

view_frames Result

Recorded at time: 1379.796

odom

Broadcaster: /gazebo
Average rate: 10.208 Hz
Most recent transform: 1379.701 (0.095 sec old)
Buffer length: 4.800 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1379.796 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1379.796 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1379.796 sec old)
Buffer length: 0.000 sec

camera_depth

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1379.796 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.206 Hz
Most recent transform: 1379.701 (0.095 sec old)
Buffer length: 4.801 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.206 Hz
Most recent transform: 1379.701 (0.095 sec old)
Buffer length: 4.801 sec

right_wheel