

# data science for (physical) scientists VIII

Tree methods

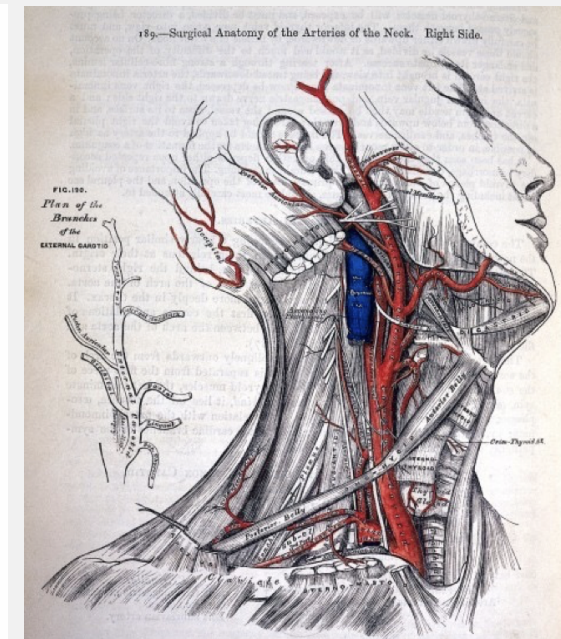
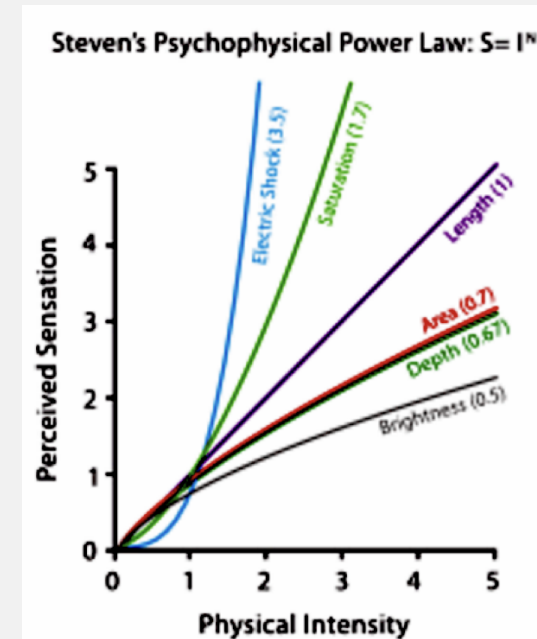
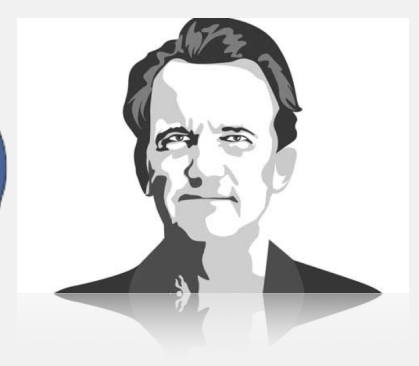
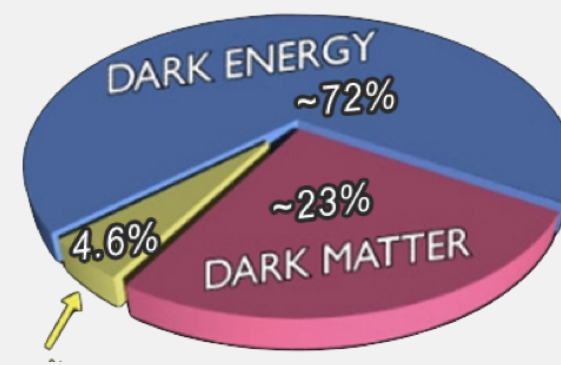
*dr.federica bianco | fbb.space |  fedhere |  fedhere*

this slide deck: <http://bit.ly/dspsVIII>

- Descriptive data viz
  - Lie with statistics
  - Tufte's rules

- Exploratory data viz  
Jer Thorp

- Psychophysics
- Esthetics vs(??) functionality
  - color blindness
  - the third dimension
- Interactivity



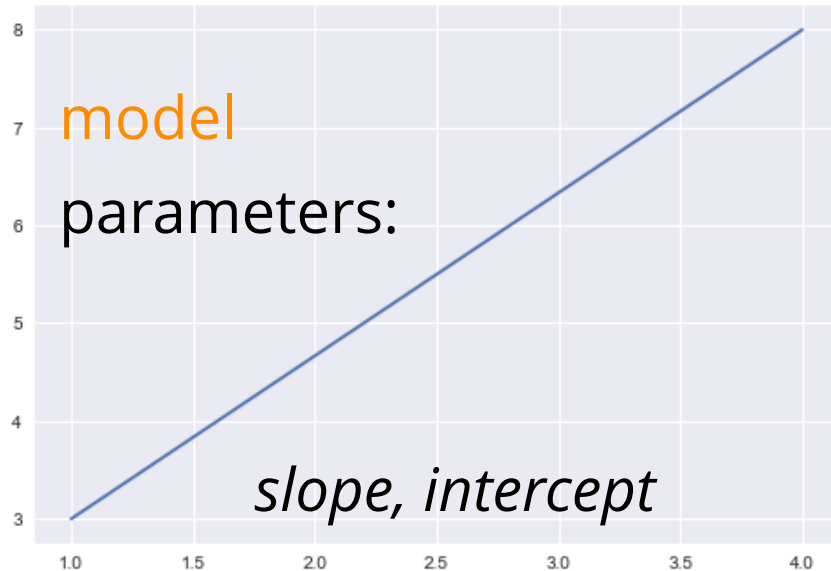


what is machine learning

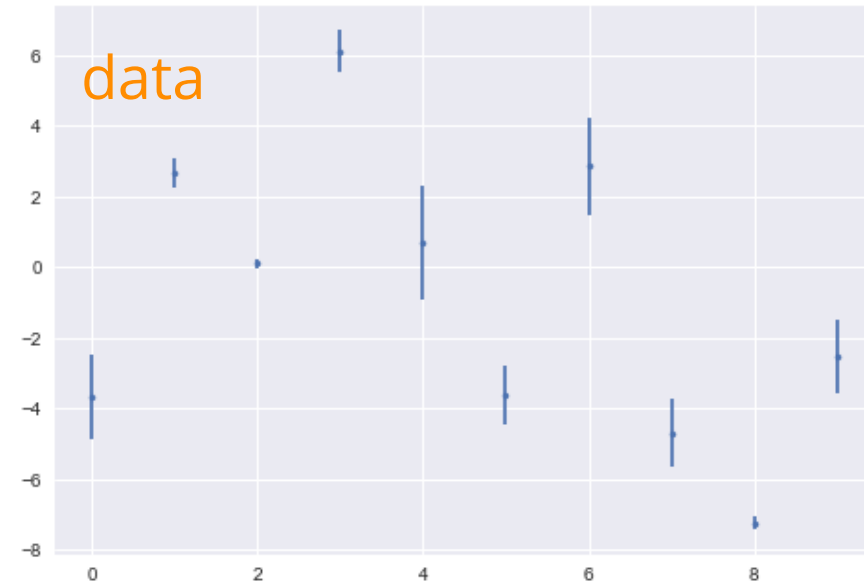
# what is machine learning?

*[Machine Learning is the] field of study that gives computers the ability to learn without being explicitly programmed.*

Arthur Samuel, 1959



ML: any model  
with parameters  
learnt from the  
data



# what is machine learning?



## **supervised learning**

*classification*  
prediction  
feature selection

## **unsupervised learning**

*understanding structure*  
organizing/compressing data  
anomaly detection  
dimensionality reduction

# what is machine learning?



## supervised learning

k-Nearest Neighbors

**Regression**

Support Vector Machines

**Classification/Regression Trees**

**Neural networks**

*classification*

*prediction*

*feature selection*

## unsupervised learning

*understanding structure*

*organizing/compressing data*

*anomaly detection*

*dimensionality reduction*

**clustering**

PCA

Apriori

# general ML parts

used to:

understand structure of feature space  
classify based on examples,  
regression (classification with infinitely  
small classes)



# general ML parts

should be interpretable: why?

*ethical implication,*  
predictive policing,  
selection of conference participants.

# general ML parts

ML models have *parameters* and  
*hyperparameters*

*parameters*: the model optimizes based on the data

*hyperparameters*: chosen by the model author,  
could be based on domain knowledge, other data,  
guessed (?!). e.g. the shape of the polynomial

# general ML parts

should be interpretable: why?

*ethical implication,*  
predictive policing,  
selection of conference participants.

*connect to causality*  
why the model made a choice?  
which feature mattered

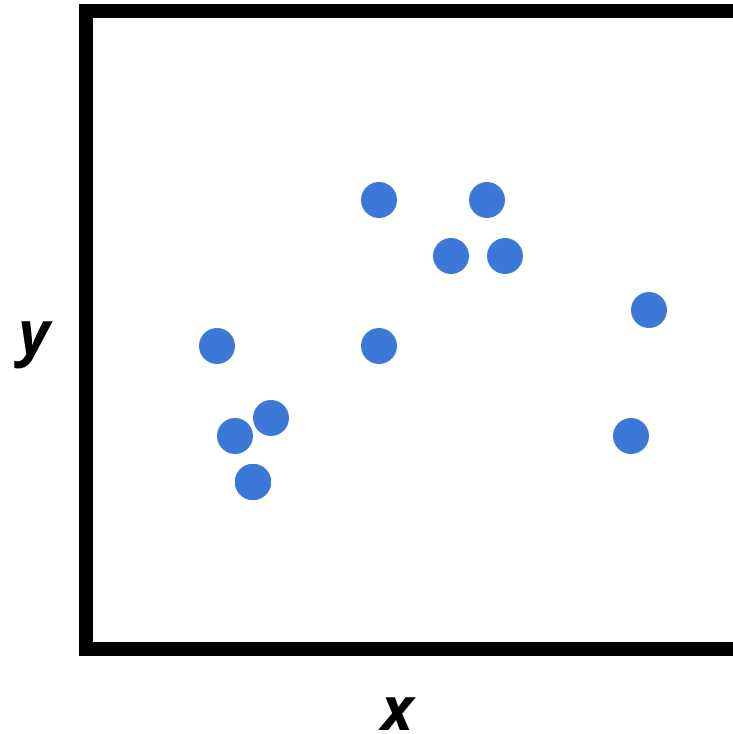
# classification vs clustering

1

# clustering vs classifying

## *unsupervised*

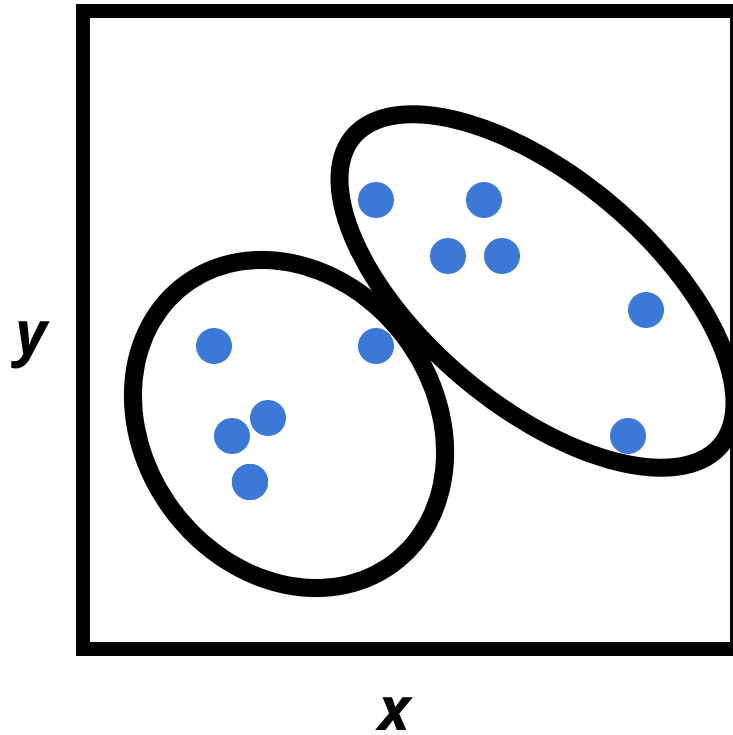
observed **features:**  
 $(\vec{x}, \vec{y})$



# clustering vs classifying

## *unsupervised*

observed **features:**  
 $(\vec{x}, \vec{y})$



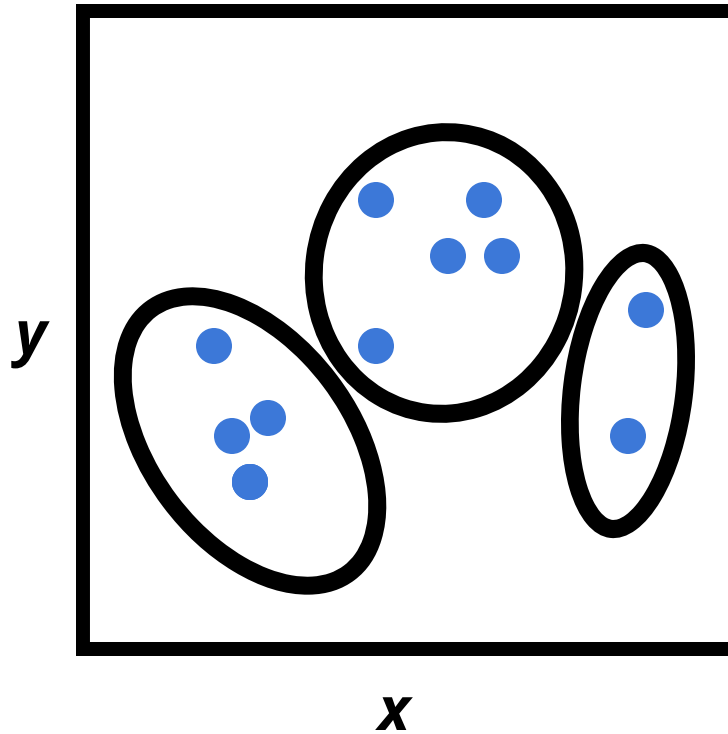
# clustering vs classifying

## *unsupervised*

goal is to partition the space so that the **observed** variables are separated into

- maximally homogeneous
- maximally distinguishable groups

observed **features:**  
 $(\vec{x}, \vec{y})$



models typically return a cluster label by object

# clustering vs classifying

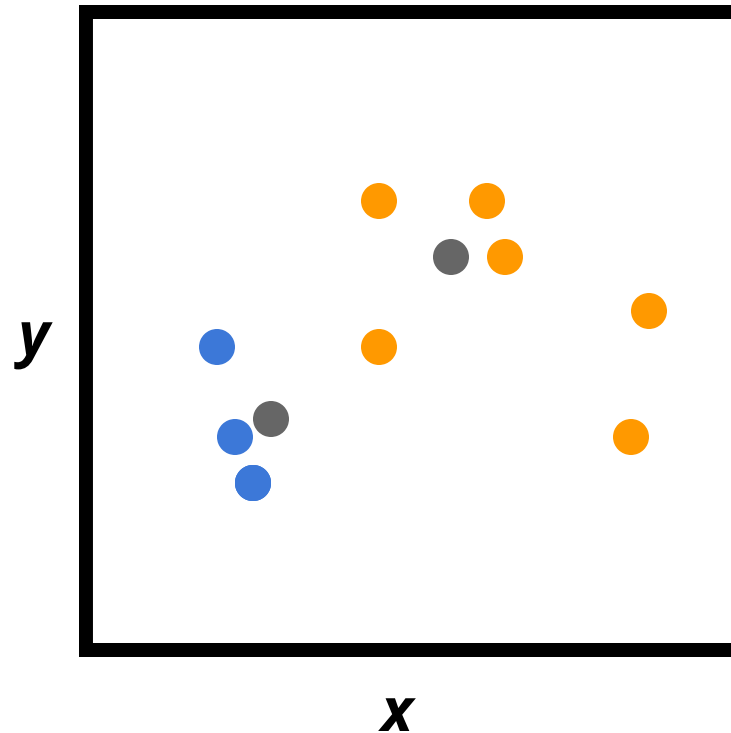
## *unsupervised*      *supervised*

goal is to partition the space so that the **unobserved** variables are

separated in groups

1 consistently with  
an observed subset

observed **features:**  
 $(\vec{x}, \vec{y})$



target **features:**  
 $(\overrightarrow{color})$

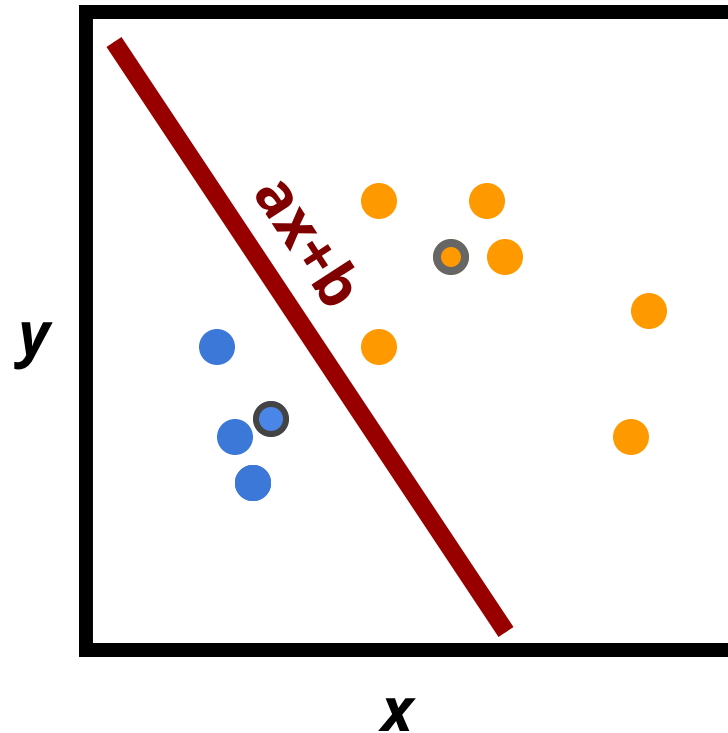
models typically return a partition of the space



# clustering vs classifying

*unsupervised*      *supervised*

observed **features:**  
 $(\vec{x}, \vec{y})$



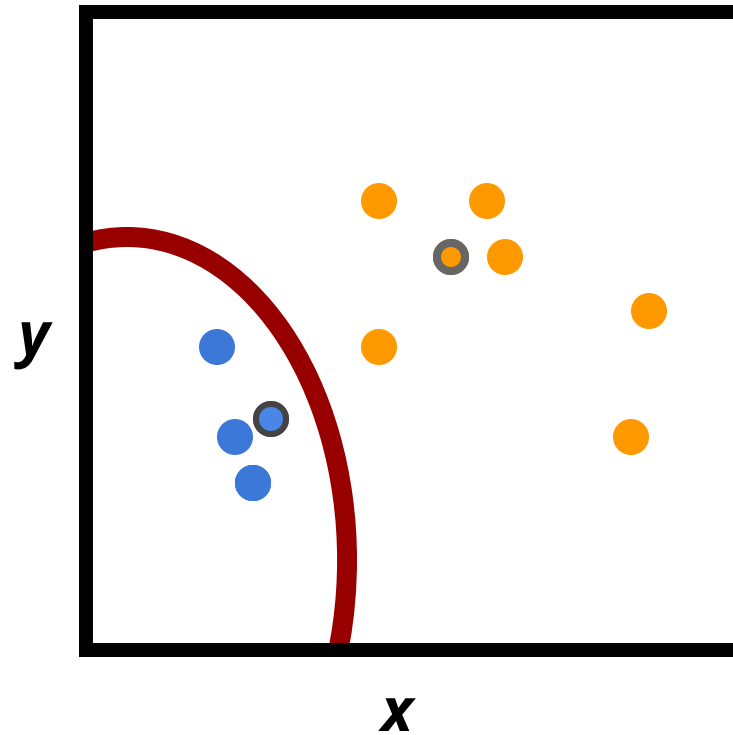
target **features:**  
 $\overrightarrow{(color)}$

```
if y >= a*x + b :  
    return blue  
else:  
    return orange
```

# clustering vs classifying

*unsupervised*      *supervised*

observed **features:**  
 $(\vec{x}, \vec{y})$



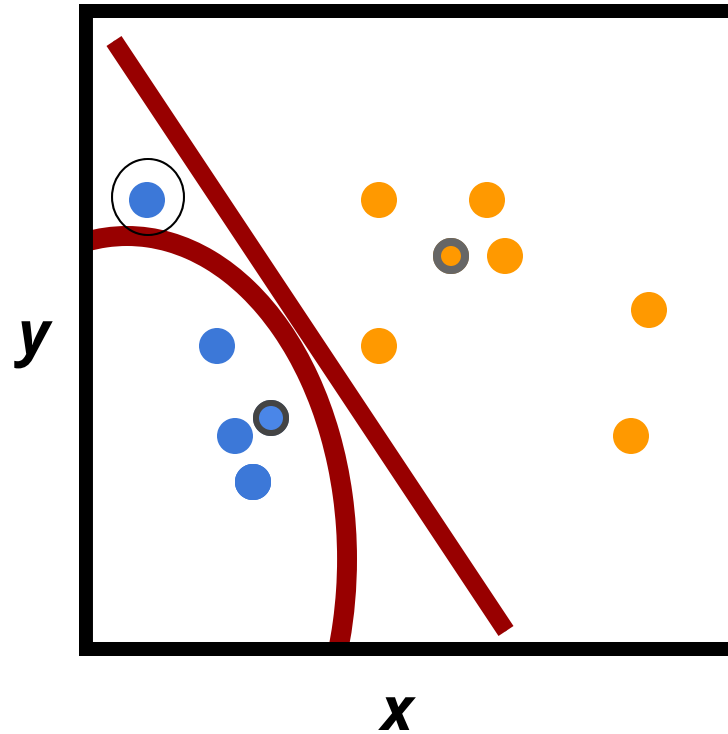
target **features:**  
*(color)*

```
if x**2 + y**2 >= (x-a)**2 + (y-b)**2 :  
    return blue  
else:  
    return orange
```

# clustering vs classifying

## *unsupervised*      *supervised*

observed **features:**  
 $(\vec{x}, \vec{y})$



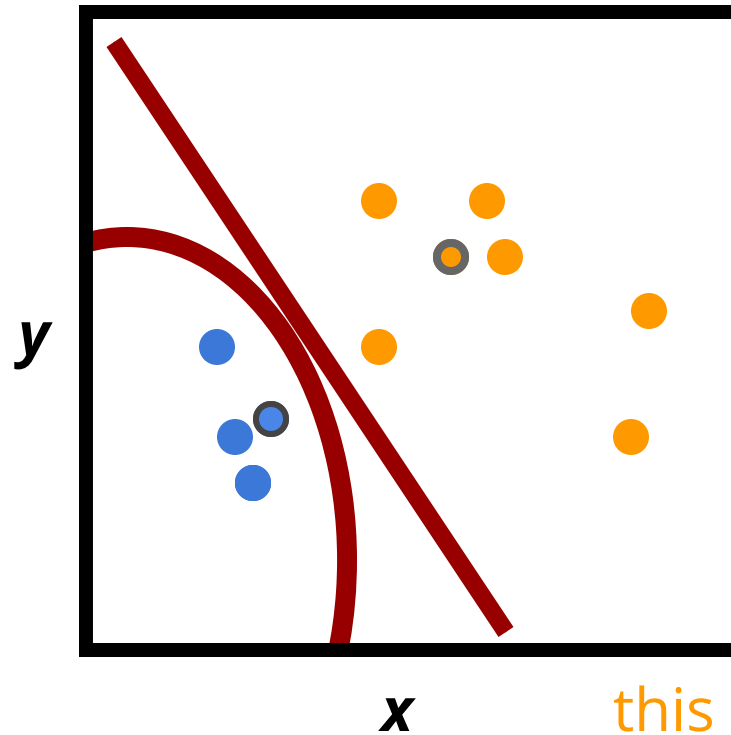
target **features:**  
 $\overrightarrow{(color)}$

```
if x**2 + y**2 >= (x-a)**2 + (y-b)**2 :  
    return blue  
else:  
    return orange
```

# clustering vs classifying

*unsupervised*      *supervised*

observed **features:**  
 $(\vec{x}, \vec{y})$



target **features:**  
 $(\overrightarrow{color})$

this is a solution SVM would provide:  
*Support Vector Machine*

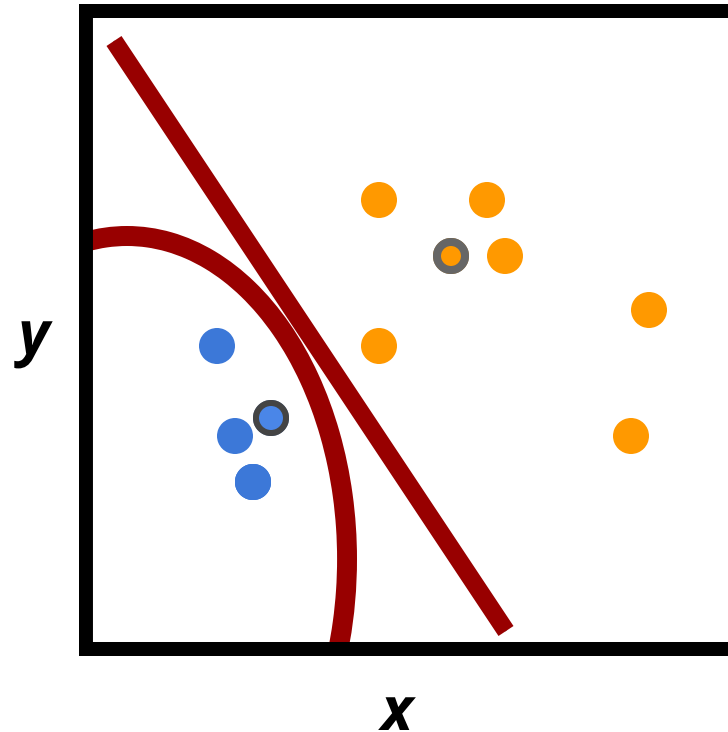
# supervised ML: classification

A subset of variables has class labels.  
Guess the label for the other variables

***Support Vector Machine:***

finds a hyperplane that partitions the space

observed **features:**  
 $(\vec{x}, \vec{y})$



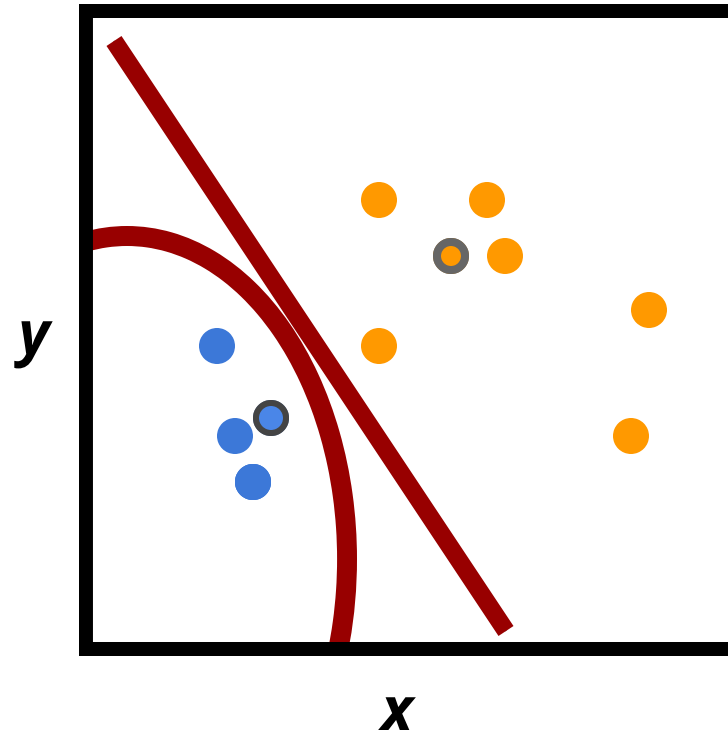
target **features:**  
 $\overrightarrow{(color)}$

# supervised ML: classification

A subset of variables has class labels.  
Guess the label for the other variables

## *Support Vector Machine:*

finds a hyperplane that partitions the space



2d hyperplane: line (curve)

3d hyperplane: surface

4d hyperplane: volume

... target **features:**  
 $(\overrightarrow{color})$

observed **features:**  
 $(\overrightarrow{x}, \overrightarrow{y})$

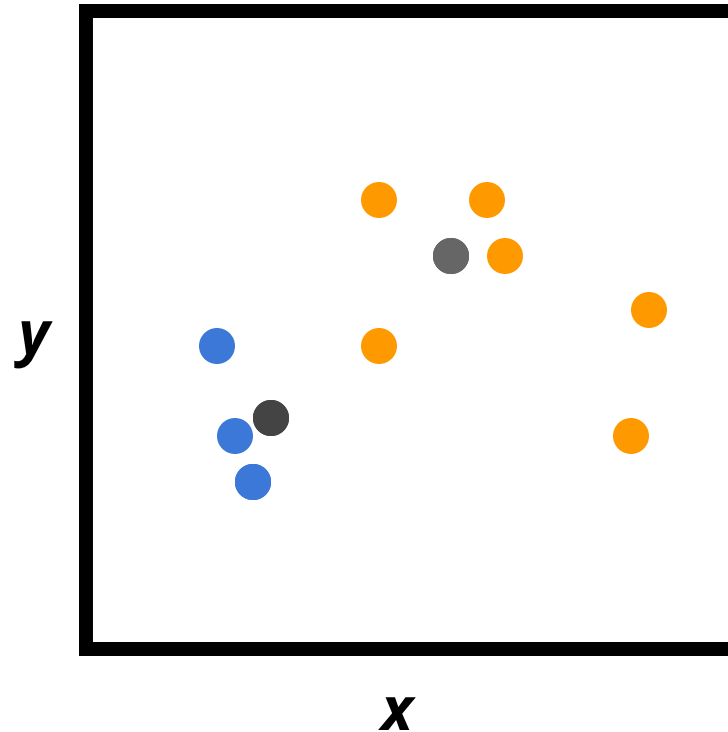
# supervised ML: classification

A subset of variables has class labels.  
Guess the label for the other variables

## *Tree Methods*

split spaces along each axis separately

observed **features:**  
 $(\vec{x}, \vec{y})$



target **features:**  
 $(\overrightarrow{color})$

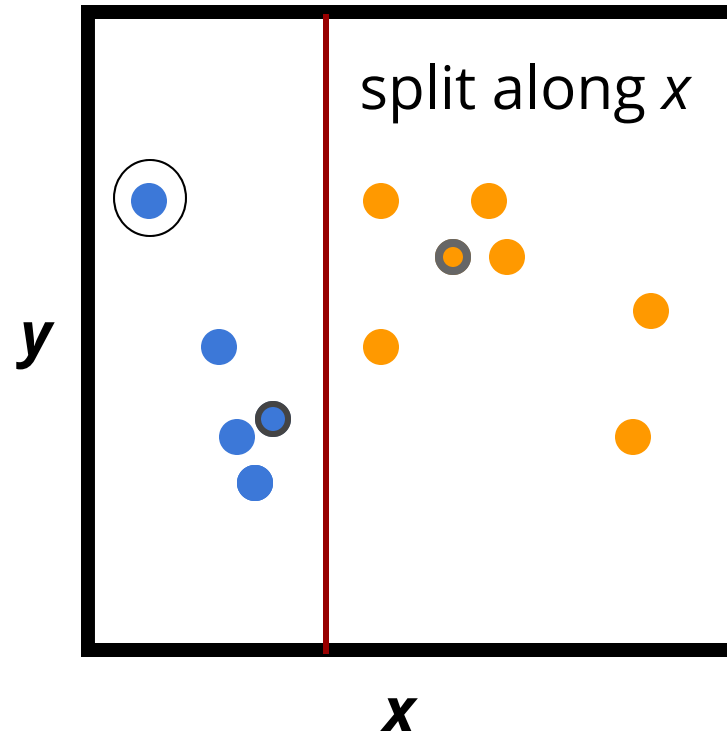
# supervised ML: classification

A subset of variables has class labels.  
Guess the label for the other variables

## *Tree Methods*

split spaces along each axis separately

observed **features:**  
 $(\vec{x}, \vec{y})$



target **features:**  
 $(\overrightarrow{color})$

```
if x <= a :  
    return blue  
else:  
    return orange
```



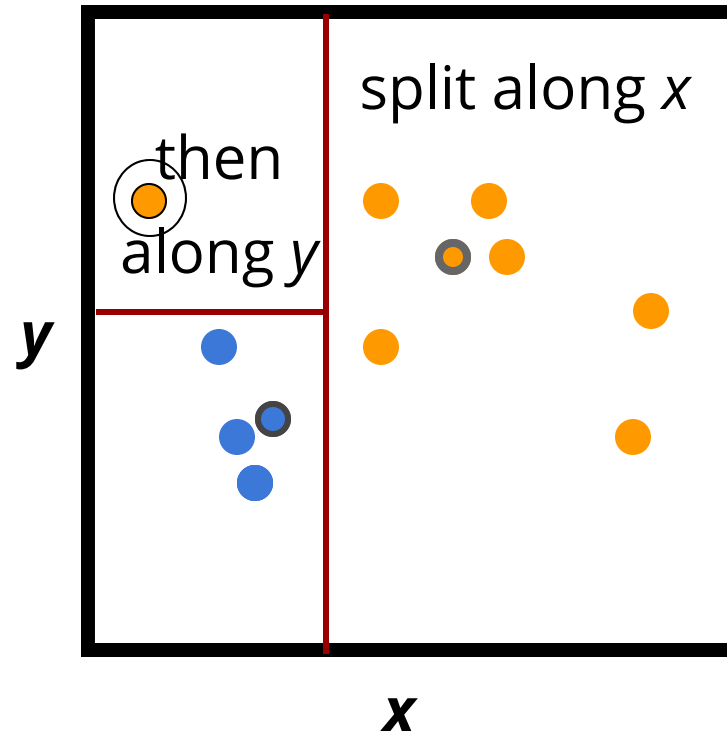
# supervised ML: classification

A subset of variables has class labels.  
Guess the label for the other variables

## *Tree Methods*

split spaces along each axis separately

observed **features:**  
 $(\vec{x}, \vec{y})$



target **features:**  
*(color)*

```
if x <= a :  
    if y <= b:  
        return blue  
return orange
```

# *Tree Methods*

## *supervised learning method*

partitions feature space along each feature separately

### **The good**

- Non-Parametric
- White-box: can be easily interpreted
- Works with any feature type and mixed feature types
- Works with missing data
- Robust to outliers

### **The bad**

- High variability (-> use ensemble methods)
- Tendency to overfit
- (not really easily interpretable after all...)

single tree

1

**Application:**  
**a robot to predict surviving the Titanic**

**(Kaggle)**

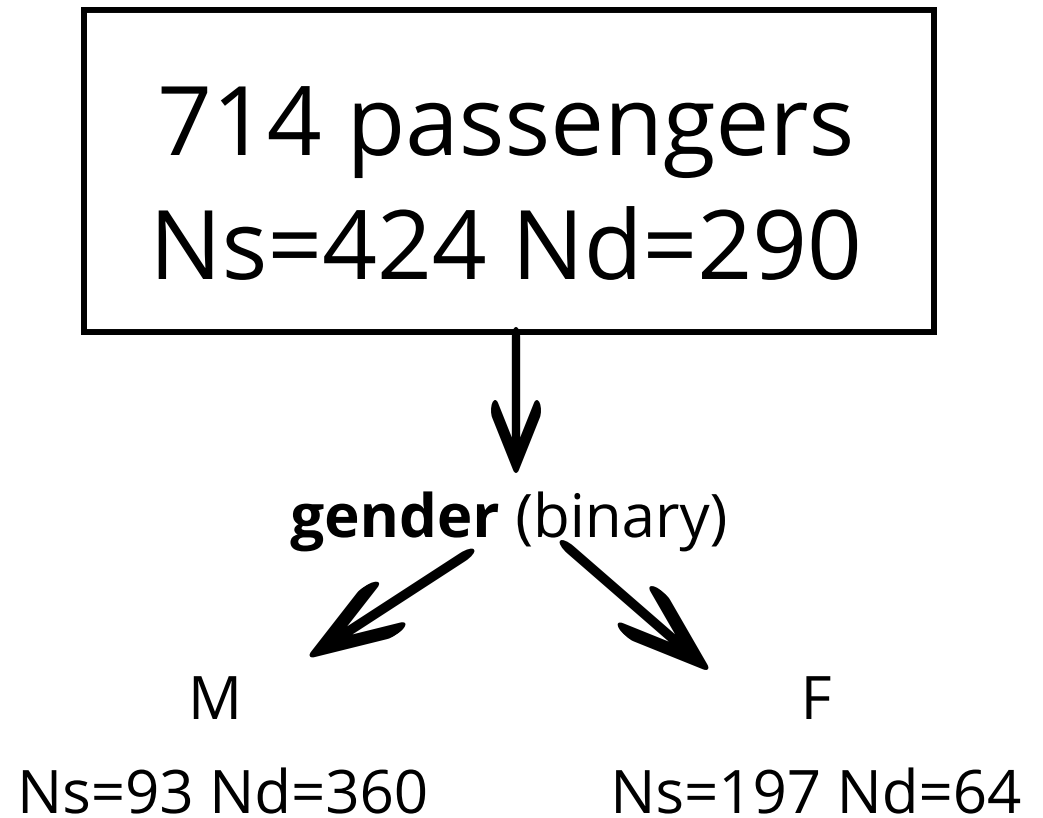
<https://www.kaggle.com/c/titanic>

**features:**

- gender
- ticket class
- age

**target variable:**

-> survival (y/n)



**Application:**  
a robot to predict surviving the  
Titanic

(Kaggle)

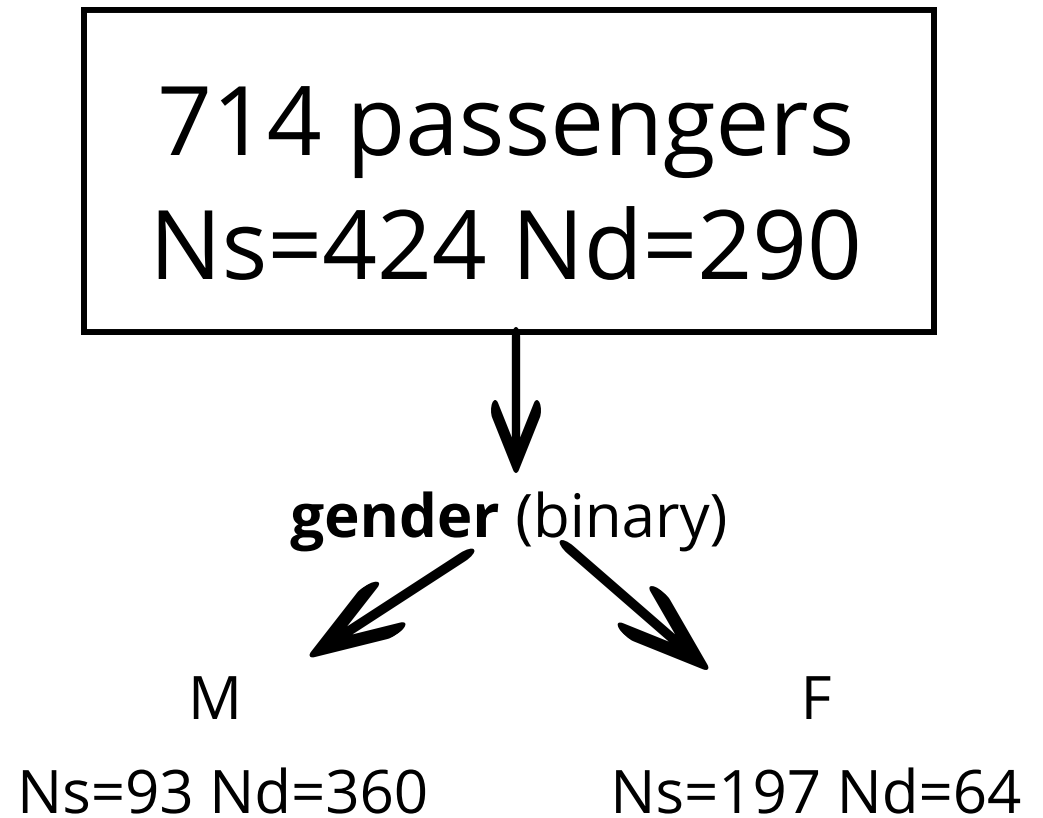
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optimize over purity:

$$p = \frac{N_{largest\ class}}{N_{total}}$$

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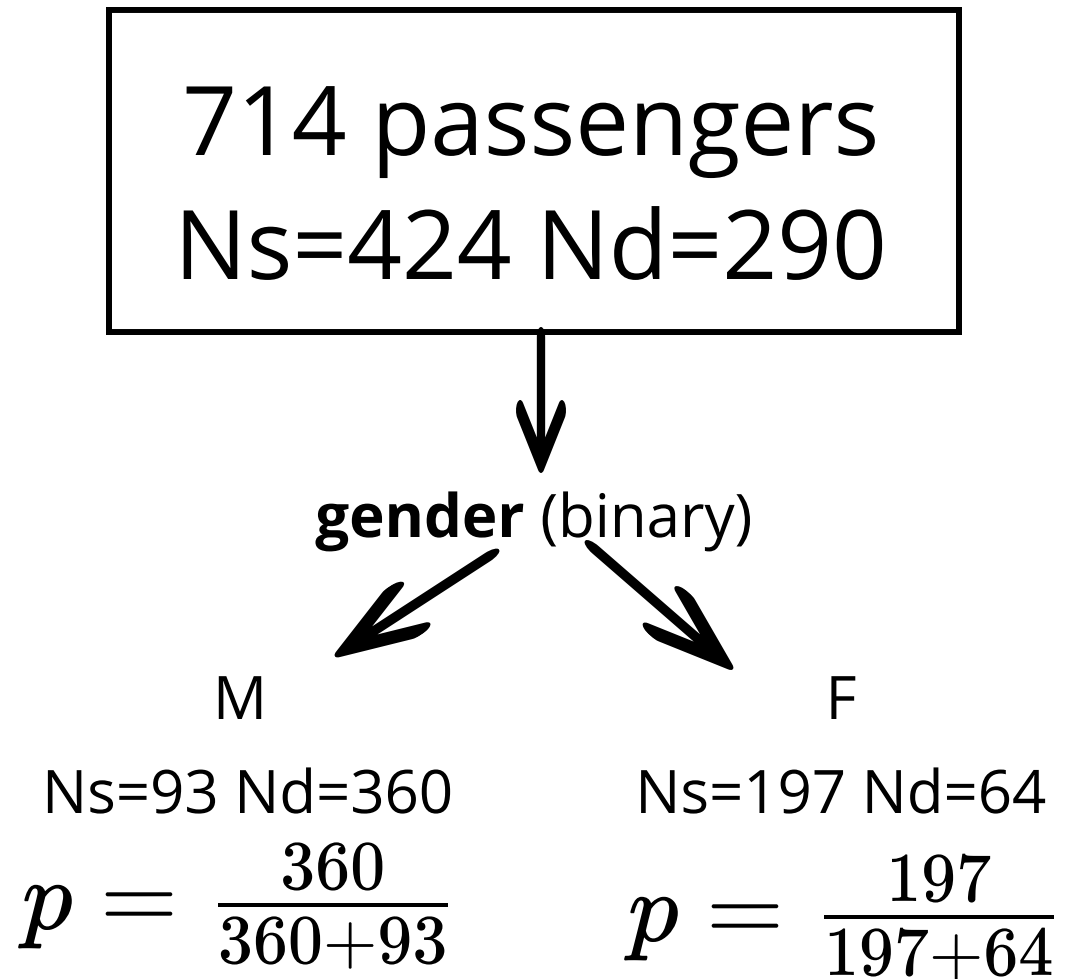
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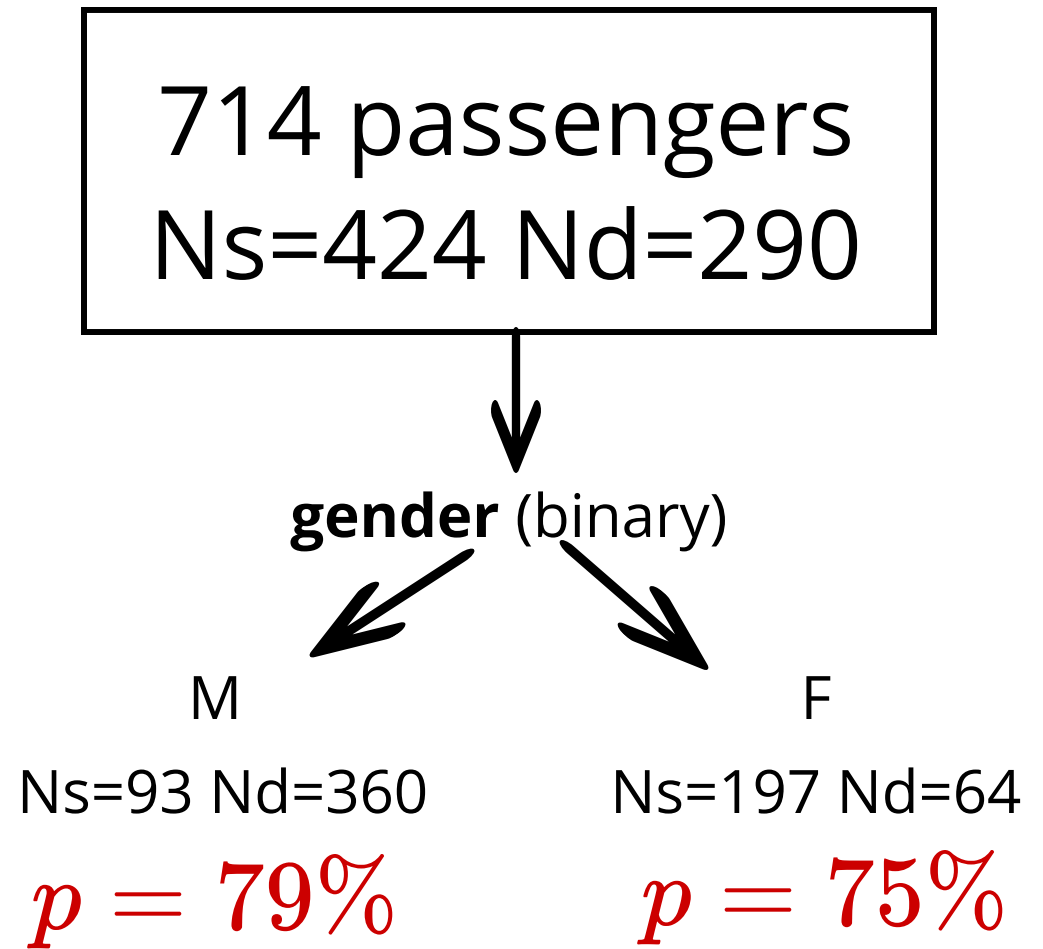
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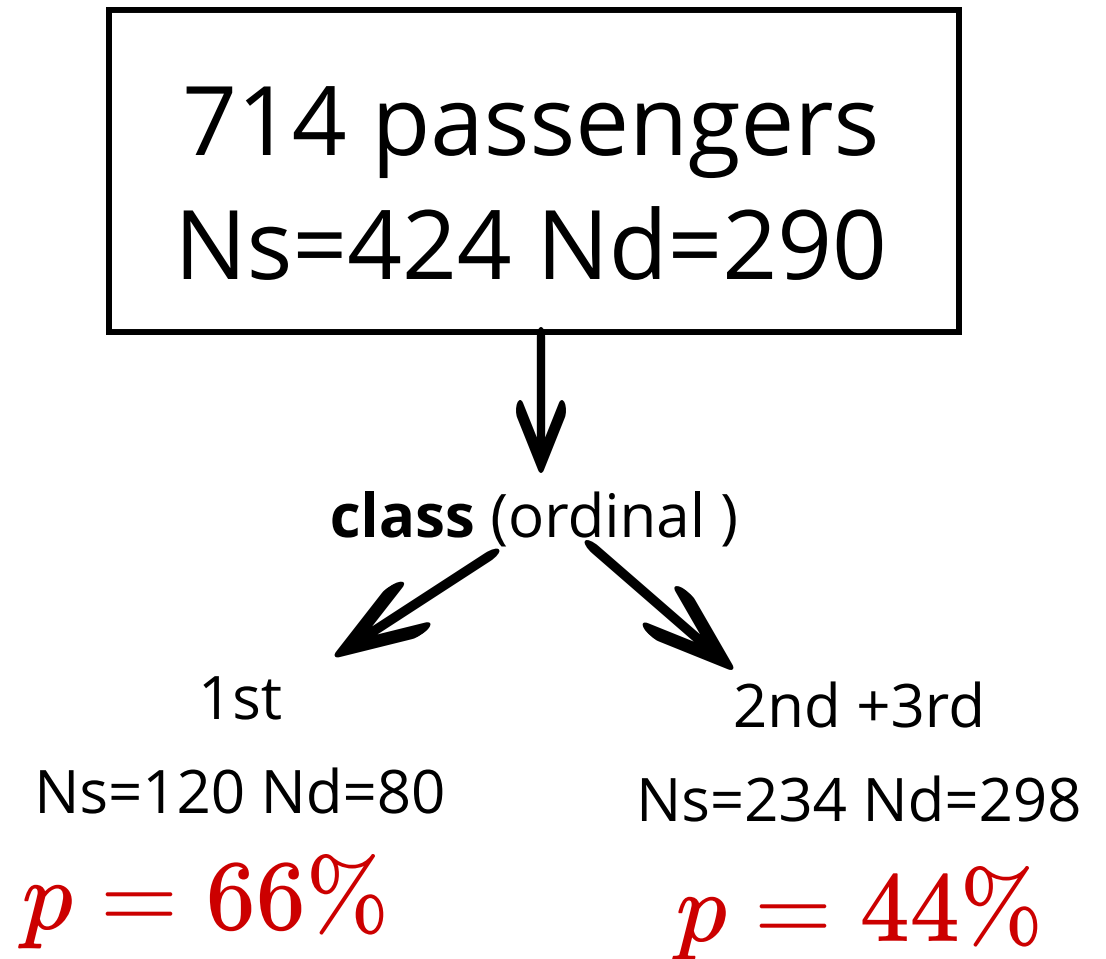
<https://www.kaggle.com/c/titanic>

**features:**

- gender 79% | 75%
- ticket class 66 | 54%
- age

**target variable:**

-> survival (y/n)





**Application:**  
**a robot to predict surviving the Titanic**

**(Kaggle)**

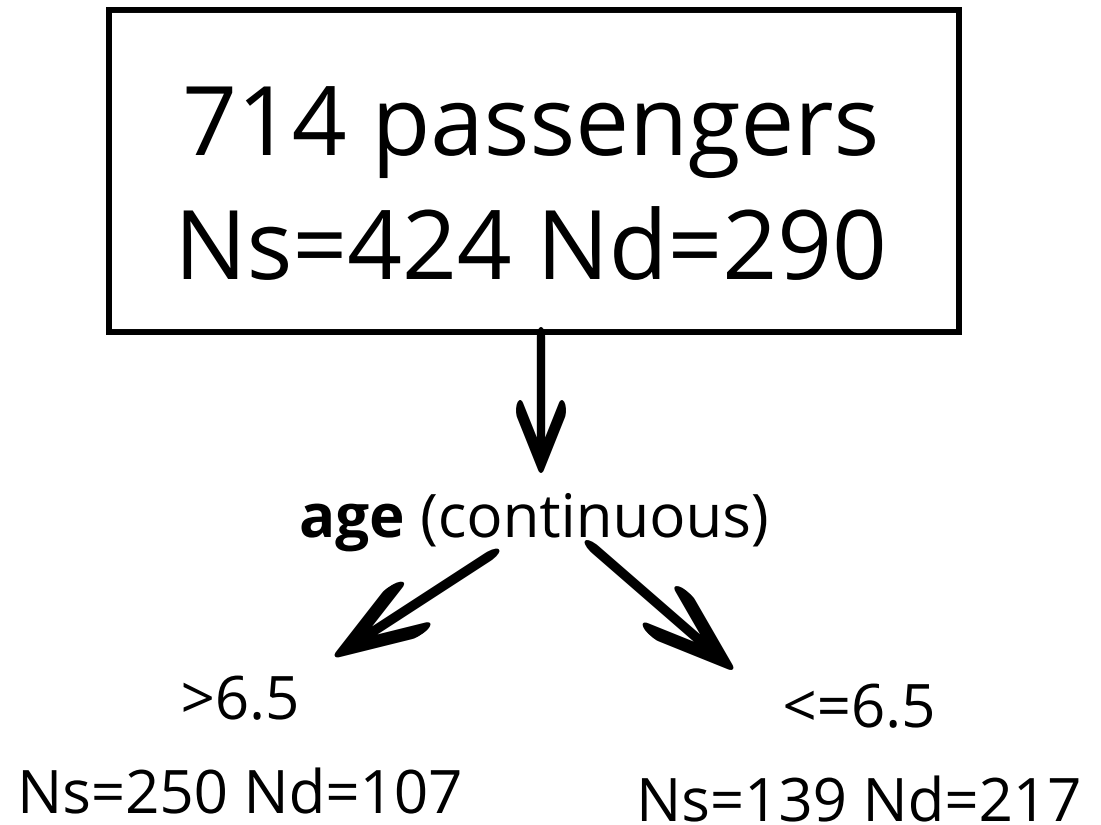
<https://www.kaggle.com/c/titanic>

**features:**

- gender 79% | 75%
- ticket class 66% | 44%
- age 66% | 61%

**target variable:**

-> survival (y/n)



**Application:**  
**a robot to predict surviving the Titanic**

**(Kaggle)**

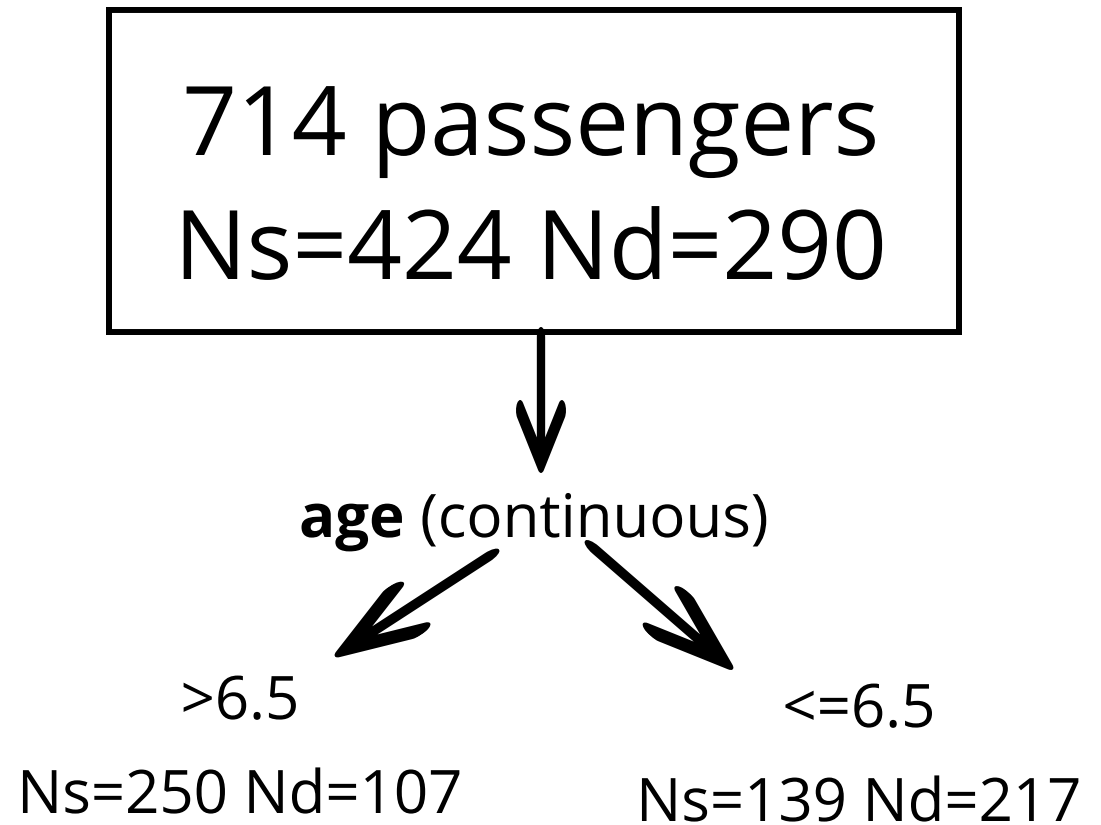
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**features:**

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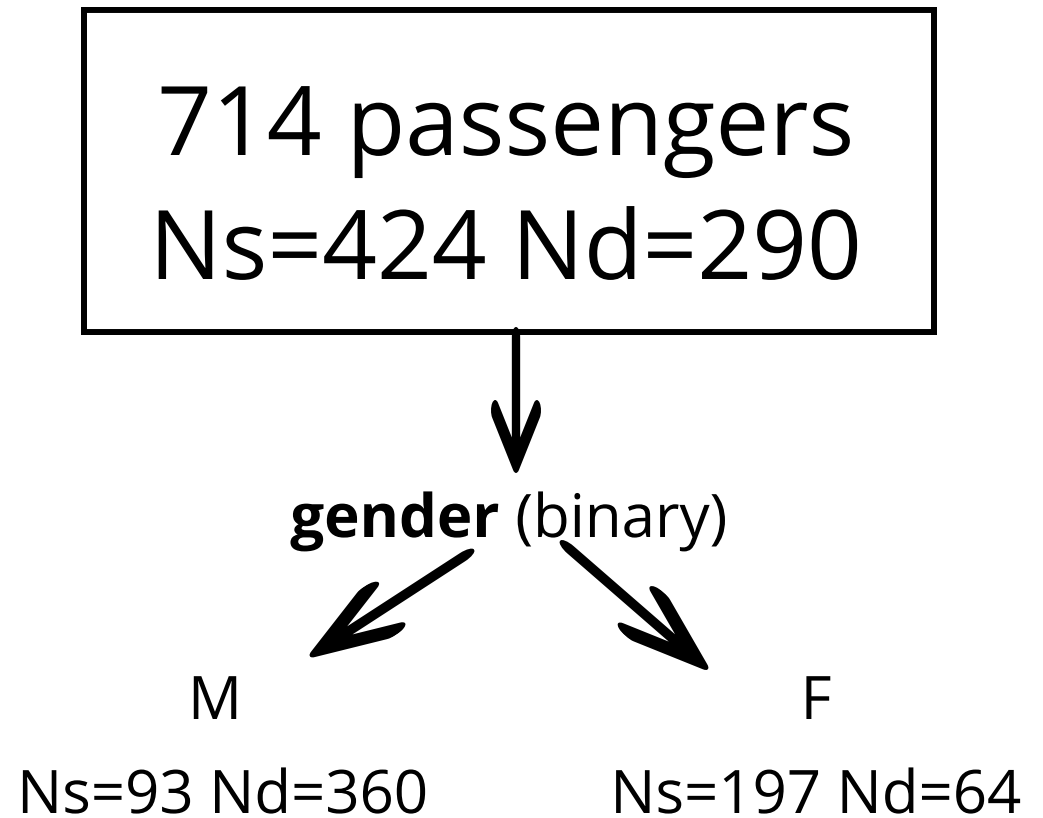
<https://www.kaggle.com/c/titanic>

**features:**

- gender 79 | 75%
- ticket class *M* 60 | 85% *F* 96 | 65%
- age *M* 74 | 67% *F* 66 | 60%

**target variable:**

-> survival (y/n)



**Application:**  
**a robot to predict surviving the  
Titanic**

**(Kaggle)**

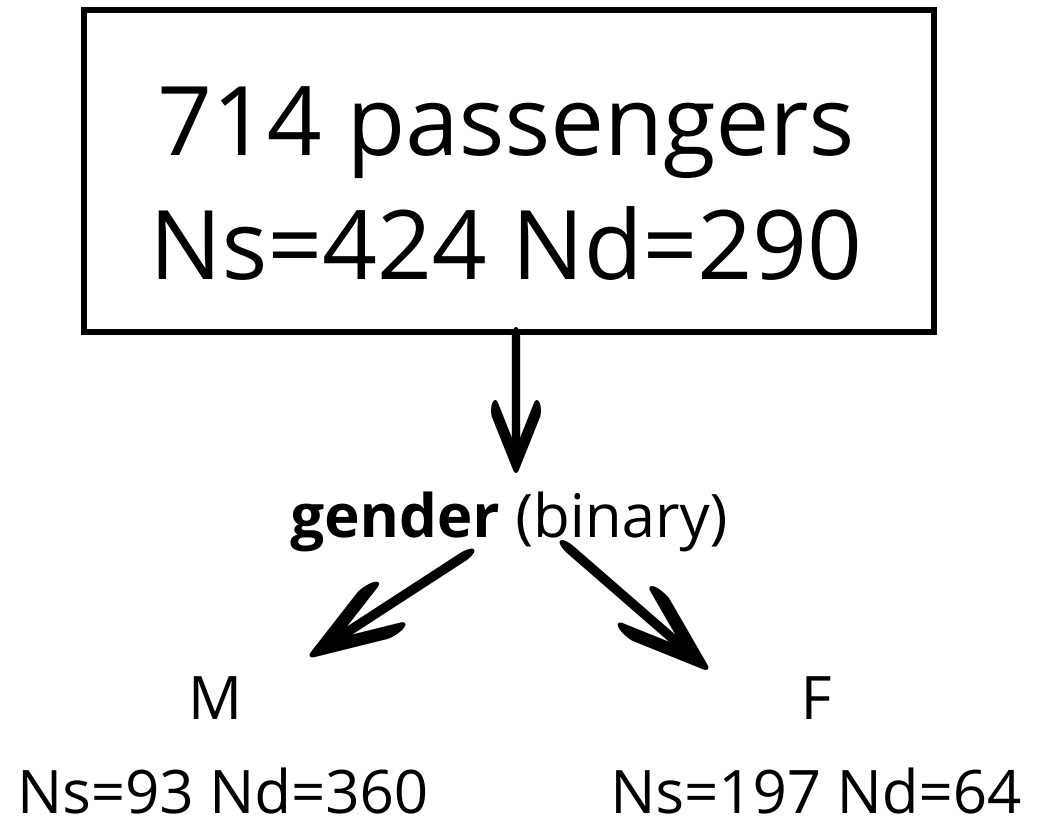
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**features:**

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**target variable:**

-> survival (y/n)



**Application:**  
a robot to predict surviving the  
Titanic

(Kaggle)

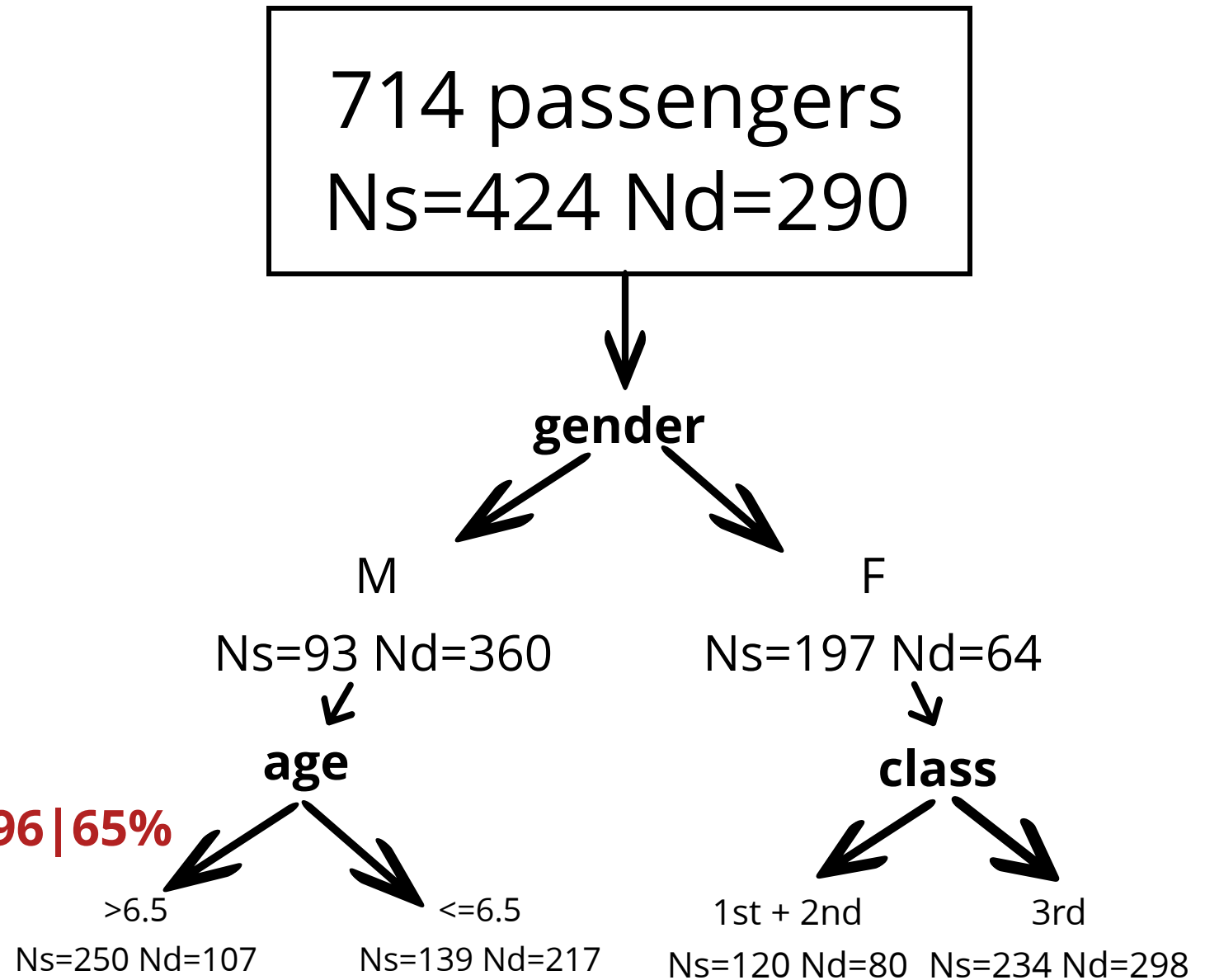
<https://www.kaggle.com/c/titanic>

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- ticket class *M* 60 | 85% *F* 96 | 65%
- age *M* 74 | 67% *F* 66 | 60%

**target variable:**

-> survival (y/n)

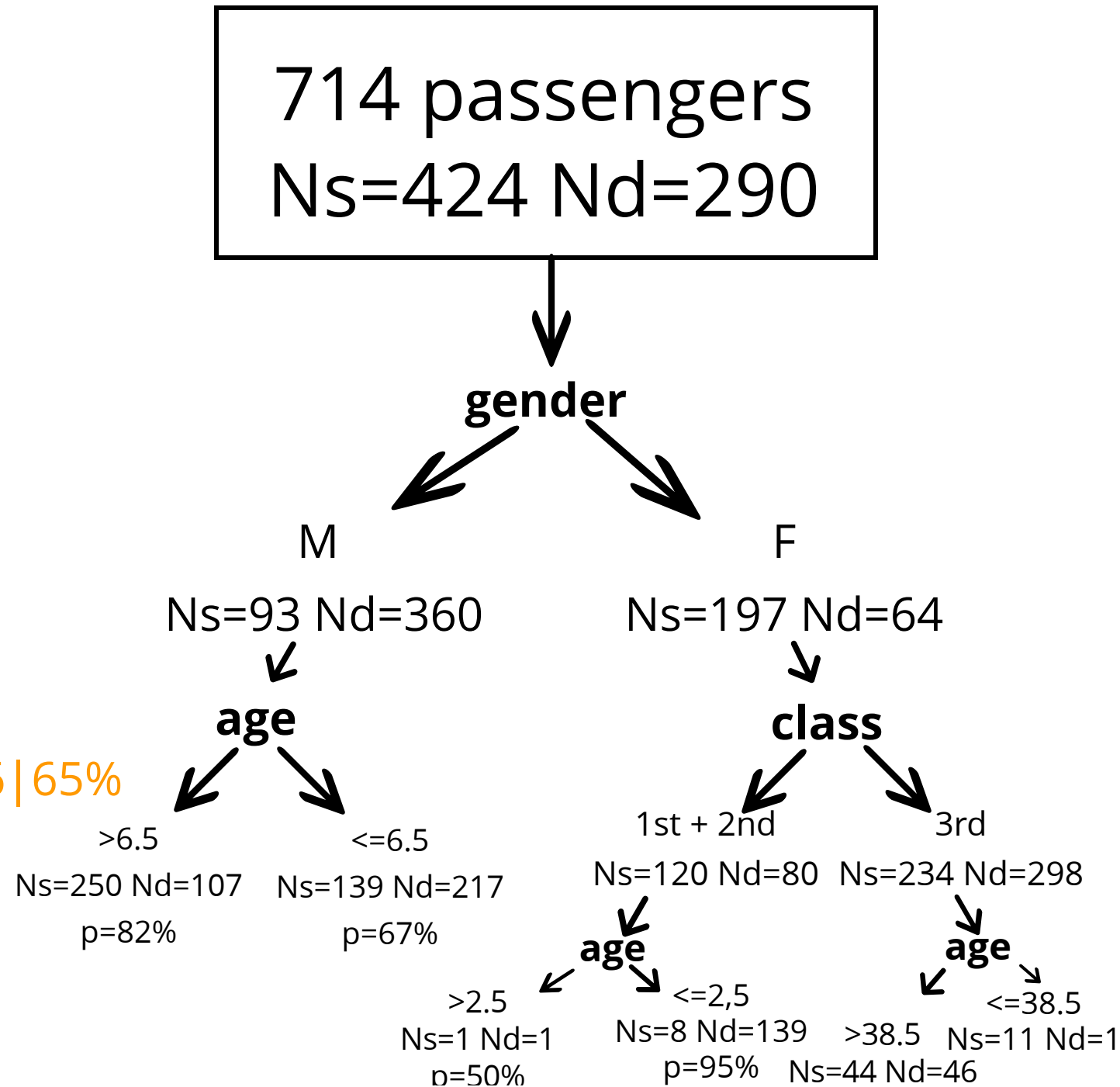


(Kaggle)

## features:

- ## target variable:

-> survival (y/n)



**Application:**  
a robot to predict surviving the  
Titanic

(Kaggle)

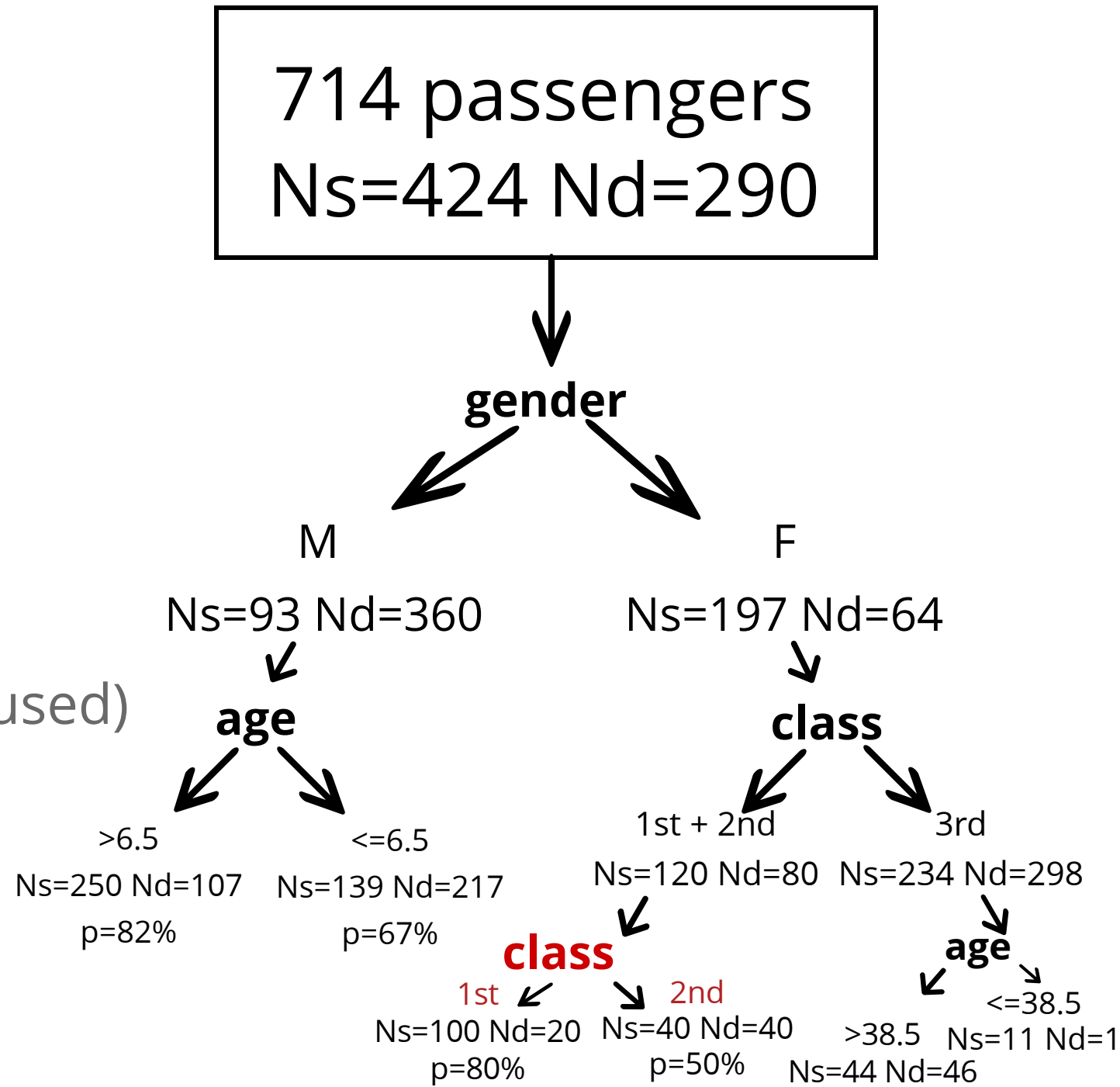
<https://www.kaggle.com/c/titanic>

**features:**

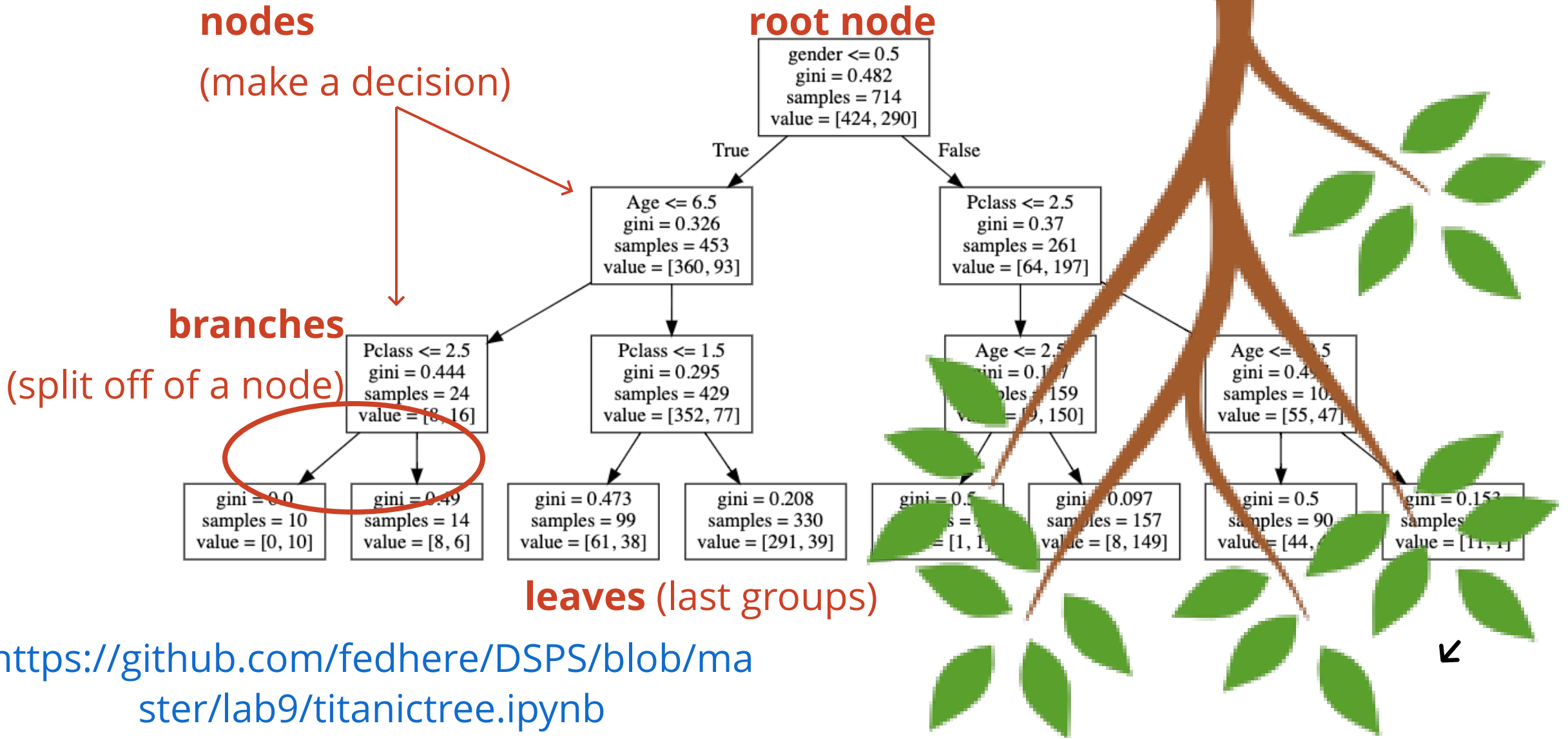
- gender (binary already used)
- ticket class (*ordinal*)
- age (contunuous)

**target variable:**

-> survival (y/n)



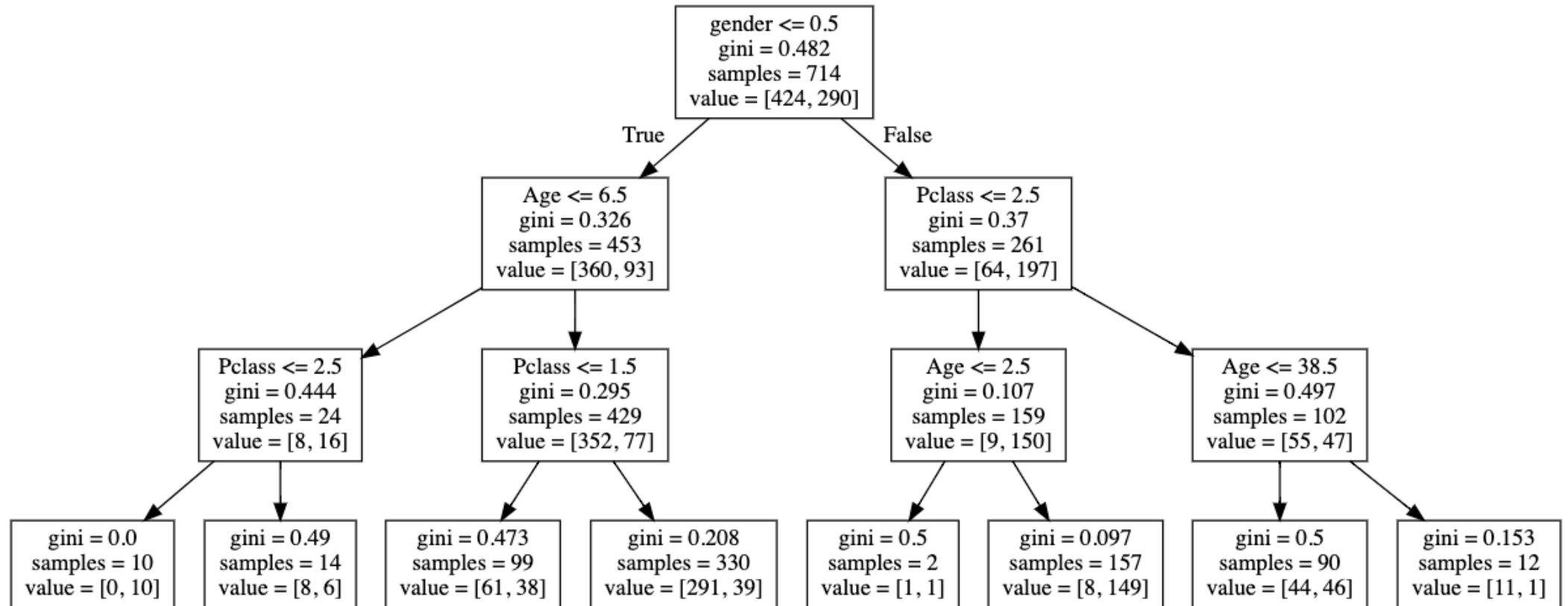
# A single tree





## A single tree

this visualization is called a "dendrogram"



# tree hyperparameters 2

# tree hyperparameters

`sklearn.tree`.**DecisionTreeClassifier** ¶

```
class sklearn.tree. DecisionTreeClassifier (criterion='gini', splitter='best',  
max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0,  
max_features=None, random_state=None, max_leaf_nodes=None,  
min_impurity_decrease=0.0, min_impurity_split=None, class_weight=None, presort=False)
```

[\[source\]](#)

# A single tree: hyperparameters

---

**criterion** : *string, optional (default="gini")*

The function to measure the quality of a split. Supported criteria are “gini” for the Gini impurity and “entropy” for the information gain.

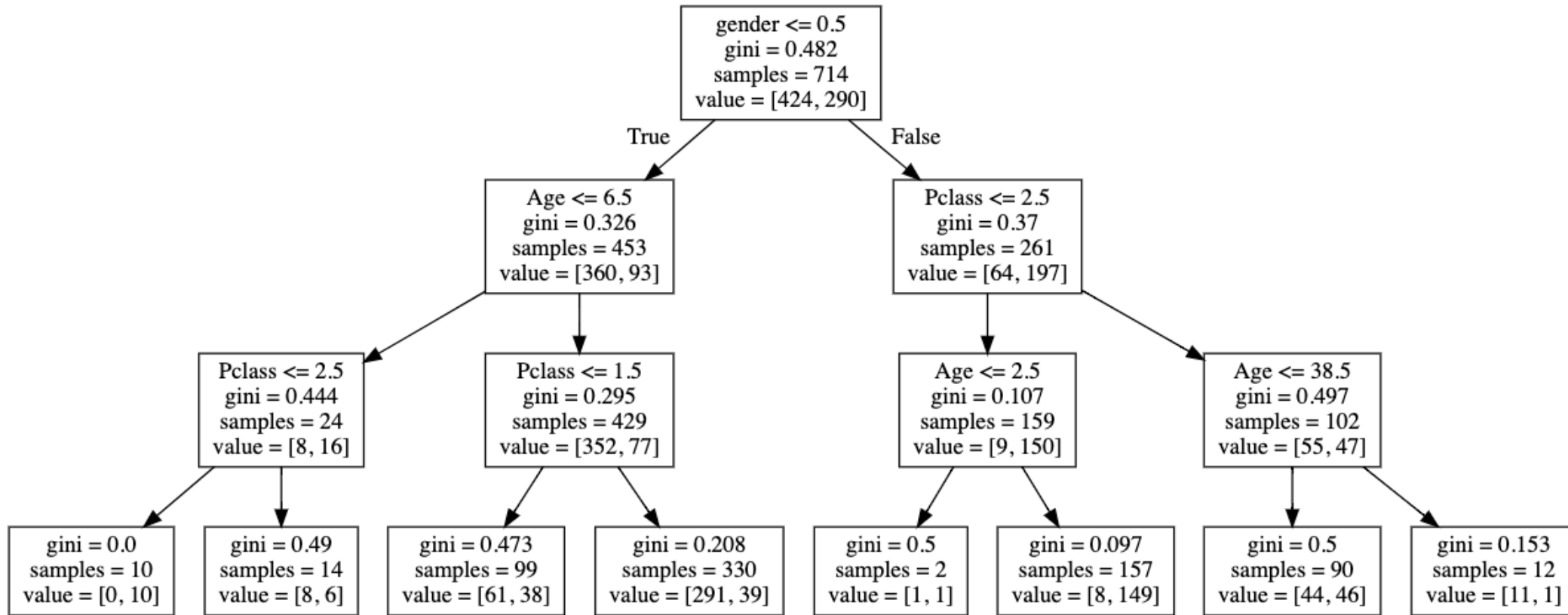
**gini impurity**

$$I_G(p) = 1 - \sum_{i=1}^J p_i^2$$

**information gain** (entropy)

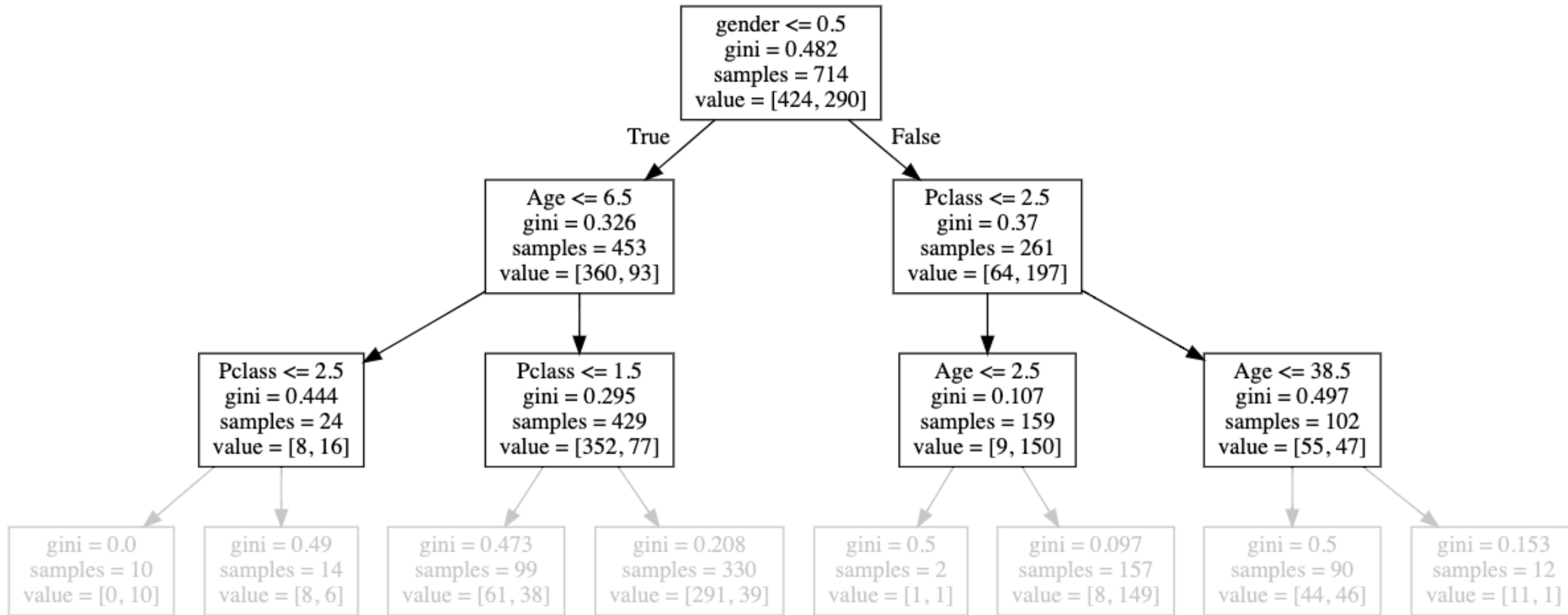
$$H(T) = - \sum_{i=1}^J p_i \log_2 p_i$$

# A single tree: hyperparameters



depth

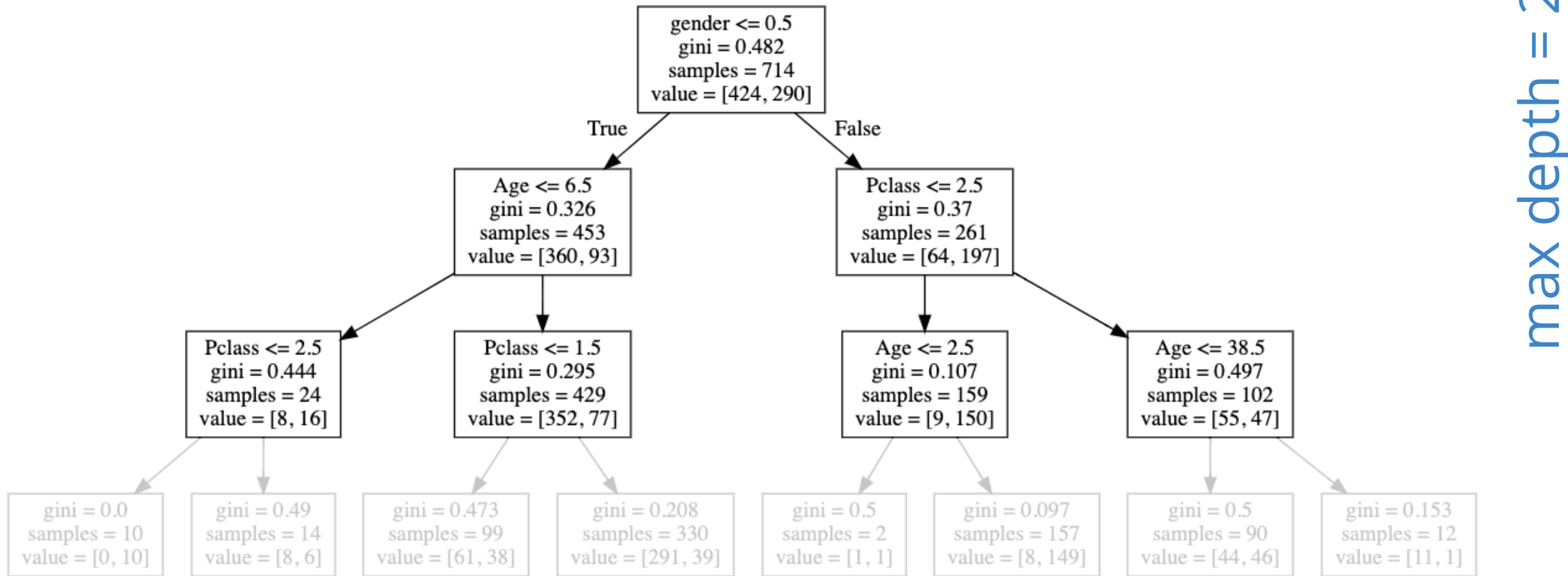
# A single tree: hyperparameters



max depth = 2

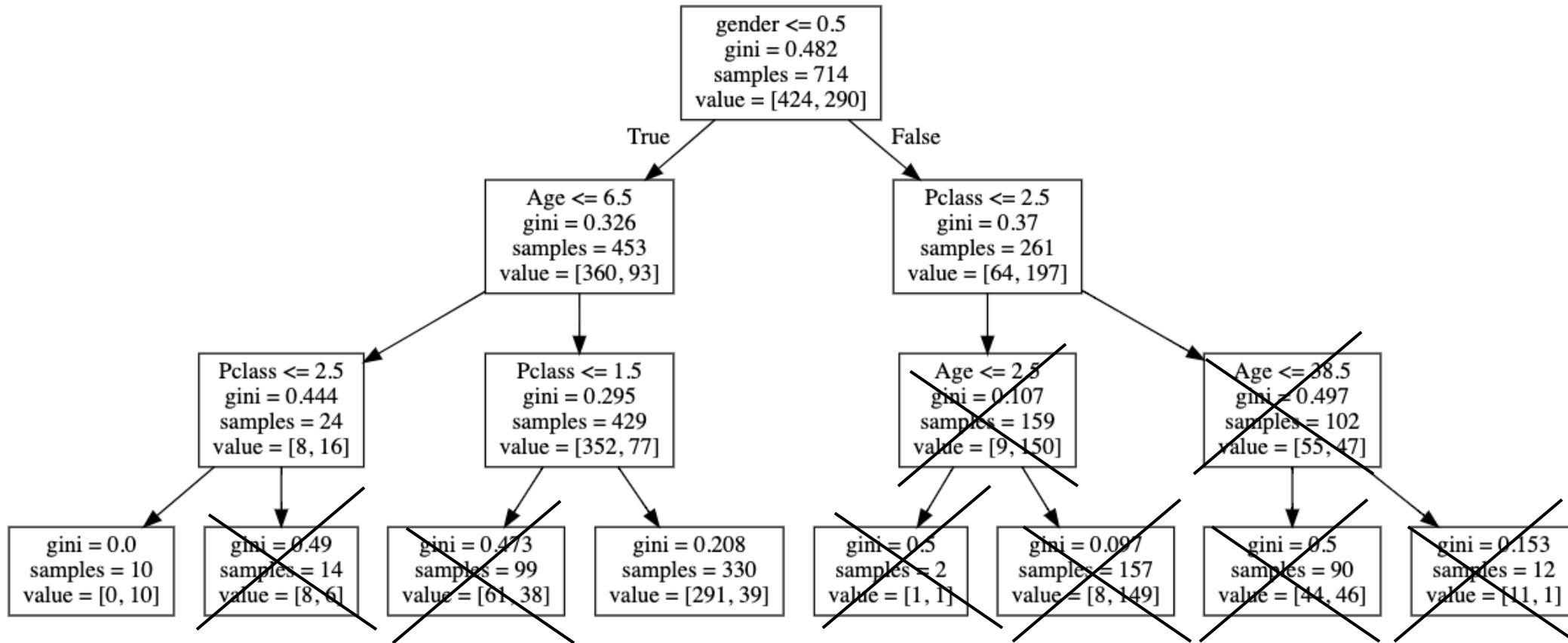


# A single tree: hyperparameters



**PREVENTS  
OVERFITTING**

# A single tree: hyperparameters



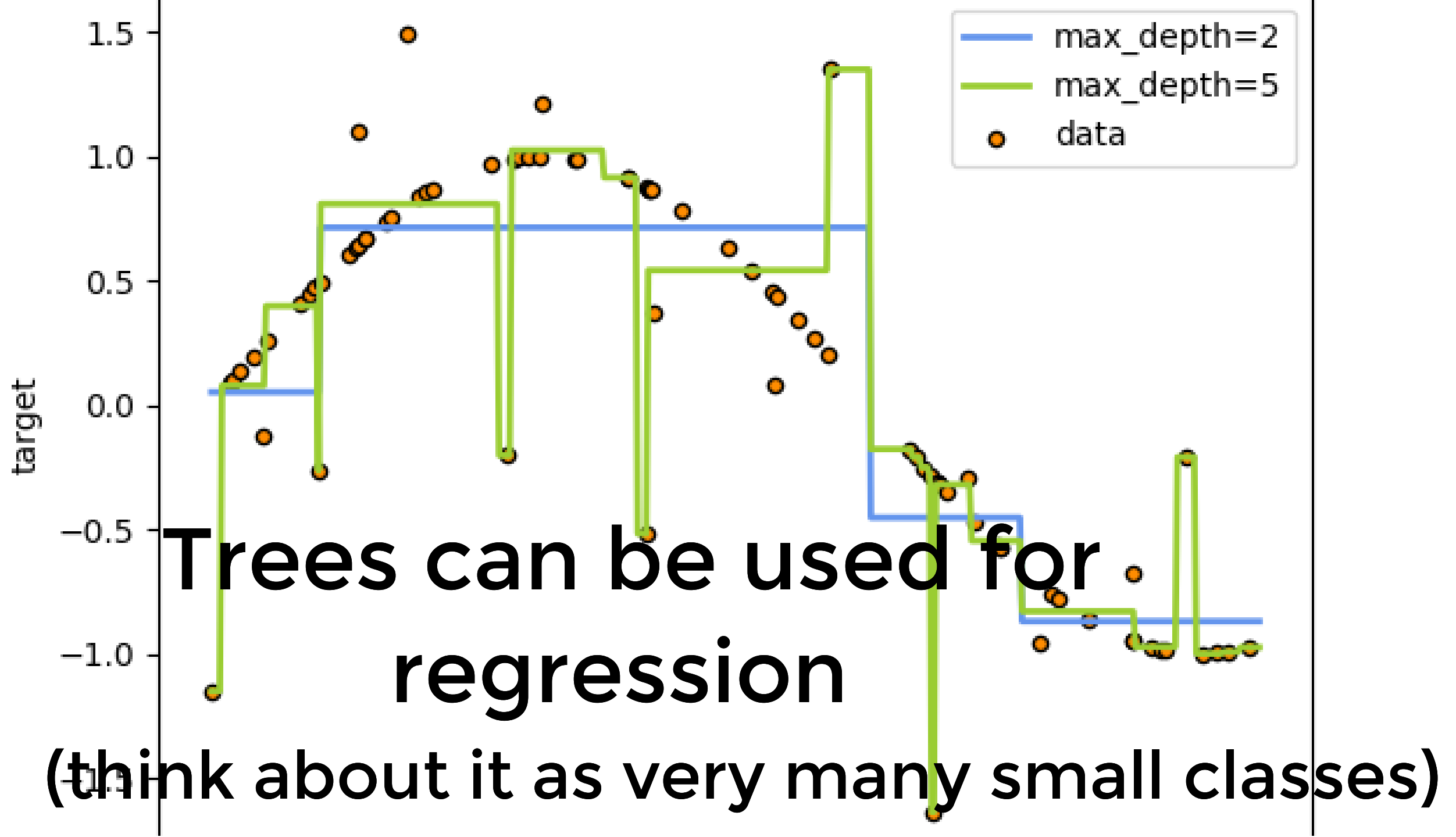
**alternative: tree pruning**



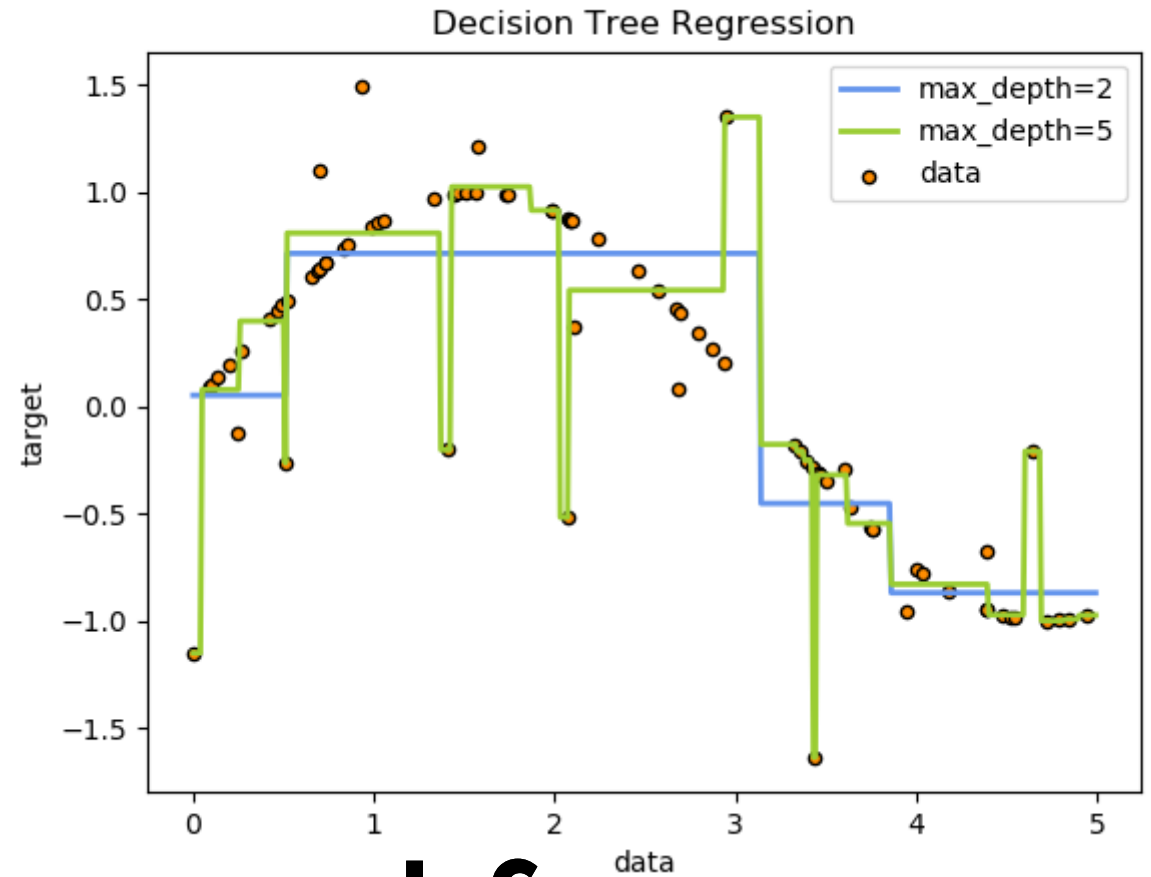
# regression with trees

# 3

CART: Classification and Regression Trees



[https://scikit-learn.org/stable/auto\\_examples/tree/plot\\_tree\\_regression.html](https://scikit-learn.org/stable/auto_examples/tree/plot_tree_regression.html)



# Trees can be used for regression

(think about it as very many small classes)

# `sklearn.tree`.DecisionTreeRegressor

```
class sklearn.tree. DecisionTreeRegressor (criterion='mse', splitter='best',  
max_depth=None, min_samples_split=2, min_samples_leaf=1, min_weight_fraction_leaf=0.0,  
max_features=None, random_state=None, max_leaf_nodes=None,  
min_impurity_decrease=0.0, min_impurity_split=None, presort=False) ¶
```

[\[source\]](#)

# A single tree: hyperparameters

**criterion** : *string, optional (default="mse")*

The function to measure the quality of a split. Supported criteria are “mse” for the mean squared error, which is equal to variance reduction as feature selection criterion and minimizes the L2 loss using the mean of each terminal node, “friedman\_mse”, which uses mean squared error with Friedman’s improvement score for potential splits, and “mae” for the mean absolute error, which minimizes the L1 loss using the median of each terminal node.

**mean square error**

$$L_2 = (y_{true} - y_{predicted})^2$$

**mean absolute error**

$$L_1 = |y_{true} - y_{predicted}|$$

issues with trees

4

# issues with trees

***variance:***

***different trees lead to different results***

# issues with trees

***variance:***

***different trees lead to different results***

**why?**

**because calculating the criterion for every split and every  
node is an untractable problem!**

e.g. 2 continuous variables would be a problem of order  $\infty^2$



# issues with trees

***variance:***

***different trees lead to different results***

**solution**

**run many trees and take an "ensemble" decision!**

**Random Forests**

**a bunch of parallel trees**

**Gradient Boosted Trees**

**a series of trees**

ensemble  
methods

5

# ensemble methods

run multiple versions of the same model with some small (stochastic or progressive) variation and learn from the ensemble of methods

# tree ensemble methods

## Random forest:

trees run in parallel  
(independently of each other)

each tree uses a random subset  
of observations/features  
(bootstrap - bagging)

class predicted by majority vote:  
what class do most trees<sup>1</sup> think a  
point belong to

## Gradient boosted trees:

trees run in series (one after  
the other)

each tree uses different  
*weights* for the features  
learning the weights from the  
previous tree

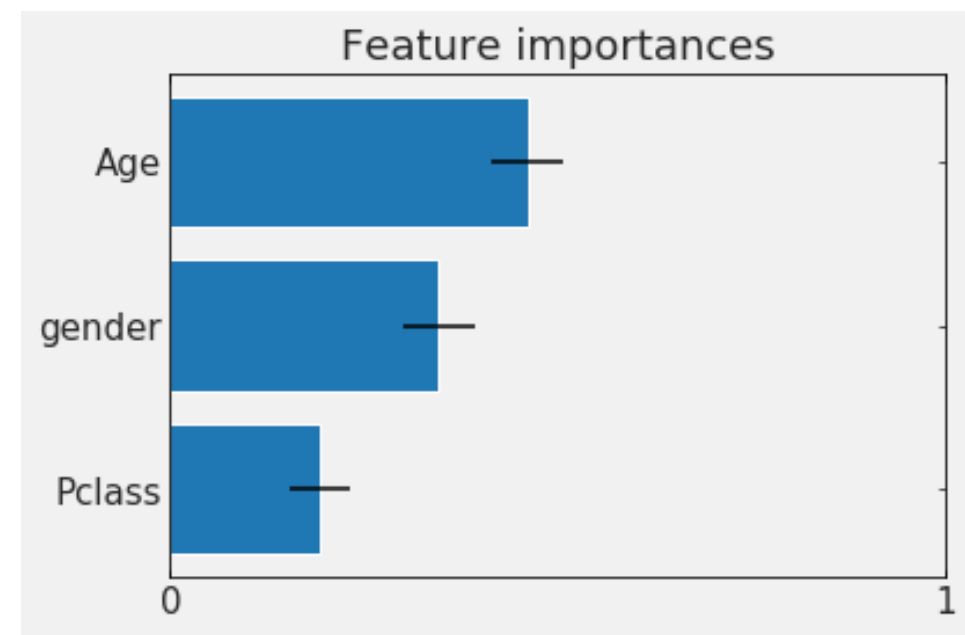
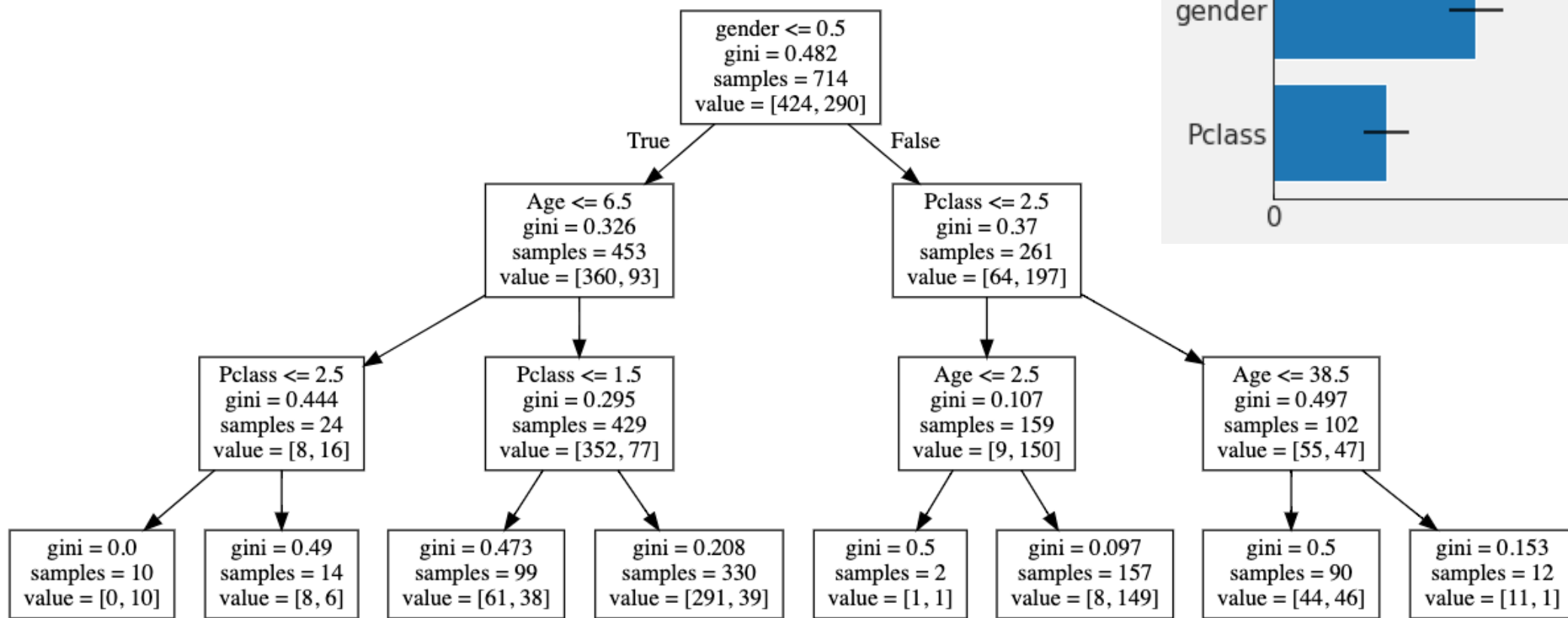
the last tree has the prediction

feature  
importance

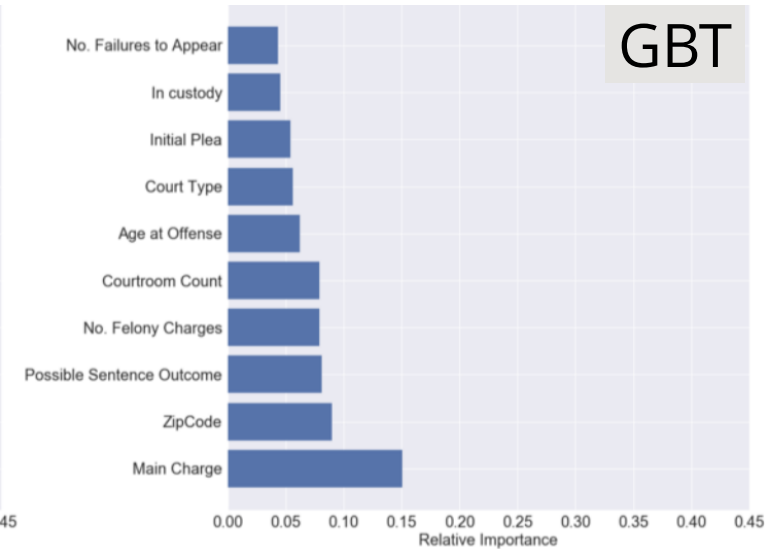
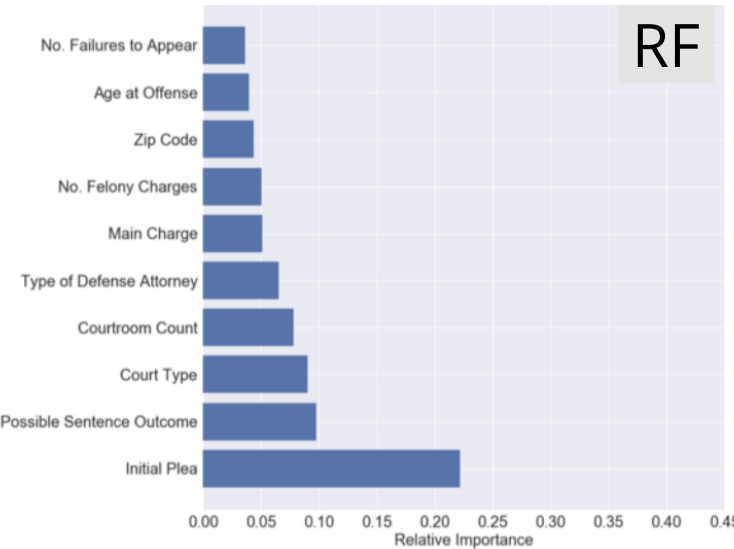
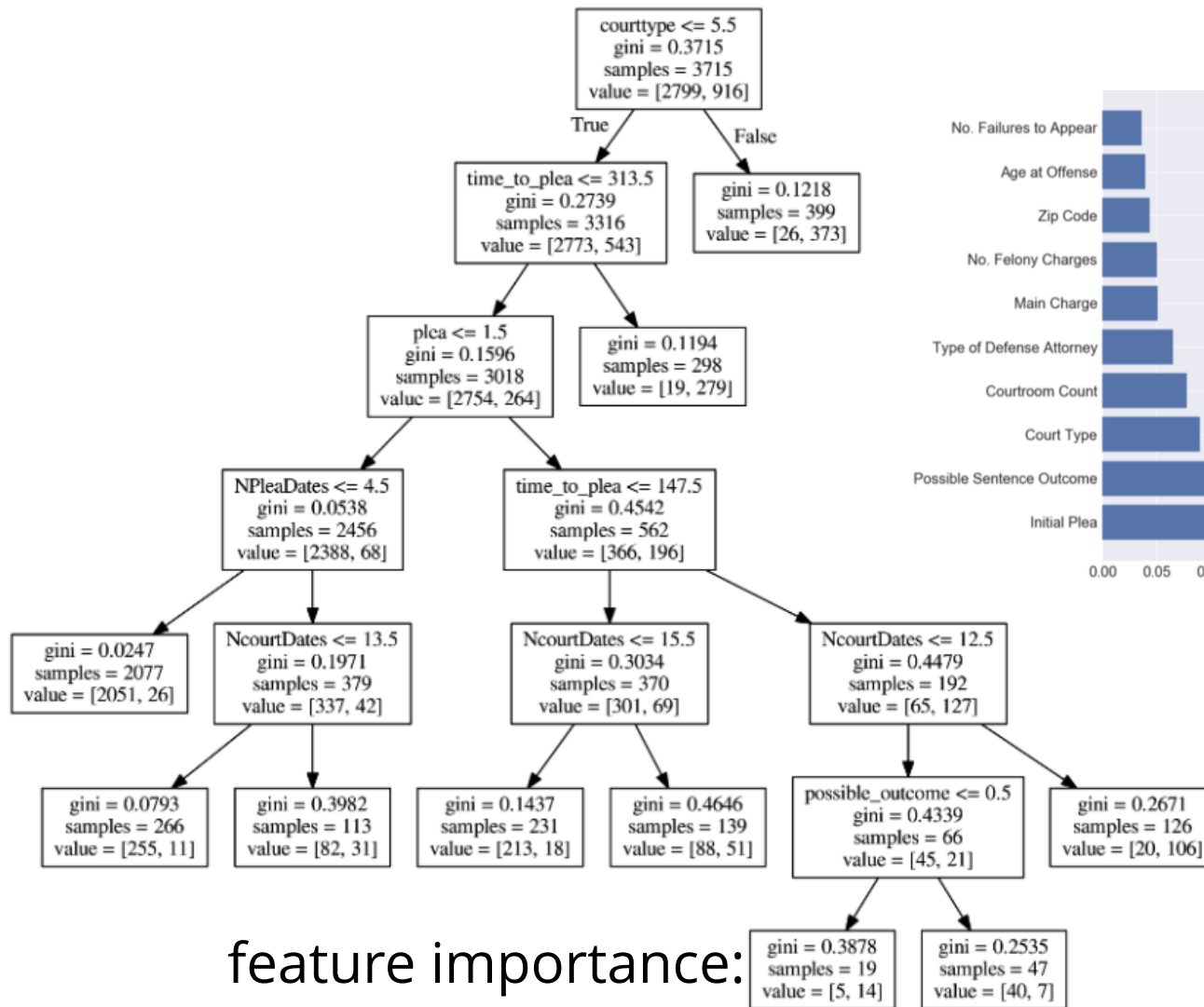
6

# feature importance

In principle CART methods are interpretable  
you can measure the influence that each  
feature has on the decision : feature importance



<https://github.com/fedhere/DSPS/blob/master/lab9/titanictree.ipynb>



feature importance:

how soon was a feature chosen,

how many times was it used...

<https://explained.ai/rf-importance/>

## A Data-Driven Evaluation of Delays in Criminal Prosecution

<https://doi.org/10.22541/au.155535549.97131926>



# feature importance

In principle CART methods are interpretable  
you can measure the influence that each  
feature has on the decision : feature importance

**In practice the interpretation is complicated  
by covariance of features**

# tree ensemble methods

## Random forest:

trees run in parallel  
(independently of each other)

each tree uses a random subset  
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class predicted by majority vote:  
what class do most trees<sup>1</sup> think a  
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trees run in series (one after  
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each tree uses different  
*weights* for the features  
learning the weights from the  
previous tree

the last tree has the prediction

**Machine Learning** includes models that learn parameters from data

ML models have parameters learned from the data and **hyperparameters** assigned by the user.

**Unsupervised** learning:

- all variables observed for all data points
- learns the structure of the features space from the data
- predicts a label (group of belonging) based on similarity of all features

**Supervised** learning:

- a target feature is observed only for a subset of the data
- learns target feature for data where it is not observed based on similarity of the other features
- predicts a class/value for each datum without observed label

**Tree methods:**

- partition the space one feature at a time with binary choices
- prone to overfitting
- can be used for regression

**single trees** have high variance as the optimization has to be local

**ensemble methods** solve variance issue by running multiple trees and making an ensemble decision

**random forest:** trees run in parallel with a random subset of features and the decision scheme is "majority" decision

**gradient boosted trees:** trees run in series with feature weighted learning the weights from the outcome of the previous tree. The last tree has the division

**feature importance:** the importance of each feature can be extracted. In presence of covariance the feature importance may be hard to interpret

Keynotes

<http://what-when-how.com/artificial-intelligence/decision-tree-applications-for-data-modelling-artificial-intelligence/>

<https://www.ncbi.nlm.nih.gov/pmc/articles/PMC4466856/>

# resources

actually a video: watching  
not reading (~1 hour)

[https://www.youtube.com/watch?  
v=Trar7GZOPl8&feature=youtu.be&utm\\_medium=email&utm\\_source=intercom&utm  
\\_campaign=modular-code-event](https://www.youtube.com/watch?v=Trar7GZOPl8&feature=youtu.be&utm_medium=email&utm_source=intercom&utm_campaign=modular-code-event)

reading

Create a plot, of whatever data (and models if you want) you choose from open data (if you have doubt about whether your dataset is relevant for this homework please email me.)

You can make the plot in any coding language you want (e.g. python, javascript, R...), as long as you upload the code that generates the plot onto your repo (which means no tableau, or any other non reproducible).

Create a directory HW8\_<firstLast> in your DSPS repo. **The plot needs to be uploaded onto the HW8 folder in your github DSPS repo and be embedded in the README.md.** That means: when I click on the HW8 link the plot must be rendered in the front page of the repo. Your readme must contain the plot, and a brief caption. If it is an interactive graphic, upload a static image of it in the README and provide a link to the interactive version.

Please make an effort to make it a good, compelling graphic. Put <sup>4</sup>though into the esthetic of the plot, how clearly the content is communicated, avoid clutter, avoid misleading elements, mind your choice of colors accordingly to what was discussed in class.

**Each of you needs to upload their own plot, no group submissions.**

If your plot shows up as I described above in the repo and the code is also uploaded you will get 100% of the HW points. (Next week you will be tasked to review 3 plots of your classmates and you will be graded on the quality of the review.)

# Homework 1

Follow skeleton notebook to create an H-R diagram visualization with datapoints and contours

EC: make your visualization interactive so that rolling on any datapoint provides information about the data

# homework 2