

Project 3 Report

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1 CODE REWRITE

Thanks to TA provided code :). It is much clean so I rewrite my code of the part of MCTS completely, so that the implementation of the following is not hard to do.

2 MCTS

For each tree node s , Q_s is the win rate of who takes turn at s , so in opponents nodes, MCTS selection prefers actions beneficial to opponents. This makes sense (like min-max search) and is mentioned in one random teacher's slide, while it's not implemented in TA provided sample code, nor mentioned in main part of slides.

3 RAVE

$k = 100$

4 BITBOARD

A board is stored in 4 `uint128`. The first 2 is black pieces and white pieces. The last two are legal moves of black and white, so when we want to place a piece on a board, we check the masks easily, and when a piece is placed, we update the masks. I think this can do faster when simulation, since we only check legal moves instead of all moves and check liberty again and again. But I don't compare them anyways.

5 PARALLELIZATION

I implement lock-free tree parallelization. In the selection stage, add the virtual loss, i.e., visit count and rave visit count.

Pre-allocated space for nodes is set to 10^6 . That is, `std::vector::reserve`.

Note that `expend` fails when the node is a terminal or the space is full. It is important to prevent thinking-too-long attack. I mean if the opponent takes too much time in one move on purpose, my MCTS may memory exceed and explodes.

Also, my MCTS will still proceed in opponent's round.

Lock-free tree parallelization maybe a pit! A little bit too large or too small c dramatically reduce the performance, and finding the best c is a waste of time.

6 TREE RECYCLE

For each move, I don't release the MCTS tree, instead, when the next time taking action. I set the root be the new state.

7 THINKING WHEN OPPONENT THINKING

As the title said, after taking action $s \xrightarrow{a} s'$, MCTS search continues to search s' . Adding this with tree recycling, sometimes the saved tree size can be over millions.

8 TIME MANAGEMENT

I use enhanced time management, where $c = 20$, $maxply = 20$. The approximated MCTS per millisecond is 200.

Also, I use EARLY-C. It is easy to implement but in mock contest, I found nobody do this, because they think too long in the endgame.

9 SIMULATION BALANCING

I attempt to do simulation balancing. The score of a move is the score of s' minus the score of s . Anyways my conclusion is that my design of the score may be too complicated, so the simulation is too slow, and the performance is super bad. I was thinking a new method that takes advantage of bitboard, which will be much faster. But I win the mock contest, so.... But I got second place today :(, maybe I should finish this.