# Task\_1

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# **Perceptron:**

#### **Different Features:**

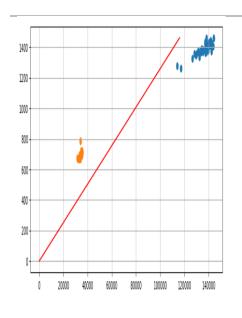
#### Hyperparameters

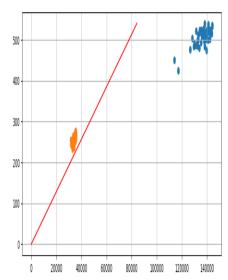
Class = Bombay, C2 = Cali, eta = 0.001, epochs = 150, b = False

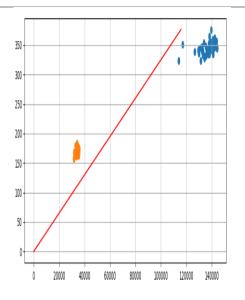
#### **Features**

F1 = Area, F2 = Perimeter F1 = Area, F2 = MajorAxisLength F1 = Area, F2 = MinorAxisLength

#### Visualization







Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

# **Analysis**

Perceptron algorithm managed to discriminate between different features all in one epoch with an accuracy of 100% as all of them are linearly separable as none of them took all the epochs.

### **Different Classes:**

### Hyperparameters

F1 = Area, F2 = Perimeter, eta = 0.001, epochs = 150, b = True

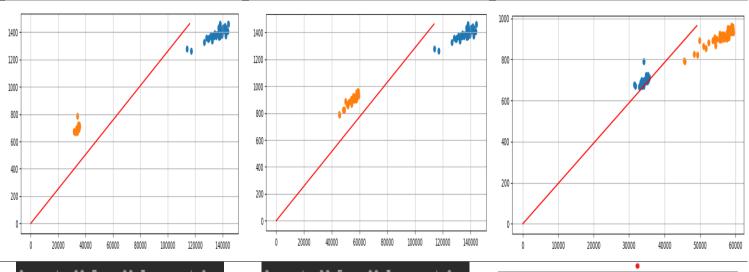
### Classes

C1 = Bombay, C2 = Cali

C1 = Bombay, C2 = Sira

**C1** = **Sira**, **C2** = **Cali** 

#### Visualization



Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 19 From 20 Incorrect 1

accuracy: 97.5

# **Analysis**

The second case shows that the accuracy is 97.5% and it took all the epochs which means the model needs more epochs to discriminate well or these features with these classes are not linearly separable.

# Different eta:

### Hyperparameters

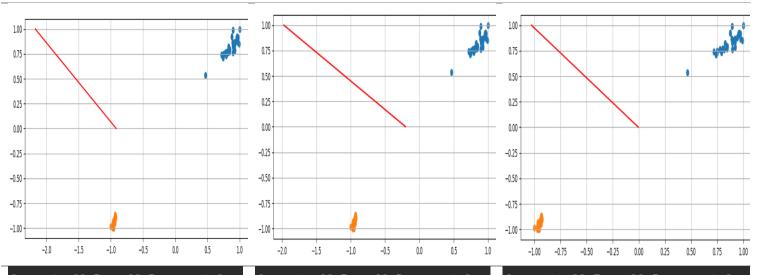
F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, m = 150, b = True

#### Eta

Eta = 0.2 Eta = 0.5

Eta = 20

#### Visualization



Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

# **Analysis**

Changing the learning rate affects how fast the model reaches the local minimum as shown when the eta is too small it takes more epochs to reach the local minimum.

## **Different epochs:**

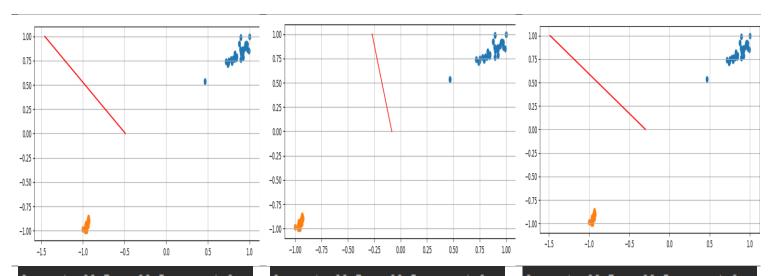
### Hyperparameters

F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, eta = 0.001, b = True

# **Epochs**

M = 10 M = 100

#### Visualization



Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

M = 1000

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

# **Analysis**

Changing the number of epochs affects the accuracy if it's too small the model may need more epochs to be well-trained.

## Different bias:

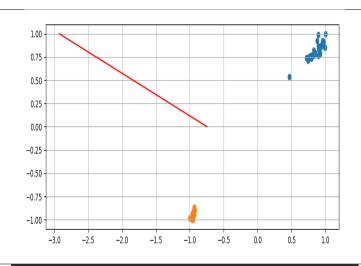
# Hyperparameters

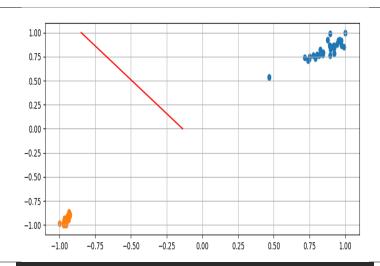
F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, eta = 0.01, m = 150

#### Bias

B = False B = True

#### Visualization





Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

Correct: 20 From 20 Incorrect 0

Correct: 20 From 20 Incorrect 0

accuracy: 100.0

# **Analysis**

Adding bias to the model affects the accuracy. Sometime the model train better with bias.

# **Adaline:**

# **Different Features:**

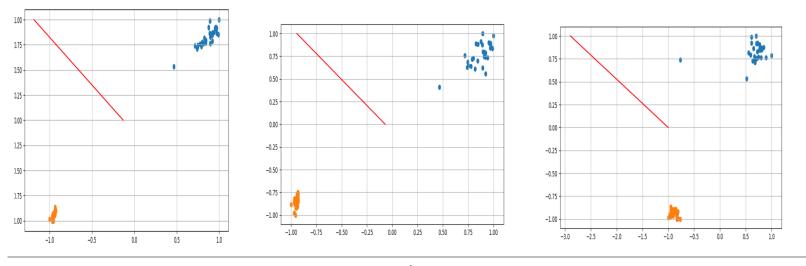
# Hyperparameters

C1 = Bombay, C2 = Cali, eta = 0.01, m = 150, b = 0, MSE = 0.01

#### **Features**

F1 = Area, F2 = Perimeter F1 = Area, F2 = MajorAxisLength F1 = MinorAxisLength, F2 = Perimeter

#### Visualization



# **Analysis**

Adaline algorithm managed to discriminate between different features all in one epoch with an accuracy of 100% as all of them are linearly separable.

# **Different Classes:**

## Hyperparameters

F1 = Area, F2 = Perimeter, eta = 0.01, m = 150, b = True, MSE = 0.01

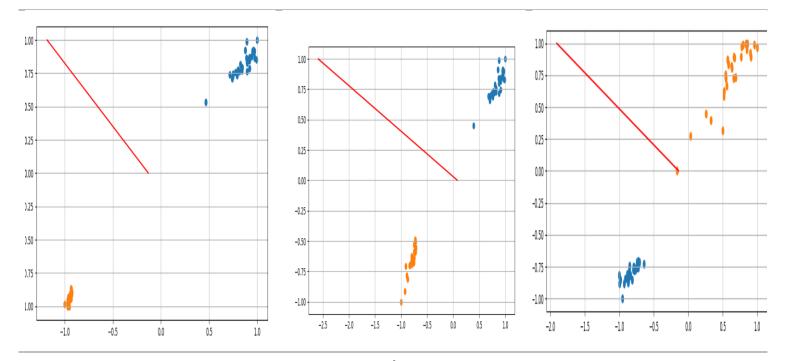
# Classes

C1 = Bombay, C2 = Cali

C1 = Bombay, C2 = Sira

C1 = Cali, C2 = Sira

# Visualization



# **Analysis**

The second case shows that the accuracy is 98% and it took all the epochs which means the model needs more epochs to learn or these two classes aren't linearly separable.

# **Different eta:**

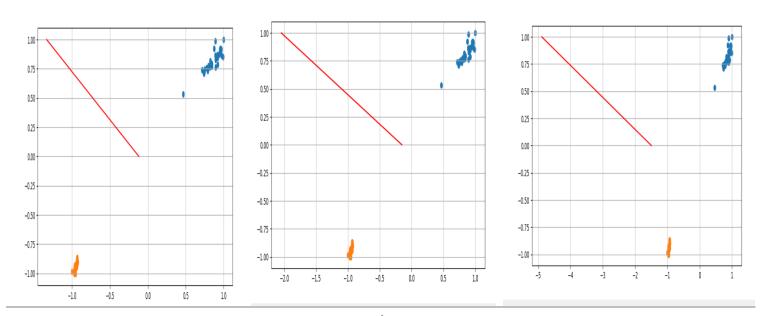
# Hyperparameters

F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, m = 150, b = True, MSE = 0.01

#### Eta

Eta = 0.1 Eta = 0.01 Eta = 0.00001

### Visualization



# **Analysis**

Changing the learning rate affects how fast the model reaches the local minimum as shown when the eta is too small it takes more epochs to reach the local minimum.

# **Different epochs:**

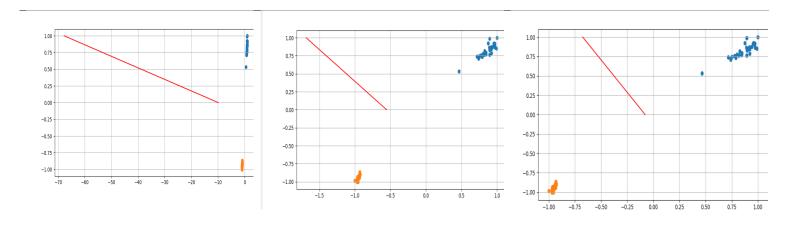
# Hyperparameters

F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, eta = 0.01, b = True, MSE = 0.01

# **Epochs**

M = 10 M = 100 M = 1000

## Visualization



# **Analysis**

Every time the model takes all the epochs because of 2 outliers from the given classes or they aren't linearly separable.

# **Different bias:**

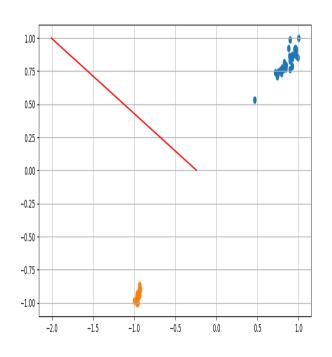
# Hyperparameters

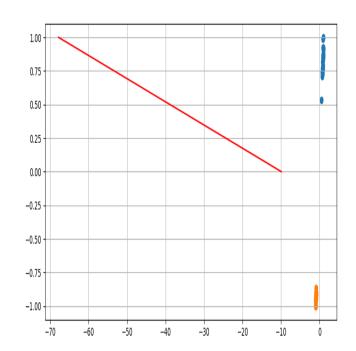
F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, eta = 0.01, m = 150, MSE = 0.01

### Bias

B = False B = True

## Visualization





# **Analysis**

Adding bias to the model affects the accuracy. Sometimes the model trains better with bias, in this case it didn't affect the accuracy but it took less epochs (faster convergence).

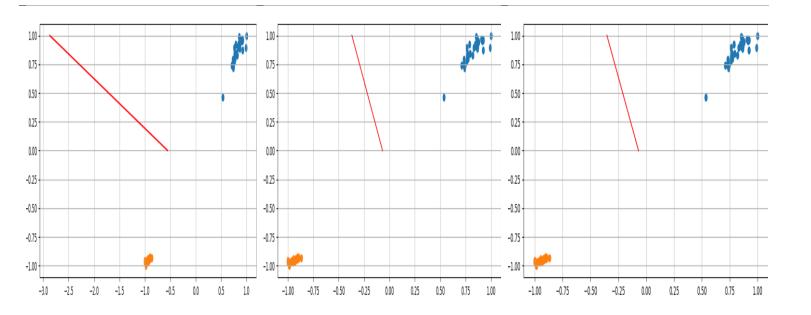
# **Different MSE:**

# Hyperparameters

F1 = Area, F2 = Perimeter, C1 = Bombay, C2 = Cali, m = 150, b = True, eta = 0.01

## **MSE**

## Visualization



# **Analysis**

Achieving lower MSE requires more training epochs.

# **Conclusion**

In general, Adaline is an improvement as it solves the problem of cost function by using Mean Square Error while Perceptron doesn't have a cost function to stop and might lead to an infinite loop in case of non-linearly separable data because it stops only in case of zero error.