# Spectral Theory and Jordan Canonical Form

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#### Abstract

Summary of spectral theory (including Jordan canonical form) as presented in Lax[2].

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The content of this note is based on Lax[2] Chapter 6 and Appendix 15. To make use of the Fundamental Theorem of Algebra so that characteristic polynomials have a full set of roots, the spectral theory of linear maps is formulated in linear spaces over the field of complex numbers.

#### 1 Eigenvalues, Eigenvectors

**Proposition 1.** Every  $n \times n$  matrix over the field of complex numbers has an eigenvector in  $\mathbb{C}^n$ .

*Proof.* Choose any nonzero vector w, the following set of n+1 vectors must be linearly dependent:

$$w, Aw, A^2w, \cdots, A^nw.$$

This implies the existence of a polynomial  $p(t) = \sum_{j=0}^{n} c_j t^j$  over the complex numbers, such that p(A)w = 0. By the Fundamental Theorem of Algebra, p(t) can be written as a product of linear factors:

$$p(t) = c \prod_{i=1}^{n} (x - a_i), \ a_i, c \in \mathbb{C}, c \neq 0,$$

and consequently, p(A)w = 0 can be rewritten as

$$c\prod_{j=1}^{n}(A-a_{j}I)w=0.$$

This implies at least one of the matrices  $(A - a_j I)$  is not invertible; such a matrix  $(A - a_{j_0} I)$  has a nontrivial nullspace. So, there is an eigenvector pertaining to the eigenvalue  $a_{j_0}$ .

**Proposition 2.** Eigenvectors of a matrix A corresponding to distinct eigenvalues are linearly independent.

*Proof.* Consider a nontrivial linear relation among the eigenvectors that involves the least number m of eigenvectors:

$$\sum_{j=1}^{m} b_j h_j = 0, b_j \neq 0, j = 1, \cdots, m;$$

here  $h_j$  is the eigenvector pertaining to eigenvalue  $a_j$  ( $a_j \neq a_k$  for  $j \neq k$ ). Applying A to the equation, we get

$$\sum_{j=1}^{m} b_j a_j h_j = 0,$$

and hence

$$a_m \sum_{i=1}^m b_j h_j - \sum_{i=1}^m b_j a_j h_j = \sum_{i=1}^m b_j (a_m - a_j) h_j = 0.$$

Clearly the coefficient of  $h_m$  is zero and none of the others is zero, so we have a nontrivial linear relation among the  $h_j$  involving only (m-1) of the vectors, contrary to the m being the smallest number of vectors satisfying such a relation.

### 2 Characteristic Polynomial

Proposition 1 shows that every matrix A has at least one eigenvalue, but it does not show how many or how to calculate them. Recall Lax[2] Chapter 5, Corollary 3 states that "an  $n \times n$  matrix A is invertible iff det  $A \neq 0$ ". This implies the following

**Proposition 3.** For a to be an eigenvalue of A it is necessary and sufficient that

$$\det(aI - A) = 0.$$

The polynomial  $p_A(\lambda) = \det(\lambda I - A)$  is called the **characteristic polynomial** of the matrix A.

#### 3 Spectral Mapping Theorem

Theorem 1 (Spectral Theory, part 1: spectral mapping theorem). (a) Let q be any polynomial, A a square matrix, a an eigenvalue of A. Then q(a) is an eigenvalue of q(A).

(b) Every eigenvalue of q(A) is of the form q(a), where a is an eigenvalue of A.

*Proof.* (a) is easy to prove. For (b), suppose b is an eigenvalue of q(A). Then q(A) - bI is not invertible. By the Fundamental Theorem of Algebra, q(s) - b can be decomposed as

$$q(s) - b = c \prod (s - r_i),$$

where  $r_i$ 's may repeat. By  $q(A) - bI = c \prod (A - r_i I)$ , at lease one  $A - r_i I$  is not invertible; such an  $r_i$  is an eigenvalue of A. Note  $q(r_i) = b$ , we are done.

#### 4 Cayley-Hamilton Theorem

**Theorem 2** (Cayley-Hamilton). Every matrix A satisfies its own characteristic equation:

$$p_A(A) = 0.$$

The proof of Cayley-Hamilton Theorem relies on a clever use of the following version of Cramer's rule:

**Proposition 4.** Let A be an  $n \times n$  matrix and B defined as the matrix of cofactors of A; that is,

$$B_{ij} = (-1)^{i+j} \det A_{ji},$$

where  $A_{ji}$  is the (ji)th minor of A. Then  $AB = BA = \det A \cdot I_{n \times n}$ .

*Proof.* Suppose A has the column form  $A = (a_1, \dots, a_n)$ . By replacing the jth column with the ith column in A, we obtain

$$M = (a_1, \cdots, a_{j-1}, a_i, a_j, \cdots, a_n).$$

On one hand, Property (i) of a determinant gives  $\det M = \delta_{ij} \det A$ ; on the other hand, Laplace expansion of a determinant gives

$$\det M = \sum_{k=1}^{n} (-1)^{k+j} a_{ki} \det A_{kj} = \sum_{k=1}^{n} a_{ki} B_{jk} = (B_{j1}, \dots, B_{jn}) \begin{pmatrix} a_{1i} \\ \vdots \\ a_{ni} \end{pmatrix}.$$

Combined, we can conclude det  $A \cdot I_{n \times n} = BA$ . By replacing the *i*th column with the *j*th column in A, we can get similar result for AB.

*Proof.* (Cayley-Hamilton) Let Q(s) = sI - A and P(s) defined as the matrix of cofactors of Q(s):

$$P_{ij}(s) = (-1)^{i+j} D_{ji}(s),$$

where  $D_{ij}$  is the determinant of the ijth minor of Q(s). By Proposition 4,

$$P(s)Q(s) = \det Q(s) \cdot I = p_A(s)I.$$

Since Q(A) = 0, it follows that

$$p_A(A) = 0.$$

#### 5 Spectral Theorem

**Theorem 3 (Spectral Theory, part 2: spectral theorem).** Let A be an  $n \times n$  matrix with complex entries. Every vector in  $\mathbb{C}^n$  can be written as a sum of eigenvectors of A, genuine or generalized.

*Proof.* The key to the proof is the following observation:

$$N_{pq} = N_p \bigoplus N_q,$$

where p and q are polynomials with complex coefficients and have no common zero,  $N_p = \ker p(A)$ ,  $N_q = \ker q(A)$ , and  $N_{pq} = \ker [p(A)q(A)]$ . This observation is based on the existence of two polynomials a and b such that

$$ap + bq \equiv 1. (1)$$

Equation (1) holds for the ring of polynomials over a field, and more generally, for a principal ideal ring or a Euclidean domain. See any textbook on abstract algebra for reference.

By induction, we can easily conclude

$$N_{p_1\cdots p_k}=N_{p_1}\bigoplus\cdots\bigoplus N_{p_k},$$

where  $p_1, \dots, p_k$  are a collection of polynomials that are pairwise without a common zero. In particular, if we denote A's distinct eigenvalues by  $a_1, \dots, a_k$ , the characteristic polynomial  $p_A(s)$  can be written as

$$p_A(s) = c \prod_{i=1}^k (s - a_i)^{m_i}.$$

and hence by Theorem 2 (Cayley-Hamilton)

$$\mathbb{C}^n = N_{p_A} = N_{m_1}(a_1) \bigoplus \cdots \bigoplus N_{m_k}(a_k),$$

where  $N_{m_i}(a_i) = \ker(A - a_i I)^{m_i}$   $(i = 1, \dots, m)$ . This finishes our proof.

Corollary 1. Real symmetric matrices can be diagonalized.

*Proof.* It suffices to show for any eigenvalue a of a real symmetric matrix A, we have d(a) = 1. Indeed, assume  $N_1(a) \subseteq N_2(a)$ , then for any  $x \in N_2(a) \setminus N_1(a)$ , we have

$$(aI - A)x \neq 0, (aI - A)^2x = 0.$$

But  $(aI - A)^2 x = 0$  means

$$\langle (aI - A)x, (aI - A)x \rangle = \langle (aI - A)^2 x, x \rangle = 0,$$

which implies (aI - A)x = 0, contradiction. So we must have d(a) = 1.

#### 6 Minimal Polynomial

Denote by  $\wp = \wp_A$  the set of all polynomials p which satisfy p(A) = 0. Denote by m a nonzero polynomial of smallest degree in  $\wp$ , then

**Proposition 5.** All p in  $\wp$  are multiples of m, and except for a constant factor, m is unique.

We denote by  $m_A$  the unique m whose leading coefficient is 1, and call  $m_A$  the **minimal polynomial** of A.

For given  $a \in \mathbb{C}$ , we denote by  $N_m = N_m(a)$  the nullspace of  $(A - aI)^m$ . The subspaces  $N_m$  consist of generalized eigenvectors; they are indexed increasingly:

$$N_1 \subset N_2 \subset \cdots$$
.

Since these are subspaces of a finite-dimensional space, they must be equal from a certain index on.<sup>1</sup> We denote by d = d(a) the smallest such index, that is

$$N_d = N_{d+1} = \cdots$$

but

$$N_{d-1} \neq N_d$$
;

d(a) is called the **index** of the eigenvalue a.

**Theorem 4** (Minimal Polynomial). Let A ben an  $n \times n$  matrix: denote its distinct eigenvalues by  $a_1, \dots, a_k$ , and denote the index of  $a_i$  by  $d_i$ . We claim that the minimal polynomial  $m_A$  is

$$m_A(s) = \prod_{i=1}^k (s - a_i)^{d_i}.$$

*Proof.* A number is an eigenvalue of A if and only if it's a root of the characteristic polynomial  $p_A$ . So  $p_A(s)$  can be written as  $p_A(s) = \prod_1^k (s - a_i)^{m_i}$  with each  $m_i$  a positive integer  $(i = 1, \dots, k)$ . We have shown in the text that  $p_A$  is a multiple of  $m_A$ , so we can assume  $m_A(s) = \prod_{i=1}^k (s - a_i)^{r_i}$  with each  $r_i$  satisfying  $0 \le r_i \le m_i$   $(i = 1, \dots, k)$ . We argue  $r_i = d_i$  for any  $1 \le i \le k$ .

Indeed, we have

$$\mathbb{C}^n = N_{p_A} = \bigoplus_{j=1}^k N_{m_j}(a_j) = \bigoplus_{j=1}^k N_{d_j}(a_j).$$

where the last equality comes from the observation  $N_{m_j}(a_j) \subseteq N_{m_j+d_j}(a_j) = N_{d_j}(a_j)$  by the definition of  $d_j$ . This shows the polynomial  $\prod_{j=1}^k (s-a_j)^{d_j} \in \wp$ . By the definition of minimal polynomial,  $r_j \leq d_j$  for  $j=1,\dots,n$ .

Assume for some  $j, r_j < d_j$ , we can then find  $x \in N_{d_j}(a_j) \setminus N_{r_j}(a_j)$  with  $x \neq 0$ . Define  $q(s) = \prod_{i=1, i\neq j}^k (s-a_i)^{r_i}$ , then by Corollary 10 x can be uniquely decomposed into x'+x'' with  $x' \in N_q$  and  $x'' \in N_{r_j}(a_j)$ . We have  $0 = (A-a_jI)^{d_j}x = (A-a_jI)^{d_j}x' + 0$ . So  $x' \in N_q \cap N_{d_j}(a_j) = \{0\}$ . This implies  $x = x'' \in N_{r_j}(a_j)$ . Contradiction. Therefore,  $r_i \geq d_i$  for any  $1 \leq i \leq k$ .

Combined, we conclude 
$$m_A(s) = \prod_{i=1}^k (s - a_i)^{d_i}$$
.

**Remark 1.** Along the way, we have shown that the index d of an eigenvalue is no greater than the multiplicity of the eigenvalue as a root of the characteristic polynomial. This is also a consequence of the theorem itself, since  $m_A(s)$  divides  $p_A(s)$ .

#### 7 Index and Multiplicities

We summarize several relationships among index, algebraic multiplicity, geometric multiplicity, and the dimension of the space of generalized eigenvectors pertaining to a given eigenvalue. The first result is an algebraic proof of Lax[2, page 132], Lemma 10 of Chapter 9.

**Proposition 6** (Geometric and algebraic multiplicities). Let A be an  $n \times n$  matrix over a field  $\mathbb{F}$  and  $\alpha$  an eigenvalue of A. If  $m(\alpha)$  is the multiplicity of  $\alpha$  as a root of the characteristic polynomial  $p_A$  of A, then dim  $N_1(\alpha) \leq m(\alpha)$ .

$$(A - aI)x \in N_{d+1} = N_d.$$

So  $x \in N_{d+1} = N_d$ . Then we work by induction.

<sup>&</sup>lt;sup>1</sup>To see it's impossible to have the scenario where  $N_d = N_{d+1}$  but  $N_d \neq N_l$  for some l > d+1, we note  $\forall x \in N_{d+2}$ ,

 $m(\alpha)$  is called the **algebraic multiplicity** of  $\alpha$  and dim  $N_1(\alpha)$  is called the **geometric multiplicity** of  $\alpha$ . So this result says "geometric multiplicity dim  $N_1(\alpha) \leq$  algebraic multiplicity  $m(\alpha)$ ".

*Proof.* Let  $v_1, \dots, v_s$  be a basis of  $N_1(\alpha)$  and extend it to a basis of  $\mathbb{F}^n$ :  $v_1, \dots, v_s, u_1, \dots, u_r$ . Define  $U = (v_1, \dots, v_s, u_1, \dots, u_r)$ . Then

$$U^{-1}AU = U^{-1}A(v_1, \dots, v_s, u_1, \dots, u_r)$$

$$= U^{-1}(\alpha v_1, \dots, \alpha v_s, Au_1, \dots, Au_r)$$

$$= (\alpha U^{-1}v_1, \dots, \alpha U^{-1}v_s, U^{-1}Au_1, \dots, U^{-1}Au_r).$$

Because 
$$U^{-1}U = I$$
, we must have  $U^{-1}AU = \begin{bmatrix} \alpha I_{s \times s} & B \\ 0 & C \end{bmatrix}$  and  $\det(\lambda I - A) = \det(\lambda I - U^{-1}AU) = \det\begin{bmatrix} (\lambda - \alpha)I_{s \times s} & -B \\ 0 & \lambda I_{(n-s)\times(n-s)} - C \end{bmatrix} = (\lambda - \alpha)^s \det(\lambda I - C)^{-2}$  So  $s \leq m(\alpha)$ .

We continue to use the notation from Proposition 6, and we define  $d(\alpha)$  as the index of  $\alpha$ . Then we have **Proposition 7** (Index and algebraic multiplicity).  $d(\alpha) \leq m(\alpha)$ .

*Proof.* Use the result on minimal polynomial (Theorem 4) or its remark.

Using the notations from Propositions 6 and 7, we have

Proposition 8 (Algebraic multiplicity and the dimension of the space of generalized eigenvectors).  $m(\alpha) = \dim N_{d(\alpha)}(\alpha)$ .

In summary, we have

$$\dim N_1(\alpha), d(\alpha) \le m(\alpha) = \dim N_{d(\alpha)}(\alpha).$$

In words, it becomes

geometric multiplicity of  $\alpha$ , index of  $\alpha$ 

- $\leq$  algebraic multiplicity of  $\alpha$  as a root of the characteristic polynomial
- = dim. of the space of generalized eigenvectors pertaining to  $\alpha$ .

### 8 When Are Two Matrices Similar (and Jordan Canonical Form)

**Theorem 5** (Spectral Theory, part 3: Jordan canonical form). (i) Suppose the pair of matrices A and B are similar,

$$A = SBS^{-1}$$
,

S some invertible matrix. Then A and B have the same eigenvalues:

$$a_1 = b_1, \cdots, a_k = b_k;$$

furthermore, the null spaces  $N_m(a_j) = \ker(A - a_j I)^m$  and  $M_m(a_j) = \ker(B - a_j I)^m$  have for all j and m the same dimension:

$$\dim N_m(a_i) = \dim M_m(a_i). \tag{2}$$

(ii) Conversely, if A and B have the same eigenvalues, and if condition (2) about the nullspaces having the same dimension is satisfied, then A and B are similar.

Proof. Part (i) is obvious. For part (ii), see Lax[2, page 363], Appendix 15.

Corollary 2 (Jordan canonical form). Every  $n \times n$  matrix over complex field is similar to a Jordan canonical form.

<sup>&</sup>lt;sup>2</sup>For the last equality, see, for example, Munkres [1, page 24], Problem 6.

## References

- $[1]\,$  J. Munkres. Analysis on manifolds, Westview Press, 1997.
- [2] P. Lax. Linear algebra and its applications, 2nd Edition, Wiley-Interscience, 2007.