Lecture 14

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1 Stokes' Theorem

Using the previous example from the last lecture, we observe that Stokes' Theorem guarantees that the integral is the same for different surfaces, as long as they are bounded by the same curve. Therefore, we try the surface on the xy plane.

$$I = \iint_{S'} (2\hat{i} + 3\hat{j} + 4\hat{k}) \cdot \hat{k}dS$$
$$= 4 \iint_{S'} dS$$
$$= 4\pi 3^{2}$$
$$= 36\pi$$

2 Divergence Theorem

Theorem 2.1. Suppose E is a solid region bounded by the closed surface S with positive (outward) orientation. Let \vec{F} be a vector field whose component functions have continuous first partial derivatives in E, then

$$\iint_{S} \vec{F} \cdot \vec{n} dS = \iiint_{E} \left(\vec{\nabla} \cdot \vec{F} \right) dV$$

Example 2.1. Compute the flux of the vector field

$$\vec{F}(x,y,z) = z\hat{i} + y\hat{j} + x\hat{k}$$

over the unit sphere $x^2 + y^2 + z^2 = 1$ using the divergence theorem.

$$\iint_{S} \vec{F} \cdot \vec{n} dS = \iiint_{V} \left(\vec{\nabla} \cdot \vec{F} \right) dV$$
$$= \iiint_{V} dV$$
$$= \frac{4}{3}\pi$$

3 Fluid Mechanics

Calculus is over!

Liquids and gases called *fluids*, as they deform easily without permanent changes. Under an external load,

- A solid changes in shape and eventually comes to a stop when it reaches the angle of deformation
- Fluid in contact with a solid boundary sticks to it

The second property is called the **NO SLIP CONDITION**.

Definition 3.1. A fluid is a substance that deforms continuously under the application of a tangential force.

There are 2 approaches to studying fluid mechanics, which is the statistical or continuum approach. The continuum approach is more conventinal, and depends on the Knudsen number

$$\frac{\rm microscopic\ length\ scale}{\rm macroscopic\ length\ scale} << 1$$

The continuum assumption does not hold for

- Tiny passages, e.g. blood flow in micro-vessels
- Granular flow, e.g. flow of salt grains
- Spacecraft entering Earth's atmosphere
- Flows with shock waves, e.g. supersonic bullet

Force on fluid particles include

- Body Forces: developed without physical contact, e.g. gravity
- Surface Forces: developed with physical contact, e.g. friction

The stress tensor is denoted as σ_{xy} where x is the surface of application and y is the direction of action.