

CS540 Introduction to Artificial Intelligence

Lecture 1

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Based on lecture slides by Jerry Zhu, Yingyu Liang, and Charles
Dyer

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Lecture Format

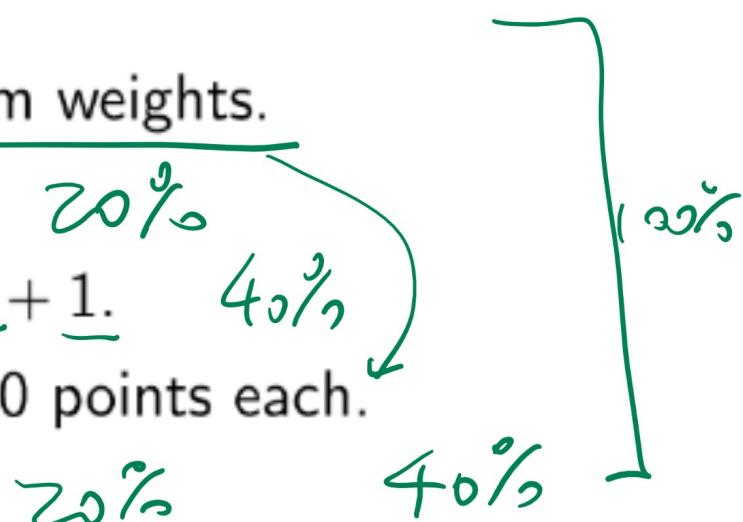
Admin

- Pre-recorded lectures will be posted on the course website.
- University-assigned lecture time will be used to go over examples and for participation quizzes.
- The remaining lecture time will be used as office hours.

Grading

Admin

- Quizzes: best 10 of 12 or double exam weights.
- Math homework: best 10 of 10 + 2. 20%
- Programming homework: best 5 of 5 + 1. 40%
- Exams: one midterm and one final, 10 points each.

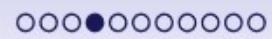


Quizzes

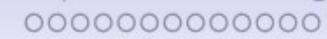
Admin

- Download Socrative, the room number is CS540E or CS540C.
- Default login for Socrative is your wisc email ID.
- If someone else tries to hack your account, please email or post on Piazza.
- Quiz questions can show up any time during the lecture.
- Missing one or two questions due to technical difficulty is okay.
- If you select obviously false answers, you might lose points.

Overview



Supervised Learning



Perceptron



Blank Quiz

Quiz

Math Homework

Admin

- Officially: due in 1 week Sunday.
- Unofficially: any time before the midterm or the final.
- Auto-graded: submit the output on Canvas.

Programming Homework

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- Officially: due in 2 weeks Sunday.
- Unofficially: any time before the final.
- Solution: posted in 1 week Sunday.
- Auto-graded: submit the output on Canvas.
- Code: any language.

Python Java

Midterm and Final

Admin

- Synchronous exam: morning and evening one, choose one to take.

(Not recommended) Ways to Get B+

Admin

- Not attending any lecture.
- Not doing any math homework.
- Not doing half of the programming homework.
- Not taking any of the exams (only this summer).

Only Way to Get A

Admin

- Do everything.

Textbook

Admin

- Lecture slides and videos will be sufficient.
- RN is a good background reading, does not cover everything.
- SS is very theoretical, useful if you are planning to take
760, 761, 861.

Admin

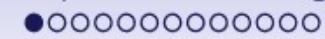
Admin

- Math and Stat Review posted under W1.
- Annotated slides will not be posted (because my handwriting is not recognizable).
- Unofficially: all homework are already posted (lots of mistakes and bugs).
- Officially: homework will be posted two to three days after the corresponding lecture.

Overview



Supervised Learning



Perceptron



Blank Quiz

Quiz

Is This Face Real

Quiz

- Which face is real?
- A: Left
- B: Right
- C: Do not choose this
- D: Do not choose this
- E: Do not choose this

Generative Adversarial Network

Motivation

- Generative Adversarial Network (GAN):

→ ① Generative part: input random noise and output fake images.

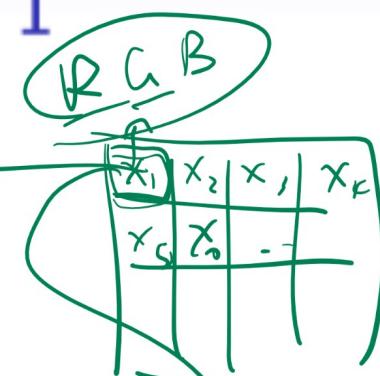
→ ② Discriminative part: input real and fake images and output labels real or fake.

③ The two parts compete with each other.

Supervised Learning Example 1



Motivation



$$\hat{f}'(\vec{x}) = \hat{y}$$

| | |
|------------------|--------------------------------|
| Data | images of cats and dogs |
| Features (Input) | height, length, eye color, ... |
| - | pixel intensity |
| Output | cat or dog |

$$f(\vec{x}) = \hat{y}$$

Supervised Learning Example 2

Motivation

$$(-f(x)) = \hat{y}$$

| | |
|------------------|-------------------------------------|
| Data | medical records |
| Features (Input) | scan, blood, and other test results |
| Output | disease or no |

| | |
|------------------|-----------------------------------|
| Data | patient information |
| Features (Input) | age, pre-existing conditions, ... |
| Output | likelihood of death |

Supervised Learning Example 3

Motivation

| | |
|------------------|--------------------|
| Data | face images |
| Features (Input) | edges corners, ... |
| Output | face or non-face |

2D

CNN

| | |
|------------------|---------------------------------|
| Data | self-driving car data |
| Features (Input) | distance (depth), movement, ... |
| Output | road or non-road |

2D

4D

Supervised Learning Example 4

Motivation

$f(x_1, x_2, x_3, \dots)$

$f(x) = \hat{y}$

emails

RNN

| Data | |
|------------------|---------------------------------|
| Features (Input) | word count, capitalization, ... |
| Output | spam or ham |

| Data | |
|------------------|---------------------------------|
| Features (Input) | word count, capitalization, ... |
| Output | offensive or not |

Supervised Learning Example 5

Motivation

| | |
|------------------|---------------------------------|
| Data | reviews |
| Features (Input) | word count, capitalization, ... |
| Output | positive or negative |

| | |
|------------------|------------------------|
| Data | financial transactions |
| Features (Input) | amount, frequency, ... |
| Output | fraud or not |

Supervised Learning Example 6

Motivation

O o O

$\delta \sigma$ $\varphi \psi$ P_1

| | |
|------------------|--|
| Data | handwritten letters |
| Features (Input) | pixel, stroke |
| Output | δ or σ , φ or ψ |

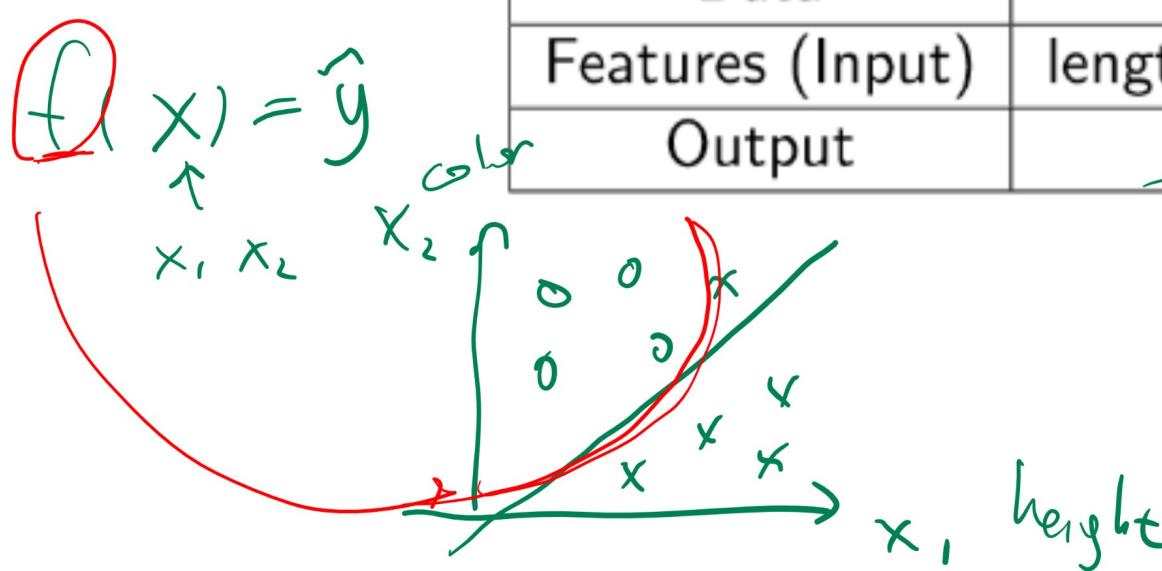
| | |
|------------------|--|
| Data | voice recording |
| Features (Input) | signal, sound (phoneme) |
| Output | recognize speech or wreck a nice beach |

Supervised Learning Example 7

Motivation

| | |
|------------------|------------------------|
| Data | painting |
| Features (Input) | appearance, price, ... |
| Output | art or garbage |

| | |
|------------------|-------------------|
| Data | essay |
| Features (Input) | length, key words |
| Output | A+ or F |



Supervised Learning

Motivation

$$\hat{f}(x) \approx y$$

- Supervised learning:

Diagram illustrating the supervised learning process:

m # pixel
 n # images
 n # label

| Data | Features (Input) | Output | - |
|--------|---------------------------------------|-------------------|-------------------------------|
| Sample | $\{(x_{i1}, \dots, x_{im})\}_{i=1}^n$ | $\{y_i\}_{i=1}^n$ | find "best" \hat{f} |
| - | observable | known | - |
| New | (x'_1, \dots, x'_m) | y' | guess $\hat{y} = \hat{f}(x')$ |
| - | observable | unknown | - |

Training and Test Sets

Motivation

- Supervised learning:

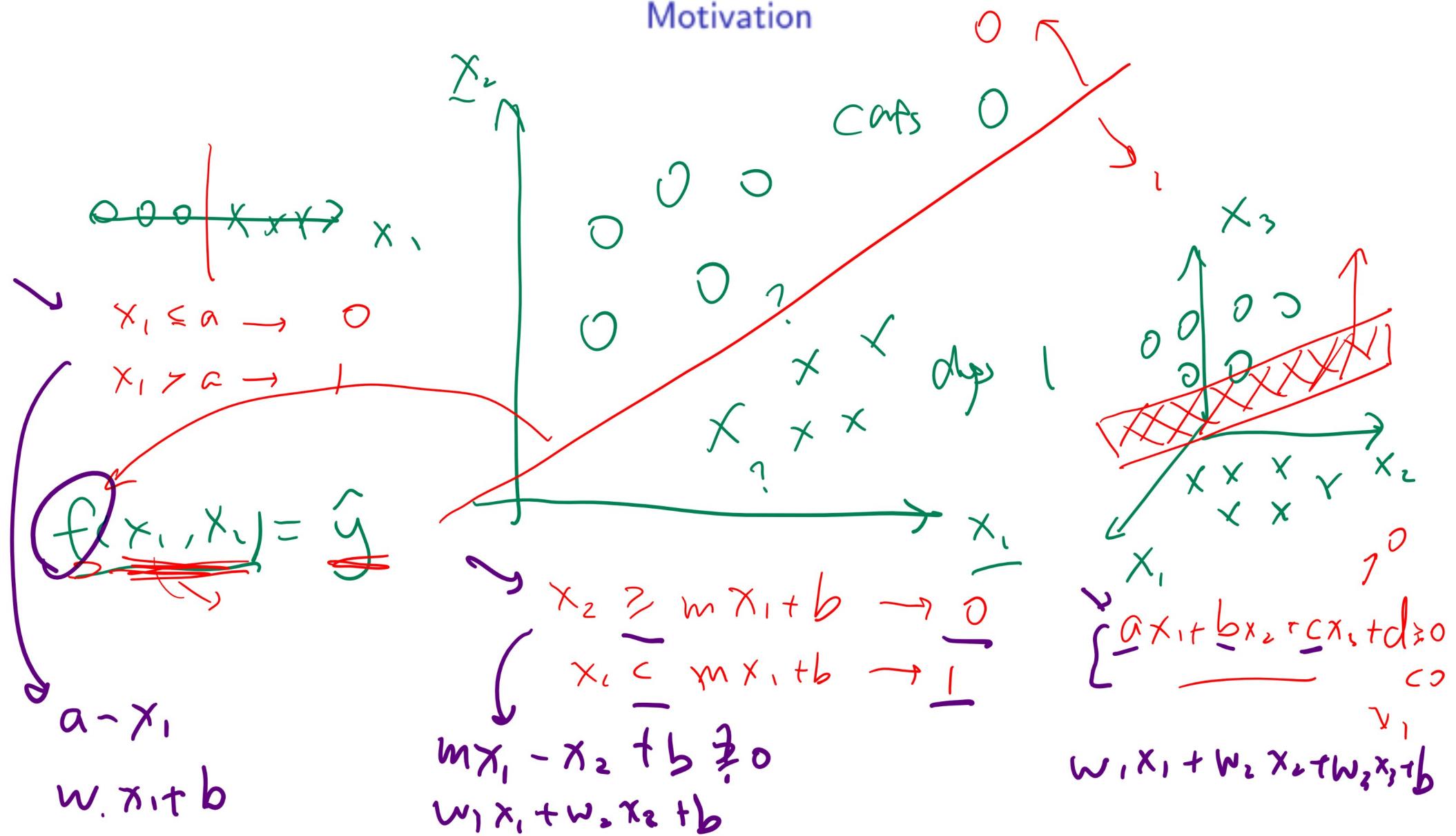
The diagram illustrates a process flow. An input x enters two parallel paths, each labeled with a function: $\hat{f}_1(x)$ and $\hat{f}_2(x)$. The outputs of these two paths are then combined or compared to produce a final output, represented by a circle containing a stylized letter f .

| Data | Features (Input) | Output | - |
|------------|--|----------------------|-------------------------------|
| Training | $\{(x_{i1}, \dots, x_{im})\}_{i=1}^{n'}$ | $\{y_i\}_{i=1}^{n'}$ | find "good" \hat{f} |
| - | observable | known | - |
| Validation | $\{(x_{i1}, \dots, x_{im})\}_{i=n'}^n$ | $\{y_i\}_{i=n'}^n$ | find "best" \hat{f} |
| - | observable | known | - |
| Test | (x'_1, \dots, x'_m) | y' | guess $\hat{y} = \hat{f}(x')$ |
| - | observable | unknown | - |

Sample

Simple 2D Example Diagram

Motivation



Linear Classifier

Motivation

- One possible guess is in the form of a linear classifier.

$$\hat{y} = \mathbb{1}_{\{w_1x_1 + w_2x_2 + \dots + w_mx_m + b \geq 0\}}$$

$w = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_m \end{pmatrix}$

$w^T x + b \geq 0$

m - D features

hyper plane

The $\mathbb{1}$ (open number 1) is the indicator function.

$$w^T = (w_1, w_2, \dots, w_m)$$

$$\mathbb{1}_E = \begin{cases} 1 & \text{if } E \text{ is true} \\ 0 & \text{if } E \text{ is false} \end{cases}$$

$$w^T x + b = (\underbrace{w_1, w_2, \dots, w_m}_{}) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix} + b = w_1x_1 + w_2x_2 + \dots + w_mx_m + b$$

Linear Threshold Unit

Motivation

- This simple linear classifier is also called a Linear Threshold Unit (LTU) Perceptron.
- w_1, w_2, \dots, w_m are called the weights, and b is called the bias.
- The function that makes the prediction based on $w^T x + b$ is called the activation function.
- For an LTU Perceptron, the activation function is the indicator function.

$$g(\boxed{\cdot}) = \mathbb{1}_{\{\boxed{\cdot} \geq 0\}}$$

$$\hat{y} = g(w^T x + b)$$

Equation of a Line

Motivation

- In 1D, $\underbrace{w_1 x_1 + b \geq 0}$ is just a threshold rule: $x_1 \geq -\frac{b}{w_1}$ implies $\hat{y} = 1$.
- In 2D, $\underbrace{w_1 x_1 + w_2 x_2 + b \geq 0}$ can be written as
$$\begin{bmatrix} w_1 & w_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b \geq 0.$$
Note that $w_1 x_1 + w_2 x_2 + b = 0$ is the equation of a line, usually written as $x_2 = -\frac{w_1}{w_2} x_1 - \frac{b}{w_2}$.

Equation of a Hyperplane

Motivation

- In 3D, $w_1x_1 + w_2x_2 + w_3x_3 + b \geq 0$ can be written as

$$\begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + b \geq 0. \text{ Note that}$$

$w_1x_1 + w_2x_2 + w_3x_3 + b = 0$ is the equation of a plane, and

$\begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$ is normal vector of the plane.

- The normal vector is perpendicular to all vectors on the plane.

LTU Perceptron Training

Motivation

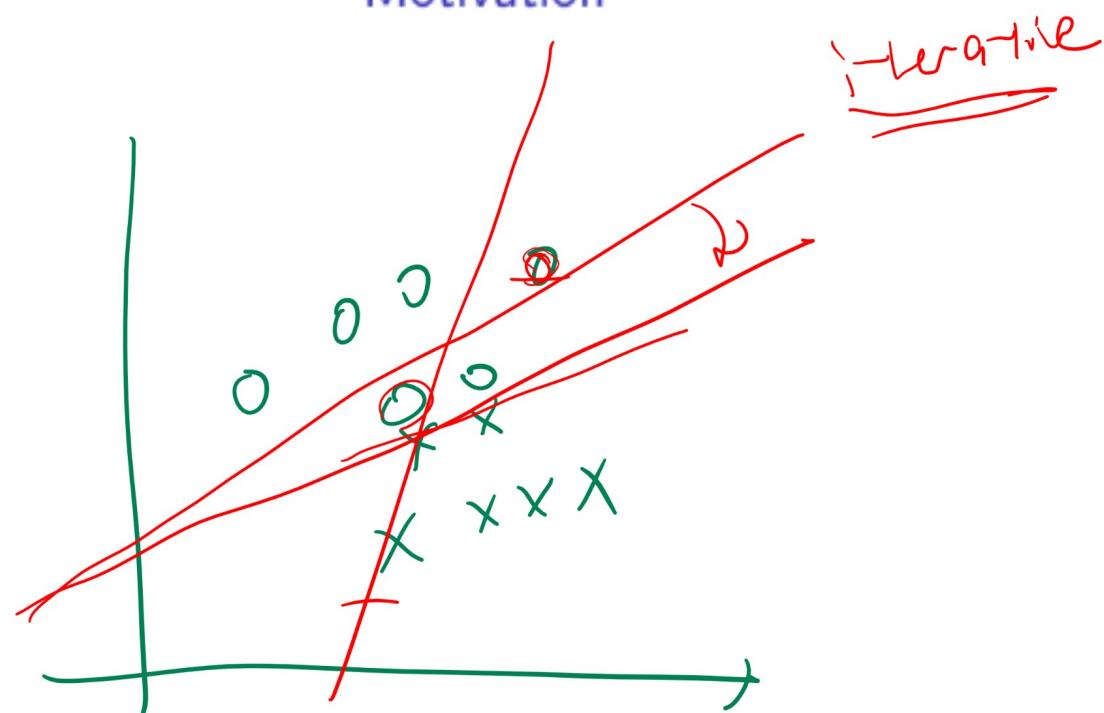
Sample

Instances

- Given the training set $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$, the process of figuring out the weights and the bias is called training an LTU Perceptron.
- One algorithm to train an LTU Perceptron is called the Perceptron Algorithm.

Brute Force LTU Learning

Motivation



Perceptron Algorithm

Description

- Initialize random weights.
- Evaluate the activation function at one instance x_i to get \hat{y}_i .
- If the prediction \hat{y}_i is 0 and actual y_i is 1, increase the weights by x_i .
- If the prediction \hat{y}_i is 1 and actual y_i is 0, decrease the weights by x_i .
- Repeat for all data points and until convergent.

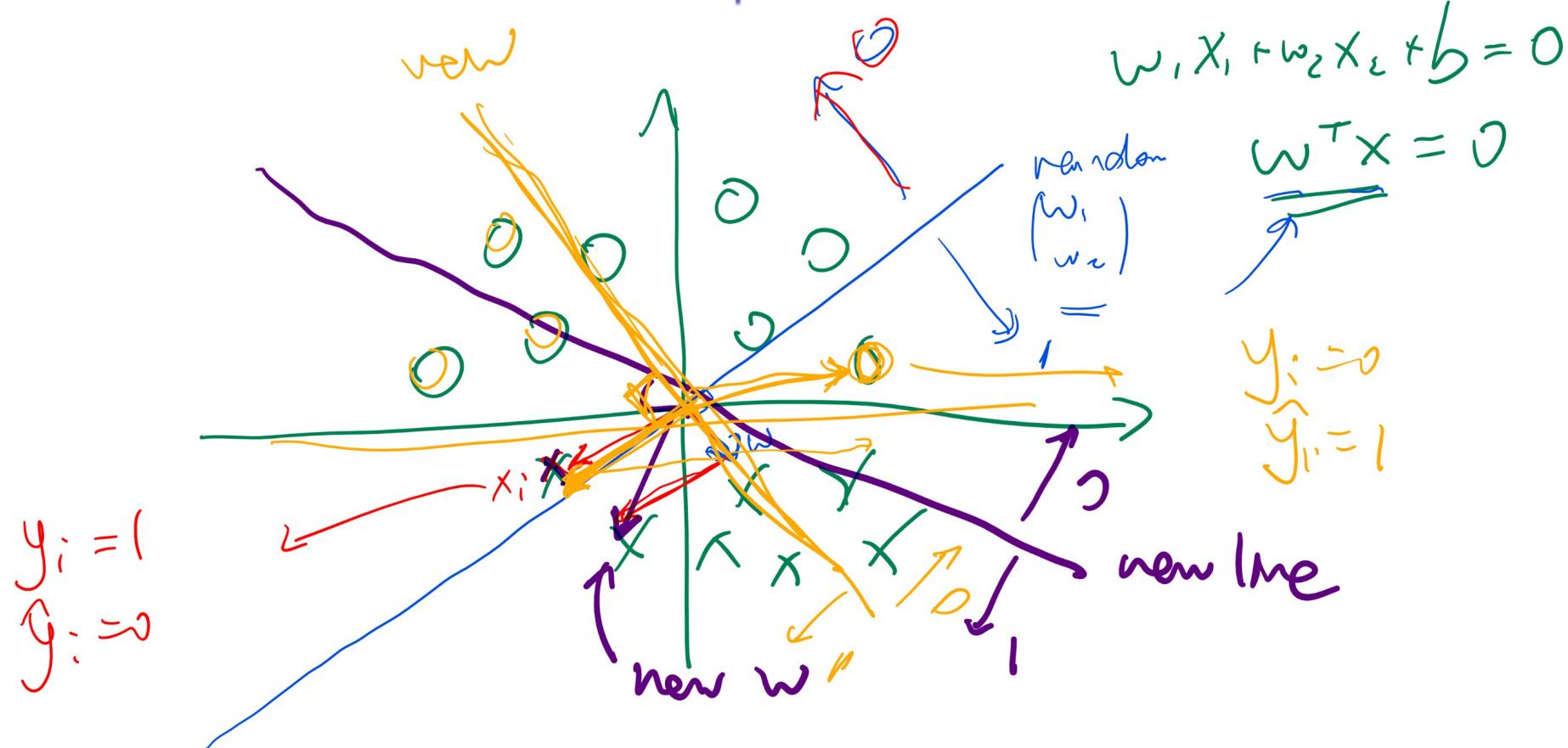
x_i, y_i

$$w + x_i$$

$$w - x_i$$

Perceptron Algorithm Diagram, 0 Example

Description



Perceptron Algorithm Diagram, 1 Example

Description

Perceptron Algorithm, Part 1

Algorithm

- Inputs: instances: $\{x_i\}_{i=1}^n$ and $\{y_i\}_{i=1}^n$
- Outputs: weights and biases: w_1, \dots, w_m , and b .
- Initialize the weights.

$w_1, \dots, w_m, b \sim \text{Unif } [-1, 1]$

$\text{Unif } [l, u]$ means picking a random number between l and u .

- Evaluate the activation function at a single data point x_i :

$$a_i = \mathbb{1}_{\{w^T x_i + b \geq 0\}}$$

Perceptron Algorithm, Part 2

Algorithm

- Update weights using the following rule.

$$w = w - \alpha (a_i - y_i) x_i$$

$$b = b + \alpha (a_i - y_i)$$

$$\begin{aligned} a_i &= y_i = 0, 1 \\ w &= w \quad \checkmark \end{aligned}$$

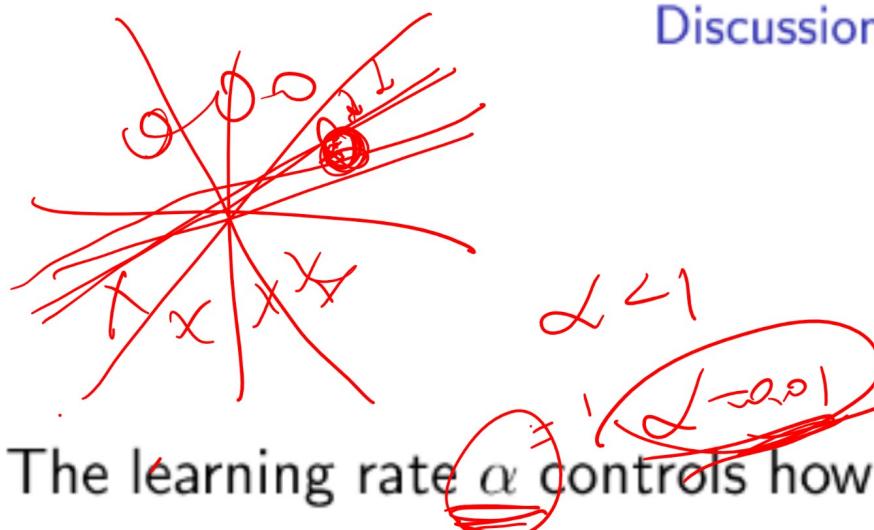
$$\begin{aligned} a_i &= 1, y_i = 0 \\ w &= w - x_i \end{aligned}$$

$$\begin{aligned} a_i &= 0, y_i = 1 \\ w &= w + x_i \end{aligned}$$

- Repeat the process for every $x_i, i = 1, 2, \dots, n$.
- Repeat until $a_i = y_i$ for every $i = 1, 2, \dots, n$.

Learning Rate

Discussion



- The learning rate α controls how fast the weights are updated.
- They can be constant for each update or they can change (usually decrease) for each update.
- For perceptron learning, it is typically set to 1.

Perceptron Algorithm

Quiz