Early and Revocable Time Series Classification: Supplementary material

This document gives further details on experiments presented in our paper, Section 1 shows that the percentage of samples for which a revocation is useful is relatively low, that demonstrates that the tackled problem is hard, then Section 2 presents results of the Friedmann test comparing the two proposed approaches, Section 3 shows the pareto curves for additional values of β and finally experiments on multi-class classification problems are presented in Section 4.

1 Percentage of samples for which a revocation is useful

This section is an extension to Section 5.5 in our paper, In order to check if the cost paid by the user can be improved by revoking the decision made by the irrevocable regime, statistics about results of Economy- γ were computed. Figure 6 shows the percentage of samples for which the score paid by the user can be improved by revoking the decision of Economy- γ for each dataset and α value.

These statistics show that decisions can be successfully revoked on very few samples which makes the *early* and revocable time series classification problem difficult to solve, because the algorithm needs to identify those samples using incomplete knowledge of the time series in order to revoke the decision on them and keep the decision of the irrevocable regime on the other samples.

| Datasets | 0.0001 | 0.0003 | 0.0005 | 0.0008 | 0.001 | 0.0025 | 0.005 | 0.0075 | 0.01 | 0.025 | 0.05 | 0.075 | 0.1 | 0.25 | 0.5 | 0.75 | 1 |
|-------------------------------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| CBF | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 1.075 | 2.151 | 3.226 | 3.226 | 4.659 | 5.018 | 6.452 |
| ChlorineConcentration | 12.142 | 12.142 | 12.142 | 12.142 | 12.142 | 12.142 | 12.142 | 12.142 | 12.142 | 16.705 | 12.142 | 18.097 | 20.65 | 21.036 | 21.346 | 23.279 | 23.511 |
| CinCECGTorso | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 1.174 | 0.939 | 1.643 | 1.643 | 1.643 |
| Crop | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.139 | 0.139 | 0.139 | 0.139 | 0.153 | 0.417 | 0.486 | 0.5 | 1.014 | 3.681 | 3.681 | 3.681 |
| ECG5000 | 0.267 | 0.267 | 0.267 | 0.267 | 0.267 | 0.267 | 0.533 | 9.0 | 0.8 | 0.867 | 0.867 | 0.867 | 0.933 | 0.933 | 1.667 | 1.6 | 1.733 |
| ECGFiveDays | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 2.256 | 2.256 | 2.256 | 2.256 | 10.902 | 8.271 | 12.406 |
| ElectricDevices | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1.302 | 1.302 | 5.028 | 5.329 | 8.594 | 10.877 | 12.28 | 13.241 |
| FaceAll | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.296 | 0.148 | 0.296 | 0.444 | 0.444 |
| FacesUCR | 1.63 | 1.63 | 1.63 | 1.63 | 1.63 | 1.63 | 1.63 | 1.63 | 1.63 | 2.519 | 2.074 | 3.407 | 3.407 | 4.741 | 5.778 | 6.519 | 6.519 |
| FiftyWords | 4.044 | 4.044 | 4.044 | 4.044 | 4.044 | 4.044 | 4.044 | 4.044 | 4.044 | 4.044 | 2.206 | 4.779 | 4.779 | 3.309 | 5.515 | 4.412 | 5.515 |
| FordA | 0 | 0 | 0 | 0 | 0 | 0 | 2.031 | 2.031 | 2.031 | 2.573 | 2.979 | 3.453 | 3.859 | 4.875 | 5.281 | 7.177 | 10.494 |
| FreezerRegularTrain | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.111 | 0.556 | 0.556 | 1.333 | 1.333 |
| HandOutlines | 4.38 | 4.38 | 4.38 | 4.38 | 4.38 | 4.623 | 4.623 | 4.623 | 4.623 | 4.623 | 6.083 | 4.623 | 8.029 | 8.273 | 11.922 | 14.599 | 15.815 |
| InsectWingbeatSound | 1.97 | 1.97 | 1.97 | 1.97 | 1.97 | 1.97 | 4.848 | 4.848 | 4.848 | 4.848 | 1.667 | 1.667 | 2.424 | 3.333 | 4.697 | 5 | 7.727 |
| ItalyPowerDemand | 0.912 | 0.912 | 0.912 | 0.912 | 0.912 | 0.912 | 0.912 | 0.912 | 0.912 | 3.04 | 3.04 | 2.432 | 5.775 | 8.815 | 18.541 | 22.188 | 25.836 |
| Mallat | 0.139 | 0.139 | 0.139 | 0.139 | 0.139 | 0.139 | 0.139 | 0.139 | 0.139 | 0.417 | 0.417 | 0.556 | 0.556 | 1.528 | 2.222 | 3.889 | 3.611 |
| Medicallmages | 9.621 | 9.621 | 9.621 | 9.621 | 9.621 | 9.621 | 9.621 | 9.621 | 9.621 | 9.913 | 9.913 | 11.662 | 12.245 | 18.659 | 18.659 | 23.907 | 23.907 |
| MelbournePedestrian | 0.367 | 0.367 | 0.367 | 0.367 | 0.367 | 0.367 | 0.367 | 0.367 | 0.367 | 0.642 | 0.642 | 0.826 | 0.826 | 1.743 | 1.651 | 2.294 | 8.532 |
| MixedShapesRegularTrain | 1.025 | 1.025 | 1.025 | 1.025 | 1.025 | 1.025 | 1.025 | 1.025 | 1.025 | 1.253 | 1.253 | 1.253 | 1.367 | 1.822 | 1.822 | 2.733 | 2.164 |
| MoteStrain | 3.141 | 3.141 | 3.141 | 3.141 | 3.141 | 3.141 | 3.141 | 2.094 | 2.094 | 3.927 | 3.927 | 5.236 | 6.021 | 908.9 | 7.068 | 8.377 | 15.445 |
| NonInvasiveFatalECGThorax2 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.619 | 0.708 | 1.239 |
| PhalangesOutlinesCorrect | 15.414 | 15.414 | 15.414 | 15.414 | 15.414 | 15.414 | 15.414 | 16.165 | 16.165 | 14.787 | 18.045 | 18.045 | 18.045 | 22.306 | 24.311 | 28.947 | 30.827 |
| ProximalPhalanxOutlineCorrect | 8.209 | 8.209 | 8.209 | 8.209 | 8.209 | 8.209 | 8.209 | 8.209 | 8.209 | 9.701 | 9.701 | 10.821 | 11.194 | 17.164 | 26.493 | 26.119 | 26.493 |
| SemgHandGenderCh2 | 7 | 7 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 6.5 | 7 | 11 | 15 | 14.5 |
| SonyAIBORobotSurface2 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 5.442 | 6.463 | 8.503 | 10.204 | 9.864 |
| StarLightCurves | 0 | 0 | 0 | 0 | 0 | 0 | 0.974 | 1.155 | 1.191 | 1.119 | 1.263 | 2.382 | 2.382 | 2.382 | 3.428 | 4.15 | 4.367 |
| Strawberry | 4.407 | 4.407 | 4.407 | 4.407 | 4.407 | 4.407 | 4.407 | 4.407 | 4.746 | 4.746 | 5.085 | 5.085 | 5.085 | 7.119 | 13.559 | 14.237 | 15.593 |
| Symbols | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 1.333 | 2 | 2.333 | 2.333 | 3 | 3 | 10 |
| TwoLeadECG | 0.86 | 0.86 | 0.86 | 0.86 | 0.287 | 0.287 | 0.287 | 0.287 | 0.86 | 0.86 | 98.0 | 0.86 | 0.86 | 2.292 | 4.585 | 5.158 | 8.023 |
| TwoPatterns | 1.467 | 1.467 | 1.467 | 1.467 | 1.467 | 1.467 | 1.467 | 1.467 | 1.867 | 1.933 | 1.933 | 3.133 | 3.267 | 10.067 | 24.533 | 25.067 | 25.4 |
| UWaveGestureLibraryX | 1.265 | 1.265 | 1.265 | 1.265 | 1.265 | 1.265 | 1.265 | 1.265 | 1.265 | 1.562 | 2.455 | 2.455 | 5.679 | 3.646 | 4.836 | 6.994 | 7.887 |
| Wafer | 0 | 0 | 0 | 0 | 0 | 0.047 | 0.047 | 0.047 | 0.047 | 0.047 | 0.14 | 0.14 | 0.14 | 0.14 | 0.186 | 0.279 | 0.279 |
| WordSynonyms | 5.515 | 5.515 | 5.515 | 5.515 | 5.515 | 5.515 | 5.515 | 5.515 | 5.515 | 5.882 | 4.412 | 6.985 | 4.412 | 6.25 | 8.456 | 9.559 | 14.338 |
| Yoga | 10.303 | 10.303 | 10.303 | 10.303 | 10.303 | 10.303 | 10.505 | 10.808 | 10.808 | 10.808 | 11.616 | 12.626 | 12.424 | 13.232 | 13.434 | 14.747 | 14.747 |
| | | | | | | | | | | | | | | | | | ١ |

Figure 1: Percentage of samples for which the score paid by the user can be improved by revoking the decision of ECONOMY- γ . Each column represent a different value of α in ascending order.

2 Average ranking using the Friedman test

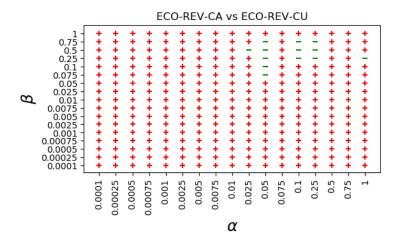


Figure 2: ECO-REV-CA vs. ECO-REV-CU: Average ranking based on AvgCost using the Friedman test, for different values of α and β : "+" indicates ECO-REV-CA having a better average rank than ECO-REV-CA, and "-" indicates the opposite .

In our paper, we used Wilcoxon signed-rank test to compare the two proposed approaches (see Section 5). In addition, Figure 2 uses the Friedman test and shows that ECO-REV-CA has better average rank than ECO-REV-CU in 96% of cases.

3 Average Earliness vs. Average Kappa for different values of β

This section presents the pareto curve for additional values of β , we notice that the same order holds for all values of β except for β =0.75 and β =1 where ECO-REV-CA becomes worse than ECONOMY- γ , however ECO-REV-CU still performs better.

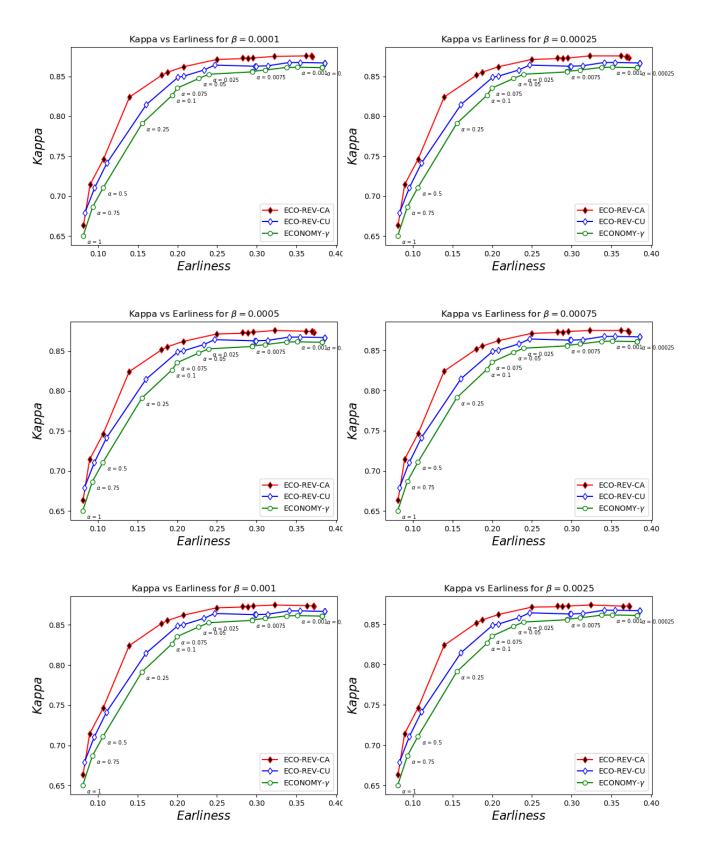


Figure 3: Average Earliness vs. Average Kappa score obtained over the 34 datasets by varying α of the delay cost.

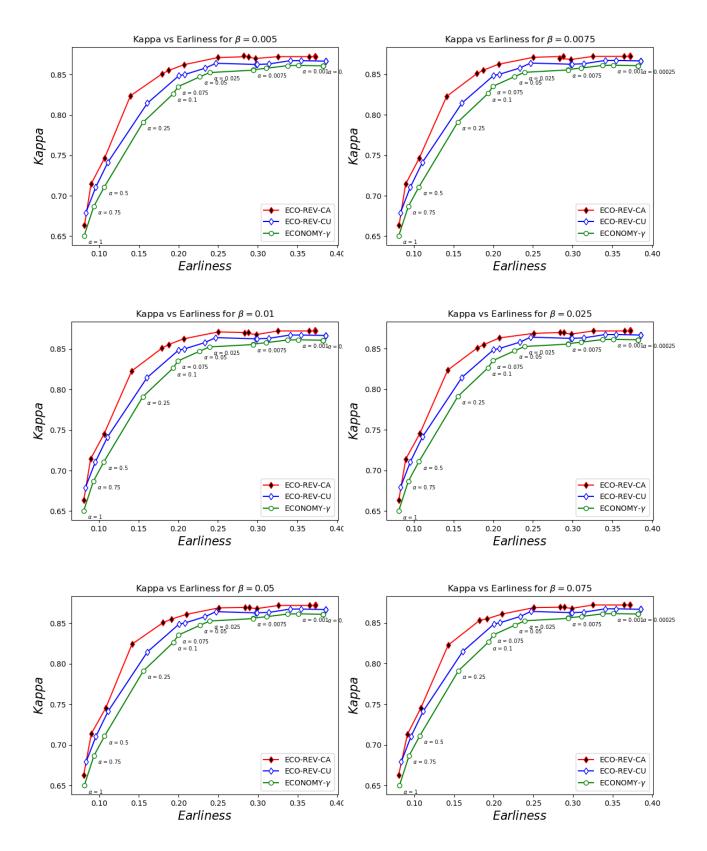


Figure 4: Average Earliness vs. Average Kappa score obtained over the 34 datasets by varying α of the delay cost.

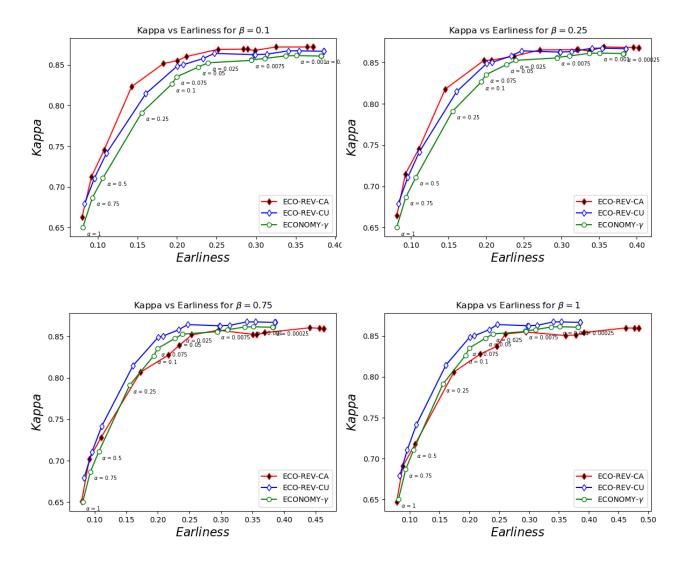


Figure 5: Average Earliness vs. Average Kappa score obtained over the 34 datasets by varying α of the delay cost.

4 Experiments on multi-class early and revocable classification problems

This section gives two simple implementation examples of the ECONOMY framework, in the case of multiclass problems and revocable decisions.

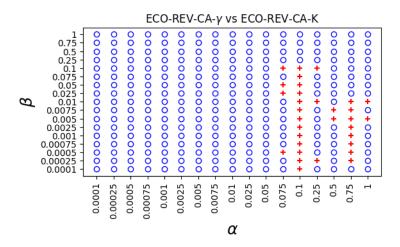


Figure 6: ECO-REV-CA- γ vs. ECO-REV-CA-K: Wilcoxon signed-rank test applied on the AvgCost criterion over the 22 test sets, for a range of couples of values α and β , with "+" indicating a significant success of the first approach, "o" an insignificant difference and "–" indicating a significant failure of the first approach.

ECONOMY- γ is by design limited to binary early classification problems. The reason behind this limitation is that the partitioning of time series in the training set is done by discretising the confidence level of the classifiers regarding the positive class. We propose a new method ECONOMY- γ -MC which handles multi-class early classification problems. The intuition behind this method is that time series with similar uncertainty level of classifiers belong to the same group. In fact, instead of discretising the confidence level of the classifiers to the positive class, we propose to discretise the uncertainty of the classifier. This uncertainty is measured using the relative entropy function. The mechanism of predicting the groups at future time steps using Markov chain remains unchanged compared to ECONOMY- γ .

ECONOMY-K partition time series using the clustering algorithm K-means. This approach can deal by design with multi-class classification problems. ECONOMY-K and ECONOMY- γ -MC are used to implement early and revocable framework described in our paper. Experiments were performed on 22 datasets chosen at random from the UAE-UCR archive to compare performance of these two revocable strategies called respectively ECO-REV-CA-K and ECO-REV-CA- γ . Results of Wilcoxon signed-rank test applied on the AvgCost criterion are shown in Figure 6. Further detailed results focusing on AvgCost are presented in Table 1 and Table 2.

| Datasets | Class | $\alpha = 0.0001$ | .0001 | $\alpha = 0.0025$ | 0025 | $\alpha = 0$. | 0.0005 | $\alpha = 0.0$ | 0.00075 | $\alpha = 0$ | 0.001 | $\alpha = 0$. | 0.0025 | $\alpha = 0$ | 0.005 | $\alpha = 0$ | 0.0075 | $\alpha = 0$ | 0.01 |
|-------------------------------|-------|-------------------|--|-------------------|--------|---|--------|----------------|---------|--------------|--------|----------------|--------|--------------|--------|--------------|--------|--------------|--------|
| | | ŭ | × | ŭ | X | The contract of | × | ŭ | × | ŭ | × | U | X | ŭ | X | U | ¥ | ŭ | X |
| Plane | 7 | 0.0953 | 0.0953 0.0955 0.0953 0.0956 | 0.0953 | 0.0956 | 0.0953 | 0.0957 | 0.0953 | 0.0959 | 0.0954 | 960.0 | 0.0956 | 0.0969 | 0.0959 | 0.0827 | 0.0962 | 0.0841 | 0.0965 | 0.0694 |
| BirdChicken | 2 | 0.3334 | 0.3334 0.3335 | | 0.3335 | 0.3337 | 0.3337 | 0.3338 | 0.3338 | 0.334 | 0.334 | 0.335 | 0.335 | 0.3368 | 0.3368 | 0.3385 | 0.3385 | 0.3402 | 0.3402 |
| MoteStrain | 2 | 0.0341 | $0.0341 \mid 0.0446 \mid 0.0342 \mid 0.0473$ | 0.0342 | 0.0473 | 0.0343 | 0.0475 | 0.0344 | 0.0477 | 0.0344 | 0.0479 | 0.0349 | 0.0361 | 0.0357 | 0.0381 | 0.0366 | 0.0401 | 0.0374 | 0.0395 |
| ProximalPhalanxOutlineCorrect | 2 | 0.1197 | 0.1158 | 0.1198 | 0.1159 | 0.1199 | 0.1162 | 0.1201 | 0.1164 | 0.1239 | 0.1166 | 0.1246 | 0.1181 | 0.1258 | 0.1205 | 0.127 | 0.1228 | 0.1352 | 0.1252 |
| Fungi | 18 | 0.1775 | 0.0807 | 0.1775 | 0.0808 | 0.1776 | 0.081 | 0.1777 | 0.0811 | 0.1778 | 0.0813 | 0.1785 | 0.0822 | 0.1795 | 0.0838 | 0.1806 | 0.117 | 0.1816 | 0.1184 |
| RefrigerationDevices | က | 0.4134 | 0.4134 | 0.4134 | 0.4134 | 0.4136 | 0.4136 | 0.4137 | 0.4137 | 0.4138 | 0.4138 | 0.4145 | 0.4145 | 0.4156 | 0.4156 | 0.4167 | 0.4167 | 0.3597 | 0.4178 |
| SemgHandMovementCh2 | 9 | 0.2993 | 0.3038 | 0.2994 | 0.3039 | 0.2995 | 0.3041 | 0.2996 | 0.3043 | 0.2998 | 0.3046 | 0.3005 | 0.3058 | 0.3017 | 0.308 | 0.3069 | 0.3101 | 0.3081 | 0.3122 |
| Ham | 2 | 0.2785 | 0.4154 | 0.2785 | 0.4155 | 0.2786 | 0.4156 | 0.2786 | 0.4157 | 0.2787 | 0.4158 | 0.279 | 0.4164 | 0.2799 | 0.4173 | 0.2804 | 0.4183 | 0.2809 | 0.4193 |
| Wine | 2 | 0.3824 | 0.1765 | 0.3824 | 0.1766 | 0.3825 | 0.1768 | 0.3826 | 0.1769 | 0.3827 | 0.1771 | 0.3831 | 0.178 | 0.3838 | 0.1795 | 0.3846 | 0.1811 | 0.3853 | 0.1825 |
| HandOutlines | 2 | 0.1193 | 0.0949 | 0.1193 | 0.095 | 0.1194 | 0.0951 | 0.1195 | 0.0952 | 0.1196 | 0.0953 | 0.1201 | 0.0959 | 0.1209 | 0.0969 | 0.1216 | 0.0979 | 0.1003 | 0.0989 |
| OliveOil | 4 | 0.2778 | 0.5001 | 0.2778 | 0.5002 | 0.2779 | 0.5004 | 0.2779 | 0.5007 | 0.278 | 0.5009 | 0.2782 | 0.5022 | 0.2787 | 0.5045 | 0.2792 | 0.5067 | 0.2797 | 0.5087 |
| FreezerRegularTrain | 2 | 0.0011 | 0.0023 | 0.0011 | 0.0023 | 0.0012 | 0.0024 | 0.0012 | 0.0024 | 0.0012 | 0.0014 | 0.0014 | 0.0028 | 0.0017 | 0.0033 | 0.002 | 0.0047 | 0.0022 | 0.0061 |
| Earthquakes | 2 | 0.2015 | 0.2159 | 0.2015 | 0.216 | 0.2016 | 0.2161 | 0.2016 | 0.2163 | 0.2017 | 0.2164 | 0.2021 | 0.2173 | 0.2027 | 0.2188 | 0.2031 | 0.2202 | 0.2036 | 0.2217 |
| Trace | 4 | 0.0334 | 0.0334 | 0.0335 | 0.0336 | 0.0336 | 0.0338 | 0.0337 | 0.034 | 0.0338 | 0.0342 | 0.0345 | 0.0356 | 0.0357 | 0.0378 | 0.0369 | 0.0401 | 0.0381 | 0.0423 |
| SonyAIBORobotSurface1 | 2 | 0.0321 | 0.0268 | 0.0322 | 0.0269 | 0.0324 | 0.0271 | 0.0326 | 0.0273 | 0.0327 | 0.0275 | 0.0337 | 0.0233 | 0.0353 | 0.0301 | 0.0369 | 0.027 | 0.0385 | 0.033 |
| ArrowHead | က | 0.2188 | 0.1719 | 0.2188 | 0.1721 | 0.2189 | 0.1722 | 0.219 | 0.1724 | 0.219 | 0.1726 | 0.2195 | 0.1737 | 0.2202 | 0.1756 | 0.2209 | 0.1775 | 0.2216 | 0.1793 |
| ChlorineConcentration | က | 0.219 | 0.2174 | 0.2191 | 0.2175 | 0.2193 | 0.2178 | 0.2195 | 0.2172 | 0.2197 | 0.2174 | 0.221 | 0.2187 | 0.2181 | 0.2209 | 0.219 | 0.217 | 0.2261 | 0.2252 |
| Strawberry | 2 | 0.0611 | $0.0511 \mid 0.0611$ | 0.0611 | 0.0512 | 0.0612 | 0.0513 | 0.0613 | 0.0515 | 0.0614 | 0.0516 | 0.0619 | 0.0557 | 0.0659 | 0.064 | 0.0666 | 0.0783 | 0.0673 | 0.0784 |
| ScreenType | က | 0.4408 | 0.4535 | 0.4409 | 0.4537 | 0.4411 | 0.4539 | 0.4413 | 0.4542 | 0.4415 | 0.4544 | 0.4428 | 0.4514 | 0.4448 | 0.4538 | 0.4469 | 0.4695 | 0.449 | 0.4761 |
| InsectEPGRegularTrain | က | 0.0 | 0.0 | 0.0 | 0.0001 | 0.0 | 0.0001 | 0.0 | 0.0002 | 0.0 | 0.0003 | 0.0001 | 0.0006 | 0.0002 | 0.0011 | 0.0004 | 0.012 | 0.0005 | 0.0123 |
| FordA | 2 | 0.3016 | $0.3016 \mid 0.3016 \mid$ | 0.3016 | 0.3016 | 0.3016 | 0.3016 | 0.3016 | 0.3016 | 0.3016 | 0.3016 | 0.3017 | 0.3017 | 0.3018 | 0.3018 | 0.302 | 0.302 | 0.3021 | 0.3021 |
| FacesUCR | 14 | 0.0617 | 0.0617 0.1215 0.0617 | 0.0617 | 0.1216 | 0.0618 | 0.1218 | 0.0619 | 0.122 | 0.062 | 0.1221 | 0.0626 | 0.1231 | 0.0635 | 0.1247 | 0.0601 | 0.1263 | 0.061 | 0.1279 |

Table 1: AvgCost for every dataset in the 22 benchmark for ECO-REV-CA- γ and ECO-REV-CA-K given a fixed value of $\beta=0.01$

| : 1 | X | 0.2764 | .6533 |).2248 | 0.341 | 0.6529 | .4848 | 0.6481 | 0.5629 | 0.6403 | 0.2853 | 0.3799 | 0.0632 | 0.2934 | 0.3541 | 0.1498 | 0.4618 | 0.4456 | 0.2846 | 0.6462 | 0.0499 | 0.3516 | 0.5166 |
|------------------|----------|------------------|-------------------|------------------|-------------------------------|-------------------|----------------------|---------------------|------------------|------------------|-------------------|-----------------|---------------------|-----------------------|-------------------|-----------------------|-------------------|-----------------------|------------------|-------------------|-----------------------|------------------|-------------------|
| α | _ ტ | 0.2124 0 | 0 6029' | $0.2162 \mid 0$ | .3239 (| $0.6025 \mid 0$ | $0.4533 \mid 0$ | $0.6481 \mid 0$ | $0.4518 \mid 0$ | 0.5844 0 | $0.2595 \mid 0$ | .4661 0 | 0.06 0 | $0.2934 \mid 0$ | $0.3483 \mid 0$ | $0.1412 \mid 0$ | $0.4369 \mid 0$ | 0.4077 0 | $0.2371 \mid 0$ | 0 6289'(| $0.0499 \mid 0$ | $0.3516 \mid 0$ | 0 9966 0 |
| 0.75 | K | .2698 0 | 0.6984 0 | $0.2124 \mid 0$ | $0.3285 \mid 0$ | 0.5281 0 | $0.4691 \mid 0$ | $0.6231 \mid 0$ | $0.5156 \mid 0$ | 0.669 0 | 0.2791 0 | $0.3842 \mid 0$ | 0.0507 | $0.2812 \mid 0$ | $0.3162 \mid 0$ | $0.1391 \mid 0$ | 0.4181 0 | $0.4239 \mid 0$ | $0.2396 \mid 0$ | $0.6429 \mid 0$ | $0.0374 \mid 0$ | $0.3391 \mid 0$ | $0.4482 \mid 0$ |
| $\alpha = 0$ | ڻ ڻ | .2093 0. | $0.7359 \mid 0.$ | $0.1915 \mid 0.$ | $0.3024 \mid 0.$ | $0.4782 \mid 0.$ | 0.4283 0. | $0.6231 \mid 0.$ | $0.4249 \mid 0.$ | $0.4531 \mid 0$ | $0.2366 \mid 0.$ | $0.419 \mid 0.$ | $0.0517 \mid 0.$ | $0.2812 \mid 0.$ | $0.3768 \mid 0.$ | $0.1085 \mid 0.$ | $0.2977 \mid 0.$ | $0.384 \mid 0.$ | 0.213 0. | $0.6826 \mid 0.$ | $0.0374 \mid 0.$ | $0.3391 \mid 0.$ | 3352 0 |
| 2 | K | .1792 0. | 0.6322 0. | 0.1917 0. | 0.316 0. | 0.3758 0. | 0.4706 0. | 0.565 0. | 0.4771 0. | 0.4769 0. | 0.2359 0. | 0.3569 0 | 0.0383 0. | 0.269 0. | 0.3112 0. | 0.1284 0. | 0.301 0. | 0.3943 0 | 0.2129 0 | 0.6345 0. | 0.025 0. | 0.3266 0. | .3565 0. |
| $\alpha = 0.5$ | <u> </u> | .1597 0. | $0.6851 \mid 0.0$ | 0.169 0. | 0.2601 0. | 0.4098 0.3 | 0.4236 0. | $0.4827 \mid 0.$ | 0.3803 0. | $0.531 \mid 0.4$ | $0.2052 \mid 0.3$ | 0.3719 0.3 | $0.0361 \mid 0.0$ | $0.269 \mid 0.$ | $0.3681 \mid 0.3$ | 0.1016 | $0.3071 \mid 0.$ | 3425 0.3 | .1718 0.3 | .6575 0.0 | 0.025 0.0 | .3266 0.3 | .2626 0.3 |
| 5 | × | .1427 0.1 | $.5042 \mid 0.6$ | .1598 0. | $0.2697 \mid 0.2$ | $0.2497 \mid 0.4$ | 4331 0.4 | $0.4854 \mid 0.4$ | .5388 0.3 | $0.3168 \mid 0.$ | .1754 0.5 | 3218 0.3 | $0.0262 \mid 0.0$ | $0.2568 \mid 0.$ | $0.1399 \mid 0.3$ | .1131 0.1 | $0.2949 \mid 0.3$ | 3285 0.3 | $.1504 \mid 0.1$ | $0.6107 \mid 0.6$ | $0.0125 \mid 0.0$ | $3141 \mid 0.5$ | $0.2826 \mid 0.2$ |
| z = 0.25 | 7.8 | 0 | _ | 0 | _ | _ | 0 | _ | 0 | _ | _ | _ | $\overline{}$ | $\overset{\smile}{-}$ | _ | <u> </u> | _ | _ | 0 | _ | _ | 0 | _ |
| σ | ŭ | $41 \mid 0.1275$ | 22 0.5042 | 31 0.1236 | 94 0.1994 | 76 0.2821 | 33 0.4075 | $41 \mid 0.3922$ | 44 0.2993 | $57 \mid 0.4567$ | 18 0.1655 | 26 0.3249 | $53 \mid 0.0212$ | $95 \mid 0.2568$ | 23 0.2147 | $5 \mid 0.0801$ | 54 0.2912 | $71 \mid 0.2923$ | 22 0.1254 | $51 \mid 0.5684$ | $12 \mid 0.0125$ | $36 \mid 0.314$ | $56 \mid 0.1638$ |
| = 0.1 | K | 0.0641 | 0.4822 | 0.1061 | 0.2294 | 3 0.1676 | 6 0.4583 | 0.3741 | 0.4544 | 0.2057 | 0.1348 | 0.3226 | 0.0153 | 0.2495 | 3 0.1123 | 0.075 | 0.2054 | 0.2871 | 0.1022 | 0.5051 | 0.0112 | 0.3066 | -0.1856 |
| σ | ರ | 0.1081 | 0.4017 | 0.0772 | 0.1686 | 0.2193 | 0.3886 | 0.3491 | 0.3004 | 0.4121 | 0.122 | 0.2966 | 0.0109 | 0.2472 | 0.0853 | 0.067 | 0.1584 | 0.2545 | 0.00 | 0.489 | 0.005 | 0.3066 | 0.1031 |
| 0.075 | X | 0.0736 | 0.3833 | 0.097 | 0.2204 | 0.1539 | 0.4471 | 0.3943 | 0.4446 | 0.191 | 0.1248 | 0.3236 | 0.0122 | 0.2483 | 0.0869 | 0.0503 | 0.2082 | 0.2743 | 0.0895 | 0.4817 | 0.0085 | 0.3053 | 0.1696 |
| σ = (| ŭ | 0.1049 | 0.3846 | 0.0595 | 0.1524 | 0.2088 | 0.3724 | 0.3253 | 0.295 | 0.4046 | 0.1153 | 0.2919 | 0.0074 | 0.2412 | 0.069 | 0.065 | 0.2405 | 0.2474 | 0.0844 | 0.4718 | 0.0037 | 0.3053 | 0.0968 |
| 0.05 | X | 0.0664 | 0.3678 | 0.0821 | 0.1868 | 0.1403 | 0.4358 | 0.3462 | 0.4349 | 0.1764 | 0.1148 | 0.3661 | 0.0095 | 0.247 | 0.0582 | 0.0643 | 0.1762 | 0.2551 | 0.0859 | 0.4813 | 0.0059 | 0.3041 | 0.1535 |
| $\alpha = 0$ | To | 0.1017 | 0.3675 | 0.0606 | 0.1249 | 0.1984 | 0.3727 | 0.3263 | 0.2896 | 0.3972 | 0.1114 | 0.2872 | 0.0062 | 0.2352 | 0.0571 | 0.0845 | 0.2332 | 0.2388 | 0.0824 | 0.477 | 0.0025 | 0.3041 | 0.0829 |
| 025 | X | 0.074 | 0.3504 | 0.0565 | 0.1394 | 0.1266 | 0.4246 | 0.325 | 0.4251 | 0.1914 | 0.1049 | 0.4085 | 0.0064 | 0.2641 | 0.0555 | 0.04 | 0.1903 | 0.2404 | 0.0754 | 0.4524 | 0.0151 | 0.3028 | 0.1375 |
| $\alpha = 0.025$ | U U | 0.0985 | 0.3504 | 0.0518 | 0.1415 | 0.1879 | 0.3627 | 0.3149 | 0.2842 | 0.3898 | 0.1045 | 0.2825 | 0.007 | 0.2087 | 0.0452 | 0.0659 | 0.226 | 0.2335 | 0.0749 | 0.4635 | 0.0012 | 0.3028 | 0.0665 |
| Class | | 2 | 2 | 2 | 2 | 18 | ი | 9 | 2 | 2 | 2 | 4 | 2 | 2 | 4 | 2 | က | ღ | 2 | ღ | <u> </u> | 2 | 14 |
| Datasets | | Plane | BirdChicken | MoteStrain | ProximalPhalanxOutlineCorrect | Fungi | RefrigerationDevices | SemgHandMovementCh2 | Ham | Wine | HandOutlines | OliveOil | FreezerRegularTrain | Earthquakes | Trace | SonyAIBORobotSurface1 | ArrowHead | ChlorineConcentration | Strawberry | ScreenType | InsectEPGRegularTrain | FordA | FacesUCR |

Table 2: AvgCost for every dataset in the 22 benchmark for ECO-REV-CA- γ and ECO-REV-CA-K given a fixed value of $\beta=0.01$