

Full Code

December 8, 2022

```
[13]: %pylab inline
%config InlineBackend.figure_format = 'retina'
from ipywidgets import interact
import tensorflow as tf
import numpy as np
from matplotlib import pyplot as plt
import pandas as pd
from sklearn.preprocessing import MinMaxScaler
import keras #
from keras.models import Model, Sequential
from keras.layers import Dense, LSTM, Dropout, GRU, CuDNNLSTM, Flatten
import math
from sklearn.metrics import mean_squared_error
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Activation, Dense, Dropout, LSTM, Input, LeakyReLU, ConvLSTM2D, Conv2D
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
from sklearn.metrics import mean_absolute_error
import numpy as np
from numpy import pi
import tensorflow as tf
import tensorflow.python.keras.backend as K
```

Populating the interactive namespace from numpy and matplotlib

```
[2]: class Particle_Tracking_Training_Data(tf.Module):
    def __init__(self, Nt, rings=True):
        self.Nt = int(Nt)
        self.Ny = self.Nx = 256
        self.d = 3
        ximg = [[[i, j] for i in np.arange(self.Ny)]
                 for j in np.arange(self.Nx)]
        self.ximg = np.float32(ximg)

        x = np.arange(self.Nx) - self.Nx//2
        y = np.arange(self.Ny) - self.Ny//2
```

```

X0, Y0 = np.meshgrid(x, y)
self.X = np.float32(X0)
self.Y = np.float32(Y0)

if rings:
    self.ring_indicator = 1.
else:
    self.ring_indicator = 0.

self._gen_video = tf.function(
    input_signature=(
        tf.TensorSpec(
            shape=[self.Ny, self.Nx, self.Nt, None], dtype=tf.float32),
        tf.TensorSpec(shape=[self.Nt, None], dtype=tf.float32),
        tf.TensorSpec(shape=[], dtype=tf.float32),
        tf.TensorSpec(shape=[], dtype=tf.float32),
        tf.TensorSpec(shape=[], dtype=tf.float32),
    )(self._gen_video)

self._gen_labels = tf.function(
    input_signature=(
        tf.TensorSpec(
            shape=[self.Ny, self.Nx, self.Nt, None], dtype=tf.float32),
    )(self._gen_labels)

def __call__(self, kappa, a, IbackLevel, Nparticles, sigma_motion):
    ## random brownian motion paths
    ## Nt, Nparticles, 3
    xi = self._sample_motion(Nparticles, sigma_motion)

    #### translate track positions to img coords
    ## Ny, Nx, Nt, Np, 2
    XALL = (self.ximg[:, :, None, None, :]
            - xi[None, None, :, :, :2])
    ## Ny, Nx, Nt, Np
    r = tf.math.sqrt(XALL[..., 0]**2 + XALL[..., 1]**2)
    z = xi[..., 2]

    ### generate video
    I = self._gen_video(r, z, kappa, a, IbackLevel)

    ### generate labels
    labels = self._gen_labels(r)

    return I, labels, xi

```

@staticmethod

```

def rand(n):
    return tf.random.uniform([n], dtype=tf.float32)

@tf.function(
    input_signature=(
        tf.TensorSpec(shape=[], dtype=tf.int32),
        tf.TensorSpec(shape=[], dtype=tf.float32),))
def _sample_motion(self, Nparticles, sigma_motion):
    ##### boundaries
    b_lower = tf.constant(
        [-10, -10, -30.], tf.float32)
    b_upper = tf.constant(
        [self.Nx+10, self.Ny+10, 30.], tf.float32)
    ##### uniform random initial positions
    U = tf.random.uniform(
        [1, Nparticles, self.d],
        dtype=tf.float32)
    X0 = b_lower + (b_upper - b_lower)*U
    ##### normal increments
    dX = tf.random.normal(
        [self.Nt, Nparticles, self.d],
        stddev=sigma_motion,
        dtype=tf.float32)
    ##### unbounded Brownian motion
    X = X0 + tf.math.cumsum(dX, axis=0)
    ##### reflected brownian motion
    ## note that this is imperfect,
    ## if increments are very large it wont work
    X = tf.math.abs(X - b_lower) + b_lower
    X = -tf.math.abs(b_upper - X) + b_upper
    return X

def _gen_video(self, r, z, kappa, a, IbackLevel):
    uw = (0.5 + self.rand(1))/2.
    un = tf.floor(3*self.rand(1))
    uampRing = 0.2 + 0.8*self.rand(1)
    ufade = 15 + 10*self.rand(1)
    rmax = ufade*(un/uw)**(2./3.)
    ufadeMax = 0.85
    fade = (1. - ufadeMax*tf.abs(tf.tanh(z/ufade)))
    core = tf.exp(-(r**2/(8.*a))**2)
    ring = fade*(tf.exp(-(r - z)**4/(a)**4)
        + 0.5*uampRing*tf.cast(r<z, tf.float32))
    I = tf.transpose(
        tf.reduce_sum(
            fade*(core + self.ring_indicator*ring),
            axis=3),

```

```

        [2, 0, 1]) # Nt, Ny, Nx
    I += IbackLevel*tf.sin(
        self.rand(1)*6*pi/512*tf.sqrt(
            self.rand(1)*(self.X - self.rand(1)*512)**2
            + self.rand(1)*(self.Y - self.rand(1)*512)**2))
    I += tf.random.normal(
        [self.Nt, self.Ny, self.Nx],
        stddev=kappa,
        dtype=tf.float32)
    Imin = tf.reduce_min(I)
    Imax = tf.reduce_max(I)
    I = (I - Imin)/(Imax - Imin)
    I = tf.round(I*tf.maximum(256., tf.round(2**16*self.rand(1))))
    return I

def _gen_labels(self, r):
    R_detect = 3.
    ## (Ny, Nx, Nt)
    detectors = tf.reduce_sum(
        tf.cast(r[:, :, 2, :] < R_detect, tf.int32),
        axis=3)
    ## (Nt, Ny, Nx)
    P = tf.transpose(
        tf.cast(detectors > 0, tf.int32), [2, 0, 1])
    ## (Nt, Ny, Nx, 2)
    labels = tf.stack([1-P, P], 3)
    return labels

```

```

[3]: Nt = 300 ## number of frames for each video
kappa = 0.1 ## standard deviation of background noise added to image
a = 3. ## scale factor for the size of particle spots (not true size of
    ↪ particles)
IbackLevel = 0.1 ## relative intensity of randomly generated background pattern;
    ↪ in (0, 1)
Nparticles = 3 ## the number of particles (more => slower)
sigma_motion = 2 ## the standard deviation for particle brownian motion; should
    ↪ be in (0, 10)

pt = Particle_Tracking_Training_Data(Nt) ## create object instance

vid, labels, tracks = pt(kappa, a, IbackLevel, Nparticles, sigma_motion)

```

0.1 Generating the Data

```
[4]: @interact(t=(0, Nt-1, 1))
def plotfn(t=0):
    fig = figure(1, [14, 7])
    imshow(vid[t], origin='lower')
    #xlim(-10, 265)
    #ylim(-10, 265)
```

```
interactive(children=(IntSlider(value=0, description='t', max=299), Output()),  
            _dom_classes=('widget-interact'...
```

```
[5]: def generate_data(size, pt, kappa, a, IbackLevel, Nparticles, sigma_motion):
    all_vid, all_labels, all_tracks = [], [], []
    for i in range(size):
        vid, labels, tracks = pt(kappa, a, IbackLevel, Nparticles, sigma_motion)
        all_vid.append(vid[:, ::2, ::2]) # downsample video to Ntx128x128
        all_labels.append(labels)
        all_tracks.append(tracks)
    all_vid = tf.convert_to_tensor(all_vid)
    all_labels = tf.convert_to_tensor(all_labels)
    all_tracks = tf.convert_to_tensor(all_tracks)

    all_vid = tf.expand_dims(all_vid, 4)
    all_labels = tf.squeeze(all_labels)
    return all_vid, all_labels, all_tracks
```

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1 Detecting the Particles

```
[67]: train_size = 20
val_size = 3
Nt = 10
Nparticles_det = 10
pt = Particle_Tracking_Training_Data(Nt)

train_vid, train_labels, train_tracks = generate_data(train_size, pt, kappa, a,  
            IbackLevel, Nparticles_det, sigma_motion)
val_vid, val_labels, val_tracks = generate_data(val_size, pt, kappa, a,  
            IbackLevel, Nparticles_det, sigma_motion)
```

1.0.1 CNN model

```
[68]: #https://stackoverflow.com/questions/51793737/
      ↪ custom-loss-function-for-u-net-in-keras-using-class-weights-class-weight-not

def weightedLoss(originalLossFunc, weightsList):

    def lossFunc(true, pred):
        axis = -1 #if channels last
        #axis= 1 #if channels first

        #argmax returns the index of the element with the greatest value
        #done in the class axis, it returns the class index
        classSelectors = K.argmax(true, axis=axis)
        #if your loss is sparse, use only true as classSelectors

        #considering weights are ordered by class, for each class
        #true(1) if the class index is equal to the weight index
        classSelectors = tf.cast(classSelectors, tf.int32)
        classSelectors = [K.equal(i, classSelectors) for i in
            ↪ range(len(weightsList))]

        #casting boolean to float for calculations
        #each tensor in the list contains 1 where ground true class is equal to
        ↪ its index
        #if you sum all these, you will get a tensor full of ones.
        classSelectors = [K.cast(x, K.floatx()) for x in classSelectors]

        #for each of the selections above, multiply their respective weight
        weights = [sel * w for sel,w in zip(classSelectors, weightsList)]

        #sums all the selections
        #result is a tensor with the respective weight for each element in
        ↪ predictions
        weightMultiplier = weights[0]
        for i in range(1, len(weights)):
            weightMultiplier = weightMultiplier + weights[i]

        #make sure your originalLossFunc only collapses the class axis
        #you need the other axes intact to multiply the weights tensor
        loss = originalLossFunc(true,pred)
        loss = loss * weightMultiplier

    return loss
return lossFunc
```

```
[69]: precision_f = tf.keras.metrics.Precision(class_id=1)
      recall_f = tf.keras.metrics.Recall(class_id=1)

      def f1_score(y_true, y_pred):
          precision = precision_f(y_true, y_pred)
          recall = recall_f(y_true, y_pred)
          f1_val = 2*(precision*recall)/(precision+recall)
          return f1_val

[70]: train_vid_cnn = tf.reshape(train_vid, (train_size*Nt, 128, 128, 1))
      train_labels_cnn = tf.reshape(train_labels, (train_size*Nt, 128, 128, 2))
      val_vid_cnn = tf.reshape(val_vid, (val_size*Nt, 128, 128, 1))
      val_labels_cnn = tf.reshape(val_labels, (val_size*Nt, 128, 128, 2))

[71]: loss_list1 = list()

      class SaveBatchLoss1(tf.keras.callbacks.Callback):
          def on_train_batch_end(self, batch, logs=None):
              loss_list1.append(logs['loss'])

[72]: batch_size = 10
      epochs = 50

      model1 = Sequential()
      model1.add(Input((128,128,1)))
      model1.add(Conv2D(12, 3, padding='same', activation=LeakyReLU(alpha=0.01),
          ↪strides=(1,1)))
      model1.add(Conv2D(32, 3, padding='same', activation=LeakyReLU(alpha=0.01),
          ↪strides=(1,1)))
      model1.add(Conv2D(2, 3, padding='same', strides=(1,1)))
      model1.add(Activation('softmax'))

      model1.compile(optimizer='adam',
          ↪loss=weightedLoss(keras.losses.categorical_crossentropy, [0.2, 0.
          ↪8]),
          ↪metrics=['accuracy', tf.keras.metrics.
          ↪Precision(name='precision_1', class_id=1),
          ↪tf.keras.metrics.Recall(name='recall_1', class_id=1),
          ↪f1_score])

      num_batches = int(train_size/batch_size)
      model1.fit(train_vid_cnn, train_labels_cnn, steps_per_epoch=num_batches,
          ↪epochs=epochs, verbose=1,
          ↪validation_data=(val_vid_cnn, val_labels_cnn),
          ↪callbacks=SaveBatchLoss1())
```

Epoch 1/50

2/2 [=====] - 7s 4s/step - loss: 8.6499 - accuracy:
0.9531 - precision_1: 0.0032 - recall_1: 0.0375 - f1_score: 0.0060 - val_loss:
6.9045 - val_accuracy: 0.9922 - val_precision_1: 0.0015 - val_recall_1: 0.0017 -
val_f1_score: 0.0057
Epoch 2/50
2/2 [=====] - 5s 3s/step - loss: 8.9291 - accuracy:
0.9934 - precision_1: 0.0045 - recall_1: 0.0037 - f1_score: 0.0056 - val_loss:
5.1317 - val_accuracy: 0.9933 - val_precision_1: 0.0020 - val_recall_1: 0.0017 -
val_f1_score: 0.0055
Epoch 3/50
2/2 [=====] - 5s 3s/step - loss: 6.0940 - accuracy:
0.9929 - precision_1: 0.0065 - recall_1: 0.0062 - f1_score: 0.0055 - val_loss:
2.0264 - val_accuracy: 0.9810 - val_precision_1: 0.0257 - val_recall_1: 0.1148 -
val_f1_score: 0.0072
Epoch 4/50
2/2 [=====] - 5s 3s/step - loss: 3.8997 - accuracy:
0.9358 - precision_1: 0.0172 - recall_1: 0.2952 - f1_score: 0.0155 - val_loss:
1.9006 - val_accuracy: 0.9421 - val_precision_1: 0.0274 - val_recall_1: 0.4323 -
val_f1_score: 0.0219
Epoch 5/50
2/2 [=====] - 5s 3s/step - loss: 2.3909 - accuracy:
0.9663 - precision_1: 0.0309 - recall_1: 0.2704 - f1_score: 0.0274 - val_loss:
1.5458 - val_accuracy: 0.9926 - val_precision_1: 0.0938 - val_recall_1: 0.1198 -
val_f1_score: 0.0292
Epoch 6/50
2/2 [=====] - 5s 3s/step - loss: 2.6187 - accuracy:
0.9941 - precision_1: 0.1002 - recall_1: 0.0757 - f1_score: 0.0308 - val_loss:
1.6484 - val_accuracy: 0.9951 - val_precision_1: 0.1734 - val_recall_1: 0.0890 -
val_f1_score: 0.0316
Epoch 7/50
2/2 [=====] - 5s 3s/step - loss: 2.5580 - accuracy:
0.9954 - precision_1: 0.1926 - recall_1: 0.0801 - f1_score: 0.0331 - val_loss:
1.0222 - val_accuracy: 0.9939 - val_precision_1: 0.2099 - val_recall_1: 0.2447 -
val_f1_score: 0.0350
Epoch 8/50
2/2 [=====] - 5s 3s/step - loss: 1.6063 - accuracy:
0.9920 - precision_1: 0.1454 - recall_1: 0.2437 - f1_score: 0.0397 - val_loss:
0.8481 - val_accuracy: 0.9695 - val_precision_1: 0.0727 - val_recall_1: 0.6288 -
val_f1_score: 0.0443
Epoch 9/50
2/2 [=====] - 5s 3s/step - loss: 1.5747 - accuracy:
0.9614 - precision_1: 0.0543 - recall_1: 0.5815 - f1_score: 0.0518 - val_loss:
1.0891 - val_accuracy: 0.9540 - val_precision_1: 0.0577 - val_recall_1: 0.7609 -
val_f1_score: 0.0554
Epoch 10/50
2/2 [=====] - 5s 3s/step - loss: 1.3431 - accuracy:
0.9688 - precision_1: 0.0674 - recall_1: 0.5869 - f1_score: 0.0613 - val_loss:
0.5417 - val_accuracy: 0.9889 - val_precision_1: 0.1763 - val_recall_1: 0.5633 -


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val_f1_score: 0.0649
Epoch 11/50
2/2 [=====] - 5s 3s/step - loss: 1.1557 - accuracy:
0.9918 - precision_1: 0.1929 - recall_1: 0.3859 - f1_score: 0.0702 - val_loss:
0.6029 - val_accuracy: 0.9944 - val_precision_1: 0.3093 - val_recall_1: 0.4429 -
val_f1_score: 0.0730
Epoch 12/50
2/2 [=====] - 5s 3s/step - loss: 1.2881 - accuracy:
0.9947 - precision_1: 0.2948 - recall_1: 0.3189 - f1_score: 0.0772 - val_loss:
0.5032 - val_accuracy: 0.9936 - val_precision_1: 0.2885 - val_recall_1: 0.5190 -
val_f1_score: 0.0801
Epoch 13/50
2/2 [=====] - 5s 3s/step - loss: 1.0422 - accuracy:
0.9930 - precision_1: 0.2394 - recall_1: 0.4213 - f1_score: 0.0851 - val_loss:
0.4527 - val_accuracy: 0.9854 - val_precision_1: 0.1609 - val_recall_1: 0.7133 -
val_f1_score: 0.0886
Epoch 14/50
2/2 [=====] - 5s 3s/step - loss: 0.8922 - accuracy:
0.9832 - precision_1: 0.1266 - recall_1: 0.6107 - f1_score: 0.0942 - val_loss:
0.6655 - val_accuracy: 0.9707 - val_precision_1: 0.0951 - val_recall_1: 0.8275 -
val_f1_score: 0.0970
Epoch 15/50
2/2 [=====] - 5s 3s/step - loss: 0.9626 - accuracy:
0.9760 - precision_1: 0.1000 - recall_1: 0.6966 - f1_score: 0.1014 - val_loss:
0.4469 - val_accuracy: 0.9832 - val_precision_1: 0.1495 - val_recall_1: 0.7760 -
val_f1_score: 0.1042
Epoch 16/50
2/2 [=====] - 5s 3s/step - loss: 0.7692 - accuracy:
0.9876 - precision_1: 0.1673 - recall_1: 0.6008 - f1_score: 0.1091 - val_loss:
0.3495 - val_accuracy: 0.9920 - val_precision_1: 0.2650 - val_recall_1: 0.6792 -
val_f1_score: 0.1120
Epoch 17/50
2/2 [=====] - 5s 3s/step - loss: 0.7896 - accuracy:
0.9933 - precision_1: 0.2760 - recall_1: 0.5096 - f1_score: 0.1166 - val_loss:
0.3375 - val_accuracy: 0.9935 - val_precision_1: 0.3136 - val_recall_1: 0.6568 -
val_f1_score: 0.1194
Epoch 18/50
2/2 [=====] - 5s 3s/step - loss: 0.7653 - accuracy:
0.9937 - precision_1: 0.2941 - recall_1: 0.5141 - f1_score: 0.1237 - val_loss:
0.3224 - val_accuracy: 0.9909 - val_precision_1: 0.2463 - val_recall_1: 0.7273 -
val_f1_score: 0.1265
Epoch 19/50
2/2 [=====] - 5s 3s/step - loss: 0.6671 - accuracy:
0.9907 - precision_1: 0.2188 - recall_1: 0.6008 - f1_score: 0.1311 - val_loss:
0.3833 - val_accuracy: 0.9848 - val_precision_1: 0.1683 - val_recall_1: 0.8091 -
val_f1_score: 0.1335
Epoch 20/50
2/2 [=====] - 5s 3s/step - loss: 0.6722 - accuracy:

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0.9854 - precision_1: 0.1571 - recall_1: 0.6863 - f1_score: 0.1375 - val_loss:
0.3908 - val_accuracy: 0.9836 - val_precision_1: 0.1594 - val_recall_1: 0.8225 -
val_f1_score: 0.1396

Epoch 21/50

2/2 [=====] - 5s 3s/step - loss: 0.6342 - accuracy:
0.9867 - precision_1: 0.1698 - recall_1: 0.6805 - f1_score: 0.1432 - val_loss:
0.2988 - val_accuracy: 0.9898 - val_precision_1: 0.2319 - val_recall_1: 0.7766 -
val_f1_score: 0.1455

Epoch 22/50

2/2 [=====] - 5s 3s/step - loss: 0.5927 - accuracy:
0.9917 - precision_1: 0.2462 - recall_1: 0.6112 - f1_score: 0.1494 - val_loss:
0.2667 - val_accuracy: 0.9929 - val_precision_1: 0.3030 - val_recall_1: 0.7279 -
val_f1_score: 0.1517

Epoch 23/50

2/2 [=====] - 5s 3s/step - loss: 0.5902 - accuracy:
0.9936 - precision_1: 0.3012 - recall_1: 0.5759 - f1_score: 0.1555 - val_loss:
0.2563 - val_accuracy: 0.9925 - val_precision_1: 0.2923 - val_recall_1: 0.7486 -
val_f1_score: 0.1577

Epoch 24/50

2/2 [=====] - 5s 3s/step - loss: 0.5484 - accuracy:
0.9925 - precision_1: 0.2695 - recall_1: 0.6142 - f1_score: 0.1614 - val_loss:
0.2753 - val_accuracy: 0.9891 - val_precision_1: 0.2242 - val_recall_1: 0.8091 -
val_f1_score: 0.1635

Epoch 25/50

2/2 [=====] - 5s 3s/step - loss: 0.5287 - accuracy:
0.9892 - precision_1: 0.2052 - recall_1: 0.6801 - f1_score: 0.1668 - val_loss:
0.2966 - val_accuracy: 0.9866 - val_precision_1: 0.1921 - val_recall_1: 0.8354 -
val_f1_score: 0.1686

Epoch 26/50

2/2 [=====] - 6s 3s/step - loss: 0.5161 - accuracy:
0.9885 - precision_1: 0.1969 - recall_1: 0.6982 - f1_score: 0.1716 - val_loss:
0.2487 - val_accuracy: 0.9899 - val_precision_1: 0.2388 - val_recall_1: 0.8085 -
val_f1_score: 0.1735

Epoch 27/50

2/2 [=====] - 6s 3s/step - loss: 0.4849 - accuracy:
0.9915 - precision_1: 0.2484 - recall_1: 0.6564 - f1_score: 0.1766 - val_loss:
0.2190 - val_accuracy: 0.9926 - val_precision_1: 0.2998 - val_recall_1: 0.7738 -
val_f1_score: 0.1786

Epoch 28/50

2/2 [=====] - 6s 3s/step - loss: 0.4783 - accuracy:
0.9932 - precision_1: 0.2954 - recall_1: 0.6222 - f1_score: 0.1818 - val_loss:
0.2121 - val_accuracy: 0.9926 - val_precision_1: 0.3006 - val_recall_1: 0.7772 -
val_f1_score: 0.1836

Epoch 29/50

2/2 [=====] - 6s 3s/step - loss: 0.4584 - accuracy:
0.9927 - precision_1: 0.2813 - recall_1: 0.6419 - f1_score: 0.1867 - val_loss:
0.2227 - val_accuracy: 0.9905 - val_precision_1: 0.2518 - val_recall_1: 0.8135 -
val_f1_score: 0.1884

Epoch 30/50
2/2 [=====] - 6s 3s/step - loss: 0.4432 - accuracy: 0.9907 - precision_1: 0.2355 - recall_1: 0.6816 - f1_score: 0.1912 - val_loss: 0.2332 - val_accuracy: 0.9890 - val_precision_1: 0.2257 - val_recall_1: 0.8337 - val_f1_score: 0.1927

Epoch 31/50
2/2 [=====] - 6s 3s/step - loss: 0.4338 - accuracy: 0.9901 - precision_1: 0.2249 - recall_1: 0.6956 - f1_score: 0.1953 - val_loss: 0.2102 - val_accuracy: 0.9908 - val_precision_1: 0.2570 - val_recall_1: 0.8147 - val_f1_score: 0.1968

Epoch 32/50
2/2 [=====] - 6s 3s/step - loss: 0.4185 - accuracy: 0.9919 - precision_1: 0.2629 - recall_1: 0.6706 - f1_score: 0.1995 - val_loss: 0.1907 - val_accuracy: 0.9926 - val_precision_1: 0.3023 - val_recall_1: 0.7889 - val_f1_score: 0.2011

Epoch 33/50
2/2 [=====] - 6s 3s/step - loss: 0.4099 - accuracy: 0.9931 - precision_1: 0.2963 - recall_1: 0.6463 - f1_score: 0.2037 - val_loss: 0.1881 - val_accuracy: 0.9924 - val_precision_1: 0.2947 - val_recall_1: 0.7923 - val_f1_score: 0.2053

Epoch 34/50
2/2 [=====] - 5s 3s/step - loss: 0.3976 - accuracy: 0.9925 - precision_1: 0.2787 - recall_1: 0.6626 - f1_score: 0.2078 - val_loss: 0.1965 - val_accuracy: 0.9909 - val_precision_1: 0.2590 - val_recall_1: 0.8152 - val_f1_score: 0.2092

Epoch 35/50
2/2 [=====] - 6s 3s/step - loss: 0.3889 - accuracy: 0.9913 - precision_1: 0.2499 - recall_1: 0.6905 - f1_score: 0.2116 - val_loss: 0.1955 - val_accuracy: 0.9906 - val_precision_1: 0.2538 - val_recall_1: 0.8191 - val_f1_score: 0.2129

Epoch 36/50
2/2 [=====] - 6s 3s/step - loss: 0.3800 - accuracy: 0.9914 - precision_1: 0.2537 - recall_1: 0.6898 - f1_score: 0.2150 - val_loss: 0.1811 - val_accuracy: 0.9919 - val_precision_1: 0.2818 - val_recall_1: 0.8001 - val_f1_score: 0.2164

Epoch 37/50
2/2 [=====] - 5s 3s/step - loss: 0.3710 - accuracy: 0.9926 - precision_1: 0.2829 - recall_1: 0.6693 - f1_score: 0.2187 - val_loss: 0.1726 - val_accuracy: 0.9926 - val_precision_1: 0.3026 - val_recall_1: 0.7934 - val_f1_score: 0.2200

Epoch 38/50
2/2 [=====] - 5s 3s/step - loss: 0.3646 - accuracy: 0.9930 - precision_1: 0.2956 - recall_1: 0.6629 - f1_score: 0.2223 - val_loss: 0.1731 - val_accuracy: 0.9921 - val_precision_1: 0.2877 - val_recall_1: 0.7984 - val_f1_score: 0.2236

Epoch 39/50
2/2 [=====] - 6s 3s/step - loss: 0.3559 - accuracy: 0.9924 - precision_1: 0.2800 - recall_1: 0.6792 - f1_score: 0.2257 - val_loss:

0.1767 - val_accuracy: 0.9913 - val_precision_1: 0.2696 - val_recall_1: 0.8163 - val_f1_score: 0.2269

Epoch 40/50

2/2 [=====] - 5s 3s/step - loss: 0.3496 - accuracy: 0.9919 - precision_1: 0.2661 - recall_1: 0.6932 - f1_score: 0.2289 - val_loss: 0.1723 - val_accuracy: 0.9915 - val_precision_1: 0.2744 - val_recall_1: 0.8158 - val_f1_score: 0.2301

Epoch 41/50

2/2 [=====] - 5s 3s/step - loss: 0.3424 - accuracy: 0.9923 - precision_1: 0.2771 - recall_1: 0.6889 - f1_score: 0.2320 - val_loss: 0.1637 - val_accuracy: 0.9923 - val_precision_1: 0.2959 - val_recall_1: 0.8091 - val_f1_score: 0.2332

Epoch 42/50

2/2 [=====] - 5s 3s/step - loss: 0.3365 - accuracy: 0.9929 - precision_1: 0.2968 - recall_1: 0.6778 - f1_score: 0.2353 - val_loss: 0.1605 - val_accuracy: 0.9925 - val_precision_1: 0.3006 - val_recall_1: 0.8102 - val_f1_score: 0.2364

Epoch 43/50

2/2 [=====] - 5s 3s/step - loss: 0.3306 - accuracy: 0.9929 - precision_1: 0.2952 - recall_1: 0.6828 - f1_score: 0.2383 - val_loss: 0.1636 - val_accuracy: 0.9919 - val_precision_1: 0.2861 - val_recall_1: 0.8247 - val_f1_score: 0.2395

Epoch 44/50

2/2 [=====] - 5s 3s/step - loss: 0.3255 - accuracy: 0.9924 - precision_1: 0.2810 - recall_1: 0.6973 - f1_score: 0.2414 - val_loss: 0.1625 - val_accuracy: 0.9918 - val_precision_1: 0.2853 - val_recall_1: 0.8309 - val_f1_score: 0.2424

Epoch 45/50

2/2 [=====] - 6s 3s/step - loss: 0.3204 - accuracy: 0.9925 - precision_1: 0.2861 - recall_1: 0.6979 - f1_score: 0.2442 - val_loss: 0.1549 - val_accuracy: 0.9925 - val_precision_1: 0.3033 - val_recall_1: 0.8264 - val_f1_score: 0.2453

Epoch 46/50

2/2 [=====] - 5s 3s/step - loss: 0.3153 - accuracy: 0.9930 - precision_1: 0.3021 - recall_1: 0.6892 - f1_score: 0.2471 - val_loss: 0.1518 - val_accuracy: 0.9925 - val_precision_1: 0.3055 - val_recall_1: 0.8287 - val_f1_score: 0.2482

Epoch 47/50

2/2 [=====] - 5s 3s/step - loss: 0.3106 - accuracy: 0.9931 - precision_1: 0.3037 - recall_1: 0.6918 - f1_score: 0.2499 - val_loss: 0.1523 - val_accuracy: 0.9923 - val_precision_1: 0.2980 - val_recall_1: 0.8343 - val_f1_score: 0.2510

Epoch 48/50

2/2 [=====] - 5s 3s/step - loss: 0.3063 - accuracy: 0.9927 - precision_1: 0.2929 - recall_1: 0.7028 - f1_score: 0.2527 - val_loss: 0.1520 - val_accuracy: 0.9921 - val_precision_1: 0.2944 - val_recall_1: 0.8371 - val_f1_score: 0.2536

Epoch 49/50

```

2/2 [=====] - 6s 3s/step - loss: 0.3021 - accuracy:
0.9928 - precision_1: 0.2950 - recall_1: 0.7042 - f1_score: 0.2553 - val_loss:
0.1459 - val_accuracy: 0.9927 - val_precision_1: 0.3102 - val_recall_1: 0.8337 -
val_f1_score: 0.2563
Epoch 50/50
2/2 [=====] - 5s 3s/step - loss: 0.2980 - accuracy:
0.9931 - precision_1: 0.3063 - recall_1: 0.6978 - f1_score: 0.2579 - val_loss:
0.1438 - val_accuracy: 0.9927 - val_precision_1: 0.3124 - val_recall_1: 0.8343 -
val_f1_score: 0.2589

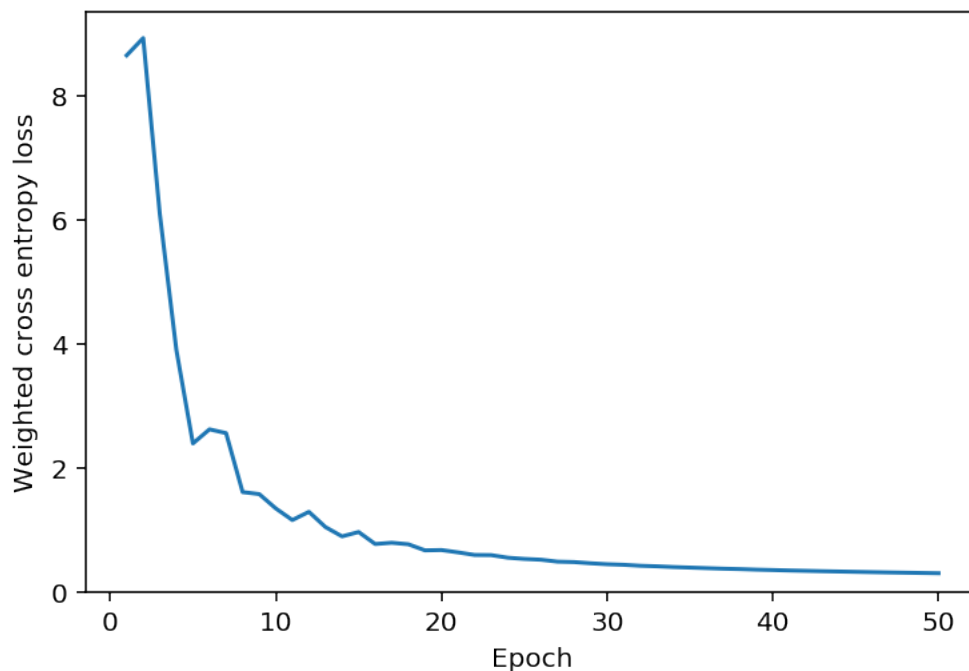
```

```
[72]: <keras.callbacks.History at 0x1e09af2bbc8>
```

```

[73]: plt.plot(range(1,epochs+1), loss_list1[num_batches-1::num_batches])
plt.xlabel('Epoch')
plt.ylabel('Weighted cross entropy loss')
plt.ylim(0)
plt.show()

```



```
[74]: model1.summary()
```

```
Model: "sequential_4"
```

Layer (type)	Output Shape	Param #
conv2d_6 (Conv2D)	(None, 128, 128, 12)	120

```

-----
conv2d_7 (Conv2D)          (None, 128, 128, 32)      3488
-----
conv2d_8 (Conv2D)          (None, 128, 128, 2)       578
-----
activation_2 (Activation)  (None, 128, 128, 2)       0
=====
Total params: 4,186
Trainable params: 4,186
Non-trainable params: 0
-----

```

1.0.2 CNN-LSTM

```
[88]: loss_list2 = list()
```

```

class SaveBatchLoss2(tf.keras.callbacks.Callback):
    def on_train_batch_end(self, batch, logs=None):
        loss_list2.append(logs['loss'])

```

```

[89]: # check which percentage is particles
num_part = tf.math.reduce_sum(train_labels[:, :, :, :1])
print(1-num_part/(10*10*128*128))

```

```
tf.Tensor(0.9926837158203125, shape=(), dtype=float64)
```

```

[90]: batch_size = 2
epochs = 50

model2 = Sequential()
model2.add(Input((Nt,128,128,1)))
model2.add(ConvLSTM2D(12, kernel_size=(3, 3), padding='same', strides=(1,1),
                    return_sequences=True, data_format='channels_last'))
model2.add(ConvLSTM2D(16, kernel_size=(3, 3), padding='same', strides=(1,1),
                    return_sequences=True, data_format='channels_last'))
model2.add(ConvLSTM2D(2, kernel_size=(3, 3), padding='same', strides=(1,1),
                    return_sequences=True, data_format='channels_last',
                    ↪activation="softmax"))

model2.compile(optimizer='adam',
              loss=weightedLoss(keras.losses.categorical_crossentropy, [0.005, 0.
                    ↪995]),
              metrics=['accuracy', tf.keras.metrics.Precision(name='precision_1',
                    ↪class_id=1),
                    tf.keras.metrics.Recall(name='recall_1', class_id=1),
                    ↪f1_score])

```

```

num_batches = int(train_size/batch_size)
model2.fit(train_vid, train_labels, steps_per_epoch=num_batches, epochs=epochs,
↳ verbose=1,
        validation_data=(val_vid, val_labels), callbacks=SaveBatchLoss2())

```

Epoch 1/50

WARNING:tensorflow:Model was constructed with shape (None, 20, 128, 128, 1) for input KerasTensor(type_spec=TensorSpec(shape=(None, 20, 128, 128, 1), dtype=tf.float32, name='input_6'), name='input_6', description="created by layer 'input_6'"), but it was called on an input with incompatible shape (2, 10, 128, 128, 1).

WARNING:tensorflow:Model was constructed with shape (None, 20, 128, 128, 1) for input KerasTensor(type_spec=TensorSpec(shape=(None, 20, 128, 128, 1), dtype=tf.float32, name='input_6'), name='input_6', description="created by layer 'input_6'"), but it was called on an input with incompatible shape (2, 10, 128, 128, 1).

10/10 [=====] - ETA: 0s - loss: 0.0058 - accuracy:

0.9801 - precision_1: 0.0000e+00 - recall_1: 0.0000e+00 - f1_score:

0.2583WARNING:tensorflow:Model was constructed with shape (None, 20, 128, 128, 1) for input KerasTensor(type_spec=TensorSpec(shape=(None, 20, 128, 128, 1), dtype=tf.float32, name='input_6'), name='input_6', description="created by layer 'input_6'"), but it was called on an input with incompatible shape (None, 10, 128, 128, 1).

10/10 [=====] - 40s 4s/step - loss: 0.0058 - accuracy:

0.9801 - precision_1: 0.0000e+00 - recall_1: 0.0000e+00 - f1_score: 0.2583 -

val_loss: 0.0056 - val_accuracy: 0.9857 - val_precision_1: 0.0000e+00 -

val_recall_1: 0.0000e+00 - val_f1_score: 0.2577

Epoch 2/50

10/10 [=====] - 36s 4s/step - loss: 0.0055 - accuracy:

0.9830 - precision_1: 0.0000e+00 - recall_1: 0.0000e+00 - f1_score: 0.2572 -

val_loss: 0.0050 - val_accuracy: 0.9780 - val_precision_1: 0.0000e+00 -

val_recall_1: 0.0000e+00 - val_f1_score: 0.2566

Epoch 3/50

10/10 [=====] - 36s 4s/step - loss: 0.0047 - accuracy:

0.9552 - precision_1: 0.0000e+00 - recall_1: 0.0000e+00 - f1_score: 0.2560 -

val_loss: 0.0038 - val_accuracy: 0.9493 - val_precision_1: 0.0000e+00 -

val_recall_1: 0.0000e+00 - val_f1_score: 0.2554

Epoch 4/50

10/10 [=====] - 36s 4s/step - loss: 0.0039 - accuracy:

0.9480 - precision_1: 0.4286 - recall_1: 2.5027e-04 - f1_score: 0.2549 -

val_loss: 0.0033 - val_accuracy: 0.9336 - val_precision_1: 1.0000 -

val_recall_1: 5.5991e-04 - val_f1_score: 0.2543

Epoch 5/50

10/10 [=====] - 36s 4s/step - loss: 0.0032 - accuracy:

0.9518 - precision_1: 0.0000e+00 - recall_1: 0.0000e+00 - f1_score: 0.2538 -

val_loss: 0.0027 - val_accuracy: 0.9351 - val_precision_1: 1.0000 -

val_recall_1: 0.0011 - val_f1_score: 0.2532

Epoch 6/50
10/10 [=====] - 41s 4s/step - loss: 0.0031 - accuracy: 0.9530 - precision_1: 0.6829 - recall_1: 0.0047 - f1_score: 0.2526 - val_loss: 0.0030 - val_accuracy: 0.9507 - val_precision_1: 0.7500 - val_recall_1: 0.0202 - val_f1_score: 0.2521

Epoch 7/50
10/10 [=====] - 41s 4s/step - loss: 0.0033 - accuracy: 0.9537 - precision_1: 0.6109 - recall_1: 0.0113 - f1_score: 0.2516 - val_loss: 0.0032 - val_accuracy: 0.8821 - val_precision_1: 0.6518 - val_recall_1: 0.0409 - val_f1_score: 0.2511

Epoch 8/50
10/10 [=====] - 36s 4s/step - loss: 0.0031 - accuracy: 0.9299 - precision_1: 0.5165 - recall_1: 0.0652 - f1_score: 0.2507 - val_loss: 0.0025 - val_accuracy: 0.9539 - val_precision_1: 0.5075 - val_recall_1: 0.1333 - val_f1_score: 0.2505

Epoch 9/50
10/10 [=====] - 36s 4s/step - loss: 0.0029 - accuracy: 0.9490 - precision_1: 0.4700 - recall_1: 0.1175 - f1_score: 0.2503 - val_loss: 0.0023 - val_accuracy: 0.9535 - val_precision_1: 0.5000 - val_recall_1: 0.1568 - val_f1_score: 0.2502

Epoch 10/50
10/10 [=====] - 36s 4s/step - loss: 0.0026 - accuracy: 0.9465 - precision_1: 0.5326 - recall_1: 0.1281 - f1_score: 0.2501 - val_loss: 0.0021 - val_accuracy: 0.9560 - val_precision_1: 0.5800 - val_recall_1: 0.1299 - val_f1_score: 0.2500

Epoch 11/50
10/10 [=====] - 36s 4s/step - loss: 0.0022 - accuracy: 0.9458 - precision_1: 0.5736 - recall_1: 0.1271 - f1_score: 0.2498 - val_loss: 0.0019 - val_accuracy: 0.9473 - val_precision_1: 0.5991 - val_recall_1: 0.1557 - val_f1_score: 0.2498

Epoch 12/50
10/10 [=====] - 35s 4s/step - loss: 0.0021 - accuracy: 0.9525 - precision_1: 0.5947 - recall_1: 0.1184 - f1_score: 0.2496 - val_loss: 0.0018 - val_accuracy: 0.9465 - val_precision_1: 0.5565 - val_recall_1: 0.1405 - val_f1_score: 0.2495

Epoch 13/50
10/10 [=====] - 33s 3s/step - loss: 0.0019 - accuracy: 0.9542 - precision_1: 0.5711 - recall_1: 0.1226 - f1_score: 0.2494 - val_loss: 0.0016 - val_accuracy: 0.9616 - val_precision_1: 0.5773 - val_recall_1: 0.1109 - val_f1_score: 0.2492

Epoch 14/50
10/10 [=====] - 34s 3s/step - loss: 0.0018 - accuracy: 0.9549 - precision_1: 0.5655 - recall_1: 0.0925 - f1_score: 0.2491 - val_loss: 0.0015 - val_accuracy: 0.9658 - val_precision_1: 0.6000 - val_recall_1: 0.0739 - val_f1_score: 0.2488

Epoch 15/50
10/10 [=====] - 34s 3s/step - loss: 0.0017 - accuracy: 0.9497 - precision_1: 0.6232 - recall_1: 0.0817 - f1_score: 0.2485 - val_loss:

0.0014 - val_accuracy: 0.9589 - val_precision_1: 0.5851 - val_recall_1: 0.0616 - val_f1_score: 0.2483

Epoch 16/50

10/10 [=====] - 36s 4s/step - loss: 0.0016 - accuracy: 0.9504 - precision_1: 0.6567 - recall_1: 0.0732 - f1_score: 0.2480 - val_loss: 0.0013 - val_accuracy: 0.9644 - val_precision_1: 0.6373 - val_recall_1: 0.0728 - val_f1_score: 0.2477

Epoch 17/50

10/10 [=====] - 35s 4s/step - loss: 0.0015 - accuracy: 0.9547 - precision_1: 0.6742 - recall_1: 0.0767 - f1_score: 0.2475 - val_loss: 0.0013 - val_accuracy: 0.9678 - val_precision_1: 0.6386 - val_recall_1: 0.0722 - val_f1_score: 0.2472

Epoch 18/50

10/10 [=====] - 34s 3s/step - loss: 0.0016 - accuracy: 0.9607 - precision_1: 0.6859 - recall_1: 0.0902 - f1_score: 0.2470 - val_loss: 0.0013 - val_accuracy: 0.9667 - val_precision_1: 0.6694 - val_recall_1: 0.0918 - val_f1_score: 0.2468

Epoch 19/50

10/10 [=====] - 34s 3s/step - loss: 0.0014 - accuracy: 0.9574 - precision_1: 0.6756 - recall_1: 0.0860 - f1_score: 0.2466 - val_loss: 0.0012 - val_accuracy: 0.9650 - val_precision_1: 0.6579 - val_recall_1: 0.0700 - val_f1_score: 0.2463

Epoch 20/50

10/10 [=====] - 35s 3s/step - loss: 0.0014 - accuracy: 0.9578 - precision_1: 0.6717 - recall_1: 0.0669 - f1_score: 0.2461 - val_loss: 0.0012 - val_accuracy: 0.9643 - val_precision_1: 0.6420 - val_recall_1: 0.0633 - val_f1_score: 0.2458

Epoch 21/50

10/10 [=====] - 36s 4s/step - loss: 0.0013 - accuracy: 0.9643 - precision_1: 0.6550 - recall_1: 0.0672 - f1_score: 0.2455 - val_loss: 0.0012 - val_accuracy: 0.9583 - val_precision_1: 0.5927 - val_recall_1: 0.0823 - val_f1_score: 0.2452

Epoch 22/50

10/10 [=====] - 35s 3s/step - loss: 0.0013 - accuracy: 0.9650 - precision_1: 0.6960 - recall_1: 0.1003 - f1_score: 0.2450 - val_loss: 0.0011 - val_accuracy: 0.9586 - val_precision_1: 0.6986 - val_recall_1: 0.1103 - val_f1_score: 0.2449

Epoch 23/50

10/10 [=====] - 36s 4s/step - loss: 0.0013 - accuracy: 0.9597 - precision_1: 0.7115 - recall_1: 0.0979 - f1_score: 0.2447 - val_loss: 0.0011 - val_accuracy: 0.9698 - val_precision_1: 0.6991 - val_recall_1: 0.0845 - val_f1_score: 0.2446

Epoch 24/50

10/10 [=====] - 36s 4s/step - loss: 0.0012 - accuracy: 0.9688 - precision_1: 0.7190 - recall_1: 0.0939 - f1_score: 0.2444 - val_loss: 9.8384e-04 - val_accuracy: 0.9756 - val_precision_1: 0.6840 - val_recall_1: 0.0885 - val_f1_score: 0.2442

Epoch 25/50

10/10 [=====] - 37s 4s/step - loss: 0.0011 - accuracy: 0.9691 - precision_1: 0.7038 - recall_1: 0.0975 - f1_score: 0.2440 - val_loss: 9.7861e-04 - val_accuracy: 0.9729 - val_precision_1: 0.6640 - val_recall_1: 0.0941 - val_f1_score: 0.2439

Epoch 26/50

10/10 [=====] - 36s 4s/step - loss: 0.0011 - accuracy: 0.9650 - precision_1: 0.7073 - recall_1: 0.1080 - f1_score: 0.2437 - val_loss: 9.9471e-04 - val_accuracy: 0.9648 - val_precision_1: 0.6690 - val_recall_1: 0.1053 - val_f1_score: 0.2436

Epoch 27/50

10/10 [=====] - 37s 4s/step - loss: 0.0011 - accuracy: 0.9694 - precision_1: 0.7228 - recall_1: 0.1009 - f1_score: 0.2434 - val_loss: 9.4111e-04 - val_accuracy: 0.9697 - val_precision_1: 0.7111 - val_recall_1: 0.1075 - val_f1_score: 0.2433

Epoch 28/50

10/10 [=====] - 36s 4s/step - loss: 0.0011 - accuracy: 0.9689 - precision_1: 0.7158 - recall_1: 0.1065 - f1_score: 0.2432 - val_loss: 8.7831e-04 - val_accuracy: 0.9710 - val_precision_1: 0.7257 - val_recall_1: 0.1170 - val_f1_score: 0.2430

Epoch 29/50

10/10 [=====] - 37s 4s/step - loss: 0.0011 - accuracy: 0.9659 - precision_1: 0.7252 - recall_1: 0.1068 - f1_score: 0.2429 - val_loss: 9.4258e-04 - val_accuracy: 0.9627 - val_precision_1: 0.7068 - val_recall_1: 0.0985 - val_f1_score: 0.2428

Epoch 30/50

10/10 [=====] - 37s 4s/step - loss: 0.0011 - accuracy: 0.9639 - precision_1: 0.7334 - recall_1: 0.1014 - f1_score: 0.2426 - val_loss: 0.0010 - val_accuracy: 0.9594 - val_precision_1: 0.6990 - val_recall_1: 0.1170 - val_f1_score: 0.2425

Epoch 31/50

10/10 [=====] - 36s 4s/step - loss: 0.0010 - accuracy: 0.9695 - precision_1: 0.7252 - recall_1: 0.1054 - f1_score: 0.2424 - val_loss: 9.2951e-04 - val_accuracy: 0.9635 - val_precision_1: 0.7323 - val_recall_1: 0.1041 - val_f1_score: 0.2422

Epoch 32/50

10/10 [=====] - 37s 4s/step - loss: 0.0010 - accuracy: 0.9685 - precision_1: 0.7216 - recall_1: 0.0891 - f1_score: 0.2421 - val_loss: 9.3777e-04 - val_accuracy: 0.9599 - val_precision_1: 0.7174 - val_recall_1: 0.1109 - val_f1_score: 0.2419

Epoch 33/50

10/10 [=====] - 37s 4s/step - loss: 9.9412e-04 - accuracy: 0.9690 - precision_1: 0.7394 - recall_1: 0.1044 - f1_score: 0.2418 - val_loss: 8.3993e-04 - val_accuracy: 0.9690 - val_precision_1: 0.7113 - val_recall_1: 0.1159 - val_f1_score: 0.2416

Epoch 34/50

10/10 [=====] - 37s 4s/step - loss: 9.5458e-04 - accuracy: 0.9705 - precision_1: 0.7168 - recall_1: 0.1058 - f1_score: 0.2415 - val_loss: 8.7521e-04 - val_accuracy: 0.9667 - val_precision_1: 0.7051 -

val_recall_1: 0.1165 - val_f1_score: 0.2414

Epoch 35/50

10/10 [=====] - 37s 4s/step - loss: 9.3119e-04 -
accuracy: 0.9752 - precision_1: 0.7557 - recall_1: 0.1071 - f1_score: 0.2413 -
val_loss: 8.1733e-04 - val_accuracy: 0.9709 - val_precision_1: 0.7382 -
val_recall_1: 0.1137 - val_f1_score: 0.2412

Epoch 36/50

10/10 [=====] - 37s 4s/step - loss: 9.0908e-04 -
accuracy: 0.9746 - precision_1: 0.7546 - recall_1: 0.1100 - f1_score: 0.2410 -
val_loss: 7.8211e-04 - val_accuracy: 0.9718 - val_precision_1: 0.7668 -
val_recall_1: 0.1344 - val_f1_score: 0.2410

Epoch 37/50

10/10 [=====] - 37s 4s/step - loss: 8.9394e-04 -
accuracy: 0.9720 - precision_1: 0.7650 - recall_1: 0.1445 - f1_score: 0.2409 -
val_loss: 7.6925e-04 - val_accuracy: 0.9758 - val_precision_1: 0.8787 -
val_recall_1: 0.1501 - val_f1_score: 0.2410

Epoch 38/50

10/10 [=====] - 37s 4s/step - loss: 9.7315e-04 -
accuracy: 0.9709 - precision_1: 0.8095 - recall_1: 0.1543 - f1_score: 0.2410 -
val_loss: 7.6086e-04 - val_accuracy: 0.9720 - val_precision_1: 0.8386 -
val_recall_1: 0.2066 - val_f1_score: 0.2411

Epoch 39/50

10/10 [=====] - 38s 4s/step - loss: 8.9251e-04 -
accuracy: 0.9707 - precision_1: 0.7681 - recall_1: 0.1931 - f1_score: 0.2412 -
val_loss: 7.1644e-04 - val_accuracy: 0.9733 - val_precision_1: 0.8194 -
val_recall_1: 0.2133 - val_f1_score: 0.2414

Epoch 40/50

10/10 [=====] - 37s 4s/step - loss: 8.5011e-04 -
accuracy: 0.9738 - precision_1: 0.7396 - recall_1: 0.1881 - f1_score: 0.2416 -
val_loss: 6.8593e-04 - val_accuracy: 0.9740 - val_precision_1: 0.7744 -
val_recall_1: 0.1999 - val_f1_score: 0.2417

Epoch 41/50

10/10 [=====] - 36s 4s/step - loss: 8.0731e-04 -
accuracy: 0.9746 - precision_1: 0.7439 - recall_1: 0.1766 - f1_score: 0.2418 -
val_loss: 6.7548e-04 - val_accuracy: 0.9723 - val_precision_1: 0.7719 -
val_recall_1: 0.2027 - val_f1_score: 0.2420

Epoch 42/50

10/10 [=====] - 36s 4s/step - loss: 7.9422e-04 -
accuracy: 0.9749 - precision_1: 0.7557 - recall_1: 0.1791 - f1_score: 0.2421 -
val_loss: 6.9754e-04 - val_accuracy: 0.9687 - val_precision_1: 0.7884 -
val_recall_1: 0.2357 - val_f1_score: 0.2422

Epoch 43/50

10/10 [=====] - 36s 4s/step - loss: 7.8828e-04 -
accuracy: 0.9755 - precision_1: 0.7532 - recall_1: 0.1828 - f1_score: 0.2424 -
val_loss: 8.0602e-04 - val_accuracy: 0.9582 - val_precision_1: 0.7554 -
val_recall_1: 0.2335 - val_f1_score: 0.2425

Epoch 44/50

10/10 [=====] - 36s 4s/step - loss: 8.8035e-04 -

```

accuracy: 0.9685 - precision_1: 0.7438 - recall_1: 0.1708 - f1_score: 0.2426 -
val_loss: 8.5405e-04 - val_accuracy: 0.9522 - val_precision_1: 0.7214 -
val_recall_1: 0.2363 - val_f1_score: 0.2427
Epoch 45/50
10/10 [=====] - 36s 4s/step - loss: 8.5774e-04 -
accuracy: 0.9701 - precision_1: 0.7268 - recall_1: 0.1795 - f1_score: 0.2428 -
val_loss: 8.5326e-04 - val_accuracy: 0.9521 - val_precision_1: 0.7012 -
val_recall_1: 0.2615 - val_f1_score: 0.2430
Epoch 46/50
10/10 [=====] - 36s 4s/step - loss: 8.3066e-04 -
accuracy: 0.9733 - precision_1: 0.7092 - recall_1: 0.1916 - f1_score: 0.2431 -
val_loss: 7.8960e-04 - val_accuracy: 0.9589 - val_precision_1: 0.6987 -
val_recall_1: 0.2324 - val_f1_score: 0.2433
Epoch 47/50
10/10 [=====] - 37s 4s/step - loss: 8.1517e-04 -
accuracy: 0.9743 - precision_1: 0.7005 - recall_1: 0.1906 - f1_score: 0.2434 -
val_loss: 6.9579e-04 - val_accuracy: 0.9704 - val_precision_1: 0.7350 -
val_recall_1: 0.2531 - val_f1_score: 0.2436
Epoch 48/50
10/10 [=====] - 36s 4s/step - loss: 7.7358e-04 -
accuracy: 0.9748 - precision_1: 0.6978 - recall_1: 0.1942 - f1_score: 0.2438 -
val_loss: 7.0020e-04 - val_accuracy: 0.9679 - val_precision_1: 0.7355 -
val_recall_1: 0.2912 - val_f1_score: 0.2440
Epoch 49/50
10/10 [=====] - 37s 4s/step - loss: 7.8194e-04 -
accuracy: 0.9747 - precision_1: 0.7088 - recall_1: 0.2547 - f1_score: 0.2443 -
val_loss: 7.7402e-04 - val_accuracy: 0.9606 - val_precision_1: 0.7345 -
val_recall_1: 0.3639 - val_f1_score: 0.2447
Epoch 50/50
10/10 [=====] - 40s 4s/step - loss: 8.2024e-04 -
accuracy: 0.9730 - precision_1: 0.7444 - recall_1: 0.2573 - f1_score: 0.2450 -
val_loss: 8.3197e-04 - val_accuracy: 0.9537 - val_precision_1: 0.7039 -
val_recall_1: 0.3701 - val_f1_score: 0.2454

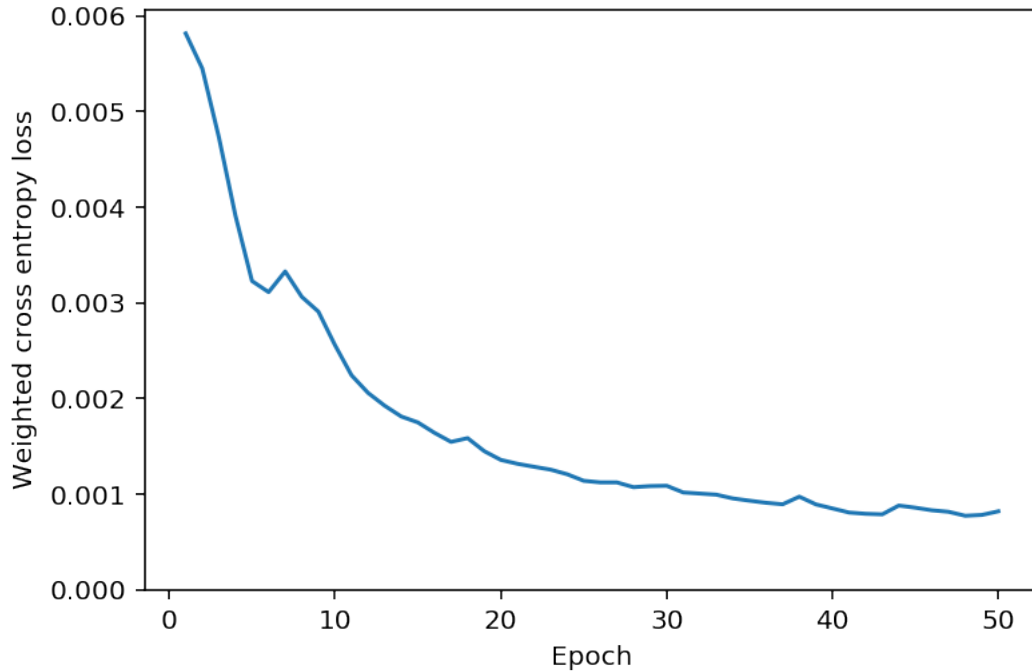
```

[90]: <keras.callbacks.History at 0x1e0992282c8>

```

[92]: plt.plot(range(1,epochs+1), loss_list2[num_batches-1::num_batches])
plt.xlabel('Epoch')
plt.ylabel('Weighted cross entropy loss')
plt.ylim(0)
plt.show()

```



```
[93]: model2.summary()
```

Model: "sequential_5"

Layer (type)	Output Shape	Param #
conv_lst_m2d_6 (ConvLSTM2D)	(None, 20, 128, 128, 12)	5664
conv_lst_m2d_7 (ConvLSTM2D)	(None, 20, 128, 128, 16)	16192
conv_lst_m2d_8 (ConvLSTM2D)	(None, 20, 128, 128, 2)	1304

Total params: 23,160
 Trainable params: 23,160
 Non-trainable params: 0

1.0.3 Visualizing the results

```
[94]: Nt = 20
pt_test = Particle_Tracking_Training_Data(Nt)
vid, labels, tracks = pt_test(kappa, a, lbackLevel, Nparticles_det,
    ↪sigma_motion)
input_vid = tf.expand_dims(vid[:,:,:2,:,:2], 3)
```

```
[95]: # get model predictions
#pred = model1.predict(input_vid)
pred = model2.predict(tf.expand_dims(input_vid,0))[0]
```

```
[100]: # convert predictions to binary output
threshold = 0.4
pred_bin = pred.copy()
pred_bin[pred_bin <= threshold] = 0
pred_bin[pred_bin > threshold] = 1
```

```
[101]: @interact(t=(0, Nt-1, 1))
def plotfn(t=0, show_tracks=True):
    fig = figure(1, [14, 7])
    fig.add_subplot(131)
    imshow(vid[t], origin='lower')
    #if show_tracks:
    #    plot(tracks[t, :, 0], tracks[t, :, 1], 'rx')
    xlim(0, 255)
    ylim(0, 255)
    plt.title('Input image', fontsize=25)

    fig.add_subplot(132)
    imshow(vid[t], origin='lower')
    imshow(pred_bin[t, ..., 1], origin='lower')
    plt.title('Predicted particles', fontsize=25)

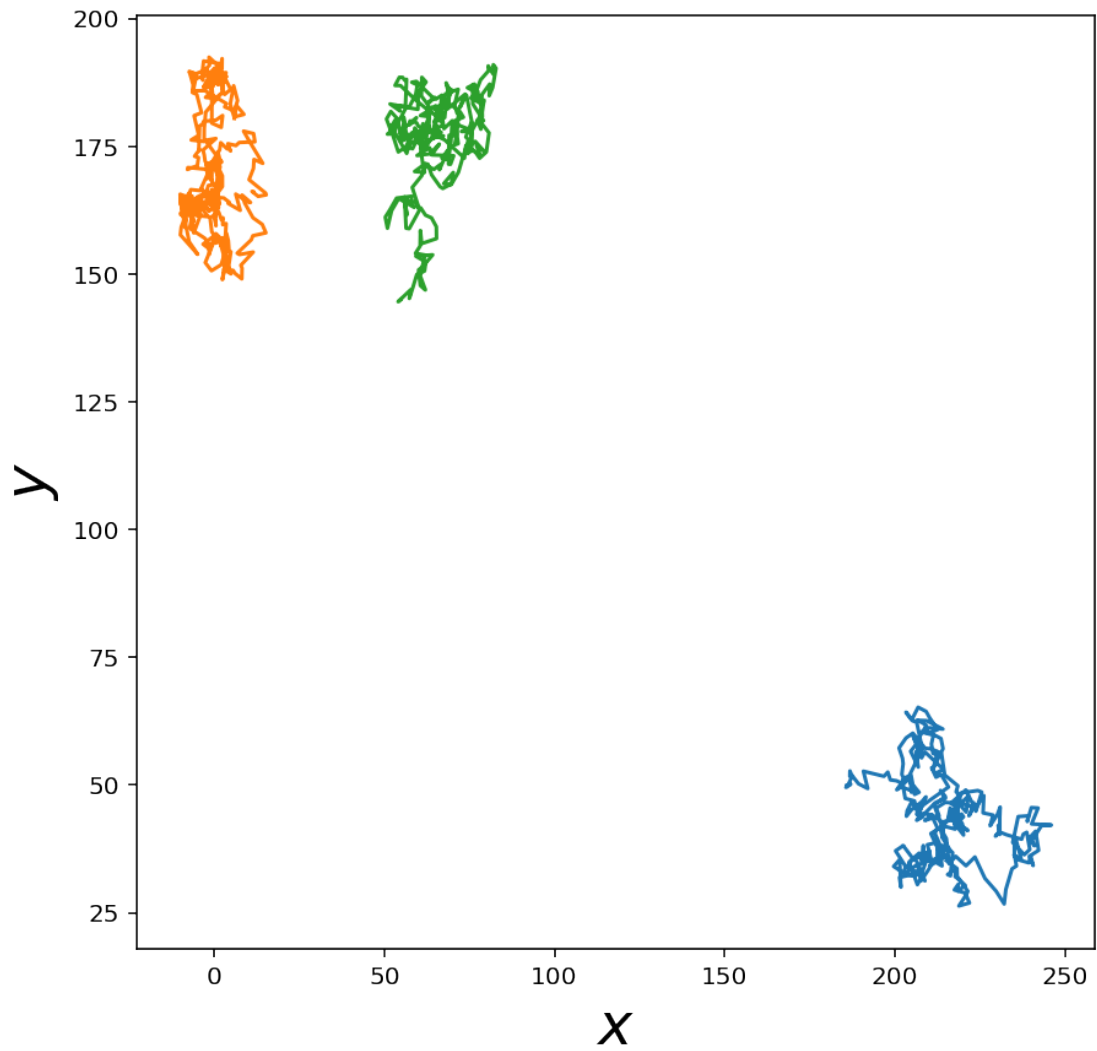
    fig.add_subplot(133)
    imshow(vid[t], origin='lower')
    imshow(labels[t, ..., 1], origin='lower')
    plt.title('Ground truth', fontsize=25)
```

```
interactive(children=(IntSlider(value=0, description='t', max=19),
    Checkbox(value=True, description='show_trac...
```

```
[ ]:
```

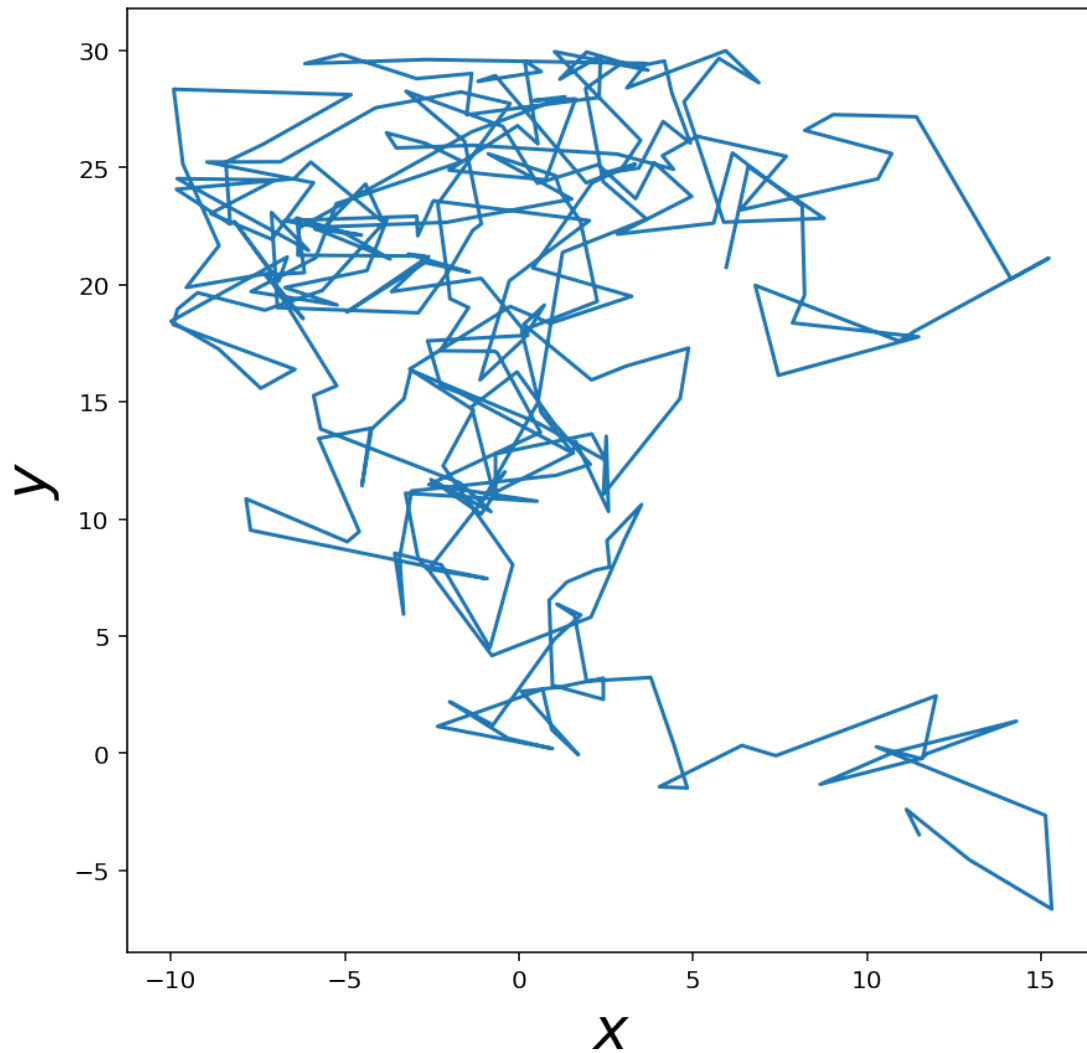
2 Tracking the Particles

```
[9]: figure(1, [7, 7])
plot(tracks[..., 0], tracks[..., 1])
#xlim(-12, 300)
#ylim(-12, 300)
xlabel(r'$x$', fontsize=24)
ylabel(r'$y$', fontsize=24);
```



[]:

```
[11]: figure(1, [7, 7])
      plot(tracks[:,1,0], tracks[:,1,2])
      #xlim(-12, 300)
      #ylim(-12, 300)
      xlabel(r'$x$', fontsize=24)
      ylabel(r'$y$', fontsize=24);
```



```
[115]: X=np.array(tracks[:,0,0])
X_scaled=(X-np.mean(X))/np.std(X)
Y=np.array(tracks[:,0,1])
Y_scaled=(Y-np.mean(Y))/np.std(Y)
```

```
[169]: def get_data(data):
    a_train=[]
    b_train=[]
    for i in range(10,len(data)):
        a_train.append(data[i-10:i])
        b_train.append(data[i])
    a_train, b_train = np.array(a_train), np.array(b_train)
    return(a_train, b_train)
```



```
[170]: X_train, y_train=get_data(X_scaled[:250])
X_test, y_test=get_data(X_scaled[250:])
Xy_train, yy_train=get_data(Y_scaled[:250])
Xy_test, yy_test=get_data(Y_scaled[250:])
```

```
[ ]:
```

```
[ ]:
```

```
[247]: X_train = []
y_train = []
X_train_scaled=X_scaled[:250]
#train_data=train_data.numpy()
for i in range(30,len(X_scaled)):
    X_train.append(X_scaled[i-30:i])
    y_train.append(X_scaled[i])
X_train, y_train = np.array(X_train), np.array(y_train)
```

```
[248]: Xy_train = []
yy_train = []
Xy_train_scaled=Y_scaled[:250]
#train_data=train_data.numpy()
```

```
[ ]: X_test = []
y_test = []

for i in range(30,len(X_scaled)):
    X_train.append(X_scaled[i-30:i])
    y_train.append(X_scaled[i])
X_train, y_train = np.array(X_train), np.array(y_train)

X_test = np.reshape(X_test, (X_test.shape[0],X_test.shape[1],1))
```

```
[ ]:
```

```
[ ]:
```

```
[ ]:
```

```
[210]:
```

```
[ ]:
```

```
[ ]:
```

```
[76]: opt=tf.keras.optimizers.RMSprop(
        learning_rate=0.001
    )
    model = Sequential()
    model.add(CuDNNLSTM(units=32,return_sequences=True, input_shape=(X_train.
        ↪shape[1],1)))
    #model.add(CuDNNLSTM(units=256,return_sequences=True))
    #model.add(CuDNNLSTM(units=128,return_sequences=True))
    #model.add(Dropout(0.2))
    model.add(CuDNNLSTM(units=16,return_sequences=True))
    #model.add(CuDNNLSTM(units=32,return_sequences=True))
    model.add(Dropout(0.2))
    model.add(CuDNNLSTM(units=8,return_sequences=True))
    #model.add(CuDNNLSTM(units=8,return_sequences=True))
    model.add(CuDNNLSTM(units=4,return_sequences=True))
    model.add(Flatten())
    model.add(Dense(1))
    model.compile(optimizer=opt,loss='mean_squared_error',metrics=["mae"])
```

```
[171]: model=Sequential()
    model.add(CuDNNLSTM(units=128,return_sequences=True, input_shape=(X_train.
        ↪shape[1],1)) )
    model.add(Dropout(0.2))
    model.add(CuDNNLSTM(units=64,return_sequences=True) )
    model.add(Dropout(0.2))
    model.add(Flatten())
    model.add(Dense(units=1))
    # Compiling the RNN
    model.compile(optimizer='rmsprop',loss='mean_squared_error')
    # Fitting to the training set
    #model.fit(X_train,y_train,epochs=50,batch_size=16)
```

```
[172]: model.fit(Xy_train,yy_train,epochs=50,batch_size=16,validation_data=(Xy_test[:
        ↪2], yy_test[:2]))
    y_pred = model.predict(Xy_test)
```

Epoch 1/50

15/15 [=====] - 3s 51ms/step - loss: 0.3942 - val_loss: 0.0273

Epoch 2/50

15/15 [=====] - 0s 17ms/step - loss: 0.2671 - val_loss: 0.0733

Epoch 3/50

15/15 [=====] - 0s 14ms/step - loss: 0.2214 - val_loss: 0.0130

Epoch 4/50

15/15 [=====] - 0s 15ms/step - loss: 0.2123 - val_loss:

```

0.0633
Epoch 5/50
15/15 [=====] - 0s 14ms/step - loss: 0.2002 - val_loss:
0.0469
Epoch 6/50
15/15 [=====] - 0s 14ms/step - loss: 0.1866 - val_loss:
0.0533
Epoch 7/50
15/15 [=====] - 0s 14ms/step - loss: 0.1691 - val_loss:
0.1987
Epoch 8/50
15/15 [=====] - 0s 14ms/step - loss: 0.1565 - val_loss:
0.1699
Epoch 9/50
15/15 [=====] - 0s 14ms/step - loss: 0.1450 - val_loss:
0.0362
Epoch 10/50
15/15 [=====] - 0s 14ms/step - loss: 0.1434 - val_loss:
0.0080
Epoch 11/50
15/15 [=====] - 0s 14ms/step - loss: 0.1394 - val_loss:
0.0292
Epoch 12/50
15/15 [=====] - 0s 14ms/step - loss: 0.1349 - val_loss:
0.0361
Epoch 13/50
15/15 [=====] - 0s 14ms/step - loss: 0.1274 - val_loss:
0.0794
Epoch 14/50
15/15 [=====] - 0s 14ms/step - loss: 0.1211 - val_loss:
0.0272
Epoch 15/50
15/15 [=====] - 0s 14ms/step - loss: 0.1308 - val_loss:
0.1241
Epoch 16/50
15/15 [=====] - 0s 15ms/step - loss: 0.1114 - val_loss:
0.1256
Epoch 17/50
15/15 [=====] - 0s 14ms/step - loss: 0.1246 - val_loss:
0.0750
Epoch 18/50
15/15 [=====] - 0s 14ms/step - loss: 0.1083 - val_loss:
0.0807
Epoch 19/50
15/15 [=====] - 0s 14ms/step - loss: 0.1047 - val_loss:
0.3538
Epoch 20/50
15/15 [=====] - 0s 14ms/step - loss: 0.1097 - val_loss:

```

0.1290
Epoch 21/50
15/15 [=====] - 0s 14ms/step - loss: 0.1005 - val_loss:
0.0386
Epoch 22/50
15/15 [=====] - 0s 14ms/step - loss: 0.0917 - val_loss:
0.0923
Epoch 23/50
15/15 [=====] - 0s 14ms/step - loss: 0.0891 - val_loss:
0.1447
Epoch 24/50
15/15 [=====] - 0s 14ms/step - loss: 0.0866 - val_loss:
0.0242
Epoch 25/50
15/15 [=====] - 0s 14ms/step - loss: 0.0836 - val_loss:
0.0344
Epoch 26/50
15/15 [=====] - 0s 14ms/step - loss: 0.0791 - val_loss:
0.0398
Epoch 27/50
15/15 [=====] - 0s 15ms/step - loss: 0.0812 - val_loss:
0.0130
Epoch 28/50
15/15 [=====] - 0s 14ms/step - loss: 0.0772 - val_loss:
0.0553
Epoch 29/50
15/15 [=====] - 0s 14ms/step - loss: 0.0874 - val_loss:
0.0650
Epoch 30/50
15/15 [=====] - 0s 14ms/step - loss: 0.0785 - val_loss:
0.0113
Epoch 31/50
15/15 [=====] - 0s 14ms/step - loss: 0.0745 - val_loss:
0.0046
Epoch 32/50
15/15 [=====] - 0s 15ms/step - loss: 0.0760 - val_loss:
0.0064
Epoch 33/50
15/15 [=====] - 0s 14ms/step - loss: 0.0692 - val_loss:
0.0457
Epoch 34/50
15/15 [=====] - 0s 14ms/step - loss: 0.0792 - val_loss:
0.0433
Epoch 35/50
15/15 [=====] - 0s 14ms/step - loss: 0.0727 - val_loss:
0.0077
Epoch 36/50
15/15 [=====] - 0s 14ms/step - loss: 0.0660 - val_loss:

```

0.0548
Epoch 37/50
15/15 [=====] - 0s 14ms/step - loss: 0.0626 - val_loss:
0.1822
Epoch 38/50
15/15 [=====] - 0s 14ms/step - loss: 0.0756 - val_loss:
0.0087
Epoch 39/50
15/15 [=====] - 0s 15ms/step - loss: 0.0612 - val_loss:
0.0471
Epoch 40/50
15/15 [=====] - 0s 14ms/step - loss: 0.0723 - val_loss:
0.0122
Epoch 41/50
15/15 [=====] - 0s 15ms/step - loss: 0.0667 - val_loss:
0.0166
Epoch 42/50
15/15 [=====] - 0s 14ms/step - loss: 0.0701 - val_loss:
0.0294
Epoch 43/50
15/15 [=====] - 0s 14ms/step - loss: 0.0719 - val_loss:
0.0903
Epoch 44/50
15/15 [=====] - 0s 14ms/step - loss: 0.0723 - val_loss:
0.0355
Epoch 45/50
15/15 [=====] - 0s 14ms/step - loss: 0.0615 - val_loss:
0.0617
Epoch 46/50
15/15 [=====] - 0s 14ms/step - loss: 0.0592 - val_loss:
0.0164
Epoch 47/50
15/15 [=====] - 0s 14ms/step - loss: 0.0651 - val_loss:
0.0809
Epoch 48/50
15/15 [=====] - 0s 14ms/step - loss: 0.0608 - val_loss:
0.0430
Epoch 49/50
15/15 [=====] - 0s 14ms/step - loss: 0.0639 - val_loss:
0.0327
Epoch 50/50
15/15 [=====] - 0s 14ms/step - loss: 0.0631 - val_loss:
0.0348

```

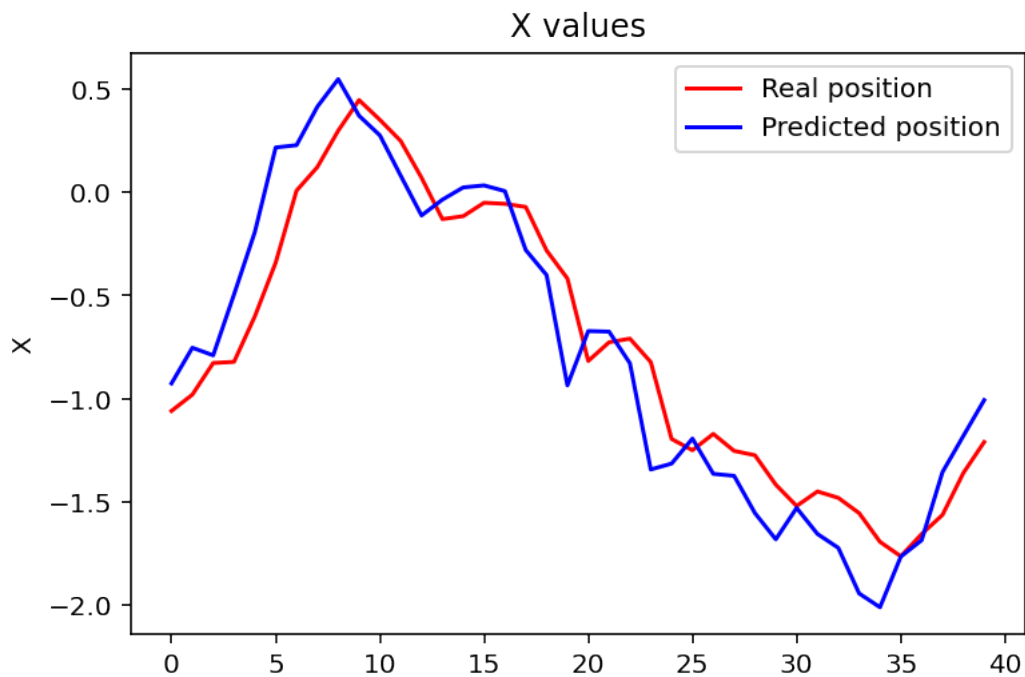
```

[173]: plt.plot(y_pred, color='red',label='Real position')
plt.plot(yy_test, color='blue',label='Predicted position');
plt.title('X values')

```

```
#plt.xlabel('Date')
plt.ylabel('X')
plt.legend()
plt.show()

MSE1=mean_squared_error(y_pred, yy_test, squared=False)
print("MSE = ", MSE1)
```



MSE = 0.23956507

```
[174]: model.fit(X_train,y_train,epochs=50,batch_size=16, validation_data=(X_test[:2],
↪y_test[:2]))
x_pred = model.predict(X_test)
```

```
Epoch 1/50
15/15 [=====] - 0s 20ms/step - loss: 0.0490 - val_loss:
0.0503
Epoch 2/50
15/15 [=====] - 0s 14ms/step - loss: 0.0478 - val_loss:
0.0663
Epoch 3/50
15/15 [=====] - 0s 14ms/step - loss: 0.0443 - val_loss:
0.0869
Epoch 4/50
15/15 [=====] - 0s 14ms/step - loss: 0.0480 - val_loss:
```

```

0.0574
Epoch 5/50
15/15 [=====] - 0s 14ms/step - loss: 0.0452 - val_loss:
0.0537
Epoch 6/50
15/15 [=====] - 0s 15ms/step - loss: 0.0460 - val_loss:
0.0717
Epoch 7/50
15/15 [=====] - 0s 14ms/step - loss: 0.0409 - val_loss:
0.0620
Epoch 8/50
15/15 [=====] - 0s 14ms/step - loss: 0.0392 - val_loss:
0.0819
Epoch 9/50
15/15 [=====] - 0s 14ms/step - loss: 0.0424 - val_loss:
0.0612
Epoch 10/50
15/15 [=====] - 0s 14ms/step - loss: 0.0402 - val_loss:
0.0589
Epoch 11/50
15/15 [=====] - 0s 15ms/step - loss: 0.0414 - val_loss:
0.0709
Epoch 12/50
15/15 [=====] - 0s 14ms/step - loss: 0.0466 - val_loss:
0.0882
Epoch 13/50
15/15 [=====] - 0s 16ms/step - loss: 0.0358 - val_loss:
0.0707
Epoch 14/50
15/15 [=====] - 0s 14ms/step - loss: 0.0393 - val_loss:
0.1082
Epoch 15/50
15/15 [=====] - 0s 14ms/step - loss: 0.0424 - val_loss:
0.0858
Epoch 16/50
15/15 [=====] - 0s 14ms/step - loss: 0.0446 - val_loss:
0.0722
Epoch 17/50
15/15 [=====] - 0s 14ms/step - loss: 0.0465 - val_loss:
0.1270
Epoch 18/50
15/15 [=====] - 0s 14ms/step - loss: 0.0450 - val_loss:
0.0623
Epoch 19/50
15/15 [=====] - 0s 14ms/step - loss: 0.0453 - val_loss:
0.0855
Epoch 20/50
15/15 [=====] - 0s 14ms/step - loss: 0.0437 - val_loss:

```

0.0955
Epoch 21/50
15/15 [=====] - 0s 14ms/step - loss: 0.0375 - val_loss:
0.0755
Epoch 22/50
15/15 [=====] - 0s 14ms/step - loss: 0.0426 - val_loss:
0.0796
Epoch 23/50
15/15 [=====] - 0s 14ms/step - loss: 0.0400 - val_loss:
0.0636
Epoch 24/50
15/15 [=====] - 0s 14ms/step - loss: 0.0423 - val_loss:
0.0743
Epoch 25/50
15/15 [=====] - 0s 14ms/step - loss: 0.0378 - val_loss:
0.0720
Epoch 26/50
15/15 [=====] - 0s 14ms/step - loss: 0.0398 - val_loss:
0.0781
Epoch 27/50
15/15 [=====] - 0s 14ms/step - loss: 0.0428 - val_loss:
0.0781
Epoch 28/50
15/15 [=====] - 0s 14ms/step - loss: 0.0373 - val_loss:
0.0836
Epoch 29/50
15/15 [=====] - 0s 15ms/step - loss: 0.0444 - val_loss:
0.0846
Epoch 30/50
15/15 [=====] - 0s 16ms/step - loss: 0.0395 - val_loss:
0.1001
Epoch 31/50
15/15 [=====] - 0s 15ms/step - loss: 0.0420 - val_loss:
0.0917
Epoch 32/50
15/15 [=====] - 0s 15ms/step - loss: 0.0385 - val_loss:
0.0747
Epoch 33/50
15/15 [=====] - 0s 15ms/step - loss: 0.0390 - val_loss:
0.0739
Epoch 34/50
15/15 [=====] - 0s 14ms/step - loss: 0.0404 - val_loss:
0.0949
Epoch 35/50
15/15 [=====] - 0s 14ms/step - loss: 0.0396 - val_loss:
0.0648
Epoch 36/50
15/15 [=====] - 0s 15ms/step - loss: 0.0358 - val_loss:


```

0.0788
Epoch 37/50
15/15 [=====] - 0s 14ms/step - loss: 0.0376 - val_loss:
0.0836
Epoch 38/50
15/15 [=====] - 0s 14ms/step - loss: 0.0494 - val_loss:
0.0925
Epoch 39/50
15/15 [=====] - 0s 14ms/step - loss: 0.0369 - val_loss:
0.0889
Epoch 40/50
15/15 [=====] - 0s 14ms/step - loss: 0.0383 - val_loss:
0.0903
Epoch 41/50
15/15 [=====] - 0s 14ms/step - loss: 0.0369 - val_loss:
0.0861
Epoch 42/50
15/15 [=====] - 0s 14ms/step - loss: 0.0359 - val_loss:
0.0741
Epoch 43/50
15/15 [=====] - 0s 14ms/step - loss: 0.0395 - val_loss:
0.0815
Epoch 44/50
15/15 [=====] - 0s 16ms/step - loss: 0.0371 - val_loss:
0.0868
Epoch 45/50
15/15 [=====] - 0s 14ms/step - loss: 0.0413 - val_loss:
0.0813
Epoch 46/50
15/15 [=====] - 0s 14ms/step - loss: 0.0415 - val_loss:
0.0933
Epoch 47/50
15/15 [=====] - 0s 14ms/step - loss: 0.0372 - val_loss:
0.0847
Epoch 48/50
15/15 [=====] - 0s 15ms/step - loss: 0.0385 - val_loss:
0.0904
Epoch 49/50
15/15 [=====] - 0s 14ms/step - loss: 0.0394 - val_loss:
0.1009
Epoch 50/50
15/15 [=====] - 0s 15ms/step - loss: 0.0371 - val_loss:
0.0846

```

```

[175]: plt.plot(x_pred, color='red',label='Real position')
plt.plot(y_test, color='blue',label='Predicted position');
plt.title('Y values')

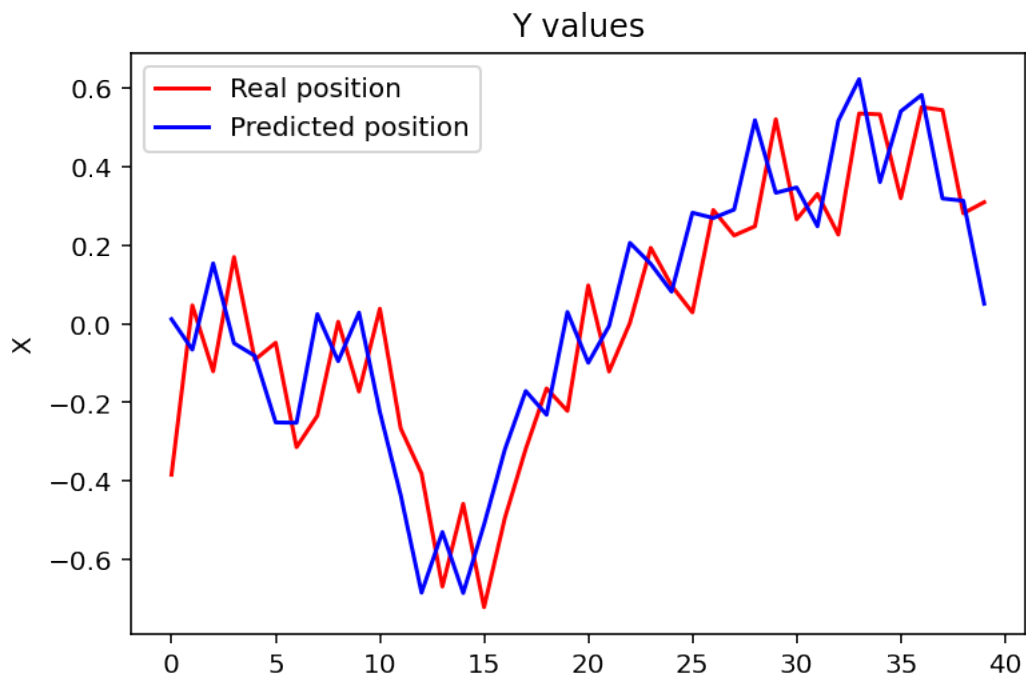
```

```

plt.xlabel('Date')
plt.ylabel('X')
plt.legend()
plt.show()

MSE1=mean_squared_error(x_pred, y_test, squared=False)
print("MSE = ", MSE1)

```



MSE = 0.190686

```
[139]: x_pred
```

```

[139]: array([[ 0.02891346],
              [-0.25876385],
              [-0.09110858],
              [ 0.08409639],
              [-0.03282701],
              [-0.1471768 ],
              [ 0.1513299 ],
              [ 0.12525119],
              [ 0.06137033],
              [ 0.47542968],
              [ 0.11650269],
              [ 0.24012011],
              [ 0.12309794],

```

```

[ 0.4640012 ],
[ 0.4176118 ],
[ 0.29948637],
[ 0.4742349 ],
[ 0.4235113 ],
[ 0.16309182],
[ 0.21584761]], dtype=float32)

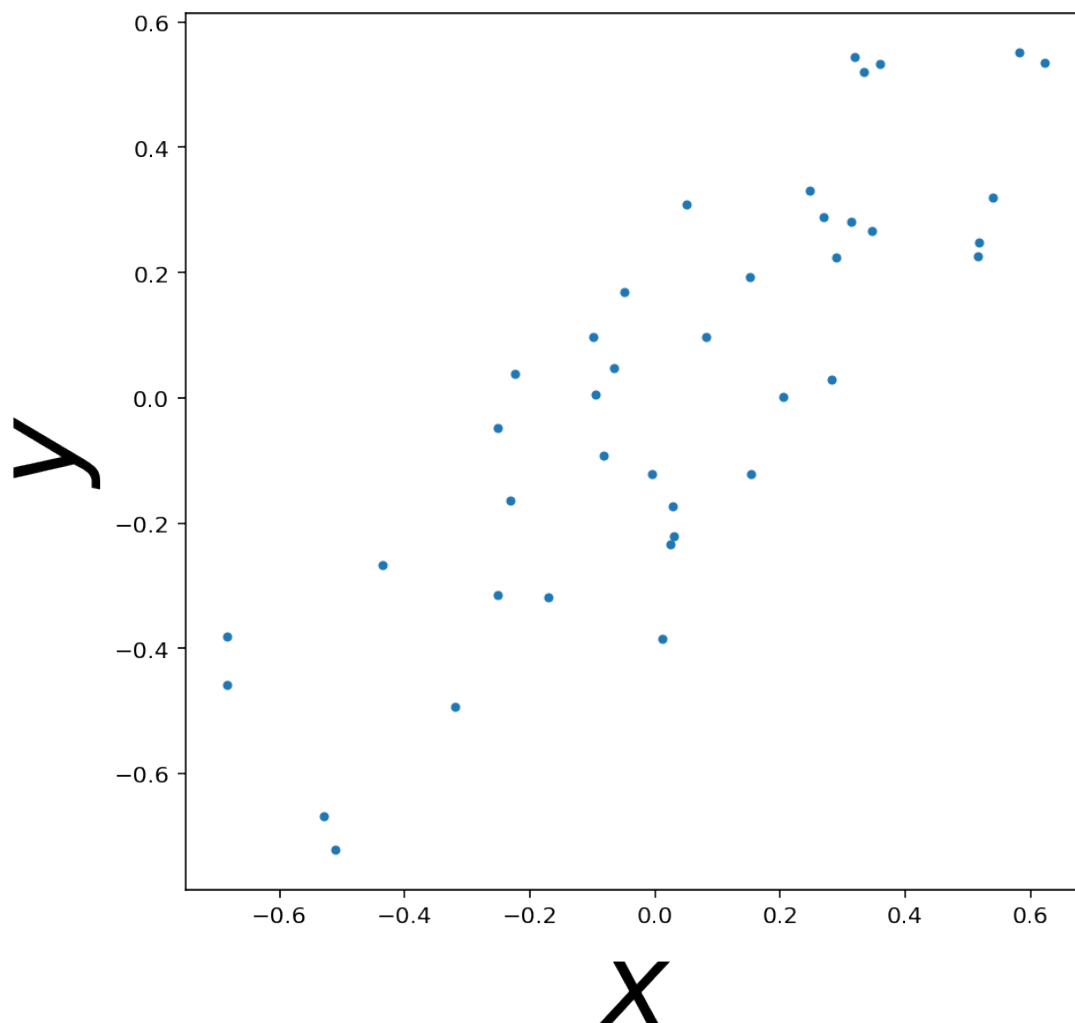
```

```

[176]: figure(1, [7, 7])
plot(y_test,x_pred,'. ')
#xlim(50, 200)
#ylim(50, 200)

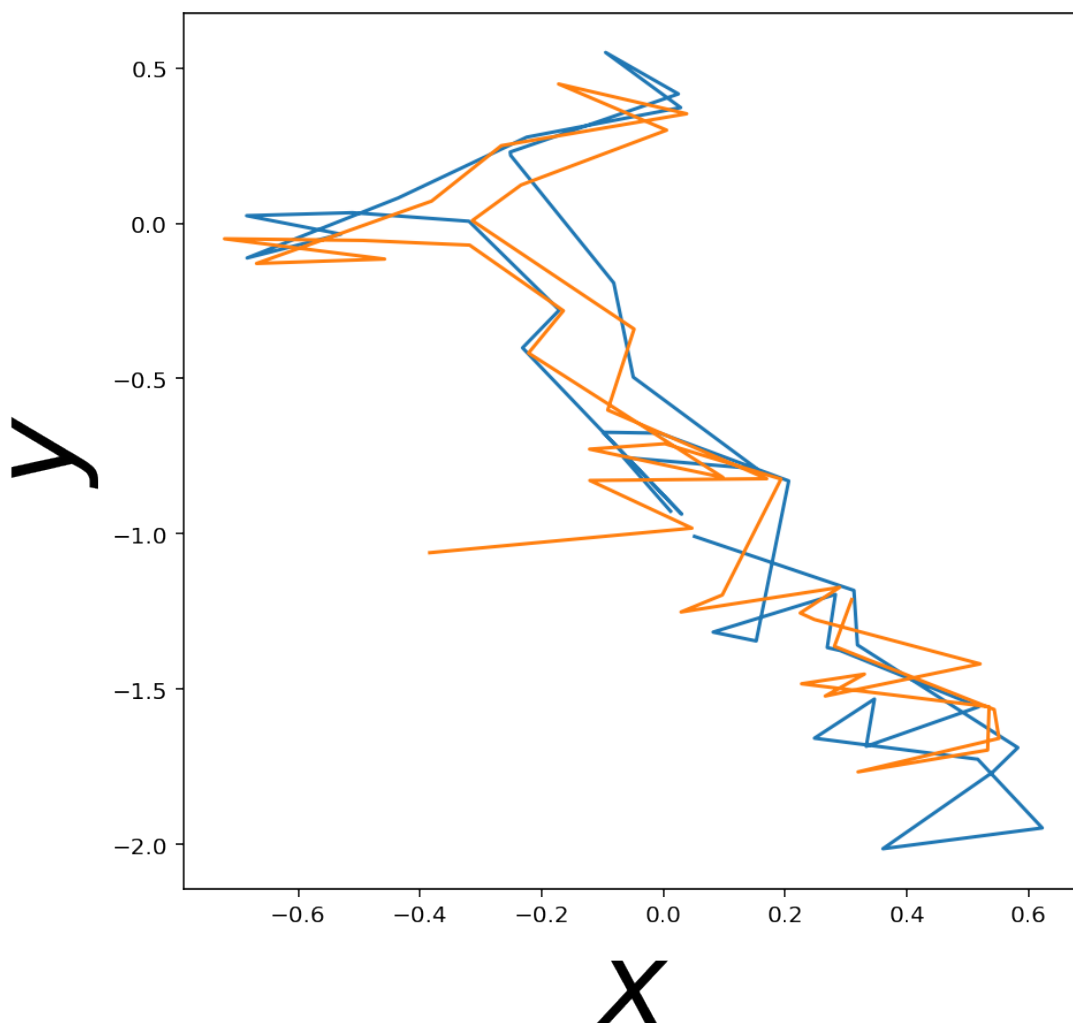
xlabel(r'$x$', fontsize=50)
ylabel(r'$y$', fontsize=50);

```



```
[ ]:
```

```
[178]: figure(1, [7, 7])  
plot(y_test,yy_test)  
#xlim(50, 200)  
#ylim(50, 200)  
plot(x_pred, y_pred)  
  
xlabel(r'$x$', fontsize=50)  
ylabel(r'$y$', fontsize=50);
```



```
[227]: tracks[250:,1,0]
```

```
[227]: <tf.Tensor: shape=(50,), dtype=float32, numpy=
array([140.36302, 140.77554, 142.66766, 143.36247, 138.62723, 139.49977,
      137.80324, 138.58437, 140.95016, 139.20639, 142.53313, 142.88295,
      143.422   , 144.35042, 144.1716  , 147.77264, 148.27075, 149.94284,
      149.1331  , 151.54823, 152.08319, 147.50658, 150.85767, 148.4269  ,
      146.19507, 144.34917, 144.93454, 145.3479  , 146.17107, 144.64603,
      142.63339, 144.39685, 147.15265, 147.89957, 146.23137, 146.45193,
      145.42044, 145.14705, 143.46056, 145.62779, 147.03528, 146.47115,
      146.88373, 144.29402, 147.31657, 150.4178  , 150.03902, 149.02408,
      146.62305, 147.32089], dtype=float32)>
```

```
[242]: values[0][0]
```

```
[242]: array([[150.30185],
      [151.6066  ],
      [150.32213],
      [149.27074],
      [151.90056],
      [153.61559],
      [153.69879],
      [153.30333],
      [152.88086],
      [150.43613],
      [149.56084],
      [149.60457],
      [148.94038],
      [148.6731  ],
      [151.73859],
      [150.84282],
      [148.69049],
      [150.13455],
      [152.71347],
      [152.8232  ]], dtype=float32)
```

```
[243]: y_test
```

```
[243]: array([142.63339, 144.39685, 147.15265, 147.89957, 146.23137, 146.45193,
      145.42044, 145.14705, 143.46056, 145.62779, 147.03528, 146.47115,
      146.88373, 144.29402, 147.31657, 150.4178  , 150.03902, 149.02408,
      146.62305, 147.32089], dtype=float32)
```

```
[ ]:
```