Gauss-Manin connections for arrangements: Cosmology

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Abstract

We study the Gauss-Manin connection for an arrangement of real hyperplanes in the cohomology of a complex rank-1 local system. Typically, we work on a special type of hyperplane arrangement related to cosmology.

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1 Conventions

The aim is to investigate the twisted integral:

$$\int_{\Delta \otimes U_{\Delta}} U \cdot \varphi \tag{1.1}$$

with:

$$\varphi \in \Omega^n \left(\mathbb{C}^n \backslash \mathcal{D} \right), U(u) = \prod_{j=1}^m P_j(u)^{\alpha_j}, P_j(u) \in \mathbb{R}[u_1, \cdots, u_n]$$
 (1.2)

The key object is intersection number, the pairing between $\varphi_L \in H^n\left(\mathbb{C}^n \setminus \mathcal{D}, \mathcal{L}_{\omega}^{\vee}\right)$ and $\varphi_R \in H^n\left(\mathbb{C}^n \setminus \mathcal{D}, \mathcal{L}_{\omega}\right)$:

$$\langle \varphi_L | \varphi_R \rangle_{\omega} := \int_{\mathbb{C}^n \setminus \mathcal{D}} \text{Reg}[\varphi_L \mod (\mathbb{C} \cdot (-\omega))] \wedge (\varphi_R \mod (\mathbb{C} \cdot \omega))$$
 (1.3)

The above integration can be performed via residue theory:

$$\int_{\mathbb{C}^n \setminus \mathcal{D}} \operatorname{Reg}[\varphi \langle J \rangle] \wedge \varphi \langle K \rangle = \frac{\delta(J; K)}{\prod_{i=1}^n \alpha_{j_i}}$$
(1.4)

with:

$$\varphi\langle J\rangle := \mathrm{d}\log P_{j_1} \wedge \cdots \wedge \mathrm{d}\log P_{j_n}, J = \{j_1, \cdots, j_n\}$$
(1.5)

In practice, mod $(\mathbb{C} \cdot \omega)$ seems to have something to do with the basis choice of $H^n(\mathbb{C}^n \setminus \mathcal{D}, \mathcal{L}_\omega)$.

We want to compute the Gauss-Manin connection A:

$$d\int_{\Delta \otimes U_{\Delta}} U \cdot \vec{\varphi} = \mathbf{A} \wedge \int_{\Delta \otimes U_{\Delta}} U \cdot \vec{\varphi}$$
(1.6)

with $\vec{\phi}$ to be vector of all basis in $H^n(\mathbb{C}^n \setminus \mathcal{D}, \mathcal{L}_{\omega})$.

It is given directly via the intersection number:

$$\mathbf{A} = \langle \vec{\varphi} | (\mathbf{d} + \mathbf{d} \log U \wedge) \vec{\varphi} \rangle \times \langle \vec{\varphi} | \vec{\varphi} \rangle^{-1}$$
(1.7)

with

2 Basis choice 1: bounded chambers

The basis for $H^n(\mathbb{C}^n \setminus \mathcal{D}, \mathcal{L}_{\omega})$ can be associated to the independent (twisted) cycles via isomorphism:

$$H^{n}\left(\mathbb{C}^{n}\backslash\mathcal{D},\mathcal{L}_{\omega}\right)\cong H_{n}^{lf}\left(\mathbb{C}^{n}\backslash\mathcal{D},\mathcal{L}_{\omega}\right)\cong\bigoplus_{\nu}\mathbb{C}\cdot\left[\Delta_{\nu}\otimes U_{\Delta_{\nu}}\right]$$
(2.1)

Explicitly, for a n-simplex Δ , denoted as $[\tilde{J}] = [j_0, \dots, j_n]$, the associated logarithmic n-form, named as canonical form, is:

$$\varphi\left[\tilde{J}\right] := d\log\left(\frac{P_{j_0}}{P_{j_1}}\right) \wedge \dots \wedge d\log\left(\frac{P_{j_{n-1}}}{P_{j_n}}\right) \tag{2.2}$$

Note that for general position in hyperplanes, the number of bounded chambers is:

$$\dim H^n\left(\mathbb{C}^n \backslash \mathcal{D}, \mathcal{L}_{\omega}\right) = \binom{m-1}{n} \tag{2.3}$$

It is stated that for the intersection number between such n-forms, we can the φ $[\tilde{J}] \mod (\mathbb{C} \cdot \omega)$ is taken as simply φ $[\tilde{J}]$ itself.

Empirically, $(\mathsf{d} + \mathsf{d} \log U \wedge) \varphi\left[\tilde{\mathit{J}}\right] \mod (\mathbb{C} \cdot \omega)$ is also taken as simply $(\mathsf{d} + \mathsf{d} \log U \wedge) \varphi\left[\tilde{\mathit{J}}\right]$ itself.

Example 2.1 $_2F_1(a,b;c|x)$ hypergeometric function

The twisted integral is:

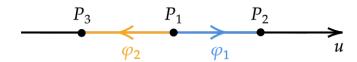
$$\int_{0}^{\infty} \underbrace{P_{1}^{b} P_{2}^{c-b} P_{3}^{-a}}_{U} \underbrace{\frac{\mathrm{d}u}{P_{1} P_{2}}}_{\varphi} \tag{2.4}$$

with P_i to be:

$$P_1 = u, P_2 = 1 - u, P_3 = 1 - xu (2.5)$$

The φ part is:

$$\varphi = \varphi[1,2] = \varphi\langle 1 \rangle - \varphi\langle 2 \rangle \tag{2.6}$$



Notice that there are two independent cycles $\Delta_1 = [1,2], \Delta_2 = [1,3]$. The canonical forms associated to each cycle are:

$$\varphi_1 = \varphi[1,2] = \varphi\langle 1 \rangle - \varphi\langle 2 \rangle
\varphi_2 = \varphi[1,3] = \varphi\langle 1 \rangle - \varphi\langle 3 \rangle$$
(2.7)

First compute $\langle \vec{\varphi} | \vec{\varphi} \rangle$. Simply apply the formula in Eq.(1.4):

$$\langle \varphi[1,2]|\varphi[1,2]\rangle = \langle \varphi\langle 1\rangle|\varphi\langle 1\rangle\rangle + \langle \varphi\langle 2\rangle|\varphi\langle 2\rangle\rangle = \frac{1}{b} + \frac{1}{c-b}$$

$$\langle \varphi[1,2]|\varphi[1,3]\rangle = \langle \varphi\langle 1\rangle|\varphi\langle 1\rangle\rangle = \frac{1}{b}$$
(2.8)

Similarly, we work out the rest to obtain $\langle \vec{\varphi} | \vec{\varphi} \rangle$:

$$\langle \vec{\varphi} | \vec{\varphi} \rangle = \begin{pmatrix} \frac{1}{b} + \frac{1}{c-b} & \frac{1}{b} \\ \frac{1}{b} & \frac{1}{b} - \frac{1}{a} \end{pmatrix} \tag{2.9}$$

Then we compute $(d + d \log U \wedge) \vec{\varphi}$ and reorganize them as linear combination of $\varphi(J)$, with $d = \partial_x dx$:

$$(d + d \log U \wedge) \varphi_1 = \frac{a}{x-1} (\varphi \langle 2 \rangle - \varphi \langle 3 \rangle) (d + d \log U \wedge) \varphi_2 = \frac{c-b}{x-1} \varphi \langle 2 \rangle + \frac{a-c+(b-a)x}{x(x-1)} \varphi \langle 3 \rangle$$
 (2.10)

Likewise, we compute the intersection number $\langle \vec{\varphi} | (d + d \log U \wedge) \vec{\varphi} \rangle$. Finally, the Gauss-Manin connection **A** is:

$$\mathbf{A} = \langle \vec{\varphi} | (\mathbf{d} + \mathbf{d} \log U \wedge) \vec{\varphi} \rangle \times \langle \vec{\varphi} | \vec{\varphi} \rangle^{-1} = \begin{pmatrix} -\frac{a}{x-1} & \frac{a}{x-1} \\ \frac{b-c}{x-1} - \frac{b-c}{x} & -\frac{b-c}{x-1} - \frac{c}{x} \end{pmatrix} dx$$
 (2.11)

Example 2.2 4-point conformal correlation function in FRW cosmology

The twisted integral is:

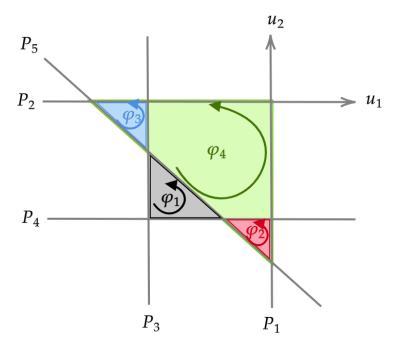
$$\int_0^\infty \underbrace{P_1^{\epsilon} P_2^{\epsilon} P_3^{\gamma} P_4^{\gamma} P_5^{\gamma}}_{U} \underbrace{\frac{\mathrm{d}u_1 \wedge \mathrm{d}u_2}{P_3 P_4 P_5}}_{\varphi} \tag{2.12}$$

with P_i to be:

$$P_1 = u_1, P_2 = u_2, P_3 = u_1 + X_1 + 1, P_4 = u_2 + X_2 + 1, P_5 = u_1 + u_2 + X_1 + X_2$$
 (2.13)

The φ part is:

$$\varphi = \varphi[3,4,5] = \varphi(3,4) - \varphi(3,5) + \varphi(4,5) \tag{2.14}$$



There are four independent cycles: $\Delta_1 = [3,4,5], \Delta_2 = [1,4,5], \Delta_3 = [2,3,5], \Delta_4 = [1,2,5]$. Likewise, we obtain the 4 canonical forms associated to each cycle, denoted as $\varphi_{1,\dots,4}$.

Following the same procedure as above, we can derive the Gauss-Manin connection. Here we just present the results:

$$\langle \vec{\varphi} | \vec{\varphi} \rangle = \begin{pmatrix} \frac{3}{\gamma^2} & \frac{1}{\gamma^2} & -\frac{1}{\gamma^2} & 0\\ \frac{1}{\gamma^2} & \frac{2\gamma + \epsilon}{\gamma^2 \epsilon} & 0 & \frac{1}{\gamma \epsilon} \\ -\frac{1}{\gamma^2} & 0 & \frac{2\gamma + \epsilon}{\gamma^2 \epsilon} & -\frac{1}{\gamma \epsilon} \\ 0 & \frac{1}{\gamma \epsilon} & -\frac{1}{\gamma \epsilon} & \frac{\gamma + 2\epsilon}{\gamma \epsilon^2} \end{pmatrix}$$
(2.15)

$$\mathbf{A}_{X_{1}} \mid_{\gamma \to 0} = \epsilon \begin{pmatrix} \frac{1}{X_{1}+1} & \frac{1}{X_{1}-1} - \frac{1}{X_{1}+1} & 0 & 0\\ 0 & \frac{1}{X_{1}-1} & 0 & \frac{1}{X_{1}+X_{2}}\\ 0 & 0 & \frac{1}{X_{1}+1} & \frac{1}{X_{1}+1} - \frac{1}{X_{1}+X_{2}}\\ 0 & 0 & 0 & \frac{2}{X_{1}+X_{2}} \end{pmatrix} dX_{1}$$
 (2.16)

with $d = \underbrace{\partial_{X_1} dX_1}_{d_{X_1}} + \underbrace{\partial_{X_2} dX_2}_{d_{X_2}}$. Likewise, we compute $\mathbf{A}_{X_2} \mid_{\gamma \to 0}$.

The Gauss-Manin connection $\mathbf{A} = \mathbf{A}_{X_1} + \mathbf{A}_{X_2}$:

$$\mathbf{A}\mid_{\gamma\to 0} = \epsilon \begin{pmatrix} \operatorname{d}\log((X_1+1)(X_2+1)) & \operatorname{d}\log\left(\frac{X_1-1}{X_1+1}\right) & \operatorname{d}\log\left(\frac{X_1-1}{X_2+1}\right) & 0 \\ 0 & \operatorname{d}\log((X_1-1)(X_2+1)) & 0 & \operatorname{d}\log\left(\frac{X_1+X_2}{X_2+1}\right) \\ 0 & 0 & \operatorname{d}\log((X_1+1)(X_2-1)) & \operatorname{d}\log\left(\frac{X_1+1}{X_1+X_2}\right) \\ 0 & 0 & 0 & 2\operatorname{d}\log(X_1+X_2) \end{pmatrix}$$

3 Basis choice 2: $\varphi\langle J\rangle$

Note that we have the isomorphism:

$$H^{n}(\log \mathcal{D}, \nabla_{\omega}) \cong H^{n}(\Omega^{\bullet}(*\mathcal{D}), \nabla_{\omega}) \cong H^{n}(\mathbb{C}^{n} \backslash \mathcal{D}, \mathcal{L}_{\omega})$$
(3.1)

which suggests that we can simply use $\varphi(I)$ as basis.

For general position in hyperplanes, we can just pick m-1 hyperplanes, then collect all $\varphi(J)$ with J to be indices: $1 \le j_1 < \cdots < j_n \le m-1$.

And then mod $(\pm \mathbb{C} \cdot \omega)$ means that for a $\varphi(K)$ that involves the m-th hyperplane $P_m(u)$, we need to replace it with $\varphi(J)$, via the relations:

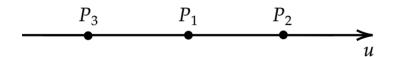
$$0 = \omega \wedge \varphi(\overline{J}), \forall \overline{J} = \{j_1, \dots, j_{n-1}\} \text{ s.t. } 1 \leqslant j_1 < \dots < j_{n-1} \leqslant m-1$$
(3.2)

For special position in hyperplanes, we take extra procedure:

- If some hyperplanes are parallel to each other $P_i \parallel P_j$, we just set $\varphi(J) = 0, \forall J \ s.t. \ i, j \in J$.
- For multi-intersection, i.e. $P_{i_1} \cap \cdots \cap P_{i_k} \neq \emptyset$ with k > n, we add the relation $\varphi[i_{j_0}, \dots, i_{j_n}] = 0$ to further eliminate some certain $\varphi(J)$, where $j_0, \dots, j_n \in I \equiv \{i_1, \dots, i_k\}$.

Example 3.1 Revisit: ${}_{2}F_{1}(a,b;c|x)$ hypergeometric function

We come back to the twisted integral in Example 2.1, which is an example for general position in hyperplanes.



First pick the 2 hyperplanes P_1 , P_2 , thus all relevant $\varphi(J)$ are $\{\varphi(1), \varphi(2)\}$. Hence, the basis choice is:

$$\vec{\varphi} = \begin{pmatrix} \varphi \langle 1 \rangle \\ \varphi \langle 2 \rangle \end{pmatrix} \tag{3.3}$$

Obviously, the matrix $\langle \vec{\varphi} | \vec{\varphi} \rangle$ is diagonal:

$$\langle \vec{\varphi} | \vec{\varphi} \rangle = \begin{pmatrix} \frac{1}{b} & 0\\ 0 & \frac{1}{-b+c} \end{pmatrix} \tag{3.4}$$

Then for $\varphi(3)$, we use the relation $0 = \omega \wedge 1 = \omega$ to replace it with $\varphi(1)$, $\varphi(2)$:

$$\varphi\langle 3\rangle = \frac{b}{a}\varphi\langle 1\rangle - \frac{b-c}{a}\varphi\langle 2\rangle \tag{3.5}$$

Thus, when computing $\langle \vec{\varphi} | (d + d \log U \wedge) \vec{\varphi} \rangle$, we need to first eliminate all $\varphi(3)$ as mod $(\pm \mathbb{C} \cdot \omega)$, e.g.:

$$(d + d \log U \wedge) \varphi_1 = -\frac{a}{x} \varphi \langle 3 \rangle \to -\frac{b}{x} \varphi \langle 1 \rangle + \frac{b - c}{x} \varphi \langle 2 \rangle \tag{3.6}$$

Thus,

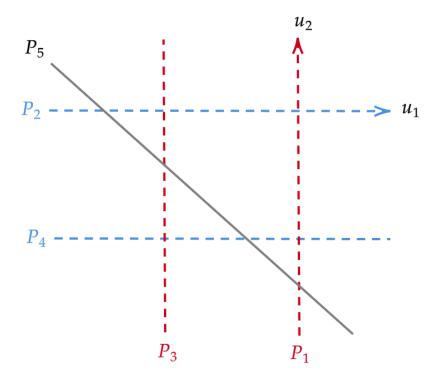
$$\langle \varphi_1 | (d + d \log U \wedge) \varphi_1 \rangle = -\frac{b}{x} \langle \varphi \langle 1 \rangle | \varphi \langle 1 \rangle \rangle = -\frac{1}{x}$$
(3.7)

Repeat the same procedure as $_2F_1$ hypergeometric function, we derive the Gauss-Manin connection:

$$\mathbf{A} = \begin{pmatrix} -\frac{b}{x} & \frac{b-c}{x} \\ \frac{b}{x-1} - \frac{b}{x} & -\frac{a+b-c}{x-1} + \frac{b-c}{x} \end{pmatrix} dx \tag{3.8}$$

Example 3.2 Revisit: 4-point conformal correlation function in FRW cosmology

We now come to the twisted integral in Example 2.2, which involves parallel hyperplanes.



We first find all $\binom{5}{2}$ many $\varphi\langle J\rangle$, and eliminate the ones that involves parallel hyperplanes $\varphi\langle 1,3\rangle$, $\varphi\langle 2,4\rangle$:

$$\{\varphi\langle 1,2\rangle, \varphi\langle 1,4\rangle, \varphi\langle 1,5\rangle, \varphi\langle 2,3\rangle, \varphi\langle 2,5\rangle, \varphi\langle 3,4\rangle, \varphi\langle 3,5\rangle, \varphi\langle 4,5\rangle\}$$
(3.9)

Note that the above 8 $\varphi(J)$ just correspond to the 8 intersection points.

Then we do the mod $(\pm \mathbb{C} \cdot \omega)$ part. Via the relation $0 = \omega \wedge \varphi \langle i \rangle$, $i = 1, \cdots$, 5, we can eliminate $4 \varphi \langle J \rangle$:

$$\begin{cases} \varphi\langle 1,5\rangle = -\frac{\epsilon}{\gamma}\varphi\langle 1,2\rangle - \varphi\langle 1,4\rangle \\ \varphi\langle 2,5\rangle = \frac{\epsilon}{\gamma}\varphi\langle 1,2\rangle - \varphi\langle 2,3\rangle \\ \varphi\langle 3,5\rangle = \frac{\epsilon}{\gamma}\varphi\langle 2,3\rangle - \varphi\langle 3,4\rangle \\ \varphi\langle 4,5\rangle = \frac{\epsilon}{\gamma}\varphi\langle 1,4\rangle + \varphi\langle 3,4\rangle \end{cases}$$
(3.10)

Hence, the basis choice is:

$$\vec{\varphi} = \begin{pmatrix} \varphi\langle 1, 2 \rangle \\ \varphi\langle 1, 4 \rangle \\ \varphi\langle 2, 3 \rangle \\ \varphi\langle 3, 4 \rangle \end{pmatrix} \tag{3.11}$$

The diagonal matrix $\langle \vec{\varphi} | \vec{\varphi} \rangle$ is:

$$\langle \vec{\varphi} | \vec{\varphi} \rangle = \begin{pmatrix} \frac{1}{\epsilon^2} & 0 & 0 & 0\\ 0 & \frac{1}{\gamma \epsilon} & 0 & 0\\ 0 & 0 & \frac{1}{\gamma \epsilon} & 0\\ 0 & 0 & 0 & \frac{1}{\gamma^2} \end{pmatrix}$$
(3.12)

Again, we need to substitute the $\{\varphi(2,5), \varphi(3,4), \varphi(3,5), \varphi(4,5)\}$ for mod $(\pm \mathbb{C} \cdot \omega)$, e.g.:

$$(d + d \log U \wedge) \varphi_{1} = \left(\frac{\gamma}{X_{1}+1} + \frac{\gamma}{X_{1}+X_{2}}\right) \varphi\langle 1, 2 \rangle - \frac{\gamma}{X_{1}+X_{2}} \varphi\langle 1, 5 \rangle + \frac{\gamma}{X_{1}+1} \varphi\langle 2, 3 \rangle + \frac{\gamma}{X_{1}+X_{2}} \varphi\langle 2, 5 \rangle$$

$$\rightarrow \left(\frac{\gamma}{X_{1}+1} + \frac{\gamma}{X_{1}+X_{2}} + \frac{\epsilon}{X_{1}+X_{2}}\right) \varphi\langle 1, 2 \rangle - \frac{\gamma}{X_{1}+X_{2}} \varphi\langle 1, 5 \rangle + \left(\frac{\gamma}{X_{1}+1} - \frac{\gamma}{X_{1}+X_{2}}\right) \varphi\langle 2, 3 \rangle$$

$$(3.13)$$

Thus, we have:

$$\langle \varphi_{1} | (d + d \log U \wedge) \varphi_{1} \rangle = \left(\frac{\gamma}{X_{1} + 1} + \frac{\gamma}{X_{1} + X_{2}} + \frac{\epsilon}{X_{1} + X_{2}} \right) \langle \varphi \langle 1, 2 \rangle | \varphi \langle 1, 2 \rangle \rangle$$

$$= \frac{1}{\epsilon^{2}} \left(\frac{\gamma}{X_{1} + 1} + \frac{\gamma}{X_{1} + X_{2}} + \frac{\epsilon}{X_{1} + X_{2}} \right)$$
(3.14)

After similar computation, we obtain:

$$\mathbf{A}_{X_1}|_{\gamma \to 0} = \epsilon \begin{pmatrix} \frac{2}{X_1 + X_2} & 0 & 0 & 0\\ \frac{1}{X_1 - 1} & \frac{1}{X_1 - 1} & 0 & 0\\ \frac{1}{X_1 + 1} & 0 & \frac{1}{X_1 + 1} & 0\\ 0 & -\frac{1}{X_1 + 1} & 0 & \frac{1}{X_1 + 1} \end{pmatrix} dX_1$$
(3.15)

Example 3.3 $_3F_2(a_1, a_2, a_3; b_1, b_2|x)$ hypergeometric function