

Image Classification Using CNNs

Presented by

BENOUAKLIL Hodhaifa

BOUKACEM Younes



Presentation Plan

- 01** INTRODUCTION
- 02** WHY CNN?
- 03** CNN ARCHITECTURE
- 04** PRACTICAL EXAMPLE



01 INTRODUCTION



What is Image Classification?

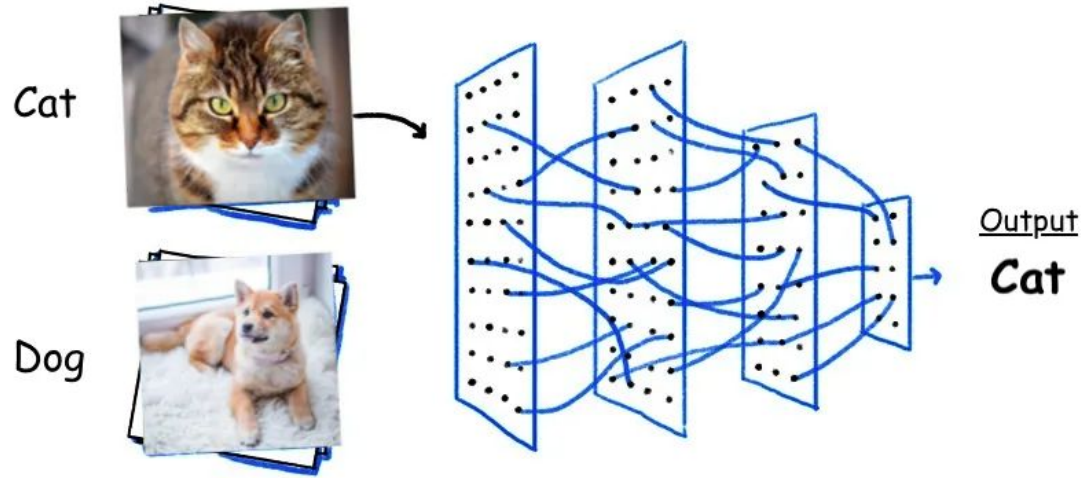
*“Image classification is a **computer vision** task where the goal is to **categorize** an entire image into a specific **class** or **label**”*



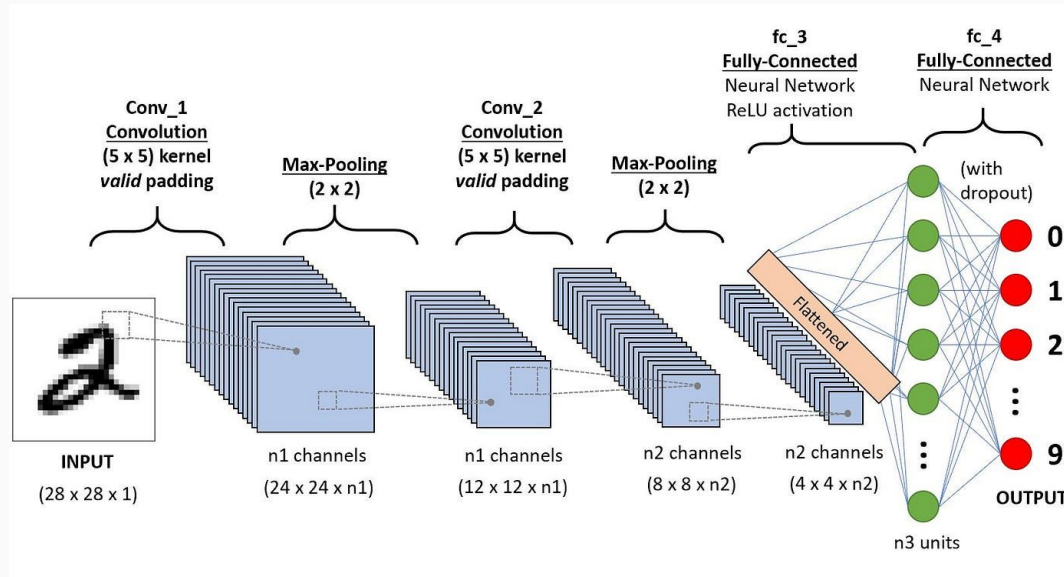
For Example

- Identifying whether an image contains a cat or a dog
- Recognizing handwritten digits
- Classifying medical images (e.g., detecting tumors)
- Identifying plant species from leaf images

Example



What are Convolutional Neural Networks (CNNs)?



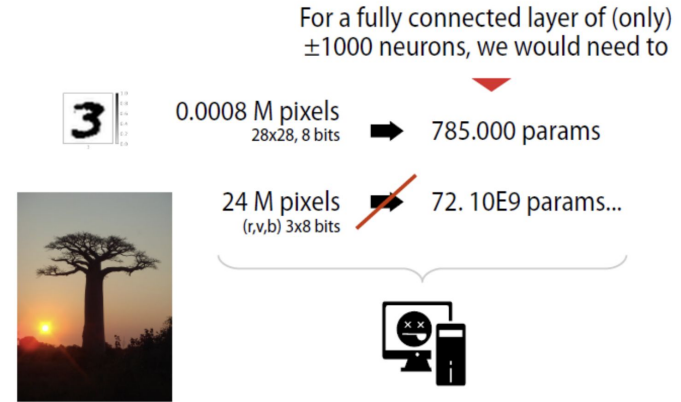


02

WHY CNN?

Limitations of Traditional Neural Networks

- Spatial information loss
- High computational complexity
- Large number of parameters
- Poor scaling with image size



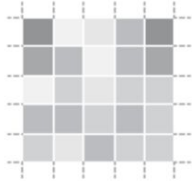


03 CNN ARCHITECTURE

Convolution Operation



By Jan Kroon, from Pixels.com



5	2	1	3	5
4	3	2	3	4
0	2	1	2	2
3	3	2	3	2
2	1	3	2	2

Image piece

5	2	1
4	3	2
0	2	1

x

Kernel 3x3

1	0	1
0	1	0
1	0	1

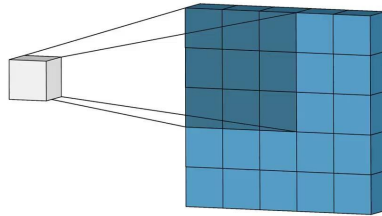
w



10

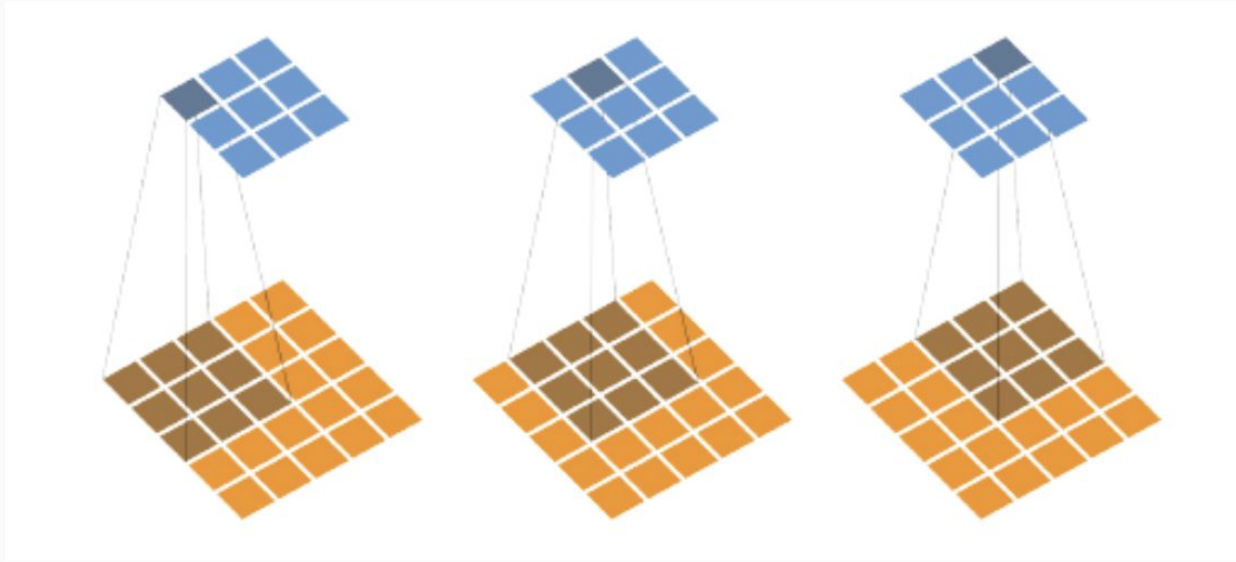
y

$$\begin{aligned} y &= 5 \times 1 + 2 \times 0 + 1 \times 1 \\ &+ 4 \times 0 + 3 \times 1 + 2 \times 0 \\ &+ 0 \times 1 + 2 \times 0 + 1 \times 1 = 10 \end{aligned}$$



Padding

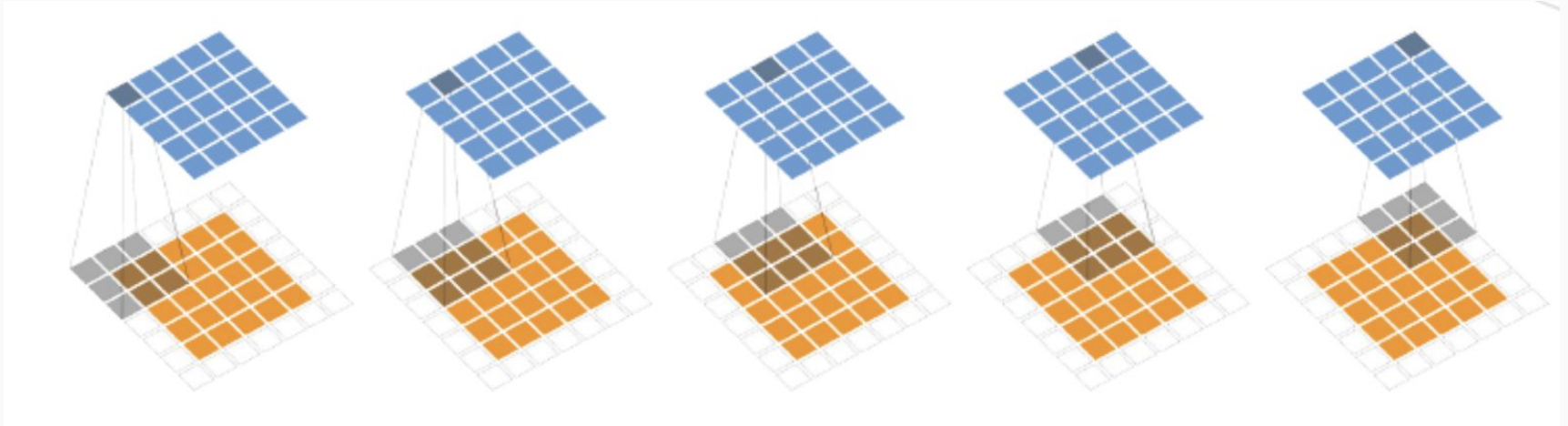
Valid padding (no padding):





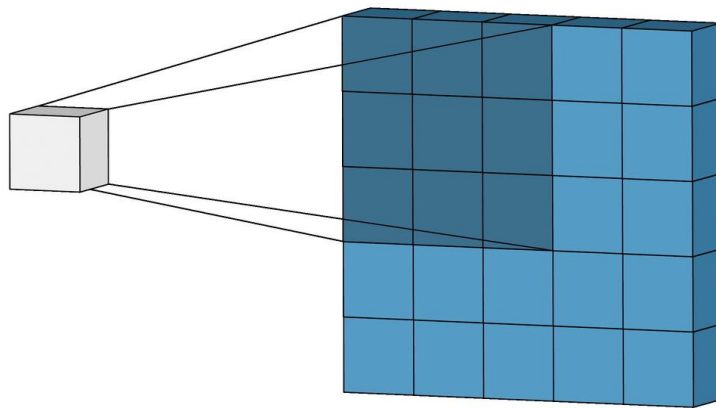
Padding

Same padding (output size = input size):



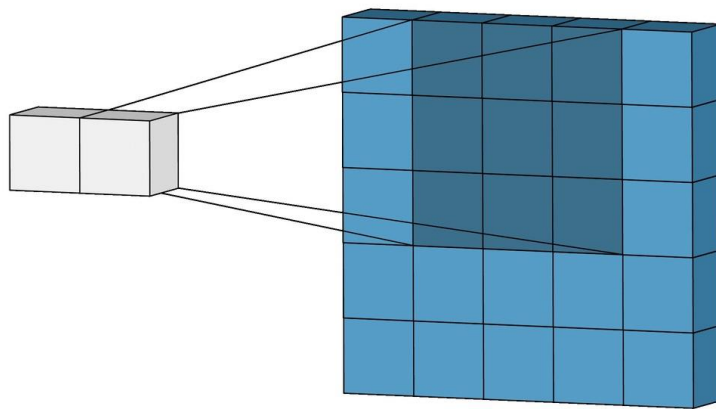
Stride

Stride = 1:



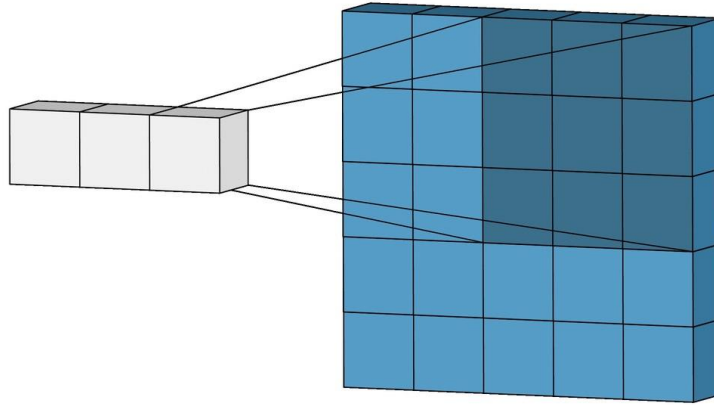
Stride

Stride = 1:



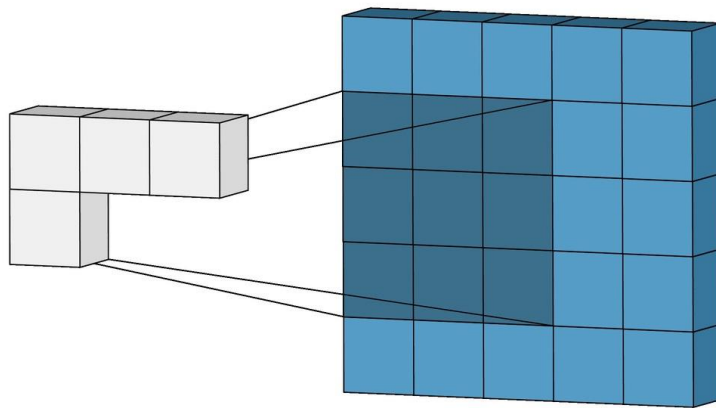
Stride

Stride = 1:



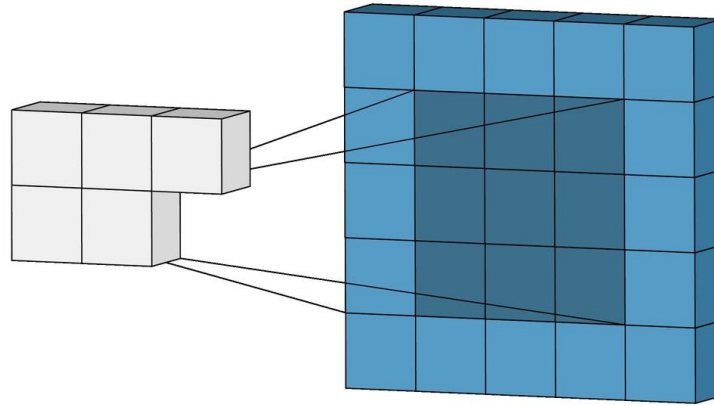
Stride

Stride = 1:



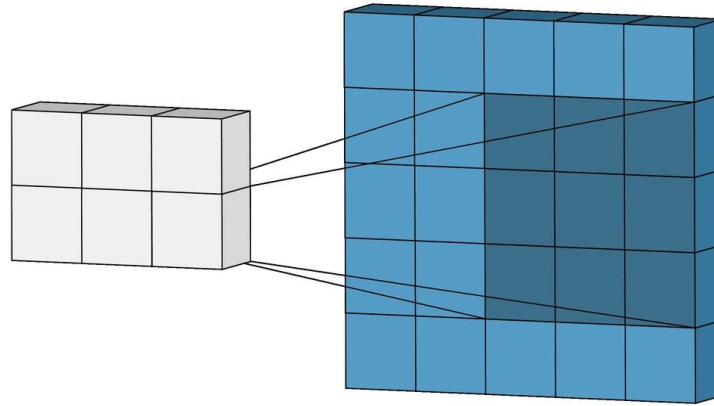
Stride

Stride = 1:



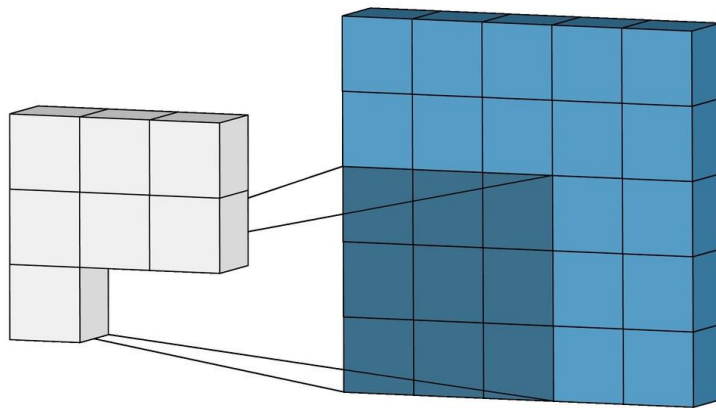
Stride

Stride = 1:



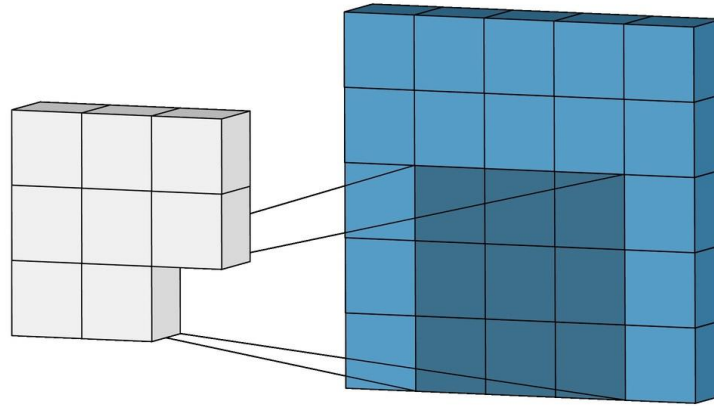
Stride

Stride = 1:



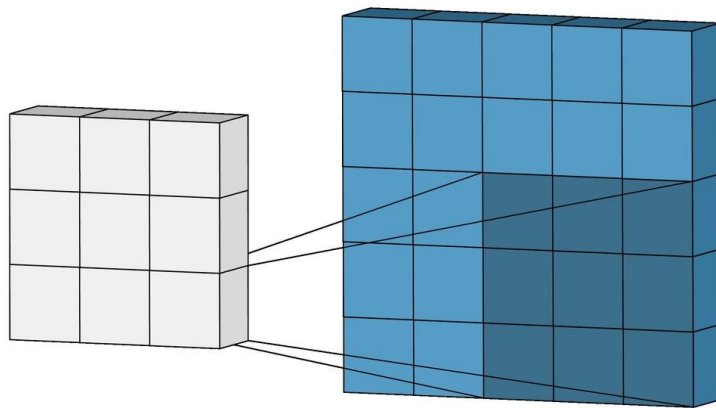
Stride

Stride = 1:



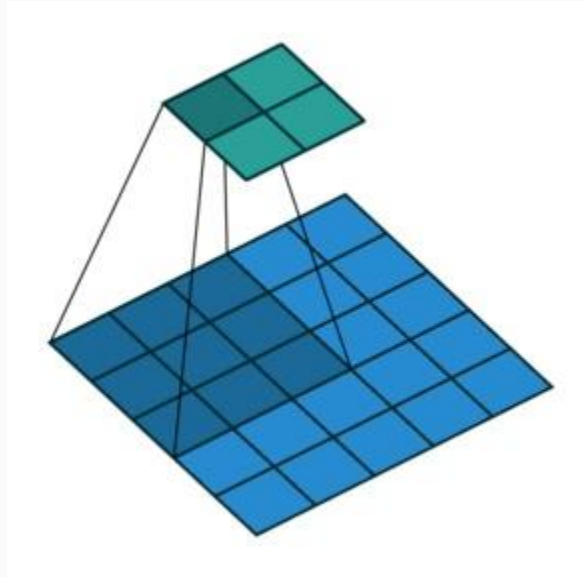
Stride

Stride = 1:



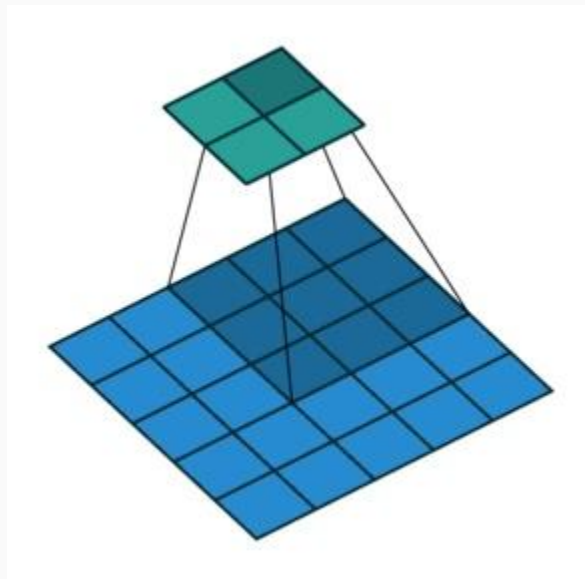
Stride

Stride = 2:



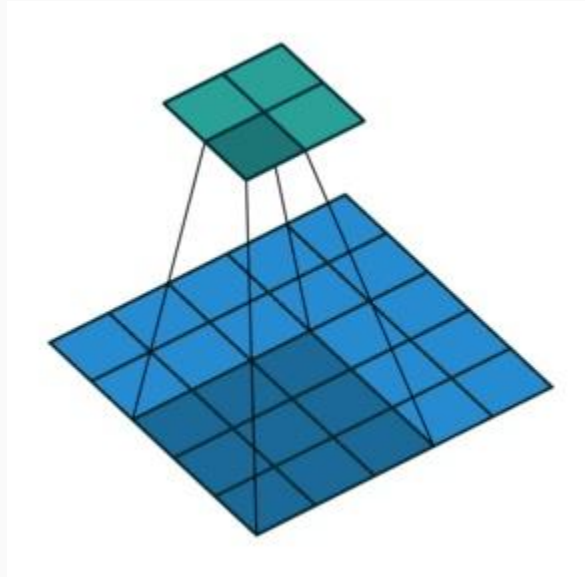
Stride

Stride = 2:



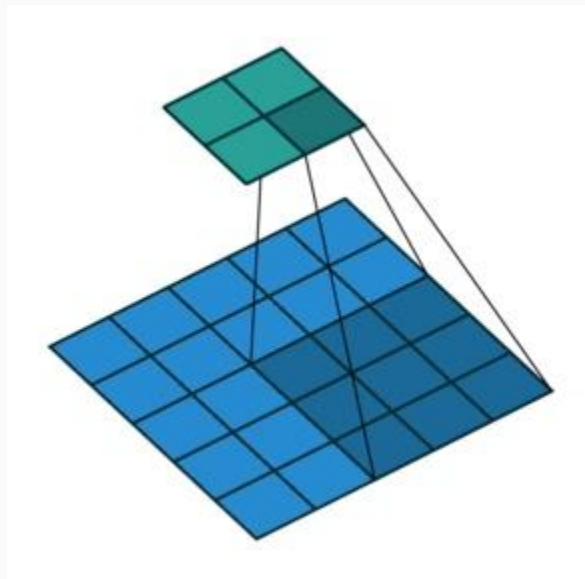
Stride

Stride = 2:



Stride

Stride = 2:

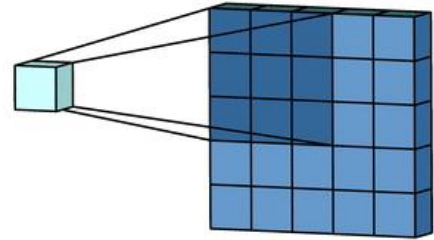
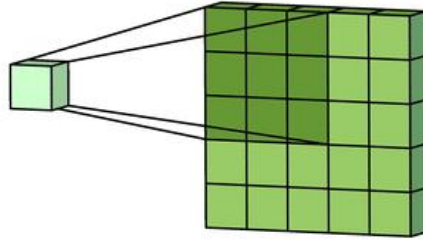
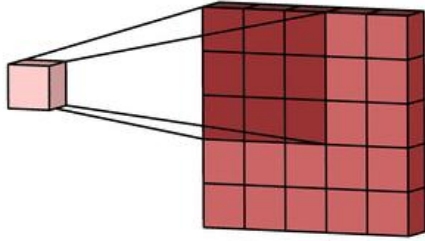




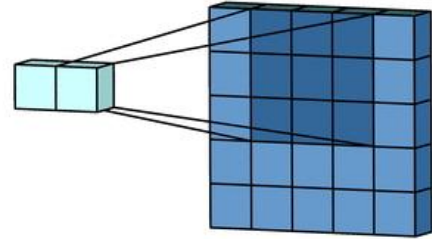
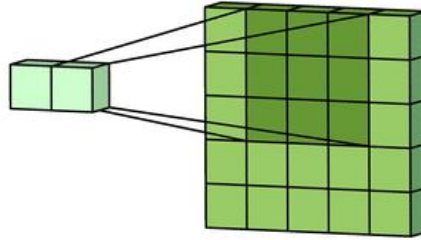
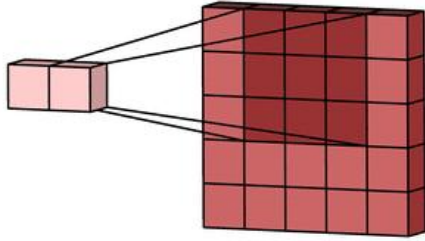
Stride

- Step size for filter movement
- Controls output size
- Impact on feature detection:
 - Larger stride → Less detail / faster training
 - Smaller stride → More detail / slower training

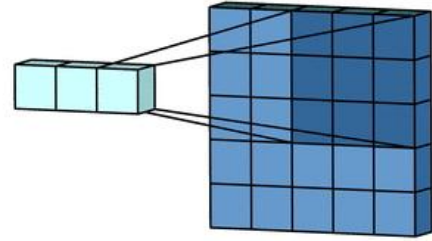
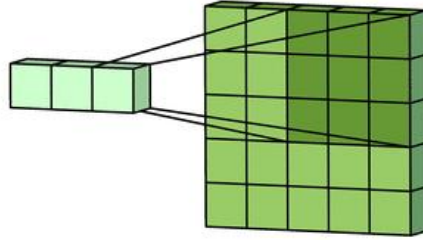
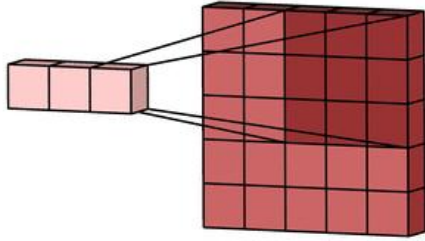
Multi-channel (RGB for ex)



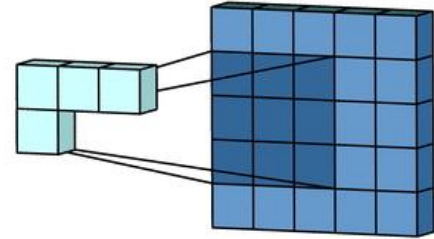
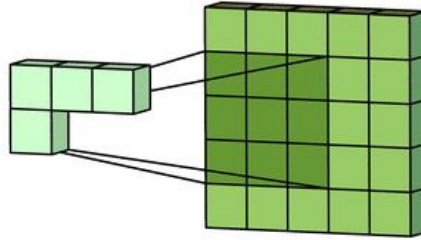
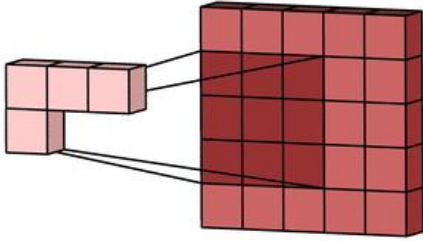
Multi-channel (RGB for ex)



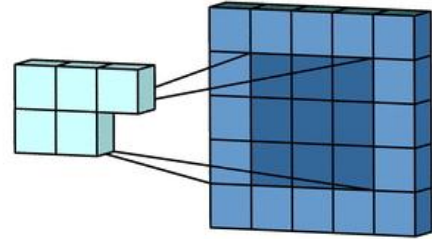
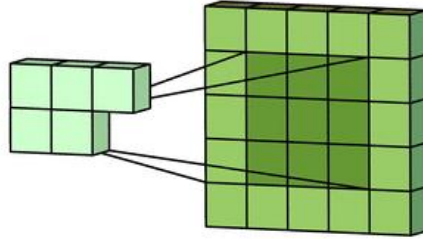
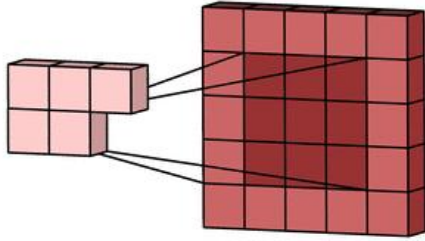
Multi-channel (RGB for ex)



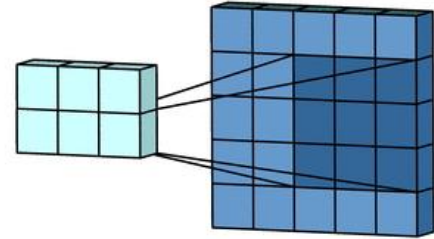
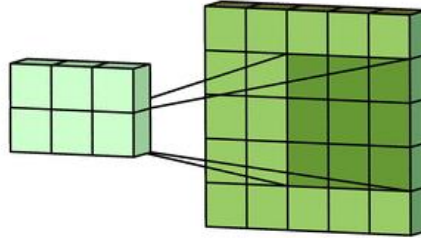
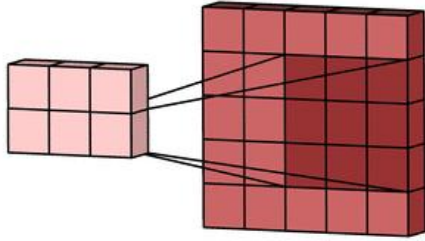
Multi-channel (RGB for ex)



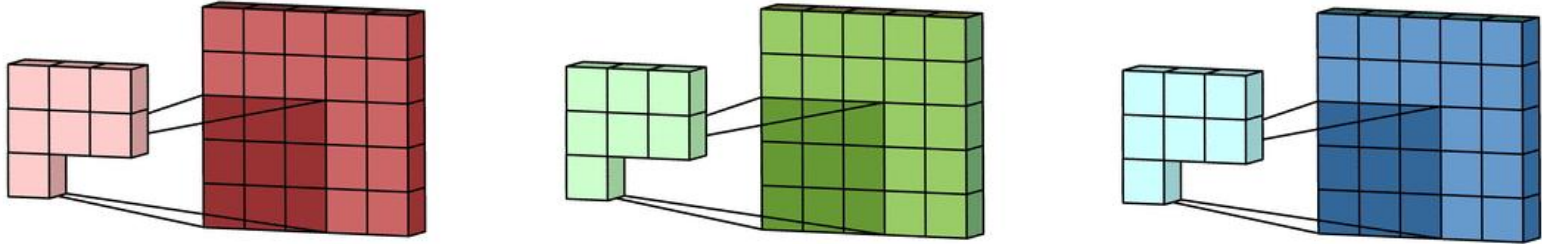
Multi-channel (RGB for ex)



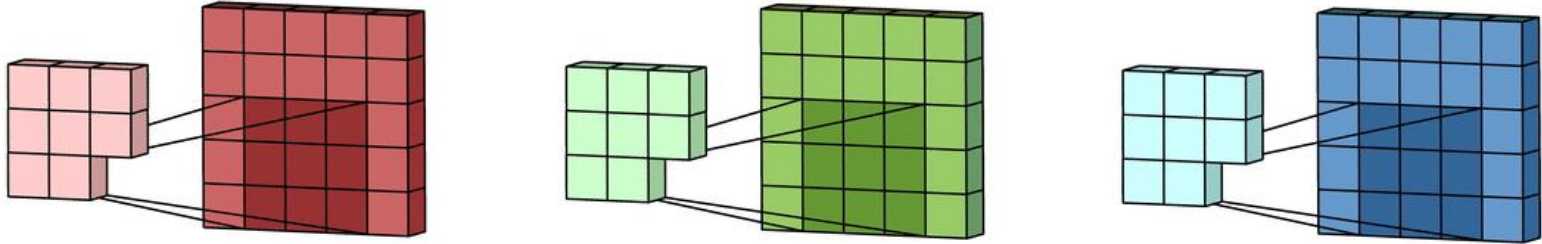
Multi-channel (RGB for ex)



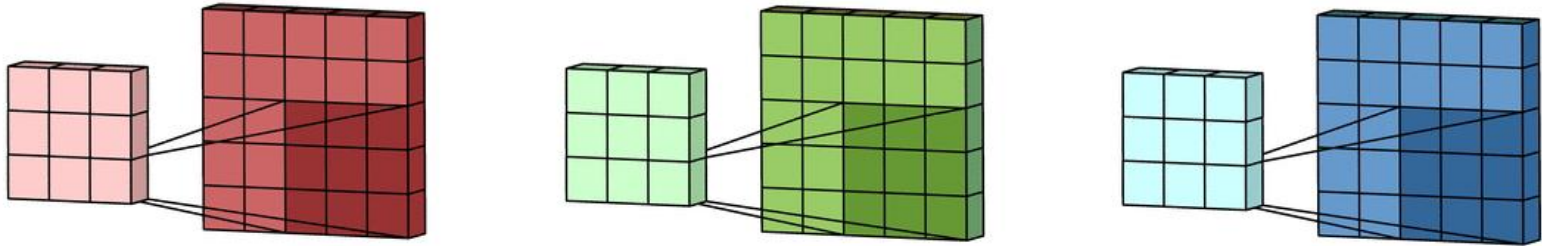
Multi-channel (RGB for ex)



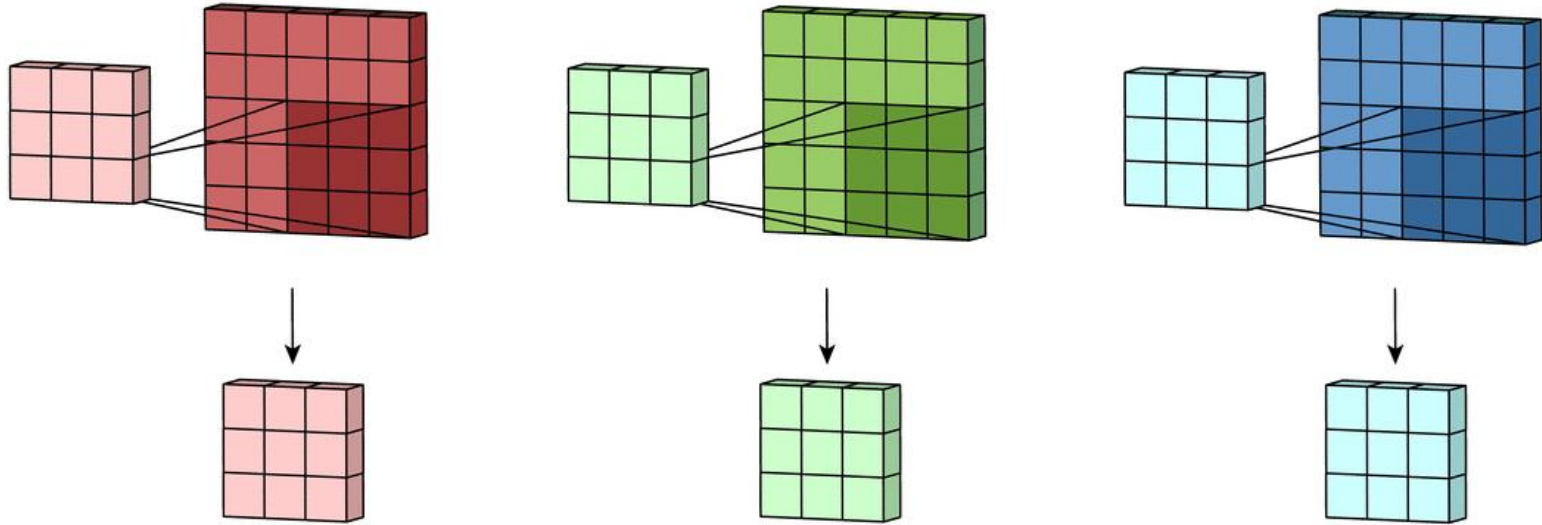
Multi-channel (RGB for ex)



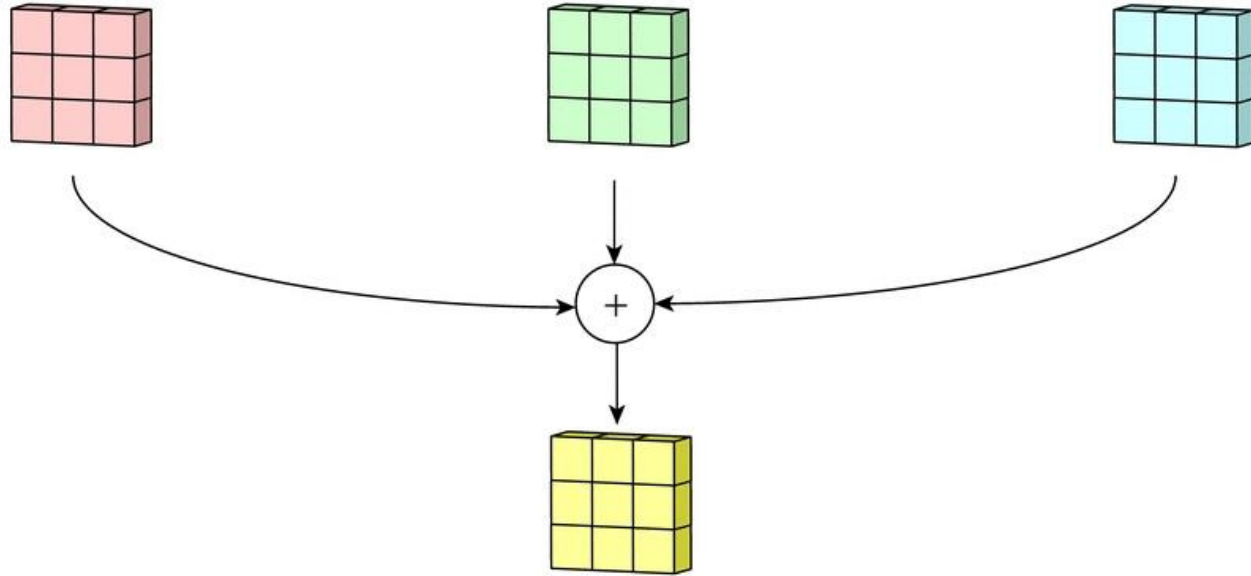
Multi-channel (RGB for ex)



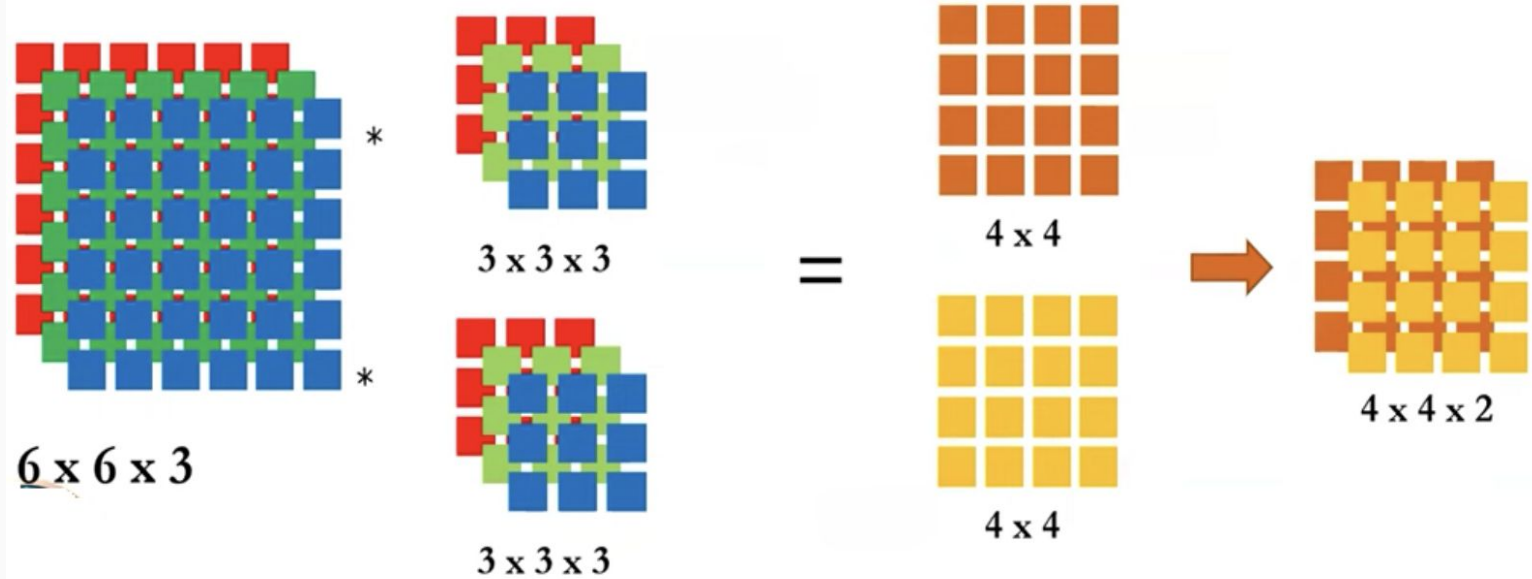
Multi-channel (RGB for ex)



Multi-channel (RGB for ex)



Multiple Filters





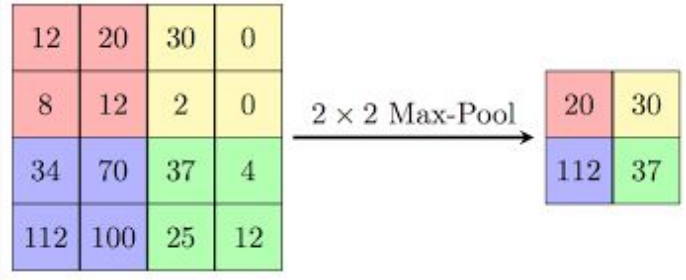
Multiple Filters

- Each filter detects different features
- Creates multiple feature maps
- Parallel processing
- Feature diversity

Pooling Layers

1. Max Pooling

- Takes maximum value
- Preserves strong features



2. Average Pooling

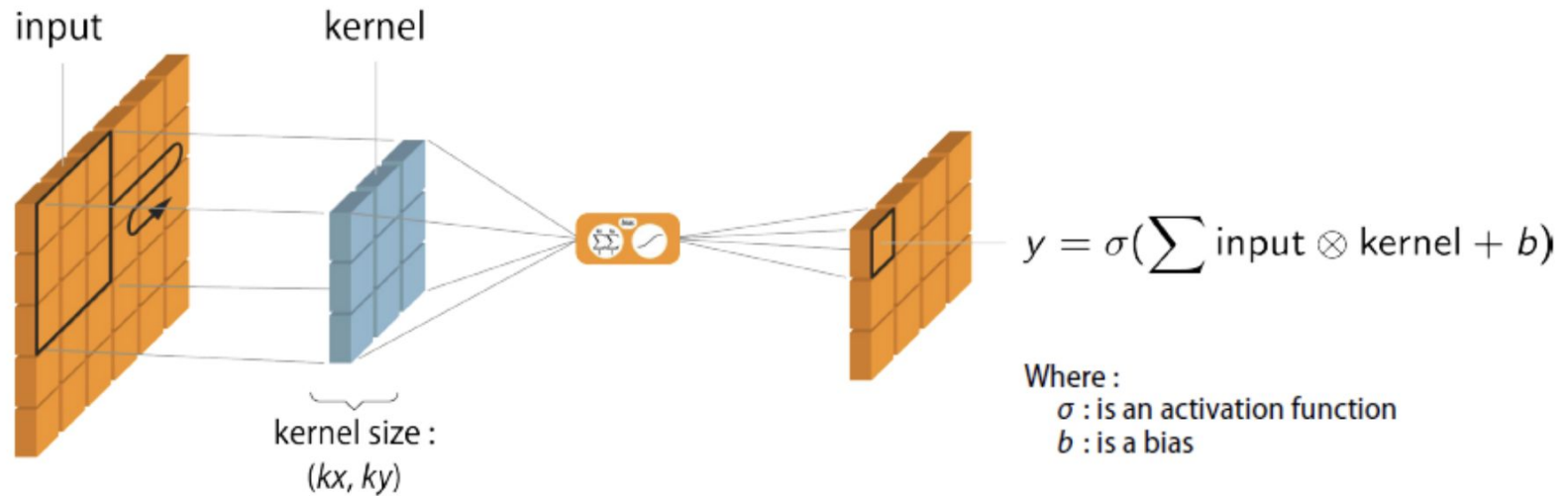
- Takes average value
- Preserves feature distribution



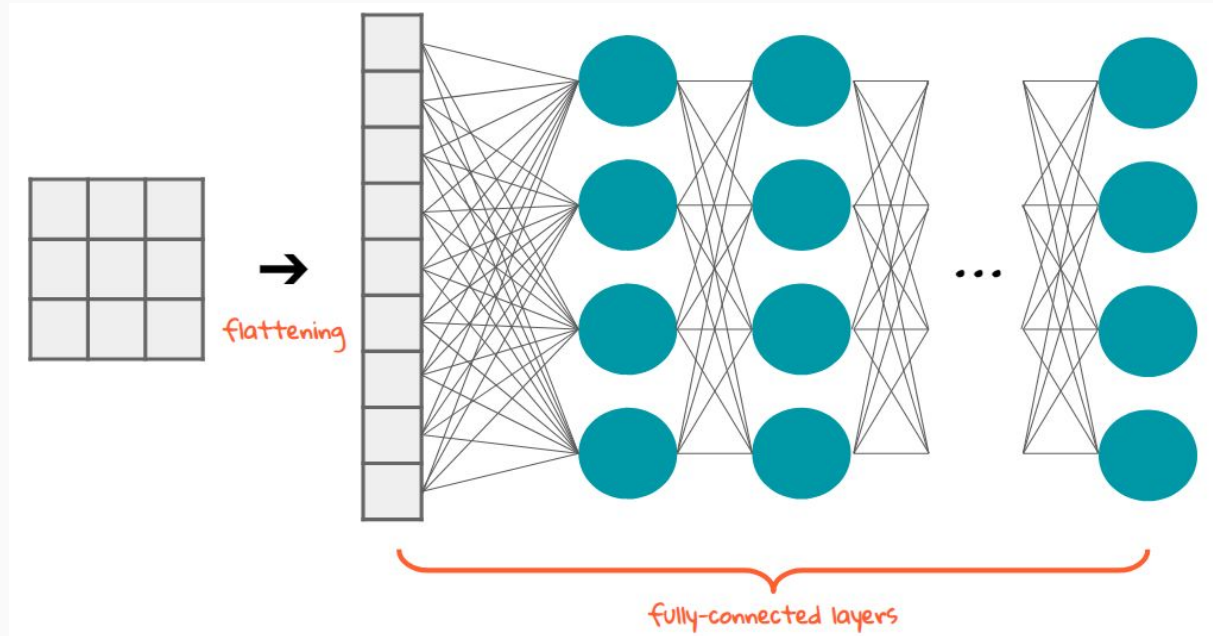
Pooling Layers

- Dimensionality reduction
- Computational efficiency
- Spatial invariance

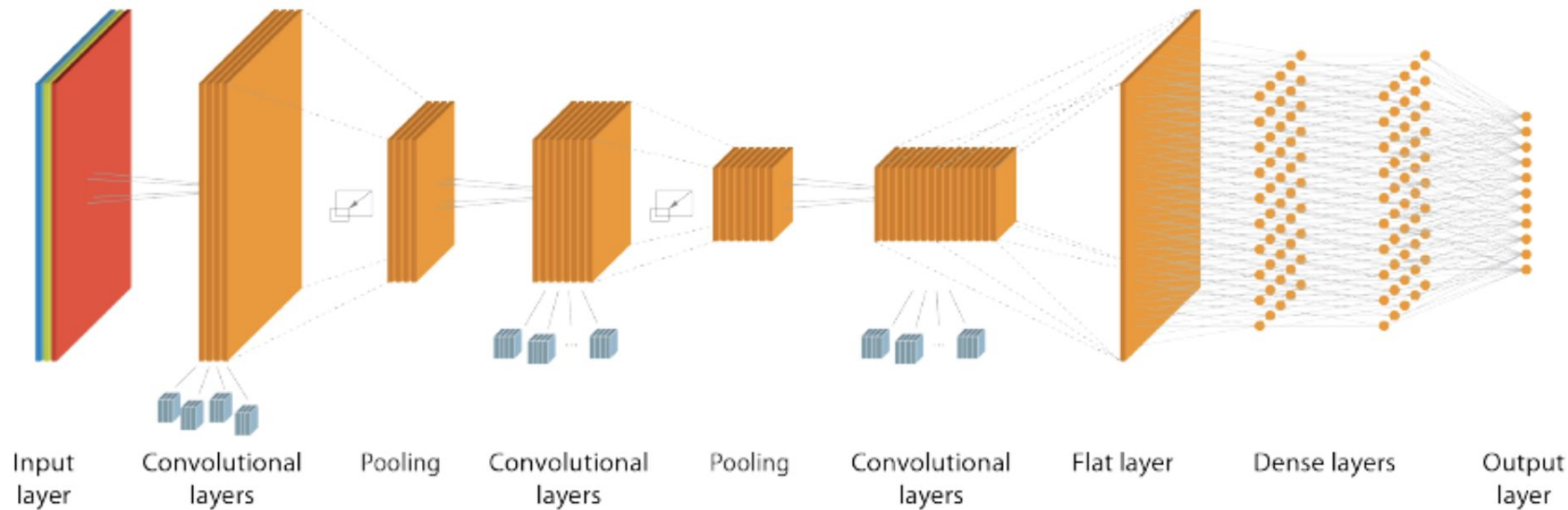
Activation functions



Fully Connected Layer



Typical CNN Structure





05

PRACTICAL EXAMPLE



MNIST Classification

Notebook available here:

<https://www.kaggle.com/code/hodhaifabenouaklil/mnist-classification>



THANKS FOR YOUR ATTENTION

Do you have any questions?