

Chapter 9

Sinusoidal Steady-State Analysis

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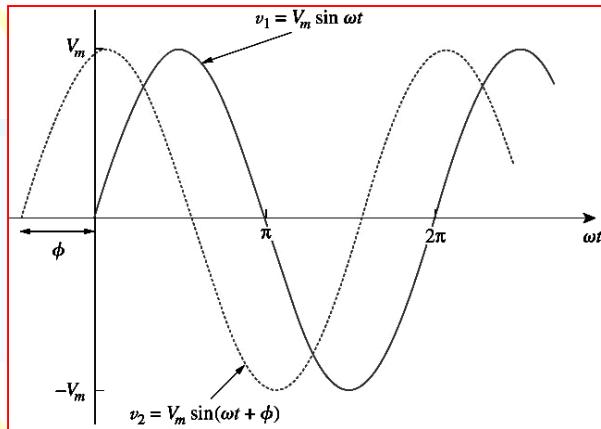
Sinusoids and Phasor

Chapter 9

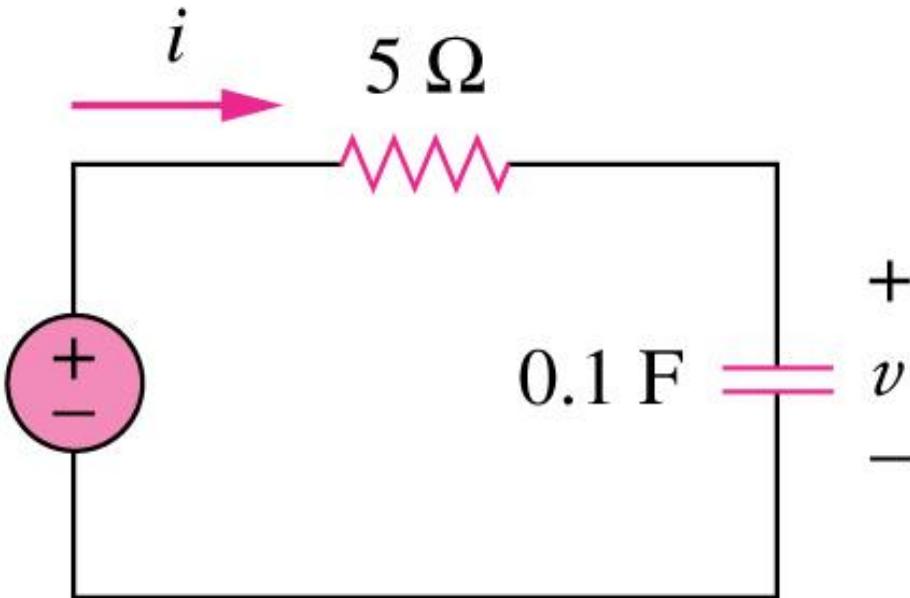
- 9.1 Motivation
- 9.2 Sinusoids' features
- 9.3 Phasors
- 9.4 Phasor relationships for circuit elements
- 9.5 Impedance and admittance
- 9.6 Kirchhoff's laws in the frequency domain
- 9.7 Impedance combinations

9.1 Motivation (1)

How to determine $v(t)$ and $i(t)$?



$$v_s(t) = 10V$$

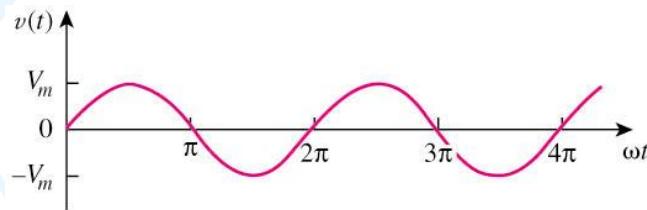


How can we apply what we have learned before to determine $i(t)$ and $v(t)$?

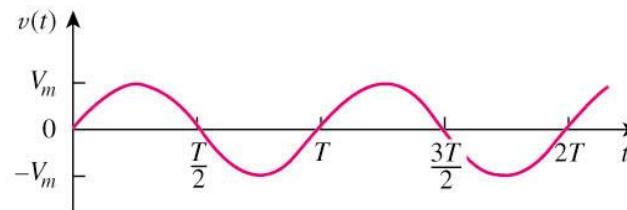
9.2 Sinusoids (1)

- A sinusoid is a signal that has the form of the sine or cosine function.
- A general expression for the sinusoid,

$$v(t) = V_m \sin(\omega t + \phi)$$



(a)



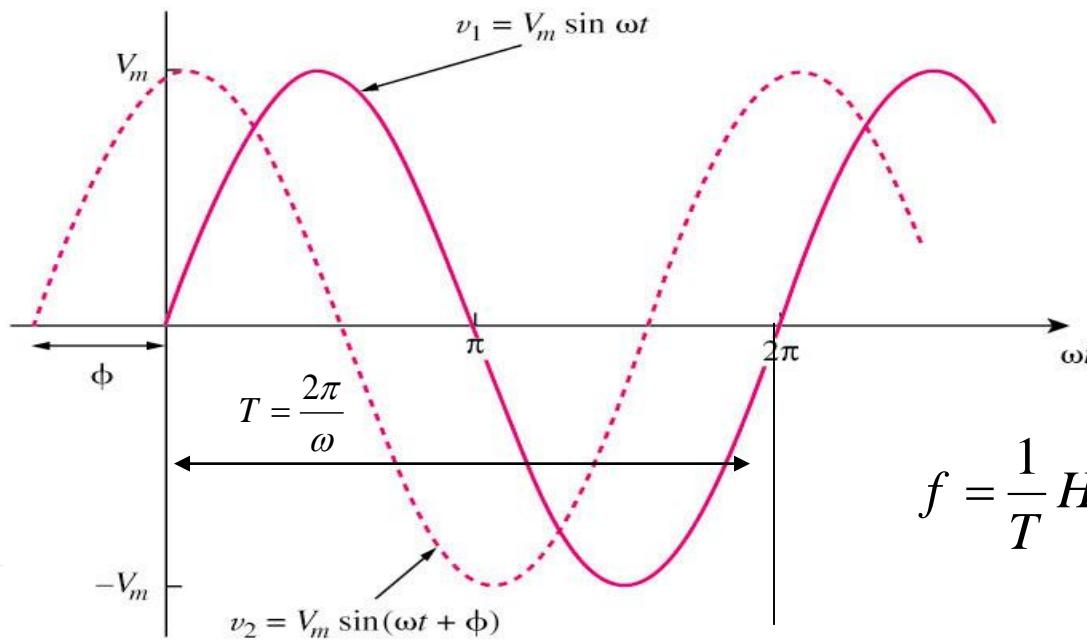
(b)

where

V_m = the **amplitude** of the sinusoid
 ω = the angular frequency in radians/s
 ϕ = the phase

9.2 Sinusoids (2)

A **periodic function** is one that satisfies $v(t) = v(t + nT)$, for all t and for all integers n.



- Only two sinusoidal values with the same frequency can be compared by their amplitude and phase difference.
- If phase difference is zero, they are in phase; if phase difference is not zero, they are out of phase.



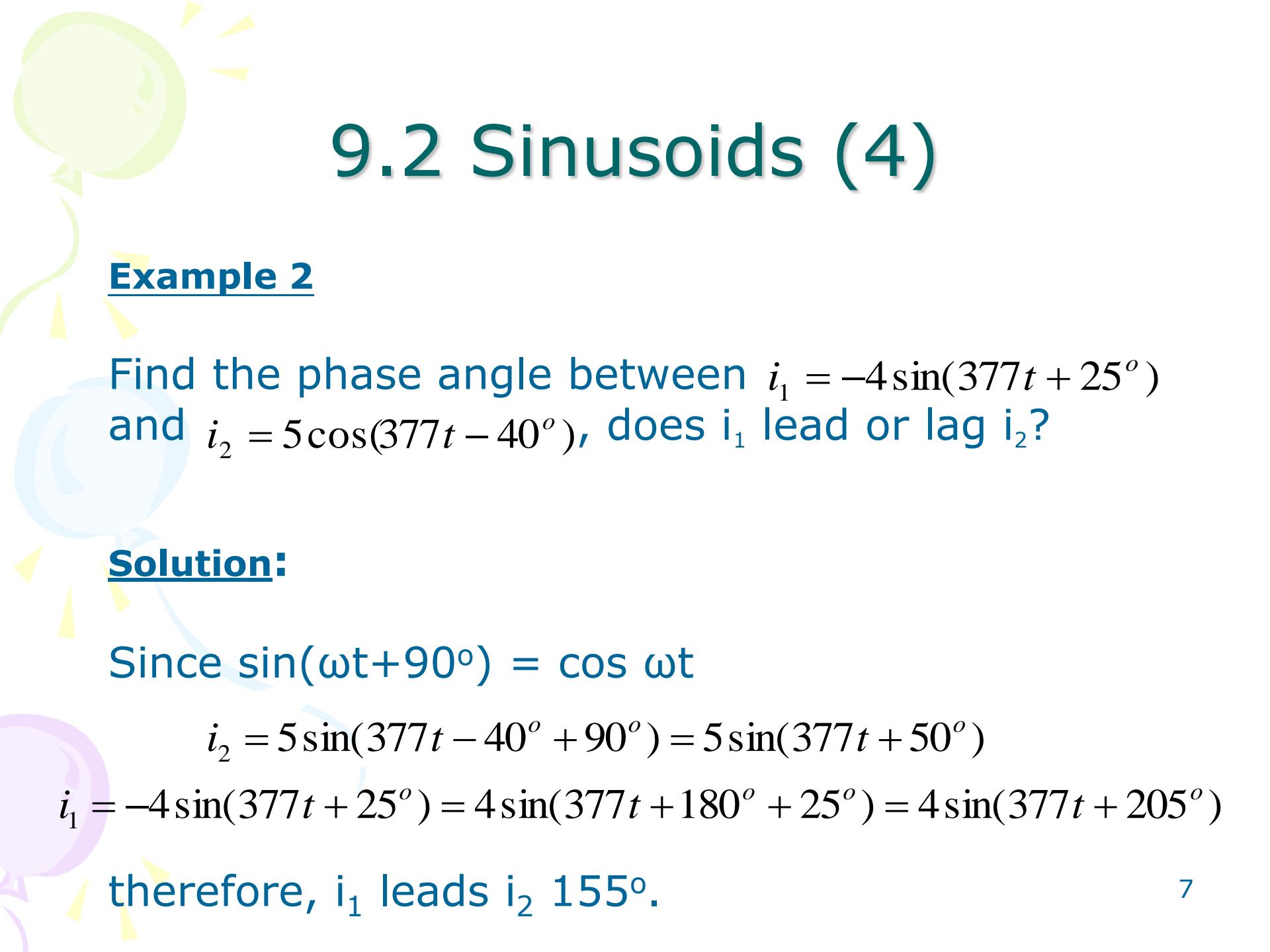
9.2 Sinusoids (3)

Example 1

Given a sinusoid, $5\sin(4\pi t - 60^\circ)$, calculate its amplitude, phase, angular frequency, period, and frequency.

Solution:

Amplitude = 5, phase = -60° , angular frequency = 4π rad/s, Period = 0.5 s, frequency = 2 Hz.



9.2 Sinusoids (4)

Example 2

Find the phase angle between $i_1 = -4 \sin(377t + 25^\circ)$ and $i_2 = 5 \cos(377t - 40^\circ)$, does i_1 lead or lag i_2 ?

Solution:

Since $\sin(\omega t + 90^\circ) = \cos \omega t$

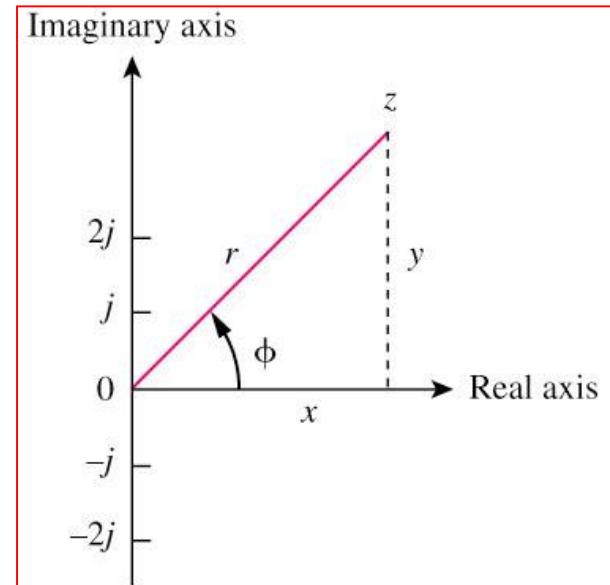
$$i_2 = 5 \sin(377t - 40^\circ + 90^\circ) = 5 \sin(377t + 50^\circ)$$

$$i_1 = -4 \sin(377t + 25^\circ) = 4 \sin(377t + 180^\circ + 25^\circ) = 4 \sin(377t + 205^\circ)$$

therefore, i_1 leads i_2 155° .

9.3 Phasor (1)

- A phasor is a complex number that represents the amplitude and phase of a sinusoid.
- It can be represented in one of the following three forms:
 - a. Rectangular $z = x + jy = r(\cos\phi + j \sin\phi)$
 - b. Polar $z = r \angle \phi$
 - c. Exponential $z = re^{j\phi}$



where

$$r = \sqrt{x^2 + y^2}$$

$$\phi = \tan^{-1} \frac{y}{x}$$

9.3 Phasor (2)

Example 9.3

- Evaluate the following complex numbers:

Evaluate these complex numbers:

Example 9.3

(a) $(40\angle 50^\circ + 20\angle -30^\circ)^{1/2}$

Solution:

(a) Using polar to rectangular transformation,

$$40\angle 50^\circ = 40(\cos 50^\circ + j \sin 50^\circ) = 25.71 + j30.64$$

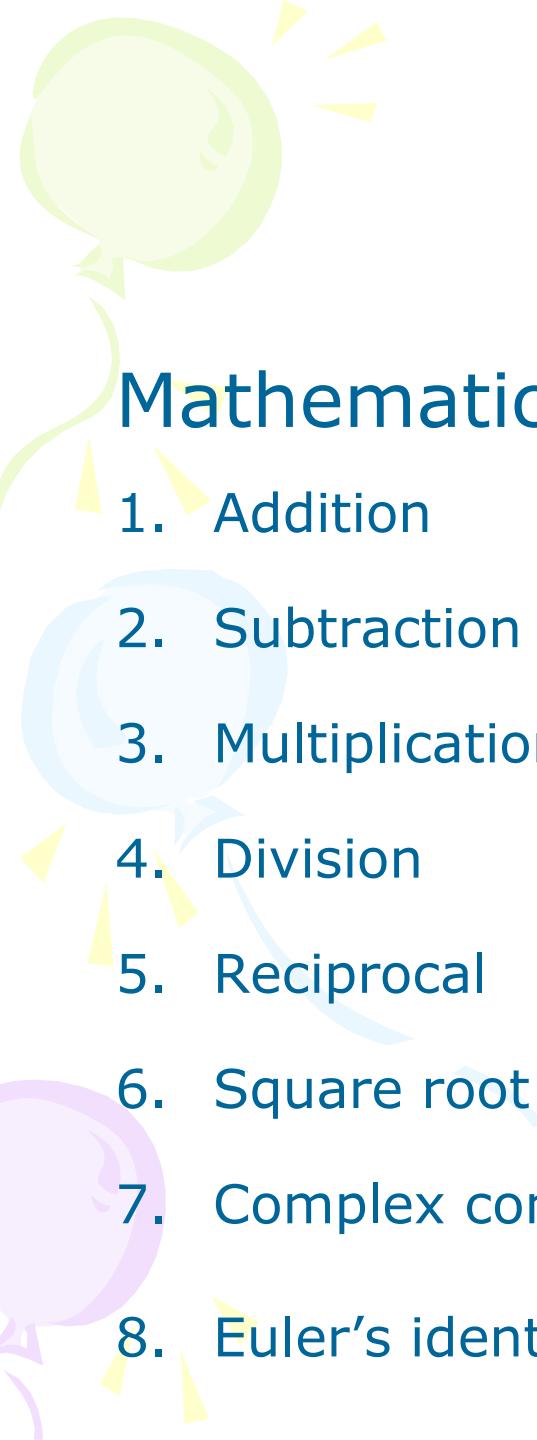
$$20\angle -30^\circ = 20[\cos(-30^\circ) + j \sin(-30^\circ)] = 17.32 - j10$$

Adding them up gives

$$40\angle 50^\circ + 20\angle -30^\circ = 43.03 + j20.64 = 47.72\angle 25.63^\circ$$

Taking the square root of this,

$$(40\angle 50^\circ + 20\angle -30^\circ)^{1/2} = 6.91\angle 12.81^\circ$$



9.3 Phasor (3)

Mathematic operation of complex number:

1. Addition

$$z_1 + z_2 = (x_1 + x_2) + j(y_1 + y_2)$$

2. Subtraction

$$z_1 - z_2 = (x_1 - x_2) + j(y_1 - y_2)$$

3. Multiplication

$$z_1 z_2 = r_1 r_2 \angle \phi_1 + \phi_2$$

4. Division

$$\frac{z_1}{z_2} = \frac{r_1}{r_2} \angle \phi_1 - \phi_2$$

5. Reciprocal

$$\frac{1}{z} = \frac{1}{r} \angle -\phi$$

6. Square root

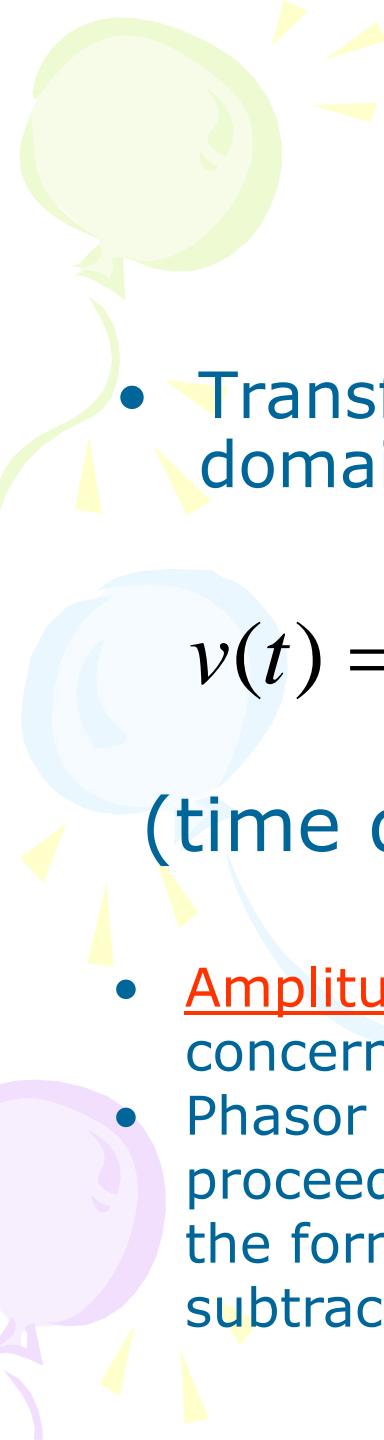
$$\sqrt{z} = \sqrt{r} \angle \phi/2$$

7. Complex conjugate

$$z^* = x - jy = r \angle -\phi = re^{-j\phi}$$

8. Euler's identity

$$e^{\pm j\phi} = \cos\phi \pm j \sin\phi$$



9.3 Phasor (4)

- Transform a sinusoid to and from the time domain to the phasor domain:

$$v(t) = V_m \cos(\omega t + \phi) \longleftrightarrow V = V_m \angle \phi$$

(time domain)

(phasor domain)

- Amplitude and phase difference are two principal concerns in the study of voltage and current sinusoids.
- Phasor will be defined from the cosine function in all our proceeding study. If a voltage or current expression is in the form of a sine, it will be changed to a cosine by subtracting from the phase.

9.3 Phasor (5)

Example 4

Transform the following sinusoids to phasors:

$$i = 6\cos(50t - 40^\circ) \text{ A}$$

$$v = -4\sin(30t + 50^\circ) \text{ V}$$

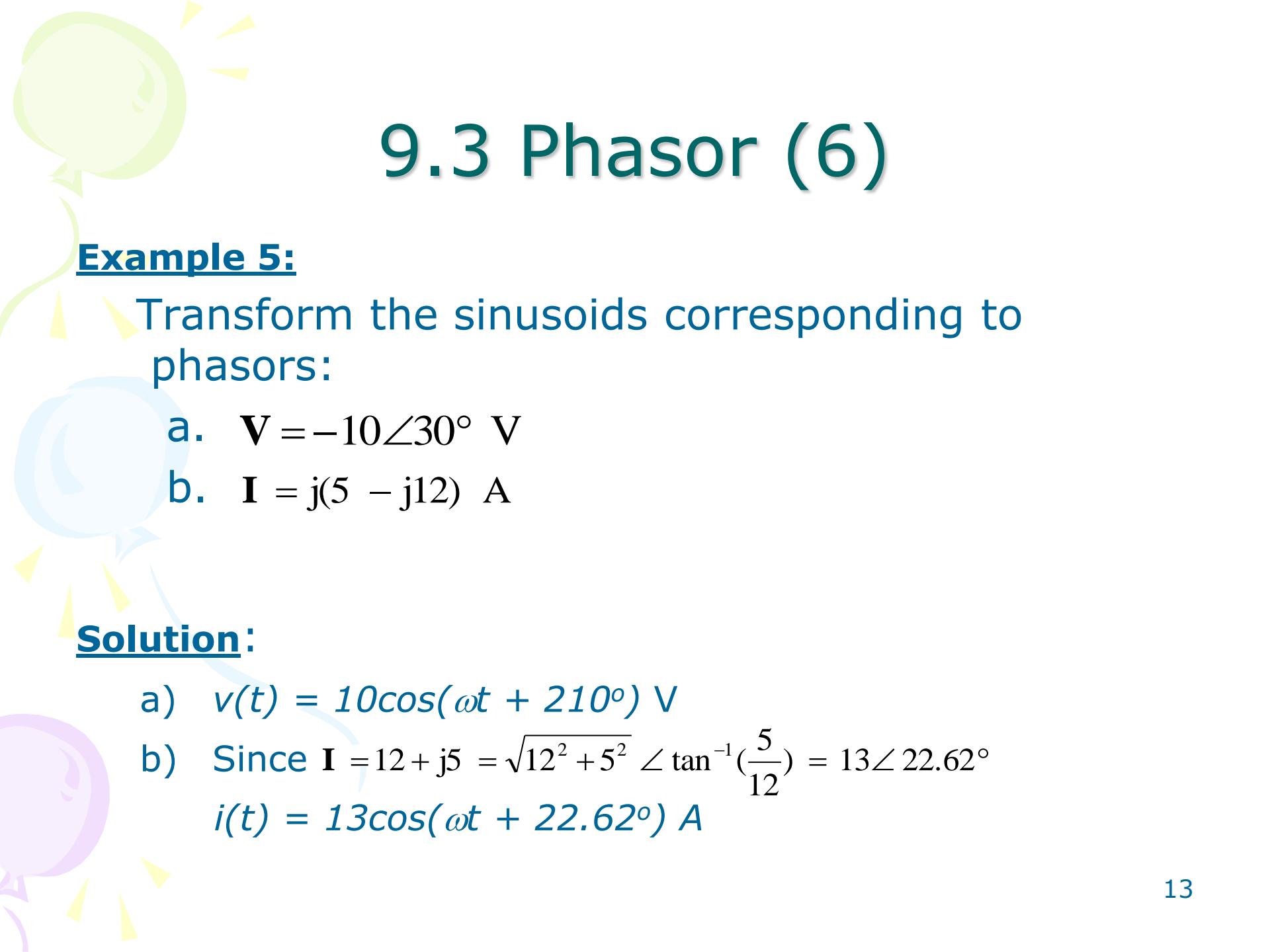
Solution:

a. $I = 6\angle -40^\circ \text{ A}$

b. Since $-\sin(A) = \cos(A+90^\circ)$;

$$v(t) = 4\cos(30t + 50^\circ + 90^\circ) = 4\cos(30t + 140^\circ) \text{ V}$$

Transform to phasor $\Rightarrow V = 4\angle 140^\circ \text{ V}$



9.3 Phasor (6)

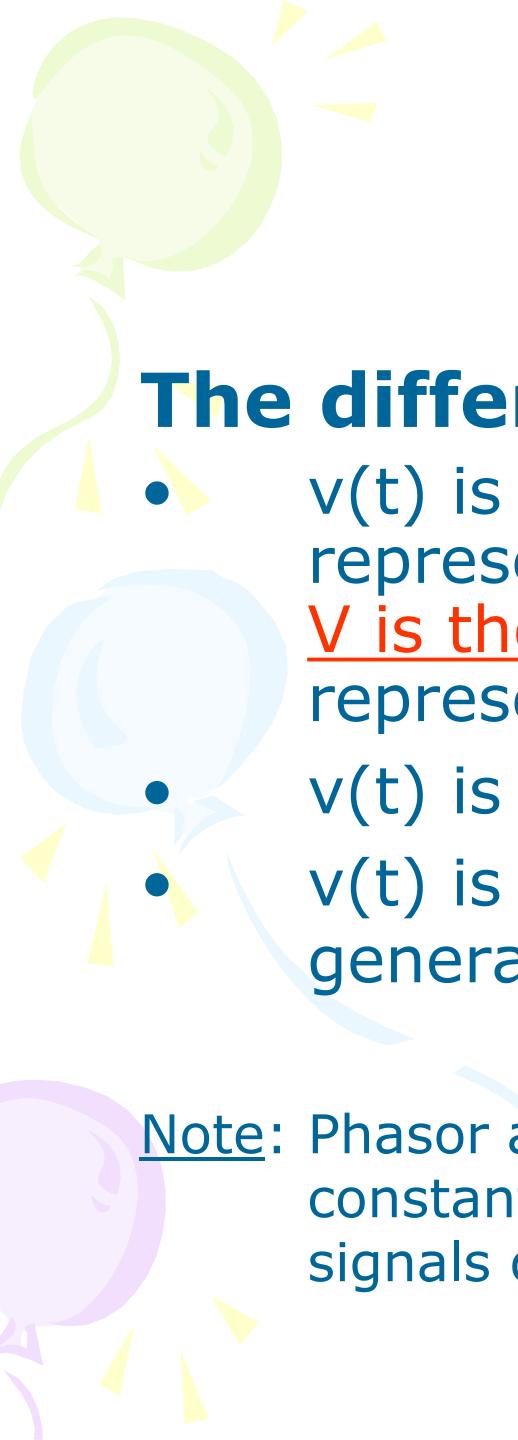
Example 5:

Transform the sinusoids corresponding to phasors:

- $\mathbf{V} = -10\angle 30^\circ \text{ V}$
- $\mathbf{I} = j(5 - j12) \text{ A}$

Solution:

- $v(t) = 10\cos(\omega t + 210^\circ) \text{ V}$
- Since $\mathbf{I} = 12 + j5 = \sqrt{12^2 + 5^2} \angle \tan^{-1}\left(\frac{5}{12}\right) = 13\angle 22.62^\circ$
 $i(t) = 13\cos(\omega t + 22.62^\circ) \text{ A}$



9.3 Phasor (7)

The differences between $v(t)$ and V :

- $v(t)$ is instantaneous or time-domain representation
 V is the frequency or phasor-domain representation.
- $v(t)$ is time dependent, V is not.
- $v(t)$ is always real with no complex term, V is generally complex.

Note: Phasor analysis applies only when frequency is constant; when it is applied to two or more sinusoid signals only if they have the same frequency.

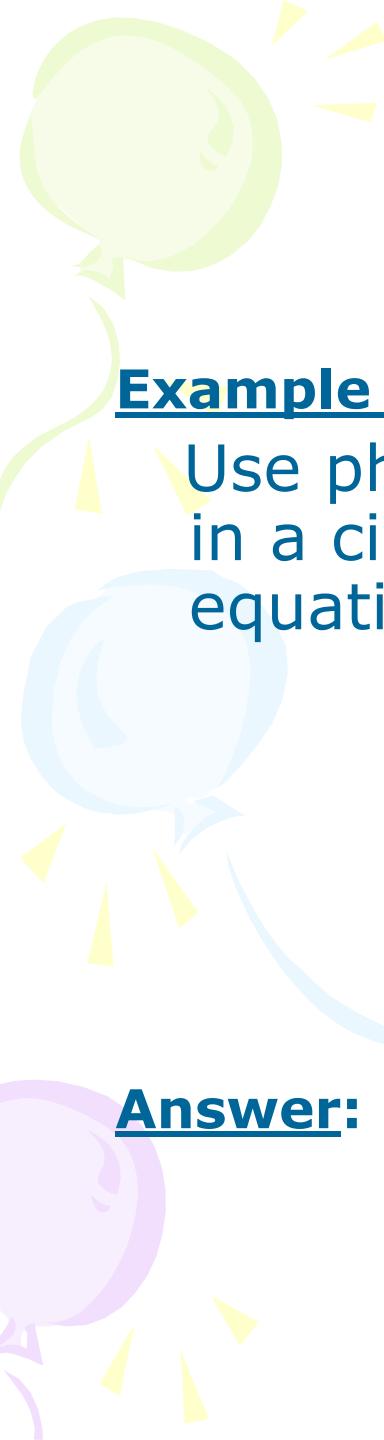
9.3 Phasor (8)

Relationship between differential, integral operation
in phasor listed as follow:

$$v(t) \longleftrightarrow V = V\angle\phi$$

$$\frac{dv}{dt} \longleftrightarrow j\omega V$$

$$\int v dt \longleftrightarrow \frac{V}{j\omega}$$



9.3 Phasor (9)

Example 6

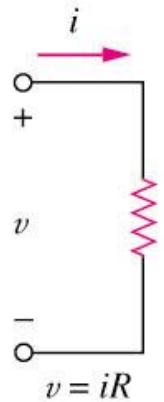
Use phasor approach, determine the current $i(t)$ in a circuit described by the integro-differential equation.

$$4i + 8 \int idt - 3 \frac{di}{dt} = 50 \cos(2t + 75^\circ)$$

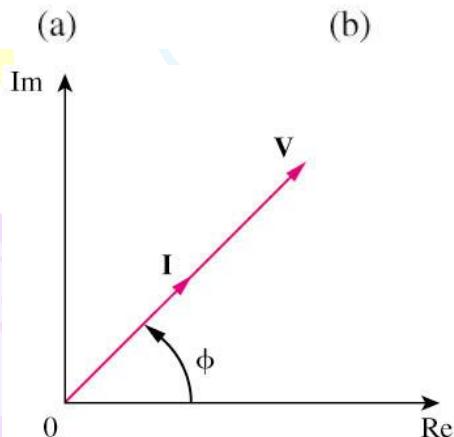
Answer: $i(t) = 4.642 \cos(2t + 143.2^\circ) A$

9.4 Phasor Relationships for Circuit Elements (1)

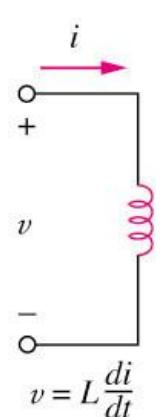
Resistor:



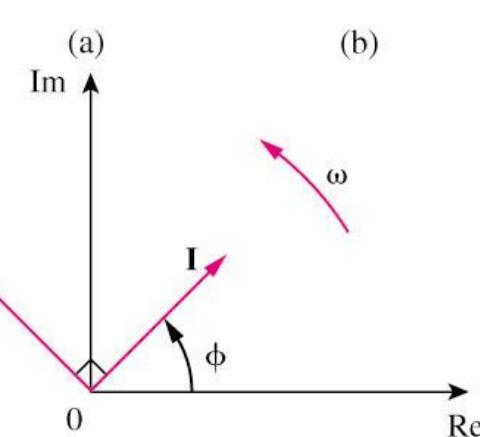
$$(b) \quad \mathbf{V} = \mathbf{IR}$$



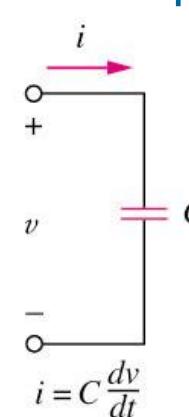
Inductor:



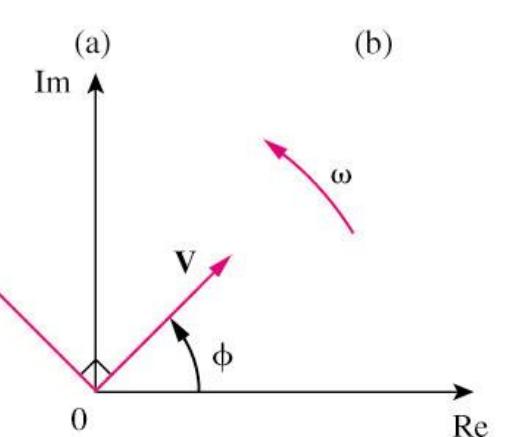
$$(b) \quad \mathbf{V} = j\omega L \mathbf{I}$$



Capacitor:



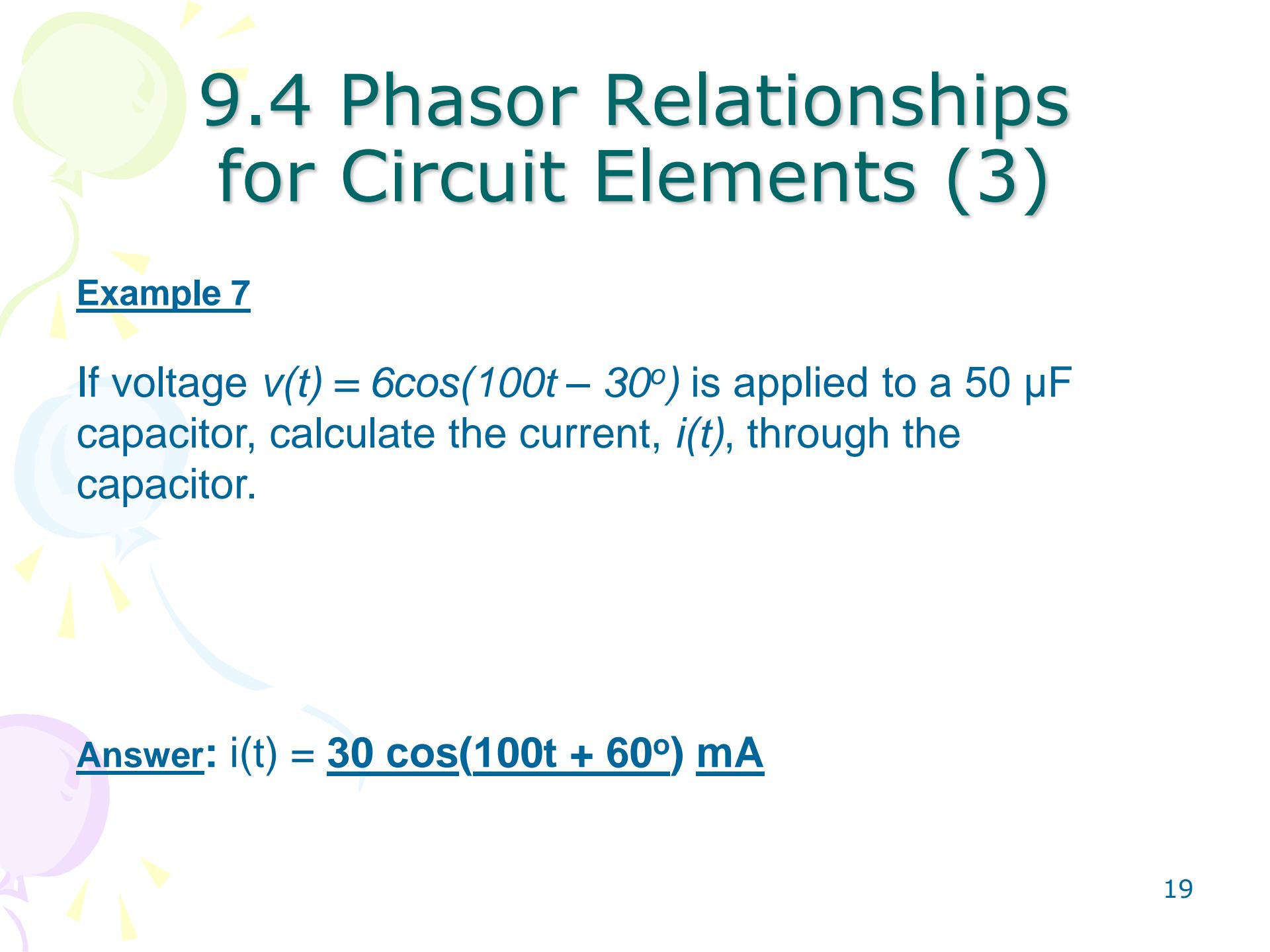
$$(b) \quad \mathbf{I} = j\omega C \mathbf{V}$$



9.4 Phasor Relationships for Circuit Elements (2)

Summary of voltage-current relationship

Element	Time domain	Frequency domain
R	$v = Ri$	$V = RI$
L	$v = L \frac{di}{dt}$	$V = j\omega LI$
C	$i = C \frac{dv}{dt}$	$V = \frac{I}{j\omega C}$



9.4 Phasor Relationships for Circuit Elements (3)

Example 7

If voltage $v(t) = 6\cos(100t - 30^\circ)$ is applied to a $50 \mu\text{F}$ capacitor, calculate the current, $i(t)$, through the capacitor.

Answer: $i(t) = 30 \cos(100t + 60^\circ) \text{ mA}$

9.5 Impedance and Admittance (1)

- The impedance Z of a circuit is the ratio of the phasor voltage V to the phasor current I , measured in ohms Ω .

$$Z = \frac{V}{I} = R + jX$$

where $R = \text{Re}$, Z is the resistance and $X = \text{Im}$, Z is the reactance. Positive X is for L and negative X is for C.

- The admittance Y is the reciprocal of impedance, measured in siemens (S).

$$Y = \frac{1}{Z} = \frac{I}{V}$$

9.5 Impedance and Admittance (2)

Impedances and admittances of passive elements

Element	Impedance	Admittance
R	$Z = R$	$Y = \frac{1}{R}$
L	$Z = j\omega L$	$Y = \frac{1}{j\omega L}$
C	$Z = \frac{1}{j\omega C}$	$Y = j\omega C$

9.5 Impedance and Admittance (3)

$$L$$

$$Z = j\omega L$$

Short circuit at dc

$$\omega = 0; Z = 0$$

Open circuit at
high frequencies

$$\omega \rightarrow \infty; Z \rightarrow \infty$$

(a)

$$C$$

$$Z = \frac{1}{j\omega C}$$

Open circuit at dc

$$\omega = 0; Z \rightarrow \infty$$

Short circuit at
high frequencies

$$\omega \rightarrow \infty; Z = 0$$

(b)

9.5 Impedance and Admittance (4)

After we know how to convert RLC components from time to phasor domain, we can transform a time domain circuit into a phasor/frequency domain circuit.

Hence, we can apply the KCL laws and other theorems to directly set up phasor equations involving our target variable(s) for solving.

Impedance and Admittance

Find $v(t)$ and $i(t)$ in the circuit shown in Fig. 9.16.

Solution:

From the voltage source $10 \cos 4t$, $\omega = 4$,

$$\mathbf{V}_s = 10 \angle 0^\circ \text{ V}$$

The impedance is

$$\mathbf{Z} = 5 + \frac{1}{j\omega C} = 5 + \frac{1}{j4 \times 0.1} = 5 - j2.5 \Omega$$

Hence the current

$$\begin{aligned} \mathbf{I} &= \frac{\mathbf{V}_s}{\mathbf{Z}} = \frac{10 \angle 0^\circ}{5 - j2.5} = \frac{10(5 + j2.5)}{5^2 + 2.5^2} \\ &= 1.6 + j0.8 = 1.789 \angle 26.57^\circ \text{ A} \end{aligned} \quad (9.9.1)$$

The voltage across the capacitor is

$$\begin{aligned} \mathbf{V} &= \mathbf{I} \mathbf{Z}_C = \frac{\mathbf{I}}{j\omega C} = \frac{1.789 \angle 26.57^\circ}{j4 \times 0.1} \\ &= \frac{1.789 \angle 26.57^\circ}{0.4 \angle 90^\circ} = 4.47 \angle -63.43^\circ \text{ V} \end{aligned} \quad (9.9.2)$$

Converting \mathbf{I} and \mathbf{V} in Eqs. (9.9.1) and (9.9.2) to the time domain, we get

$$i(t) = 1.789 \cos(4t + 26.57^\circ) \text{ A}$$

$$v(t) = 4.47 \cos(4t - 63.43^\circ) \text{ V}$$

Notice that $i(t)$ leads $v(t)$ by 90° as expected.

Example 9.9

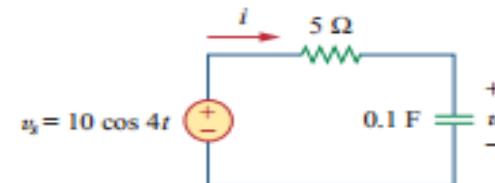
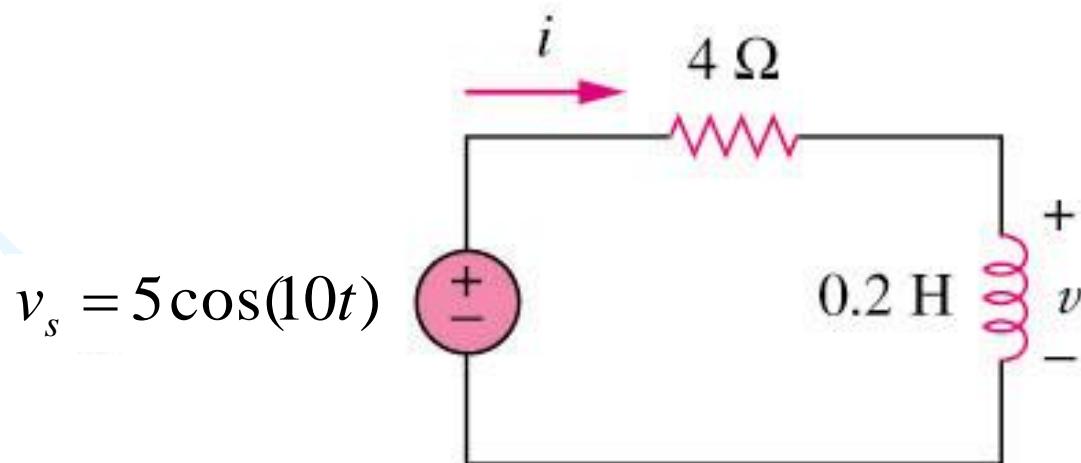


Figure 9.16
For Example 9.9.

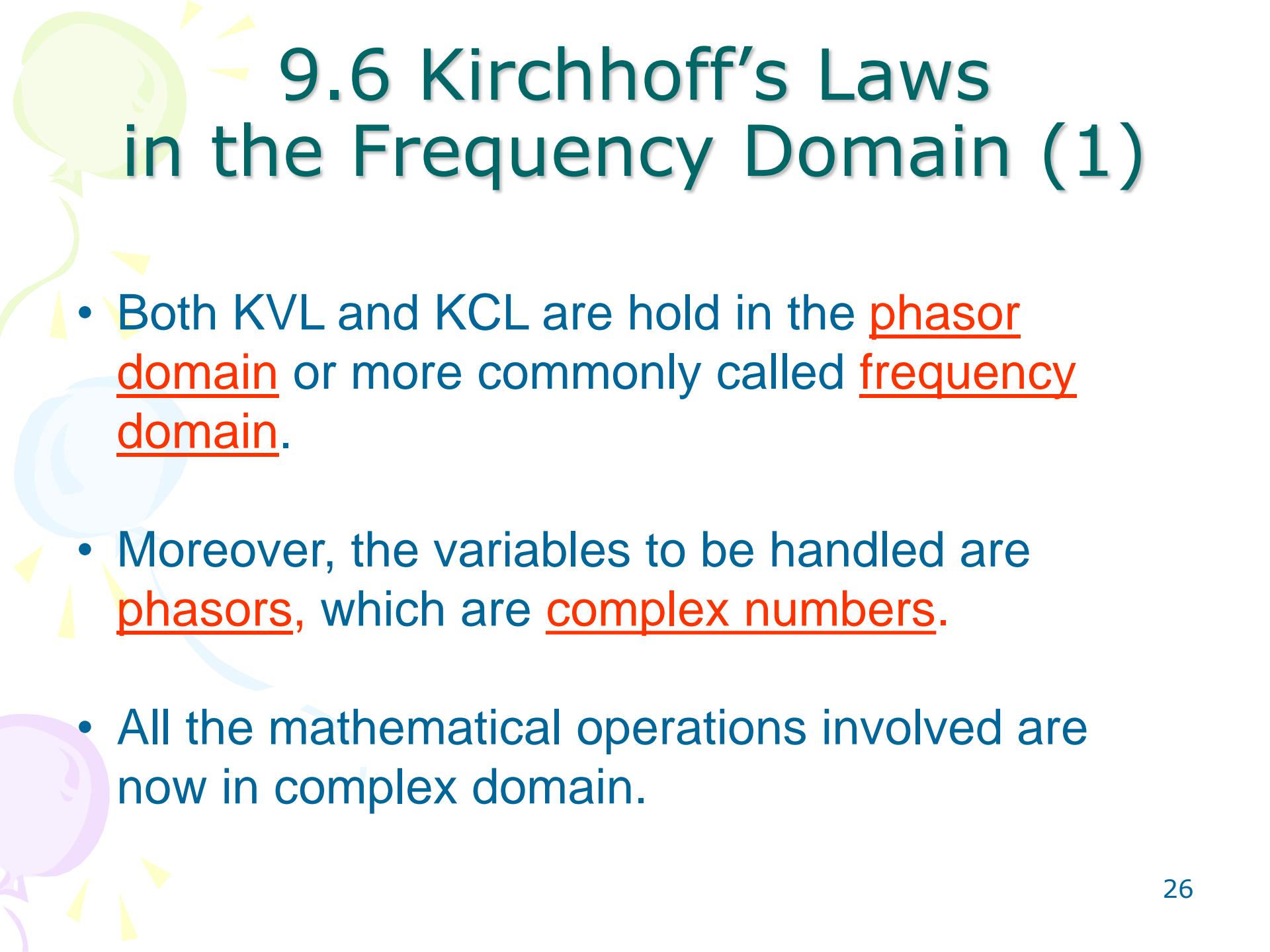
9.5 Impedance and Admittance (5)

Example 9.9 and practice problem 9.9

Refer to Figure below, determine $v(t)$ and $i(t)$.



Answers: $i(t) = 1.118\cos(10t - 26.56^\circ) \text{ A}$; $v(t) = 2.236\cos(10t + 63.43^\circ) \text{ V}$



9.6 Kirchhoff's Laws in the Frequency Domain (1)

- Both KVL and KCL are hold in the phasor domain or more commonly called frequency domain.
- Moreover, the variables to be handled are phasors, which are complex numbers.
- All the mathematical operations involved are now in complex domain.

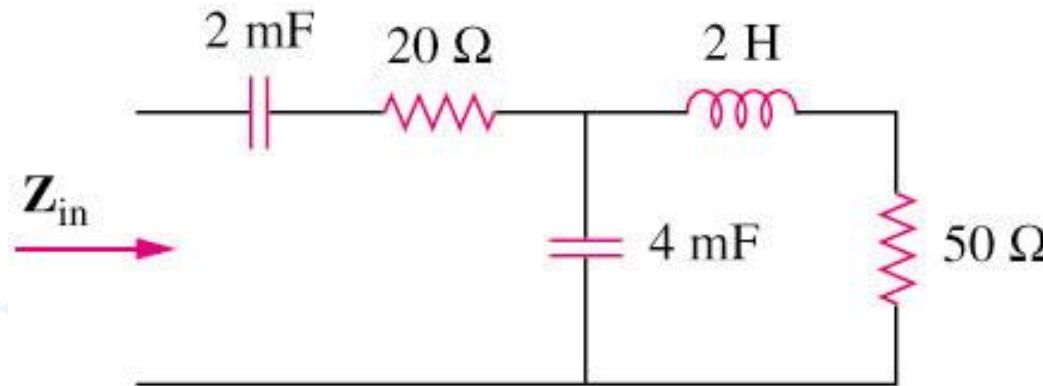
9.7 Impedance Combinations (1)

- The following principles used for DC circuit analysis all apply to AC circuit.
- For example:
 - a. voltage division
 - b. current division
 - c. circuit reduction
 - d. impedance equivalence
 - e. Y- Δ transformation

9.7 Impedance Combinations (2)

Example 9

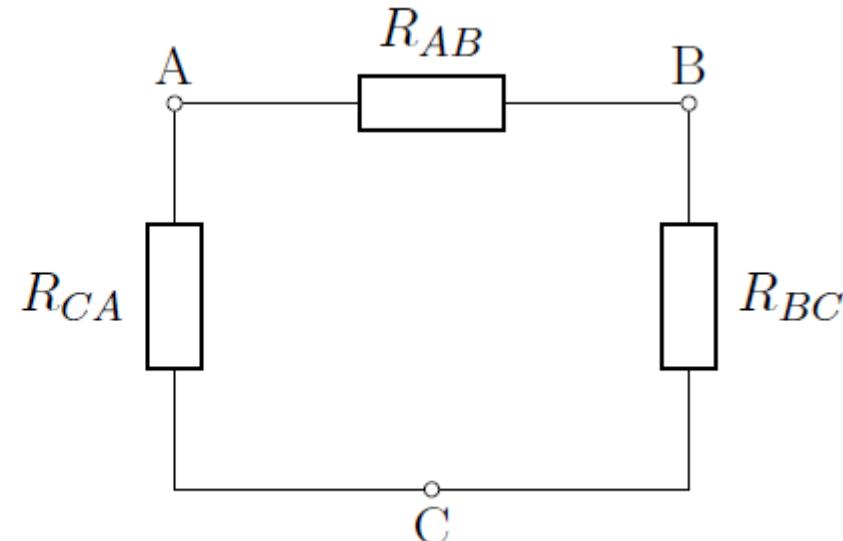
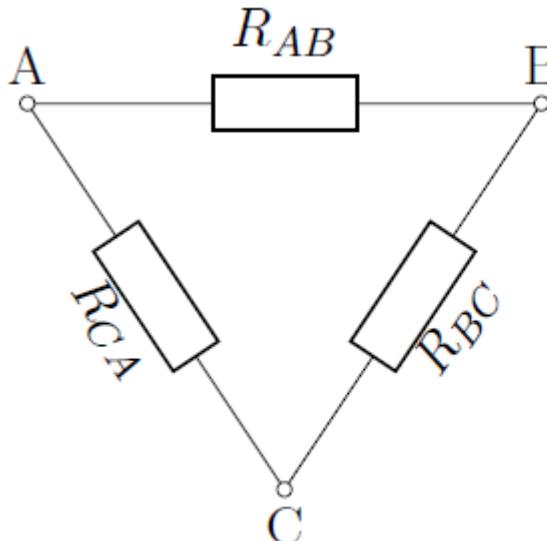
Determine the input impedance of the circuit in figure below at $\omega = 10 \text{ rad/s}$.



Answer: $Z_{in} = 32.38 - j73.76$

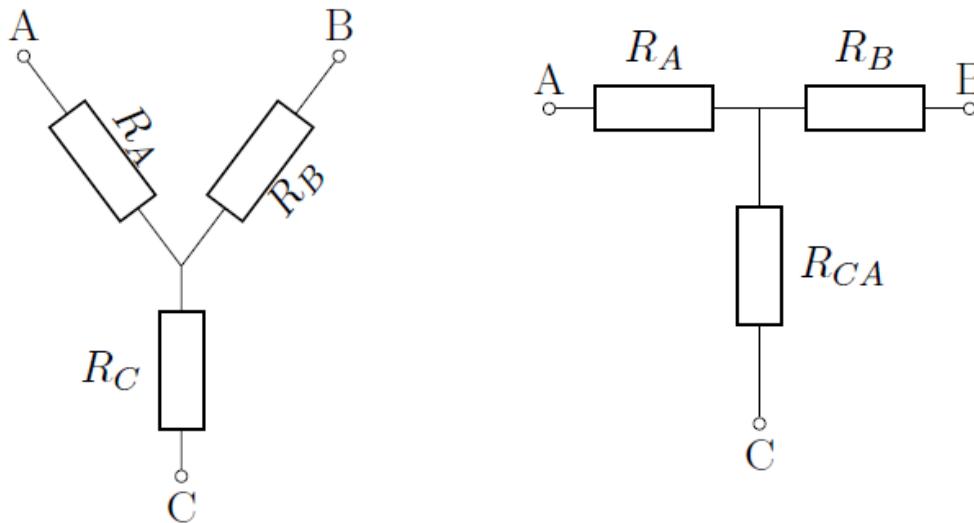
Delta-Y conversions

- In many applications circuits or fragments of circuits form a three-terminal network. Components are then connected together in one of two ways: the “Delta,” or (also known as the “Pi,” or) configuration, and the “Y” (also known as the “T”) configuration.
- The Delta (left side) and (*right side*)



Delta-Y conversions

- The Y (left side) and T (right side) configuration take the form presented below...



Delta-Y conversions

- From Delta (Δ) to Wye (Y).

$$R_A = \frac{R_{AB} * R_{AC}}{R_{AB} + R_{AC} + R_{BC}}$$

$$R_B = \frac{R_{AB} * R_{BC}}{R_{AB} + R_{AC} + R_{BC}}$$

$$R_C = \frac{R_{BC} * R_{AC}}{R_{AB} + R_{AC} + R_{BC}}$$

- From Wye (Y) to Delta (Δ).

$$R_{AB} = \frac{R_A * R_B + R_A * R_C + R_B * R_C}{R_C}$$

$$R_{AC} = \frac{R_A * R_B + R_A * R_C + R_B * R_C}{R_B}$$

$$R_{BC} = \frac{R_A * R_B + R_A * R_C + R_B * R_C}{R_A}$$