

# Polymorphic Type Inference (III)

Loose ends

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Overview

SL vs. SPL

Mutual Recursion

Overloading

Other analyses

Fun

Conclusion

# Work your way up

## Mandatory

Decide what you will do (see rubric)

- ▶ Monomorphic type inference (insufficient)
- ▶ Polymorphic type inference
- ▶ Polymorphic type checking

## Optional

- ▶ Overloading
- ▶ Mutual recursion
- ▶ Return path checking
- ▶ Global variables
- ▶ ...

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# SL vs. SPL

Map the typing rules

```
var x = 5;  
var y = (True, 1:2:3:[]);  
id (x) {  
    return (x);  
}  
myFunction (x,y) {  
    if (x) { return id(y); }  
    else   { return y + 1; }  
}  
main () {  
    print(myFunction(True, 42));  
}
```

```
let  x = 5 in  
let  y = (True, [1,2,3]) in  
let  id =  $\lambda x.x$  in  
let  myFunction =  
         $\lambda xy.$ if x then id(y) else y + 1  
in   print(myFunction(True,42))
```

# SL vs. SPL

## Statements

$$\begin{aligned}\mathcal{C}(\Gamma, s_1; s_2, \sigma) &= \mathcal{C}(\Gamma^*, s_2, \sigma^*) \circ * \\ &\quad * = \mathcal{C}(\Gamma, s_1, \sigma) \\ \mathcal{C}(\Gamma, \mathbf{while} (p) \{s\}, \sigma) &= \mathcal{C}(\Gamma^*, s, \sigma^*) \circ * \\ &\quad * = \mathcal{C}(\Gamma, p, Bool) \\ \mathcal{C}(\Gamma, \mathbf{if} (p) \{s_t\} \mathbf{else} \{s_e\}, \sigma) &= * = \mathcal{C}(\Gamma^{*2}, s_e, \sigma^{*2}) \circ *_2 \\ &\quad *_2 = \mathcal{C}(\Gamma^{*1}, s_t, \sigma^{*1}) \circ *_1 \\ &\quad *_1 = \mathcal{C}(\Gamma, p, Bool) \\ \mathcal{C}(\Gamma, f(e_1, \dots, e_n), \sigma) &= \mathcal{C}(\Gamma, f(e_1, \dots, e_n), \alpha) \quad \alpha \text{ fresh} \\ \mathcal{C}(\Gamma, \mathbf{return}, \sigma) &= \mathcal{U}(\sigma, Void) \\ \mathcal{C}(\Gamma, \mathbf{return} e, \sigma) &= \mathcal{C}(\Gamma, e, \sigma) \\ \mathcal{C}(\Gamma, v = e, \sigma) &= \mathcal{C}(\Gamma, e, \tau) \\ &\quad \text{where } \Gamma(v) = \forall. \tau\end{aligned}$$

## Variable restriction

SPL	SL	Values	Types ( $\Gamma$ )
<b>var</b> $x = []$ ;	<b>let</b> $x = []$ <b>in</b>	$x=[]$	$x :: A.a : [a]$
$x = 3:x$ ;	<b>ref</b> $x = 3 : x$ <b>in</b>	$x=[3]$	$x :: A.a : [a]$
$x = \text{True}:x$ ;	<b>ref</b> $x = \text{True} : x$ <b>in</b>	$x=[\text{True},3]$	$x :: A.a : [a]$
...			

## Recap

$$\begin{aligned}\mathcal{C}(\Gamma, \text{let } x = e_1 \text{ in } e_2, \sigma) &= \mathcal{C}((\Gamma^*, x:\forall \vec{\beta}. \alpha^*), e_2, \sigma^*) \circ * \\ \vec{\beta} &= \text{TV}(\alpha^*) - \text{TV}(\Gamma^*) \\ * &= \mathcal{C}((\Gamma, x:\alpha), e_1, \alpha), \alpha \text{ fresh}\end{aligned}$$

- ▶ Variables may be assigned to, destructively updated
- ▶ Problem when type variables appear, e.g. lambdas
- ▶ SPL only has one polymorph value: Empty list
- ▶ Variable restriction: don't generalise variables.

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## Mutual recursion

```
odd (x) {  
    if (x == 0) { return (False); }  
    else { return (even (x - 1)); }  
}  
even (x) {  
    if (x == 0) { return (True); }  
    else { return (odd (x - 1)); }  
}
```

```
let odd x = if (x == 0) False (even (x-1)) in  
let even x = if (x == 0) True  (odd  (x-1)) in  
odd 42
```

```
let odd x = if (x == 0) False (even (x-1))  
    even x = if (x == 0) True  (odd  (x-1)) in  
odd 42
```

## Multiple let

**let**  $x_1 = e_1$   
 $x_2 = e_2$   
 $\dots$   
 $x_n = e_n$  **in**  
 $e$

## Mutual Recursion (2)

- Partition the let in strongly connected components, and then for each one

$$\mathcal{C}(\Gamma, \text{let } \vec{x} = \vec{e} \text{ in } e, \sigma) = *$$

- where

$$\Gamma' = \Gamma, \vec{x}:\vec{\alpha} \quad \text{where } \vec{\alpha} \text{ fresh}$$

$$*_1 = \mathcal{C}(\Gamma', e_1, \alpha_1)$$

$$*_2 = \mathcal{C}(\Gamma'^{*_1}, e_2, \alpha_2^{*_1}) \circ *_1$$

...

$$*_n = \mathcal{C}(\Gamma'^{*_{n-1}}, e_n, \alpha_n^{*_{n-1}}) \circ *_{n-1}$$

$$* = \mathcal{C}(\Gamma^{*_n}, \dots, x_i:\forall \vec{\beta}_i. \alpha_i^*, \dots, e, \sigma^{*_n}) \circ *_n$$

$$\vec{\beta}_i = \text{TV}(\alpha_i^{*_n}) - \text{TV}(\Gamma^{*_n})$$

## Too Much Isn't Good

If you unify definitions simultaneously that aren't mutually recursive

```
let    id  =  $\lambda x.x$   
        x   = id True  
        y   = id 10  
in    (x,y)  
  
        id  : int  $\rightarrow$  int  
        id  : bool  $\rightarrow$  bool  
 $\mathcal{U}(\textit{int} \ , \ \textit{bool}) \not\models$ 
```

# What to do in SPL?

## Disallow mutual recursion

- ▶ First step
- ▶ A bit annoying

## Burden the programmer

- ▶ Introduce syntax to group the functions that are mutually recursive  
`mutrec { ... }`
- ▶ Annoying too

## Partition the functions in the compiler

- ▶ Strongly connected components analysis
- ▶ Awesome

## How to partition

- ▶ See the AST as a (call) graph
- ▶ Function calls are edges
- ▶ Functions are vertices
- ▶ Do the analysis (tarjan's)<sup>1</sup>
- ▶ Convert back
- ▶ Side effect, ordering is correct as well
- ▶ Complicated in a functional language (libraries available)

### Tarjan's algorithm

*The data structures that he devised for this problem fit together in an amazingly beautiful way, so that the quantities you need to look at while exploring a directed graph are always magically at your fingertips. And his algorithm also does **topological sorting as a byproduct**. — Knuth*

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<sup>1</sup><https://rosettacode.org/wiki/Tarjan>

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# Type Inference vs. Overloading

- ▶ SPL knows polymorphic functions and overloaded functions
  - ▶ Polymorph: a single implementation for the same function (parametric polymorphism)
  - ▶ Doesn't touch the values
  - ▶ Overloaded: a different implementation for the same function (ad-hoc polymorphism)
  - ▶ Touch the values
- ▶ Example: **print** (5) and **print** (True)
- ▶ Code generator decides which function to call
- ▶ `foo (x) :: a → Void { print (x); }`



# Solutions

- ▶ Limit the types that you can print
  - ▶ If argument type of **print** isn't supported, e.g. a type var: error
  - ▶ Supported: **Int**, **Bool**, **Char**...
  - ▶ [**Int**], (**Bool**, **Char**).
- ▶ Monomorphise the overloaded functions
  - ▶ Generate a specific version for every call
  - ▶ Don't do this for actual polymorph functions!
  - ▶ Some languages do this
- ▶ Proper overloading using class dictionaries
  - ▶ Suitable extension
  - ▶ Many languages do this

## Proper overloading

- ▶ `foo (x) { print (x); } :: a → Void`
- ▶ Change type to: `:: (a → Void) a → Void`
- ▶ Change implementation to: `foo (printfun, x) { printfun (x); }`
- ▶ Either generate the specific function\* or build it on the fly\*
- ▶  
`printInt (x) :: Int → Void { ... }`  
`printBool (x) :: Bool → Void { ... }`  
`printChar (x) :: Char → Void { ... }`  
`printTuple (pLeft, pRight, tuple) :: (a → Void) (b → Void) (a, b) → Void {`  
`printList (pEl, list) :: (a → Void) [a] → Void {`  
  
`print(True);`                    `→ printBool(True);`  
`print(42);`                    `→ printInt(42);`  
`print([42]);`                `→ printList(printInt, [42]);`  
`print((True, [42]));` `→ printTuple(printBool, printList(printInt), (True, [42]));`
- ▶ Requires higher order functions (above) or function pointers (generate all but the top level functions at compiletime), or generate all functions.

## Proper overloading (2)

When using multiple overloaded functions, the extra arguments increase (or placed in a struct):

```
foo(x, y) :: a a → Void {
```

```
  if (x == y) {
    print('e':'q':':':[]);

    print(x);
  } else {
    print(x);
    print(' ':':n':':e':':q':': ':[]);

    print(y);
  }
}
```

```
foo(eqa, printa, x, y) ::
  (a a → Bool)
  (a → Void)
  a a → Void {
  if (eqa(x, y)) {
    printList(printChar
      , 'e':'q':':':[]);
    printa(x);
  } else {
    printa(x);
    printList(printChar
      , ' ':':n':':e':':q':': ':[]);
    printa(y);
  }
}
```

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# Assignment: Semantic Analyses

- ▶ Check restrictions on globals
- ▶ Binding time analysis (definition checking)
- ▶ Type checking/inference
- ▶ Return path analyses

## Restriction on globals

- ▶ Can globals call functions?
- ▶ Can globals use other globals?
- ▶ What happens if you call the print function in a global?

Make a well-founded design choice and document this.

## Definition checking

- ▶ Global variables
- ▶ Local variables
- ▶ Function arguments

(Polymorphic) type inference/checking mostly  
does this already

Does every function return if it needs to?

- ▶ Extra phase or during type checking
- ▶ Smart to this before type checking



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## Fun fact

- ▶ Type inference might take very long
- ▶  
f0 x = (x, x)  
f1 x = f0 (f0 x)  
f2 x = f1 (f1 x)  
f3 x = f2 (f2 x)  
f4 x = f3 (f3 x)  
f5 x = f4 (f4 x)
- ▶ What is the type signature?

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# Work your way up

## Main course

Decide what you will do (see rubric)

- ▶ Monomorphic type inference
- ▶ Polymorphic type inference
- ▶ Polymorphic type checking<sup>†</sup>

## Side dishes

- ▶ Overloading
- ▶ Mutual recursion
- ▶ Return paths
- ▶ Global variables