta = \frac{l_i - \alpha(x_i)}{a_{ij}}$

Simplex

Update with a violated bound

- Thus, $\alpha(x_i) < l_i$ and $x_i = \sum_{x_j \in \mathcal{N}} a_{ij} x_j$
 - To increase x_i we increase some x_j with $a_{i,j} > 0$ and $\alpha(x_j) < u_j$
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 - We increase $\alpha(x_j)$ by $\theta = \frac{l_i - \alpha(x_i)}{a_{ij}}$
- x_i will now satisfy the bound

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(decreasing is symmetric)
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 - We increase $\alpha(x_j)$ by $\theta = \frac{l_i - \alpha(x_i)}{a_{ij}}$
- x_i will now satisfy the bound
- x_j may now violate the bound

Pivot Operation

Intuition to preserve invariants

Pivot Operation

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- If nonbasic variable x_j now violates its bound, make it basic

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- Rewrite $x_i = a_{ij}x_j + \sum_{j \neq k, k \in \mathcal{N}} a_{ik}x_k$ to $x_j = \frac{x_i - \sum \dots}{a_{ij}}$

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- Use this to substitute all occurrences of x_j in the tableaux

Pivot

$$\begin{array}{cc} & x_1 & x_2 \\ s_1 & \left[\begin{array}{cc} 1 & 1 \end{array} \right] \\ s_2 & \left[\begin{array}{cc} 2 & -1 \end{array} \right] \\ s_3 & \left[\begin{array}{cc} -1 & 2 \end{array} \right] \end{array} \quad s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1$$
$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Pivot

$$\begin{array}{cc} & x_1 & x_2 \\ \begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} & \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} & \begin{array}{l} s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1 \\ \\ \alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \end{array}\end{array}$$

- s_1 violates its bound, x_1 is suitable.

Pivot

$$\begin{array}{cc} & x_1 & x_2 \\ \begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} & \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} & \begin{array}{l} s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1 \\ \\ \alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \end{array}\end{array}$$

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- Rewrite $s_1 = x_1 + x_2$ into $x_1 = s_1 - x_2$, use as a substitution rule

Pivot

$$\begin{array}{cc} & x_1 & x_2 \\ \begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} & \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} & \end{array} \quad s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1$$
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 $s_3 = -1x_1 + 2x_2$ becomes $s_3 = -s_1 + 3x_2$

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Update assignment

By example

$$\begin{array}{cc} & x_1 & x_2 \\ \begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} & \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} & \begin{array}{l} s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1 \\ \alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \end{array}\end{array}$$

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 \end{array}
 \quad
 s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1
 \quad
 \alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

- s_1 violates its bound, x_1 is suitable.

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

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$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

- s_1 violates its bound, x_1 is suitable.
- We must increase s_1 by two, we do this by increasing x_1 by two

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 2 & 0 & 2 & 0 & 0 \end{pmatrix}$$

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Update assignment

By example

$$\begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} \begin{array}{cc} x_1 & x_2 \\ \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} \end{array} \quad s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1$$

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

- s_1 violates its bound, x_1 is suitable.
- We must increase s_1 by two, we do this by increasing x_1 by two
- And update all other assignments accordingly

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 2 & 0 & 2 & 0 & 0 \end{pmatrix}$$

$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 2 & 0 & 2 & 4 & -2 \end{pmatrix}$$

$$\begin{array}{c} s_1 \\ s_2 \\ s_3 \end{array} \begin{array}{cc} x_1 & x_2 \\ \begin{bmatrix} 1 & 1 \\ 2 & -1 \\ -1 & 2 \end{bmatrix} \end{array} \quad \text{becomes} \quad \begin{array}{c} x_1 \\ s_2 \\ s_3 \end{array} \begin{array}{cc} s_1 & x_2 \\ \begin{bmatrix} 1 & -1 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} \end{array}$$

Pivot

By example

$$\begin{array}{cc} & s_1 & x_2 \\ \begin{array}{c} x_1 \\ s_2 \\ s_3 \end{array} & \begin{bmatrix} 1 & -1 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} & \end{array} \quad s_1 \geq 2 \wedge s_2 \geq 0 \wedge s_3 \geq 1$$
$$\alpha = \begin{pmatrix} x_1 & x_2 & s_1 & s_2 & s_3 \\ 2 & 0 & 2 & 4 & -2 \end{pmatrix}$$

- s_3 violates its bound, x_2 is suitable.
- Rewrite $s_3 = -s_1 + 3x_2$ into $x_2 = \frac{s_3 + s_1}{3}$, use as a substitution rule

$$\begin{array}{cc} & s_1 & x_2 \\ \begin{array}{c} x_1 \\ s_2 \\ s_3 \end{array} & \begin{bmatrix} 1 & -1 \\ 2 & -3 \\ -1 & 3 \end{bmatrix} & \end{array} \quad \text{becomes} \quad \begin{array}{cc} & s_1 & s_3 \\ \begin{array}{c} x_1 \\ s_2 \\ x_2 \end{array} & \begin{bmatrix} \frac{2}{3} & \frac{-1}{3} \\ 1 & -1 \\ \frac{1}{3} & \frac{1}{3} \end{bmatrix} & \end{array}$$

About Pivots

(Again)

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- Pivots are equivalence transformations, describe the same system
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- We do not cycle...
 - Assuming we pick variables satisfying the bounds and suitable variables from a global order, we are guaranteed to terminate (Bland's Rule).

Generalized Simplex

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 - A. Find the **smallest** suitable nonbasic variable or **return** UNSAT
 - B. **Pivot and update assignment**
4. **return** SAT

Beyond Generalized Simplex

- Use some heuristic to pick variables, if we do not terminate, fall back to Bland's Rule.
- Select variables to minimize $\text{sum of violations} / \text{slack}$
- Handle strict inequalities using an infinitesimal small constant
- Lots of preprocessing

Summary

- Linear programming & QF_LRA
- Generalized Simplex
- Incrementality & Backtracking for Generalized Simplex
- Branch & Bound for QF_LIA
- Difference logic

Iterative Simplex

Focus on essential aspects

- How to generate unfeasible subsets?
- How to ensure incrementality?

Infeasible Subsets

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- UNSAT, so no x_j suitable. Bounds for x_i and all x_j with $a_{ij} \neq 0$ are explanation
- Only additional variables have bounds \rightarrow these encode constraints.

Incrementality and Backtracking

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- Assume an LP with constraints C has been checked and now you want to check $C \cup \{c\}$?

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- Just adding a row can be difficult as the nonbasic variables may not coincide with the original variables
- (Assume that all constraints are part of an a-priori known system)
- Create a tableaux with all constraints, but only enforce bounds for active constraints
- Adding a constraint: Enforcing the bound.
Removing a constraint: Restore assignment to last known satisfying assignment

DPLL(T)

Example

Initialize the Simplex tableau with all equalities but **without any bounds**.

$$\begin{array}{llllll}
 p_1 = 0 & \rightarrow & s_1 = & p_1 & & s_1 = 0 \\
 p_2 = 0 & \rightarrow & s_2 = & & p_2 & s_2 = 0 \\
 p_3 = 0 & \rightarrow & s_3 = & & & p_3 & s_3 = 0 \\
 p_1 + p_2 + p_3 \geq 100 & \rightarrow & s_4 = & p_1 + & p_2 + & p_3 & s_4 \geq 100 \\
 p_1 \geq 5 & \rightarrow & s_5 = & p_1 & & & s_5 \geq 5 \\
 p_2 \geq 5 & \rightarrow & s_6 = & & p_2 & & s_6 \geq 5 \\
 p_3 \geq 10 & \rightarrow & s_7 = & & & p_3 & s_7 \geq 10 \\
 p_1 + 2p_2 + 5p_3 \leq 180 & \rightarrow & s_8 = & p_1 + & 2p_2 + & 5p_3 & s_8 \leq 180 \\
 3p_1 + 2p_2 + p_3 \leq 300 & \rightarrow & s_9 = & 3p_1 + & 2p_2 + & p_3 & s_9 \leq 300
 \end{array}$$

	$p_1(0)$	$p_2(0)$	$p_3(0)$
$s_1(0)$	1	0	0
$s_2(0)$	0	1	0
$s_3(0)$	0	0	1
$s_4(0)$	1	1	1
$s_5(0)$	1	0	0
$s_6(0)$	0	1	0
$s_7(0)$	0	0	1
$s_8(0)$	1	2	5
$s_9(0)$	3	2	1

DPLL(T)

Example

$$(a_1 \vee a_2 \vee a_3) \wedge a_4 \wedge (a_5 \vee a_6) \wedge a_7 \wedge a_8 \wedge a_9$$

Assume a fixed variable order: a_1, \dots, a_9

Assignment to decision variables: false

$DL0 : a_4 : 1, a_7 : 1, a_8 : 1, a_9 : 1$

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 = p_1$	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 = p_2$	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 = p_3$	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 = p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 = p_1$	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 = p_2$	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 = p_3$	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 = p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 = 3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

Variable order: $s_1 < \dots < s_9 < p_1 < p_2 < p_3$, the values of the variables are given in parentheses

	$p_1(0)$	$p_2(0)$	$p_3(0)$
$s_1(0)$	1	0	0
$s_2(0)$	0	1	0
$s_3(0)$	0	0	1
$s_4(0)$	1	1	1
$s_5(0)$	1	0	0
$s_6(0)$	0	1	0
$s_7(0)$	0	0	1
$s_8(0)$	1	2	5
$s_9(0)$	3	2	1

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 =$	p_1	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 =$	p_2	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 =$	p_3	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$	p_2	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$	p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

Variable order: $s_1 < \dots < s_9 < p_1 < p_2 < p_3$, the values of the variables are given in parentheses

	$p_1(0)$	$p_2(0)$	$p_3(0)$		$s_4(100)$	$p_2(0)$	$p_3(0)$
$s_1(0)$	1	0	0	$s_1(100)$	1	-1	-1
$s_2(0)$	0	1	0	$s_2(0)$	0	1	0
$s_3(0)$	0	0	1	$s_3(0)$	0	0	1
$s_4(0)$	1	1	1	$p_1(100)$	1	-1	-1
$s_5(0)$	1	0	0	$s_5(100)$	1	-1	-1
$s_6(0)$	0	1	0	$s_6(0)$	0	1	0
$s_7(0)$	0	0	1	$s_7(0)$	0	0	1
$s_8(0)$	1	2	5	$s_8(100)$	1	1	4
$s_9(0)$	3	2	1	$s_9(300)$	3	-1	-2

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 =$	p_1	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 =$	p_2	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 =$	p_3	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$	p_2	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$	p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

Variable order: $s_1 < \dots < s_9 < p_1 < p_2 < p_3$, the values of the variables are given in parentheses

	$p_1(0)$	$p_2(0)$	$p_3(0)$		$s_4(100)$	$p_2(0)$	$p_3(0)$		$s_4(100)$	$p_2(0)$	$s_7(10)$
$s_1(0)$	1	0	0	$s_1(100)$	1	-1	-1	$s_1(90)$	1	-1	-1
$s_2(0)$	0	1	0	$s_2(0)$	0	1	0	$s_2(0)$	0	1	0
$s_3(0)$	0	0	1	$s_3(0)$	0	0	1	$s_3(10)$	0	0	1
$s_4(0)$	1	1	1	$p_1(100)$	1	-1	-1	$p_1(90)$	1	-1	-1
$s_5(0)$	1	0	0	$s_5(100)$	1	-1	-1	$s_5(90)$	1	-1	-1
$s_6(0)$	0	1	0	$s_6(0)$	0	1	0	$s_6(0)$	0	1	0
$s_7(0)$	0	0	1	$s_7(0)$	0	0	1	$p_3(10)$	0	0	1
$s_8(0)$	1	2	5	$s_8(100)$	1	1	4	$s_8(140)$	1	1	4
$s_9(0)$	3	2	1	$s_9(300)$	3	-1	-2	$s_9(280)$	3	-1	-2

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 =$	p_1	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 =$	p_2	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 =$	p_3	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$	p_2	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$	p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

Variable order: $s_1 < \dots < s_9 < p_1 < p_2 < p_3$, the values of the variables are given in parentheses

	$p_1(0)$	$p_2(0)$	$p_3(0)$		$s_4(100)$	$p_2(0)$	$p_3(0)$		$s_4(100)$	$p_2(0)$	$s_7(10)$
$s_1(0)$	1	0	0	$s_1(100)$	1	-1	-1	$s_1(90)$	1	-1	-1
$s_2(0)$	0	1	0	$s_2(0)$	0	1	0	$s_2(0)$	0	1	0
$s_3(0)$	0	0	1	$s_3(0)$	0	0	1	$s_3(10)$	0	0	1
$s_4(0)$	1	1	1	$p_1(100)$	1	-1	-1	$p_1(90)$	1	-1	-1
$s_5(0)$	1	0	0	$s_5(100)$	1	-1	-1	$s_5(90)$	1	-1	-1
$s_6(0)$	0	1	0	$s_6(0)$	0	1	0	$s_6(0)$	0	1	0
$s_7(0)$	0	0	1	$s_7(0)$	0	0	1	$p_3(10)$	0	0	1
$s_8(0)$	1	2	5	$s_8(100)$	1	1	4	$s_8(140)$	1	1	4
$s_9(0)$	3	2	1	$s_9(300)$	3	-1	-2	$s_9(280)$	3	-1	-2

Return partial SAT.

DPLL(T)

Example

$$(a_1 \vee a_2 \vee a_3) \wedge a_4 \wedge (a_5 \vee a_6) \wedge a_7 \wedge a_8 \wedge a_9$$

Assume a fixed variable order: a_1, \dots, a_9

Assignment to decision variables: false

$DL0 : a_4 : 1, a_7 : 1, a_8 : 1, a_9 : 1$

$DL1 : a_1 : 0$

$DL2 : a_2 : 0, a_3 : 1$

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 =$	p_1	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 =$	p_2	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 =$	p_3	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$	p_2	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$	p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 =$	p_1	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 =$	p_2	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 =$	p_3	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$	p_2	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$	p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

	$s_4(100)$	$p_2(0)$	$s_7(10)$
$s_1(90)$	1	-1	-1
$s_2(0)$	0	1	0
$s_3(10)$	0	0	1
$p_1(90)$	1	-1	-1
$s_5(90)$	1	-1	-1
$s_6(0)$	0	1	0
$p_3(10)$	0	0	1
$s_8(140)$	1	1	4
$s_9(280)$	3	-1	-2

DPLL(T)

Example

$p_1 = 0$	\rightarrow	$s_1 =$	p_1	$s_1 = 0$
$p_2 = 0$	\rightarrow	$s_2 =$	p_2	$s_2 = 0$
$p_3 = 0$	\rightarrow	$s_3 =$	p_3	$s_3 = 0$
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 + p_2 + p_3$	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1	$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$	p_2	$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$	p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 + 2p_2 + 5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 + 2p_2 + p_3$	$s_9 \leq 300$

	$s_4(100)$	$p_2(0)$	$s_7(10)$
$s_1(90)$	1	-1	-1
$s_2(0)$	0	1	0
$s_3(10)$	0	0	1
$p_1(90)$	1	-1	-1
$s_5(90)$	1	-1	-1
$s_6(0)$	0	1	0
$p_3(10)$	0	0	1
$s_8(140)$	1	1	4
$s_9(280)$	3	-1	-2

Conflict: $\underbrace{p_3 = 0}_{a_3} \wedge \underbrace{p_3 \geq 10}_{a_7}$ is not satisfiable.

DPLL(T)

Example

Current assignment:

$DL0 : a_4 : 1, a_7 : 1, a_8 : 1, a_9 : 1$

$DL1 : a_1 : 0$

$DL2 : a_2 : 0, a_3 : 1$

Add clause $(\neg a_3 \vee \neg a_7)$:

$$(a_1 \vee a_2 \vee a_3) \wedge a_4 \wedge (a_5 \vee a_6) \wedge a_7 \wedge a_8 \wedge a_9 \wedge (\neg a_3 \vee \neg a_7)$$

No conflict resolution needed, since the new clause is already asserting.
Backtracking removes $DL1$ and $DL2$ first, then propagation is applied.

$DL0 : a_4 : 1, a_7 : 1, a_8 : 1, a_9 : 1, a_3 : 0$

$DL1 : a_1 : 0, a_2 : 1$

DPLL(T)

Example

Backtracking: remove bound $s_3 = 0$, add bound $s_2 = 0$

$p_1 = 0$	\rightarrow	$s_1 =$	p_1		$s_1 = 0$	
$p_2 = 0$	\rightarrow	$s_2 =$		p_2	$s_2 = 0$	
$p_3 = 0$	\rightarrow	$s_3 =$		p_3	$s_3 = 0$	
$p_1 + p_2 + p_3 \geq 100$	\rightarrow	$s_4 =$	$p_1 +$	$p_2 +$	p_3	$s_4 \geq 100$
$p_1 \geq 5$	\rightarrow	$s_5 =$	p_1			$s_5 \geq 5$
$p_2 \geq 5$	\rightarrow	$s_6 =$		p_2		$s_6 \geq 5$
$p_3 \geq 10$	\rightarrow	$s_7 =$			p_3	$s_7 \geq 10$
$p_1 + 2p_2 + 5p_3 \leq 180$	\rightarrow	$s_8 =$	$p_1 +$	$2p_2 +$	$5p_3$	$s_8 \leq 180$
$3p_1 + 2p_2 + p_3 \leq 300$	\rightarrow	$s_9 =$	$3p_1 +$	$2p_2 +$	p_3	$s_9 \leq 300$

	$s_4(100)$	$p_2(0)$	$s_7(10)$
$s_1(90)$	1	-1	-1
$s_2(0)$	0	1	0
$s_3(10)$	0	0	1
$p_1(90)$	1	-1	-1
$s_5(90)$	1	-1	-1
$s_6(0)$	0	1	0
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$s_8(140)$	1	1	4
$s_9(280)$	3	-1	-2

Return partial SAT.

DPLL(T)

Example

- And so forth...
- Full example on https://ths.rwth-aachen.de/wp-content/uploads/sites/4/teaching/vorlesung_satchecking/ws14_15/06c_simplex_in_smt_handout.pdf

Integers

Integers

- Consider quantifier-free linear integer arithmetic (QF_LIA) which is like (QF_LRA) but over the integers.

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 - SAT implies...

Integers

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- The **relaxed problem instance** contains the same constraints, but assumes that variables are real-valued.
- Solve using simplex.
 - UNSAT implies original problem is UNSAT.
 - SAT implies...
 - Either all variables are assigned with an integer -> SAT

Integers

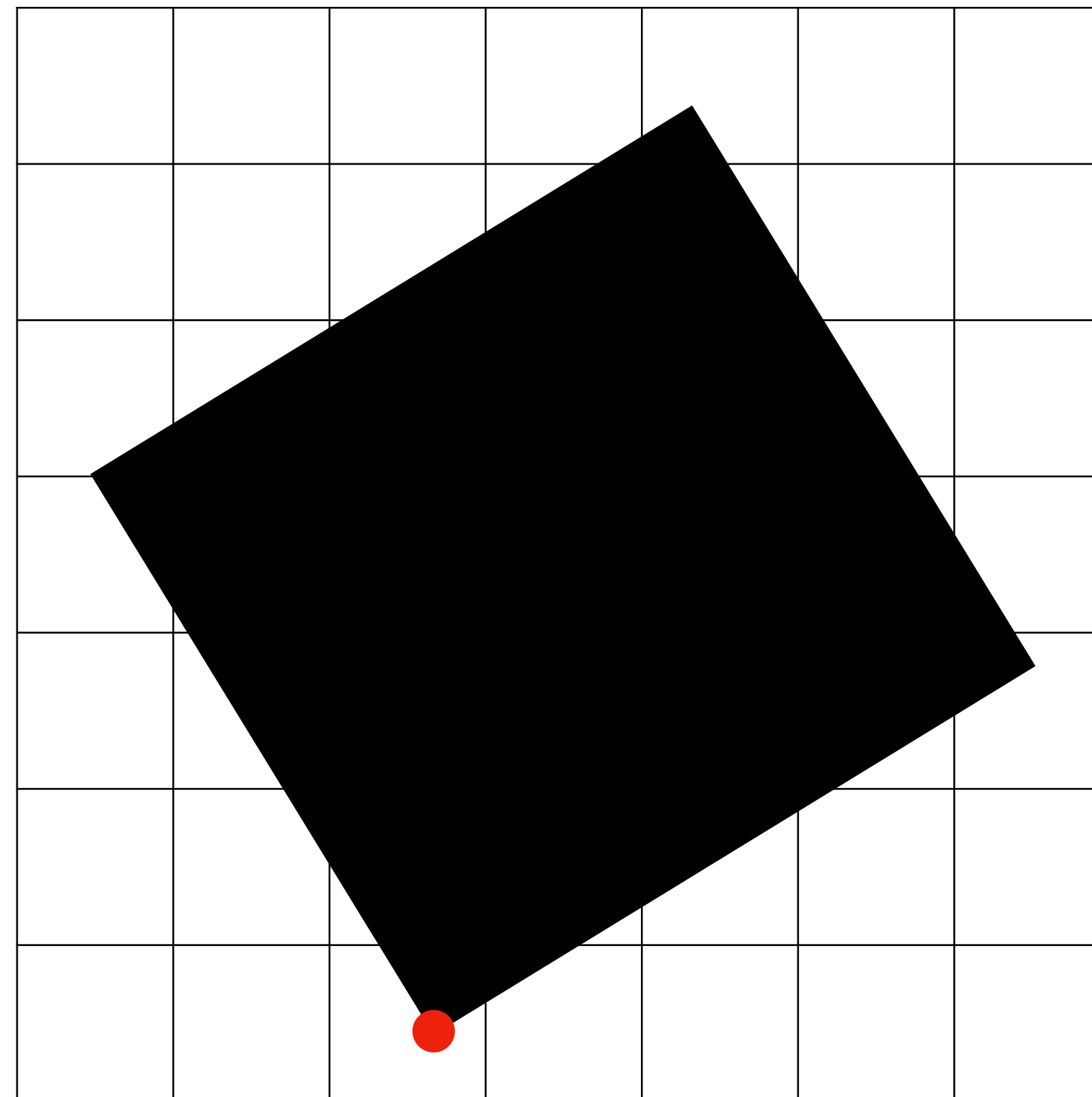
- Consider quantifier-free linear integer arithmetic (QF_LIA) which is like (QF_LRA) but over the integers.
- The **relaxed problem instance** contains the same constraints, but assumes that variables are real-valued.
- Solve using simplex.
 - UNSAT implies original problem is UNSAT.
 - SAT implies...
 - Either all variables are assigned with an integer \rightarrow SAT
 - At least one variable is assigned a real, non-integer value

Summary

- Linear programming & QF_LRA
- Generalized Simplex
- Incrementality & Backtracking for Generalized Simplex
- Branch & Bound for QF_LIA
- Difference logic

Integers

Branch-And-Bound Illustrated

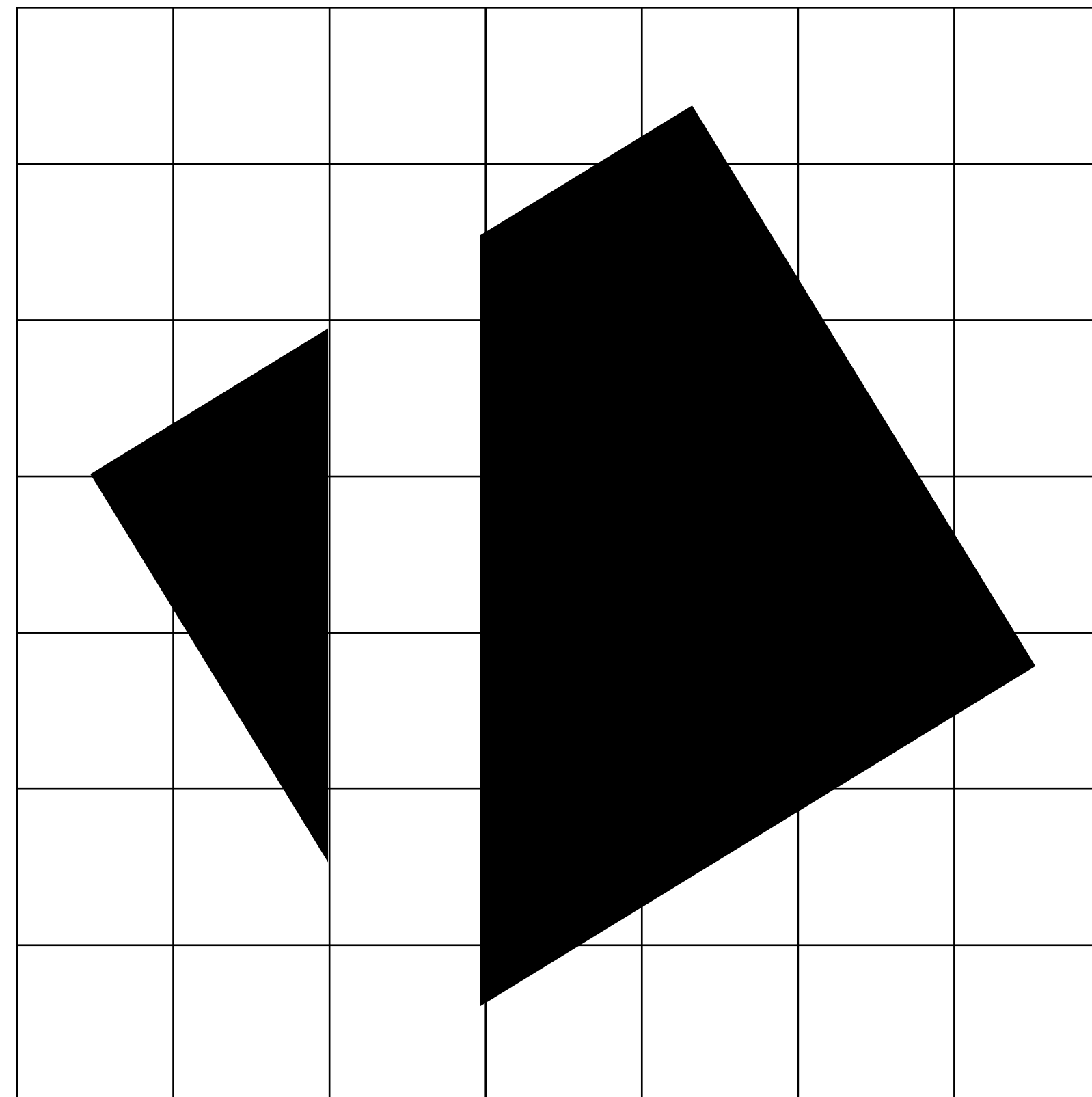


Solve the relaxed problem,

Find a real-valued solution

Integers

Branch-And-Bound Illustrated

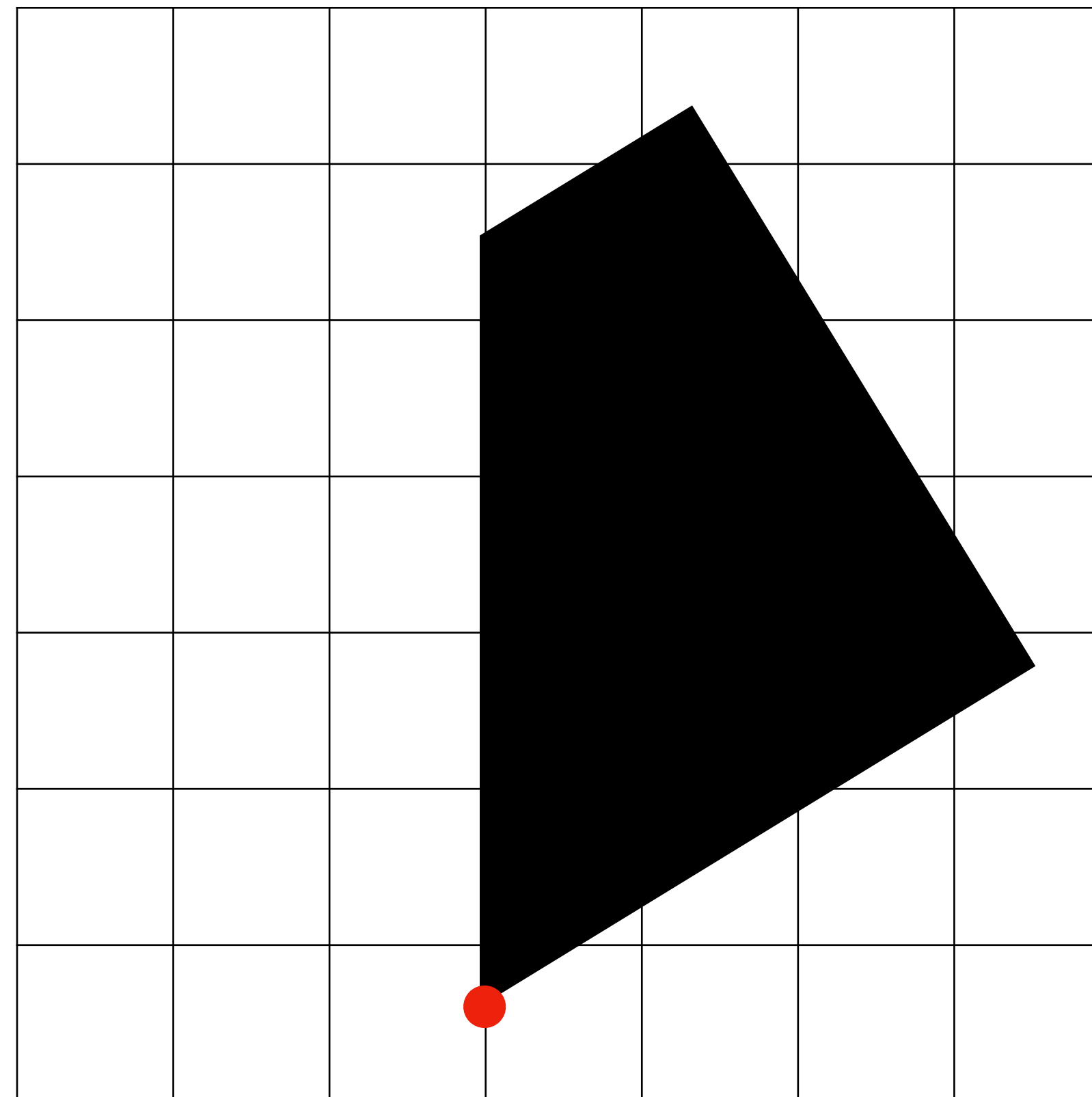


Exclude the solution

No longer conjunction
of linear constraints

Integers

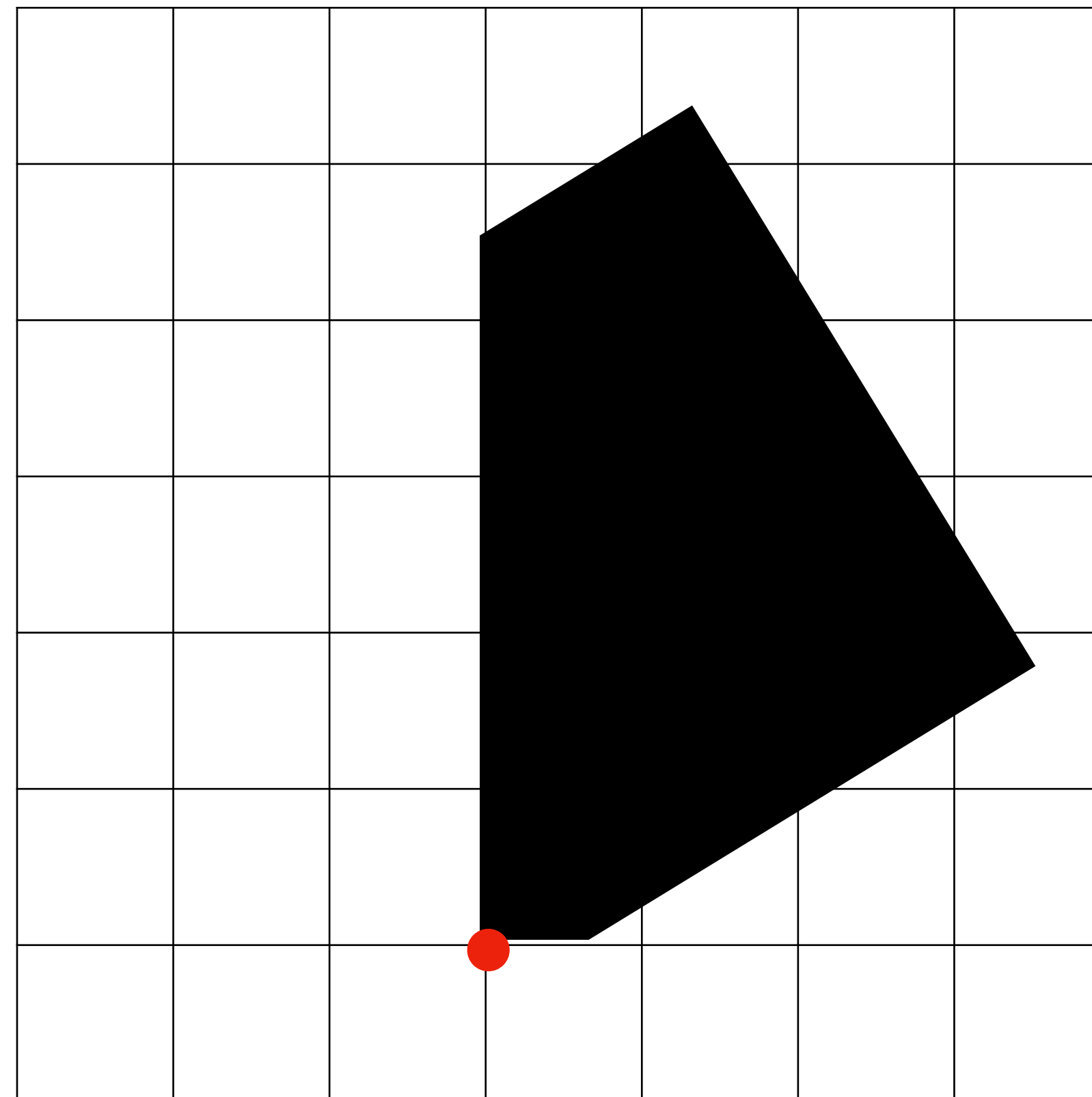
Branch-And-Bound Illustrated



Guess one side, repeat

Integers

Branch-And-Bound Illustrated



Until we find an
integer solution

Branch-And-Bound

Recursive algorithm

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex
2. **If** assignment α found

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex
2. **If** assignment α found
 - A. **If** $\alpha(x)$ integral for all variables **return** SAT

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex
2. **If** assignment α found
 - A. **If** $\alpha(x)$ integral for all variables **return** SAT
 - B. Pick variable x with $\alpha(x)$ not integral, $\alpha(x) = d.mmm$

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex
2. **If** assignment α found
 - A. **If** $\alpha(x)$ integral for all variables **return** SAT
 - B. Pick variable x with $\alpha(x)$ not integral, $\alpha(x) = d . mmm$
 - C. **If** Branch-and-bound ($C \cup \{x \leq d\}$) == SAT **return** SAT

Branch-And-Bound

Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex
2. **If** assignment α found
 - A. **If** $\alpha(x)$ integral for all variables **return** SAT
 - B. Pick variable x with $\alpha(x)$ not integral, $\alpha(x) = d . mmm$
 - C. **If** Branch-and-bound ($C \cup \{x \leq d\}$) == SAT **return** SAT
 - D. **If** Branch-and-bound ($C \cup \{x \geq d + 1\}$) == SAT **return** SAT

Branch-And-Bound

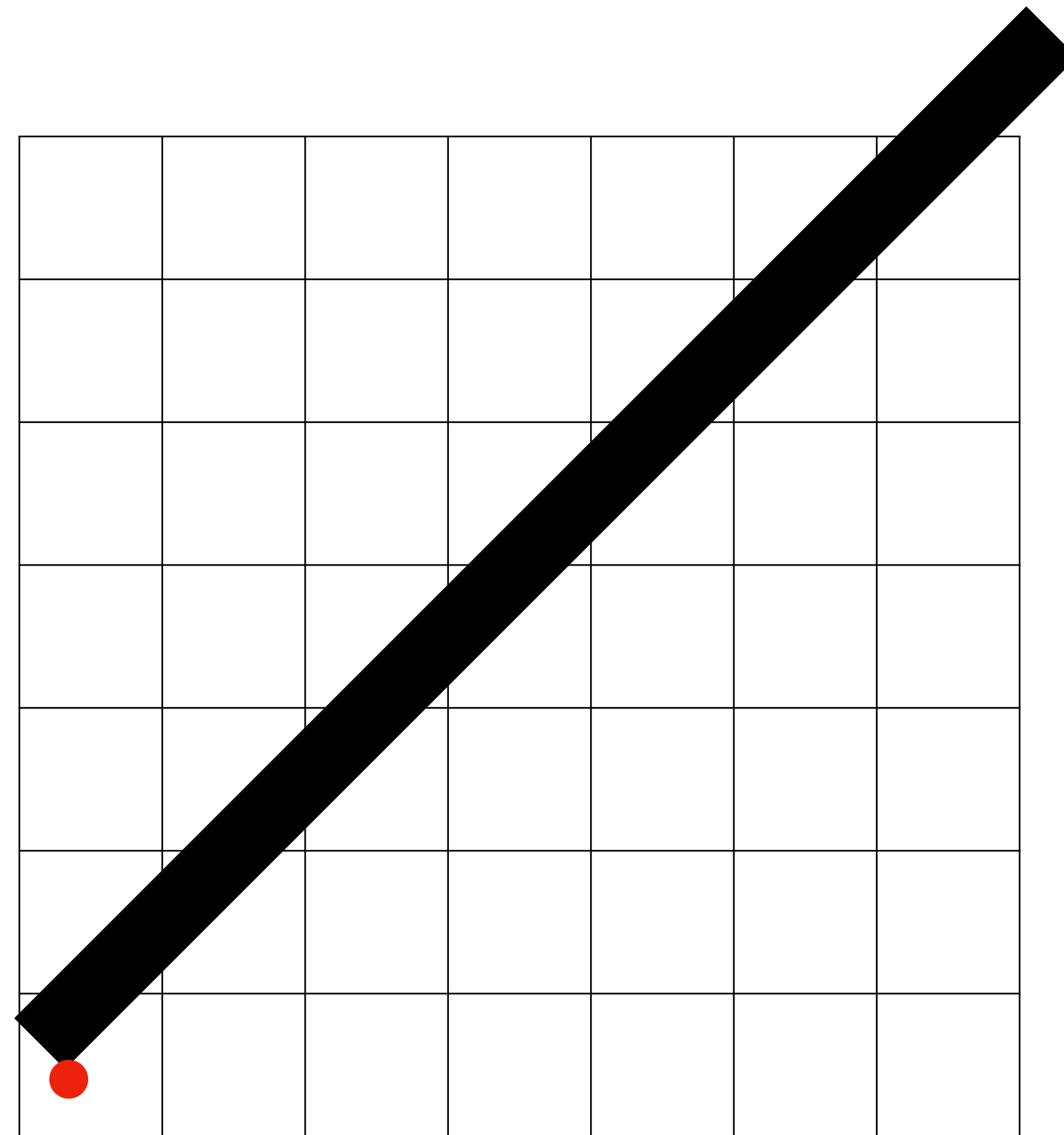
Recursive algorithm

Branch-and-bound (constraints C)

1. Solve relaxed version using Simplex
2. **If** assignment α found
 - A. **If** $\alpha(x)$ integral for all variables **return** SAT
 - B. Pick variable x with $\alpha(x)$ not integral, $\alpha(x) = d . mmm$
 - C. **If** Branch-and-bound ($C \cup \{x \leq d\}$) == SAT **return** SAT
 - D. **If** Branch-and-bound ($C \cup \{x \geq d + 1\}$) == SAT **return** SAT
3. **return** UNSAT

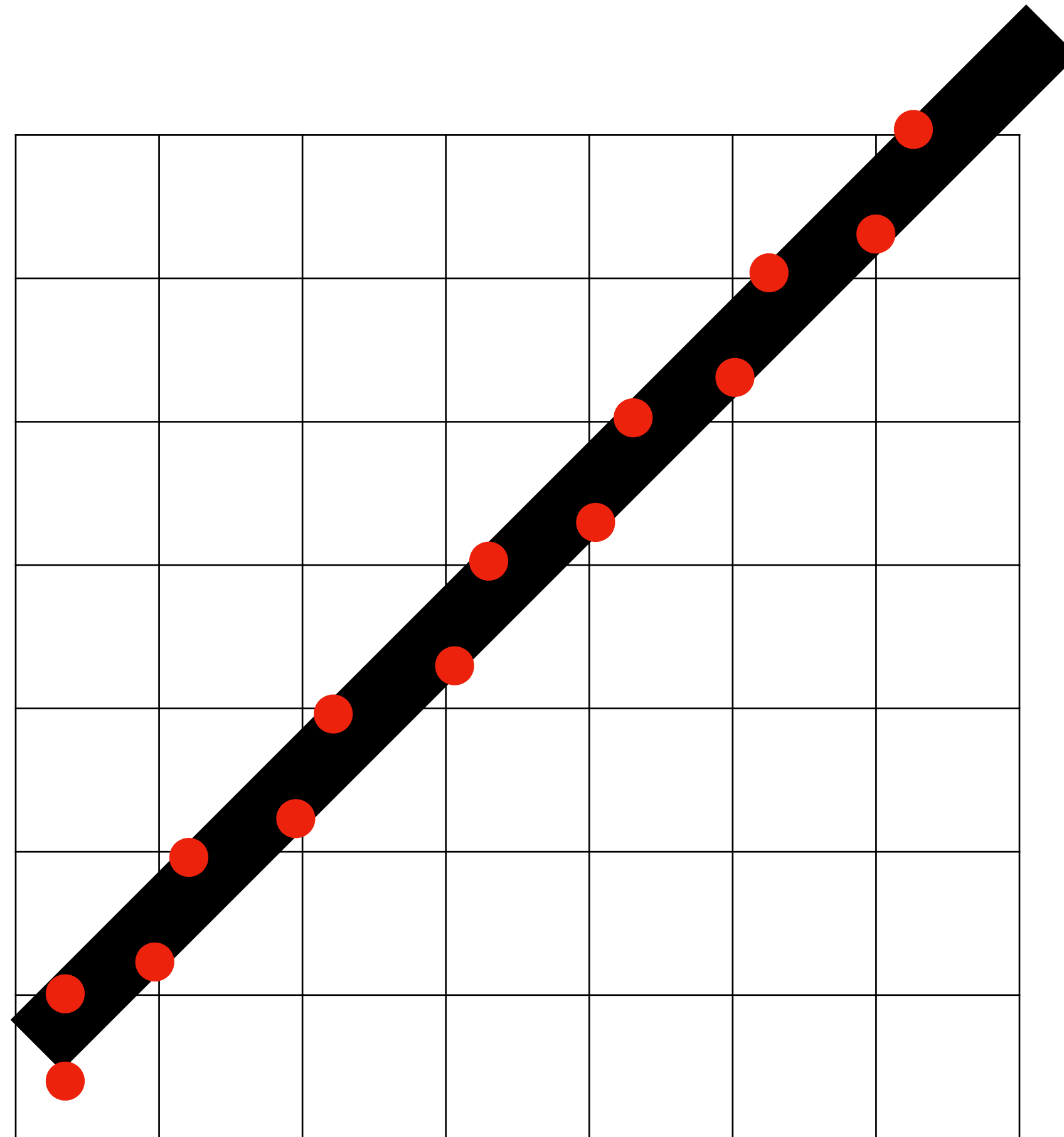
Integers

Branch-And-Bound Illustrated



Integers

Branch-And-Bound Illustrated



May diverge

Need small-model property to bound all integers

QF_LIA

- Many more ways to cut away integer-problems
- Even for a conjunction (feasibility of Integer LP) the problem is NP-complete
- In less-lazy SMT, solve relaxed version unless it is a complete assignment

Summary

- Linear programming & QF_LRA
- Generalized Simplex
- Incrementality & Backtracking for Generalized Simplex
- Branch & Bound for QF_LIA
- Difference logic

Job-Shop Scheduling

Example

- Finite N jobs consist of a chain of ordered operations
- Finite M machines that execute an operation
- Each operation consists of a machine and a duration; must be executed on machine for duration time without interruption
- Order of operations must be respected

Quiztime

Encoding?!

- Finite N jobs consist of a chain of ordered operations
- Finite M machines that execute an operation
- Each operation consists of a machine and a duration; must be executed on machine for duration time without interruption
- Order of operations must be respected

Solution

- x_p start time of operation
- $x_p \geq 0$
- $\forall p, p'$ s.t. p' in same job and after p : $x_{p'} - x_p \geq \text{duration}(p)$
- $\forall p, p'$ with $\text{machine}(p) = \text{machine}(p')$:
 $x_{p'} + \text{duration}(p') \leq x_p \vee x_p + \text{duration}(p) \leq x_{p'}$

Difference Logic

QF_DL

- Real (or integer) variables x_i , constants c
- $x_i - x_j \leq c$
- Boolean combinations
- Use x_0 special variable for 0 (and add implicit constraints $x_0 \leq x_i$)

Quiztime

- $x_1 - x_2 \leq 1 \wedge x_2 - x_3 \leq -1 \wedge x_3 - x_1 \leq -3$
- Satisfiable?

Inequality Graph

- Edges = Variables including the x_0 variable
- Constraints: For every $x - y \leq c$ an edge from x to y with weight c

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Inequality Graph

- Edges = Variables including the x_0 variable
- Constraints: For every $x - y \leq c$ an edge from x to y with weight c

There is a negative cycle in the inequality graph iff the conjunction of constraints together is unsatisfiable

Bellman-Ford (source = x_0) detects negative cycles or finds a satisfying assignment

End of SAT/SMT

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- DPLL/CDCL

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- Resolution for proofs of unsatisfiability and for clause learning

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- Many, many more logics & theory solvers....

End of SAT/SMT

- DPLL/CDCL
- Resolution for proofs of unsatisfiability and for clause learning
- Eager encodings
- DPLL(T)
- Linear arithmetic & Simplex
- Many, many more logics & theory solvers....
- But automated reasoning is more than reasoning about satisfiability....

Summary

- Linear programming & QF_LRA
- Generalized Simplex
- Incrementality & Backtracking
- Branch & Bound for QF_LIA
- Difference logic

Learning goals

You are able to:

- Describe the integration of theory solvers in a (less) lazy DPLL(T) loop
- Explain main ingredients of simplex, execute pivot steps and deduce satisfiability
- Explain and execute branch & bound for integers
- Create inequality graphs to show (un)satisfiability of difference logic

Questions

Make sure you can answer the following questions!

- A. What is a linear program? What is an LRA formula?
- B. Which data structures does simplex maintain?
- C. How does simplex update an variable with a violated bound?
- D. What is branch and bound? What problems can it solve?
- E. What is difference logic and how can we solve conjunctions?

Be able to construct LRA formulas for problem statements

See you next week!