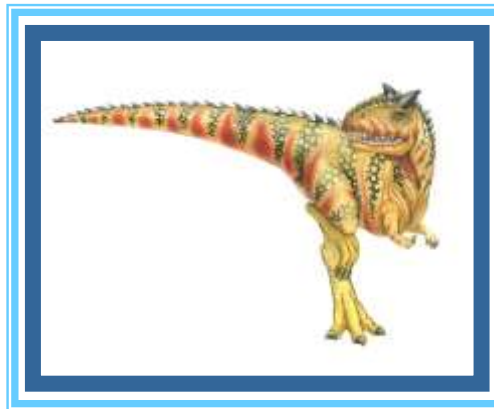


# Chapter 9: Main Memory

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# Chapter 9: Memory Management

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- Background
- Contiguous Memory Allocation
- Paging
- Structure of the Page Table
- Swapping
- Example: The Intel 32 and 64-bit Architectures
- Example: ARMv8 Architecture





# Objectives

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- To provide a detailed description of various ways of organizing memory hardware
- To discuss various memory-management techniques,
- To provide a detailed description of the Intel Pentium, which supports both pure segmentation and segmentation with paging





# Background

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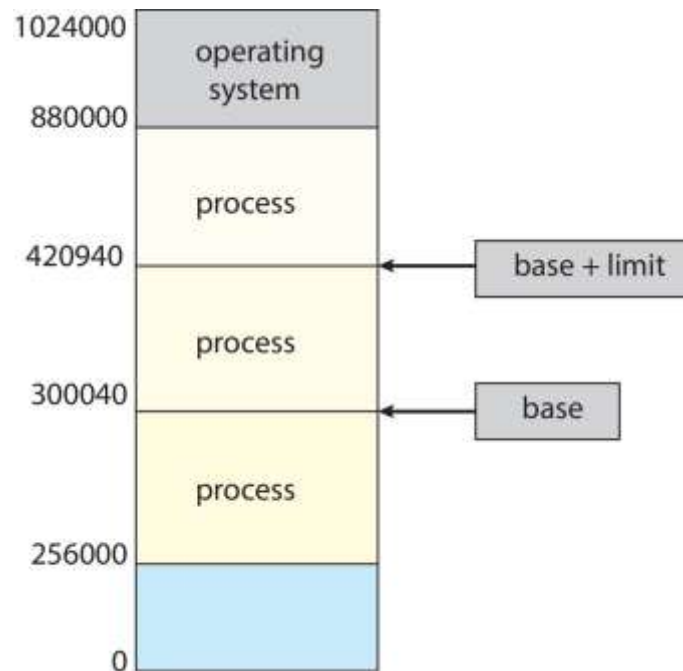
- Program must be brought (from disk) into memory and placed within a process for it to be run
- Main memory and registers are the only storage CPU can access directly
- Memory unit only sees a stream of:
  - addresses + read requests, or
  - address + data and write requests
- Register access is done in one CPU clock (or less)
- Main memory can take many cycles, causing a **stall**
- **Cache** sits between main memory and CPU registers
- Protection of memory required to ensure correct operation





# Protection

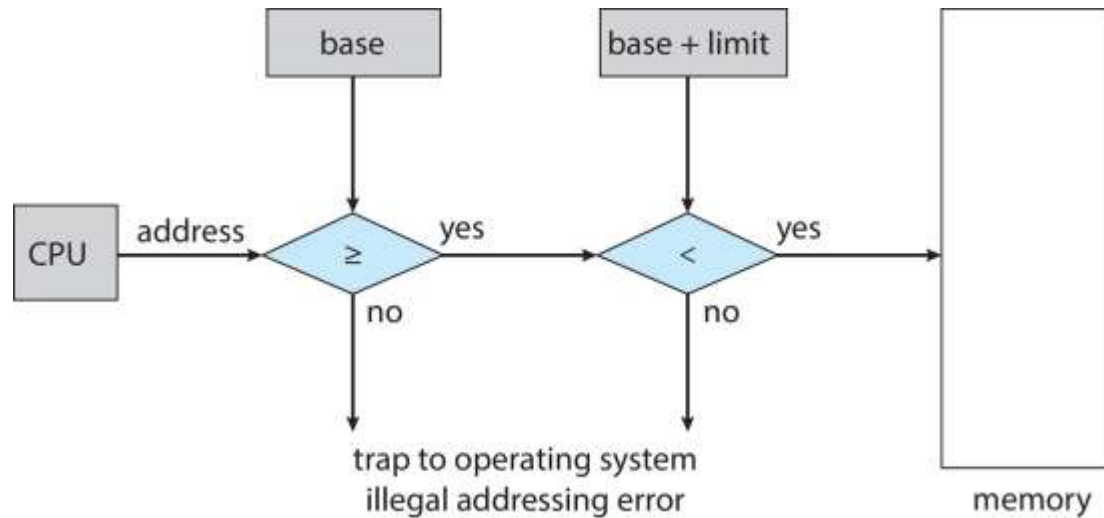
- Need to ensure that a process can access only those addresses in its address space.
- We can provide this protection by using a pair of **base** and **limit registers** to define the logical address space of a process





# Hardware Address Protection

- CPU must check every memory access generated in user mode to be sure it is between base and limit for that user



- the instructions to loading the base and limit registers are privileged





# Address Binding

- Programs on disk, ready to be brought into memory to execute form an **input queue**
  - Without support, must be loaded into address 0000
- Inconvenient to have first user process physical address always at 0000
  - How can it not be?
- Addresses represented in different ways at different stages of a program's life
  - Source code addresses usually symbolic
  - Compiled code addresses **bind** to relocatable addresses
    - 4 i.e., “14 bytes from beginning of this module”
  - Linker or loader will bind relocatable addresses to absolute addresses
    - 4 i.e., 74014
  - Each binding maps one address space to another





# Binding of Instructions and Data to Memory

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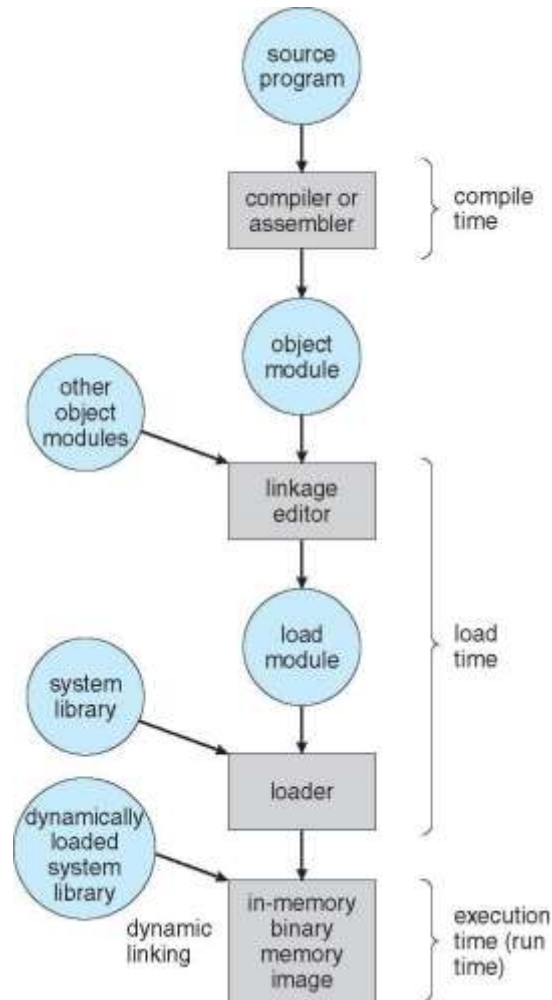
- Address binding of instructions and data to memory addresses can happen at three different stages
  - **Compile time:** If memory location known a priori, **absolute code** can be generated; must recompile code if starting location changes
  - **Load time:** Must generate **relocatable code** if memory location is not known at compile time
  - **Execution time:** Binding delayed until run time if the process can be moved during its execution from one memory segment to another
    - 4 Need hardware support for address maps (e.g., base and limit registers)







# Multistep Processing of a User Program





# Logical vs. Physical Address Space

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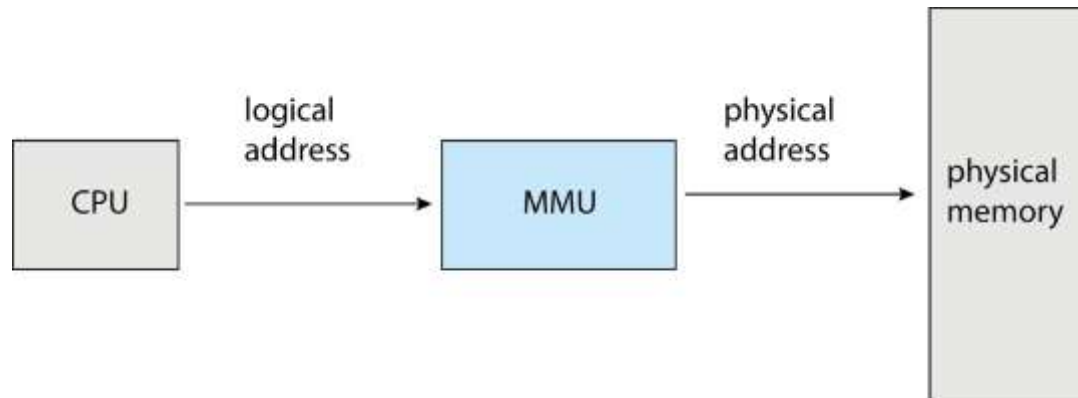
- The concept of a logical address space that is bound to a separate **physical address space** is central to proper memory management
  - **Logical address** – generated by the CPU; also referred to as **virtual address**
  - **Physical address** – address seen by the memory unit
- Logical and physical addresses are the same in compile-time and load-time address-binding schemes; logical (virtual) and physical addresses **differ in execution-time address-binding scheme**
- **Logical address space** is the set of all logical addresses generated by a program
- **Physical address space** is the set of all physical addresses generated by a program





# Memory-Management Unit (MMU)

- Hardware device that at run time maps virtual to physical address



- Many methods possible, covered in the rest of this chapter





# Memory-Management Unit (Cont.)

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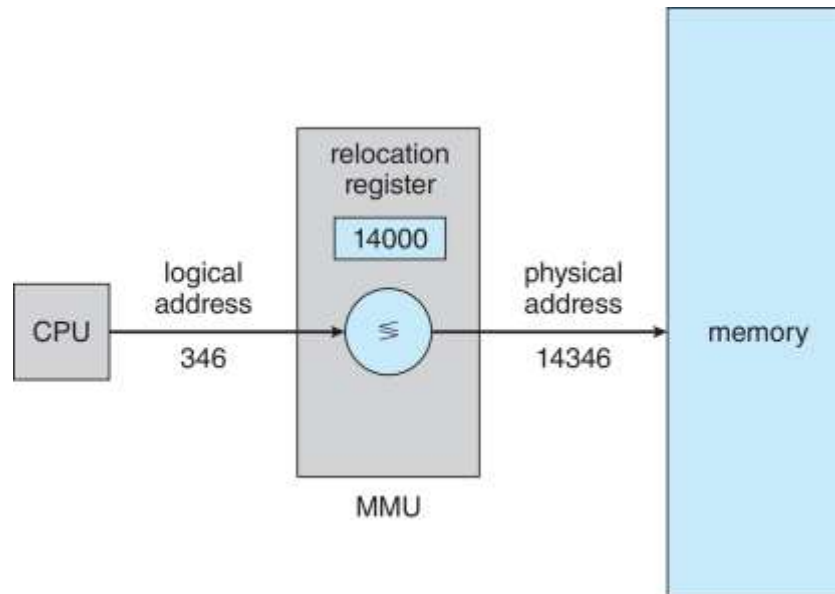
- Consider a simple scheme. Which is a generalization of the base-register scheme.
- The base register, now called the **relocation register**
- The value in the relocation register is added to every address generated by a user process at the time it is sent to memory
- The user program deals with **logical addresses**; it never sees the *real* **physical addresses**
  - Execution-time binding occurs when reference is made to a location in memory
  - **Logical address** bound to **physical addresses** in **Execution time**





# Memory-Management Unit (Cont.)

- Consider simple scheme, which is a generalization of the base-register scheme.
- The base register now called **relocation register**
- The value in the relocation register is added to every address generated by a user process at the time it is sent to memory





# Dynamic Loading

- The entire program does need to be in memory to execute
- Routine is not loaded until it is called
- Better memory-space utilization; **unused routine is never loaded**
- **All routines kept on disk in relocatable load format**

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**Relocatable Code:** This code is not bound to a specific memory address. When a program is compiled, the compiler generates **object code** with addresses **starting at some base location**, often zero. This object code is considered relocatable because it can be placed at any point in memory.

- Useful when large amounts of code are needed to handle infrequently occurring cases
- No special support from the operating system is required
  - Implemented through program design
  - OS can help by providing libraries to implement dynamic loading





# Dynamic Linking

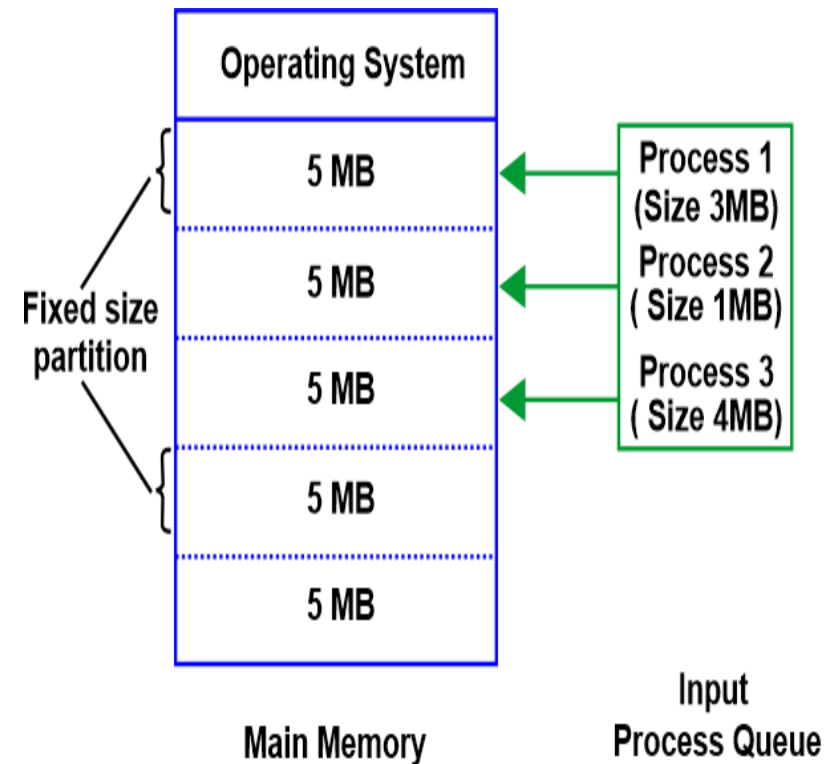
- **Static linking** – system libraries and program code combined by the loader into the **binary program image**
- **Dynamic linking** – linking **postponed** until execution time
- Small piece of code, **stub**, used to locate the appropriate memory-resident library routine
- Stub replaces itself with the address of the routine and executes the routine
- The operating system checks if the routine is in the processes' memory address
  - If not in address space, add to address space
- Dynamic linking is particularly useful for libraries
- System also known as **shared libraries**
- Consider applicability to patching system libraries
  - Versioning may be needed





# Contiguous Allocation

- Main memory must support both OS and user processes
- Limited resource, must allocate efficiently
- Contiguous allocation is one early method
- Main memory usually into two **partitions**:
  - Resident **operating system**, usually held in **low memory** with interrupt vector
  - User processes then held in high memory
  - Each process contained in single contiguous section of memory







# Contiguous Allocation (Cont.)

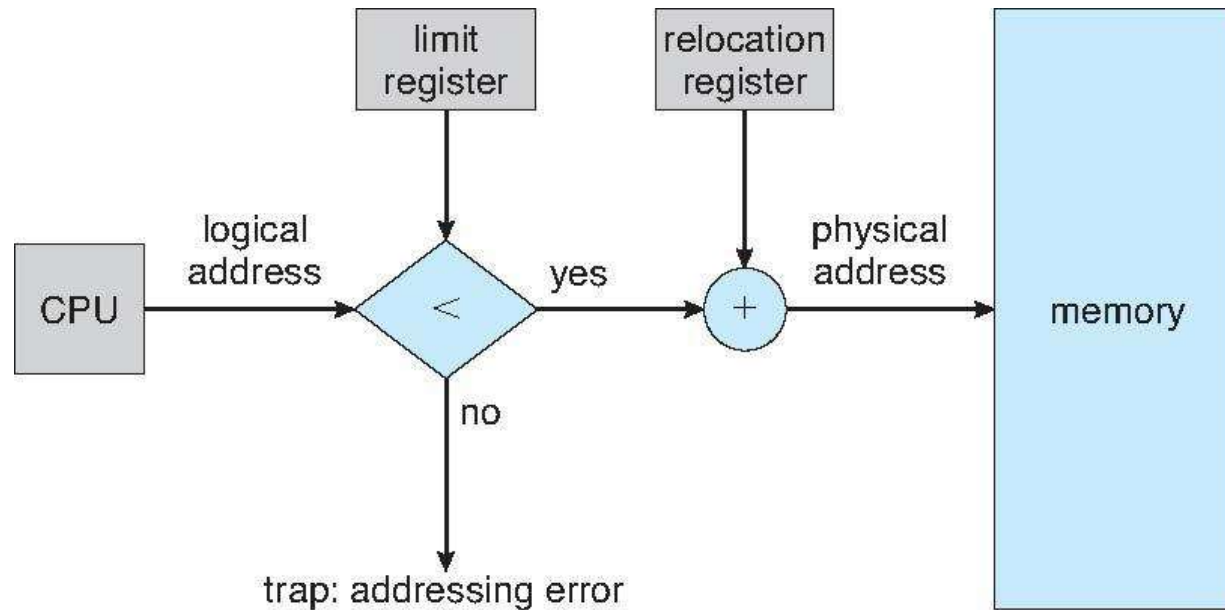
- **Relocation registers** used to protect user processes from each other, and from changing operating-system code and data
  - **Base register** contains value of **smallest physical address**
  - Limit register contains range of logical addresses – each logical address must be less than the limit register
  - MMU maps logical address *dynamically*
  - Can then allow actions such as kernel code being **transient** and kernel changing size

**The concept of transient kernel** code allows an operating system's **kernel to load and unload code dynamically**, enabling it to change size and adapt to the system's needs without requiring a full reboot.





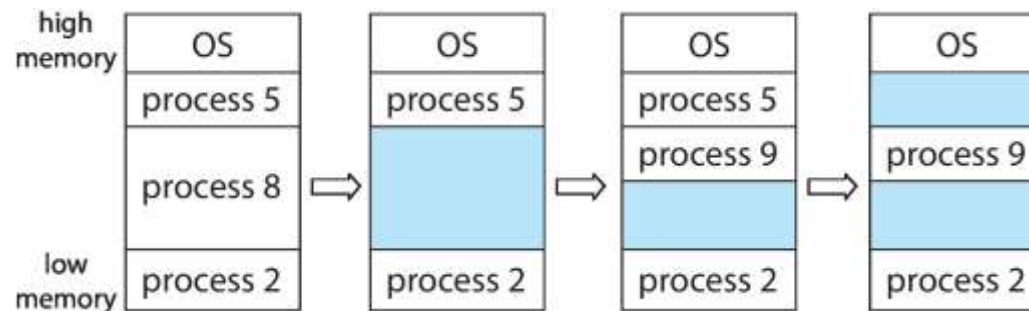
# Hardware Support for Relocation and Limit Registers





# Variable Partition

- Multiple-partition allocation
  - Degree of multiprogramming limited by number of partitions
  - **Variable-partition** sizes for efficiency (sized to a given process' needs)
  - **Hole** – block of available memory; holes of various size are scattered throughout memory
  - When a process arrives, it is allocated memory from a hole large enough to accommodate it
  - Process exiting frees its partition, adjacent free partitions combined
  - Operating system maintains information about:
    - a) allocated partitions
    - b) free partitions (hole)





# Dynamic Storage-Allocation Problem

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How to satisfy a request of size  $n$  from a list of free holes?

- **First-fit:** Allocate the **first** hole that is big enough
- **Best-fit:** Allocate the **smallest** hole that is big enough; must search entire list, unless ordered by size
  - Produces the smallest leftover hole
- **Worst-fit:** Allocate the **largest** hole; must also search entire list
  - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization





# Fragmentation

- **What is Fragmentation?**

**Small non utilized fragmented memory spaces that are so small due to which normal processes can not fit into them.**

- **External Fragmentation** – total memory space exists to satisfy a request, but it is not contiguous

When the memory space in the system can easily satisfy the requirement of the processes, but this available memory space is non-contiguous, So it can't be utilized further. Then this problem is referred to as External Fragmentation.

- **Internal Fragmentation** – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used
- First fit analysis reveals that given  $N$  blocks allocated,  $0.5 N$  blocks lost to fragmentation
  - $1/3$  may be unusable -> **50-percent rule**





# Fragmentation (Cont.)

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- Reduce external fragmentation by **compaction**
  - Shuffle memory contents to place all free memory together in one large block
  - **Compaction** is possible *only* if relocation is dynamic, and is done at execution time
  - I/O problem
    - 4 Latch job in memory while it is involved in I/O
    - 4 Do I/O only into OS buffers
- Now consider that backing store has same fragmentation problems





# Paging

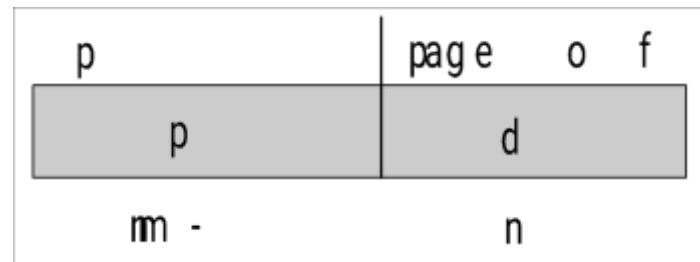
- Physical address space of a process can be **noncontiguous**; process is allocated physical memory whenever the latter is available
  - Avoids external fragmentation
  - Avoids problem of varying sized memory chunks
- Divide physical memory** into fixed-sized blocks called **frames**
  - Size is power of 2, between 512 bytes and 16 Mbytes
- Divide logical memory into blocks of same size called **pages**
- Keep track of all free frames
- To run a program of size  **$N$**  pages, need to find  **$N$**  free frames and load program
- Set up a **page table** to translate logical to physical addresses
- Backing store** likewise split into pages
- Still have Internal fragmentation





# Address Translation Scheme

- Address generated by CPU is divided into:
  - **Page number** ( $p$ ) – used as an index into a **page table** which contains base address of each page in physical memory
  - **Page offset** ( $d$ ) – combined with base address to define the physical memory address that is sent to the memory unit



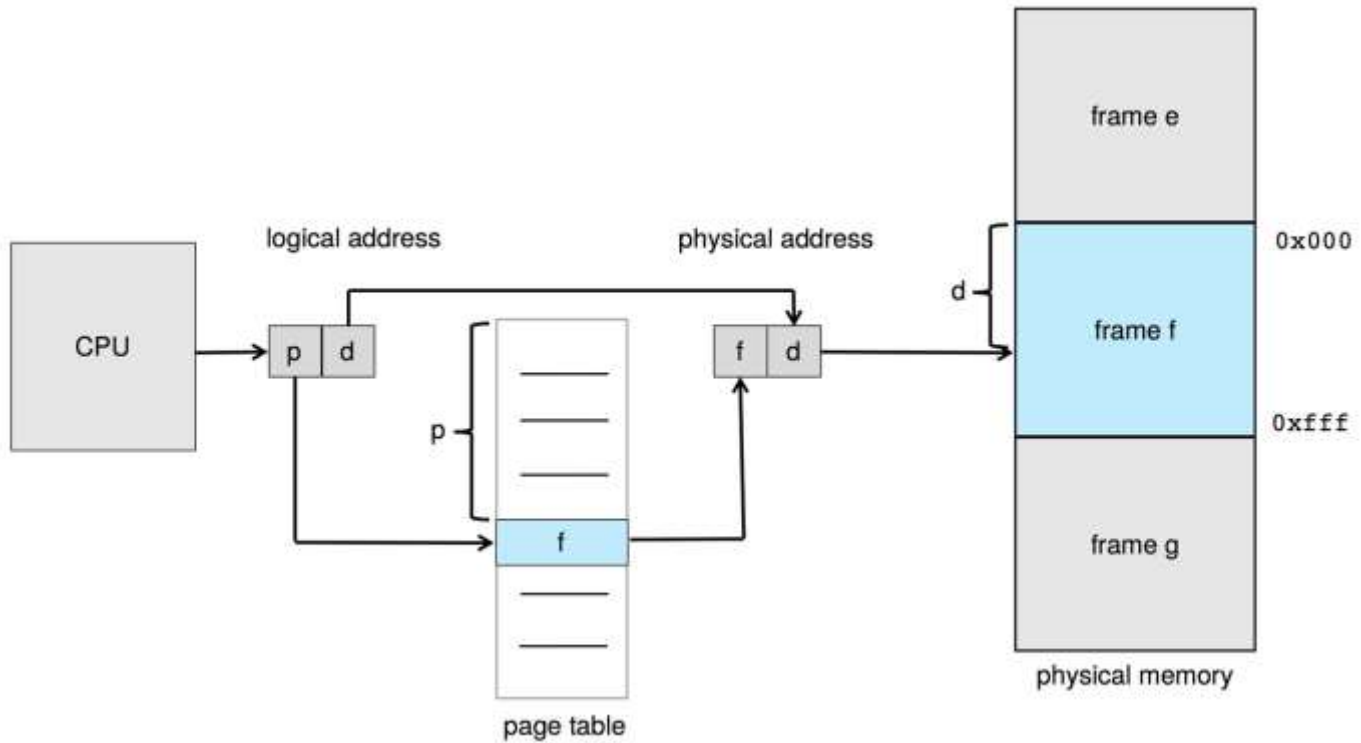
- For given logical address space  $2^m$  and page size  $2^n$





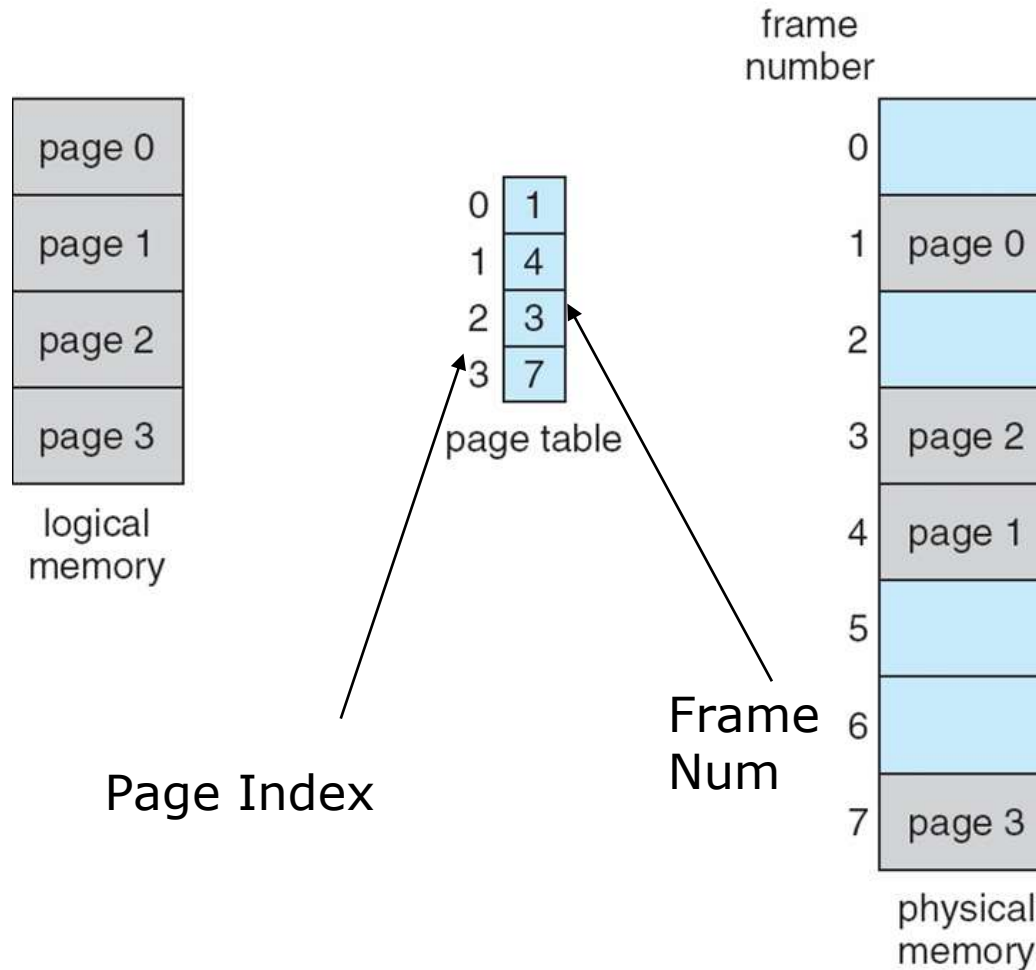


# Paging Hardware





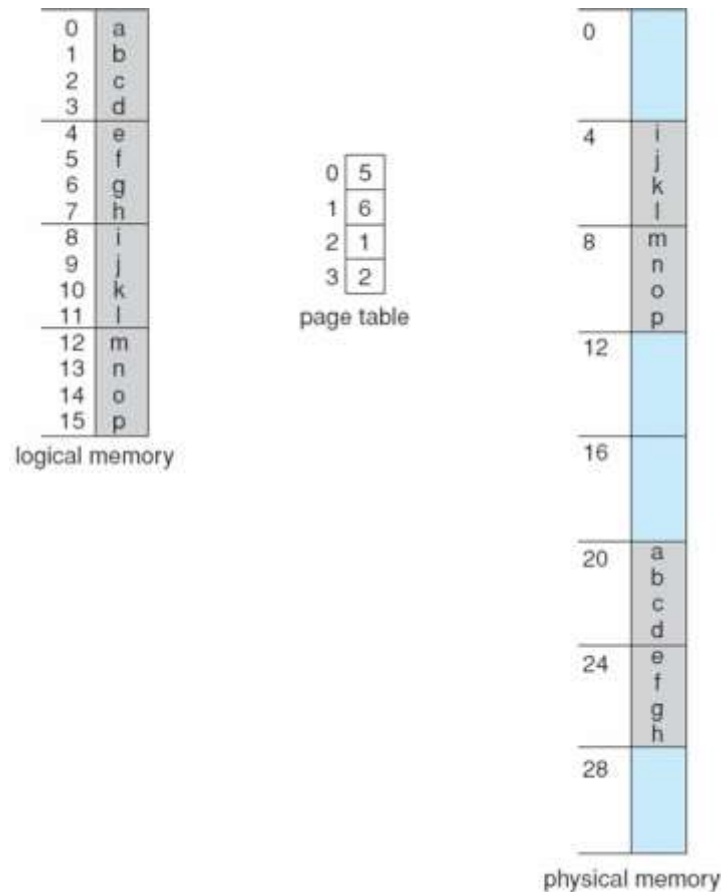
# Paging Model of Logical and Physical Memory





# Paging Example

- Logical address:  $n = 2$  and  $m = 4$ . Using a page size of 4 bytes and a physical memory of 32 bytes (8 pages)





# Paging -- Calculating internal fragmentation

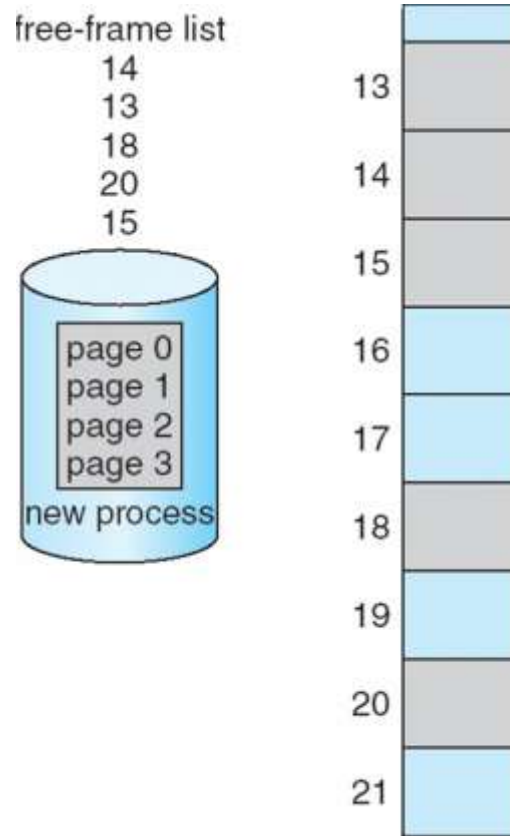
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- Page size = 2,048 bytes
- Process size = 72,766 bytes
- 35 pages + 1,086 bytes
- Internal fragmentation of  $2,048 - 1,086 = 962$  bytes
- Worst case fragmentation = 1 frame – 1 byte
- On average, fragmentation =  $1 / 2$  frame size
- So small frame sizes desirable? Decrease fragmentation
- But each page table entry takes memory to track
- Page sizes growing over time
  - Solaris supports two-page sizes – 8 KB and 4 MB



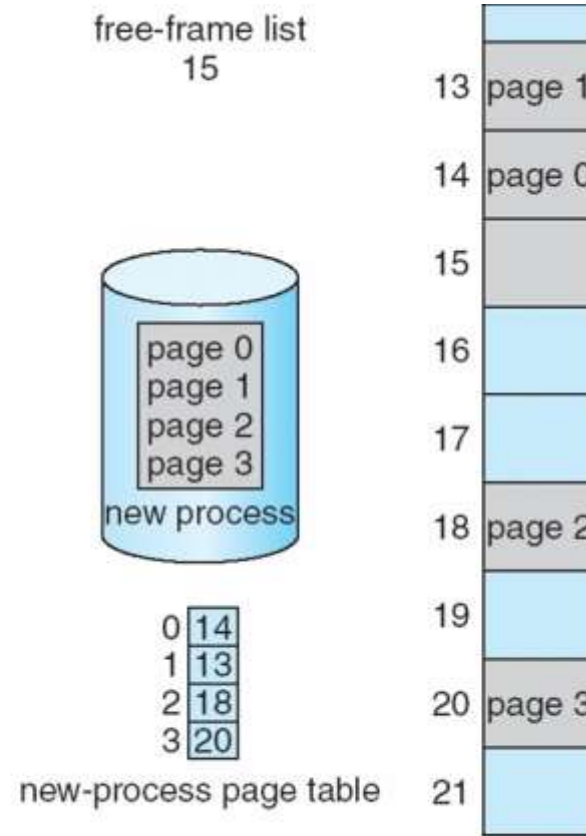


# Free Frames



(a)

Before allocation



(b)

After allocation





# Implementation of Page Table

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- Page table is kept in main memory
  - **Page-table base register (PTBR)** points to the page table
  - **Page-table length register (PTLR)** indicates size of the page table
- In this scheme every data/instruction access requires two memory accesses
  - One for the page table and one for the data / instruction
- The two-memory access problem can be solved by the use of a special fast-lookup hardware cache called **translation look-aside buffers (TLBs)** (also called **associative memory**).



# End of Chapter 9

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