Project 4: Learning

Collaboration: Tianqi Yang& Kening Hu& Yunfeng Yu

Goal:

1. Implement a decision tree learning algorithm

2. Implement a multilayer perception

3. Evaluate the two machine learning algorithms.

Algorithm:

Decision Tree

Decision tree is one of most successful machine learning algorithms despite the fact that it's straightforward and simple. Given a training set, the construction of a decision tree firstly picks the most informative feature as a node of the tree. The norms to judge whether the feature is the most useful among all features are always based on how much entropy can be reduced. For example, if we can split the whole dataset into several groups according to the feature's values, and all examples in each group belong to the same class then we can say the feature is the most informative. After selecting the most informative feature, examples in dataset are grouped according to the value of the feature of each example. The construction then is run on each sub-dataset recursively until meeting some terminal conditions.

function DECISION-TREE-LEARNING(examples, attributes, parent examples) returns a tree if examples is empty then return PLURALITY-VALUE(parent examples) else if all examples have the same classification then return the classification

```
else if attributes is empty then return PLURALITY-VALUE(examples)
       else
               A \leftarrow argmaxa \in attributes\ Information\_Gain(a, examples)
               tree \leftarrow a new decision tree with root test A
               for each value vk of A do
                      exs \leftarrow \{e : e \in examples \ and \ e.A = vk\}
                      subtree \leftarrow DECISION\text{-}TREE\text{-}LEARNING(exs, attributes} - A, examples)
                      add a branch to tree with label (A = vk) and subtree subtree
       return tree
function PLURALITY-VALUE(examples) returns a classification
       class_distribution = number of each class / total number of examples;
       class = class_distribution[random a float]
       return class
function Information_Gain(a, examples) returns a float number
       result = 0.0
       for each value_k in a.values:
               result += -P(value_k)*log(P(value_k))
       return result;
```

Neural Network

The neural network consists of input layer, hidden layer and output layer. The number of layers and the number of neurons are set before training the model. The weights between layers are usually randomly generated, and then via loss function weights are changed to minimize the loss via backward propagation. The backward propagation are described as follows:

function BACK-PROP-LEARNING(examples, network) returns a neural network inputs: examples, a set of examples, each with input vector x and output vector y network, a multilayer network with x layers, weights x activation function y local variables: x a vector of errors, indexed by network node

repeat

for each weight $w_{i,j}$ in network do

 $w_{i,j} \leftarrow a \text{ small random number}$

for each example (x, y) in examples do

/* Propagate the inputs forward to compute the outputs */ for each node i in the input layer do

$$ai \leftarrow xi$$

for l = 2 to L do

for each node j in layer l do

$$in_j \leftarrow_i w_{i,j} a_i$$

$$a_i \leftarrow g(in_i)$$

/* Propagate deltas backward from output layer to input layer */

for each node j in the output layer do

$$\Delta[j] \leftarrow g'(in_j) \times (y_j - a_j)$$

for
$$l = L - 1$$
 to 1 do

for each node i in layer l do

$$\Delta[i] \leftarrow g'(in_i)_i w_{i,j} \Delta[j]$$

/* Update every weight in network using deltas */

for each weight $w_{i,j}$ in network do

$$w_{i,j} \leftarrow w_{i,j} + \alpha \times a_i \times \Delta[j]$$

until some stopping criterion is satisfied

return network

Evaluation and Analysis

We have run the two models on two datasets, namely "iris.data.txt" and "scale1.data.txt".

Decision tree

At first attempt we divided 80% data as training set and the left 20% as test set, without shuffling the examples. The decision tree is as following:

```
{ name: 3 value: ['S', 'ML', 'MS', 'L'] }
{ name: Iris-setosa value: [] }{ name: 2 value: ['S', 'ML', 'MS', 'L'] }{ name: Iris-versicolor value: [] }{ name: Iris-virginica value: [] }{ name: Iris-versicolor value: [] }{ name: Iris
```

The first node of the tree is attribute_3, whose choice has 'S', 'ML', 'MS', 'L'. If the the attribute equals 'S' then the example will go to the left node whose classification is Irissetosa. But if the attribute of an example equals 'ML' then it will go to the second node to continue its classification. Until an example touches a leaf node, the classification will assign a label to it.

When run on the second dataset, the tree look like following:

```
{ name: 2 value: [1, 2, 3, 4, 5] }
{ name: 1 value: [1, 2, 3, 4, 5] }{ name: 1 value: [1, 2, 3, 4, 5] }{ name: 3 value: [1, 2, 3, 4, 5] }{ name: 3 value: [1, 2, 3, 4, 5] }
```

{ name: 3 value: [1, 2, 3, 4, 5] } { name: 0 value: [1, 2, 3, 4] } { name: 0 value: [1, 2, 3, 4] } { name: 3 value: [1, 2, 3, 4, 5] } { name: 3 value: [1, 2, 3, 4, 5] } { name: 3 value: [1, 2, 3, 4, 5] } { name: 3 value: [1, 2, 3, 4, 5] } { name: 1 value: [1, 2

A masser of values: [1, 2, 3, 4] M names: 0 values: [1, 2, 3, 4, 5] M names: 0 values: [1, 2, 3, 4] M names: 0 values: [1, 2,

Came: 1 value: [] X, name: 0 value: [] M name: 2 value: [] M name:

And the classification of the two test sets are as followings:

[Clris-virginica'], [Tris-virginica'], [Tris-virgin

We can see that the first node is attribute_2 with 5 distinct values and when choosing value 1 or 2 the classification will see attribute_1 and otherwise it will see attribute_3. The whole process is almost the same as that of the first dataset.

However, the method of splitting data is unreasonable for the reason that the proportion of the three classes in the training set is imbalanced and the distribution of three classes in the test set is extremely unbalanced. Therefore, we split the training set and test set according to the original class distribution to train a model with more accuracy. Besides, the result of one split is obviously biased and inaccuracy and thus we looped the split for 10 times and compute the average accuracy and precision. The results of the decision trees on the two datasets are as followings:

```
the accuracy_score: 0.6648936170212766 the avarage_precision_score_score: 0.4505186993283247

the accuracy_score: 0.6861702127659575 the avarage_precision_score_score: 0.4617685996325894

the accuracy_score: 0.68681698227872 the avarage_precision_score_score: 0.46147685936325894

the accuracy_score: 0.6868516038297872 the avarage_precision_score_score: 0.461272855456491

the accuracy_score: 0.6276595744680851018 the avarage_precision_score_score: 0.4412266659663128

the accuracy_score: 0.6276699746808510818 the avarage_precision_score_score: 0.4412266659663128

the accuracy_score: 0.6648936170212766 the avarage_precision_score_score: 0.4412266659663128

the accuracy_score: 0.6648936170212766

the accuracy_score: 0.66593744608051083 the avarage_precision_score_score: 0.4481245449280824

the accuracy_score: 0.6595744608051083 the avarage_precision_score_score: 0.4485828963118086

the accuracy_score: 0.659574460851063 the avarage_precision_score_score: 0.469873623127405

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the accuracy_score: 0.66697876321611584, 1: 0.0797872340425532, 2: 0.6675767767345098)

after 10 times, the average_precision_score_ore is 0.455746677609331 the average_precision_score_score: 0.4699873623127405

the precision_score of each class: (0: 0.699876321611584, 1: 0.0797872340425532, 2: 0.608776770345098)

after 10 times, the average_precision_score_score: 0.469873623127405

the precision_score of each class: (0: 0.699876321611584, 1: 0.0797872340425532, 2: 0.60878776345098)

after 10 times, the average_precision_score_score: 0.469873623127405

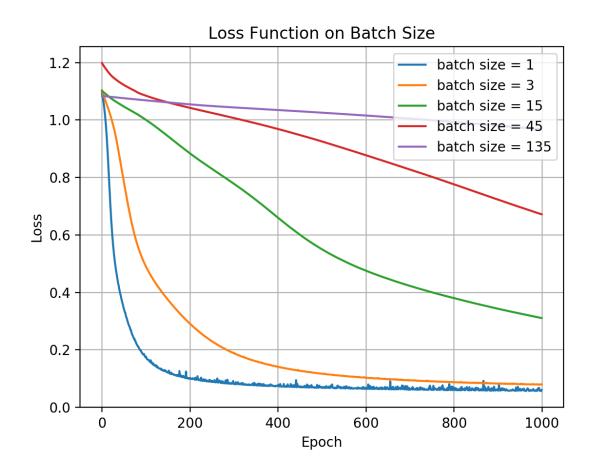
the precision_score of each class: (0: 0.699876321611584, 1: 0.0797872340425532, 2: 0.608776770345098)

after 10 times, the average_precision_score_score: 0.469
```

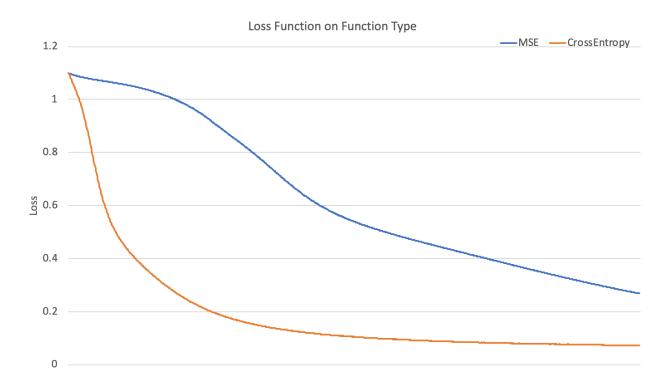
Obviously we can clearly see each label's precision score and the average accuracy. For the first dataset, the performance of the trained decision tree is relatively good because the average precision score is nearly 80% and the average accuracy score nearly 85%. However, when run on the second dataset the decision tree can only achieve 67% on accuracy and 45% on precision score. One of the most significant reason is that the distribution of classes in the second dataset is imbalanced. When looking at label 1, the precision score in each iteration is only about 8% and in fact the proportion of label 1 in the original dataset is far less than 30%.

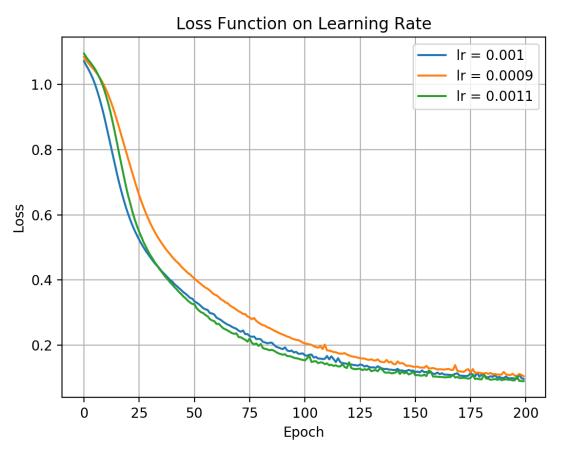
Neural Network

When other functions and parameters are fixed, we can see that the more less the batch is, the less loss the model can get. The line chart is described as below:



The relationships between loss and function type and between loss and learning rate are described as below:





models\accuracy	accuracy on iris	accuracy on scale1
Decision Tree	0.78	0.45
Neural Network	0.98	0.87

We can see that no matter on which dataset, the accuracy of neural network always performs better than decision tree does.