- Similar to dynamic programming. Used for optimization problems.
- Optimization problems typically go through a sequence of steps, with a set of choices at each step.
- For many optimization problems, using dynamic programming to determine the best choices is overkill.
- Greedy Algorithm: Simpler, more efficient

- Greedy algorithms (GA) do not always yield optimal solutions, but for many problems they do.
  - ◆ 16.1, the activity-selection problem (活动安排)
  - ◆ 16.2, basic elements of the GA; knapsack prob. (贪婪算法的基本特征; 背包问题)
  - ◆ 16.3, an important application: the design of data compression (Huffman) codes. (哈夫曼编码)
  - \*16.4 Matroids and greedy methods
  - ◆ \*16.5, A task-scheduling problem as matroid (unit-time tasks scheduling, 有限期作业调度)

- The greedy method is quite powerful and works well for a wide range of problems:
  - ◆ minimum-spanning-tree algorithms (Chap 23) (最小生成树)
  - ◆ shortest paths from a single source (Chap 24) (最短路径)
  - ◆ set-covering heuristic (Chap 35). (集合覆盖)

**•** • • •

# Example: 北京欢乐谷游玩的活动安排



#### 米奇金奖 太空飞碟 狮子主庆典 飞跃太空 幻想火车 幸会史迪仔 白雪公主 9 **10** 11 12 13 **15 16** 17 14

## **Activity Selection**

- 欢乐谷
- Disneyland

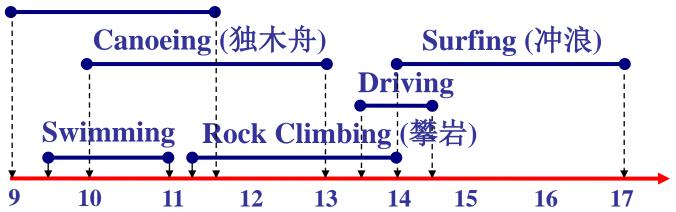






## **Example: Activity Selection**

Horseback Riding (骑马)



- How to make an arrangement to have the more activities?
  - ◆ S1. Shortest activity first (最短活动优先原则)
    Swimming, Driving
  - ◆ S2. First starting activity first (最早开始活动优先原则)
    Horseback Riding, Driving
  - ◆ S3. First finishing activity first (最早结束活动优先原则)
    Swimming, Rock Climbing, Surfing

# 16.1 An activity-selection problem

## 应用场景:

借体育馆、借会议室



exclusive use of a common resource.

#### Example, scheduling the use of a classroom.

(n) 个活动,1 项资源,任一活动进行时需唯一占用该资源)

- Set of activities  $S = \{a_1, a_2, \dots, a_n\}$ .
- $a_i$  needs resource during period  $[s_i, f_i]$ , which is a half-open interval, where  $s_i$  is start time and  $f_i$  is finish time.
- ◆ Goal: Select the largest possible set of nonoverlapping (mutually compatible) activities. (安排一个活动计划,使得相容的活动数目最多)
- Other objectives: Maximize income rental fees, ...

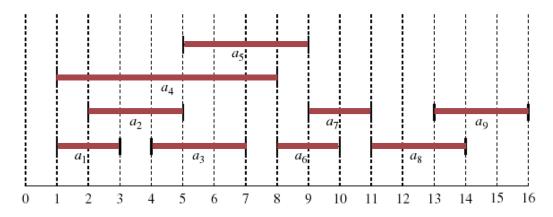




# 16.1 An activity-selection problem

- n activities require exclusive use of a common resource.
  - Set of activities  $S = \{a_1, a_2, \dots, a_n\}$
  - $a_i$  needs resource during period  $[s_i, f_i]$
- Example: S sorted by finish time:

i	1	2	3	4	5	6	7	8 11 14	9
$s_i$	1	2	4	1	5	8	9	11	13
$f_i$	3	5	7	8	9	10	11	14	16















Maximum-size mutually compatible set:

$${a_1, a_3, a_6, a_8}.$$

Not unique: also

$${a_2, a_5, a_7, a_9}.$$

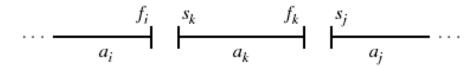
#### **Space of subproblems**

•  $S_{ij} = \{a_k \in S : f_i \le s_k < f_k \le s_j\}$ = activities that start after  $a_i$  finishes & finish before  $a_j$  starts

$$\cdots \xrightarrow{a_i} \xrightarrow{f_i} \xrightarrow{s_k} \xrightarrow{f_k} \xrightarrow{s_j} \cdots$$

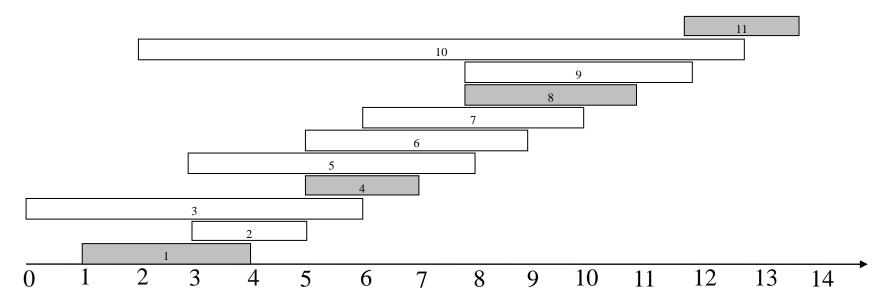
- Activities in  $S_{ij}$  are compatible with
  - all activities that finish by  $f_i$  (完成时间早于 $f_i$  的活动), and
  - all activities that start no earlier than  $s_i$ .
- To represent the entire problem, add fictitious activities:
  - $a_0 = [-\infty, 0);$   $a_{n+1} = [\infty, \infty+1]$
  - We don't care about  $-\infty$  in  $a_0$  or " $\infty+1$ " in  $a_{n+1}$ .
- Then  $S = S_{0,n+1}$ . Range for  $S_{ij}$  is  $0 \le i, j \le n+1$ .

## **Space of subproblems**



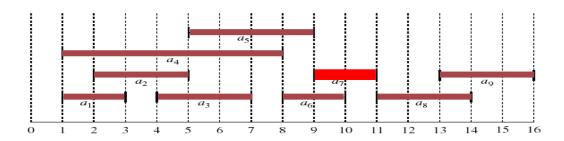
- $S_{ij} = \{a_k \in S : f_i \le s_k < f_k \le s_j\}$
- Assume that activities are sorted by monotonically increasing finish time (以结束时间单调增的方式对活动进行排序)

$$f_0 \le f_1 \le f_2 \le \dots \le f_n < f_{n+1}$$
 (if  $i \le j$ , then  $f_i \le f_j$ ) (16.1)



if 
$$f_0 \le f_1 \le f_2 \le \dots \le f_n < f_{n+1}$$
 (if  $i \le j$ , then  $f_i \le f_j$ ) (16.1)

- Then  $i \ge j \Rightarrow S_{ij} = \emptyset$ Proof If there exists  $a_k \in S_{ij}$ , then  $f_i \le s_k < f_k \le s_j < f_j \Rightarrow f_i < f_j.$ But  $i \ge j \Rightarrow f_i \ge f_j$ . Contradiction.
- So only need to worry about  $S_{ij}$  with  $0 \le i < j \le n+1$ . All other  $S_{ij}$  are  $\emptyset$ .



- Suppose that a solution to  $S_{ij}$  includes  $a_k$ . Have 2 sub-prob
  - $S_{ik}$  (start after  $a_i$  finishes, finish before  $a_k$  starts)
  - $S_{kj}$  (start after  $a_k$  finishes, finish before  $a_j$  starts)
- Solution to  $S_{ij} = (\text{solution to } S_{ik}) \cup \{a_k\} \cup (\text{solution to } S_{kj})$ Since  $a_k$  is in neither of the subproblems, and the subproblems are disjoint,  $|\text{solution to } S| = |\text{solution to } S_{ik}| + 1 + |\text{solution to } S_{kj}|$ .
- Optimal substructure: If an optimal solution to  $S_{ij}$  includes  $a_k$ , then the solutions to  $S_{ik}$  and  $S_{kj}$  used within this solution must be optimal as well. (use usual cut-and-paste argument).
- Let  $A_{ij}$  = optimal solution to  $S_{ij}$ , so  $A_{ij} = A_{ik} \cup \{a_k\} \cup A_{kj}$ , (16.2) assuming:  $S_{ij}$  is nonempty; and we know  $a_k$ .

#### 16.1.2 A recursive solution

- Let  $c[i,j] = \text{size of maximum-size subset of mutually compatible activities in } S_{ij}$  . (c[i,j] 表示  $S_{ij}$  相容的最大活动数)  $i \geq j \Rightarrow S_{ij} = \varnothing \Rightarrow c[i,j] = 0$ .
- If  $S_{ij} \neq \emptyset$ , suppose that  $a_k$  is used in a maximum-size subsets of mutually  $S_{ij}$ . Then c[i,j] = c[i,k] + 1 + c[k,j].
- But of course we don't know which k to use, and so

$$c[i,j] = \begin{cases} 0 &, & \text{if } S_{ij} = \emptyset, \\ \max_{i < k < j} \{c[i,k] + c[k,j] + 1\}, & \text{if } S_{ij} \neq \emptyset. \end{cases}$$
(16.3)

Why this range of k? Because  $S_{ij} = \{a_k \in S : f_i \le s_k < f_k \le s_j\} \Rightarrow a_k$  can't be  $a_i$  or  $a_i$  (if k = i, we have c[i,j] = c[i,j] + 1).

# 核心要素: 1. 递归; 2. 遍历n次, 选k

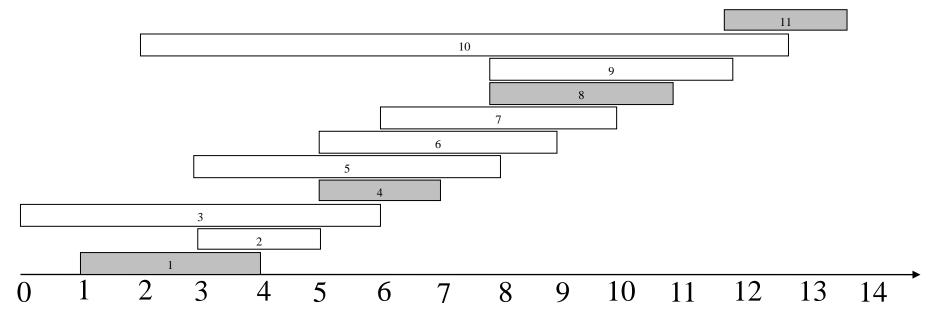
$$c[i,j] = \begin{cases} 0 &, & \text{if } S_{ij} = \emptyset, \\ \max_{i < k < j} \{c[i,k] + c[k,j] + 1\}, & \text{if } S_{ij} \neq \emptyset. \end{cases}$$
(16.3)

- It may be easy to design an algorithm to the problem based on recurrence (16.3).
  - (1) Direct recursion algorithm? complexity?
  - (2) Dynamic programming algorithm? complexity?
- For (16.3):
  - How many choices?
  - How many subproblems for a choice?
- Can we simplify our solution?

#### Theorem 16.1

Let  $S_{ij} \neq \emptyset$ , and let  $a_m$  be the activity in  $S_{ij}$  with the earliest finish time:  $f_m = \min \{f_k : a_k \in S_{ij} \}$ . Then

- 1.  $a_m$  is used in some maximum-size subset of mutually compatible activities of  $S_{ij}$ .  $(a_m$ 包含在某个最大相容活动子集中)
- 2.  $S_{im} = \emptyset$ , so that choosing  $a_m$  leaves  $S_{mj}$  as the only nonempty subproblem. (仅剩下一个非空子问题  $S_{mj}$ )



#### □ Theorem 16.1

Let  $S_{ij} \neq \emptyset$ , and let  $a_m$  be the activity in  $S_{ij}$  with the earliest finish time:  $f_m = \min \{f_k : a_k \in S_{ij} \}$ . Then

- 1. .....
- 2.  $S_{im} = \emptyset$ , so that choosing  $a_m$  leaves  $S_{mj}$  as the only nonempty subproblem. (仅剩下一个非空子问题  $S_{mj}$ )

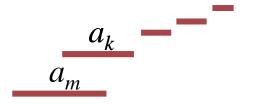
#### **Proof**

2. Suppose there is some  $a_l \in S_{im}$ . Then  $f_i \le s_l < f_l \le s_m < f_m \Rightarrow f_l < f_m$ . Then  $a_l \in S_{ij}$  and it has an earlier finish time than  $f_m$ , which contradicts our choice of  $a_m$ . Therefore, there is no  $a_l \in S_{im} \Rightarrow S_{im} = \emptyset$ .

- Theorem 16.1 Let  $S_{ij} \neq \emptyset$ , and let  $a_m$  be the activity in  $S_{ij}$  with the earliest finish time:  $f_m = \min \{ f_k : a_k \in S_{ij} \}$ . Then
  - 1.  $a_m$  is used in some maximum-size subset of mutually compatible activities of  $S_{ij}$ . ( $a_m$ 包含在某个最大相容活动子集中)

**Proof** 1. Let  $A_{ij}$  be a maximum-size subset of mutually Compatible activities in  $S_{ij}$ . Order activities in  $A_{ij}$  in monotonically increasing order of finish time. Let  $a_k$  be the first activity in  $A_{ij}$ .

• If  $a_k = a_m$ , done  $(a_m$  is used in a maximum-size subset).



• Otherwise, construct  $B_{ij} = A_{ij} - \{a_k\} \cup \{a_m\}$  (replace  $a_k$  by  $a_m$ ). Activities in  $B_{ij}$  are disjoint. (Activities in  $A_{ij}$  are disjoint,  $a_k$  is the first activity in  $A_{ij}$  to finish.  $f_m \le f_k \Rightarrow a_m$  doesn't overlap anything else in  $B_{ij}$ ). Since  $|B_{ij}| = |A_{ij}|$  and  $A_{ij}$  is a maximum-size subset, so is  $B_{ij}$ .

$$c[i,j] = \begin{cases} 0 &, & \text{if } S_{ij} = \emptyset, \\ \max_{i < k < j} \{c[i,k] + c[k,j] + 1\}, & \text{if } S_{ij} \neq \emptyset. \end{cases}$$
(16.3)

- □ Theorem 16.1 Let  $S_{ij} \neq \emptyset$ , and let  $a_m$  be the activity in  $S_{ij}$  with the earliest finish time:  $f_m = \min \{f_k : a_k \in S_{ij}\}$ . Then
  - 1.  $a_m$  is used in some maximum-size subset of mutually compatible activities of  $S_{ij}$ . ( $a_m$ 包含在某个最大相容活动子集中)
  - 2.  $S_{im} = \emptyset$ , so that choosing  $a_m$  leaves  $S_{mj}$  as the only nonempty subproblem. (仅剩下一个非空子问题  $S_{mi}$ )

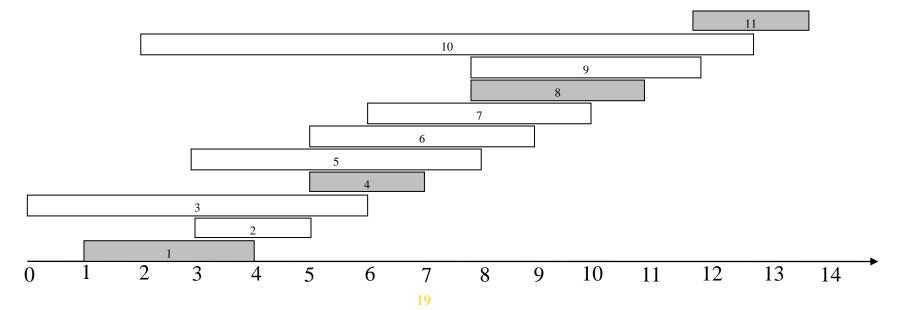
#### • This theorem is great:

	before theorem	after theorem
# of sub-prob in optimal solution	2	1
# of choices to consider	O(j-i-1)	1

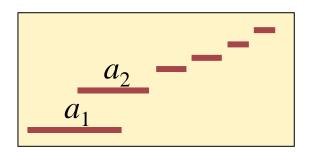
- Theorem 16.1 Let  $S_{ij} \neq \emptyset$ , and let  $a_m$  be the activity in  $S_{ij}$  with the earliest finish time:  $f_m = \min \{f_k : a_k \in S_{ij}\}$ . Then
  - 1.  $a_m$  is used in some maximum-size subset of mutually compatible activities of  $S_{ij}$ . ( $a_m$ 包含在某个最大相容活动子集中)
  - 2.  $S_{im} = \emptyset$ , so that choosing  $a_m$  leaves  $S_{mj}$  as the only nonempty subproblem. (仅剩下一个非空子问题  $S_{mj}$ )
- Now we can solve a problem  $S_{ij}$  in a top-down fashion (What kind of fashion for DP?)
  - Choose  $a_m \in S_{ij}$  with earliest finish time: the *greedy choice*. (it leaves as much opportunity as possible for the remaining activities to be scheduled) (留下尽可能多的时间来安排活动,贪心选择)
  - Then solve  $S_{mj}$ .

#### What are the subproblems?

- Original problem is  $S_{0, n+1}$  ( $a_0 = [-\infty, 0); a_{n+1} = [\infty, \infty+1]$ )
- Suppose our first choice is  $a_{m1}$  (in fact, it is  $a_1$ )
- Then next subproblem is  $S_{m1, n+1}$
- Suppose next choice is  $a_{m2}$  (it must be  $a_2$ ?)
- Next subproblem is  $S_{m2, n+1}$
- And so on



- What are the subproblems?
  - Original problem is  $S_{0, n+1}$
  - Suppose our first choice is a<sub>m1</sub>
  - Then next subproblem is  $S_{m1, n+1}$
  - Suppose next choice is  $a_{m2}$
  - Next subproblem is  $S_{m2, n+1}$
  - And so on
- Each subproblem is  $S_{mi, n+1}$ .
- And the subproblems chosen have finish times that increase. (所选的子问题,其完成时间是增序排列)
- Therefore, we can consider each activity just once, in monotonically increasing order of finish time.



- Original problem is  $S_{0, n+1}$
- Each subproblem is  $S_{mi, n+1}$

6 else return Ø

• Assumes activites already sorted by monotonically increasing finish time. (If not, then sort in  $O(n \lg n)$  time.) Return an optimal solution for  $S_{i, n+1}$ :

```
REC-ACTIVITY-SELECTOR(s, f, i, n)

1 m \leftarrow i+1 // initially i = 0, m = 1

2 while m \le n and s_m < f_i // Find next activity in S_{i, n+1}.

3 m \leftarrow m+1

4 if m \le n

5 return \{a_m\} \cup \text{REC-ACTIVITY-SELECTOR}(s, f, m, n)
```

```
a_2 — a_1
```

```
REC-ACTIVITY-SELECTOR(s, f, i, n)

1. m \leftarrow i+1
```

```
1 m \leftarrow i+1

2 while m \le n and s_m < f_i // Find next activity in S_{i, n+1}.

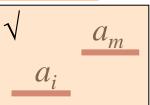
3 m \leftarrow m+1

4 if m \le n

5 return \{a_m\} \cup \text{REC-ACTIVITY-SELECTOR}(s, f, m, n)

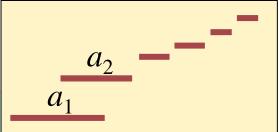
6 else return \varnothing
```

• *Initial call*: REC-ACTIVITY-SELECTOR(s, f, 0, n).



- *Idea*: The while loop checks  $a_{i+1}$ ,  $a_{i+2}$ , ...,  $a_n$  until it finds an activity  $a_m$  that is compatible with  $a_i$  (need  $s_m \ge f_i$ ).
  - If the loop terminates because  $a_m$  is found  $(m \le n)$ , then recursively solve  $S_{m, n+1}$ , and return this solution, along with  $a_m$ .
  - If the loop never finds a compatible  $a_m$  (m > n), then just return empty set.

6 else return Ø



```
REC-ACTIVITY-SELECTOR(s, f, i, n)

1 m \leftarrow i+1

2 while m \le n and s_m < f_i // Find next activity in S_{i,n+1}.

3 m \leftarrow m+1

4 if m \le n
```

**return**  $\{a_m\} \cup \text{REC-ACTIVITY-SELECTOR}(s, f, m, n)$ 

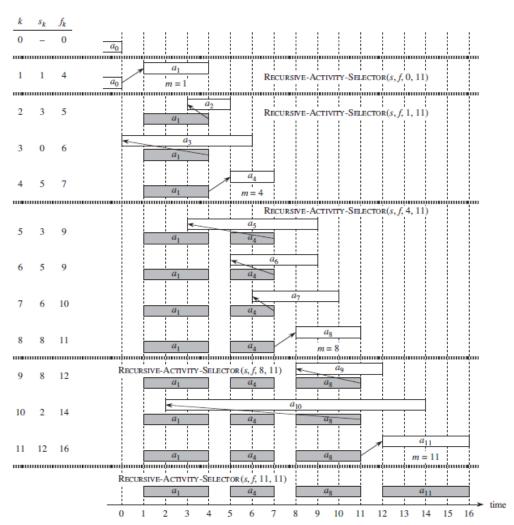
• *Time*:  $\Theta(n)$ —each activity examined exactly once.

$$T(n) = m_1 + T(n - m_1) = m_1 + m_2 + T(n - m_1 - m_2)$$

$$= m_1 + m_2 + m_3 + T(n - m_1 - m_2 - m_3) = \cdots$$

$$= \sum m_k + T(n - \sum m_k)$$
basecase:  $n - \sum m_k = 1$ , then  $\sum m_k = n - 1$ ,  $\sum m_k + T(1) = \Theta(n)$ 

- *Initial call*: REC-ACTIVITY-SELECTOR(s, f, 0, n).
- *Idea*: The while loop checks  $a_{i+1}, a_{i+2}, \ldots, a_n$  until it finds an activity  $a_m$  that is compatible with  $a_i$  (need  $s_m \ge f_i$ ).
  - If the loop terminates because  $a_m$  is found  $(m \le n)$ , then recursively solve  $S_{m,n+1}$ , and return this solution, along with  $a_m$ .
  - If the loop never finds a compatible  $a_m$  (m > n), then just return empty set.



## 16.1.5 An iterative greedy algorithm

- **REC-ACTIVITY-SELECTOR** is almost "tail recursive".
- We easily can convert the recursive procedure to an iterative one. (Some compilers perform this task automatically)

```
GREEDY-ACTIVITY-SELECTOR(s, f, n)

1 A \leftarrow \{a_1\}

2 i \leftarrow 1

3 for m \leftarrow 2 to n

4 if s_m \ge f_i

5 A \leftarrow A \cup \{a_m\}

6 i \leftarrow m // a_i is most recent addition to A

7 return A
```

#### Review

• Greedy Algorithm Idea: When we have a choice to make, make the one that looks best *right now*. Make a *locally optimal choice* in hope of getting a *globally optimal solution*.

(希望当前选择是最好的,每一个局部最优选择 能产生全局最优选择)

• Greedy Algorithm: Simpler, more efficient

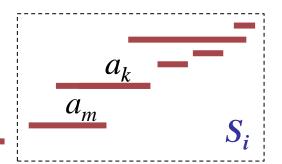
- 16.1, the activity-selection problem (活动安排)
- 16.2
   basic elements of the GA
   knapsack prob

(贪婪算法的基本特征;背包问题)

• 16.3, an important application: the design of data compression (Huffman) codes (哈夫曼编码)

- The choice that seems best at the moment is chosen (每次决策时, 当前所做的选择看起来是"最好"的)
- What did we do for activity selection?
  - 1. Determine the optimal substructure.
  - 2. Develop a recursive solution.
  - 3. Prove that at any stage of recursion, one of the optimal choices is the greedy choice.
  - 4. Show that all but one of the subproblems resulting from the greedy choice are empty. (通过贪婪选择,只有一个子问题非空)
  - 5. Develop a recursive greedy algorithm.
  - 6. Convert it to an iterative algorithm.

- These steps looked like dynamic programming.
- Develop the substructure with an eye toward
  - making the greedy choice,
  - leaving just one subproblem.



- For activity selection, we showed that the greedy choice implied that in  $S_{ii}$ , only i varied, and j was fixed at n+1,
- So, we could have started out with a greedy algorithm in mind:
  - ◆ define  $S_i = \{a_k \in S : f_i \leq s_k\}$ , (所有在  $a_i$  结束之后开始的活动)
  - show the greedy choice, first  $a_m$  to finish in  $S_i$  combined with optimal solution to  $S_m$   $\Rightarrow$  optimal solution to  $S_i$

#### **Typical streamlined steps**

1. Cast the optimization problem as one in which we make a choice and are left with one subproblem to solve. 快速做选择,且留下尽可能少的子问题,且子问题包括的信息尽可能多

- 2. Prove that there's always an optimal solution that makes the greedy choice, so that the greedy choice is always safe. 选择是解的一部分【贪婪】,因此贪婪选择是安全的
- 3. Show that greedy choice and optimal solution to subproblem ⇒ optimal solution to the problem.

贪婪选择 + 子问题的最优解 ⇒ 原问题的最优解

 No general way to tell if a greedy algorithm is optimal, but two key ingredients are

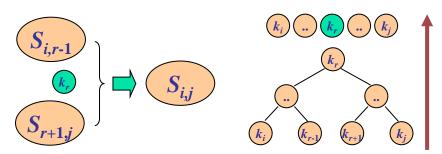
(没有一般化的规则来说明贪婪算法是否最优,但有两个基本要点)

- 1. greedy-choice property (贪婪选择属性)
- 2. optimal substructure

## 16.2.1 Greedy-choice property

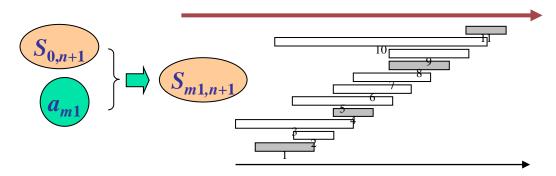
• A globally optimal solution can be arrived at by making a locally

optimal (greedy) choice.



**OBST-DP** 

- Dynamic programming
  - Make a choice at each step.
  - Choice depends on knowing optimal solutions to subproblems. Solve subproblems *first*. (依赖于已知子问题的最优解再作出选择)
  - Solve bottom-up.



**Activity-DP** 

- Greedy
  - Make a choice at each step.

**Activity-GA** 

- Make the choice before solving the subproblems.
- Solve top-down.

#### 16.2.1 Greedy-choice property

- We must prove that a greedy choice at each step yields a globally optimal solution. Difficulty! Cleverness may be required!
- Typically, Theorem 16.1, shows that the solution  $(A_{ij})$  can be modified to use the greedy choice  $(a_m)$ , resulting in one similar but smaller subproblem  $(A_{mi})$ .
- We can get efficiency gains from greedy-choice property. (For example, in activity-selection, sorted the activities in monotonically increasing order of finish times, needed to examine each activity just once.)
  - Preprocess input to put it into greedy order
  - Technically, the maximum or minimum is usually the choice.

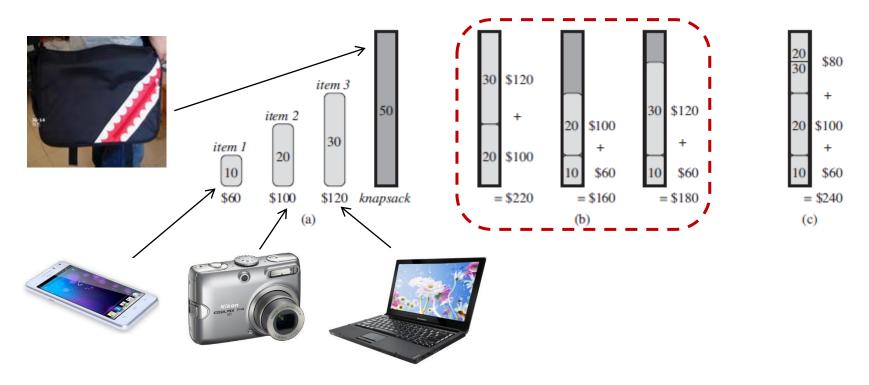
## 16.2.2 Optimal substructure

- optimal substructure: an optimal solution to the problem contains within it optimal solutions to subproblems.
- Just show that optimal solution to subproblem and greedy choice ⇒ optimal solution to problem.

(说明子问题的最优解和贪婪选择

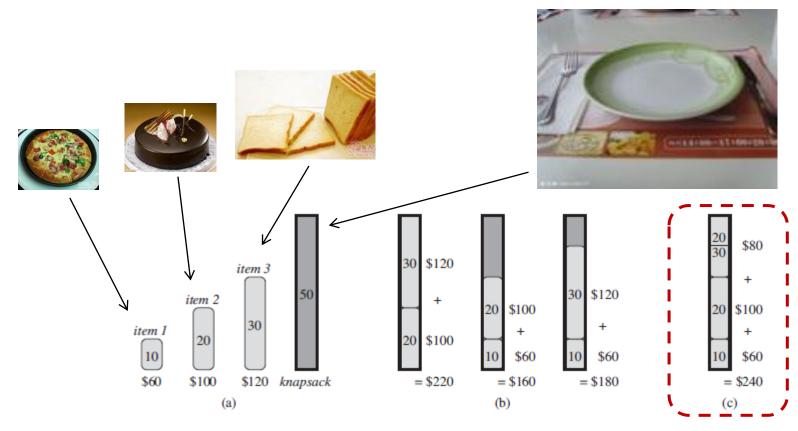
⇒ 原问题的最优解)

## 16.2.3 knapsack: Greedy vs. dynamic programming



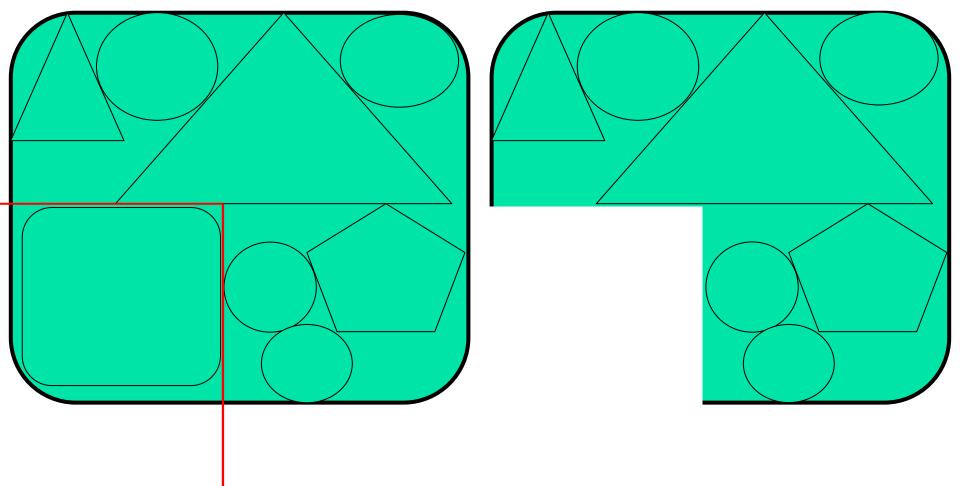
- 0-1 knapsack problem (0-1背包问题,小偷问题)
  - ◆ n items (n 个物品)
  - ◆ Item i is worth  $v_i$ , weighs  $w_i$  P (物品i 价值 $v_i$ , 重 $w_i$ )
  - Find a most valuable subset of items with total weight  $\leq W$ .
  - Have to either take an item or not take it—can't take part of it.

#### 16.2.3 knapsack: Greedy vs. dynamic programming



- Fractional knapsack problem (分数背包问题, 小偷问题)
  - Like the 0-1 knapsack problem, but can take fraction of an item.

- *0-1 knapsack problem* (0-1背包问题,小偷问题)
- Fractional knapsack problem (分数背包问题, 小偷问题)
- Both have optimal substructure property.
  - 0-1:?
  - fractional: ?

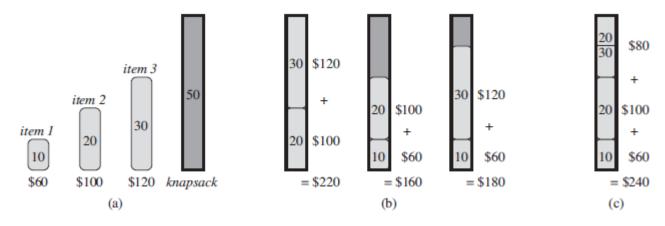


# 背包问题的最优子结构性质:

完整的圆角矩形框是一个最优背包,去掉 右下角的红色部分剩下的部分是一个子背 包,则该子背包也是一个最优背包。

- 0-1 knapsack problem (0-1背包问题,小偷问题)
- Fractional knapsack problem (分数背包问题, 小偷问题)

 But the fractional problem has the greedy-choice property, and the 0-1 problem does not.



- Fractional knapsack problem
   has the greedy-choice property,
   and the <u>0-1 knapsack problem</u>
   does not.
- To solve the fractional problem, rank decreasingly items by  $v_i/w_i$
- Let  $v_i/w_i \ge v_{i+1}/w_{i+1}$ for all i

```
FRACTIONAL-KNAPSACK(v, w, W)

1 load \leftarrow 0

2 i \leftarrow 1

3 while load < W and i \le n

4 if w_i \le W - load

5 take all of item i

6 else take W-load of w_i from item i

7 add what was taken to load

8 i \leftarrow i + 1
```

• *Time:*  $O(n \lg n)$  to sort, O(n) to greedy choice thereafter.

# 0-1 knapsack problem has not the greedy-choice property.

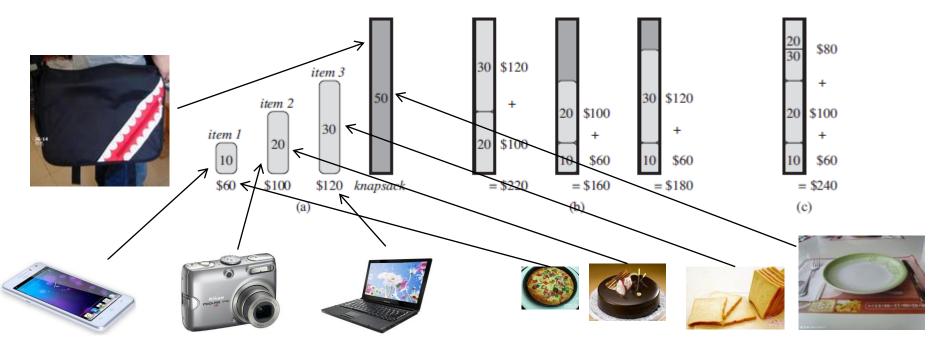
let W = 50 for the following example.

- Greedy solution:
  - take items 1 and 2
  - value = 160, weight = 30
- 20 pounds of capacity leftover.

i	1	2	3
$v_i$	60	100	120
$w_i$	10	20	30
$v_i/w_i$	6	5	4

- Optimal solution:
  - Take items 2 and 3
  - value=220, weight=50

No leftover capacity. (没有剩余空间)



# 16 Greedy Algorithms

- 16.1, the activity-selection problem (活动安排)
- 16.2, basic elements of the GA; knapsack prob (贪婪算法的基本特征; 背包问题)
- 16.3, an important application: the design of data compression (Huffman) codes (哈夫曼编码)

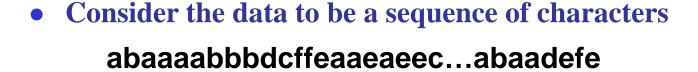
#### A method for the construction of minimum-redundancy codes

DA Huffman - Proceedings of the IRE, 1952 - ieeexplore.ieee.org

INTRODUCTION Q NE IMPORTANT METHOD of transmitting messages is to transmit in their place sequences of symbols. If there are more messages which might be sent than there are kinds of symbols available, then some of the messages must use more than one sym- bol. If it is assumed that each symbol requires the same time for transmission, then the time for transmission (length) of message is directly proportional to the number of symbols associated with it. In this paper, the symbol or sequence of symbols associated with a given message will be called the ...

☆ ワワ 被引用次数: 7783 相关文章 所有 7 个版本

- Huffman codes: widely used and very effective technique for <u>encoding file</u> or compressing data.
  - savings of 20% to 90%







作业:每人写一个压缩软件

Huffman's greedy algorithm:

uses a table of the frequencies of occurrence of the characters to build up an optimal way of representing each character as a binary string.

依据字符出现的频率表,使用二进串来建立一种表示字符的最佳方法

• Wish to store compactly 100,000-character data file.

Only six different characters appear.

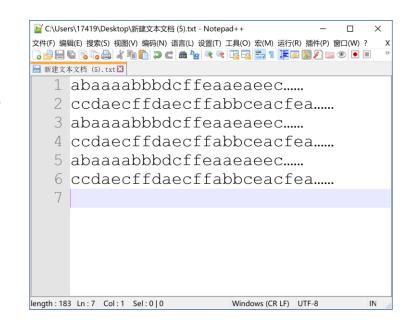
abaaaabbbdcffeaaeaeec.....

ccdaecffdaecffabbceacfea.....

#### **Frequency table:**

	a	b	c	d	e	f
Frequency (in thousands)	45	13	12	16	9	5
Fixed-length codeword	000	001	010	011	100	101
Variable-length codeword	0	101	100	111	1101	1100

- Many ways (encodes) to represent such a file of information
- binary character code (or code for short): each character is represented by a unique binary string.
  - *fixed-length code*: if use 3-bit codeword, the file can be encoded in 300,000 bits. Can we do better?



• 100,000-character data file

	a	b	c	d	e	f
Frequency (in thousands)	45	13	12	16	9	5
Fixed-length codeword	000	001	010	011	100	101
Variable-length codeword	0	101	100	111	1101	1100

- binary character code (or code for short)
  - variable-length code: by giving frequent characters short codewords and infrequent characters long codewords, here the 1-bit string 0 represents a, and the 4-bit string 1100 represents f. (高频出现的字符以短字码表示; 低频→长字码)

$$(45 \cdot 1 + 13 \cdot 3 + 12 \cdot 3 + 16 \cdot 3 + 9 \cdot 4 + 5 \cdot 4) \cdot 1,000 = 224,000 \text{ bits}$$

• 100,000-character data file

	a	b	c	d	e	f	
Frequency (in thousands)	45	13	12	16	9	5	
Fixed-length codeword	000	001	010	011	100	101	
Variable-length codeword	0	101	100	111	1101	1100	

- binary character code (or code for short)
  - fixed-length code: 300,000 bits
  - variable-length code: 224,000 bits, a savings of 25.3%. In fact, this is an optimal character code for this file.

• prefix codes (prefix-free codes): no codeword is a prefix of some other codeword.

前缀码〔前缀无关码〕:没有字码是其他字码的前缀

Frequency (in thousands) 45 13 12 16 9 5
Fixed-length codeword 000 001 010 011 100 101
Variable-length codeword 0 101 100 111 1101 1100

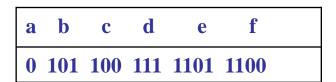
- Encoding is always simple for any binary character code
  - Concatenate (连接) the codewords representing each character. For example, "abc", with the variable-length prefix code as 0·101·100 = 0101100, where we use '.' to denote concatenation.
- Prefix codes simplify decoding

• prefix codes (prefix-free codes): no codeword is a prefix of some other codeword.

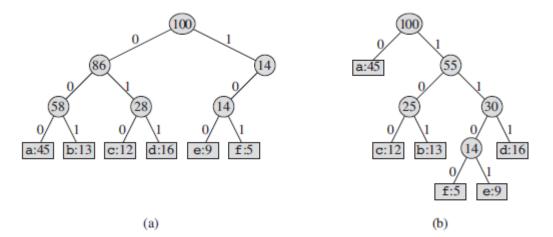
前缀码〔前缀无关码〕:没有字码是其他字码的前缀

	a	b	c	d	e	f
Variable-length codeword	0	101	100	111	1101	1100

- Encoding is always simple for any binary character code
- Prefix codes simplify decoding
  - Since no codeword is a prefix of any other, the codeword that begins an encoded file is unambiguous (明确的).
  - We can simply identify the initial codeword, translate it back to the original character, and repeat the decoding process on the remainder of the encoded file.
  - Exam: 001011101 uniquely as 0·0·101·1101, which decodes to "aabe".



# 001011101 uniquely as 0·0·101·1101, which decodes to "aabe".

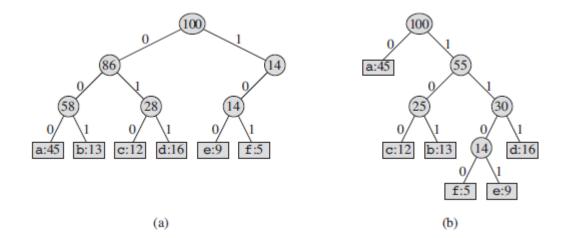


# **Decoding**

- the process needs a convenient representation for the prefix code so that the initial codeword can be easily picked off.
  - (前置无关码方便解码)
- A binary tree whose leaves are the given characters provides one such representation. (二叉树是一种方便的表示方法,树叶为给定字符,从树根到树叶的过程就是解码过程)

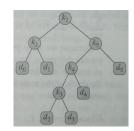
a	b	c	d	e	f
0	101	100	111	1101	1100

001011101 uniquely as 0.0.101.1101, which decodes to "aabe".

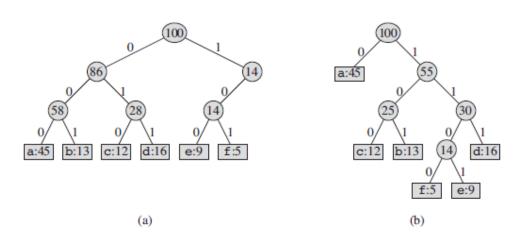


# **Decoding**

- We interpret the binary codeword for a character as the path from the root to that character. (字符的编码为一条从树根到树叶路径)
- It is not binary search trees, since the leaves need not appear in sorted order and internal nodes do not contain character keys.

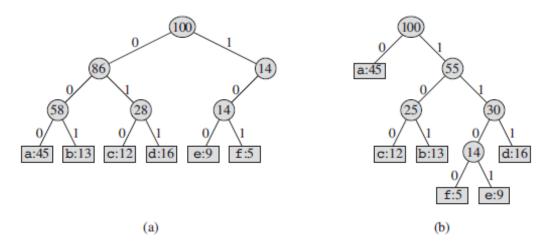


注意:不要混淆各种二叉树,如,最大(小)堆、二叉搜索树,哈夫曼树



#### full binary tree 满二叉树

- 国际定义:除叶子节点外,所有节点都有两个孩子。
- 国内定义:除了满足如上定义,所有叶子节点还需要在同一层上。
- An optimal code for a file is always represented by a *full* binary tree, every nonleaf node has two children (Ex16.3-1). The fixed-length code in our example is not optimal.
- We can restrict our attention to full binary trees
  - C is the alphabet,
  - all character frequencies >0
  - the tree for an optimal prefix code has |C| leaves, one for each letter of C, and exactly |C|-1 internal nodes.



# Compute # of bits required to encode a file

- Given a tree T corresponding to a prefix code, for each character c in the alphabet C,
  - f(c): frequency of c in the file
  - $d_T(c)$ : depth of c's leaf in the tree (length of the codeword for character c). Then, # of bits required to encode a file

$$B(T) = \sum_{c \in C} f(c)d_T(c)$$
 (16.5)

which we define as the *cost* of the tree T.

# 16.3.2 Constructing a Huffman code

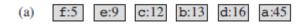
Huffman code:
a greedy algorithm
that constructs an
optimal prefix code

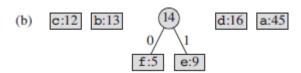
```
HUFFMAN(C)
1 n \leftarrow |C|
2 Q \leftarrow C
3 for i \leftarrow 1 to n - 1
4 allocate(分配) a new node z
5 left[z] \leftarrow x \leftarrow \text{EXTRACT-MIN}(Q)
6 right[z] \leftarrow y \leftarrow \text{EXTRACT-MIN}(Q)
7 f[z] \leftarrow f[x] + f[y]
8 INSERT(Q, z)
9 return EXTRACT-MIN(Q) //return the root of the tree.
```

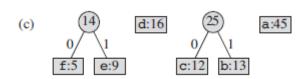
- C: set of n characters,  $c \in C$ : an object with frequency f[c].
  - Build the tree T corresponding to the optimal code.
  - Begin with |C| leaves, perform |C|-1 "merging" operations.
  - A min-priority queue Q, keyed on f, is used to identify the two least-frequent objects to merge together. Result of the merger is a new object whose frequency is the sum of the frequencies of the two objects that were merged.

# 16.3.2 Constructing a Huffman code

Example:
Huffman's algorithm
proceeds. 6 letters,
5 merge steps.
The final tree
represents the
optimal prefix code.

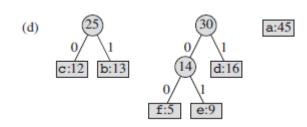


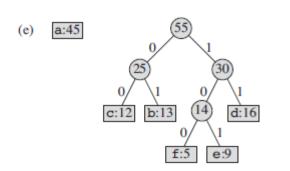


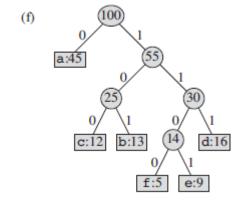


#### HUFFMAN(*C*)

- $1 n \leftarrow |C|$
- $2 Q \leftarrow C$
- 3 **for**  $i \leftarrow 1$  **to** n 1
- 4 allocate(分配) a new node z
- 5  $left[z] \leftarrow x \leftarrow \text{EXTRACT-MIN}(Q)$
- 6  $right[z] \leftarrow y \leftarrow \text{EXTRACT-MIN}(Q)$
- 7  $f[z] \leftarrow f[x] + f[y]$
- 8 INSERT(Q, z)
- 9 **return** EXTRACT-MIN(Q) //return the root of the tree.





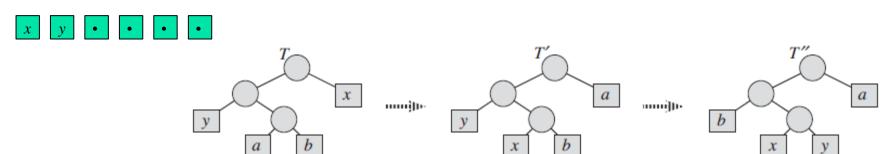


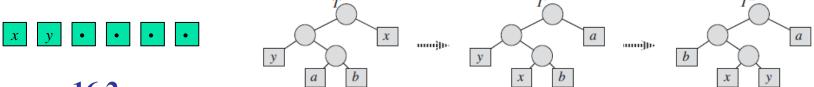
**Running time?** 

- Problem of determining an optimal prefix code exhibits the greedy-choice and optimal-substructure properties.
- Lemma 16.2 (greedy-choice property)

Let C be an alphabet, each character  $c \in C$  has frequency f[c]. x and  $y \in C$ , and having the lowest frequencies. Then there exists an optimal prefix code for C in which the codewords for x and y have the same length and differ only in the last bit.

**Proof idea:** take the tree T representing an arbitrary optimal prefix code, and modify it to make a tree representing another optimal prefix code such that x and y appear as sibling leaves (姐妹叶) of maximum depth in the new tree.





#### Lemma 16.2

 $c \in C$  has frequency f[c]. x,  $y \in C$ , having the lowest frequencies. Then, exist an optimal prefix code for C in which the codewords for x and y have the same length and differ only in the last bit.  $B(T) = \sum_{x \in C} f(c)d_T(c)$  (16.5)

**Proof**: Let a and b are sibling leaves of maximum depth in optimal T. Assume that  $f[a] \le f[b]$ ,  $f[x] \le f[y]$ . f[x] and f[y] are the two lowest leaf frequencies, f[a], f[b] are two arbitrary frequencies, in order,  $\Rightarrow f[x] \le f[a]$ ,  $f[y] \le f[b]$ . Exchange the positions in T of a and x to produce a tree T', and then exchange the positions in T' of b and y to produce a tree T''. By (16.5), we have

$$\begin{split} B(T) - B(T') &= \sum_{c \in C} f(c) d_T(c) - \sum_{c \in C} f(c) d_{T'}(c) \\ &= f[x] d_T(x) + f[a] d_T(a) - f[x] d_{T'}(x) - f[a] d_{T'}(a) \\ &= f[x] d_T(x) + f[a] d_T(a) - f[x] d_T(a) - f[a] d_T(x) \\ &= (f[x] - f[a]) d_T(x) + (f[a] - f[x]) d_T(a) \\ &= (f[a] - f[x]) (d_T(a) - d_T(x)) \, \geq \, 0 \end{split}$$

Similarly, 
$$B(T')$$
- $B(T'') \ge 0$ , therefore,  $B(T'') \le B(T)$ .  
Since  $T$  is optimal,  $B(T) \le B(T'')$ .  
Then  $B(T'') = B(T)$ .  
Thus,  $T''$  is an optimal tree.

• Lemma 16.3 (optimal-substructure property)?

Alphabet C, each character  $c \in C$  has frequency f[c]. x and  $y \in C$ , and having the lowest frequencies.  $C' = C - \{x, y\} \cup \{z\}$ . Define f for C' as for C, except that f[z] = f[x] + f[y]. Let T' be any tree representing an optimal prefix code for the alphabet C'. Then the tree T, obtained from T' by replacing the leaf node for z with an internal node having x and y as children, represents an optimal prefix code for C.

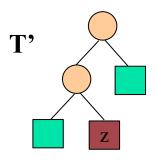
(给定字母表集C,每一个字符 $c \in C$  的频率为f[c] 。 x 和  $y \in C$ 有最小频率。从 C 中抽取字符x 和 y ,但增加新字符 z 到C中,得到新的字符集C',即 C' = C-{x, y}  $\cup$  {z}。除 f[z]=f[x]+f[y] 以外,f 在 C'中的定义与在C中相同。若 T'为 C'的最优前缀无关编码,则 T 为关于 C 的最优前缀无关编码,其中, T 为把 T'的叶节点 z 代替为以 x 和 y 作为叶节点的内点变换而来。)

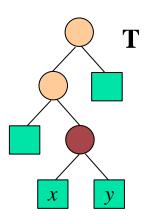
$$C: \{c_1, ..., c_m, x, y\}, C': \{c_1, ..., c_m, z\},\$$

由optimal T'能构成 optimal T

#### • Lemma 16.3 (optimal-substructure property)

**Proof**: For each  $c \in C$ - $\{x, y\}$ , we have  $d_T(c) = d_{T'}(c)$ , then  $f[c]d_T(c) = f[c]d_{T'}(c)$ . Since  $d_T(x) = d_T(y) = d_{T'}(z) + 1$ , we have  $f[x]d_T(x) + f[y]d_T(y) = (f[x] + f[y])(d_{T'}(z) + 1) = f[z]d_{T'}(z) + (f[x] + f[y])$ , from which we conclude that B(T) = B(T') + f[x] + f[y].  $(B(T) = f[x]d_T(x) + f[y]d_T(y) + f[c]d_T(c), B(T') = f[z]d_{T'}(z) + f[c]d_T(c))$ 

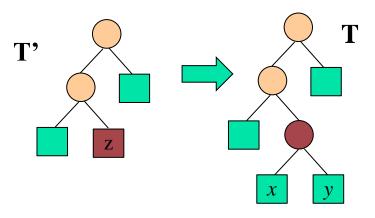




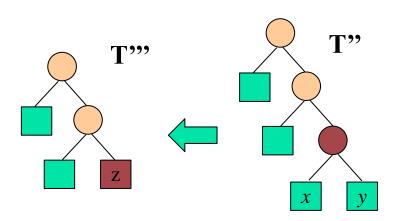
Detail of proof? Next slides.

# • Lemma 16.3 (optimal-substructure property)

$$C: \{c_1, ..., c_m, x, y\}, C': \{c_1, ..., c_m, z\},$$
 由optimal **T**'能构成 optimal **T**



Here, 
$$B(T) = B(T') + f[x] + f[y]$$

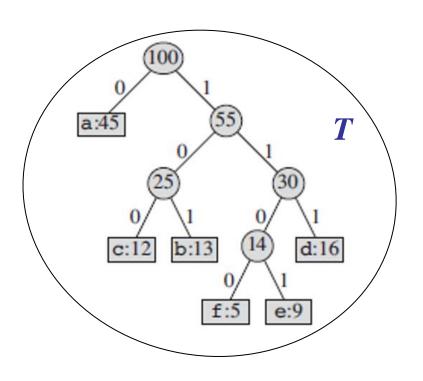


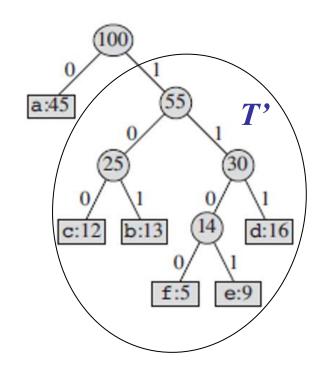
Suppose that T is not optimal, T" is. Then B(T)" B(T). Without loss of generality (by Lemma 16.2), T" has x and y as siblings. Let T" be the tree T" with the common parent of x and y replaced by a leaf z with frequency f[z]=f[x]+f[y]. Then

$$B(T"') = B(T")-f[x]-f[y]$$
  
 $< B(T)-f[x]-f[y] = B(T'),$ 

yielding a contradiction to the assumption that T' represents an optimal prefix code for C'. Thus, T must represent an optimal prefix code for the alphabet C.

• Lemma 16.3 (optimal-substructure property) 另一种解释





if **T** optimal, then **T'** optimal

□ Theorem 16.4
 Procedure HUFFMAN produces an optimal prefix code.

**Proof** Immediate from Lemmas 16.2 (每一次选择是贪婪的、是正确的) and Lemmas 16.3 (确保由子问题的最优解能导出原问题的最优解).

# **Exercises**

$$c[i,j] = \begin{cases} 0 &, & \text{if } S_{ij} = \emptyset, \\ \max_{i < k < j} \{c[i,k] + c[k,j] + 1\}, & \text{if } S_{ij} \neq \emptyset. \end{cases}$$
(16.3)

- It may be easy to design an algorithm to the problem based on recurrence (16.3).
  - (1) Direct recursion algorithm? complexity?
  - (2) Dynamic programming algorithm? complexity?
- For (16.3):
  - How many choices?
  - How many subproblems for a choice?
- Can we simplify our solution?
- 16.1.3 Converting a DP solution to a greedy solution

## Exercises

16.1-1, 16.1-2 (最晚开始优先原则)

*16.2-2* 

Give a dynamic-programming solution to the 0-1 knapsack problem that runs in  $O(n \ W)$  time, where n is number of items and W is the maximum weight of items that the thief can put in his knapsack.

# 16.3-2 (课堂作业)

What is an optimal Huffman code for the following set of frequencies, based on the first 8 Fibonacci numbers?

a:1 b:1 c:2 d:3 e:5 f:8 g:13 h:21

# 又一些大作业或讨论题提示:

- 活动安排、Huffman code等,是否都能描述为背包问题?
- 本书有多少算法是用的贪心策略(小论文:贪心算法十个经典问题?)
- 哈夫曼编码(用哈夫曼压缩方法,设计一个压缩软件:测试一下,算法导论这本书的压缩率能到多少?)
- OBST (最优二叉搜索树构建(以某本书里的词汇为基础?))
- 活动安排、分数背包
- · 0-1背包、钢管切割、ALS、MCM、LCS、最短路径
- 雇佣(雇佣多少人)、取帽子、相同生日
- RSA加密解密、FFT、串匹配、计算几何、最大流
- 算法实验室(问题求解工具、算法效果展示平台、多种算法时间复杂度对比分析、IO导入、......。支持穷举、递归、回溯、分治、DP、贪心;排序、查找;随机;图、树;等等若干方法(算法)的仿真演示。)