

CS540 Introduction to Artificial Intelligence

Lecture 8

Young Wu

Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles
Dyer

June 8, 2020

SIFT and HOG Features

Motivation

- SIFT and HOG features are expensive to compute.
- Simpler features should be used for real time face detection tasks.

Real Time Face Detection

Motivation

- Each image contains 10000 to 500000 locations and scales.
- Faces occur in 0 to 50 per image.
- Want a very small number of false positives.

Haar Features Diagram

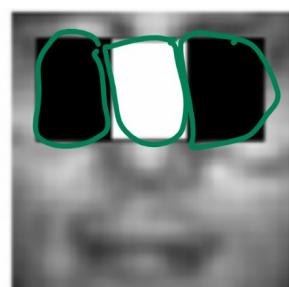
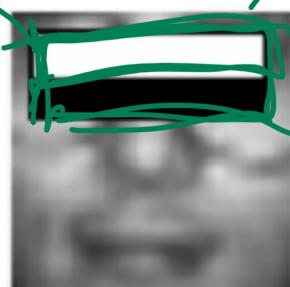
Motivation

large

large



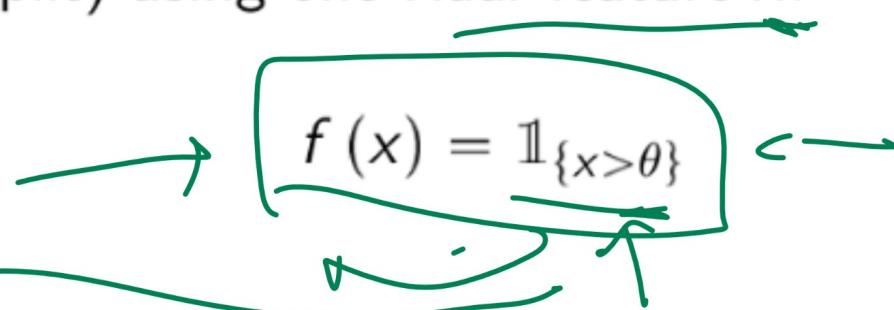
-me



Weak Classifiers

Definition

- Each weak classifier is a decision stump (decision tree with only one split) using one Haar feature x .



- Finding the threshold by comparing the information gain from all possible splits is too expensive, so θ is usually computed as the average of the mean values of the feature for each class.

$$\theta = \frac{1}{2} \left(\frac{1}{n_0} \sum_{i:y_i=0} x_i + \frac{1}{n_1} \sum_{i:y_i=1} x_i \right)$$

Non Face
Face

Strong Classifiers

Definition

- The weak classifiers are trained sequentially using ensemble methods such as AdaBoost.
- A sequence of T weak classifiers is called a T -strong classifier.
- Multiple T -strong classifiers can be trained for different values of T and combined into a cascaded classifier.

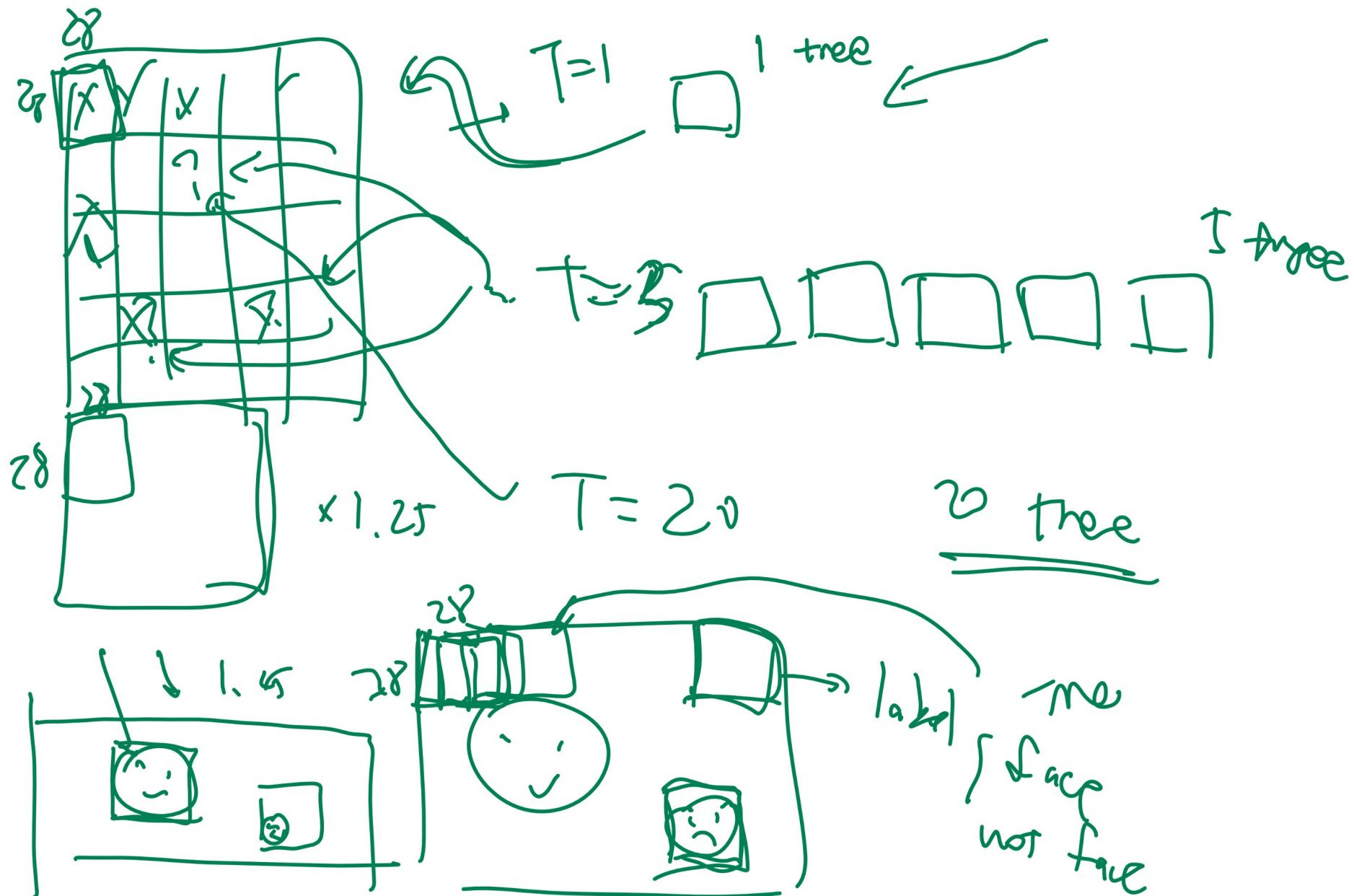
Cascaded Classifiers

Definition

- Start with aT -strong classifier with small T , and use it to reject obviously negative regions (regions with no faces).
- Train and use aT -strong classifier with larger T on only the regions that are not rejected.
- Repeat this process with stronger classifiers.

Viola Jones Diagram

Discussion



Convolution Example

Quiz

- Find the gradient magnitude and direction for the center cell of the following image. Use the derivative filters gradient filters

middle element

$$\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \text{ and } \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 0 & 1 \\ 0 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} -4 & -5 & -6 \\ -6 & -6 & -6 \\ 4 & 5 & 6 \end{bmatrix} \rightarrow \nabla_y I$$

zero-padding

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} -2 & -2 & 2 \\ -5 & -2 & 5 \\ -8 & -2 & 8 \end{bmatrix} \rightarrow \nabla_x I$$

Gradient Example

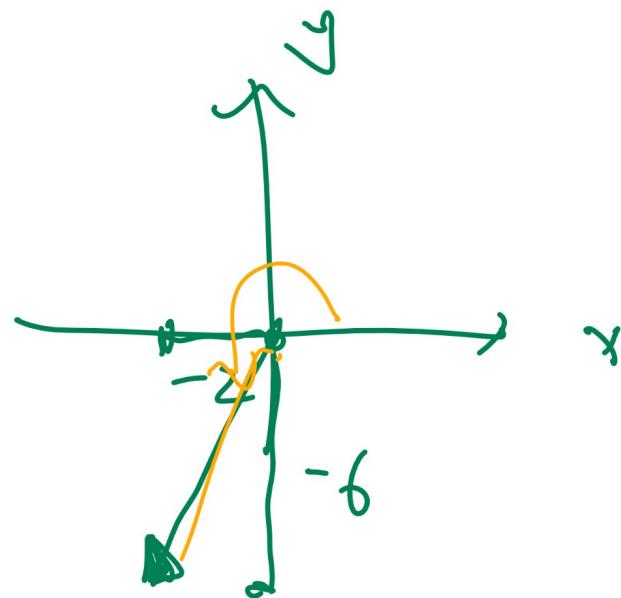
Quiz

$$G = \sqrt{(-6)^2 + (-2)^2} = \dots$$

gradient magnitude



$$\theta = \arctan\left(\frac{-2}{-6}\right)$$



Convolution Example 1

Quiz

left Sobel

$A: \begin{bmatrix} -1 & -3 & -3 \\ 0 & 0 & 0 \\ 1 & 3 & 3 \end{bmatrix}, B: \begin{bmatrix} -3 & -3 & 3 \\ -4 & -4 & 4 \\ -3 & -3 & 3 \end{bmatrix}$

$C: \begin{bmatrix} -3 & -4 & -3 \\ -3 & -4 & -3 \\ 3 & 4 & 3 \end{bmatrix}, D: \begin{bmatrix} -1 & 0 & 1 \\ -3 & 0 & 3 \\ -3 & 0 & 3 \end{bmatrix}$

$D_x = \boxed{\begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}} = F^T \text{ flip}$

$D_y = \boxed{\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}} \xrightarrow{\text{flip}} \boxed{\begin{bmatrix} 9 & 8 & 7 \\ 6 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}}$

Convolution Example 2

Quiz

on mrdeerm

Q2
back
6:45

bottom, Sobel

$$\begin{bmatrix} 0 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} * \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

A: $\begin{bmatrix} -1 & -3 & -3 \\ 0 & 0 & 0 \\ 1 & 3 & 3 \end{bmatrix}, B: \begin{bmatrix} -3 & -3 & 3 \\ -4 & -4 & 4 \\ -3 & -3 & 3 \end{bmatrix}$

C: $\begin{bmatrix} -3 & -4 & -3 \\ -3 & -4 & -3 \\ 3 & 4 & 3 \end{bmatrix}, D: \begin{bmatrix} -1 & 0 & 1 \\ -3 & 0 & 3 \\ -3 & 0 & 3 \end{bmatrix}$ flip

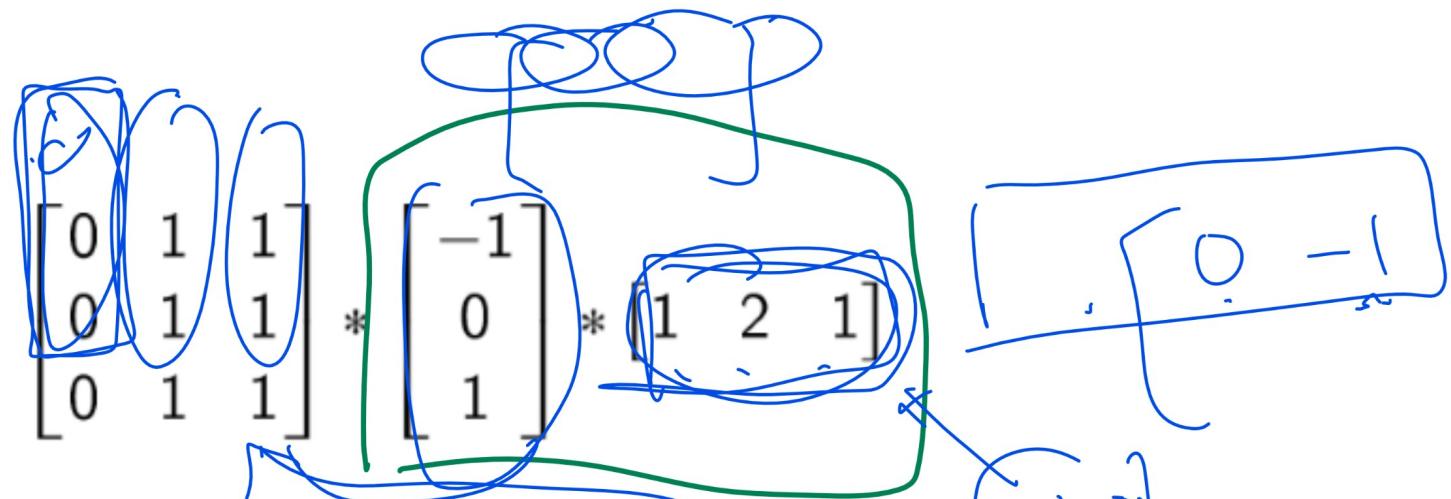
$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix}$

$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \xrightarrow{\text{flip}} \begin{bmatrix} 9 & 8 & 7 \\ 6 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}$

Convolution Example 3

Quiz

Q3



• A: $\begin{bmatrix} -1 & -3 & -3 \\ 0 & 0 & 0 \\ 1 & 3 & 3 \end{bmatrix}$, B : $\begin{bmatrix} -3 & -3 & 3 \\ -4 & -4 & 4 \\ -3 & -3 & 3 \end{bmatrix}$

• C: $\begin{bmatrix} -3 & -4 & -3 \\ -3 & -4 & -3 \\ 3 & 4 & 3 \end{bmatrix}$, D : $\begin{bmatrix} -1 & 0 & 1 \\ -3 & 0 & 3 \\ -3 & 0 & 3 \end{bmatrix}$

Convolution Example 4

Quiz

Q4

What is the gradient magnitude for the center cell?

$$\nabla_x = \begin{bmatrix} -3 & -3 & 3 \\ -4 & \textcircled{-4} & 4 \\ -3 & -3 & 3 \end{bmatrix}, \nabla_y = \begin{bmatrix} -1 & -3 & -3 \\ 0 & \textcircled{0} & 0 \\ 1 & 3 & 3 \end{bmatrix}$$

- A: 1, B: 2, C: 3, D: 4, E: 5

$$\sqrt{(-4)^2 + 0^2} = 4$$

Convolution Example 5

Quiz

Q5

hot on midterms

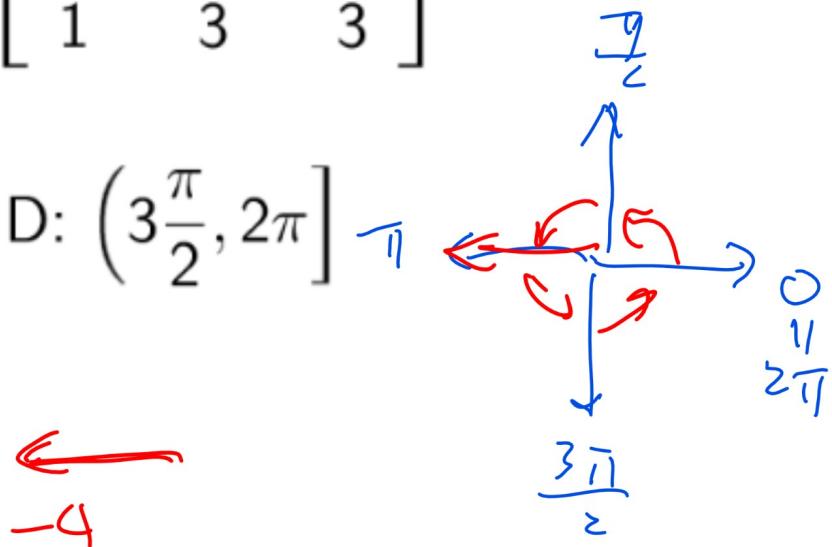
element

What is the gradient direction bin for the center cell?

$$\nabla_x = \begin{bmatrix} -3 & -3 & 3 \\ -4 & -4 & 4 \\ -3 & -3 & 3 \end{bmatrix}, \nabla_y = \begin{bmatrix} -1 & -3 & -3 \\ 0 & 0 & 0 \\ 1 & 3 & 3 \end{bmatrix}$$

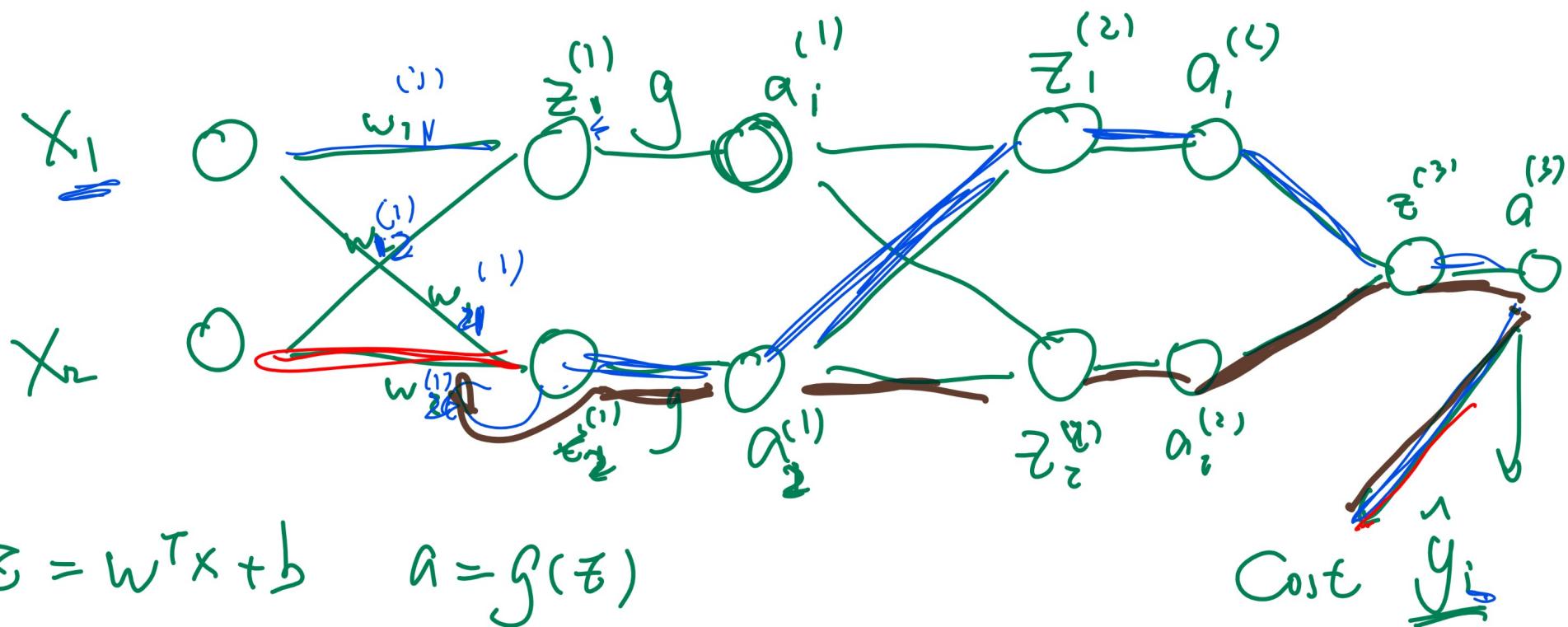
- A: $\left(0, \frac{\pi}{2}\right]$, B: $\left(\frac{\pi}{2}, \pi\right]$, C: $\left(\pi, 3\frac{\pi}{2}\right]$, D: $\left(3\frac{\pi}{2}, 2\pi\right]$

$$\text{atan} z / dy, dx$$



Three Layer Neural Network Weights Diagram 1

Quiz



$$\vec{z} = w^T x + b \quad a = g(\vec{z})$$

$$w = w - \alpha \frac{\partial C}{\partial w}$$

$$\frac{\partial C}{\partial w_{22}^{(1)}} = \sum_{i=1}^n \frac{\partial C}{\partial a_i^{(3)}} \cdot \frac{\partial a_i^{(3)}}{\partial z_i^{(2)}} \cdot \frac{\partial z_i^{(2)}}{\partial a_i^{(2)}} \cdot \frac{\partial a_i^{(2)}}{\partial z_i^{(1)}} \cdot \frac{\partial z_i^{(1)}}{\partial a_i^{(1)}} \cdot \frac{\partial a_i^{(1)}}{\partial z_i^{(1)}} \cdot \frac{\partial z_i^{(1)}}{\partial w_{22}^{(1)}}$$

Three Layer Neural Network Weights Diagram 2

Quiz

$$\begin{aligned}
 & + \frac{\partial C}{\partial a^{(3)}} \cdot \frac{\partial a^{(3)}}{\partial z^{(3)}} \cdot \frac{\partial z^{(3)}}{\partial a^{(2)}} \cdot \frac{\partial a^{(2)}}{\partial z^{(2)}} \cdot \frac{\partial z^{(2)}}{\partial a^{(1)}} \cdot \frac{\partial a^{(1)}}{\partial z^{(1)}} \cdot \frac{\partial z^{(1)}}{\partial w_{21}} \\
 & C = \frac{1}{2} (y - a)^2 \\
 & g' = g \cdot (1-g) \text{ for } \{g_i\}_{i=1}^n
 \end{aligned}$$

$a^{(2)} = \hat{a}_2 (1 - \hat{a}_2)$
 $w_{21}^{(1)} \cdot a_2^{(1)} (1 - a_2^{(1)}) \times \dots$

Three Layer Neural Network Backpropogation

Quiz

- Which of the following is correct for a three layer network?
Assume there are 10 units in the first layer and 5 units in the second layer.
- Choices on the next page.

Three Layer Neural Network Backpropogation

Quiz

$$Q6 \bullet \cancel{A.} \frac{\partial C}{\partial w_{12}^{(1)}} = \sum_{j'=1}^{10} \sum_{j=1}^5 \frac{\partial C}{\partial a_j^{(2)}} \frac{\partial a_j^{(2)}}{\partial a_{j'}^{(1)}} \frac{\partial a_{j'}^{(1)}}{\partial w_{1j'}^{(1)}}$$

$$B: \frac{\partial C}{\partial w_{12}^{(1)}} = \sum_{j=1}^5 \frac{\partial C}{\partial a_j^{(2)}} \frac{\partial a_j^{(2)}}{\partial a_1^{(1)}} \frac{\partial a_1^{(1)}}{\partial w_{12}^{(1)}}$$

$$C: \frac{\partial C}{\partial w_{12}^{(1)}} = \sum_{j=1}^5 \frac{\partial C}{\partial a_j^{(2)}} \frac{\partial a_j^{(2)}}{\partial a_2^{(1)}} \frac{\partial a_2^{(1)}}{\partial w_{12}^{(1)}}$$

• ~~D:~~ $\frac{\partial C}{\partial w_{12}^{(1)}} = \frac{\partial C}{\partial a_1^{(2)}} \frac{\partial a_1^{(2)}}{\partial a_1^{(1)}} \frac{\partial a_1^{(1)}}{\partial w_{12}^{(1)}}$

E: $\frac{\partial C}{\partial w_{12}^{(1)}} = \frac{\partial C}{\partial a_2^{(2)}} \frac{\partial a_2^{(2)}}{\partial a_2^{(1)}} \frac{\partial a_2^{(1)}}{\partial w_{12}^{(1)}}$

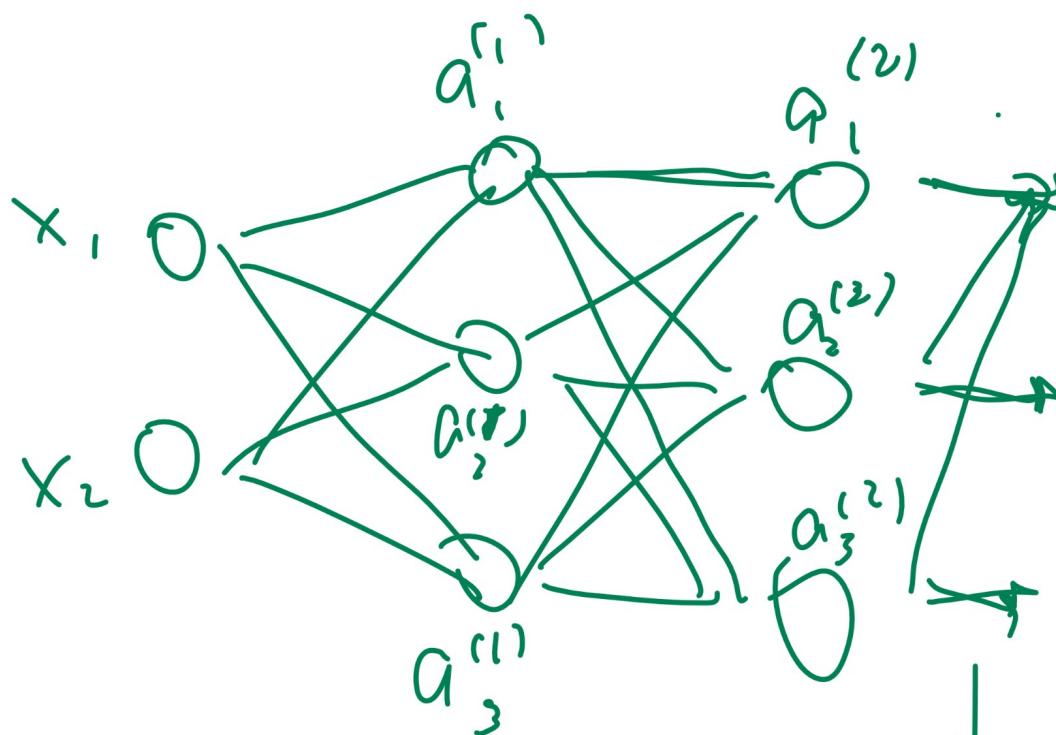
10 hidden 1
5 hidden 2



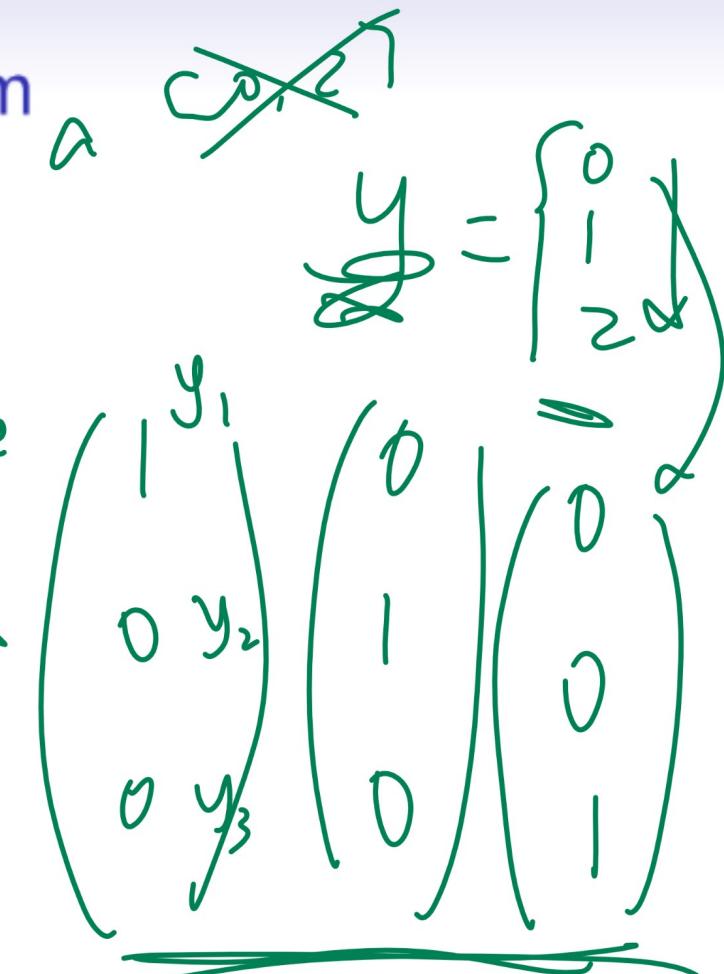
$$\begin{array}{c} \leftarrow Q > 0.5 \rightarrow J \\ \leftarrow v.5 \rightarrow D \end{array}$$

Softmax Diagram

Discussion



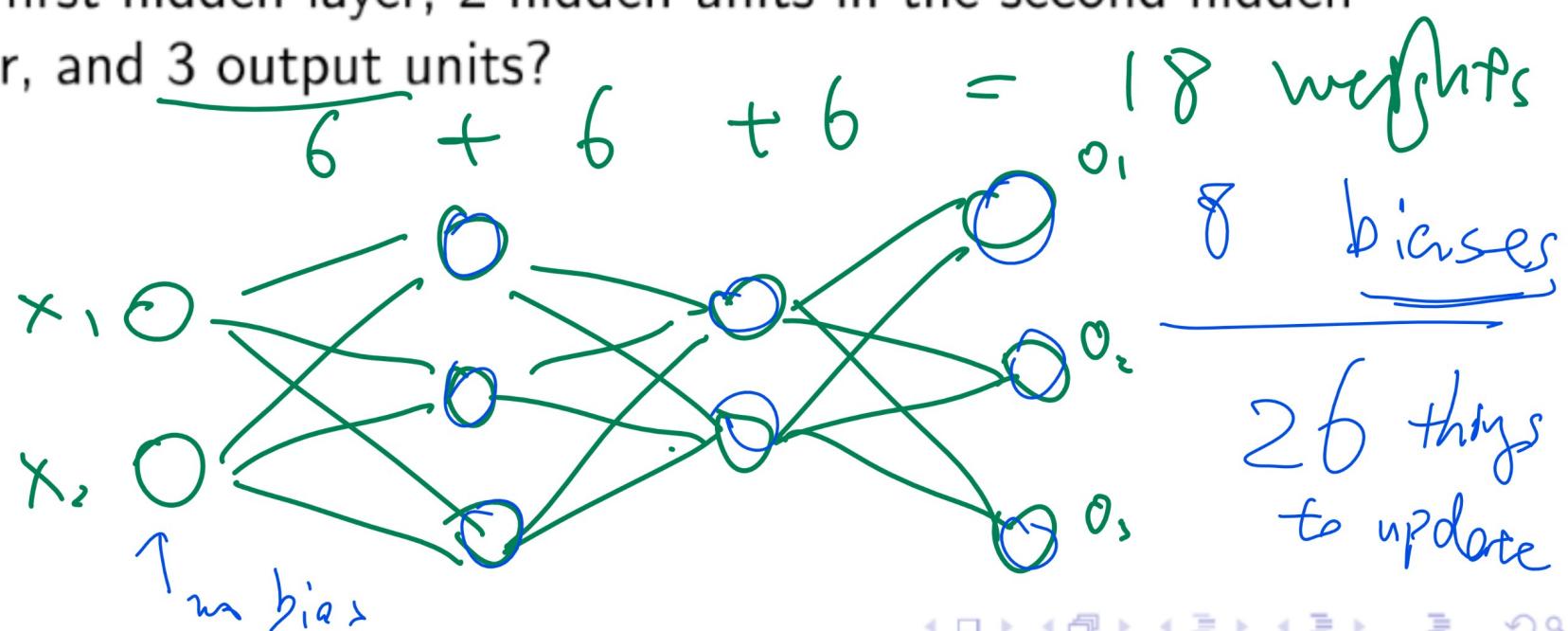
multiple logistic
Softmax



Weight Count

Quiz

- How many weights and biases are there in a (fully connected) three layer neural network with 2 input units, 3 hidden units in the first hidden layer, 2 hidden units in the second hidden layer, and 3 output units?

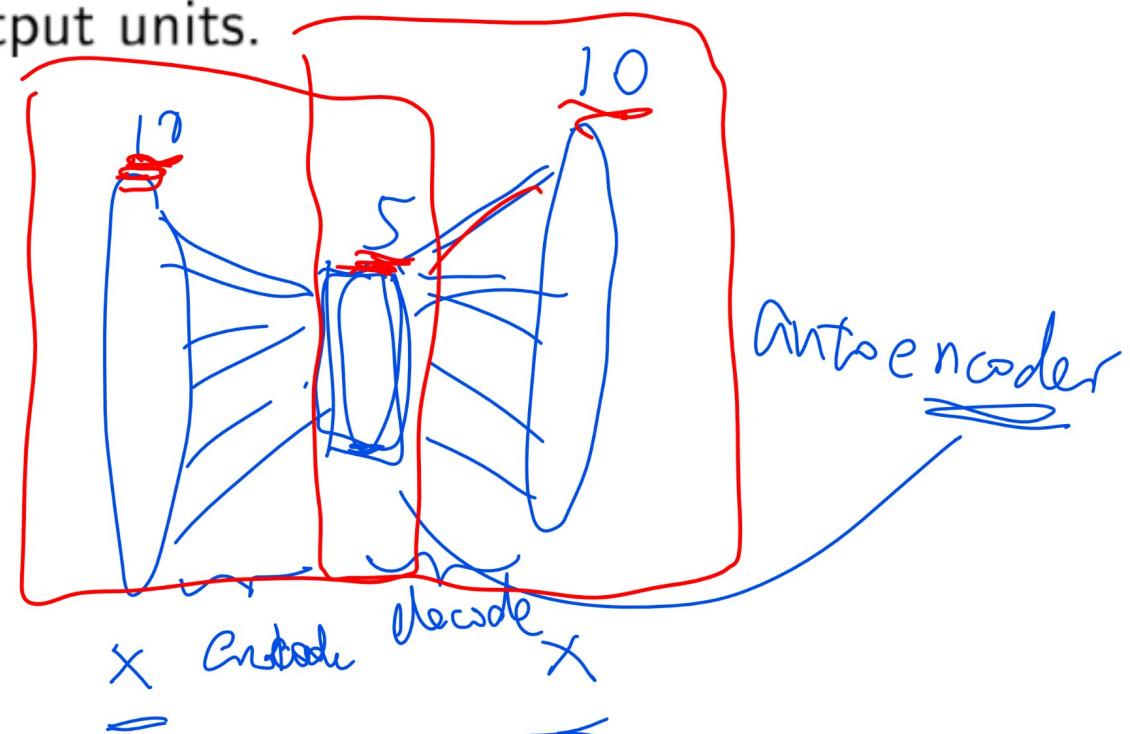


Weight Count 2

Quiz

Q7

- How many weights (not including bias) are there in a (fully connected) two layer neural network with 10 input units, 5 hidden units, and 10 output units.
- A: 50
- B: 55
- C: 100 $= 5 \cdot 10 + 10 \cdot 5$
- D: 110
- E: 500



Weight Count 3

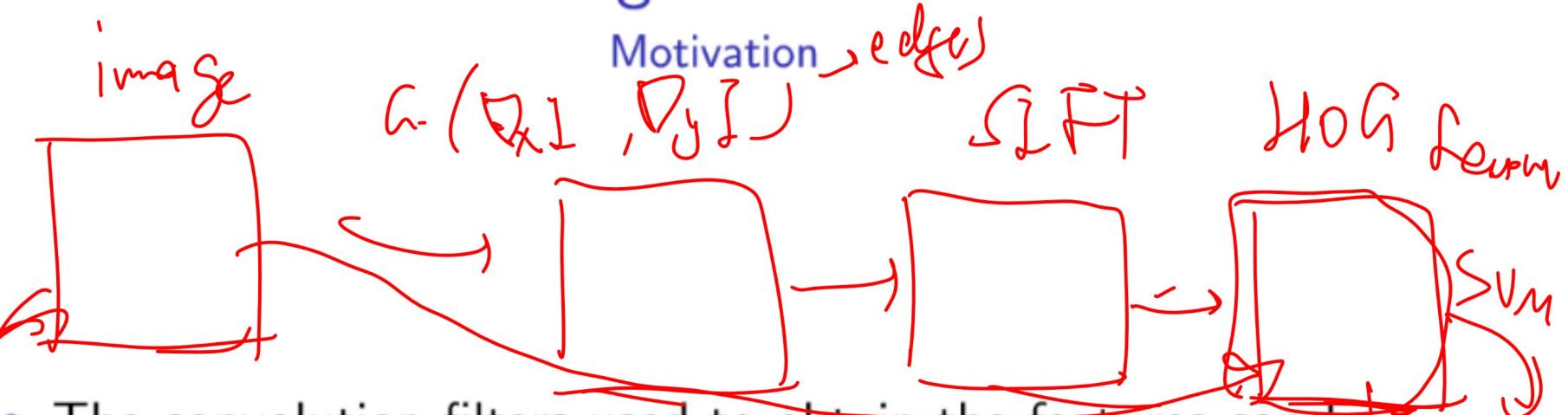
Quiz

Q8

- How many biases are there in a (fully connected) two layer neural network with 10 input units, 5 hidden units, and 10 output units.
- A: 5
- B: 10
- C: 15
- D: 20
- E: 25

$$5 + 5 = 10$$

Learning Convolution



- The convolution filters used to obtain the features can be learned in a neural network. Such networks are called convolutional neural networks and they usually contain multiple convolutional layers with fully connected and softmax layers near the end.

W
Convolution

feature

w

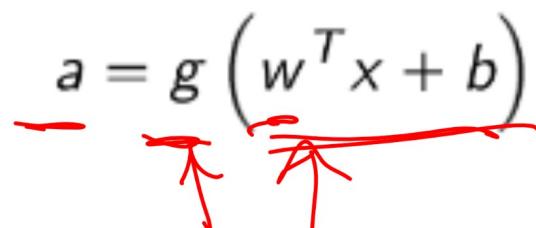
f_{ab}

feature engineering

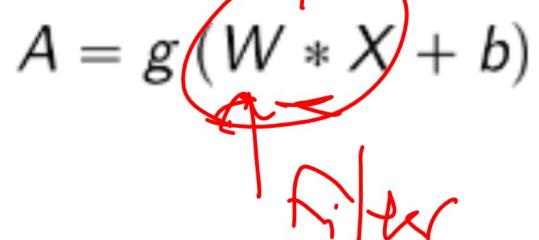
Convolutional Layers

Definition

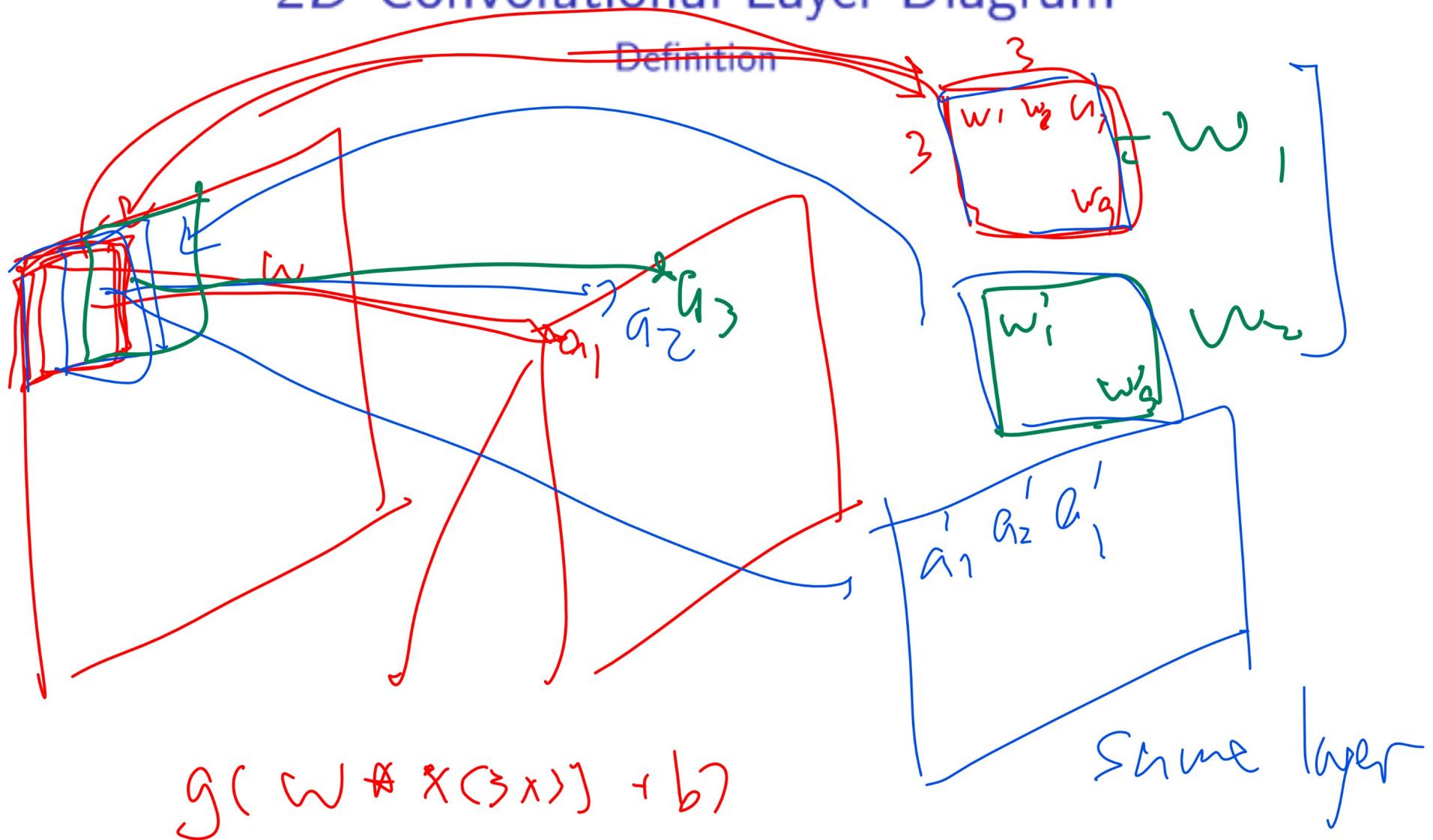
- In the (fully connected) neural networks discussed previously, each input unit is associated with a different weight.

$$a = g(w^T x + b)$$


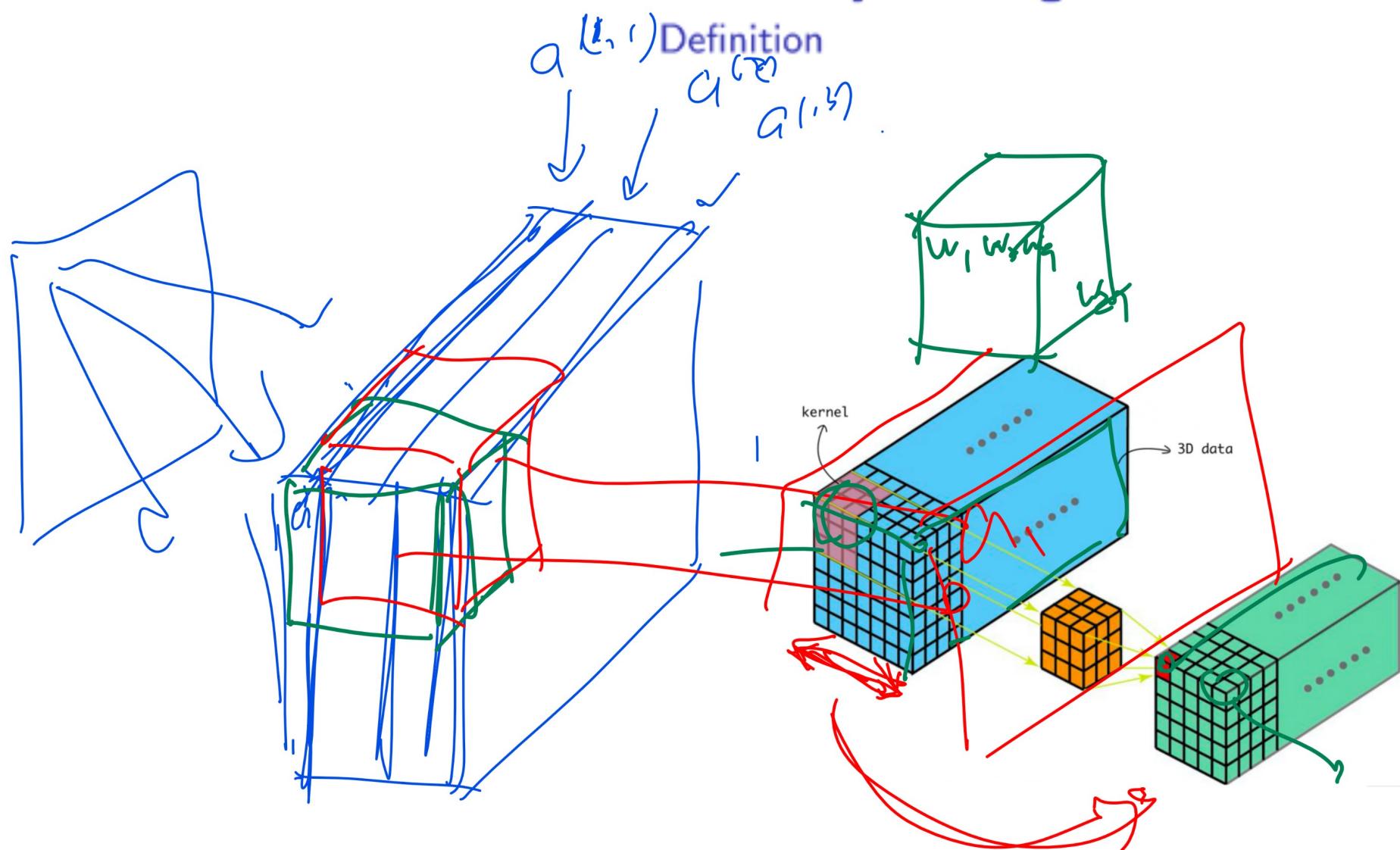
- In the convolutional layers, one single filter (a multi-dimensional array of weights) is used for all units (arranged in an array the same size as the filter).

$$A = g(W * X + b)$$


2D Convolutional Layer Diagram



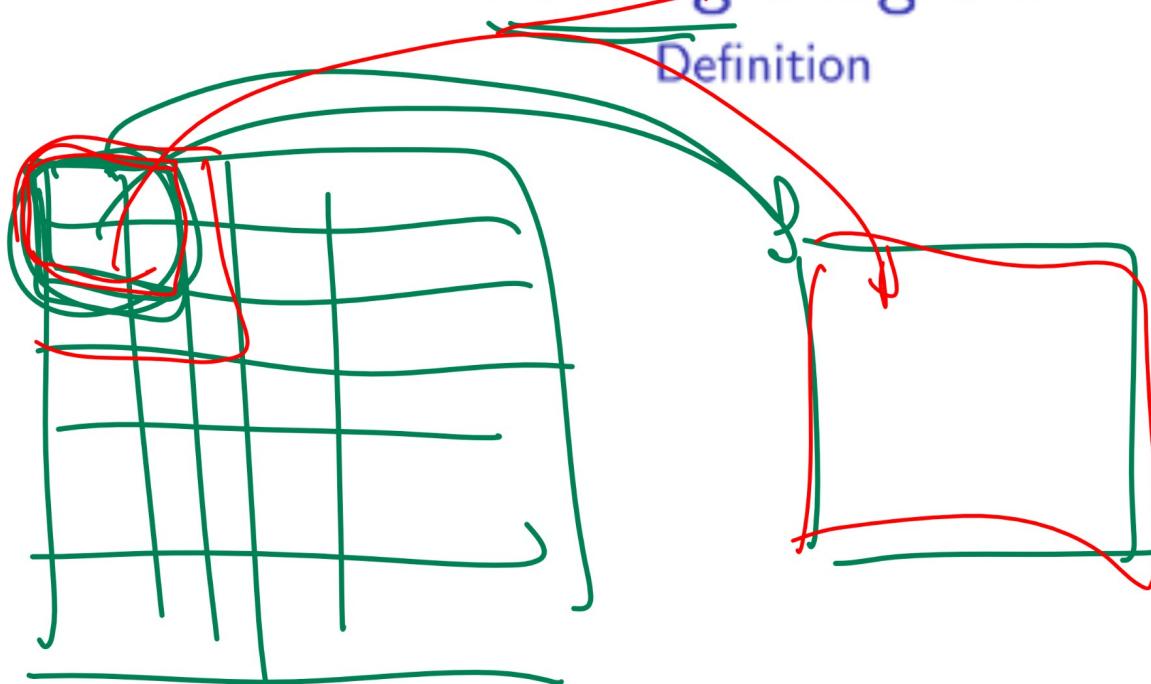
3D Convolutional Layer Diagram



Pooling Diagram

Definition

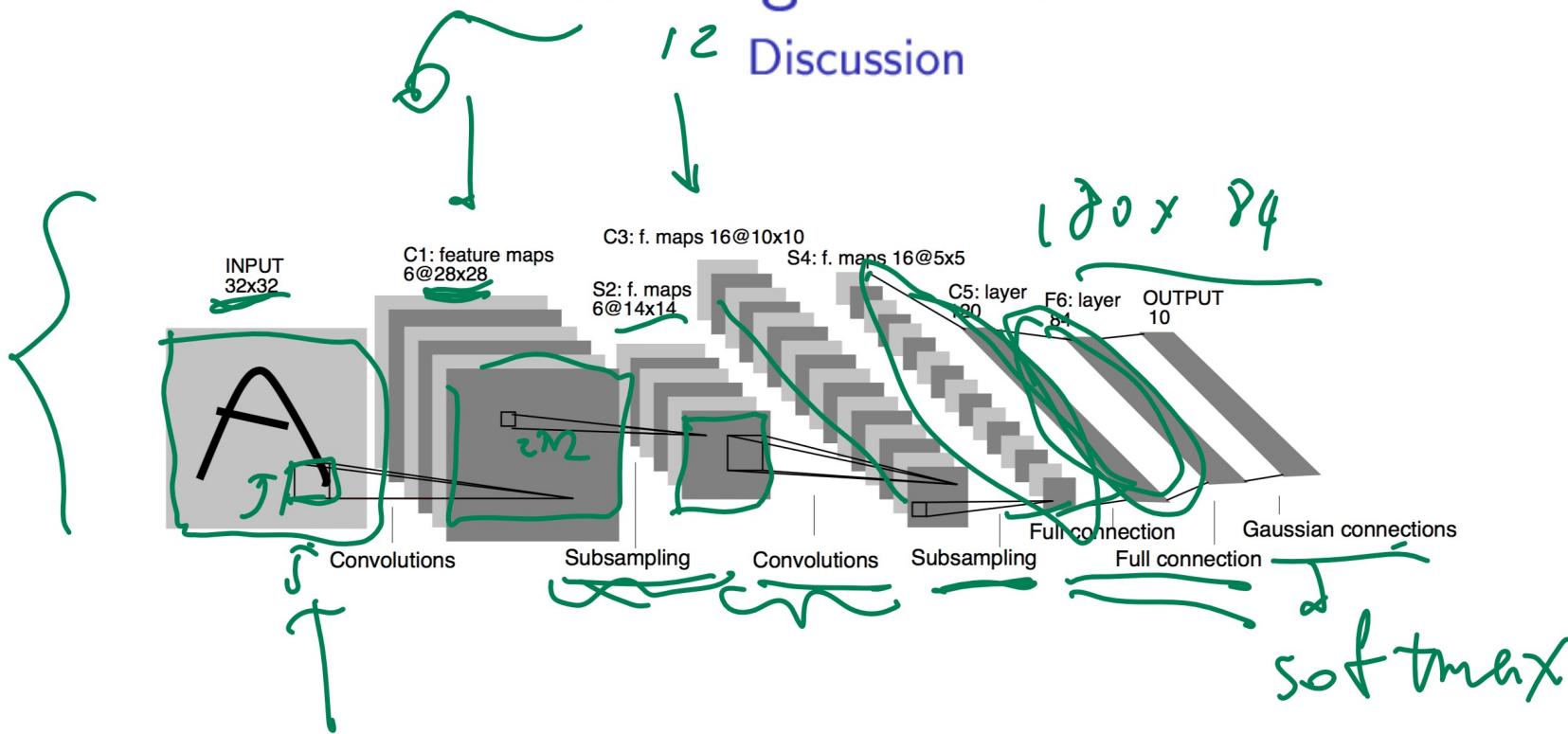
G



max pooling

average pooling

LeNet Diagram and Demo



$$\begin{matrix} 25 \\ \cancel{0} \\ 25 \times f \\ 25 \times 3 \end{matrix}$$

$$z = w * x + b$$

$$g(z)_{ij} = g(z_{ij}) \text{ matrix}$$