

#### **Analog Integrated Systems Design**

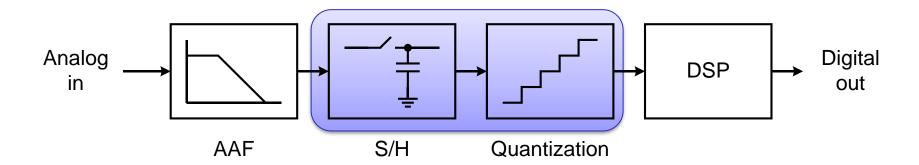
# Lecture 04 Data Converters Specifications (1)

#### Dr. Hesham A. Omran

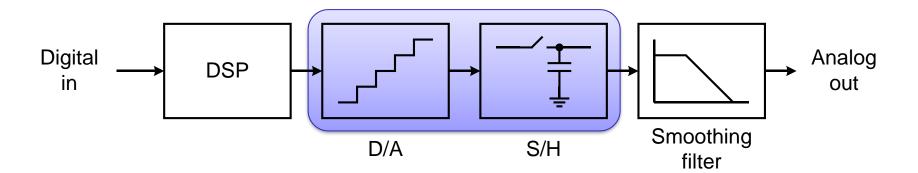
Integrated Circuits Lab (ICL)
Electronics and Communications Eng. Dept.
Faculty of Engineering
Ain Shams University

#### ADC and DAC

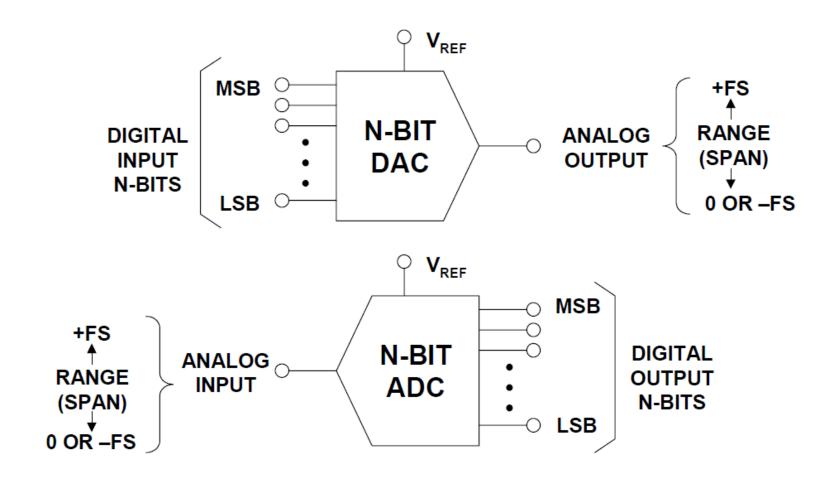
☐ ADC



DAC



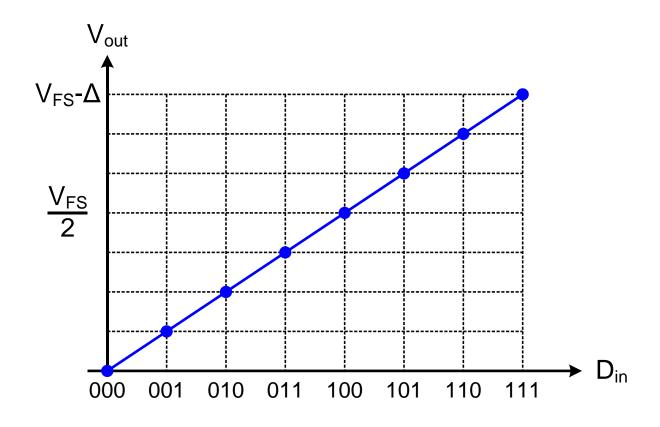
### Unipolar vs Bipolar



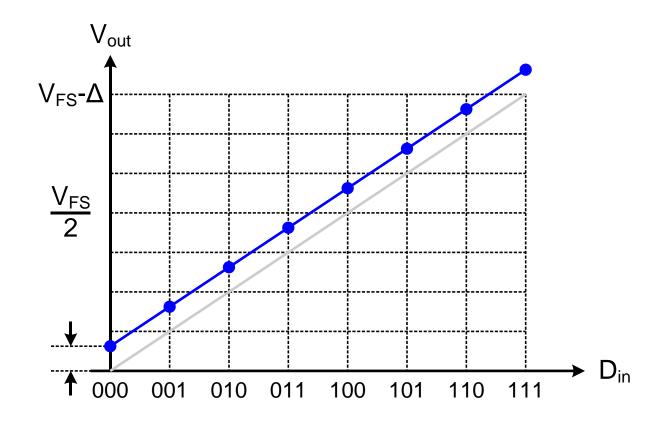
## Static (DC) Specifications

- ☐ Offset Error
- Gain Error
- Monotonicity
- Linearity
  - Differential Non-Linearity (DNL)
  - Integral Non-Linearity (INL)

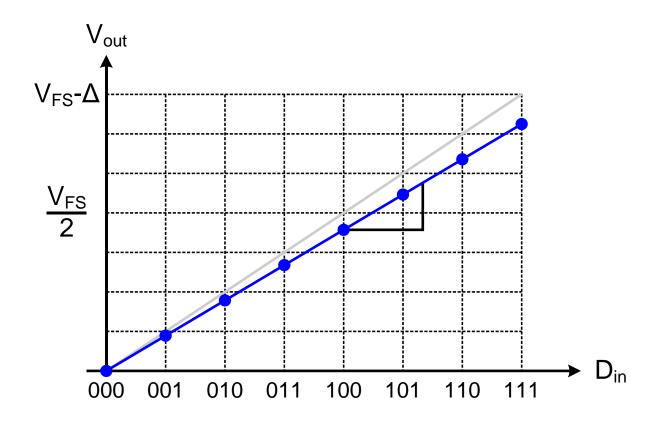
#### Ideal DAC Transfer Function



#### **DAC Offset Error**

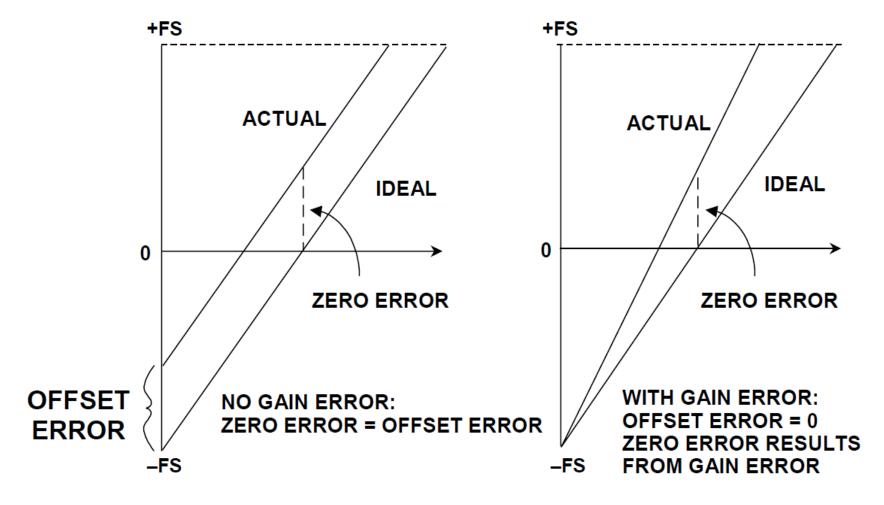


#### **DAC Gain Error**



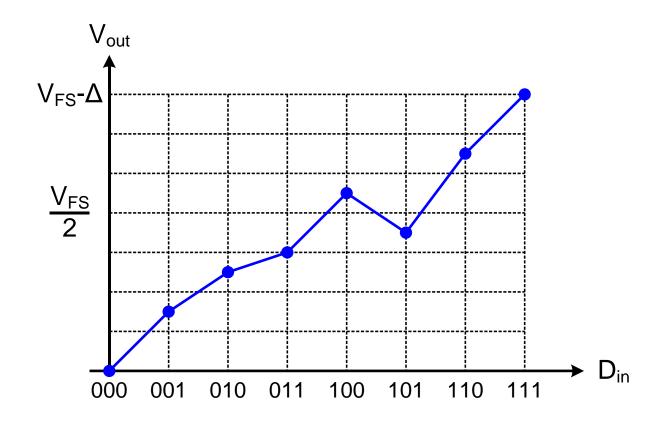
#### Offset and Gain Errors

- Can be calibrated by two points.
- First, trim offset error. Next, trim gain error.



#### **DAC Non-monotonicity**

☐ Non-monotonicity can be catastrophic in control loops (why?).

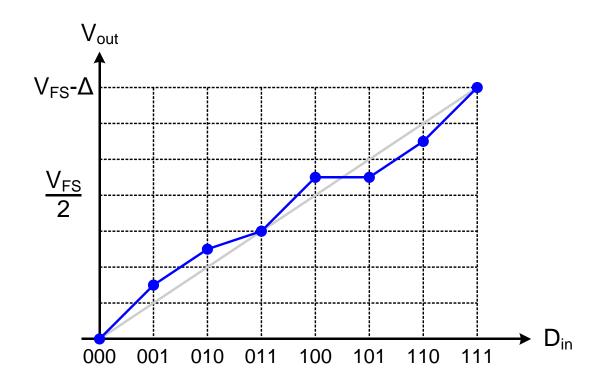


### DAC Differential Nonlinearity (DNL)

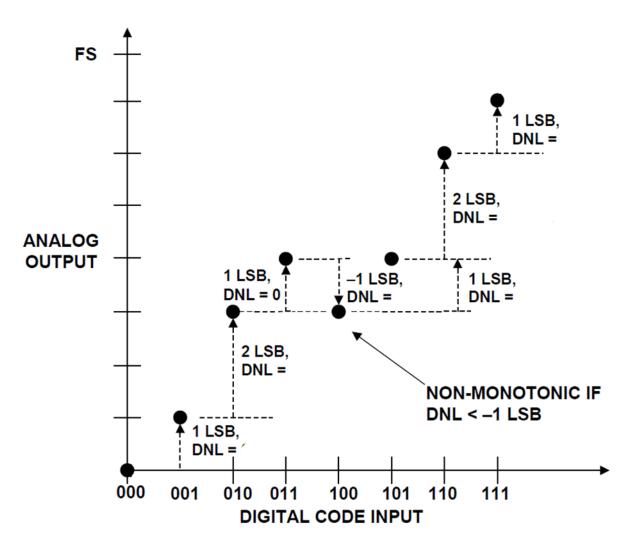
 $\square$  DNL = deviation of an output step from 1 LSB (=  $\Delta$  =  $V_{FS}/2^N$ )

$$DNL_{i} = \frac{i^{th} Step Size - \Delta}{\Delta}$$

☐ What does DNL < -1 mean?



#### DAC DNL Example



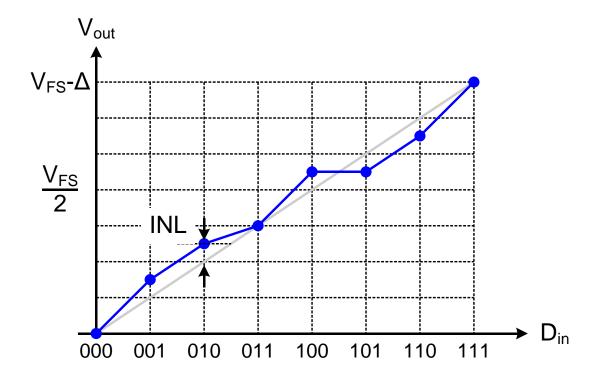
**04: Specifications (1)** [W. Kester, 2005]

11

## DAC Integral Nonlinearity (INL)

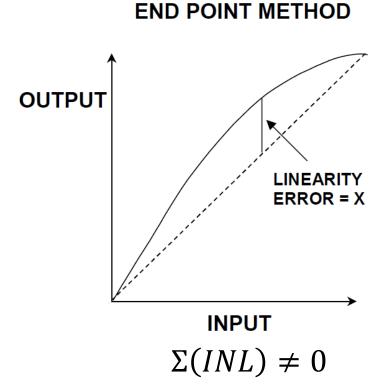
- ☐ INL = deviation of the output from the ideal transfer curve
- ☐ It can be shown that INL = cumulative sum of DNL

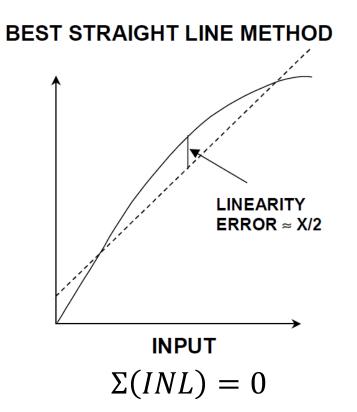
$$INL_i = \sum_{j=0}^{i} DNL_j$$



#### **INL Measurement Methods**

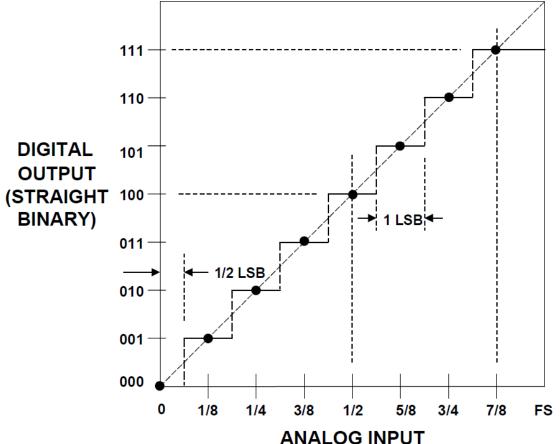
- INL can be measured relative to:
  - A line joining the ideal end points → More accurate
  - A best fit straight line → May be misleading
- ☐ The peak-to-peak INL remains the same





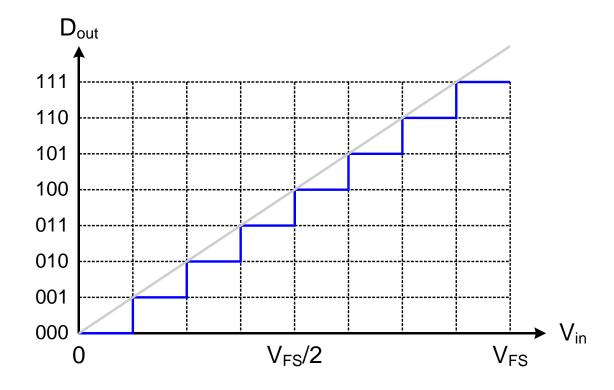
#### Unipolar ADC Transfer Function

- ☐ The first transition is at LSB/2 (mid-tread quantizer)
- The transfer ccs is the line joining the code centers (black dots)
- $\square$  Code centers are difficult to measure  $\rightarrow$  use code transitions



#### Ideal ADC Transfer Characteristic

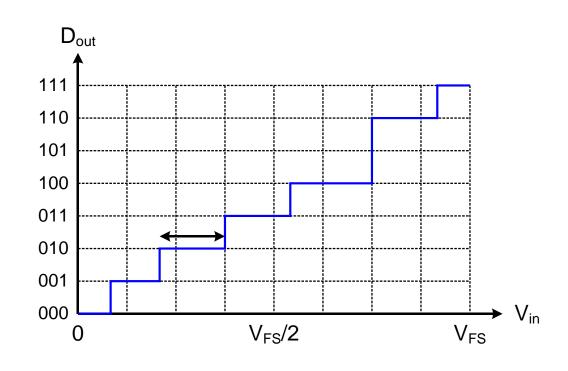
- ☐ Using floor/ceiling yields systematic offset error
- ☐ Offset and gain errors are usually not critical for ADCs
  - Can be trimmed (corrected) easily in the digital domain



### **ADC DNL and Missing Codes**

- ☐ DNL and INL always measured on the analog axis
- $\square$  DNL = deviation of code width from 1 LSB (=  $V_{ES}/2^N = \Delta$ )
  - Wide code  $\rightarrow$  +ve DNL, narrow code  $\rightarrow$  -ve DNL
- What does DNL = -1 mean? Can it be < -1?</p>
- Can we have missing codes in DAC?

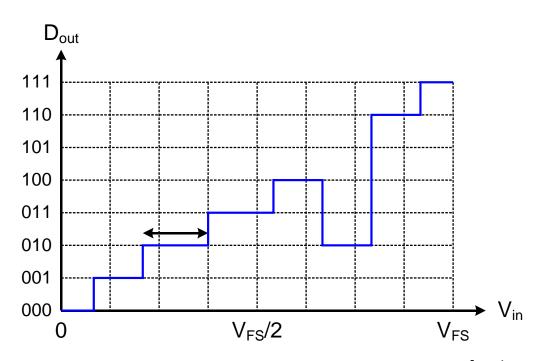
$$DNL_{i} = \frac{i^{th} Step Size - \Delta}{\Delta}$$



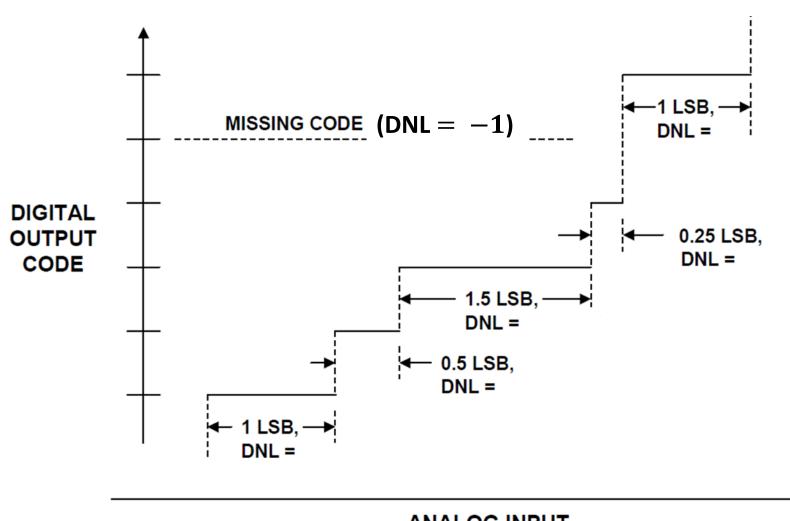
### **ADC DNL and Non-monotonicity**

- $\square$  DNL = deviation of code width from 1 LSB (=  $V_{FS}/2^N = \Delta$ )
  - Wide code → +ve DNL, narrow code → -ve DNL
- Can we characterize ADC non-monotonicity using DNL?

$$DNL_{i} = \frac{i^{th} Step Size - \Delta}{\Delta}$$



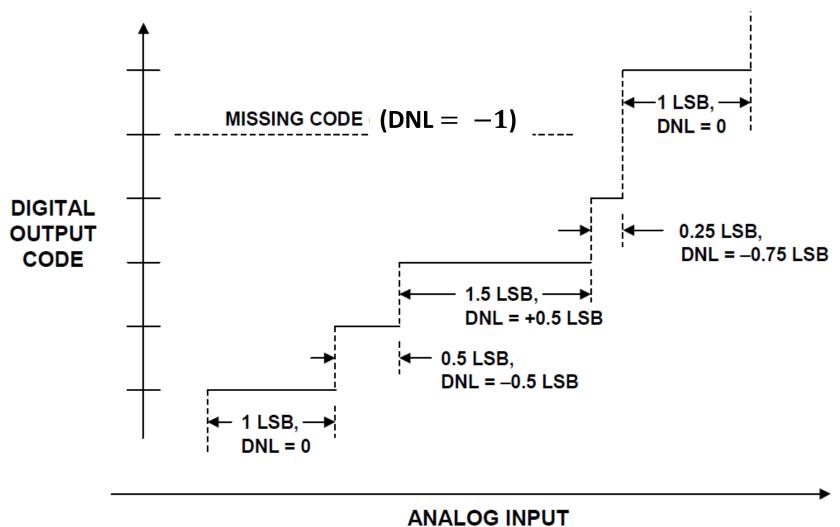
#### ADC DNL Example



**ANALOG INPUT** 

**18** 

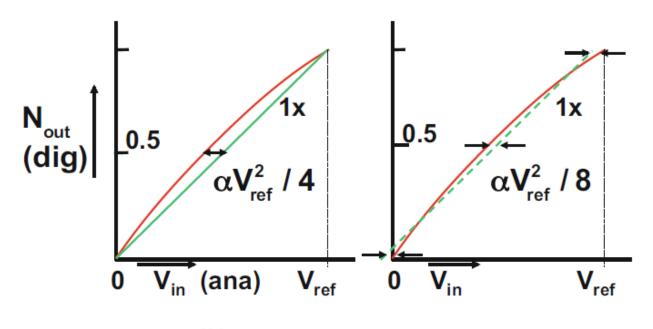
## ADC DNL Example

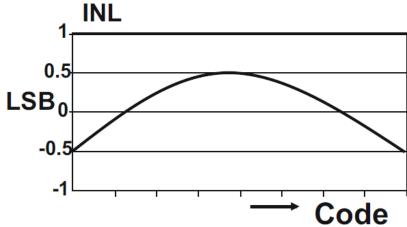


ANALOG INPO

## INL Types: 2<sup>nd</sup> Order Distortion

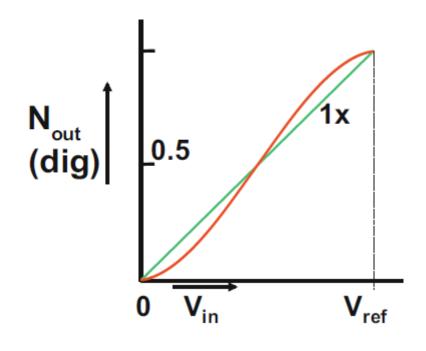
Using "best-fit" straight line will center the INL curve around zero.

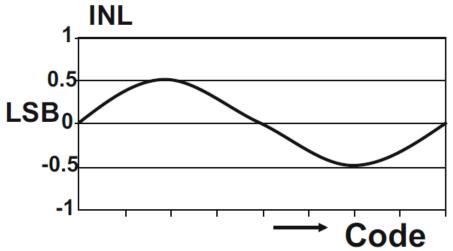




04: Specifications (1) [M. Pelgrom, 2017]

## INL Types: 3<sup>rd</sup> Order Distortion



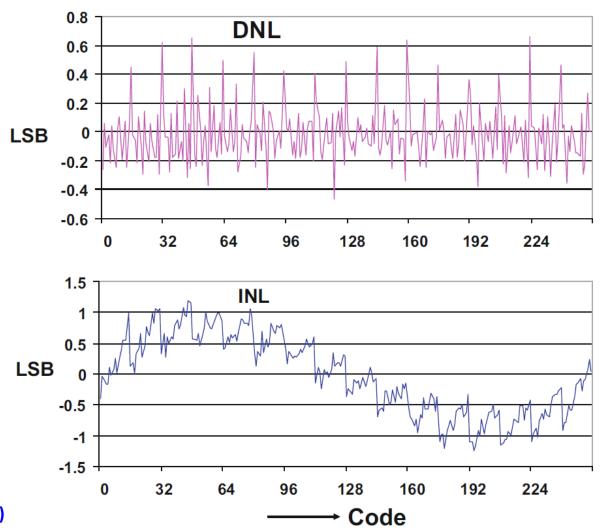


**21** 

04: Specifications (1) [M. Pelgrom, 2017]

### ADC DNL/INL Example

- ☐ DNL/INL plotted against digital code not analog input
  - More about this next lecture

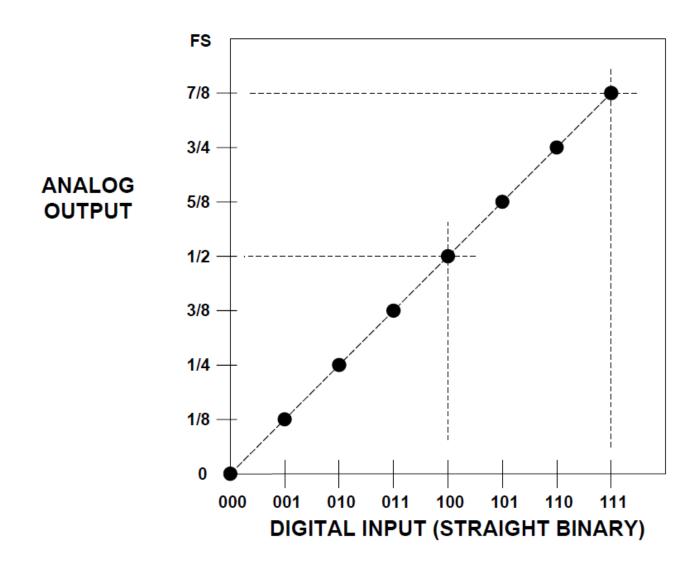


#### References

- ☐ M. Pelgrom, Analog-to-Digital Conversion, Springer, 3<sup>rd</sup> ed., 2017.
- W. Kester, The Data Conversion Handbook, ADI, Newnes, 2005.
- ☐ B. Boser and H. Khorramabadi, EECS 247 (previously EECS 240), Berkeley.
- B. Murmann, EE 315, Stanford.
- ☐ Y. Chiu, EECT 7327, UTD.

## Thank you!

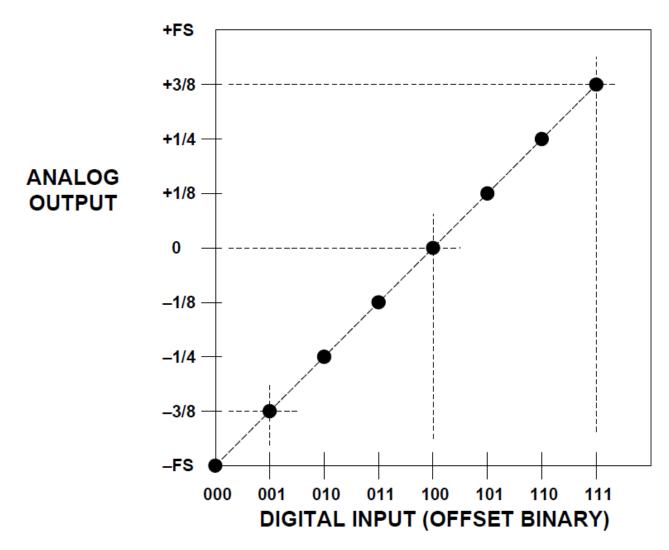
### Unipolar DAC Transfer Function



## Unipolar Code Example

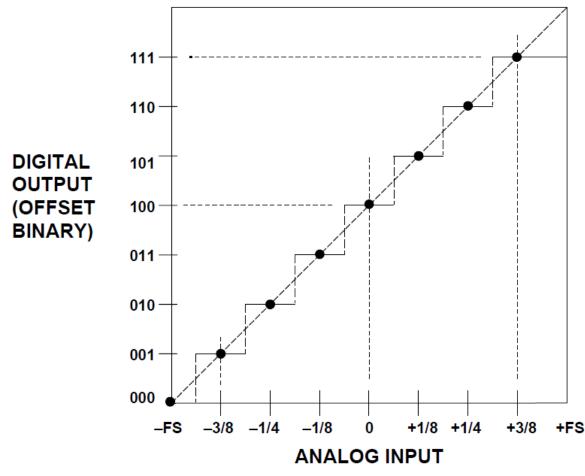
| BASE 10<br>NUMBER | SCALE                  | +10V FS | BINARY | GRAY |
|-------------------|------------------------|---------|--------|------|
| +15               | +FS - 1LSB = +15/16 FS | 9.375   | 1111   | 1000 |
| +14               | +7/8 FS                | 8.750   | 1110   | 1001 |
| +13               | +13/16 FS              | 8.125   | 1101   | 1011 |
| +12               | +3/4 FS                | 7.500   | 1100   | 1010 |
| +11               | +11/16 FS              | 6.875   | 1011   | 1110 |
| +10               | +5/8 FS                | 6.250   | 1010   | 1111 |
| +9                | +9/16 FS               | 5.625   | 1001   | 1101 |
| +8                | +1/2 FS                | 5.000   | 1000   | 1100 |
| +7                | +7/16 FS               | 4.375   | 0111   | 0100 |
| +6                | +3/8 FS                | 3.750   | 0110   | 0101 |
| +5                | +5/16 FS               | 3.125   | 0101   | 0111 |
| +4                | +1/4 FS                | 2.500   | 0100   | 0110 |
| +3                | +3/16 FS               | 1.875   | 0011   | 0010 |
| +2                | +1/8 FS                | 1.250   | 0010   | 0011 |
| +1                | 1LSB = +1/16 FS        | 0.625   | 0001   | 0001 |
| 0                 | 0                      | 0.000   | 0000   | 0000 |

#### **Bipolar DAC Transfer Function**



#### Bipolar ADC Transfer Function

- Mid-tread quantizer: The stair-case is flat around zero input
- Mid-rise quantizer: The stair-case rises at zero.



## Bipolar Code Example

| BASE 10<br>NUMBER | SCALE                 | ±5V FS | OFFSET<br>BINARY | TWOS<br>COMP. | ONES<br>COMP. | SIGN<br>MAG. |
|-------------------|-----------------------|--------|------------------|---------------|---------------|--------------|
| +7                | +FS - 1LSB = +7/8 FS  | +4.375 | 1111             | 0111          | 0111          | 0111         |
| +6                | +3/4 FS               | +3.750 | 1110             | 0110          | 0110          | 0110         |
| +5                | +5/8 FS               | +3.125 | 1101             | 0101          | 0101          | 0101         |
| +4                | +1/2 FS               | +2.500 | 1100             | 0100          | 0100          | 0100         |
| +3                | +3/8 FS               | +1.875 | 1011             | 0011          | 0011          | 0011         |
| +2                | +1/4 FS               | +1.250 | 1010             | 0010          | 0010          | 0010         |
| +1                | +1/8 FS               | +0.625 | 1001             | 0001          | 0001          | 0001         |
| 0                 | 0                     | 0.000  | 1000             | 0000          | *0 0 0 0      | *1000        |
| -1                | – 1/8 FS              | -0.625 | 0111             | 1111          | 1110          | 1001         |
| -2                | – 1/4 FS              | -1.250 | 0110             | 1110          | 1101          | 1010         |
| -3                | – 3/8 FS              | -1.875 | 0101             | 1101          | 1100          | 1011         |
| -4                | –1/2 FS               | -2.500 | 0100             | 1100          | 1011          | 1100         |
| <b>-5</b>         | −5/8 FS               | -3.125 | 0011             | 1011          | 1010          | 1101         |
| -6                | −3/4 FS               | -3.750 | 0010             | 1010          | 1001          | 1110         |
| <b>-7</b>         | – FS + 1LSB = –7/8 FS | -4.375 | 0001             | 1001          | 1000          | 1111         |

#### **DNL vs INL Errors**

- $\square$  DNL measures the uniformity of quantization steps, or incremental (local) nonlinearity
  - Small input signals are sensitive to DNL.
- INL measures the overall, or cumulative (global) nonlinearity
  - Large input signals are often sensitive to both INL and DNL.

