

# MA427 – Exercise set 3

## Academic year 2018-19

**Exercise 3.1** Let  $H_1, \dots, H_k$  be closed half-spaces in  $\mathbb{R}^d$ . Show that, if  $H_1 \cap H_2 \cap \dots \cap H_k = \emptyset$ , then there exists a collection of at most  $d + 1$  half-spaces among  $H_1, \dots, H_k$  whose intersection is already empty.

This is a special case of Helly's theorem:

**Helly's theorem.** Let  $C_1, \dots, C_k$  be closed convex sets in  $\mathbb{R}^d$ . If  $C_1 \cap C_2 \cap \dots \cap C_k = \emptyset$ , then there exists a collection of at most  $d + 1$  sets among  $C_1, \dots, C_k$  whose intersection is already empty.

**Exercise 3.2** Consider the LP problem  $\max\{c^\top x \mid Ax = b, x \geq 0\}$ , where

$$A = \begin{pmatrix} 1 & 2 & 0 & 1 & 0 & -6 \\ 0 & -1 & -1 & -3 & 2 & 1 \\ 1 & 2 & 1 & 3 & -1 & 5 \end{pmatrix}, \quad b = \begin{pmatrix} 11 \\ -6 \\ 13 \end{pmatrix}, \quad c = \begin{pmatrix} -2 \\ -2 \\ 3 \\ 4 \\ -10 \\ 5 \end{pmatrix}$$

1. Show that  $B = \{2, 4, 5\}$  is a feasible basis, and write the problem in tableau form with respect to the basis  $B$ .
2. Apply the Simplex Method with Bland's rule to solve the LP problem starting from the feasible basis  $B = \{2, 4, 5\}$ .

**Exercise 3.3** Consider the following LP problem.

$$\begin{array}{rcll} \max & 2x_1 & + & x_2 \\ & x_1 & - & 2x_2 \leq 2 \\ & 2x_1 & - & x_2 \leq 5 \\ & -4x_1 & + & x_2 \leq 4 \\ & x_1 & , & x_2 \geq 0 \end{array}$$

Transform the above problem in standard equality form by adding the slack variables  $x_4, x_5, x_6$ , relative to the first, second and third constraint, respectively. Note that  $\{4, 5, 6\}$  is a feasible basis, and apply the Simplex Method starting from such basis.

From the final tableau, determine a family of feasible solutions that can take arbitrarily large objective value.

**Exercise 3.4** Let  $A$  be an  $m \times n$  matrix. Given vectors  $b \in \mathbb{R}^m$  and  $c \in \mathbb{R}^n$ , consider the LP problem in standard equality form

$$\begin{array}{ll} \max & c^\top x \\ & Ax = b \\ & x \geq 0. \end{array} \quad (P).$$

Let  $x^*$  be an optimal basic feasible solution for  $(P)$ , and  $B$  be the basis that determines it.

1. Show that, if  $\bar{c}_j < 0$  for every  $j \in N$ , then  $x^*$  is the unique optimal solution.
2. Suppose that  $x_j^* > 0$  for every  $j \in B$ . Show that the dual solution is unique. What is the optimal dual solution for the problem?

**Exercise 3.5** Consider an LP problem in standard equality form

$$\begin{aligned} \max \quad & c^\top x \\ & Ax = b \quad (P) \\ & x \geq 0 \end{aligned}$$

and let  $B$  be a feasible basis for the problem. Let  $\bar{x}$  be the feasible solution determined by  $B$ , and let  $\bar{c}_j$ ,  $j = 1, \dots, n$ , be the reduced costs of the variables  $x_j$  with respect to the basis  $B$ .

1. We have seen that, if  $\bar{c}_j \leq 0$  for all  $j \in \{1, \dots, n\}$ , then the solution  $\bar{x}$  is optimal. Is the converse statement true? (That is, is it true that if  $\bar{x}$  is optimal, then the reduced costs associated with  $B$  must all be non-positive?)
2. Suppose that  $B$  is the current basis at an iteration of the simplex method. Let  $x_k$  be the variable selected to enter the basis (hence  $\bar{c}_k > 0$ ). Let  $x_\ell$  the variable that leaves the basis. Hence at the new iteration the basis becomes  $\tilde{B} := B \setminus \{\ell\} \cup \{k\}$ . What is the reduced cost of  $x_\ell$  with respect to the new basis  $\tilde{B}$ ?
3. Use the previous point to conclude that the variable  $x_\ell$  that leaves the basis cannot re-enter at the next iteration.