

CS540 Introduction to Artificial Intelligence

Lecture 2

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Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles Dyer

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Test

Quiz

$$\frac{2}{3} \cdot \frac{1}{h} \sum_{i=1}^n x_i$$

- Pick the number that is the closest to two-thirds of the average of the numbers other people picked.

- A: 0
- B: 1
- C: 2
- D: 3
- E: 4

↙ 0.85

Socrative Room

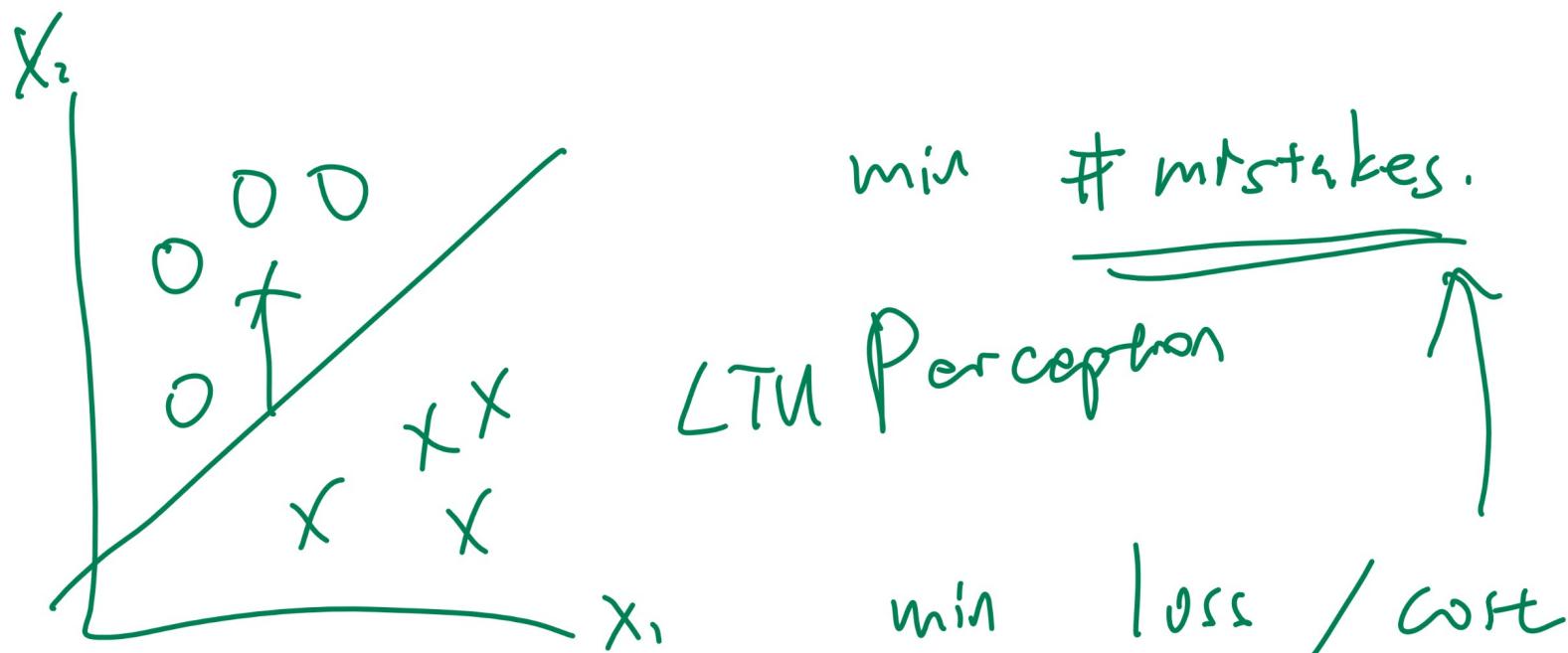
CS540C

~~→~~ @wisc.edu
↑ ID

Send all questions to "Questions" on public.

Loss Function Diagram

Motivation



Zero-One Loss Function

Motivation

- An objective function is needed to select the "best" \hat{f} . An example is the zero-one loss.

$$\hat{f} = \arg \min_f \sum_{i=1}^n \mathbb{1}_{\{f(x_i) \neq y_i\}}$$

2 mistake
0 mistake

- $\arg \min_f$ objective (f) outputs the function that minimizes the objective.
- The objective function is called the cost function (or the loss function), and the objective is to minimize the cost.

Squared Loss Function

Motivation

- Zero-one loss counts the number of mistakes made by the classifier. The best classifier is the one that makes the fewest mistakes.
- Another example is the squared distance between the predicted and the actual y value:

$$\hat{f} = \arg \min_f \frac{1}{2} \sum_{i=1}^n (f(x_i) - y_i)^2$$

↑ ↑
prediction label
↑
training

Loss Functions Equivalence

Quiz

- Which one of the following functions is not equivalent to the squared error for binary classification?

Q2

$$C = \sum_{i=1}^n (f(x_i) - y_i)^2, y_i \in \{0, 1\}$$

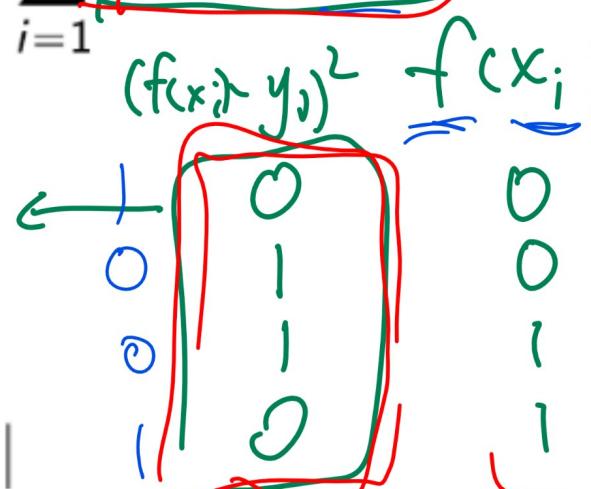
A: $\sum \mathbb{1}_{\{f(x_i) \neq y_i\}}$

B: $\sum \mathbb{1}_{\{f(x_i) = y_i\}}$

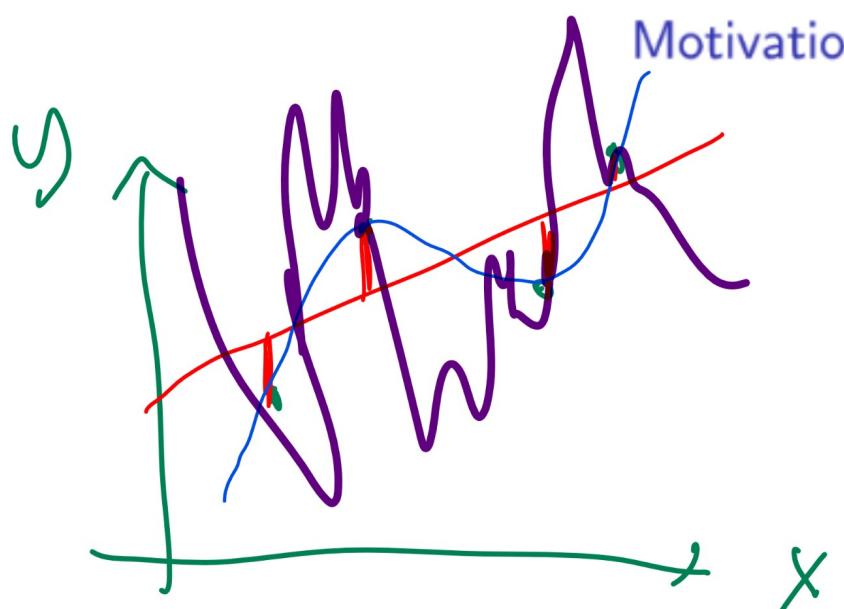
C: $\sum |f(x_i) - y_i|$

D: $\sum \max \{0, 1 - f(x_i) y_i\}$

E: $\sum \max \{0, 1 - (2 \cdot f(x_i) - 1)(2 \cdot y_i - 1)\}$



Function Space Diagram



Hypothesis Space

Motivation

- There are too many functions to choose from.
- There should be a smaller set of functions to choose \hat{f} from.

$$\hat{f} = \arg \min_{f \in \mathcal{H}} \frac{1}{2} \sum_{i=1}^n (f(x_i) - y_i)^2$$

- The set \mathcal{H} is called the hypothesis space.

Activation Function

Motivation

- Suppose \mathcal{H} is the set of functions that are compositions between another function g and linear functions.

bias
weights

$$(\hat{w}, \hat{b}) = \arg \min_{w,b} \frac{1}{2} \sum_{i=1}^n (a_i - y_i)^2$$

where $a_i = g(w^T x + b)$

activation function.

plane surface

Linear Threshold Unit

Motivation

- One simple choice is to use the step function as the activation function:

$$g(\boxed{\cdot}) = \mathbb{1}_{\{\cdot \geq 0\}} = \begin{cases} 1 & \text{if } \boxed{\cdot} \geq 0 \\ 0 & \text{if } \boxed{\cdot} < 0 \end{cases}$$

$w^\top x + b$

- This activation function is called linear threshold unit (LTU).

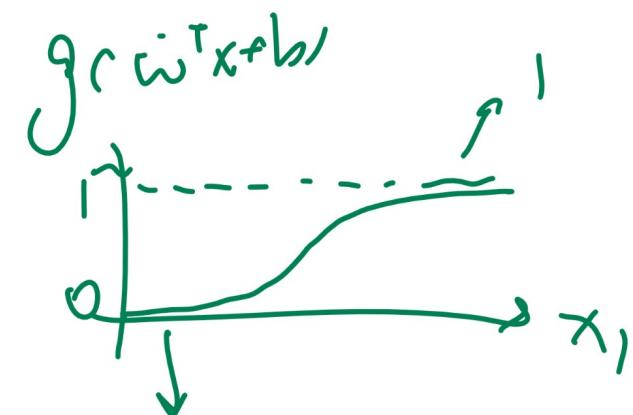
in L1

Sigmoid Activation Function

Motivation

- When the activation function g is the sigmoid function, the problem is called logistic regression.

$$g(\boxed{\cdot}) = \frac{1}{1 + \exp(-\boxed{\cdot})}$$



- This g is also called the logistic function.

Sigmoid Function Diagram

Motivation

Cross Entropy Loss Function

Motivation

$$C = (y_i - \hat{f}(x_i))^2$$

- The cost function used for logistic regression is usually the log cost function.

$$\rightarrow C(f) = - \sum_{i=1}^n (y_i \log(f(x_i)) + (1-y_i) \log(1-f(x_i)))$$

- It is also called the cross-entropy loss function.

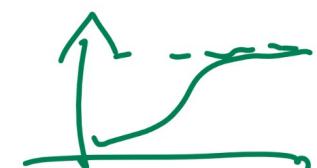
Logistic Regression Objective

Motivation

- The logistic regression problem can be summarized as the following.

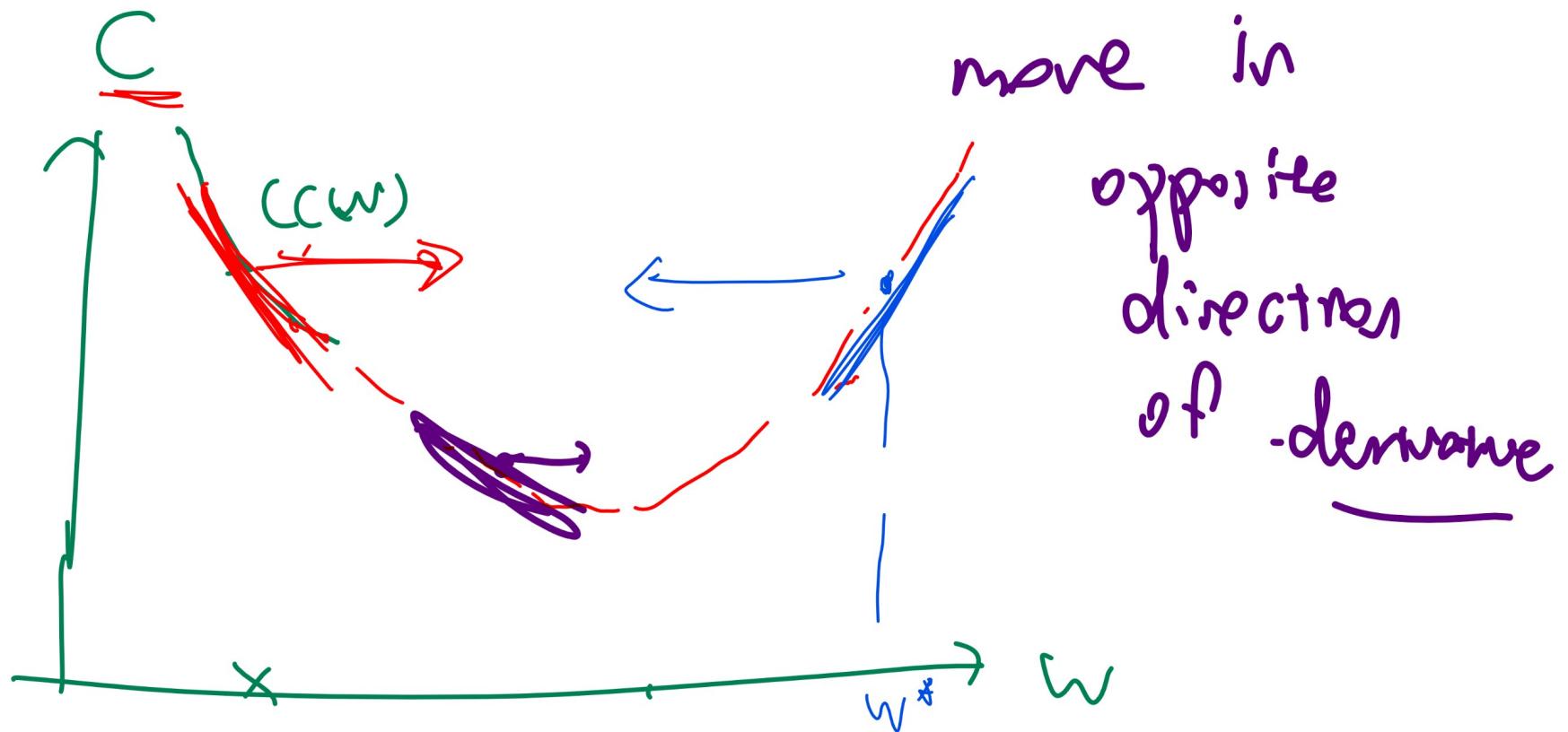
$$(\hat{w}, \hat{b}) = \arg \min_{w,b} - \sum_{i=1}^n (y_i \log(a_i) + (1 - y_i) \log(1 - a_i))$$

where $a_i = \frac{1}{1 + \exp(-z_i)}$ and $z_i = w^T x_i + b$



Optimization Diagram

Motivation



Learning Rate Demo

Motivation

Logistic Regression

Description

- Initialize random weights.
- Evaluate the activation function.
- Compute the gradient of the cost function with respect to each weight and bias.
- Update the weights and biases using gradient descent.
- Repeat until convergent.

$$a_i = g(\mathbf{x}^T \mathbf{w} + b)$$

Logistic Gradient Derivation 1

Definition
training

$$C = -\sum_{i=1}^n y_i \log q_i + (1-y_i) \log(1-q_i)$$
$$q_i = \frac{1}{1+e^{-(w^T x_i + b)}}$$

x_1, x_2, \dots, x_m
 w_1, w_2, \dots, w_m

$$\begin{aligned} \frac{\partial C}{\partial w_j} &= - \sum_{i=1}^n y_i \frac{1}{q_i} \cdot \frac{\partial q_i}{\partial w_j} - (1-y_i) \frac{1}{1-q_i} \frac{\partial q_i}{\partial w_j} \\ &= - \sum_{i=1}^n \left(\frac{y_i}{q_i} - \frac{1-y_i}{1-q_i} \right) \cdot \frac{e^{-(w^T x_i + b)}}{(1+e^{-(w^T x_i + b)})^2} x_i \end{aligned}$$

Logistic Gradient Derivation 2

Definition

$$= \left(\sum_{i=1}^n (y_i - a_i) y_i - a_i + a_i y_i \right) - a_i (1 - a_i)$$

$$\boxed{\sum_{i=1}^n (a_i - y_i) x_j}$$

$$\frac{1}{1 + e^{-(w^T x_i + b)}}$$

$$a_i (1 - a_i)$$

$$\frac{e^{-(w^T x_i + b)}}{1 + e^{-(w^T x_i + b)}}$$

Gradient Descent Step

Definition

- For logistic regression, use chain rule twice.

P_1

$$w = w - \alpha \sum_{i=1}^n (a_i - y_i) x_i$$

$$b = b - \alpha \sum_{i=1}^n (a_i - y_i)$$

$$a_i = g(w^T x_i + b), g(\cdot) = \frac{1}{1 + \exp(-\cdot)}$$

- α is the learning rate. It is the step size for each step of gradient descent.



Perceptron Algorithm

Definition

- Update weights using the following rule.

$$w = w - \alpha (a_i - y_i) x_i$$

geometric

$$b = b - \alpha (a_i - y_i)$$

Tricle,

$$a_i = \begin{cases} 1 & \text{if } w^T x_i + b \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

if $w^T x + b \geq 0$
otherwise

Gradient Descent

Quiz

- What is the gradient descent step for w if the objective (cost) function is the squared error?

$$C = \frac{1}{2} \sum_{i=1}^n (a_i - y_i)^2, a_i = g(w^T x_i + b), g'(z) = g(z) \cdot (1 - g(z))$$

$\frac{\partial C}{\partial w} = \frac{\partial C}{\partial a} \cdot \frac{\partial a}{\partial w}$

• A: $w = w - \alpha \sum (a_i - y_i)$
 • B: $w = w - \alpha \sum (a_i - y_i) x_i$ ← cross entropy loss.
 • C: $w = w - \alpha \sum (a_i - y_i) a_i x_i$
 • D: $w = w - \alpha \sum (a_i - y_i) (1 - a_i) x_i$
 • E: $w = w - \alpha \sum (a_i - y_i) [a_i (1 - a_i) x_i]$

$\frac{\partial C}{\partial w} = \frac{\partial C}{\partial a} \cdot \frac{\partial a}{\partial w}$
 $\frac{\partial C}{\partial a} = \frac{e^{-w^T x_i + b}}{1 + e^{-w^T x_i + b}}$
 $\frac{\partial a}{\partial w} = a_i (1 - a_i) x_i$

$\frac{\partial C}{\partial w} = \frac{\partial C}{\partial a} \cdot \frac{\partial a}{\partial w}$
 $\frac{\partial C}{\partial a} = \frac{e^{-w^T x_i + b}}{1 + e^{-w^T x_i + b}} \cdot x_i$
 $\frac{\partial a}{\partial w} = a_i (1 - a_i)$

$\frac{\partial C}{\partial w_1}, \frac{\partial C}{\partial w_2}, \frac{\partial C}{\partial w_3}, \frac{\partial C}{\partial w_4}$

Gradient Descent, Answer

Quiz

Gradient Descent, Another One

Quiz

- What is the gradient descent step for w if the activation function is the identity function?

Q4

$$C = \frac{1}{2} \sum_{i=1}^n (a_i - y_i)^2, a_i = w^T x_i + b$$

linear regression
least squares

$$\frac{\partial C}{\partial w} = \frac{\partial C}{\partial a} \frac{\partial a}{\partial w}$$

$\approx 1 \rightarrow \approx 12$

- A: $w = w - \alpha \sum (a_i - y_i)$
- B: $w = w - \alpha \sum (a_i - y_i) x_i$
- C: $w = w - \alpha \sum (a_i - y_i) a_i x_i$
- D: $w = w - \alpha \sum (a_i - y_i) (1 - a_i) x_i$
- E: $w = w - \alpha \sum (a_i - y_i) a_i (1 - a_i) x_i$

top 10

P1 → P6

top 5

Gradient Descent, Another One, Answer

Quiz

$$\underbrace{g^{-1}(q)}_{\textcircled{o}} \geq w^T x + b$$

$$C = \frac{1}{2} \sum_{i=1}^n (q_i - y_i)^2$$

$$q_i = w^T x_i + b$$

$$\frac{\partial C}{\partial w_j} = \sum_{i=1}^n \frac{\partial C}{\partial q_i} \frac{\partial q_i}{\partial w_j}$$

$$w_1 x_1 + w_2 x_2 + \dots + b$$

$$= \sum_{i=1}^n \left[\frac{1}{2} 2 (q_i - y_i) x_j \right]$$

$$\left[\begin{array}{c} \frac{\partial C}{\partial w_1} \\ \frac{\partial C}{\partial w_2} \\ \vdots \\ \frac{\partial C}{\partial w_n} \end{array} \right]$$

$$\frac{\partial C}{\partial w_j} = \sum_{i=1}^n (q_i - y_i) x_{ij}$$

$$\frac{\partial C}{\partial w} = \nabla_w C = \sum_{i=1}^n (q_i - y_i) x_i$$

Other Non-linear Activation Function

Discussion

- Activation function: $g(\cdot) = \tanh(\cdot) = \frac{e^{\cdot} - e^{-\cdot}}{e^{\cdot} + e^{-\cdot}}$
- Activation function: $g(\cdot) = \arctan(\cdot)$
- Activation function (rectified linear unit): $g(\cdot) = \cdot \mathbb{1}_{\{\cdot \geq 0\}}$
- All these functions lead to objective functions that are convex and differentiable (almost everywhere). Gradient descent can be used.