# MA427 Lecture 7 More on total unimodularity and the cutting plane method

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# Today's lecture

- ► More on totally unimodular matrices
- ▶ The cutting planes method

## Totally unimodular matrices

#### Definition

A matrix A is said totally unimodular if, for every square submatrix B of A,  $det(B) \in \{0, +1, -1\}$ .

#### **Theorem**

Let  $A \in \mathbb{R}^{m \times n}$  be a totally unimodular matrix. Given a vector  $b \in \mathbb{Z}^m$ , all vertices of the polyhedron  $\{x \in \mathbb{R}^n : Ax = b, x \geq 0\}$  are integer. Similarly, all vertices of the polyhedron  $\{x \in \mathbb{R}^n : Ax \leq b\}$  are integer.

#### **Theorem**

The incidence matrix of a bipartite graph is totally unimodular.

#### **Theorem**

Let  $A \in \mathbb{R}^{m \times n}$  be a totally unimodular matrix. The following hold

- i) Submatrices of A are T.U.
- ii)  $A^{\top}$  is T.U.
- iii) If matrix A' is obtained from A by multiplying one row or column by -1, then A' is T.U.
- iv) The matrix (A|-A), obtained by juxtaposing the matrices A and -A, is T.U.
  - v) The matrix (A|e) is T.U., where e is a unit vector (one entry 1, all others 0).
- vi) The matrix (A|I), obtained by juxtaposing the matrix A and the identity matrix I, is T.U.

$$\left[\begin{array}{ccccccc} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{array}\right]$$

### Corollary

Let  $A \in \mathbb{R}^{m \times n}$  be a totally unimodular matrix. Given vector  $b, d \in \mathbb{Z}^m$  and  $\ell, u \in \mathbb{Z}^n$  all vertices of the polyhedron

$$\{x \in \mathbb{R}^n : b \le Ax \le d, \ \ell \le x \le u\}$$

are integer.

## Network problems

#### **Theorem**

Let A be a matrix with all entries in  $\{0,1,-1\}$ , such that in every column of A there is exactly one entry of value 1, one entry of value -1, and all other entries with value 0. Then A is totally unimodular.

#### **Example**

$$\left[\begin{array}{ccc} 1 & -1 & 0 \\ -1 & 0 & 1 \\ 0 & 1 & -1 \end{array}\right]$$

## Network problems

Directed graph G = (V, E), source  $s \in V$ , sink  $t \in V$ , edge capacities  $u : E \to \mathbb{R}$ .

*Maximum flow problem*: find a vector  $x : E \to \mathbb{R}_+$  such that

- ▶ the total incoming amount equals the total outgoing amount at every node  $v \in V \setminus \{s, t\}$ ;
- ▶ the flow on every edge is between 0 and the upper bound: 0 < x < u.

Maximize the total amount of flow leaving s.

## Network problems

Directed graph G = (V, E), costs  $c : E \to \mathbb{R}$ , lower and upper capacity bounds  $\ell, u : E \to \mathbb{R}$ .

*Feasible circulation*: vector  $x : E \to \mathbb{R}$  such that

- ▶ the total incoming amount equals the total outgoing amount at every node  $v \in V$ .
- ▶ it is between the upper and lower bounds:  $\ell \le x \le u$ .

Find a minimum cost feasible circulation.

#### Ideal formulations

Given a set  $X \subseteq \mathbb{R}^n$ , the convex hull of X, denoted by conv(X), is the minimal convex set containing X.

Theorem (Fundamental theorem of Integer Programming)

Given  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$ , let  $X = \{x \in \mathbb{R}^n : Ax \le b, x \ge 0, x_i \in \mathbb{Z} \text{ for } i \in I\}$ . Then  $\operatorname{conv}(X)$  is a polyhedron.

 $\Longrightarrow$  there exists  $\tilde{A} \in \mathbb{Q}^{\tilde{m} \times n}$  and  $\tilde{b} \in \mathbb{Q}^{\tilde{m}}$  such that  $\operatorname{conv}(X) = \{x \in \mathbb{R}^n : \tilde{A}x \leq \tilde{b}, \, x \geq 0\}.$ 

 $\tilde{A}x \leq \tilde{b}, x \geq 0$  is the ideal formulation for X.

# Perfect matchings: ideal formulation [Edmonds, 1965]

For every graph G, the ideal formulation for the maximum weight perfect matching problem is

$$\begin{array}{rcl} \min \sum_{e \in E} c_e x_e \\ \sum_{u: uv \in E} x_{uv} &=& 1 & v \in V, \\ \sum_{e \in E[U]} x_e &\leq& \frac{|U|-1}{2} & U \subseteq V, \, |U| \text{ odd,} \\ x_e &\geq& 0 & e \in E. \end{array}$$

where  $E[U] := \{uv \in E : u, v \in U\}.$ 

The cutting planes method

# Cutting planes: motivation

- Start with the LP relaxation, and move towards the ideal formulation
- ► Repeatedly add *valid inequalities* to the current formulation, which cuts off the current fractional solution.

$$\max_{x \in X} c^{\top}x \qquad (P_I)$$
 
$$X = \{x \in \mathbb{R}^n : Ax \le b, x \ge 0, x_i \in \mathbb{Z} \text{ for all } i \in I\}$$

#### **Definition**

A linear inequality  $\alpha^{\top} x \leq \beta$ ,  $(\alpha \in \mathbb{R}^n, \beta \in \mathbb{R})$  is valid for X if, for all  $x \in X$ ,

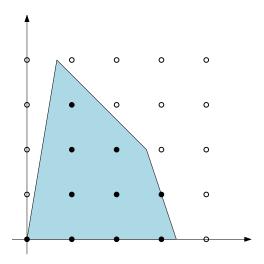
$$\alpha^{\top} x \leq \beta$$
.

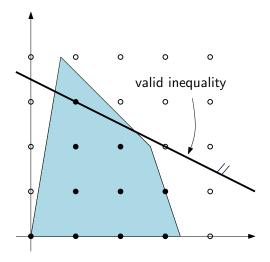
**Note:** If we append a valid inequality  $\alpha^{\top} x \leq \beta$  for X to the initial formulation  $Ax \leq b$   $x \geq 0$ , we obtain a new (tighter) formulation:

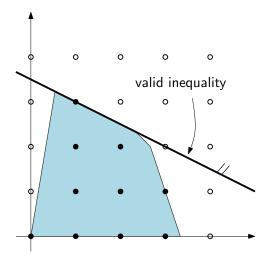
$$Ax \le b$$

$$\alpha^{\top} x \le \beta$$

$$x > 0$$







# Example: matchings in nonbipartite graphs

Starting formulation

$$\min \sum_{e \in E} c_e x_e$$

$$\sum_{u: uv \in E} x_{uv} = 1 \quad v \in V,$$

For every odd set U,

$$\sum_{e \in E[U]} x_e \le \frac{|U| - 1}{2}$$

is valid.

# Cutting planes

If we solve the LP relaxation

$$z_L = \max c^\top x$$
$$Ax \le b$$
$$x \ge 0$$

and the optimal basic solution  $x^*$  does not satisfy the integrality conditions, then  $x^* \notin \text{conv}(X)$ 

# Cutting planes

If we solve the LP relaxation

$$z_L = \max c^\top x$$
$$Ax \le b$$
$$x \ge 0$$

and the optimal basic solution  $x^*$  does not satisfy the integrality conditions, then  $x^* \notin \text{conv}(X)$ 



there exists a valid inequality  $\alpha^{\top} x \leq \beta$  cutting off  $x^*$ . Append  $\alpha^{\top} x \leq \beta$  and solve again.

# Cutting plane method

- 1. Solve the current relaxation, and let  $x^*$  be the optimal solution found;
- 2. If  $x^* \in X$ , then  $x^*$  is an optimal solution to the MILP, STOP.
- 3. Otherwise, find a valid inequality  $\alpha^{\top} x \leq \beta$  for X cutting-off  $x^*$ ;
- 4. Add the constraint  $\alpha^{\top} x \leq \beta$  to the current linear relaxation and return to 1.

# Cutting plane method

- 1. Solve the current relaxation, and let  $x^*$  be the optimal solution found;
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How do we find a valid inequality cutting off the current solution?

**WARNING:** Gomory cuts work only for pure integer programs. There exists a generalization, called Gomory mixed-integer cuts that work for general problems.

Problem in standard form (we can assume without loss of generality).

$$z_{I} = \max c^{\top} x$$

$$Ax = b$$

$$x \ge 0$$

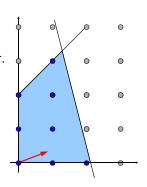
$$x \in \mathbb{Z}^{n}$$

$$\max z = 11x_1 + 4.2x_2 \\ -x_1 + x_2 \leq 2 \\ 8x_1 + 2x_2 \leq 17 \\ x_1, x_2 \geq 0 \text{ integer.}$$

$$\begin{array}{rcl} \max \ z & = & 11x_1 + 4.2x_2 \\ & -x_1 + x_2 & \leq & 2 \\ & & 8x_1 + 2x_2 & \leq & 17 \\ & & x_1, x_2 & \geq & 0 \ \ \text{integer}. \end{array}$$

#### Standard form

$$z - 11x_1 - 4.2x_2 = 0$$
  
 $-x_1 + x_2 + x_3 = 2$   
 $8x_1 + 2x_2 + x_4 = 17$   
 $x_1, x_2, x_3, x_4 \ge 0$  integer.



#### Optimal tableau:

$$z$$
 +1.16 $x_3$  +1.52 $x_4$  = 28.16  
 $x_2$  +0.8 $x_3$  +0.1 $x_4$  = 3.3  
 $x_1$  -0.2 $x_3$  +0.1 $x_4$  = 1.3

Optimal tableau:

z 
$$+1.16x_3 +1.52x_4 = 28.16$$
  
 $x_2 +0.8x_3 +0.1x_4 = 3.3$   
 $x_1 -0.2x_3 +0.1x_4 = 1.3$   
 $x_2 < 3$ 

is valid for X. It cuts off the current optimum.

Optimal tableau:

$$z +1.16x_3 +1.52x_4 = 28.16$$

$$x_2 +0.8x_3 +0.1x_4 = 3.3$$

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$$x_2 < 3$$

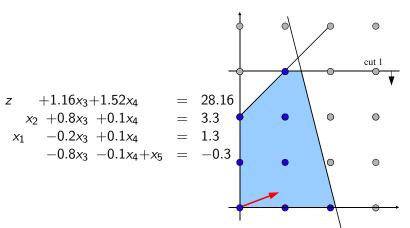
is valid for X. It cuts off the current optimum.

Can be added to the relaxation. Slack variable  $x_5$ :

$$x_2 + x_5 = 3$$

 $\{1,2,5\}$  is a basis. Write tableau w.r.t.  $\{1,2,5\}$ . Subtracting the first constraint we cancel  $x_2$ :

$$-0.8x_3 - 0.1x_4 + x_5 = -0.3$$



Basis is dual feasible! We can solve using the dual simplex method.

Optimal tableau:

- ▶ If  $\bar{b}_i \in \mathbb{Z}$  for i = 1, ..., m, then  $x^*$  is the integer optimum!
- ▶ Otherwise, choose  $h \in \{1, ..., m\}$  such that  $\bar{b}_h \notin \mathbb{Z}$ .

Optimal tableau:

- ▶ If  $\bar{b}_i \in \mathbb{Z}$  for i = 1, ..., m, then  $x^*$  is the integer optimum!
- ▶ Otherwise, choose  $h \in \{1, ..., m\}$  such that  $\bar{b}_h \notin \mathbb{Z}$ . Any solution must also satisfy

$$x_{B[h]} + \sum_{j \in N} \lfloor \bar{a}_{hj} \rfloor x_j \leq \bar{b}_h$$

Optimal tableau:

- ▶ If  $\bar{b}_i \in \mathbb{Z}$  for i = 1, ..., m, then  $x^*$  is the integer optimum!
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Any integer solution must satisfy

$$x_{B[h]} + \sum_{j \in N} \lfloor \bar{a}_{hj} \rfloor x_j \le \lfloor \bar{b}_h \rfloor$$

#### Optimal tableau:

#### Gomory cut:

$$x_{B[h]} + \sum_{j \in N} \lfloor \bar{a}_{hj} \rfloor x_j \leq \lfloor \bar{b}_h \rfloor$$

**Note:** Gomory cut cuts off  $x^*$ : indeed,  $x^*_{B[h]} = \bar{b}_h$ ,  $x^*_j = 0$  for  $j \in N$ , hence  $x^*_{B[h]} + \sum_{i \in N} \lfloor \bar{a}_{hj} \rfloor x^*_j = \bar{b}_h > \lfloor \bar{b}_h \rfloor$ 

Append the Gomory cut to the tableau:

$$x_{B[h]} + \sum_{i \in N} \lfloor \bar{a}_{hj} \rfloor x_j \leq \lfloor \bar{b}_h \rfloor$$

Append the Gomory cut to the tableau:

$$x_{B[h]} + \sum_{j \in N} \lfloor \bar{a}_{hj} \rfloor x_j + x_{n+1} = \lfloor \bar{b}_h \rfloor$$

Slack variable  $x_{n+1}$  is an integer variable (why?).

Append the Gomory cut to the tableau:

$$x_{B[h]} + \sum_{i \in N} \lfloor \bar{a}_{hj} \rfloor x_j + x_{n+1} = \lfloor \bar{b}_h \rfloor$$

Slack variable  $x_{n+1}$  is an integer variable (why?).

Write the tableau w.r.t. to basis  $B \cup \{n+1\}$ : must cancel out variable  $x_{B[h]}$ . Subtract the equation

$$x_{B[h]} + \sum_{i \in N} \bar{a}_{hj} x_j = \bar{b}_h$$

We get the Gomory cut in fractional form:

$$\sum_{j\in N}(\lfloor \bar{a}_{hj}\rfloor - a_{hj})x_j + x_{n+1} = \lfloor \bar{b}_h\rfloor - \bar{b}_h.$$

#### New tableau

▶ Tableau is dual feasible:  $\bar{c}_j \leq 0$  for all  $j \in N$ ;

#### New tableau

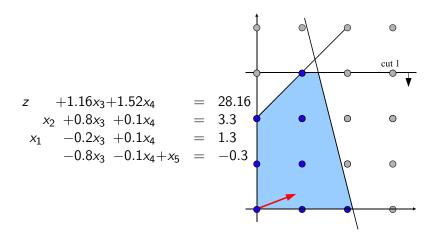
$$\begin{array}{lll} \max z \\ -z & + \sum_{j \in \mathcal{N}} \bar{c}_j x_j & = -z_B \\ x_{B[i]} & + \sum_{j \in \mathcal{N}} \bar{a}_{ij} x_j & = \bar{b}_i, & i = 1, \dots, m \\ & \sum_{j \in \mathcal{N}} (\lfloor \bar{a}_{hj} \rfloor - a_{hj}) x_j & + x_{n+1} & = \lfloor \bar{b}_h \rfloor - \bar{b}_h \\ & x_1, \dots, x_{n+1} \geq 0. \end{array}$$

- ▶ Tableau is dual feasible:  $\bar{c}_i \leq 0$  for all  $j \in N$ ;
- ▶ Tableau is not primal feasible:  $\lfloor \bar{b}_h \rfloor \bar{b}_h < 0$ ;

#### New tableau

$$\begin{array}{lll} \max z \\ -z & + \sum_{j \in \mathcal{N}} \bar{c}_j x_j & = & -z_B \\ x_{B[i]} & + \sum_{j \in \mathcal{N}} \bar{a}_{ij} x_j & = & \bar{b}_i, & i = 1, \dots, m \\ & & \sum_{j \in \mathcal{N}} (\lfloor \bar{a}_{hj} \rfloor - a_{hj}) x_j & + x_{n+1} & = & \lfloor \bar{b}_h \rfloor - \bar{b}_h \\ & & x_1, \dots, x_{n+1} \geq 0. \end{array}$$

- ▶ Tableau is dual feasible:  $\bar{c}_j \leq 0$  for all  $j \in N$ ;
- ▶ Tableau is not primal feasible:  $|\bar{b}_h| \bar{b}_h < 0$ ;
- Can re-solve using the dual simplex method instead of starting from scratch.



#### New optimal tableau

$$z$$
  $+1.375x_4$   $+1.45x_5$  = 27.725  
 $x_2$   $+x_5$  = 3  
 $x_1$   $+0.125x_4$   $-0.25x_5$  = 1.375  
 $x_3$   $+0.125x_4$   $-1.25x_5$  = 0.375

New optimal tableau

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From the tableau equation  $x_3 + 0.125x_4 - 1.25x_5 = 0.375$  we generate the Gomory cut

$$x_3-2x_5\leq 0.$$

New optimal tableau

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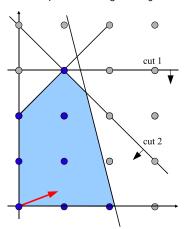
From the tableau equation  $x_3 + 0.125x_4 - 1.25x_5 = 0.375$  we generate the Gomory cut

$$x_3-2x_5\leq 0.$$

In fractional form:

$$-0.125x_4 - 0.75x_5 + x_6 = -0.375$$

$$z$$
 +1.375 $x_4$  +1.45 $x_5$  = 27.725  
 $x_2$  + $x_5$  = 3  
 $x_1$  +0.125 $x_4$  -0.25 $x_5$  = 1.375  
 $x_3$  +0.125 $x_4$  -1.25 $x_5$  = 0.375  
-0.125 $x_4$  -0.75 $x_5$  + $x_6$  = -0.375



#### New optimal tableau

$$z +17/15x_4 +29/15x_6 = 27$$

$$x_2 -1/6x_4 +4/3x_6 = 2.5$$

$$x_1 +1/6x_4 -1/3x_6 = 1.5$$

$$x_3 +x_6 = 0$$

$$1/6x_4 +x_5 -4/3x_6 = 0.5$$

#### New optimal tableau

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$$x_5-2x_6\leq 0$$

New optimal tableau

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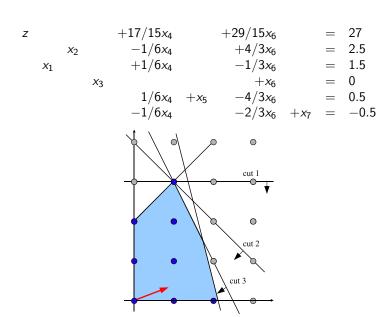
$$1/6x_4 +x_5 -4/3x_6 = 0.5$$

From the tableau equation  $1/6x_4+x_5-4/3x_6=0.5$  we generate the Gomory cut

$$x_5-2x_6\leq 0$$

In fractional form:

$$-1/6x_4 - 2/3x_6 + x_7 = -0.5$$



#### New optimal tableau

Optimal integer solution to the original problem (1,3).

Branch-and-Bound or cutting planes?

# Branch-and-Bound and cutting planes!

#### Branch-and-cut:

Apply branch and bound, but at each node decide whether or not to tighten the formulation by adding cuts, in order to obtain a better bound at the node.

# Branch-and-Bound and cutting planes!

#### Branch-and-cut:

Apply branch and bound, but at each node decide whether or not to tighten the formulation by adding cuts, in order to obtain a better bound at the node.

- State-of-the-art solvers implement many different types of cutting planes, including Gomory cuts and Gomory mixed-integer cuts (a variant that works also for general mixed-integer programming problems).
- ➤ Sometimes we can exploit special structure in the problem at hand to generate strong cutting planes.
- ► An example: cover inequalities.
- ▶ State-of-the-art solvers employ many different types of cuts.