# Machine Learning Project04

October 29, 2019

```
[1]: import torch
    from torch.utils.data import Dataset, DataLoader
    import torchvision.transforms as transforms
    from torch.autograd import Variable
    import torchvision
    import os
    import sys
    from scipy.special import xlogy
    import matplotlib.pyplot as plt
    import numpy as np
    import time
    transform = transforms.Compose([#transforms.Resize((256,256)),
                                     transforms.Grayscale(),
                                                                            # the
     \rightarrow code transforms. Graysclae() is for changing the size [3,100,100] to [1, 100,\square
     →100] (notice : [channel, height, width] )
                                     transforms.ToTensor(),])
     #train_data_path = 'relative path of training data set'
    → \\MachineLearningProject\\horse-or-human\\horse-or-human\\train'
    trainset = torchvision.datasets.ImageFolder(root=train_data_path,_u
     →transform=transform)
     # change the valuee of batch_size, num_workers for your program
     # if shuffle=True, the data reshuffled at every epoch
    trainloader = torch.utils.data.DataLoader(trainset, batch_size=1,_
     ⇒shuffle=False, num_workers=1)
    validation_data_path = 'C:\\ __
     → \\MachineLearningProject\\horse-or-human\\horse-or-human\\validation'
    valset = torchvision.datasets.ImageFolder(root=validation data path,
      →transform=transform)
```

```
# change the value of batch_size, num_workers for your program
valloader = torch.utils.data.DataLoader(valset, batch_size=1, shuffle=False,__
_num_workers=1)
```

```
[2]: train_labels=np.zeros(1027)
     test_labels=np.zeros(256)
     train_datas=np.zeros((1027,10000))
     test_datas=np.zeros((256,10000))
     for epoch in range(1):
         sum=0
         # load training images of the batch size for every iteration
         for i, data in enumerate(trainloader):
             inputs, labels = data
             train_labels[i]=int(labels)
             reinputs=inputs.reshape(10000)
             reinputs=np.array(reinputs)
             train_datas[i]=reinputs
         train_datas=train_datas.T
         for i, data in enumerate(valloader):
             sum+=1
             inputs, labels = data
             test_labels[i]=int(labels)
             reinputs=inputs.reshape(10000)
             reinputs=np.array(reinputs)
             test_datas[i]=reinputs
         test_datas=test_datas.T
```

```
[3]: def accuracy_func(h_,label):
    label_result=np.zeros(len(h_))
    correct=0
    for i in range(len(label)):
        if(h_[i]<0.5):
            label_result[i]=0
        elif(h_[i]>=0.5):
            label_result[i]=1
```

### 1 sigmoid

```
[4]: NUM_EPOCH=10000

total_loss=np.zeros(NUM_EPOCH)
total_loss_test=np.zeros(NUM_EPOCH)

accuracy=np.zeros(NUM_EPOCH)
accuracy_test=np.zeros(NUM_EPOCH)

known_data1=np.random.randn(10000,10)
known_data2=np.random.randn(10,3)
known_data3=np.random.randn(3,1)

b_1=np.random.randn(10,1)
b_2=np.random.randn(3,1)
b_3=np.random.randn(1,1)
```

```
[]: l_rate=0.085
     delta = 1e-70
     for i in range(NUM_EPOCH):
         #Vectorizing Logistic Regression for train_set
         z1=known_data1.T@train_datas+b_1 #10x1027 =a
         A1=1.0/(1+np.exp(-z1))
         z2=known_data2.T@A1 +b_2 #3x1027=b
         A2=1.0/(1+np.exp(-z2))
         z3=known data3.T@A2+b 3 #1x1027=c
         A3=1.0/(1+np.exp(-z3))
         #Vectorizing Logistic Regression for validation_set
         z1_v=known_data1.T@test_datas+b_1 #10x256=a
         A1_v=1.0/(1+np.exp(-z1_v))
         z2_v=known_data2.T@A1_v+b_2 #3x256=b
         A2_v=1.0/(1+np.exp(-z2_v))
         z3_v=known_data3.T@A2_v+b_3 #1x256=c
```

```
A3_v=1.0/(1+np.exp(-z3_v))
         j=-(xlogy(train_labels,A3)+xlogy(1-train_labels,1-A3)).sum()/1027
         j_v=-(xlogy(test_labels,A3_v)+xlogy(1-test_labels,1-A3_v)).sum()/256
         #backpropagation
         L_3=A3-train_labels #1027
         L_3=L_3.reshape(1027,1)
         L 2=known data3@L 3.T*((1-A2)*A2)
         L_1=known_data20L_2*((1-A1)*A1) #10x1027
         #backpropagation first-layer
         dL_3=(A20L_3.T)/1027
         known_data3-=1_rate*dL_3
         b3=np.sum(L_3,axis=1,keepdims=True)/1027
         #backpropagation second-layer
         dL_2 = (A10L_2.T)/1027
         known_data2-=1_rate*dL_2
         b2=np.sum(L_2,axis=1,keepdims=True)/1027
         #backpropagation third-layer
         dL_1=(train_datas@L_1.T)/1027
         known data1-=1 rate*dL 1
         b1=np.sum(L_1,axis=1,keepdims=True)/1027
         total_loss[i]=j
         A3=A3.reshape(1027)
         accuracy[i] = accuracy_func(A3,train_labels)
         A3_v=A3_v.reshape(256)
         total_loss_test[i]=j_v
         accuracy_test[i] = accuracy_func(A3_v,test_labels)
[]: plt.plot(total_loss,label='Training Loss')
     plt.plot(total_loss_test,label='Validation Loss')
     plt.legend(loc='upper right')
     plt.title("Total Loss at Every Iteration")
     plt.xlabel("Iteraion")
[]: plt.plot(accuracy, label='Training Accuracy')
     plt.plot(accuracy test,label='Validation Accuracy')
     plt.legend(loc='lower right')
     plt.title("Total Accuracy")
```

```
plt.xlabel("Iteraion")
 []: print("""
             Data set
                                       Loss
                                                          Accuracy
                                                          %6.2f %%
                                       %6.3f
             Training
        -----
                                       %6.3f
      %(total_loss[NUM_EPOCH-1],accuracy[NUM_EPOCH-1]*100,total_loss_test[NUM_EPOCH-1],accuracy_test
        tanh
[109]: NUM_EPOCH=4000
      total_loss=np.zeros(NUM_EPOCH)
      total_loss_test=np.zeros(NUM_EPOCH)
      accuracy=np.zeros(NUM_EPOCH)
      accuracy_test=np.zeros(NUM_EPOCH)
      known_data1=np.random.randn(10000,10)
      known_data2=np.random.randn(10,3)
      known_data3=np.random.randn(3,1)
      b_1=np.random.randn(10,1)
      b_2=np.random.randn(3,1)
      b_3=np.random.randn(1,1)
[110]: | l_rate=0.08
      delta = 1e-70
      for i in range(NUM_EPOCH):
          #Vectorizing Logistic Regression for train_set
          z1=known_data1.T@train_datas+b_1 #10x1027 =a
          A1=np.tanh(z1)
          z2=known_data2.T@A1 +b_2 #3x1027=b
          A2=np.tanh(z2)
          z3=known_data3.T@A2+b_3 #1x1027=c
          A3=1.0/(1+np.exp(-z3))
          #Vectorizing Logistic Regression for validation_set
```

z1\_v=known\_data1.T@test\_datas+b\_1 #10x256=a

A1\_v=np.tanh(z1\_v)

```
z2_v=known_data2.T@A1_v+b_2 #3x256=b
A2_v=np.tanh(z2_v)
z3_v=known_data3.T@A2_v+b_3 #1x256=c
A3_v=1.0/(1+np.exp(-z3_v))
j=-(xlogy(train_labels,A3)+xlogy(1-train_labels,1-A3)).sum()/1027
j_v = -(x\log y(test_labels, A3_v) + x\log y(1-test_labels, 1-A3_v)).sum()/256
#backpropagation
L_3=A3-train_labels #1027
L_3=L_3.reshape(1,1027) #3x1
L_2=known_data30L_3*(1-A2*A2)
                               #1x1027
L_1=known_data20L_2*(1-A1*A1)
#backpropagation first-layer
dL_3=(A20L_3.T)/1027 #3x1
known_data3-=1_rate*dL_3
b3=np.sum(L_3,axis=1,keepdims=True)/1027
#backpropagation second-layer
dL_2=(A10L_2.T)/1027
known_data2-=1_rate*dL_2
b2=np.sum(L_2,axis=1,keepdims=True)/1027
#backpropagation third-layer
dL_1=(train_datas@L_1.T)/1027
known_data1-=l_rate*dL_1
b1=np.sum(L_1,axis=1,keepdims=True)/1027
total_loss[i]=j
A3=A3.reshape(1027)
accuracy[i]=accuracy_func(A3,train_labels)
A3_v=A3_v.reshape(256)
total_loss_test[i]=j_v
accuracy_test[i]=accuracy_func(A3_v,test_labels)
```

```
KeyboardInterrupt Traceback (most recent call⊔ →last)

<ipython-input-110-d8d7edb2d12a> in <module>
```

```
38 #backpropagation third-layer
39 L_1=known_data2@L_2*(1-A1*A1) #10x1027
---> 40 dL_1=(train_datas@L_1.T)/1027
41 known_data1-=l_rate*dL_1
42 b1=np.sum(L_1,axis=1,keepdims=True)/1027
```

#### KeyboardInterrupt:

```
[26]: plt.plot(total_loss,label='Training Loss')
   plt.plot(total_loss_test,label='Validation Loss')
   plt.legend(loc='upper right')
   plt.title("Total Loss at Every Iteration")
   plt.xlabel("Iteraion")
```

#### [26]: Text(0.5, 0, 'Iteraion')



```
[]: plt.plot(accuracy,label='Training Accuracy')
  plt.plot(accuracy_test,label='Validation Accuracy')
  plt.legend(loc='lower right')
  plt.title("Total Accuracy")
  plt.xlabel("Iteraion")
```

```
[27]: print("""
       _____
                         %6.3f
     -----
       Validation
                 | %6.2f %%
    %(total_loss[NUM_EPOCH-1],accuracy[NUM_EPOCH-1]*100,total_loss_test[NUM_EPOCH-1],accuracy_test
        Data set | Loss | Accuracy
                         0.521
                                       74.88 %
    +----+
       Validation |
                         0.404
      ReLu
[342]: def relu_prime(A):
      dA = np.where(A>0,1,0)
      return dA
[347]: NUM_EPOCH=4000
    total_loss=np.zeros(NUM_EPOCH)
    total_loss_test=np.zeros(NUM_EPOCH)
    accuracy=np.zeros(NUM_EPOCH)
    accuracy_test=np.zeros(NUM_EPOCH)
    known_data1=np.random.randn(10000,10)*0.1
```

```
b_1=np.random.randn(10,1)*0.1
b_2=np.random.randn(3,1)*0.1
b_3=np.random.randn(1,1)*0.1

[348]:
l_rate=0.0087

delta = 1e-70
for i in range(NUM_EPOCH):
    #Vectorizing Logistic Regression for train_set
    z1=np.dot(known_data1.T,train_datas)+b_1 #10x1027 =a
```

known\_data2=np.random.randn(10,3)\*0.1
known\_data3=np.random.randn(3,1)\*0.1

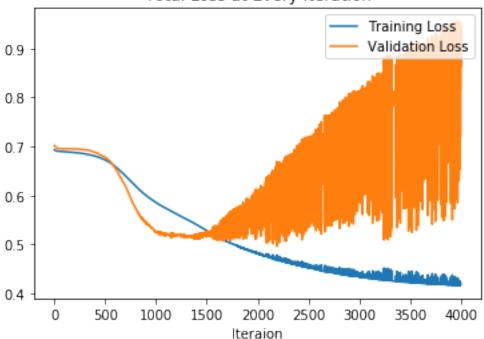
```
A1=np.maximum(0,z1)
z2=np.dot(known_data2.T,A1) +b_2 #3x1027=b
A2=np.maximum(0,z2)
z3=np.dot(known_data3.T,A2)+b_3 #1x1027=c
A3=1.0/(1+np.exp(-z3))
#Vectorizing Logistic Regression for validation_set
z1_v=np.dot(known_data1.T,test_datas)+b_1 #10x256=a
A1 v=np.maximum(0,z1 v)
z2_v=np.dot(known_data2.T,A1_v)+b_2 #3x256=b
A2 v=np.maximum(0,z2 v)
z3_v=np.dot(known_data3.T,A2_v)+b_3 #1x256=c
A3 v=1.0/(1+np.exp(-z3 v))
j=-(xlogy(train_labels,A3)+xlogy(1-train_labels,1-A3)).sum()/1027
j_v=-(xlogy(test_labels,A3_v)+xlogy(1-test_labels,1-A3_v)).sum()/256
#backpropagation
L_3=A3-train_labels #L_3=1x1027
L_3=L_3.reshape(1,1027)
L_2=np.multiply(np.dot(known_data3,L_3),relu_prime(A2)) #L_2= 3x1027
L_1=np.multiply(np.dot(known_data2,L_2),relu_prime(A1)) #L_1= 10x1027
print(j)
#backpropagation first-layer
dL 3=np.dot(A2,L 3.T)/1027
known_data3-=1_rate*dL_3
b3=np.sum(L_3,axis=1,keepdims=True)/1027
#backpropagation second-layer
dL_2=np.dot(A1,L_2.T)/1027 #10x3
known_data2-=1_rate*dL_2
b2=np.sum(L_2,axis=1,keepdims=True)/1027
#backpropagation third-layer
dL_1=np.dot(train_datas,L_1.T)/1027 #10000x10
known_data1-=l_rate*dL_1
b1=np.sum(L 1,axis=1,keepdims=True)/1027
total loss[i]=j
A3=A3.reshape(1027)
accuracy[i] = accuracy_func(A3,train_labels)
A3_v=A3_v.reshape(256)
total_loss_test[i]=j_v
```

### accuracy\_test[i] = accuracy\_func(A3\_v,test\_labels)

```
[349]: plt.plot(total_loss,label='Training Loss')
    plt.plot(total_loss_test,label='Validation Loss')
    plt.legend(loc='upper right')
    plt.title("Total Loss at Every Iteration")
    plt.xlabel("Iteraion")
```

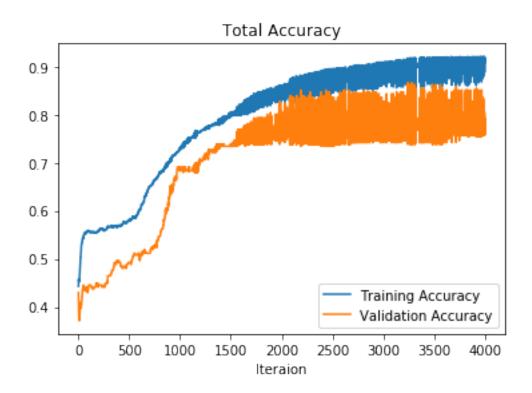
[349]: Text(0.5, 0, 'Iteraion')





```
[350]: plt.plot(accuracy,label='Training Accuracy')
    plt.plot(accuracy_test,label='Validation Accuracy')
    plt.legend(loc='lower right')
    plt.title("Total Accuracy")
    plt.xlabel("Iteraion")
```

[350]: Text(0.5, 0, 'Iteraion')



## 4 Leaky ReLu

```
[]: l_rate=0.065
     delta = 1e-70
     for i in range(NUM_EPOCH):
         #Vectorizing Logistic Regression for train set
         z1=np.dot(known_data1.T,train_datas)+b_1 #10x1027 =a
         A1=np.maximum(0.01*z1,z1)
         z2=np.dot(known_data2.T,A1) +b_2 #3x1027=b
         A2=np.maximum(0.01*z2,z2)
         z3=np.dot(known_data3.T,A2)+b_3 #1x1027=c
         A3=1.0/(1+np.exp(-z3))
         #Vectorizing Logistic Regression for validation_set
         z1_v=np.dot(known_data1.T,test_datas)+b_1 #10x256=a
         A1_v=np.maximum(0.01*z1_v,z1_v)
         z2_v=np.dot(known_data2.T,A1_v)+b_2 #3x256=b
         A2_v=np.maximum(0.01*z2_v,z2_v)
         z3_v=np.dot(known_data3.T,A2_v)+b_3 #1x256=c
         A3_v=1.0/(1+np.exp(-z3_v))
         j=-(xlogy(train_labels,A3)+xlogy(1-train_labels,1-A3)).sum()/1027
         j_v = -(x\log y(test_labels, A3_v) + x\log y(1-test_labels, 1-A3_v)).sum()/256
         #backpropagation
         L 3=A3-train labels #L 3=1x1027
         L 3=L 3.reshape(1,1027)
         L_2=np.multiply(np.dot(known_data3,L_3),leakyrelu_prime(A2)) #L_2= 3x1027
         L_1=np.multiply(np.dot(known_data2, L_2), leakyrelu_prime(A1)) #L_1= 10x1027
         print(j)
         #backpropagation first-layer
         dL_3=np.dot(A2,L_3.T)/1027
         known_data3-=1_rate*dL_3
         b3=np.sum(L_3,axis=1,keepdims=True)/1027
         #backpropagation second-layer
         dL_2=np.dot(A1,L_2.T)/1027 #10x3
         known data2-=1 rate*dL 2
         b2=np.sum(L_2,axis=1,keepdims=True)/1027
         #backpropagation third-layer
         dL_1=np.dot(train_datas,L_1.T)/1027 #10000x10
         known_data1-=l_rate*dL_1
         b1=np.sum(L_1,axis=1,keepdims=True)/1027
```

```
total_loss[i]=j
         A3=A3.reshape(1027)
         accuracy[i]=accuracy_func(A3,train_labels)
         A3_v=A3_v.reshape(256)
         total_loss_test[i]=j_v
         accuracy_test[i] = accuracy_func(A3_v,test_labels)
[]: plt.plot(total_loss,label='Training Loss')
    plt.plot(total_loss_test,label='Validation Loss')
    plt.legend(loc='upper right')
     plt.title("Total Loss at Every Iteration")
     plt.xlabel("Iteraion")
[]: plt.plot(accuracy, label='Training Accuracy')
    plt.plot(accuracy_test,label='Validation Accuracy')
     plt.legend(loc='lower right')
     plt.title("Total Accuracy")
     plt.xlabel("Iteraion")
```