
An Introduction of Support Vector Machine

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Support Vector Machine (SVM)

- A classifier derived from statistical learning theory by Vapnik, et al. in 1992
- SVM became famous when, using images as input, it gave accuracy comparable to neural-network with hand-designed features in a handwriting recognition task
- Currently, SVM is widely used in object detection & recognition, content-based image retrieval, text recognition, biometrics, speech recognition, etc.
- Also used for regression (will not cover today)



V. Vapnik

Outline

- Linear Discriminant Function
 - Large Margin Linear Classifier
 - Nonlinear SVM: The Kernel Trick
 - Demo of SVM
-

Discriminant Function

- the classifier is said to assign a feature vector \mathbf{x} to class w_i if

$$g_i(\mathbf{x}) > g_j(\mathbf{x}) \quad \text{for all } j \neq i$$

- For two-category case, $g(\mathbf{x}) \equiv g_1(\mathbf{x}) - g_2(\mathbf{x})$

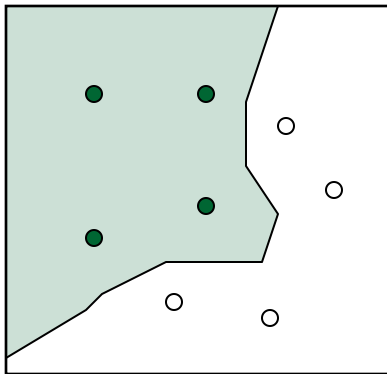
Decide ω_1 if $g(\mathbf{x}) > 0$; otherwise decide ω_2

- An example we've learned before:
 - Minimum-Error-Rate Classifier

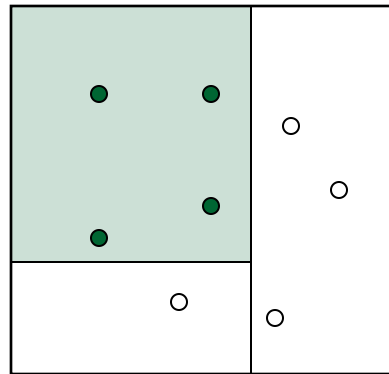
$$g(\mathbf{x}) \equiv p(\omega_1 | \mathbf{x}) - p(\omega_2 | \mathbf{x})$$

Discriminant Function

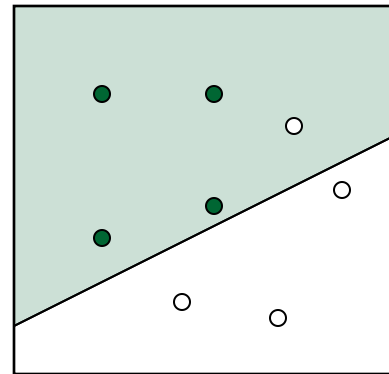
- It can be arbitrary functions of \mathbf{x} , such as:



Nearest
Neighbor

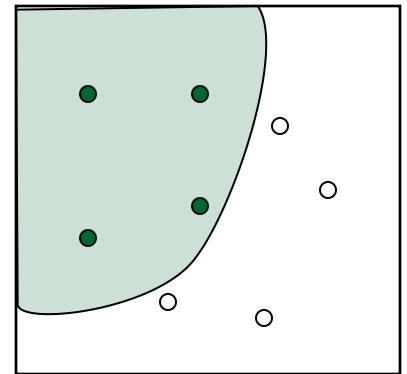


Decision
Tree



Linear
Functions

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b$$



Nonlinear
Functions

Linear Discriminant Function

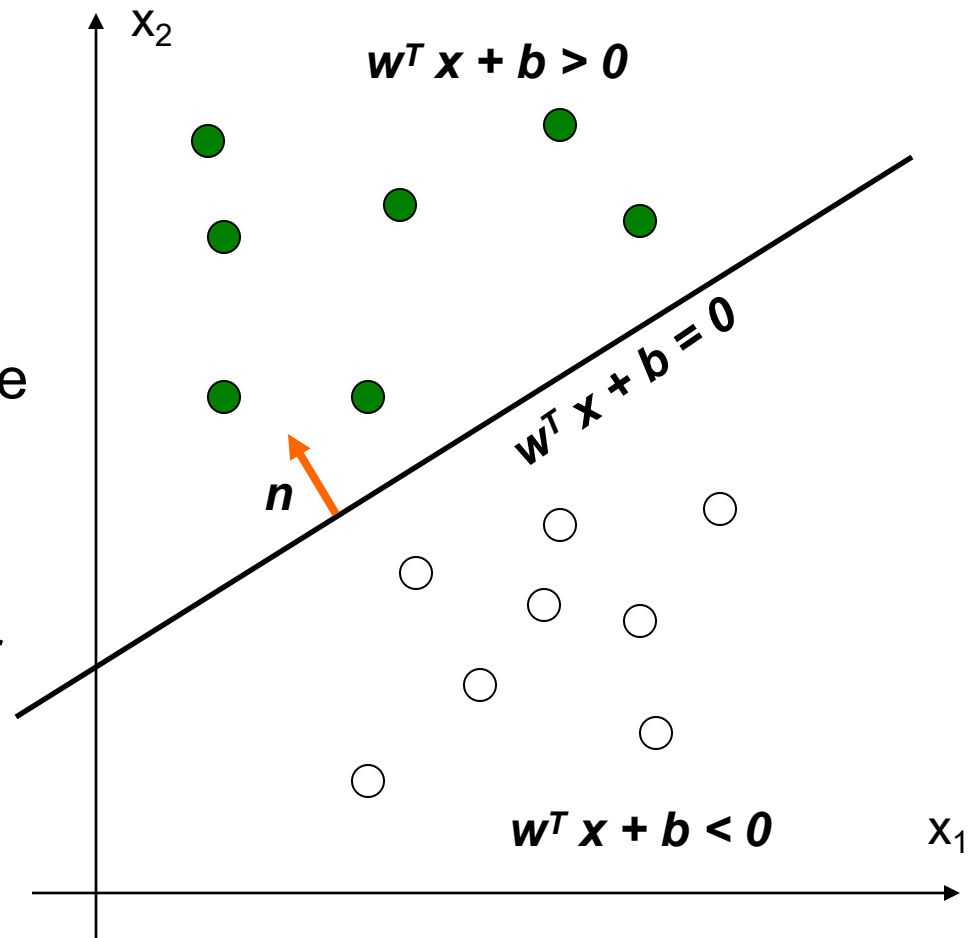
- $g(\mathbf{x})$ is a linear function:

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b$$

- A hyper-plane in the feature space

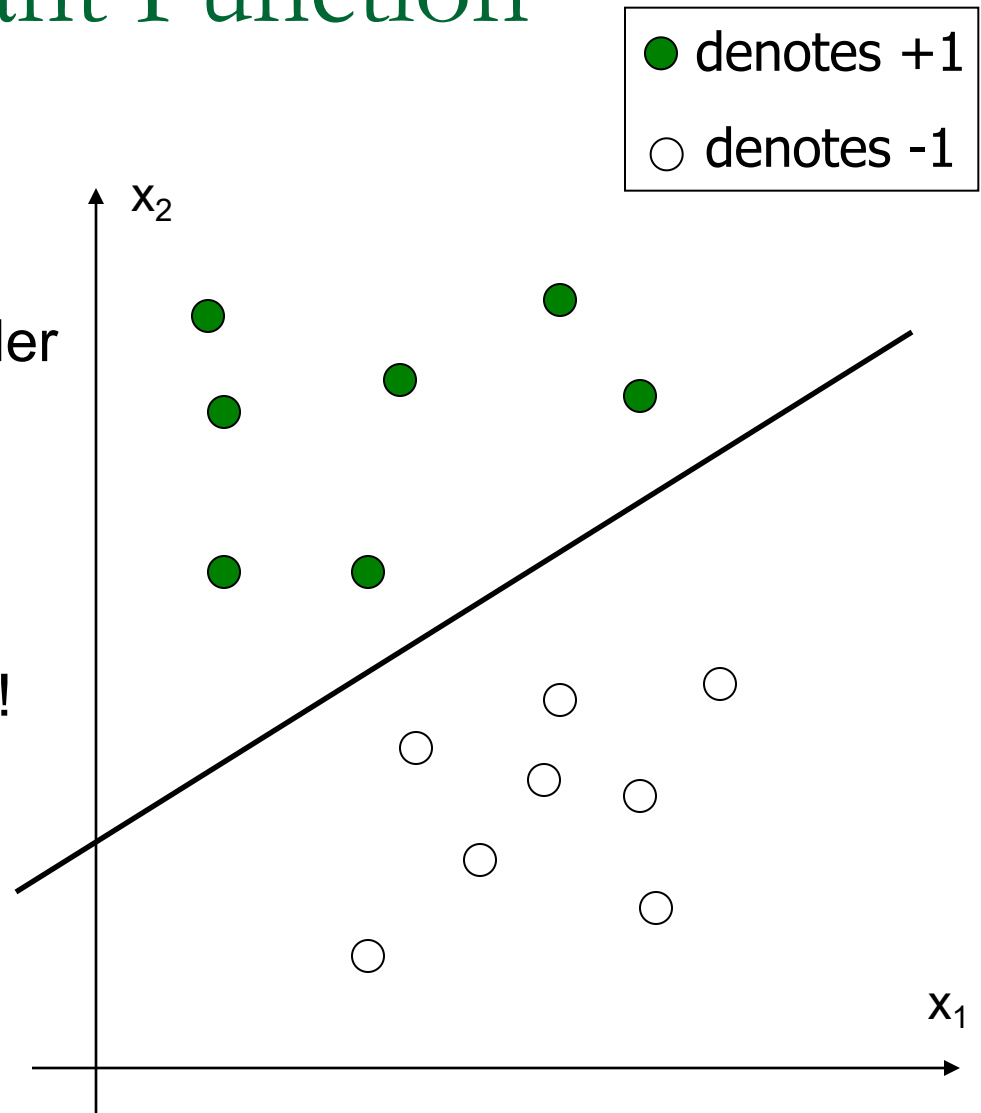
- (Unit-length) normal vector of the hyper-plane:

$$\mathbf{n} = \frac{\mathbf{w}}{\|\mathbf{w}\|}$$



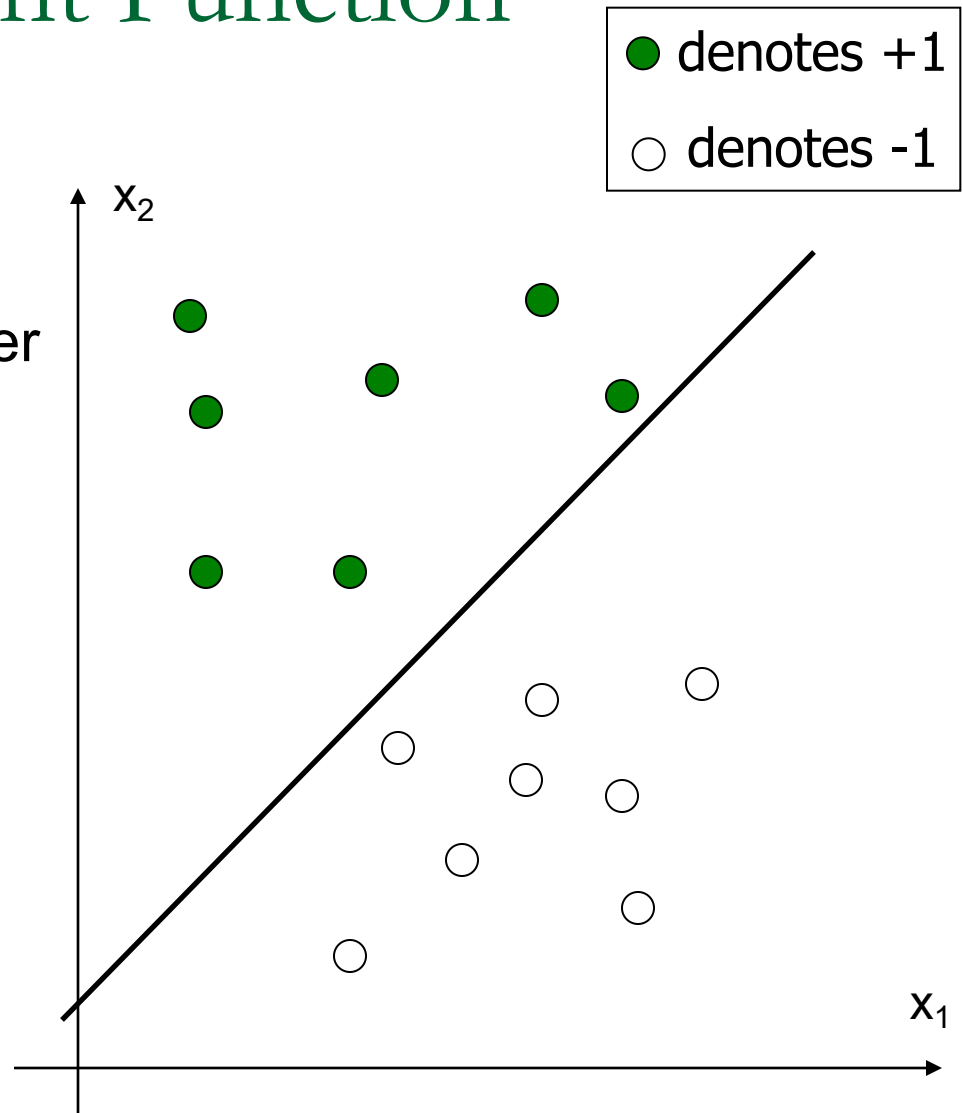
Linear Discriminant Function

- How would you classify these points using a linear discriminant function in order to minimize the error rate?
- Infinite number of answers!



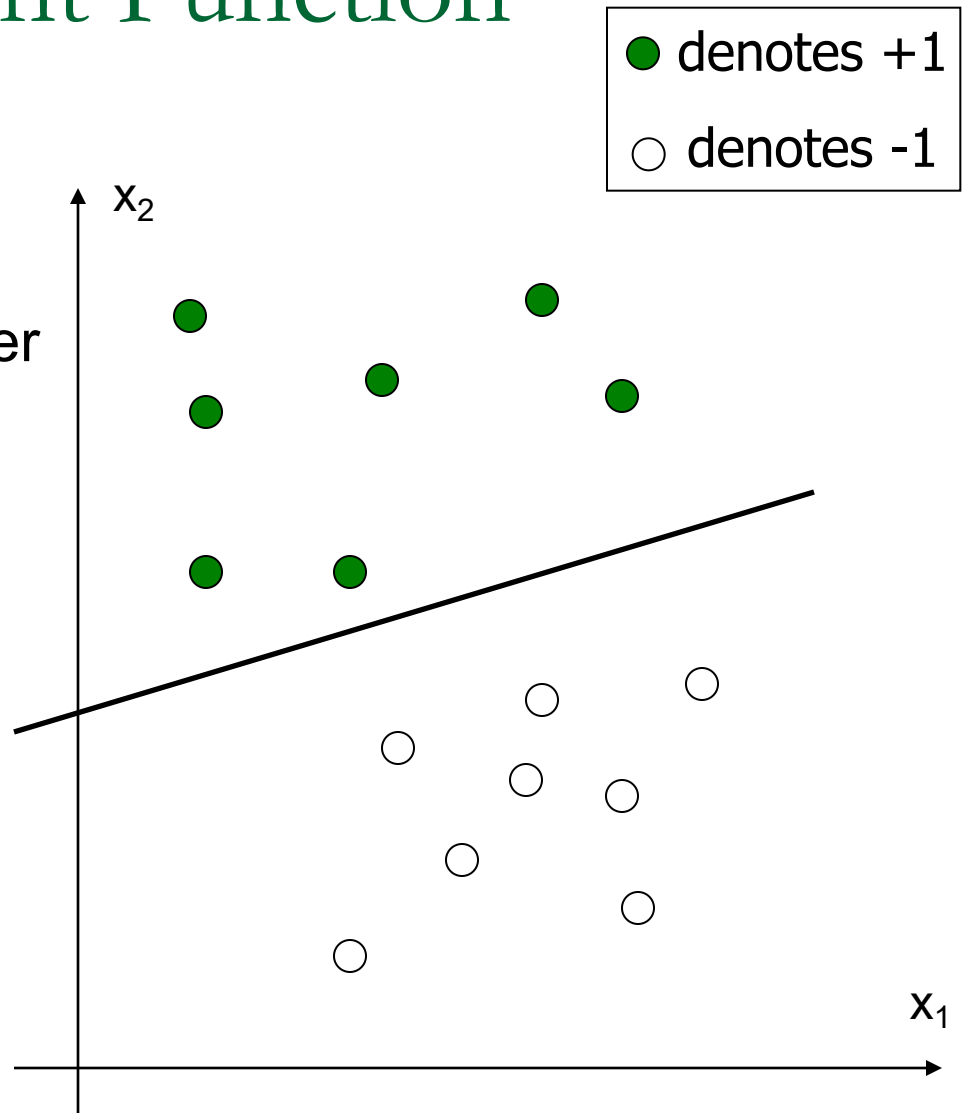
Linear Discriminant Function

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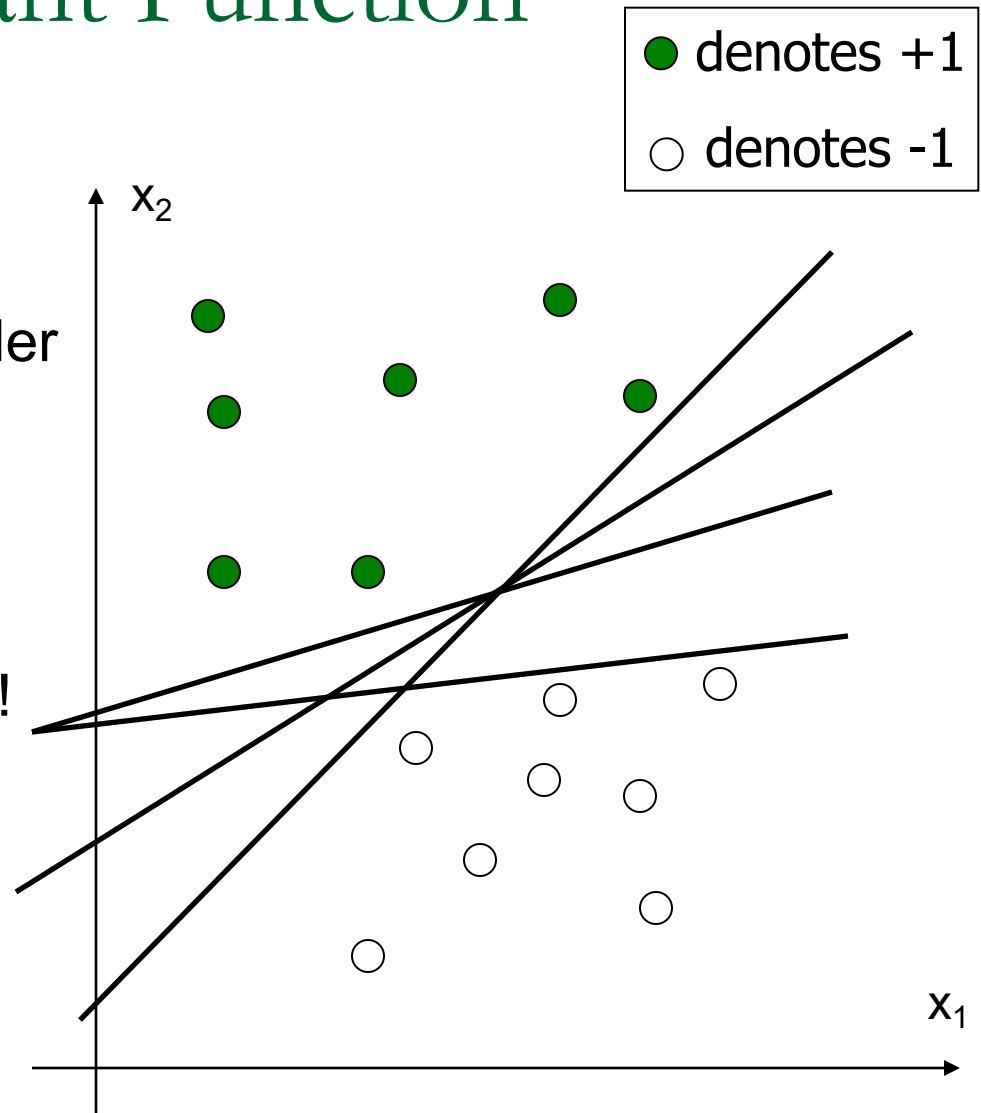
Linear Discriminant Function

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- Infinite number of answers!



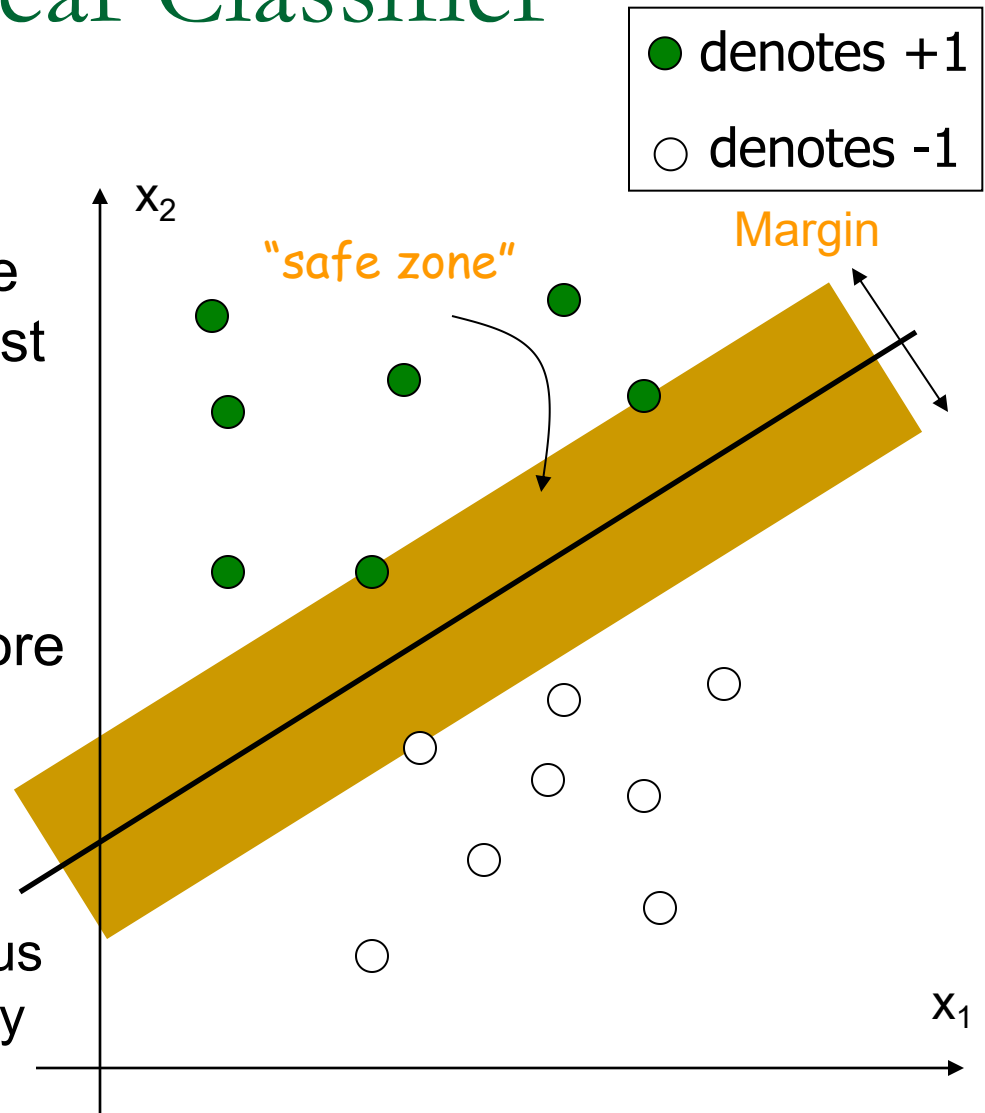
Linear Discriminant Function

- How would you classify these points using a linear discriminant function in order to minimize the error rate?
- Infinite number of answers!
- Which one is the best?



Large Margin Linear Classifier

- The linear discriminant function (classifier) with the maximum **margin** is the best
- Margin is defined as the width that the boundary could be increased by before hitting a data point
- Why it is the best?
 - Robust to outliers and thus strong generalization ability



Large Margin Linear Classifier

● denotes +1
○ denotes -1

- Given a set of data points:
 $\{(\mathbf{x}_i, y_i)\}, i = 1, 2, \dots, n$, where

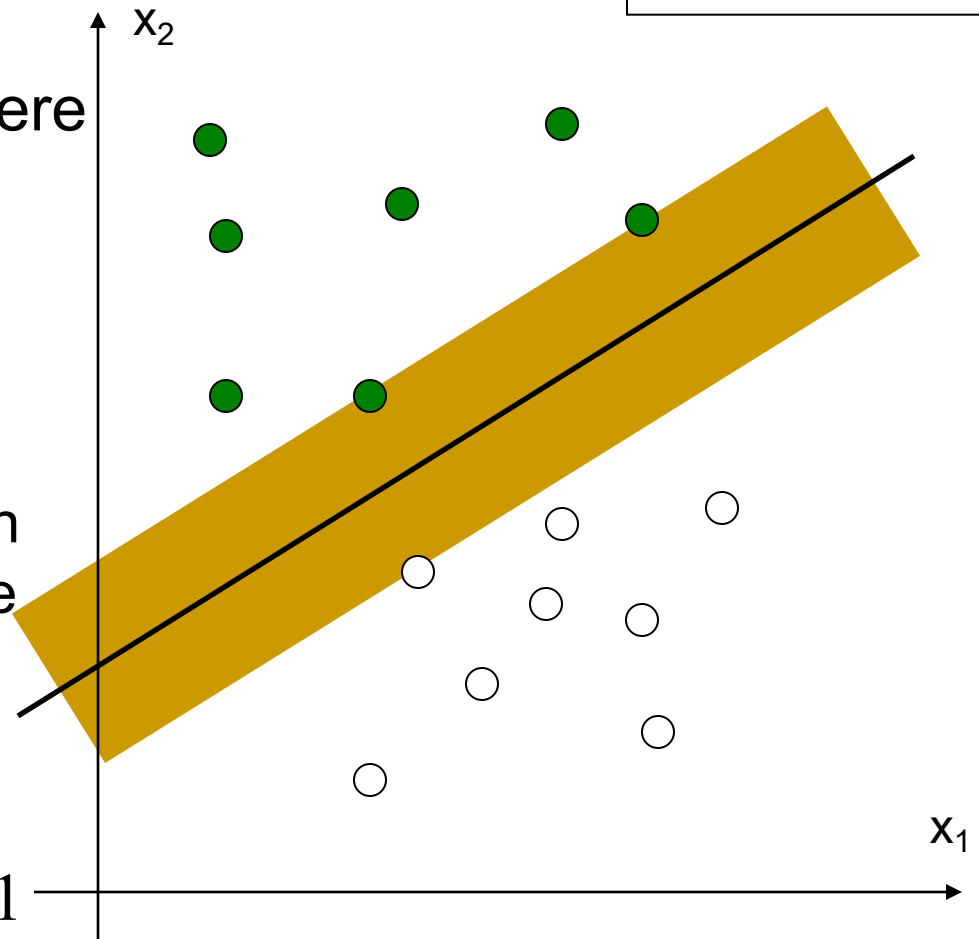
For $y_i = +1$, $\mathbf{w}^T \mathbf{x}_i + b > 0$

For $y_i = -1$, $\mathbf{w}^T \mathbf{x}_i + b < 0$

- With a scale transformation on both \mathbf{w} and b , the above is equivalent to

For $y_i = +1$, $\mathbf{w}^T \mathbf{x}_i + b \geq 1$

For $y_i = -1$, $\mathbf{w}^T \mathbf{x}_i + b \leq -1$



Large Margin Linear Classifier

- We know that

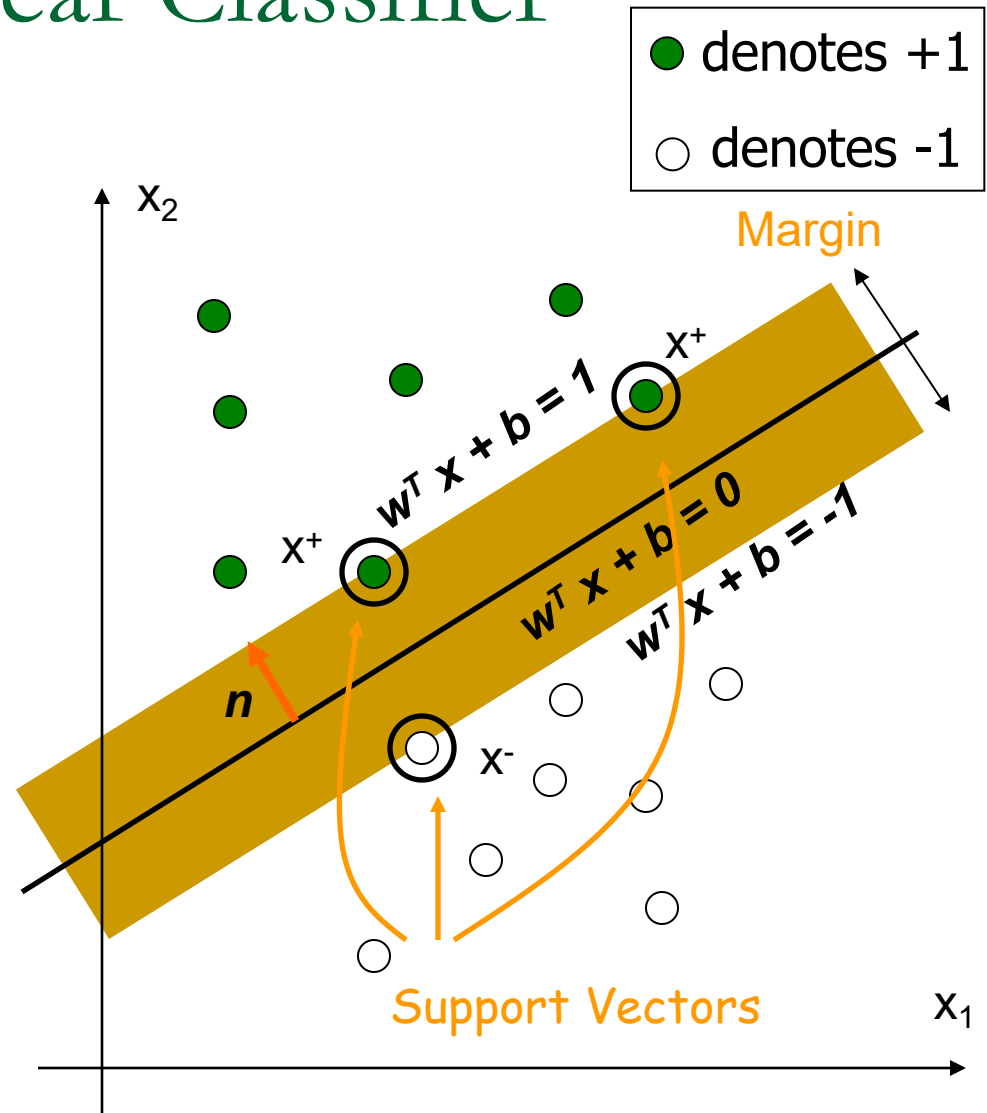
$$\mathbf{w}^T \mathbf{x}^+ + b = 1$$

$$\mathbf{w}^T \mathbf{x}^- + b = -1$$

- The margin width is:

$$M = (\mathbf{x}^+ - \mathbf{x}^-) \cdot \mathbf{n}$$

$$= (\mathbf{x}^+ - \mathbf{x}^-) \cdot \frac{\mathbf{w}}{\|\mathbf{w}\|} = \frac{2}{\|\mathbf{w}\|}$$



Large Margin Linear Classifier

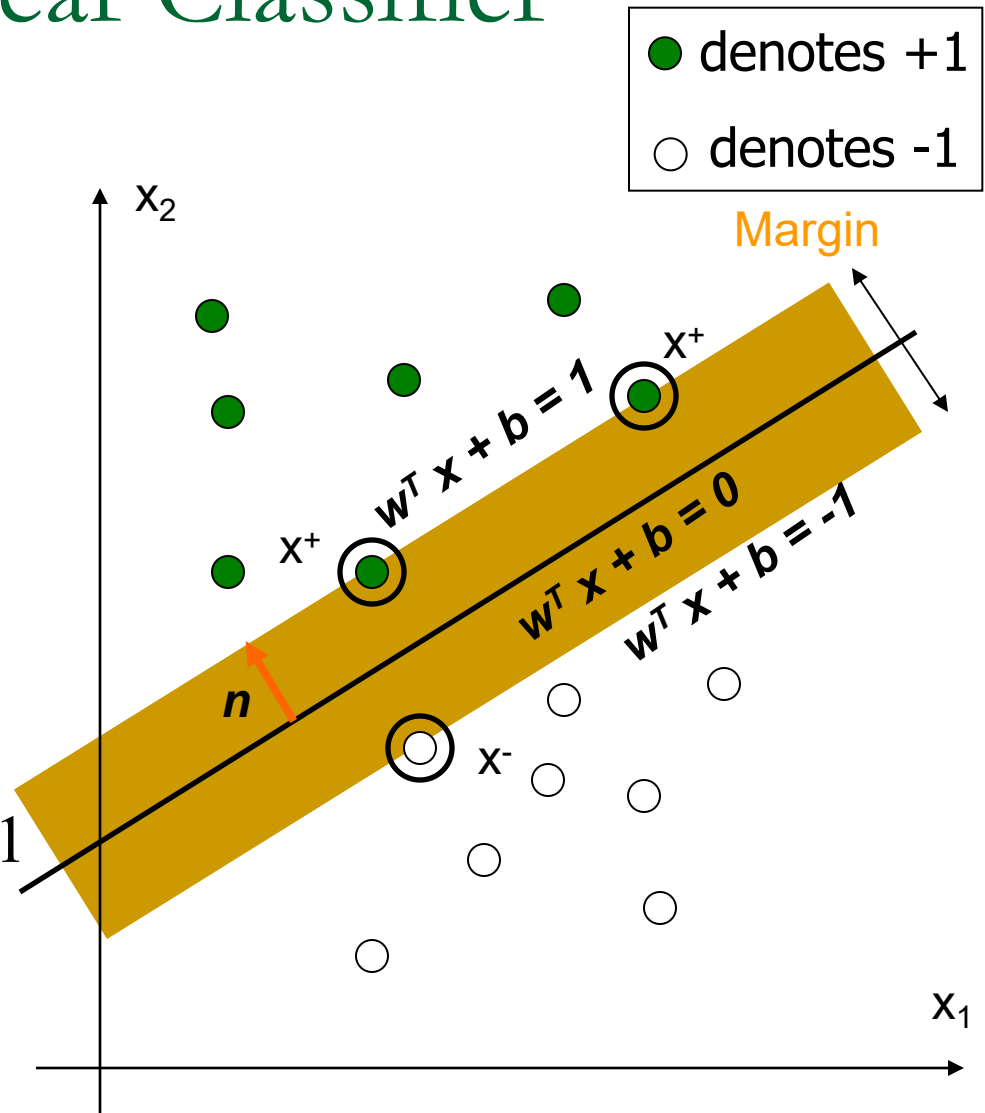
■ Formulation:

$$\max_{\mathbf{w}} \frac{2}{\|\mathbf{w}\|}$$

such that

For $y_i = +1$, $\mathbf{w}^T \mathbf{x}_i + b \geq 1$

For $y_i = -1$, $\mathbf{w}^T \mathbf{x}_i + b \leq -1$



Large Margin Linear Classifier

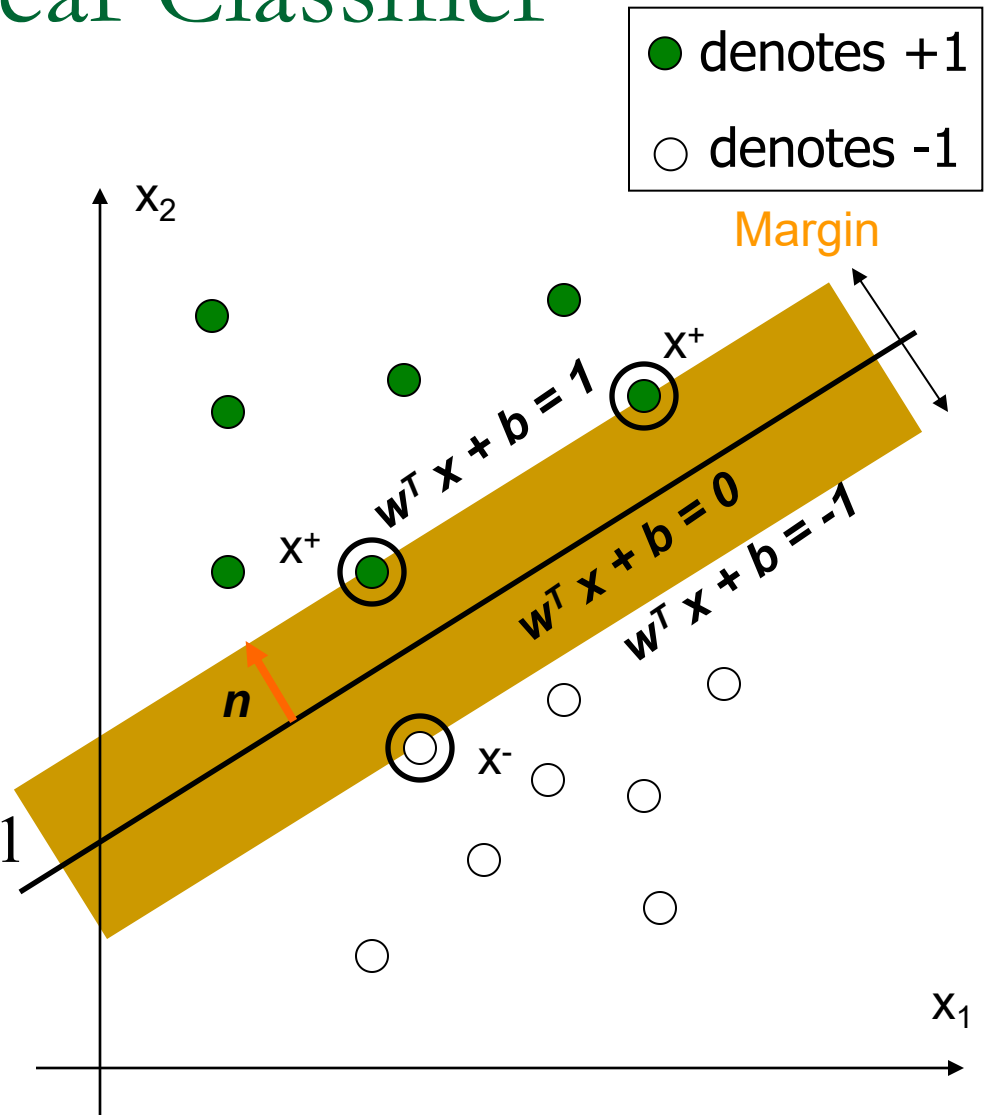
■ Formulation:

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2$$

such that

For $y_i = +1$, $\mathbf{w}^T \mathbf{x}_i + b \geq 1$

For $y_i = -1$, $\mathbf{w}^T \mathbf{x}_i + b \leq -1$



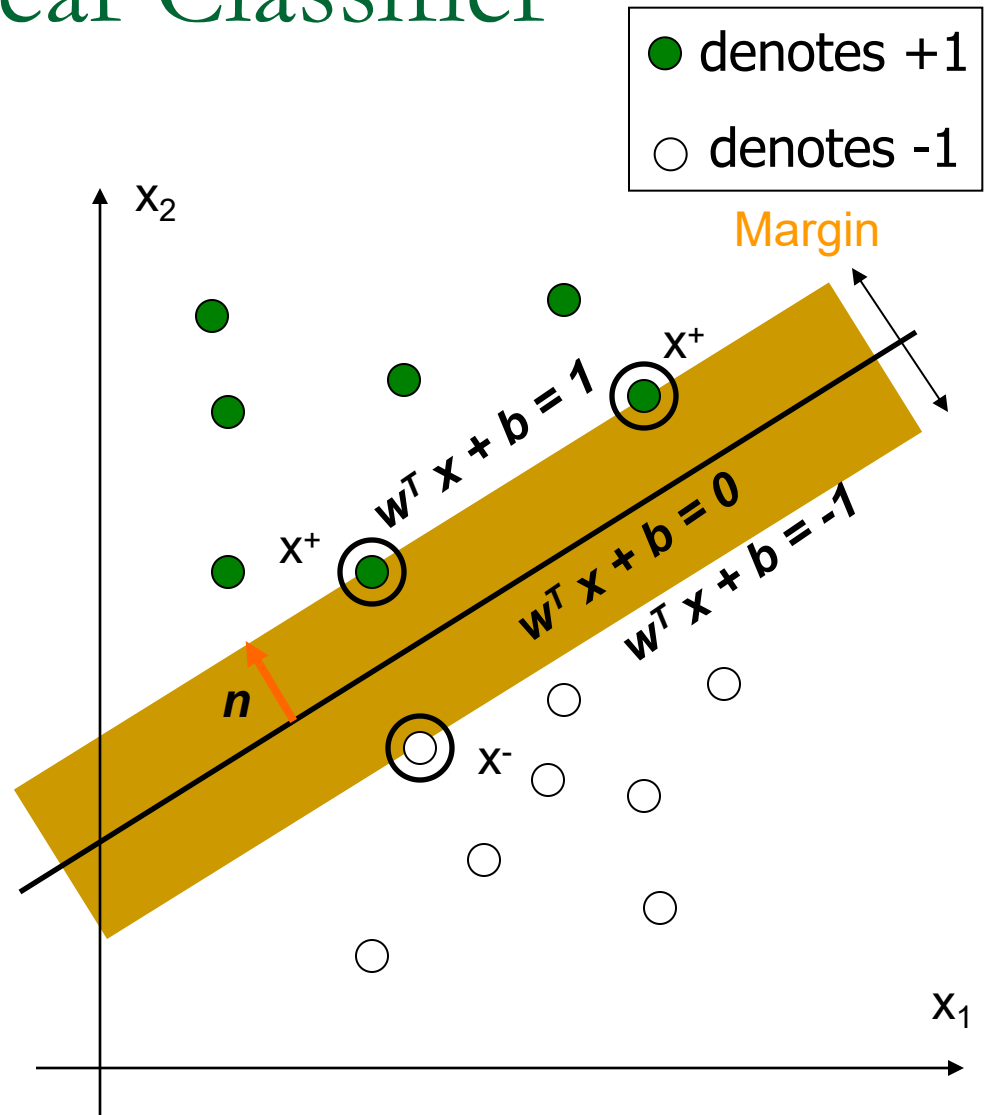
Large Margin Linear Classifier

■ Formulation:

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2$$

such that

$$y_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1$$

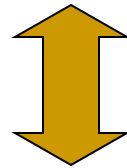


Solving the Optimization Problem

Quadratic
programming
with linear
constraints

$$\begin{aligned} \min_{\mathbf{w}} \quad & \frac{1}{2} \|\mathbf{w}\|^2 \\ \text{s.t.} \quad & y_i(\mathbf{w}^T \mathbf{x}_i + b) \geq 1 \end{aligned}$$

Lagrangian
Function



$$\begin{aligned} \min_{\alpha} \quad & L_p(\mathbf{w}, b, \alpha_i) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^n \alpha_i (y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1) \\ \text{s.t.} \quad & \alpha_i \geq 0 \end{aligned}$$

Solving the Optimization Problem

$$\begin{aligned} \min_{\alpha} L_p(\mathbf{w}, b, \alpha_i) &= \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^n \alpha_i (y_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) \\ \text{s.t.} \quad &\alpha_i \geq 0 \end{aligned}$$

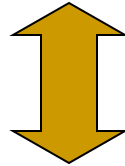
$$\frac{\partial L_p}{\partial \mathbf{w}} = 0 \quad \longrightarrow \quad \mathbf{w} = \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i$$

$$\frac{\partial L_p}{\partial b} = 0 \quad \longrightarrow \quad \sum_{i=1}^n \alpha_i y_i = 0$$

Solving the Optimization Problem

$$\begin{aligned} \min_{\mathbf{w}, b} \quad & L_p(\mathbf{w}, b, \alpha_i) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^n \alpha_i (y_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) \\ \text{s.t.} \quad & \alpha_i \geq 0 \end{aligned}$$

Lagrangian Dual
Problem



$$\begin{aligned} \max_{\alpha} \quad & \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j \\ \text{s.t.} \quad & \alpha_i \geq 0, \text{ and } \sum_{i=1}^n \alpha_i y_i = 0 \end{aligned}$$

Solving the Optimization Problem

- From KKT condition, we know:

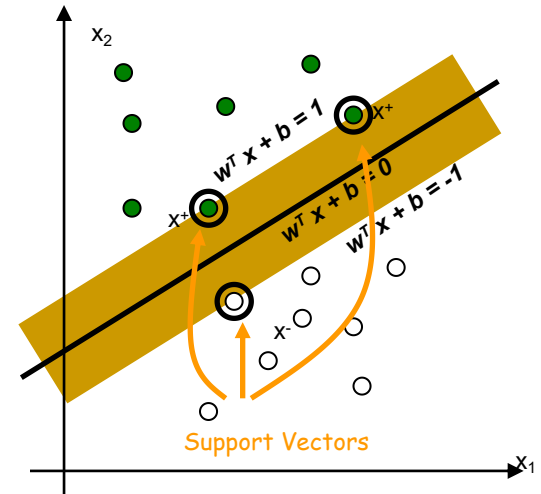
$$\alpha_i (y_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) = 0$$

- Thus, only support vectors have $\alpha_i \neq 0$

- The solution has the form:

$$\mathbf{w} = \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i = \sum_{i \in \text{SV}} \alpha_i y_i \mathbf{x}_i$$

get b from $y_i (\mathbf{w}^T \mathbf{x}_i + b) - 1 = 0$,
where \mathbf{x}_i is support vector



Solving the Optimization Problem

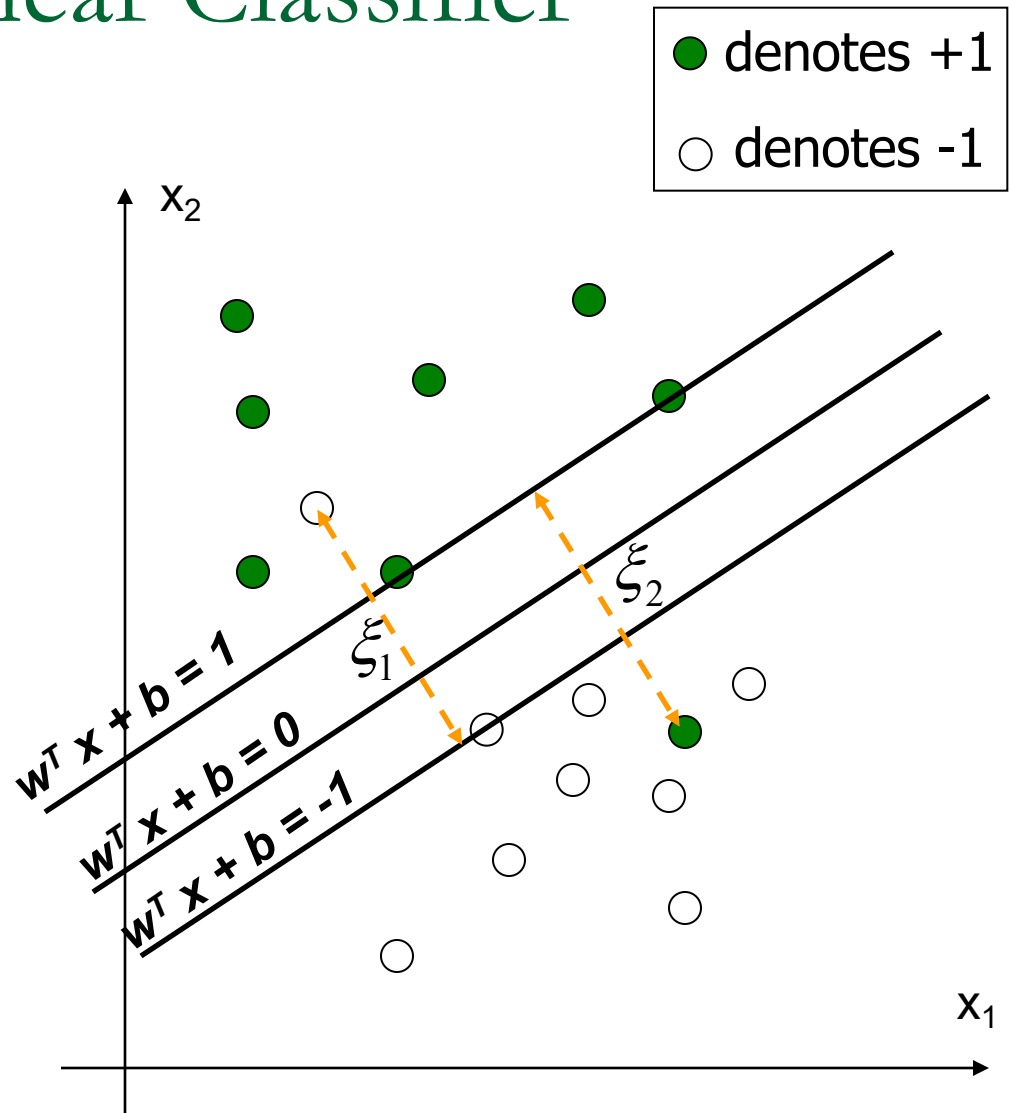
- The linear discriminant function is:

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b = \sum_{i \in \text{SV}} \alpha_i y_i \mathbf{x}_i^T \mathbf{x} + b$$

- Notice it relies on a *dot product* between the test point \mathbf{x} and the support vectors \mathbf{x}_i
- Also keep in mind that solving the optimization problem involved computing the *dot products* $\mathbf{x}_i^T \mathbf{x}_j$ between all pairs of training points

Large Margin Linear Classifier

- What if data is not linear separable? (noisy data, outliers, etc.)
- Slack variables ξ_i can be added to allow misclassification of difficult or noisy data points



Large Margin Linear Classifier

- Formulation:

$$\min_{\mathbf{w}} \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^n \xi_i$$

such that

$$y_i (\mathbf{w}^T \mathbf{x}_i + b) \geq 1 - \xi_i$$

$$\xi_i \geq 0$$

- Parameter C can be viewed as a way to control over-fitting.
-

Large Margin Linear Classifier

- Formulation: (Lagrangian Dual Problem)

$$\max_{\alpha} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j$$

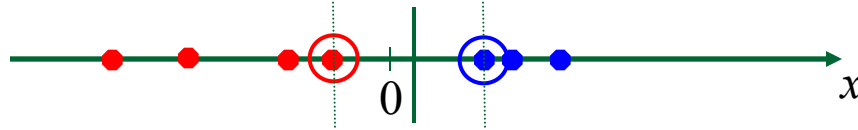
such that

$$0 \leq \alpha_i \leq C$$

$$\sum_{i=1}^n \alpha_i y_i = 0$$

Non-linear SVMs

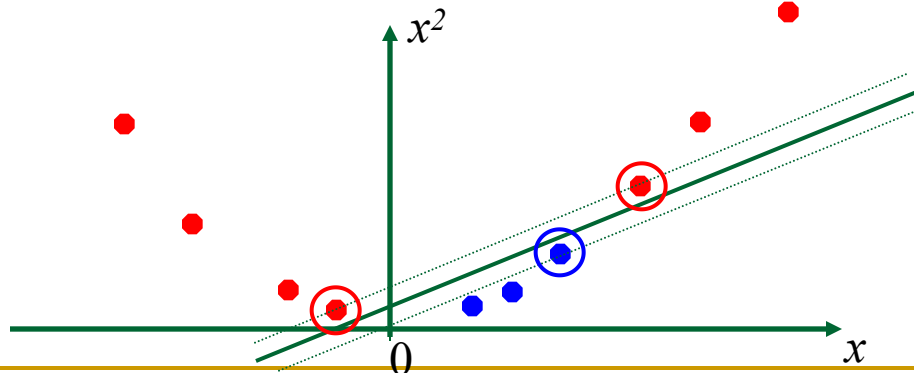
- Datasets that are linearly separable with noise work out great:



- But what are we going to do if the dataset is just too hard?

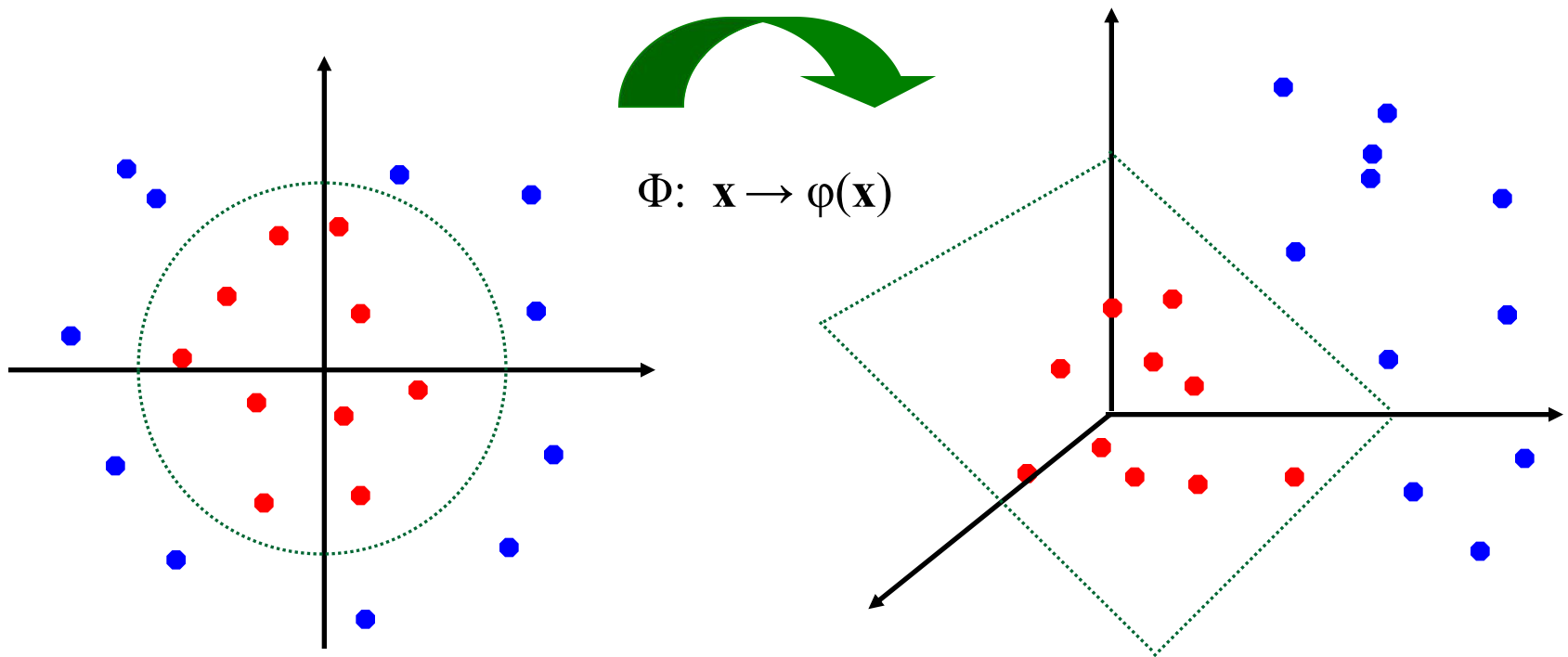


- How about... mapping data to a higher-dimensional space:



Non-linear SVMs: Feature Space

- General idea: the original input space can be mapped to some higher-dimensional feature space where the training set is separable:



Nonlinear SVMs: The Kernel Trick

- With this mapping, our discriminant function is now:

$$g(\mathbf{x}) = \mathbf{w}^T \phi(\mathbf{x}) + b = \sum_{i \in SV} \alpha_i y_i \boxed{\phi(\mathbf{x}_i)^T \phi(\mathbf{x})} + b$$

- No need to know this mapping explicitly, because we only use the **dot product** of feature vectors in both the training and test.
- A **kernel function** is defined as a function that corresponds to a dot product of two feature vectors in some expanded feature space:

$$K(\mathbf{x}_i, \mathbf{x}_j) \equiv \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$$

Nonlinear SVMs: The Kernel Trick

- An example:

2-dimensional vectors $\mathbf{x}=[x_1 \ x_2]$;

let $K(\mathbf{x}_i, \mathbf{x}_j) = (1 + \mathbf{x}_i^T \mathbf{x}_j)^2$,

Need to show that $K(\mathbf{x}_i, \mathbf{x}_j) = \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$:

$$\begin{aligned} K(\mathbf{x}_i, \mathbf{x}_j) &= (1 + \mathbf{x}_i^T \mathbf{x}_j)^2, \\ &= 1 + x_{i1}^2 x_{j1}^2 + 2 x_{i1} x_{j1} x_{i2} x_{j2} + x_{i2}^2 x_{j2}^2 + 2 x_{i1} x_{j1} + 2 x_{i2} x_{j2} \\ &= [1 \ x_{i1}^2 \ \sqrt{2} x_{i1} x_{i2} \ x_{i2}^2 \ \sqrt{2} x_{i1} \ \sqrt{2} x_{i2}]^T [1 \ x_{j1}^2 \ \sqrt{2} x_{j1} x_{j2} \ x_{j2}^2 \ \sqrt{2} x_{j1} \ \sqrt{2} x_{j2}] \\ &= \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j), \quad \text{where } \phi(\mathbf{x}) = [1 \ x_1^2 \ \sqrt{2} x_1 x_2 \ x_2^2 \ \sqrt{2} x_1 \ \sqrt{2} x_2] \end{aligned}$$

Nonlinear SVMs: The Kernel Trick

- Examples of commonly-used kernel functions:

- Linear kernel: $K(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{x}_i^T \mathbf{x}_j$

- Polynomial kernel: $K(\mathbf{x}_i, \mathbf{x}_j) = (1 + \mathbf{x}_i^T \mathbf{x}_j)^p$

- Gaussian (Radial-Basis Function (RBF)) kernel:

$$K(\mathbf{x}_i, \mathbf{x}_j) = \exp\left(-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2}\right)$$

- Sigmoid:

$$K(\mathbf{x}_i, \mathbf{x}_j) = \tanh(\beta_0 \mathbf{x}_i^T \mathbf{x}_j + \beta_1)$$

- In general, functions that satisfy *Mercer's condition* can be kernel functions.

Nonlinear SVM: Optimization

- Formulation: (Lagrangian Dual Problem)

$$\max_{\alpha} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j K(\mathbf{x}_i, \mathbf{x}_j)$$

such that

$$0 \leq \alpha_i \leq C$$

$$\sum_{i=1}^n \alpha_i y_i = 0$$

- The solution of the discriminant function is

$$g(\mathbf{x}) = \sum_{i \in \text{SV}} \alpha_i y_i K(\mathbf{x}_i, \mathbf{x}) + b$$

- The optimization technique is the same.

Support Vector Machine: Algorithm

- 1. Choose a kernel function
 - 2. Choose a value for C
 - 3. Solve the quadratic programming problem
(many software packages available)
 - 4. Construct the discriminant function from the support vectors
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Some Issues

- Choice of kernel
 - Gaussian or polynomial kernel is default
 - if ineffective, more elaborate kernels are needed
 - domain experts can give assistance in formulating appropriate similarity measures
- Choice of kernel parameters
 - e.g. σ in Gaussian kernel
 - σ is the distance between closest points with different classifications
 - In the absence of reliable criteria, applications rely on the use of a validation set or cross-validation to set such parameters.
- Optimization criterion – Hard margin v.s. Soft margin
 - a lengthy series of experiments in which various parameters are tested

Summary: Support Vector Machine

- 1. Large Margin Classifier
 - Better generalization ability & less over-fitting
 - 2. The Kernel Trick
 - Map data points to higher dimensional space in order to make them linearly separable.
 - Since only dot product is used, we do not need to represent the mapping explicitly.
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Additional Resource

- <http://www.kernel-machines.org/>

Demo of LibSVM

<http://www.csie.ntu.edu.tw/~cjlin/libsvm/>

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- <http://www.kernel-machines.org/>
 - <http://www.support-vector.net/>
 - <http://www.support-vector.net/icmltutorial.pdf>
 - <http://www.kernelmachines.org/papers/tutorial-nips.ps.gz>
 - <http://www.clopinet.com/isabelle/Projects/SVM/applist.html>
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