# Lecture 2

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## 1 Definitions and Terminology

**Definition 1.1.** The order of a differential equation is the order of the highest derivative, ordinary or partial, in the equation.

#### Example 1.1.

$$ay''' + by'' = f(t)$$

This is a 3<sup>rd</sup> order ODE.

#### Example 1.2.

$$u_t = \frac{d}{dx}(u_x + y_y + u_z)$$

This is a 1<sup>st</sup> order PDE.

**Definition 1.2.**  $u^{(n)}$  refers to the n<sup>th</sup> derivative of u.

The most general equation of an n<sup>th</sup> order derivative ODE is:

$$F[t, u, u', u'', \dots, u^{(n)}] = 0$$

**Definition 1.3.** We say an n<sup>th</sup> order ODE is linear if it can be expressed as

$$a_0(t)u(t) + a_1(t)u'(t) + \dots + a_n(t)u^{(n)}(t) = g(t)$$

If g(t) = 0 for all t, the equation is homogeneous, otherwise it is nonhomogeneous.

**Example 1.3.** Are the following differential equations linear? If so, are they homogeneous or not?

• 
$$t\sin(t^3)u + 56u''' + t^4 = 0$$

• 
$$t^3u''' + et^2u'' + 4u = 0$$

$$\bullet \ tu + 5\sqrt{u'} + 10\sin(u) = 0$$

The first equation is linear nonhomogeneous, due to the  $t^4$  term. The second equation is linear homogeneous, and the third equation is non linear, due to the second and third terms.

How could we extend these definitions to PDEs? Consider

$$a_0(x,y)u_x + a_1(x,y)u_y + a_2(x,y)u_{xx} + a_3(x,y)u_{xy} + a_4(x,y)u_{yx} + a_5(x,y)u_{yy} + a_6(x,y)u = g(x,y)u_{xy} + a_5(x,y)u_{xy} +$$

This is a linear equation. If  $g(x,y) = 0 \forall x,y$ , it is homogeneous.

**Definition 1.4.** An ODE is *autonomous* if it does not explicitly depend on the independent variable.

**Example 1.4.** • 
$$\frac{dy}{dt} = \sin(y) + y^3 \ln(y) + e^y$$

• 
$$\frac{dy}{dt} = y'\cos(y) + \frac{y^2}{1+e^y}$$

Does there exist a linear autonomous nonhomogeneous ODE? Consider

$$y + y' = 1$$

For it to be nonhomogeneous, a g(t) must exist. It must be independent of t, so it can only be a constant (since g'(t) must be 0).

**Definition 1.5.** A first order ODE is separable if it can be expressed as

$$\frac{du}{dt} = f(u)g(t)$$

**Example 1.5.** Which of the following equations are separable?

- $\frac{dx}{dt} = t^2 + \frac{\arccos(t)}{\ln(t)}$
- $u'' = ut^2e^t$
- $\frac{du}{dt} = \frac{1}{2} \left( \sin(u+t) \sin(u-t) \right) + \sin(t)$

Yes, no (second order), no, yes (trig identity).

## 2 Systems of Differential Equations

This occurs when two or more dependent variables interact with one another.

**Example 2.1.** The Lotka-Volterra equations for a predator-prey model. The assumptions are that the prey will only die when eaten, and predators either naturally die or relocate.

 $u_1(t)$ : Population count of prey

 $u_2(t)$ : Population count of predator

Considering the birth and death of prey,

$$\frac{du_1}{dt} = \alpha u_1 - \beta u_1 u_2$$

Considering the birth and death of predators,

$$\frac{du_2}{dt} = \gamma u_1 u_2 - \delta u_2$$

Intuition tells us that this should be a system of periodic functions, with  $u_2$  lagging behind  $u_1$ .

### 3 Initial Value Problems

In general, is one initial value enough?

No, it depends on the order. E.g. a second order ODE requires 2 initial values.

Example 3.1. Consider

$$\frac{d^2u}{dt^2} = 0$$

Integrating both sides with respect to t, we have

$$\frac{du}{dt} = C_0$$

and integrating again gives us

$$u = C_0 t + C_1$$

Therefore, two initial values are required to solve for the two constants.

**Definition 3.1.** An initial value problem for an  $n^{th}$  order ODE consists of the ODE itself and n initial conditions.

$$u(t_0) = a_0, u'(t_0) = a_1, \dots, u^{(n-1)}(t_0) = a_{n-1}$$