109590004 呂育瑋 作業系統 HW2 hand-written part

4.1: Provide two programming examples in which multithreading does not provide better performance than a single-threaded solution.

多線程適合高密集計算與大量IO操作，因此以下兩種情形並不會比單線程較率還高：

1. 高密集計算、少量IO操作：在計算上相比單線程，需要額外的線程管理與增加上下文切換與同步開銷。
2. 低密集計算、大量IO操作：這時跟CPU性能較無關，而是IO操作速度，而單線程能更好發揮IO操作的異步性能。

4.3: Which of the following components of program state are shared across threads in a multithreaded process?

(a) Register values (b) Heap memory (c) Global variables (d) Stack memory

所有線程都共享：Heap memory, Global variables

各線程單獨持有：Register values, Stack memory

4.4: Can a multithreaded solution using multiple *user*-level threads achieve better performance on a multiprocessor system than on a single-processor system? Explain.

在單一處理器上運行多線程會需要將線程作時間切割來共享CPU資源，增加了上下文切換與線程調度成本，降低了效率。

在多處理器上運行多線程能讓不同線程在不同CPU上同時執行，節省上下文切換與線程之間的等待，有比單一處理器更好的效能表現。

5.2: Discuss how the following pairs of scheduling criteria conflict in certain settings.

(a) CPU utilization and response time

(b) Average turnaround time and maximum waiting time

(c) I/O device utilization and CPU utilization

1. 高CPU利用率代表可以將更多進程調度到CPU上執行，來做大化系統吞吐量，但可能會讓某些進程需等待更長的時間才能被執行，所以在優化CPU利用率同時也要避免響應時間過長。
2. 透過優先調度短進程

5.8: The following processes are being scheduled using a preemptive round-robin scheduling algorithm. Each process is assigned a numerical priority, with a higher number indicating a higher relative priority. In addition to the processes listed below, the system also has an idle task (which consumes no CPU resources and is identified as Pidle). This task has priority 0 and is scheduled whenever the system has no other available processes to run.

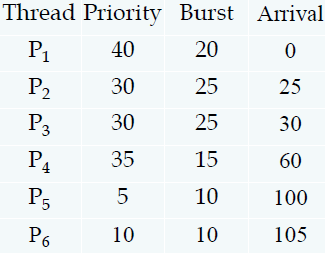
The length of a time quantum is 10 units. If a process is preempted by a higher-priority process, the preempted process is placed at the end of the queue.

(a) Show the scheduling order of the processes using a Gantt chart.

(b) What is the turnaround time for each process?

(c) What is the waiting time for each process?

(d) What is the CPU utilization rate?



Sdadw

5.14: Consider a preemptive priority scheduling algorithm based on dynamically changing priorities.

•Larger priority numbers imply higher priority

•When a process is waiting for the CPU (in the ready queue, but not running), its priority changes at a rate α

•When it is running, its priority changes at a rate β

•All processes are given a priority of 0 when they enter the ready queue

•The parameters α and β can be set to give many different scheduling algorithms

(a) What is the algorithm that results from β > α > 0?

(b) What is the algorithm that results from α < β < 0?

Sdadw

5.15: Explain the differences in how much the following scheduling algorithms discriminate in favor of short processes:

(a) FCFS (b) RR (c) Multilevel feedback queues

Sdadw

6.4: Explain why implementing synchronization primitives by disabling interrupts is not appropriate in a single-processor system if the synchronization primitives are to be used in user-level programs.

Sdadw

6.6: The Linux kernel has a policy that a process cannot hold a spinlock while attempting to acquire a semaphore. Explain why this policy is in place.

Sdadw

6.10: The implementation of mutex locks provided in Section 6.5 suffers from busy waiting.

–Describe what changes would be necessary so that a process waiting to acquire a mutex lock would be blocked and placed into a waiting queue until the lock became available.

Sdadw