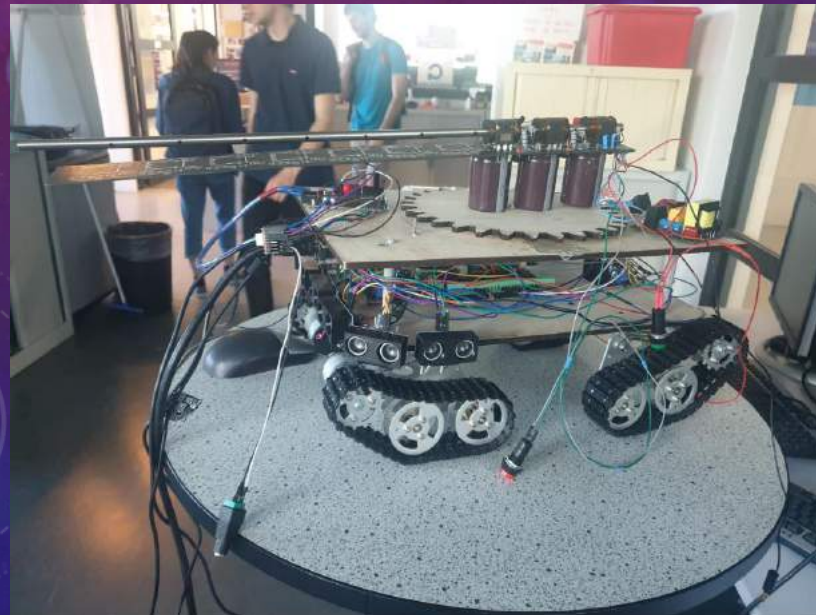


ETUDIANTS : CONSALVI NICOLAS & MIRI YOUSSEF  
ENCADRANTS : PASCAL MASSON

# MILITECH



# PRÉSENTATION DU ROBOT ET DE SES OBJECTIFS



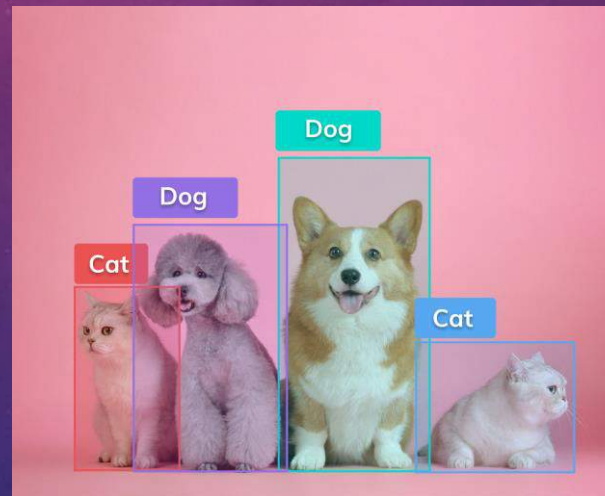
## 1. Navigation dans l'espace:

Deux modes:

- Mode autonome
- Mode dirigé par Bluetooth

## 2.Détection:

- Détection d'objets
- entrainement d'une Intelligence artificielle

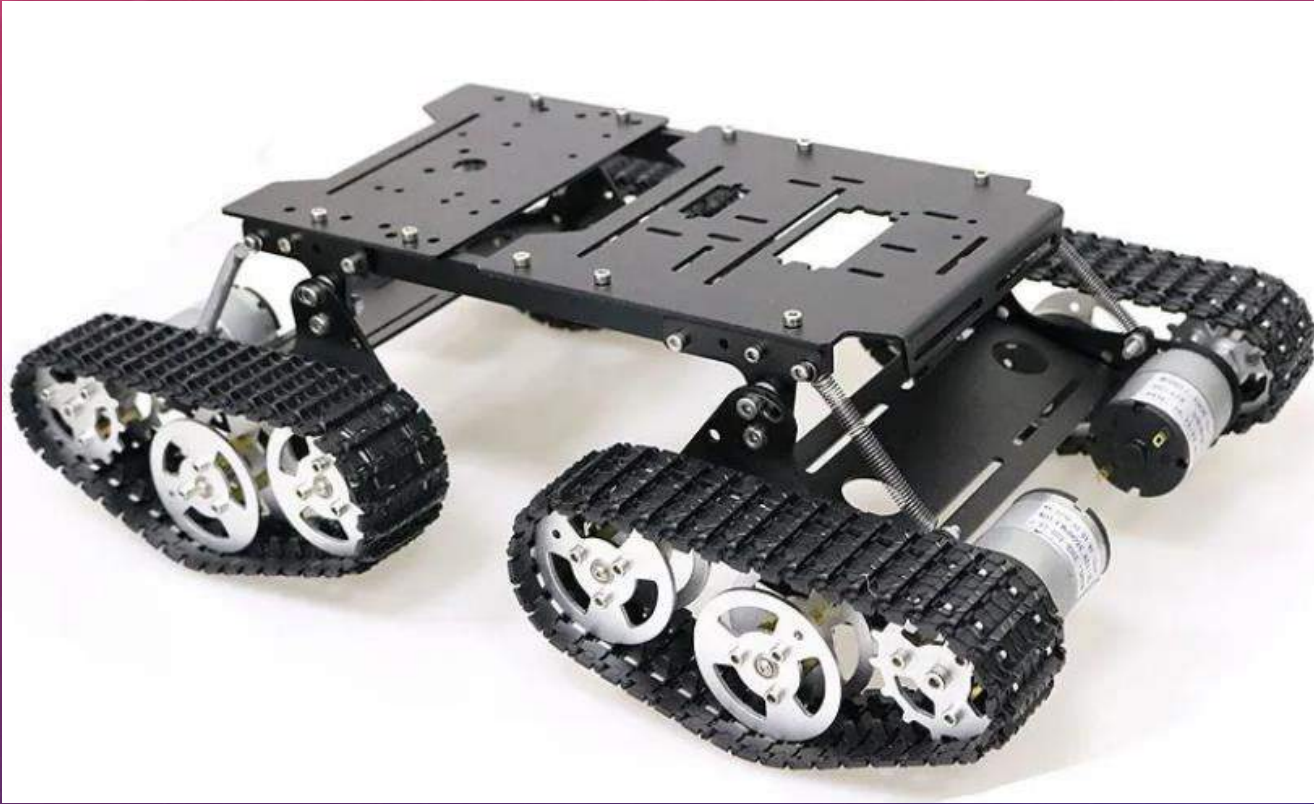


## 3.Neutralisation:

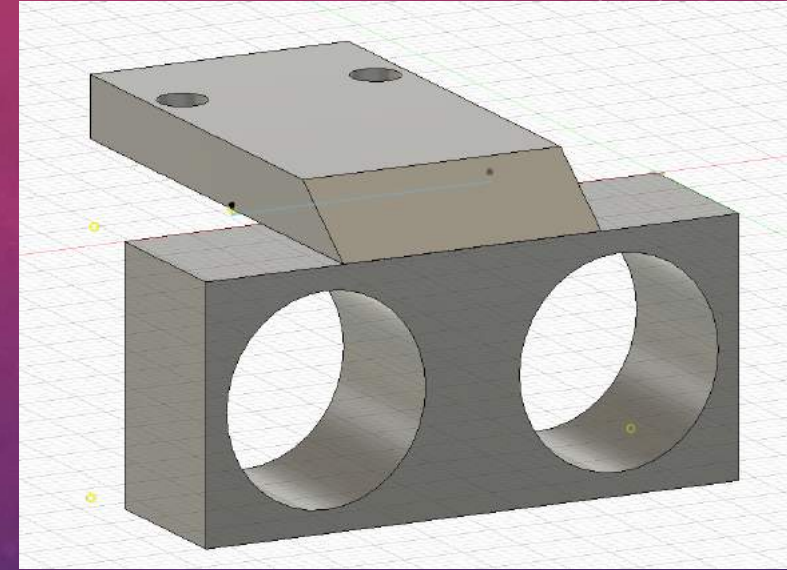
- Canon électromagnétique monté sur tourelle



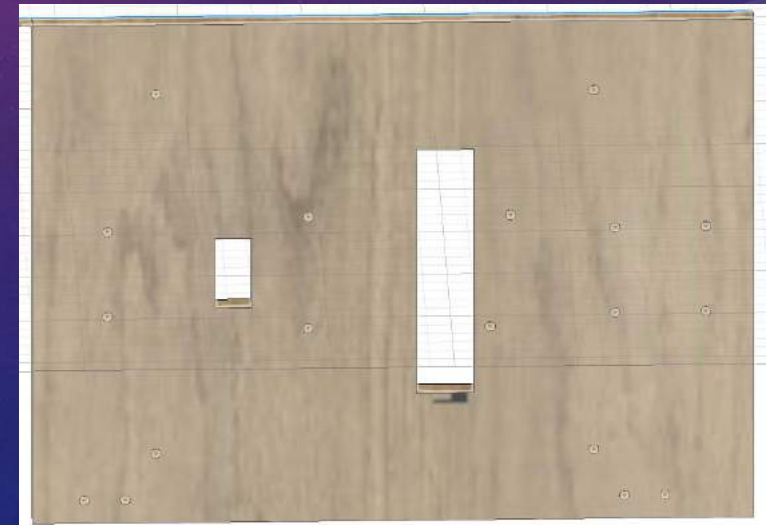
# CONCEPTION DU CHÂSSIS



CHÂSSIS EN ALUMINIUM MONTÉ



RÉALISATION DE SUPPORTS POUR  
CAPTEURS À ULTRASONS



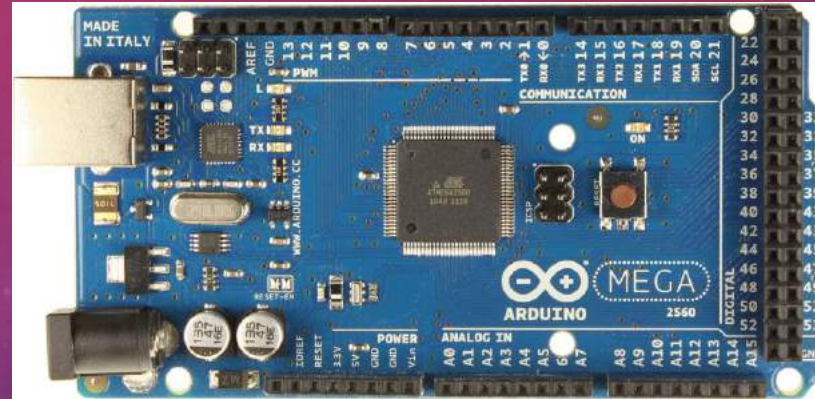
MODÉLISATION PLANCHE EN BOIS ÉTAGE 1 ET 2



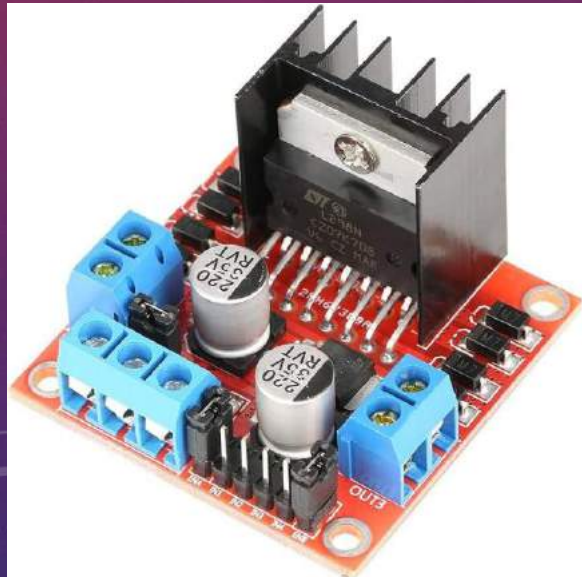
# MOTORISATION



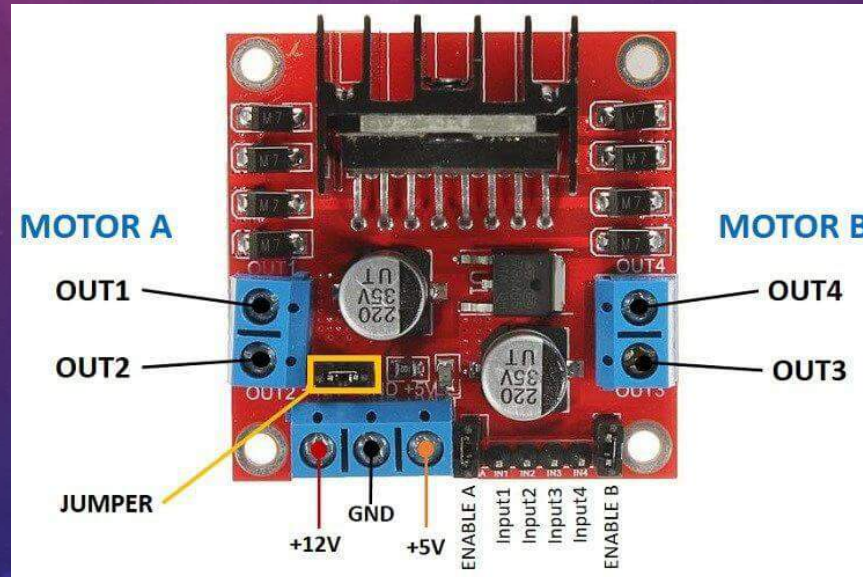
4 MOTEURS AC 12V



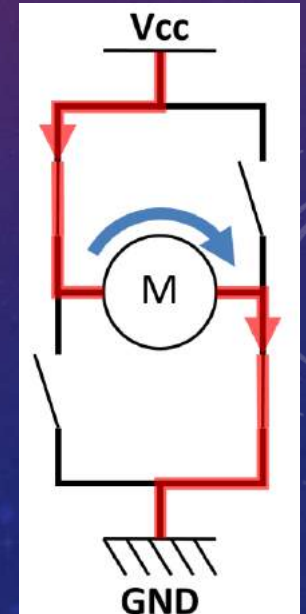
CARTE DE CONTRÔLE MEGA



2 PONTS EN H L298N-DUAL



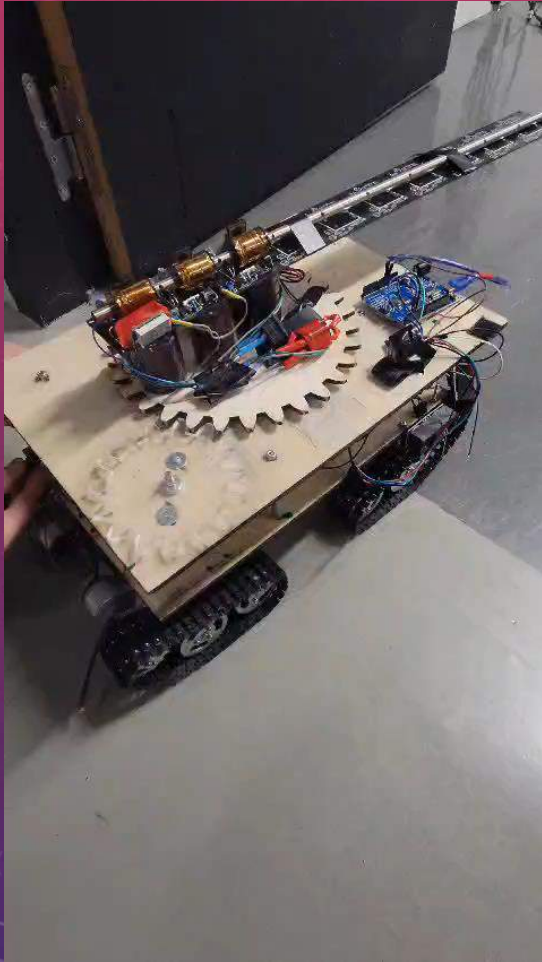
BRANCHEMENTS L298N-DUAL



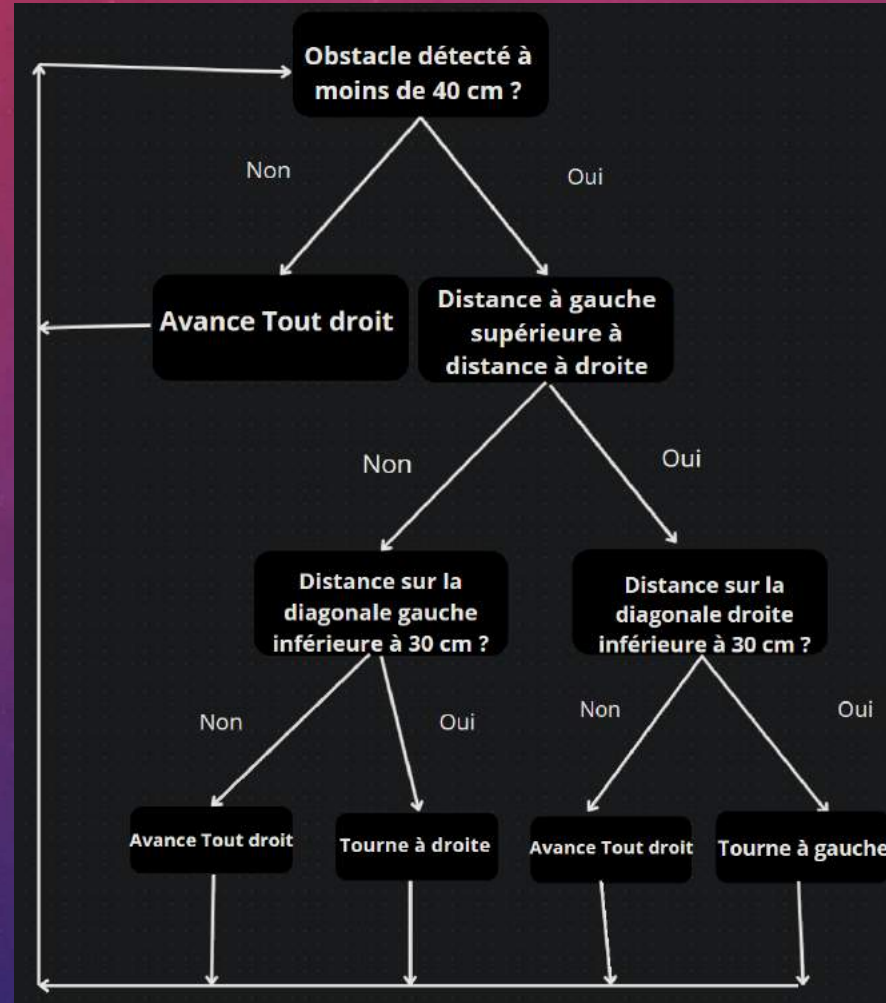
INVERSION DU SENS DE ROTATION



# DÉTECTION D'OBSTACLE



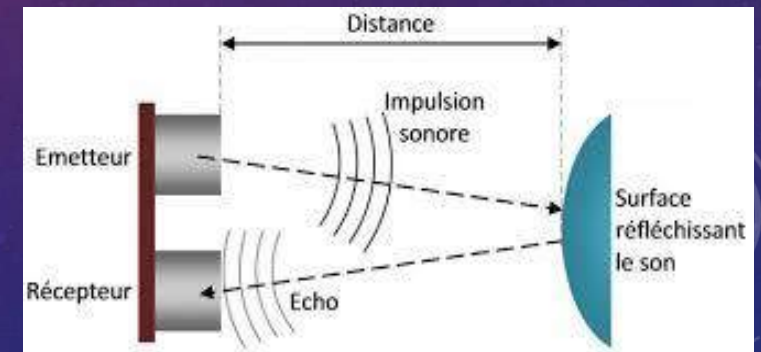
VIDÉO MONTRANT MILITECH RÉALISANT L'ALGORITHME DE DÉTECTION D'OBSTACLE



ALGORITHME DE DÉTECTION D'OBSTACLE



7 MODULES HCSR04



FONCTIONNEMENT DU CAPTEUR À ULTRASON

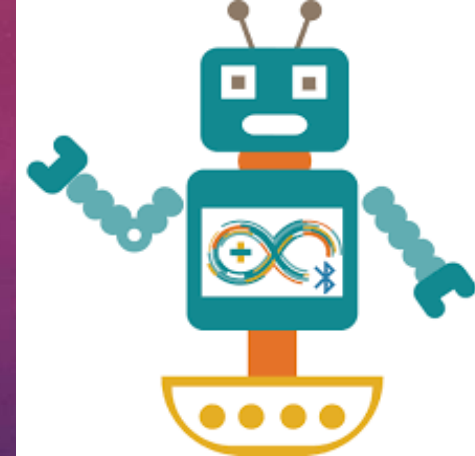
# BLUETOOTH



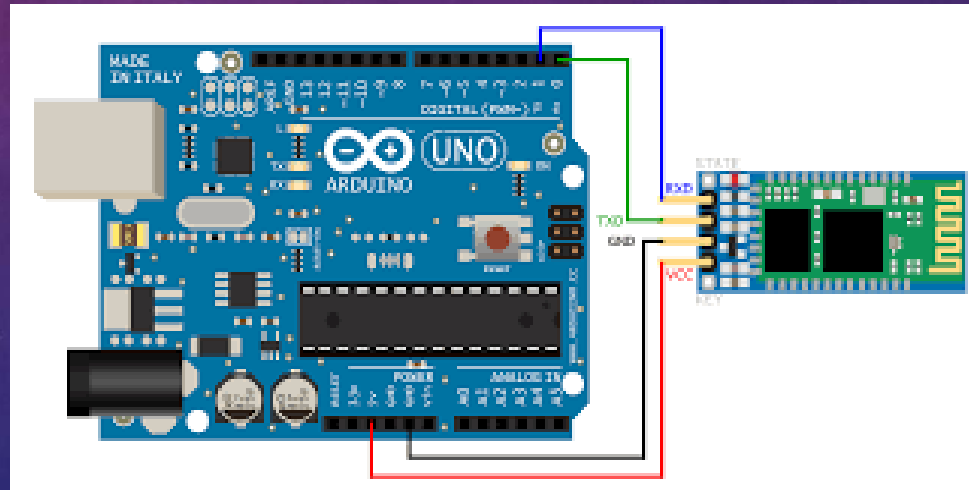
VIDÉO MONTRANT MILITECH  
CONTRÔLÉ PAR BLUETOOTH



1 MODULE HC05



APPLICATION ARDUINO  
BLUETOOTH CONTROLLER



BRANCHEMENTS HC05





# INTELLIGENCE ARTIFICIELLE

# APERÇU GLOBAL



Contrôle  
de la  
tourelle



Détection  
de la cible



Activer le  
canon  
magnétique



Contrôle  
des leds



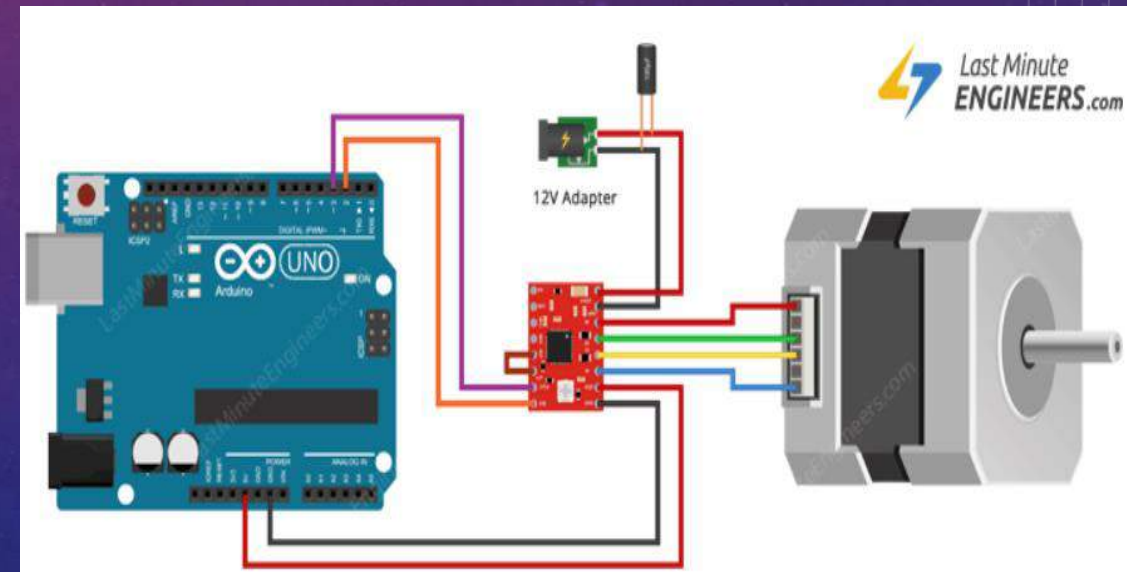
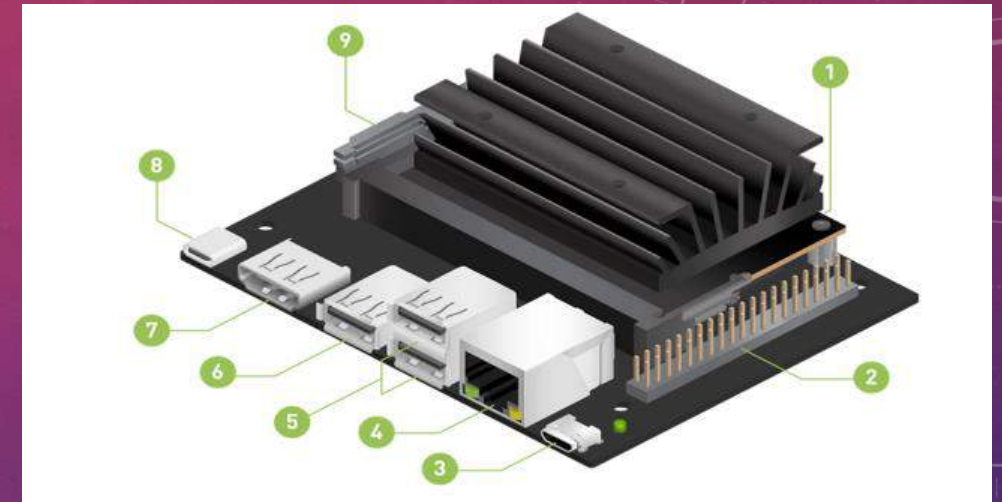
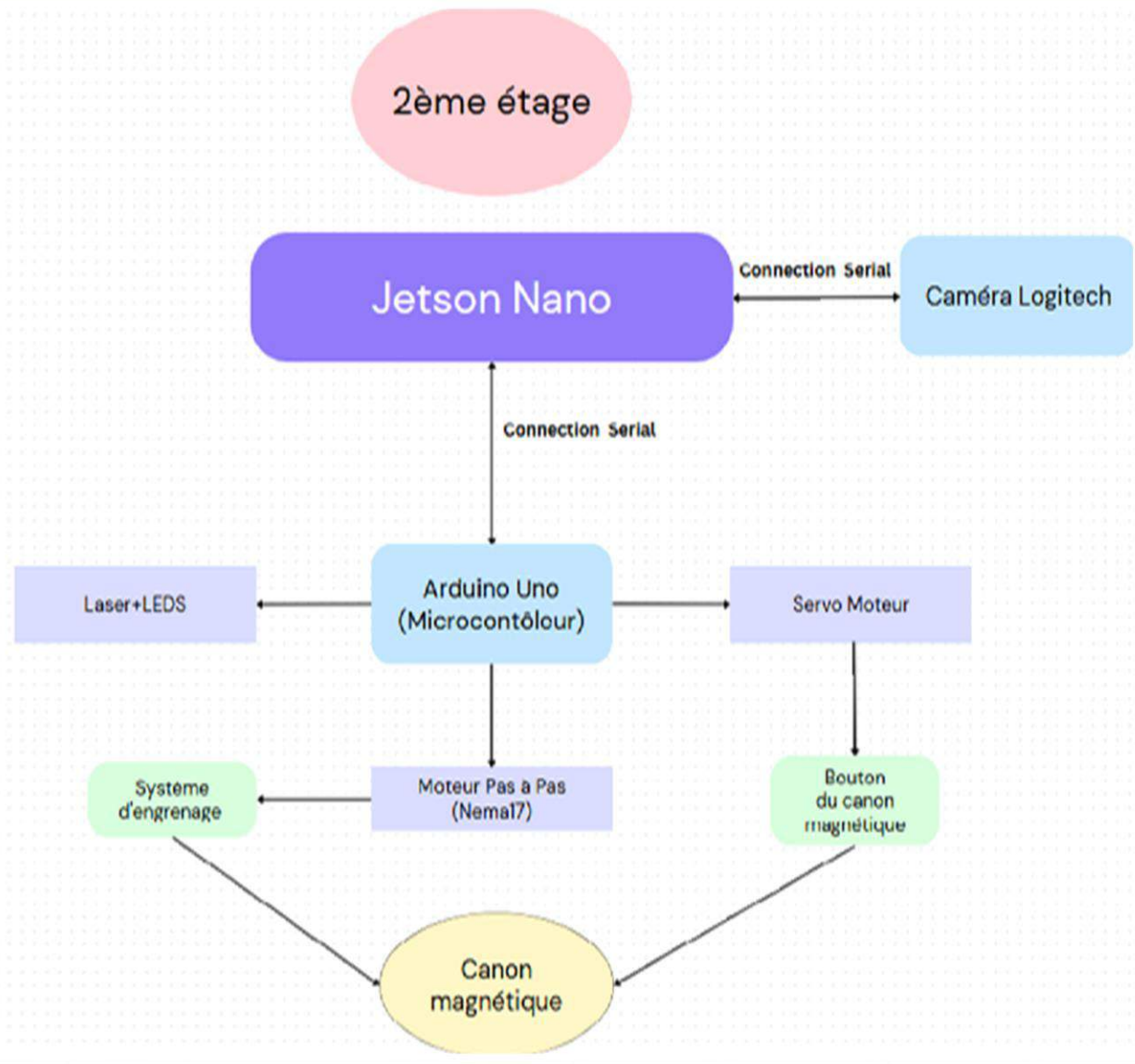


The background features a dark, starry night sky. Overlaid on this are several concentric circles. The innermost circle is a solid magenta color. Surrounding it is a ring with a blue-to-purple gradient. Further out is another magenta ring, followed by a thin white line, and then a final ring with a blue-to-purple gradient. On the right side, there is a faint, semi-circular scale with numerical markings from 120 to 190.

# Démonstration

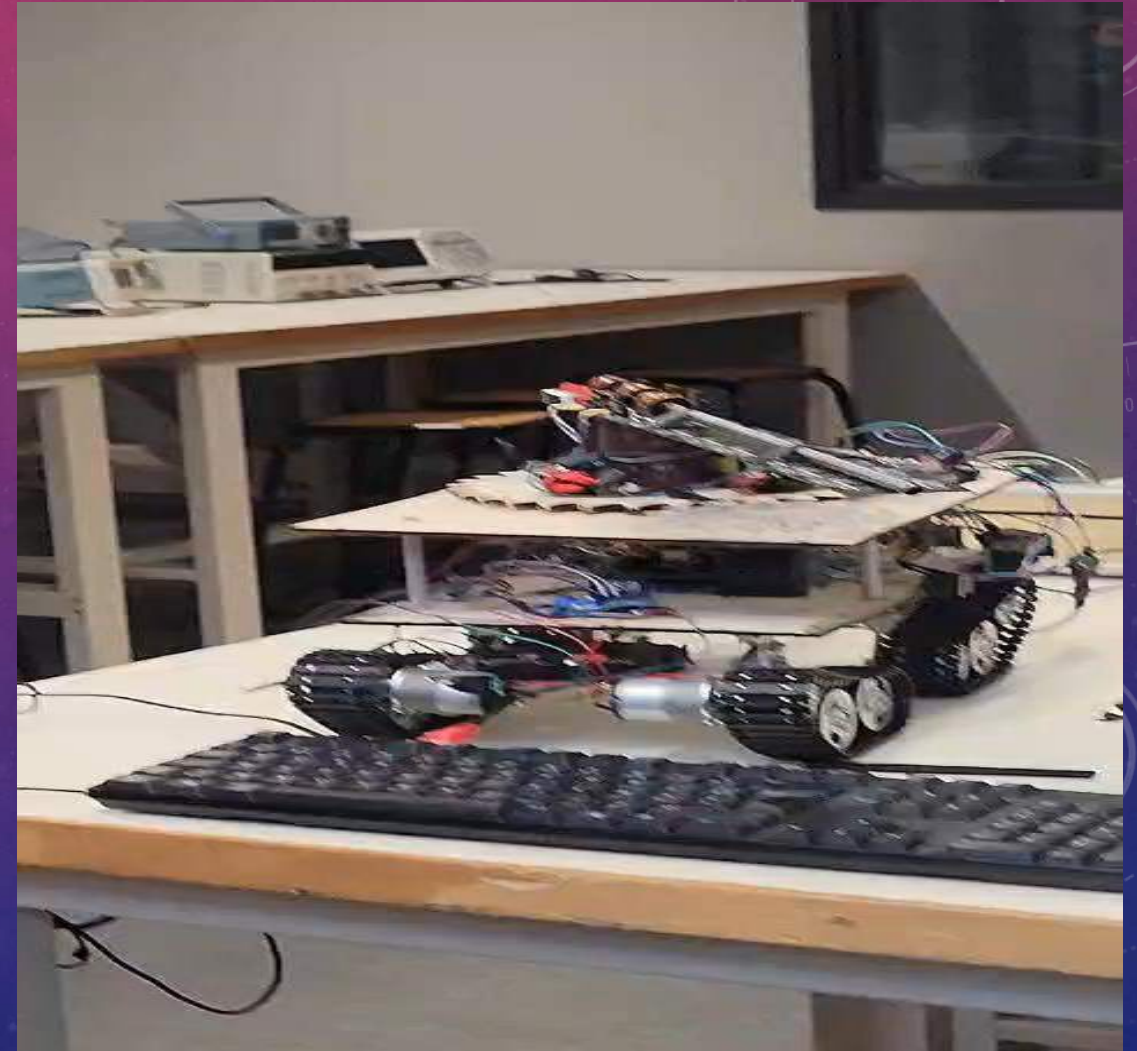
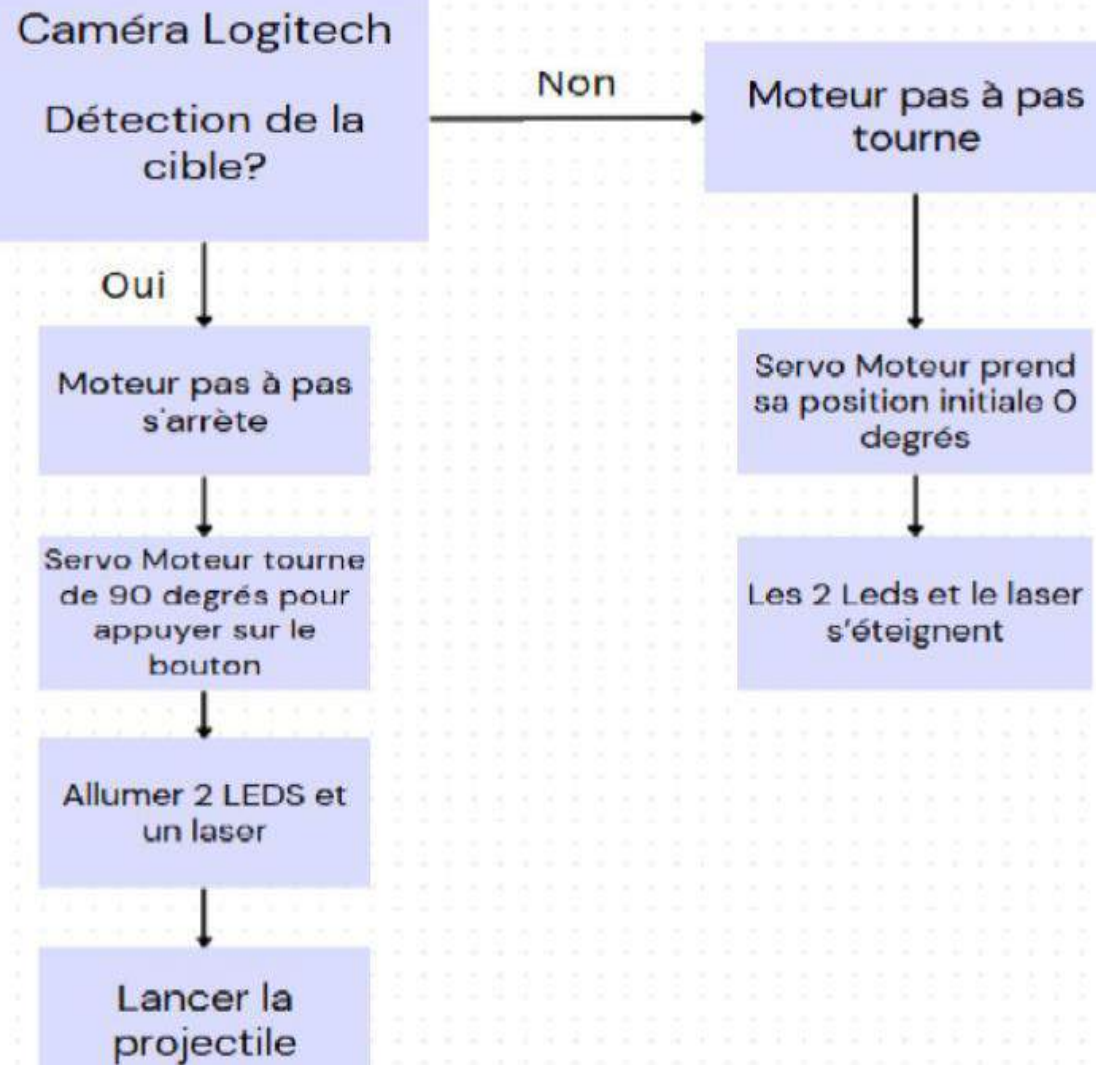


# Synoptique de l'architecture





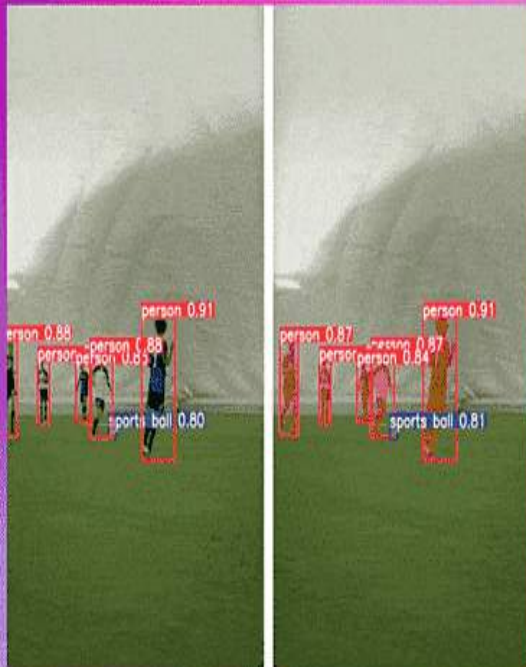
# Machine à état



# Modèle Entraîné:YOLOV8



State-of-the-Art  
YOLO Models



YoussefMiriXX commented last month

Thank you so much, @glenn-jocher.

I managed to deploy a custom trained yolov8 model on my jetson using the GPU, i got 17 fps, which is not that bad for my robot.



glenn-jocher commented last month

Member

@YoussefMiriXX that's wonderful to hear! 🌟 Achieving 17 fps on your Jetson with a custom trained YOLOv8 model is quite impressive, especially for robotics applications. If you need any more help or have further insights to share, don't hesitate to reach out. Happy building! 🚀🔧





# CANON ÉLECTRO-MAGNÉTIQUE



# Comment ça fonctionne?

Activé

Désactivé

