

第九章 正弦稳态电路的分析

主要内容:

1、阻抗、导纳的概念

2、电路的相量图

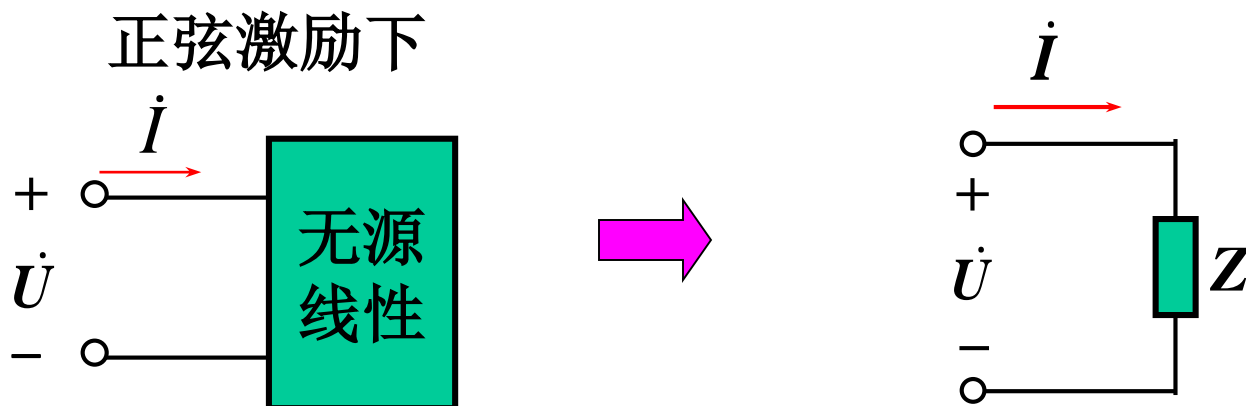
3、用相量法分析正弦稳态电路

4、正弦稳态电路中的功率分析

§ 9-1 阻抗和导纳

一、阻抗

1. 阻抗的定义



$$Z \stackrel{\text{def}}{=} \frac{\dot{U}}{\dot{I}} = \frac{U \angle \varphi_u}{I \angle \varphi_i} = \frac{U}{I} \angle \varphi_u - \varphi_i = |Z| \angle \varphi_Z$$

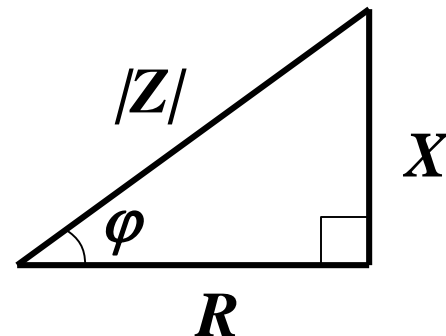
阻抗模 $|Z| = \frac{U}{I}$

阻抗角 $\varphi_Z = \varphi_u - \varphi_i$

2. 阻抗的代数形式

阻抗 $Z = \frac{\dot{U}}{\dot{I}} = |Z| \angle \varphi_Z = R + jX$

$$\begin{cases} R = \operatorname{Re}[Z] = |Z| \cos \varphi_Z & \text{电阻} \\ X = \operatorname{Im}[Z] = |Z| \sin \varphi_Z & \text{电抗} \end{cases}$$



阻抗三角形

$$|Z| = \sqrt{R^2 + X^2}, \quad \varphi_Z = \arctan\left(\frac{X}{R}\right)$$

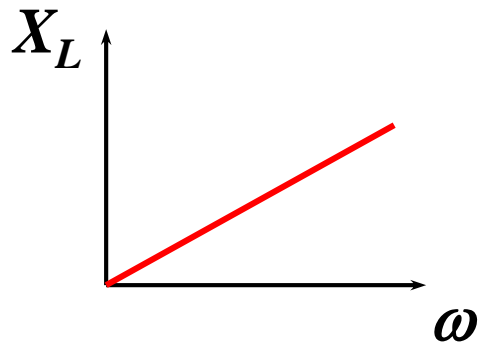
若一端口 N_0 仅含单个元件

$$\begin{cases} R: & Z_R = R \\ L: & Z_L = j\omega L & \text{感抗} \\ C: & Z_C = \frac{1}{j\omega C} = -j\frac{1}{\omega C} & \text{容抗} \end{cases}$$

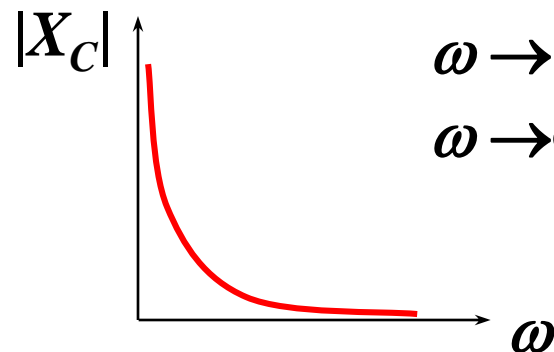
阻抗的物理意义:

(1) 表示限制电流的能力;

(2) 感抗: ωL 和频率成正比, $\omega \rightarrow 0$ 短路, $\omega \rightarrow \infty$ 开路;



(3) 容抗: $-1/\omega C$, 其绝对值和频率成反比,

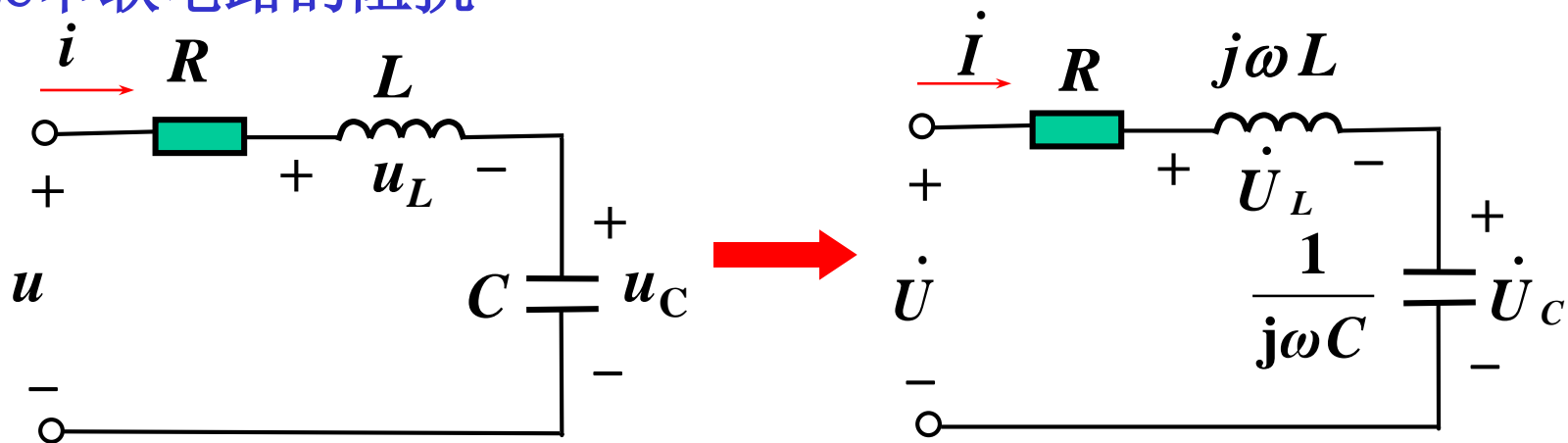


$\omega \rightarrow 0$, $|X_C| \rightarrow \infty$ 直流开路(隔直)

$\omega \rightarrow \infty$, $|X_C| \rightarrow 0$ 高频短路(旁路作用)

(4) 由于电抗的存在, 使电流、电压的相位不同, 存在相位差。

3. RLC串联电路的阻抗



由KVL: $\dot{U} = \dot{U}_R + \dot{U}_L + \dot{U}_C = R\dot{I} + j\omega L\dot{I} - j\frac{1}{\omega C}\dot{I}$

$$= (R + j\omega L - j\frac{1}{\omega C})\dot{I}$$

$$Z = \frac{\dot{U}}{\dot{I}} = R + j\omega L + \frac{1}{j\omega C} = R + j(\omega L - \frac{1}{\omega C})$$

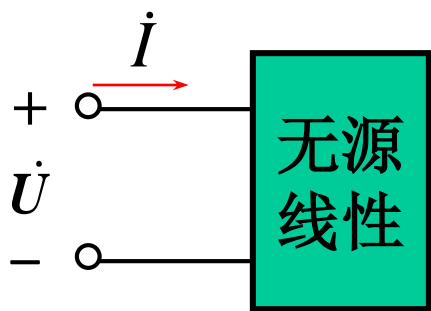
$$= R + jX = |Z| \angle \varphi_Z$$

电抗 $X = X_L - X_C = \omega L - \frac{1}{\omega C}$

电抗

$$X = X_L - X_C = \omega L - \frac{1}{\omega C}$$

- 1. $X > 0$, $\omega L > \frac{1}{\omega C}$, $\varphi_Z > 0$, Z 呈感性, 电压超前电流
- 2. $X < 0$, $\omega L < \frac{1}{\omega C}$, $\varphi_Z < 0$, Z 呈容性, 电压滞后电流
- 3. $X = 0$, $\omega L = \frac{1}{\omega C}$, $\varphi = 0$, Z 呈电阻性, 电压、电流同相



$$Z = \frac{\dot{U}}{\dot{I}}$$

$$Z(j\omega) = R(\omega) + jX(\omega)$$

电阻分量

电抗分量

二、导纳

1. 导纳的定义

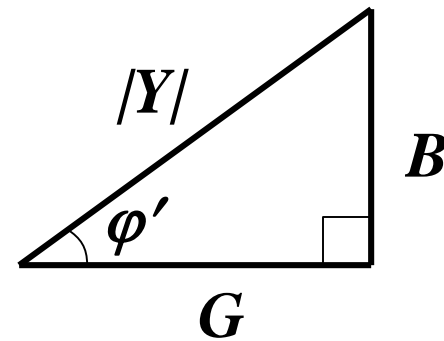
$$Y = \frac{1}{Z} = \frac{\dot{I}}{\dot{U}} = \frac{I}{U} \angle \varphi_i - \varphi_u = |Y| \angle \varphi_y$$

导纳模 $|Y| = \frac{I}{U}$ 导纳角 $\varphi_y = \varphi_i - \varphi_u$

2. 导纳的代数形式

$$Y = \frac{1}{Z} = |Y| \angle \varphi_y = G + jB$$

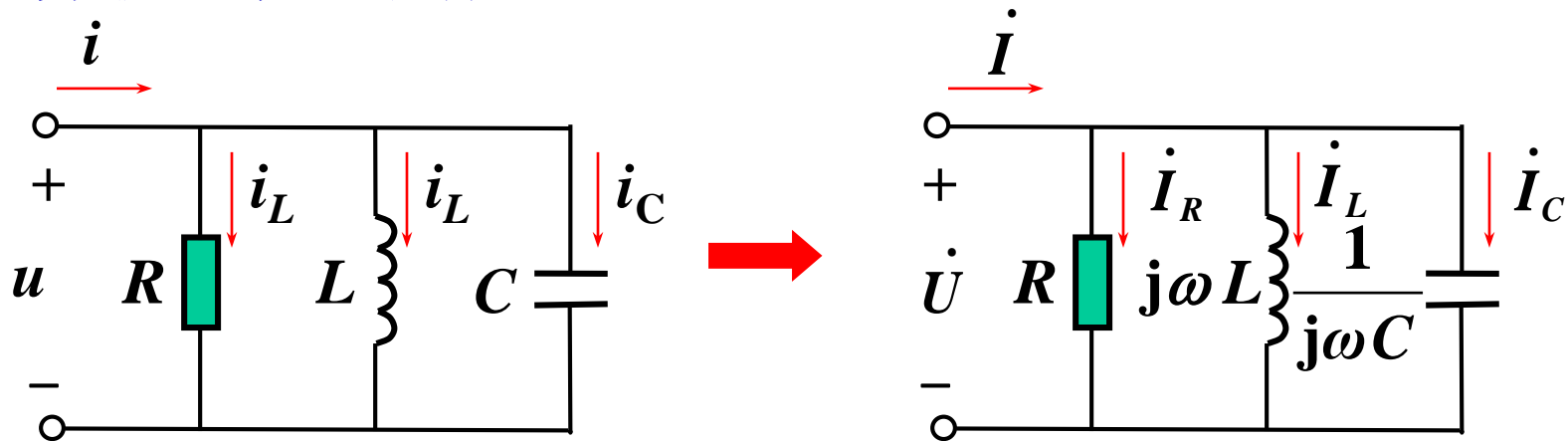
$$\begin{cases} G = \operatorname{Re}[Y] = |Y| \cos \varphi_y & \text{电导} \\ B = \operatorname{Im}[Y] = |Y| \sin \varphi_y & \text{电纳} \end{cases}$$



$$|Y| = \sqrt{G^2 + B^2}, \quad \varphi_y = \arctan\left(\frac{B}{G}\right)$$

导纳三角形

3. RLC并联电路的导纳



由KCL: $\dot{I} = \dot{I}_R + \dot{I}_L + \dot{I}_C = G\dot{U} - j\frac{1}{\omega L}\dot{U} + j\omega C\dot{U}$

$$= (G - j\frac{1}{\omega L} + j\omega C)\dot{U}$$

$$Y = \frac{\dot{I}}{\dot{U}} = \frac{1}{R} + \frac{1}{j\omega L} + j\omega C = \frac{1}{R} + j\left(\omega C - \frac{1}{\omega L}\right)$$

$$= G + jB = |Y|\angle\varphi_y$$

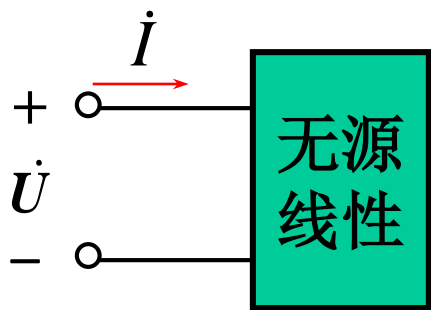
电纳

$$B = \omega C - \frac{1}{\omega L} = B_C - B_L$$

电纳

$$B = \omega C - \frac{1}{\omega L} = B_C - B_L$$

- 1. $B > 0$, $\omega C > \frac{1}{\omega L}$, $\varphi_y > 0$, Y 呈容性, 电流超前电压
- 2. $B < 0$, $\omega C < \frac{1}{\omega L}$, $\varphi_y < 0$, Y 呈感性, 电流滞后电压
- 3. $B = 0$, $\omega C = \frac{1}{\omega L}$, $\varphi_y = 0$, Y 呈电阻性, 电压电流同相



$$Y = \frac{1}{Z} = \frac{\dot{I}}{\dot{U}}$$

$$Y(j\omega) = G(\omega) + jB(\omega)$$

电导分量

电纳分量

三、阻抗和导纳的关系

$$\therefore \quad Y = \frac{1}{Z}$$

$$\therefore Z(j\omega)Y(j\omega) = 1$$

$$|Z(j\omega)||Y(j\omega)| = 1 \quad , \quad \varphi_Z + \varphi_Y = 0$$

注意：

N_0 含有受控源时，可有 $\operatorname{Re}[Z(j\omega)] < 0$ ，或 $|\varphi_Z| > 90^\circ$ 情况

四、阻抗和导纳的串并联

1、n个阻抗串联：

$$Z_{eq} = Z_1 + Z_2 + \cdots + Z_n = \sum_{k=1}^n Z_k$$

$$\dot{U}_k = \frac{Z_k}{Z_{eq}} \dot{U} \quad , \quad k = 1, 2, 3, \cdots, n$$

2、n个导纳并联：

$$Y_{eq} = Y_1 + Y_2 + \cdots + Y_n = \sum_{k=1}^n Y_k$$

$$\dot{I}_k = \frac{Y_k}{Y_{eq}} \dot{I} \quad , \quad k = 1, 2, 3, \cdots, n$$

3、两个阻抗的串联和两个导纳的并联：

① 两个阻抗的串联：

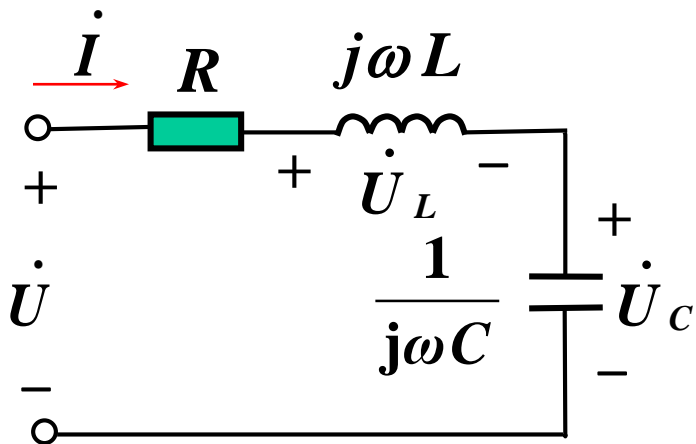
$$Z = Z_1 + Z_2, \dot{U}_1 = \frac{Z_1}{Z} \dot{U}, \dot{U}_2 = \frac{Z_2}{Z} \dot{U}$$

② 两个导纳的并联：

$$Y = Y_1 + Y_2, \dot{I}_1 = \frac{Y_1}{Y} \dot{I}, \dot{I}_2 = \frac{Y_2}{Y} \dot{I}$$

$$Z = \frac{Z_1 Z_2}{Z_1 + Z_2}, \dot{I}_1 = \frac{Z_2}{Z_1 + Z_2} \dot{I}, \dot{I}_2 = \frac{Z_1}{Z_1 + Z_2} \dot{I}$$

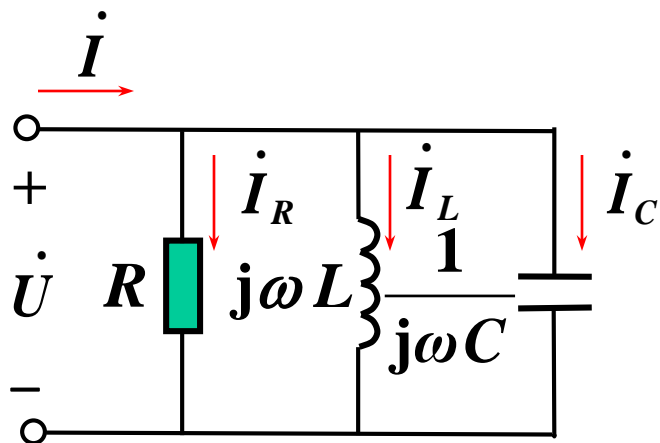
例9-1： 图示RLC串联电路，求其阻抗。



$$\begin{aligned} Z &= R + j\omega L + \frac{1}{j\omega C} \\ &= R + j\left(\omega L - \frac{1}{\omega C}\right) \\ &= R + jX \end{aligned}$$

$$Y = \frac{R}{R^2 + X^2} - j \frac{X}{R^2 + X^2}$$

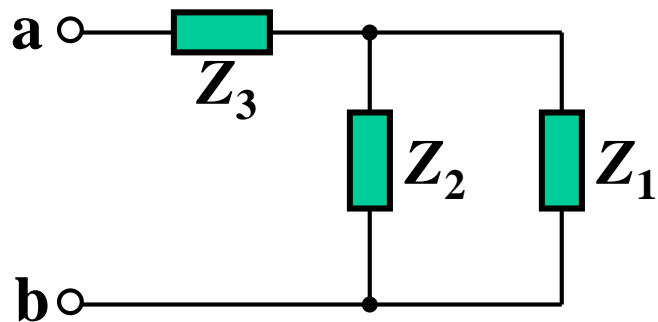
例9-2： 图示RLC并联电路，求其导纳。



$$\begin{aligned} Y &= G + \frac{1}{j\omega L} + j\omega C \\ &= G + j\left(\omega C - \frac{1}{\omega L}\right) \\ &= G + jB \end{aligned}$$

$$Z = \frac{G}{G^2 + B^2} - j \frac{B}{G^2 + B^2}$$

例9-3: 已知 $Z_1=10+j6.28\Omega$, $Z_2=20-j31.9\Omega$, $Z_3=15+j15.7\Omega$ 。
求 Z_{ab} 。



解:

$$Z_{ab} = Z_3 + Z_1 \parallel Z_2 = Z_3 + \frac{Z_1 Z_2}{Z_1 + Z_2}$$

$$= 15 + j15.7 + \frac{(10 + j6.28)(20 - j31.9)}{10 + j6.28 + 20 - j31.9}$$

$$= 15 + j15.7 + \frac{11.81 \angle 32.13^\circ \times 37.65 \angle -57.91^\circ}{39.45 \angle -40.5^\circ}$$

$$= 15 + j15.7 + 11.27 \angle 14.72^\circ$$

$$= 15 + j15.7 + 10.9 + j2.86$$

$$= 25.9 + j18.56 = 31.86 \angle 35.6^\circ \Omega$$

```
In[5]:= ArcTan[6.28 / 10] * 180 / Pi
```

```
Out[5]= 32.1288
```

```
In[6]:= ArcTan[-31.9 / 20] * 180 / Pi
```

```
Out[6]= -57.914
```

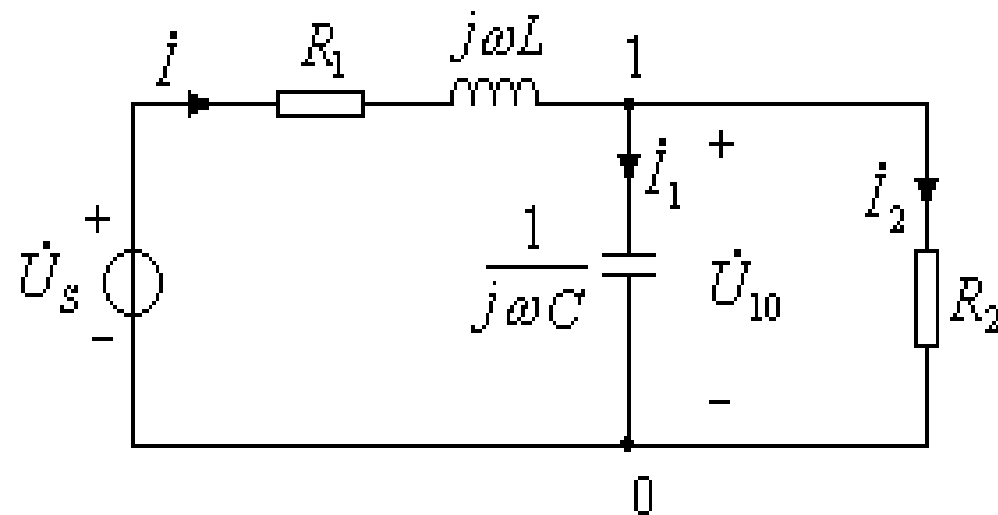
```
In[8]:= 32.13 - 57.91 - (-40.5)
```

```
Out[8]= 14.72
```

例9-4: 图示电路中, $\omega = 314 \text{ rad/s}$,

$$R_1 = 10\Omega, \quad L = 0.5H, \quad R_2 = 1000\Omega, \quad C = 10\mu F, \quad U_s = 100V$$

求各支路电流和电压。



解: $\dot{U}_s = 100 \angle 0^\circ,$

$$Z_{R1} = 10 \Omega, \quad Z_{R2} = 1000 \Omega,$$

$$Z_L = j\omega L = j157 \Omega, \quad Z_C = -j\frac{1}{\omega C} = -j318.47 \Omega$$

$$Z_{10} = Z_{R2} // Z_C = 303.45 \angle -72.33^\circ = (92.11 - j289.13) \Omega$$

$$Z_{eq} = Z_{10} + Z_{R1} + Z_L = (102.11 - j132.13) \Omega = 166.99 \angle -52.30^\circ \Omega$$

$$\therefore \dot{I} = \frac{\dot{U}}{Z_{eq}} = 0.60 \angle 52.30^\circ \text{ A} \quad \dot{U}_{10} = Z_{10} \dot{I} = 182.07 \angle -20.03^\circ \text{ V}$$

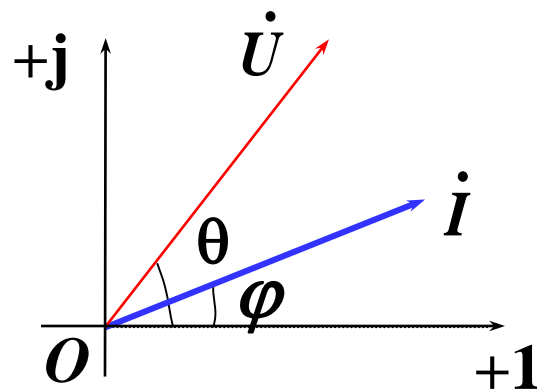
$$\dot{I}_1 = \frac{\dot{U}_{10}}{Z_C} = 0.57 \angle 69.97^\circ \text{ A} \quad \dot{I}_2 = \frac{\dot{U}_{10}}{R_2} = 0.18 \angle -20.03^\circ \text{ A}$$

§ 9-3

电路的相量图

相量图

相量和复数一样可以在平面上用向量表示



电路的相量图

反映电路的KCL、KVL和电压、电流相位关系的相量图.

§ 9-4 正弦稳态电路的分析

电阻电路与正弦稳态电路相量法分析比较：

电阻电路：

$$\left\{ \begin{array}{l} \text{KCL: } \sum i = 0 \\ \text{KVL: } \sum u = 0 \\ \text{元件约束关系: } u = Ri \\ \quad \text{或 } i = Gu \end{array} \right.$$

正弦电路相量分析：

$$\left\{ \begin{array}{l} \text{KCL: } \sum \dot{I} = 0 \\ \text{KVL: } \sum \dot{U} = 0 \\ \text{元件约束关系: } \dot{U} = Z \dot{I} \\ \quad \text{或 } \dot{I} = Y \dot{U} \end{array} \right.$$

可见，二者依据的电路定律是相似的。只要作出正弦稳态电路的相量模型，便可将电阻电路的分析方法推广到正弦稳态电路的相量分析中。

一、利用 $\dot{U} = Z \dot{I}$ 或 $\dot{I} = Y \dot{U}$ 求解

1. 同一元件的阻抗与导纳互为倒数，同一对端口之间的阻抗与导纳互为倒数，即

$$Z = \frac{1}{Y}, Y = \frac{1}{Z}$$

2. 记住基本元件的阻抗和导纳

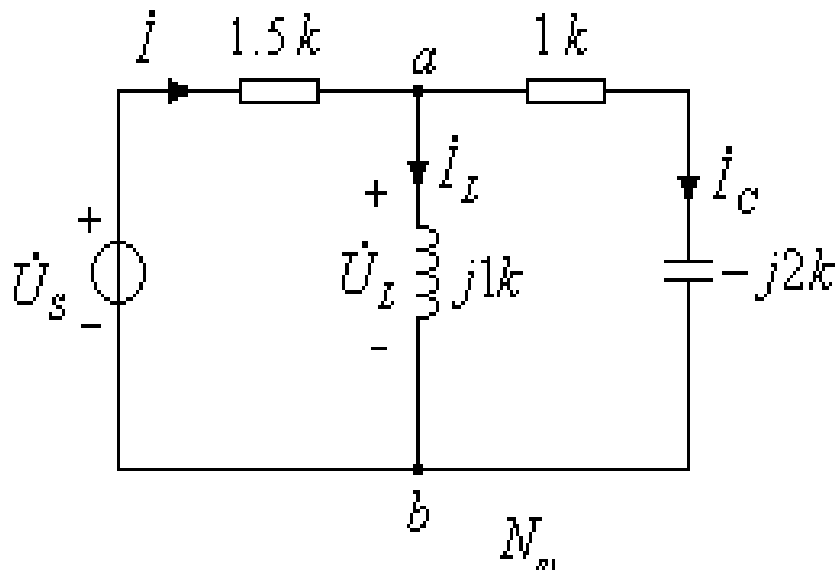
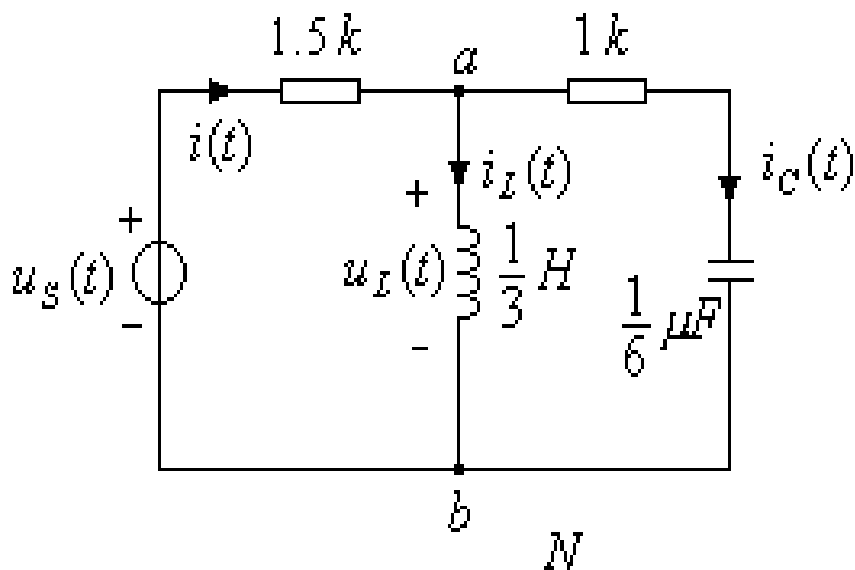
$$Z_R = R, Z_L = j\omega L, Z_C = \frac{1}{j\omega C} = -j\frac{1}{\omega C}$$

3. 串联部分总阻抗和并联部分的总导纳

$$Z = \sum_{k=1}^n Z_k \quad Y = \sum_{k=1}^n Y_k$$

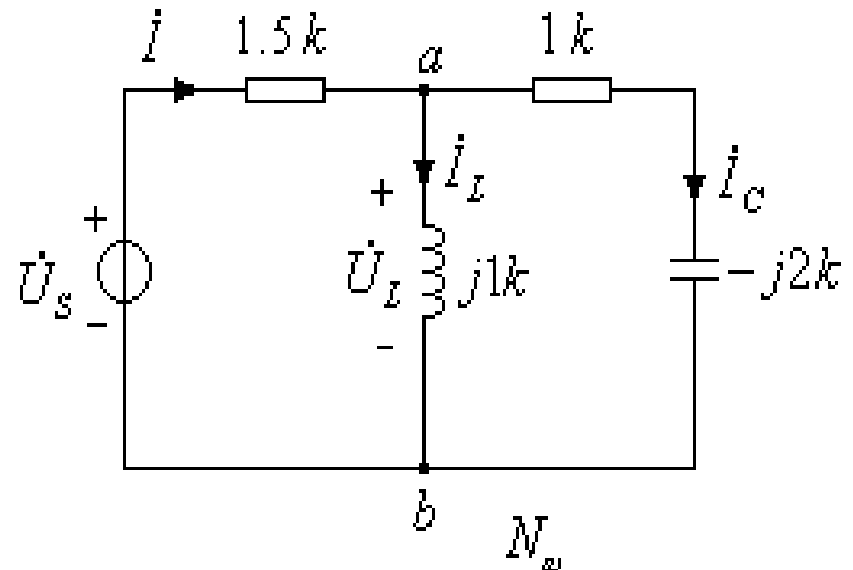
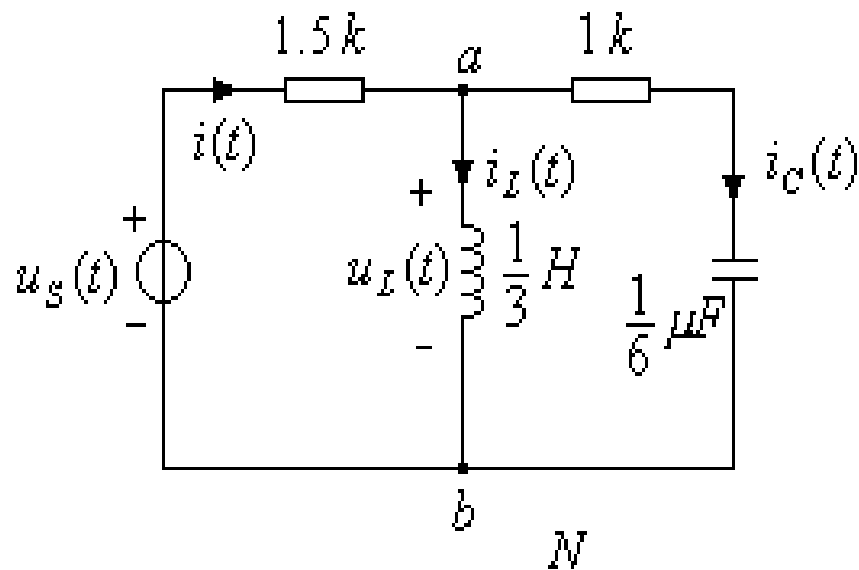
例9-5：电路如下图所示， $U_s = 40\sqrt{2} \cos 3000 t \text{ V}$ ，

求 $i(t)$, $i_C(t)$, $i_L(t)$



解：已知： $\dot{U}_s = 40\angle 0^\circ \text{ V}$

$$Z = 1.5 + Z_{ab} = 1.5 + \frac{(j1)(1 - j2)}{j1 + 1 - j2} = 2 + j1.5 = 2.5\angle 36.9^\circ \text{ k}\Omega$$



$$\dot{I} = \frac{\dot{U}_s}{Z} = \frac{40 \angle 0^\circ}{2.5 \angle 36.9^\circ} = 16 \angle -36.9^\circ \text{ mA}$$

$$\dot{I}_C = \dot{I} \frac{j1}{1 + j1 - j2} = \dot{I} \times \frac{j}{1 - j} = \frac{1}{2}(j - 1)\dot{I} = 11.3 \angle 98.1^\circ \text{ mA}$$

$$\dot{I}_L = \dot{I} \frac{1 - j2}{1 + j1 - j2} = 25.3 \angle -55.3^\circ \text{ mA}$$

$$\dot{I} = 16 \angle -36.9^\circ \text{ mA}$$

$$\dot{I}_C = 11.3 \angle 98.1^\circ \text{ mA}$$

$$\dot{I}_L = 25.3 \angle -55.3^\circ \text{ mA}$$

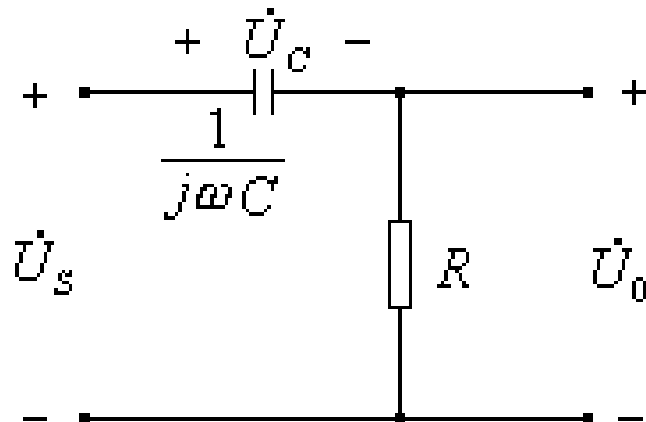
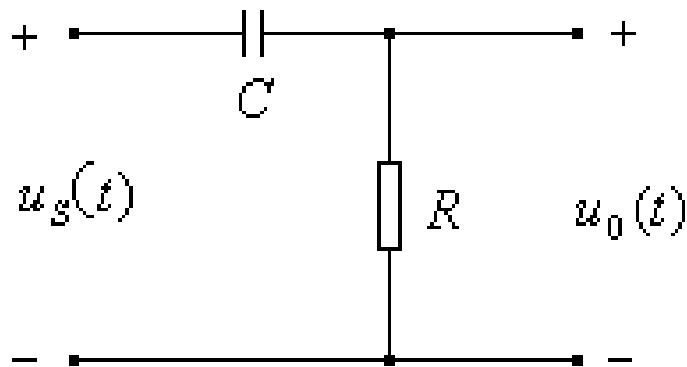
$$\therefore i(t) = 16\sqrt{2} \cos(3000 t - 36.9^\circ) \text{ mA}$$

$$i_C(t) = 11.3\sqrt{2} \cos(3000 t + 98.1^\circ) \text{ mA}$$

$$i_L(t) = 25.3\sqrt{2} \cos(3000 t - 55.3^\circ) \text{ mA}$$

例9-6：电路如下图所示， $u_s = \sqrt{2}U_s \cos \omega t$

求 $u_0(t)$ 对 $u_s(t)$ 的相位关系。



解： $\because \dot{U}_s = U_s \angle 0^\circ \text{ V}$

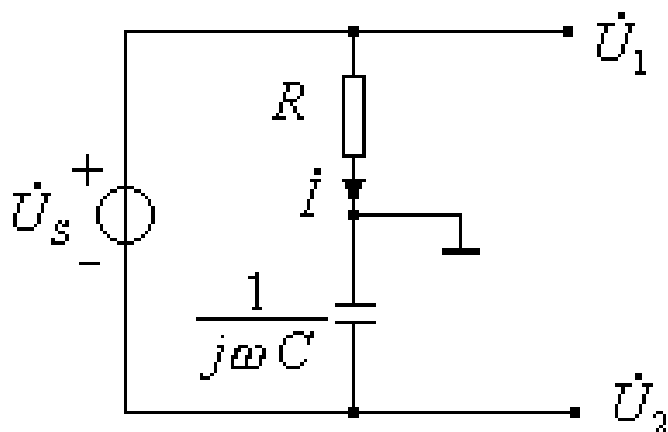
$$\dot{U}_0 = \dot{U}_s \frac{R}{R - j \frac{1}{\omega C}} = \dot{U}_s \frac{R}{\sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2}} \angle \arctan \frac{1}{\omega CR} = U_0 \angle \varphi_0$$

$$\varphi = \varphi_0 - \varphi_s = \arctan \frac{1}{\omega CR} > 0$$

$$\therefore \varphi_0 = \arctan \frac{1}{\omega CR}$$

$$\because \omega \rightarrow \infty \quad \varphi \rightarrow 0; \quad \omega \rightarrow 0 \quad \varphi \rightarrow 90^\circ \quad \therefore 0^\circ < \varphi = \arctan \frac{1}{\omega CR} < 90^\circ$$

例9-7：求下图所示相量模型中 \dot{U}_1 与 \dot{U}_2 的相位关系。



解： 令 $\dot{I} = I \angle \varphi_i$

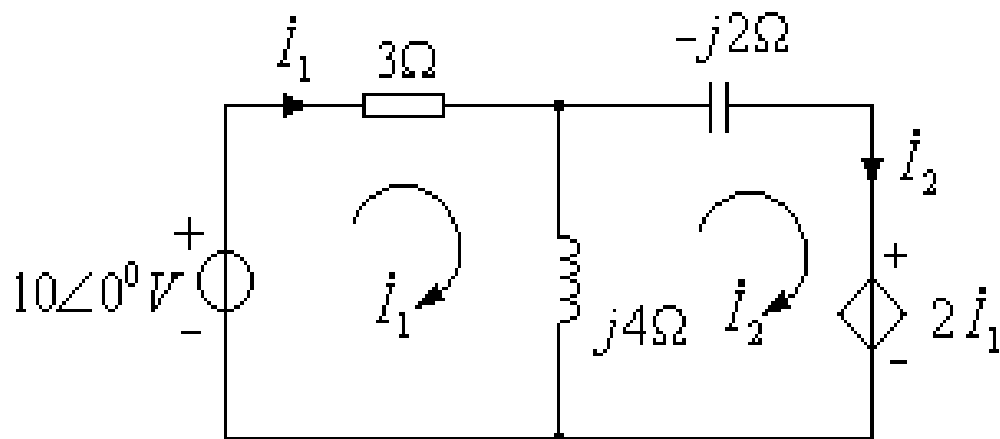
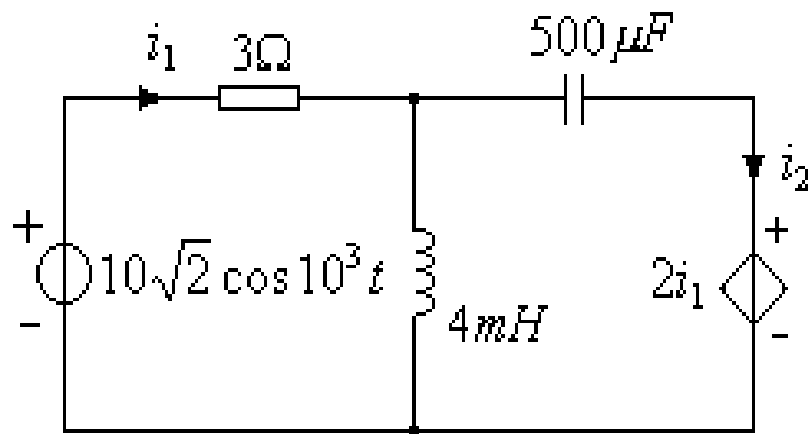
$$\dot{U}_1 = R \dot{I} = R I \angle \varphi_i = U_1 \angle \varphi_i$$

$$\dot{U}_2 = -\left(\frac{1}{j\omega C}\right)\dot{I} = j\frac{1}{\omega C}\dot{I} = \frac{I}{\omega C} \angle \varphi_i + 90^\circ = U_2 \angle \varphi_i + 90^\circ$$

$$\therefore \varphi = \varphi_i + 90^\circ - \varphi_i = 90^\circ$$

二、相量模型的网孔分析法和结点分析法

例9-8：电路如下图所示，求解 $i_1(t)$ 和 $i_2(t)$ 。

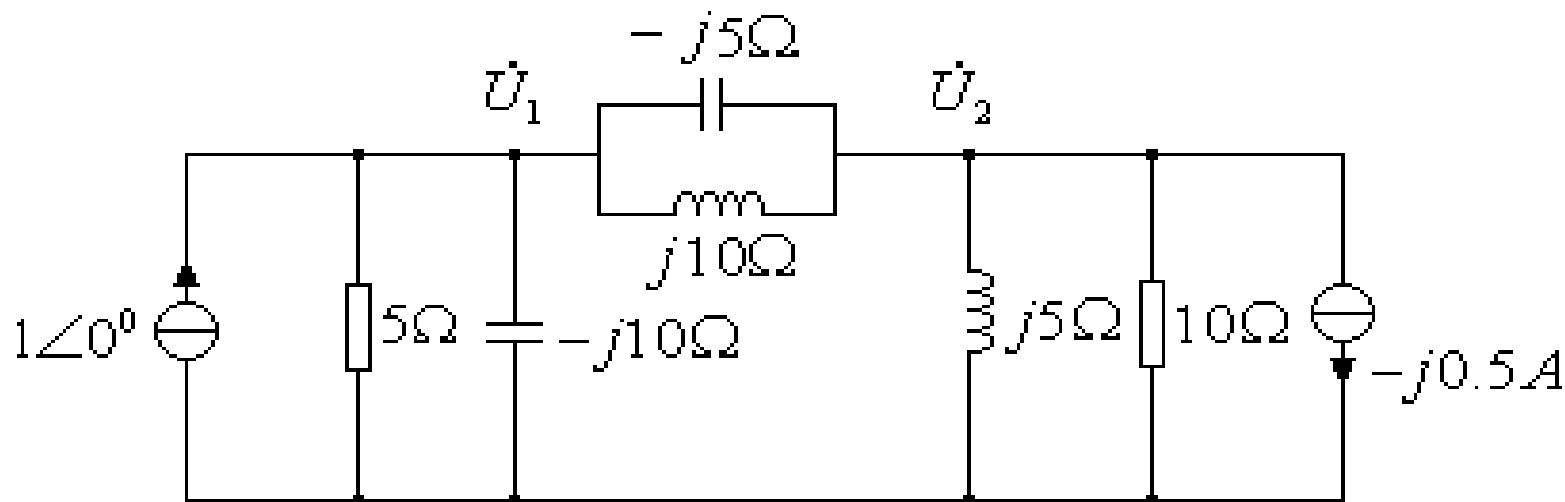


解： $Z_L = j\omega L = j4\Omega$, $Z_C = \frac{1}{j\omega C} = -j2\Omega$

$$\begin{cases} (3 + j4)\dot{I}_1 - j4\dot{I}_2 = 10\angle 0^\circ \\ -j4\dot{I}_1 + (j4 - j2)\dot{I}_2 = -2\dot{I}_1 \end{cases} \quad \therefore \begin{cases} \dot{I}_1 = \frac{10}{7 - j4} = 1.24\angle 29.7^\circ \text{ A} \\ \dot{I}_2 = \frac{20 + j30}{13} = 2.77\angle 56.3^\circ \text{ A} \end{cases}$$

$$\begin{cases} i_1(t) = 1.24\sqrt{2}\cos(10^3 t + 29.7^\circ) \text{ A} \\ i_2(t) = 2.77\sqrt{2}\cos(10^3 t + 56.3^\circ) \text{ A} \end{cases}$$

例9-9：电路相量模型如下图所示，试列出结点电压相量方程。



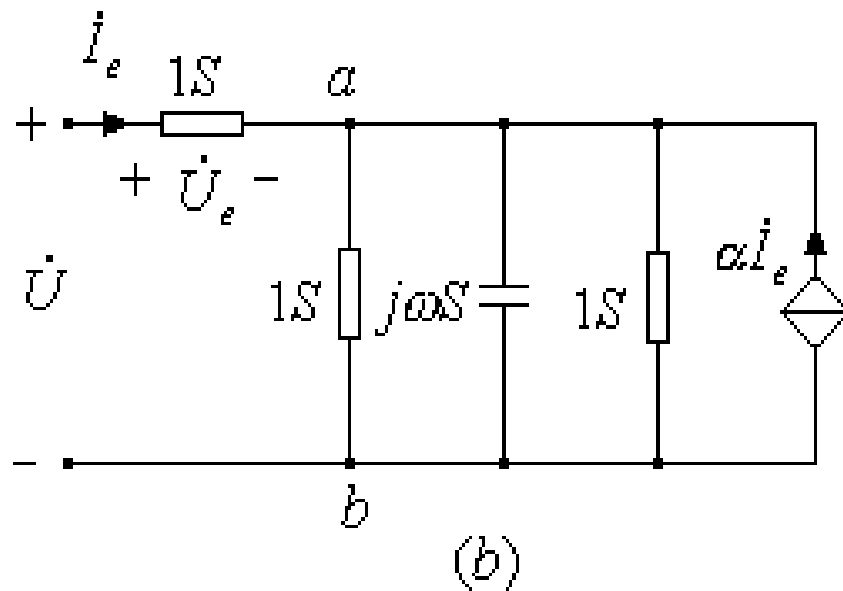
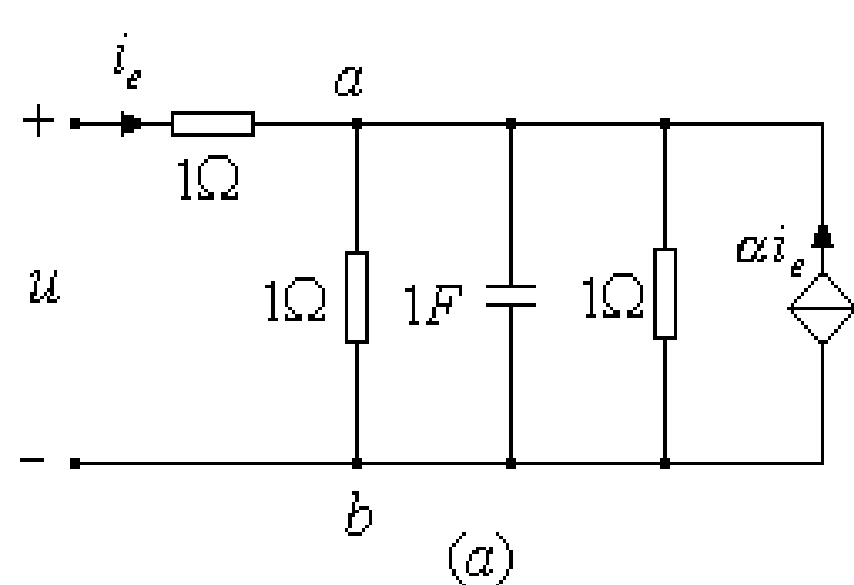
解：

$$\left(\frac{1}{5} + \frac{1}{-j10} + \frac{1}{j10} + \frac{1}{-j5}\right)\dot{U}_1 - \left(\frac{1}{-j5} + \frac{1}{j10}\right)\dot{U}_2 = 1\angle 0^\circ$$

$$-\left(\frac{1}{-j5} + \frac{1}{j10}\right)\dot{U}_1 + \left(\frac{1}{10} + \frac{1}{j5} + \frac{1}{j10} + \frac{1}{-j5}\right)\dot{U}_2 = -(-j0.5)$$

$$\therefore \begin{cases} (0.2 + j0.2)\dot{U}_1 - j0.1\dot{U}_2 = 1\angle 0^\circ \\ -j0.1\dot{U}_1 + (0.1 - j0.1)\dot{U}_2 = j0.5 \end{cases} \Rightarrow \begin{cases} 2(1 + j)\dot{U}_1 - j\dot{U}_2 = 10 \\ -j\dot{U}_1 + (1 - j)\dot{U}_2 = j5 \end{cases}$$

例9-10：单口网络如下图所示，试求输入阻抗及输入导纳。

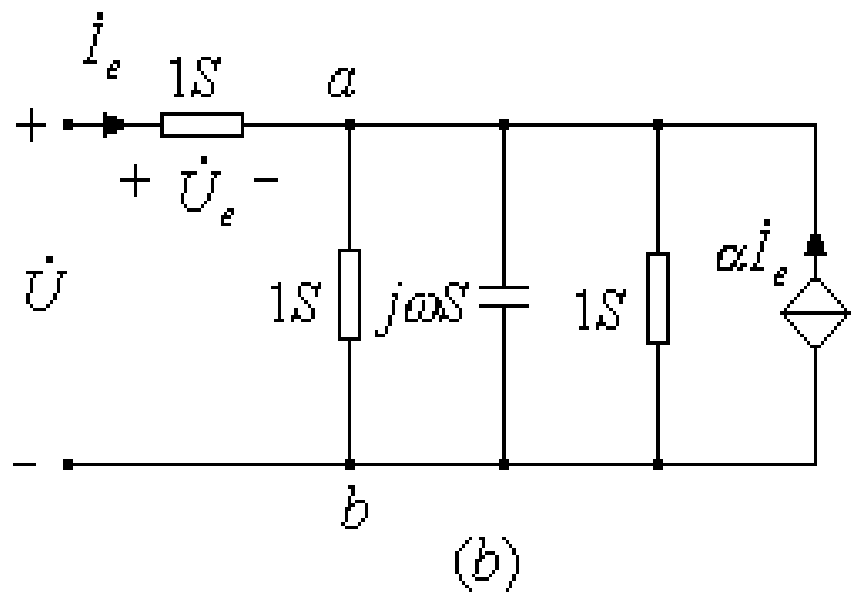
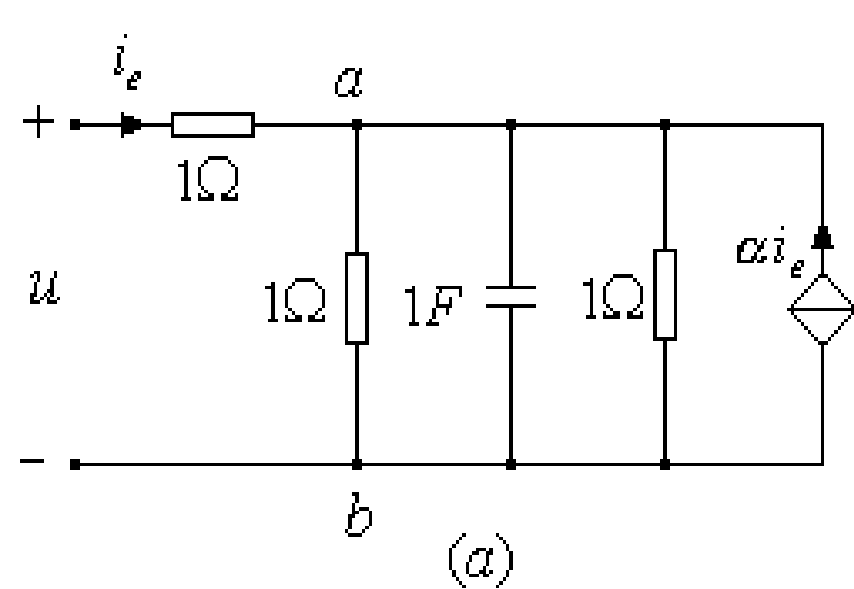


解：
$$\begin{cases} (3 + j\omega)\dot{U}_a = \dot{U} + \alpha \dot{I}_e \\ \dot{U} - \dot{U}_a = \dot{I}_e \end{cases}$$

$$\Rightarrow [(3 + j\omega) - 1]\dot{U} = [3 + j\omega + \alpha]\dot{I}_e$$

$$\therefore Z = \frac{\dot{U}}{\dot{I}_e} = \frac{3 + \alpha + j\omega}{2 + j\omega} \Omega$$

$$Y = \frac{1}{Z} = \frac{2 + j\omega}{3 + \alpha + j\omega} = \frac{6 + 2\alpha + \omega^2}{(3 + \alpha)^2 + \omega^2} + j \frac{(1 + \alpha)\omega}{(3 + \alpha)^2 + \omega^2}$$



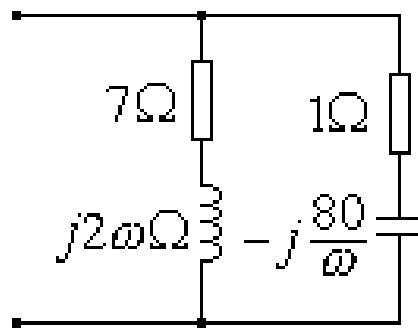
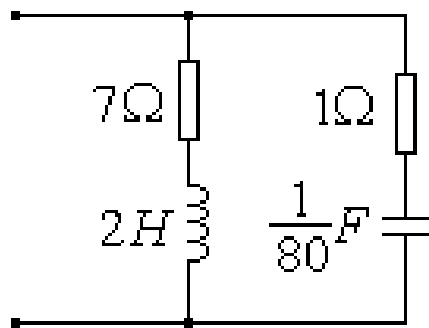
设 $\dot{I}_e = 1\text{ A}$ $\dot{U}_e = 1\text{ V}$

$$\dot{U} = \dot{U}_e + \frac{(1+\alpha)}{2+j\omega} \dot{I}_e \qquad \dot{U} = 1 + \frac{1+\alpha}{2+j\omega} = \frac{3+\alpha+j\omega}{2+j\omega}$$

$$\therefore Z = \frac{\dot{U}}{\dot{I}_e} = \frac{3+\alpha+j\omega}{2+j\omega} = \frac{6+2\alpha+\omega^2}{4+\omega^2} - j\frac{(1+\alpha)\omega}{4+\omega^2}$$

三、运用戴维南定理及诺顿定理求解

例9-11: 单口网络及相量模型如下图所示，试求在 $\omega = 4 \text{ rad/s}$ 的等效相量模型和 $\omega = 10 \text{ rad/s}$ 的等效相量模型。



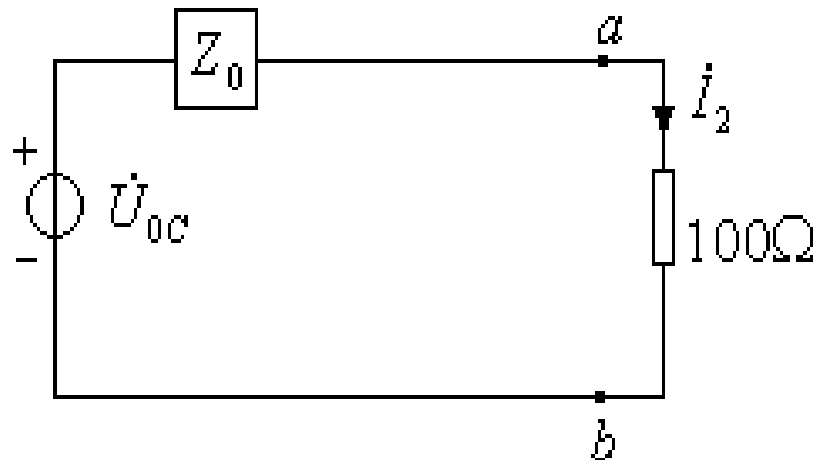
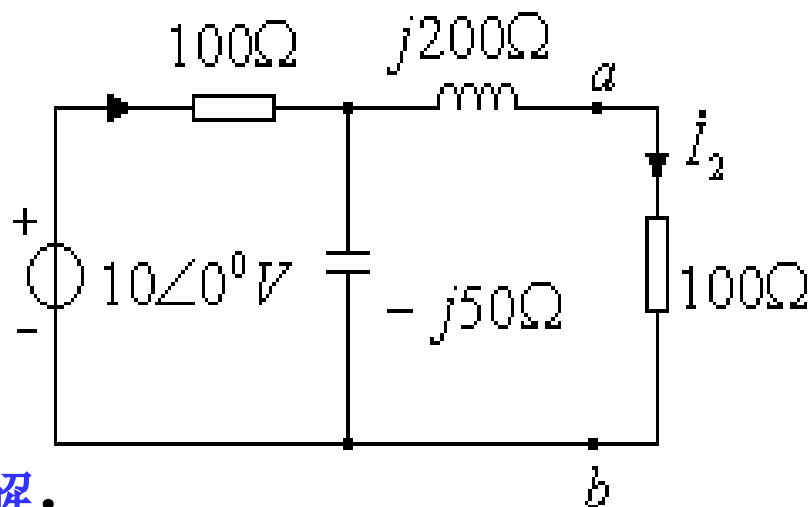
解: $\omega = 4 \text{ rad/s}$

$$Z(j4) = (7 + j8) // (1 - j20) = (14.04 + j4.56) \Omega$$

$\omega = 10 \text{ rad/s}$

$$Z(j10) = (7 + j20) // (1 - j8) = (4.35 - j11.02) \Omega$$

例9-12 用戴维南定理求下图所示相量模型中的电流相量 \dot{I}_2 。



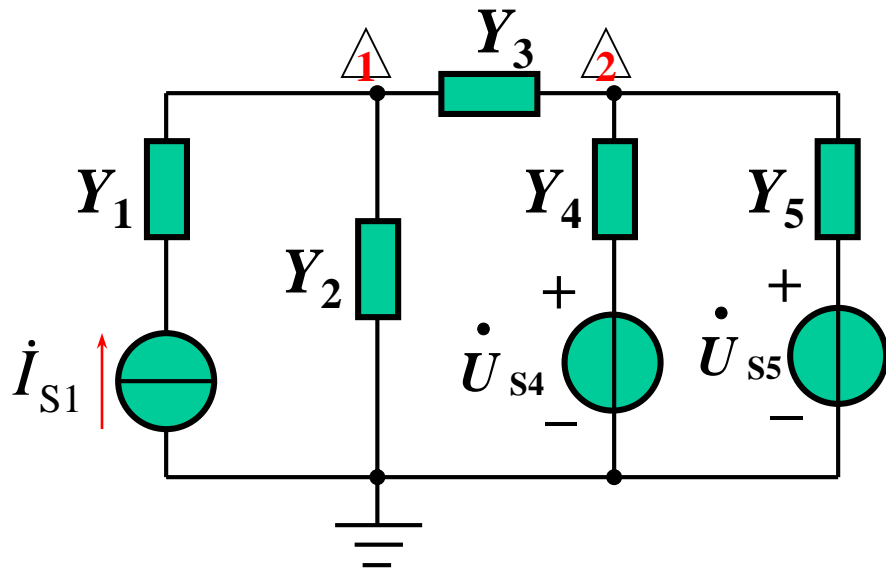
解:

$$\dot{U}_{0C} : \dot{U}_{0C(ab)} = 10\angle 0^\circ \times \frac{-j50}{100 - j50} = 10 \times \frac{-j}{2 - j} = 4.47\angle -63.4^\circ \text{ V}$$

$$Z_0 : Z_0 = j200 + 100 // (-j50) = j200 + \frac{-j100}{2 - j} = 20 + j160 \text{ } \Omega$$

$$\dot{I}_2 : \dot{I}_2 = \frac{\dot{U}_{0C}}{Z_0 + 100} = \frac{4.47\angle -63.4^\circ}{20 + j160 + 100} = 0.0224\angle -116.53^\circ \text{ A}$$

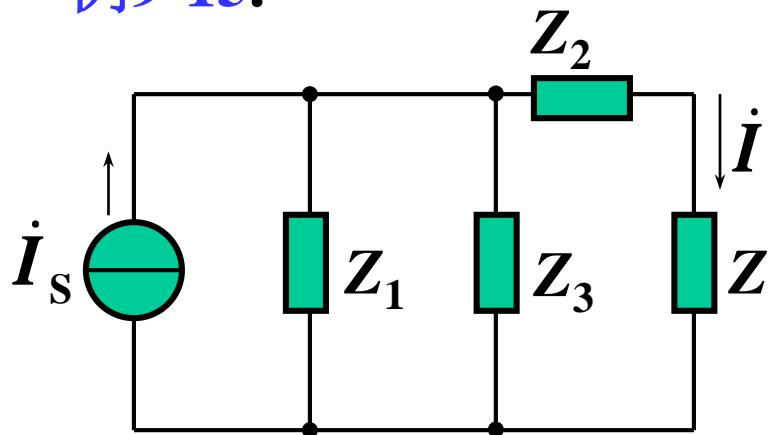
例9-14. 列写电路的节点电压方程



解:

$$\begin{cases} (Y_2 + Y_3)\dot{U}_1 - Y_3\dot{U}_2 = \dot{I}_{S1} \\ -Y_3\dot{U}_1 + (Y_3 + Y_4 + Y_5)\dot{U}_2 = Y_4\dot{U}_{S4} + Y_5\dot{U}_{S5} \end{cases}$$

例9-15.

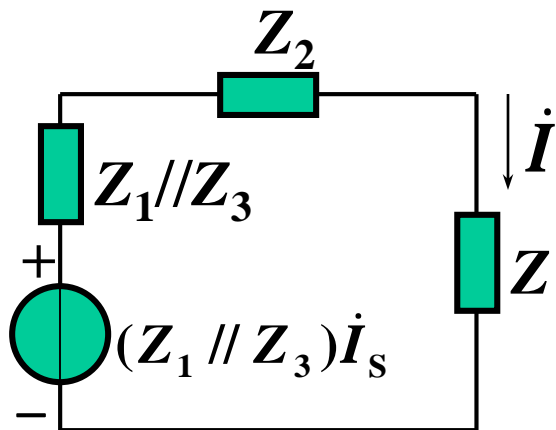


已知: $\dot{I}_s = 4\angle 90^\circ \text{ A}$, $Z_1 = Z_2 = -j30\Omega$
 $Z_3 = 30\Omega$, $Z = 45\Omega$

求: \dot{i} .

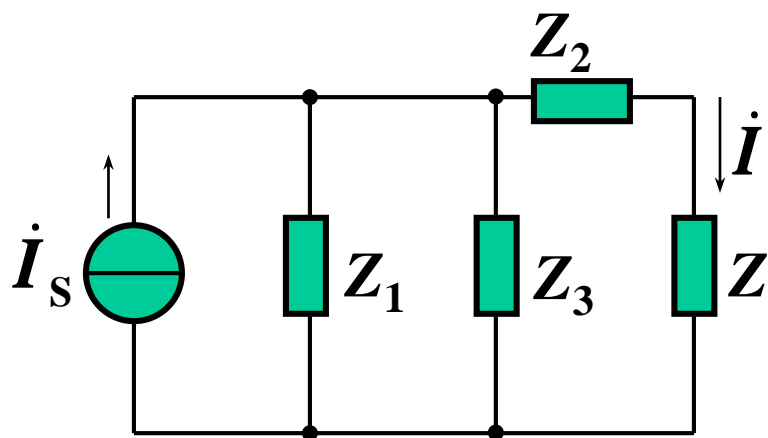
解:

法一: 电源变换



$$Z_1 // Z_3 = 15 - j15$$

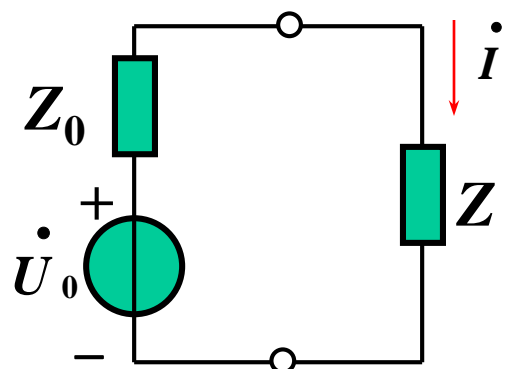
$$\begin{aligned} \dot{i} &= \frac{\dot{I}_s (Z_1 // Z_3)}{Z_1 // Z_3 + Z_2 + Z} = \frac{j4(15 - j15)}{15 - j15 - j30 + 45} \\ &= \frac{5.657\angle 45^\circ}{5\angle -36.9^\circ} \\ &= 1.13\angle 81.9^\circ \text{ A} \end{aligned}$$



已知: $\dot{I}_s = 4\angle 90^\circ \text{ A}$, $Z_1 = Z_2 = -j30\Omega$
 $Z_3 = 30\Omega$, $Z = 45\Omega$

求: \dot{I} .

法二: 戴维南等效变换

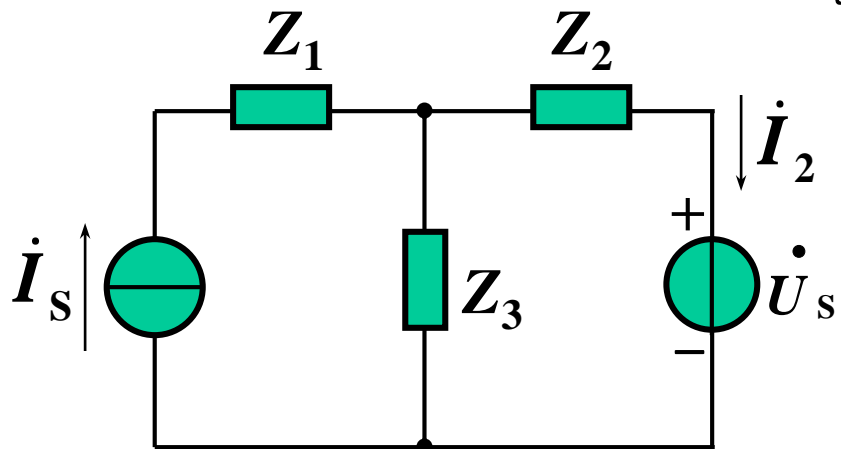


$$\dot{U}_0 = \dot{I}_s (Z_1 // Z_3) = 84.855 \angle 45^\circ \text{ V}$$

$$Z_0 = Z_1 // Z_3 + Z_2 = 15 - j45\Omega$$

$$\dot{I} = \frac{\dot{U}_0}{Z_0 + Z} = 1.13 \angle 81.9^\circ \text{ A}$$

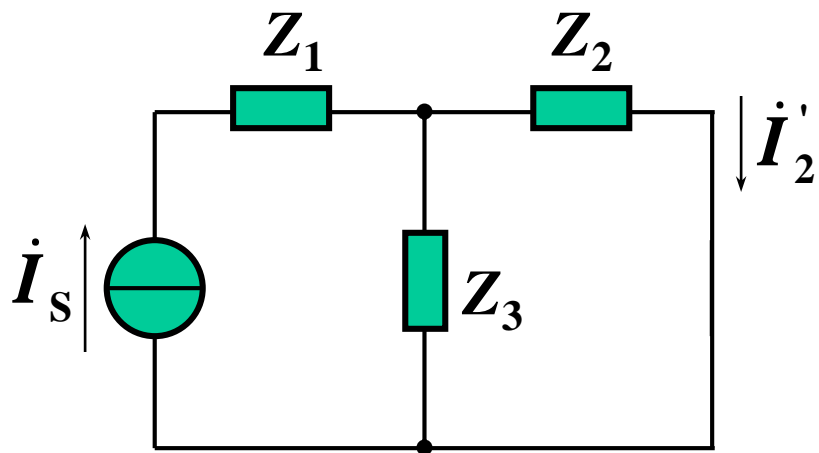
例9-16.



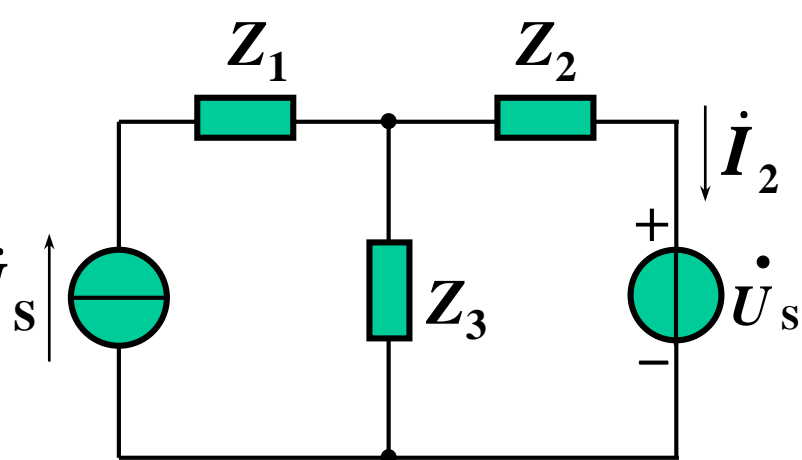
已知: $\dot{U}_s = 100 \angle 45^\circ \text{ V}$, $\dot{I}_s = 4 \angle 0^\circ \text{ A}$,
 $Z_1 = Z_3 = 50 \angle 30^\circ \Omega$, $Z_2 = 50 \angle -30^\circ \Omega$.

解:

(1) \dot{I}_s 单独作用(\dot{U}_s 短路):



$$\begin{aligned} \dot{I}'_2 &= \dot{I}_s \frac{Z_3}{Z_2 + Z_3} \\ &= 4 \angle 0^\circ \times \frac{50 \angle 30^\circ}{50 \angle -30^\circ + 50 \angle 30^\circ} \\ &= \frac{200 \angle 30^\circ}{50\sqrt{3}} = 2.31 \angle 30^\circ \text{ A} \end{aligned}$$



已知: $\dot{U}_s = 100 \angle 45^\circ \text{ V}$, $\dot{I}_s = 4 \angle 0^\circ \text{ A}$,
 $Z_1 = Z_3 = 50 \angle 30^\circ \Omega$, $Z_2 = 50 \angle -30^\circ \Omega$.

(2) \dot{U}_s 单独作用(\dot{I}_s 开路):

$$\begin{aligned} \dot{I}_2'' &= -\frac{\dot{U}_s}{Z_2 + Z_3} \\ &= \frac{-100 \angle 45^\circ}{50\sqrt{3}} = 1.155 \angle -135^\circ \text{ A} \end{aligned}$$

$$\begin{aligned} \dot{I}_2 &= \dot{I}_2' + \dot{I}_2'' \\ &= 2.31 \angle 30^\circ + 1.155 \angle -135^\circ \\ &= (2 + j1.155) + (-0.817 - j0.817) \\ &= 1.183 + j0.338 \\ &= 1.23 \angle 15.9^\circ \text{ A} \end{aligned}$$

```
In[39]:= N [-100 / (50 Sqrt[3])]
```

```
Out[39]:= -1.1547
```

```
In[42]:= -1.1547 * Cos[Pi / 4] + (-1.1547) * Sin[Pi / 4] j
```

```
Out[42]:= -0.816496 - 0.816496 i
```

```
In[43]:= Sqrt[2 * 0.816496 ^ 2]
```

```
Out[43]:= 1.1547
```

```
In[44]:= ArcTan[1]
```

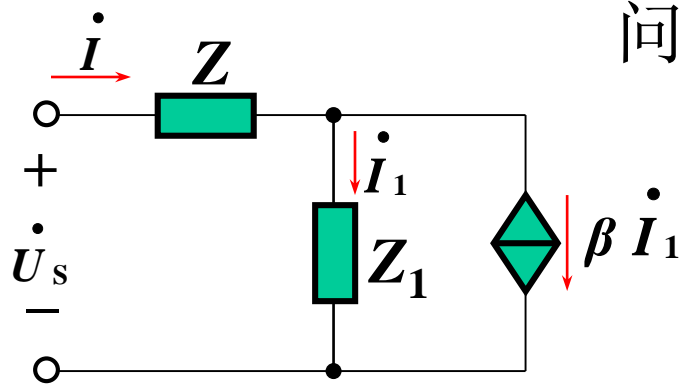
```
Out[44]:=  $\frac{\pi}{4}$ 
```

例9-17.

已知： $Z=10+j50\Omega$, $Z_1=400+j1000\Omega$ 。

问： β 等于多少时， \dot{I}_1 和 \dot{U}_s 相位差 90° ？

分析： 找出 \dot{I}_1 和 \dot{U}_s 关系： $\dot{U}_s = Z_{\text{转}} \dot{I}_1$ ，
 $Z_{\text{转}}$ 实部为零，相位差为 90° 。

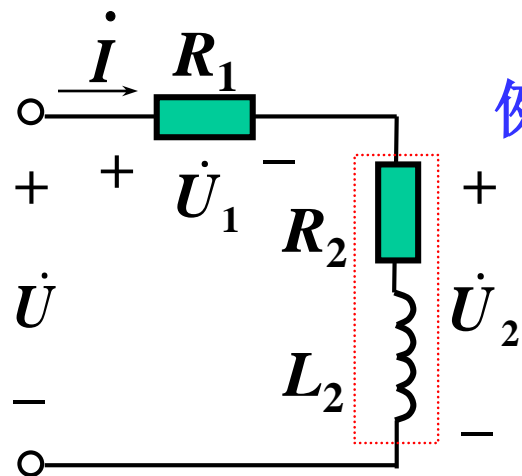


解： $\dot{U}_s = Z\dot{I} + Z_1\dot{I}_1 = Z(1 + \beta)\dot{I}_1 + Z_1\dot{I}_1$

$$\frac{\dot{U}_s}{\dot{I}_1} = (1 + \beta)Z + Z_1 = 410 + 10\beta + j(50 + 50\beta + 1000)$$

令 $410 + 10\beta = 0$, $\beta = -41$

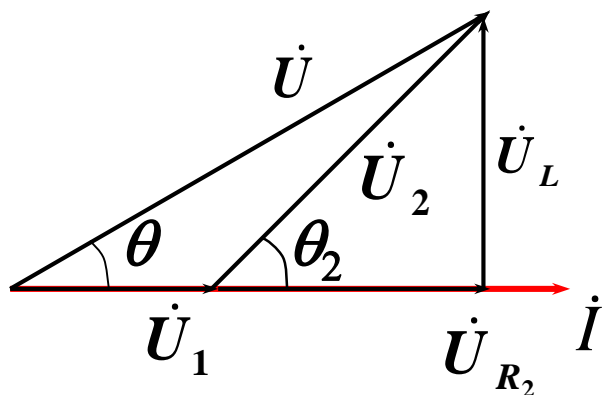
$$\frac{\dot{U}_s}{\dot{I}_1} = -j1000 \quad \text{故电流领先电压 } 90^\circ.$$



例9-18. 已知: $U=115\text{V}$, $U_1=55.4\text{V}$, $U_2=80\text{V}$,
 $R_1=32\Omega$, $f=50\text{Hz}$

求: 线圈的电阻 R_2 和电感 L_2 。

解: 画相量图进行定性分析 $U^2 = U_1^2 + U_2^2 + 2U_1U_2 \cos\theta_2$
 $\therefore \theta_2 = 64.9^\circ$



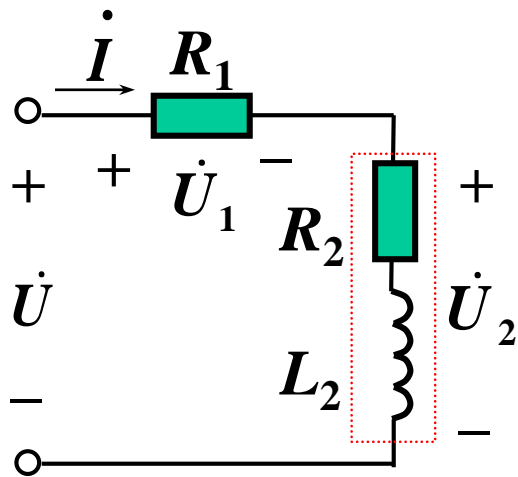
$$I = U_1 / R_1 = 55.4 / 32 = 1.73\text{A}$$

$$|Z_2| = U_2 / I = 80 / 1.73 = 46.2\Omega$$

$$R_2 = |Z_2| \cos\theta_2 = 19.6\Omega$$

$$X_2 = |Z_2| \sin\theta_2 = 41.8\Omega$$

$$L = X_2 / (2\pi f) = 0.133\text{H}$$



已知: $U=115\text{V}$, $U_1=55.4\text{V}$, $U_2=80\text{V}$,
 $R_1=32\Omega$, $f=50\text{Hz}$

求: 线圈的电阻 R_2 和电感 L_2 。

$$I = U_1 / R_1 = 55.4 / 32 = 1.73\text{A}$$

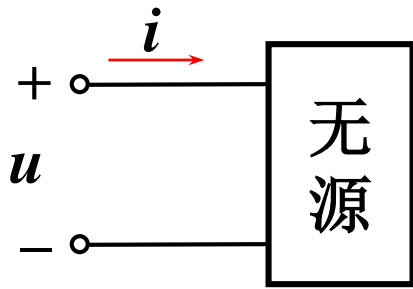
$$\frac{115}{\sqrt{(32 + R_2)^2 + (\omega L_2)^2}} = I = 1.73$$

$$\frac{80}{\sqrt{R_2^2 + (\omega L_2)^2}} = I = 1.73$$

解得:

$$R_2 = 19.58\Omega, \quad L_2 = \frac{41.86}{2\pi f} = 0.133\text{H}.$$

§ 9-5 正弦稳态电路的功率



$$u(t) = \sqrt{2}U \cos(\omega t + \varphi_u)$$

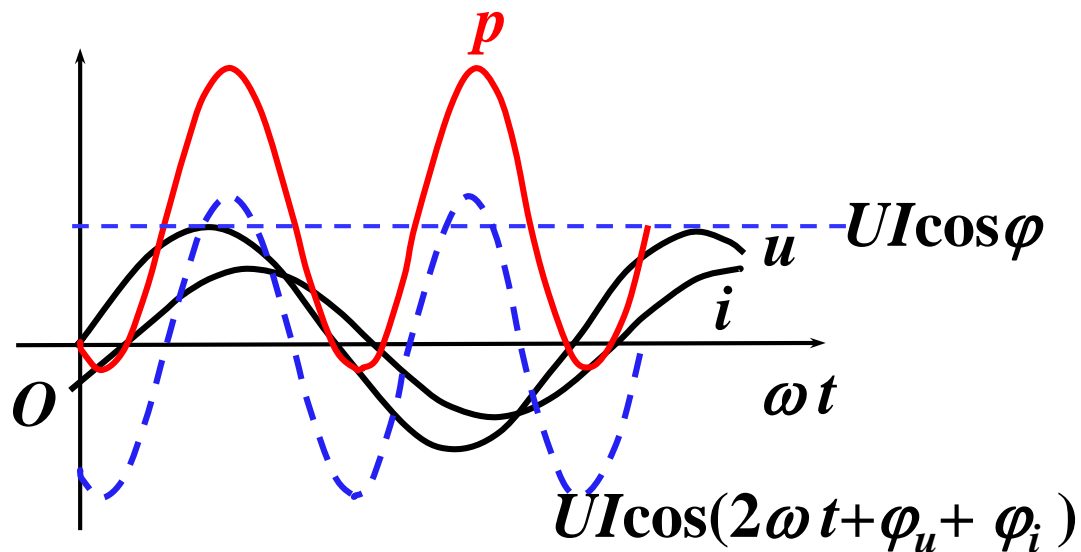
$$i(t) = \sqrt{2}I \cos(\omega t + \varphi_i)$$

$$\varphi = \varphi_u - \varphi_i$$

一、瞬时功率

$$\begin{aligned} p &= ui = \sqrt{2}U \cos(\omega t + \varphi_u) \cdot \sqrt{2}I \cos(\omega t + \varphi_i) \\ &= 2UI \cos(\omega t + \varphi_u) \cos(\omega t + \varphi_i) \\ &= UI \cos(\varphi_u - \varphi_i) + UI \cos(2\omega t + \varphi_u + \varphi_i) \\ &= UI \cos \varphi + UI \cos(2\omega t + \varphi_u + \varphi_i) \end{aligned}$$

$$p = ui = UI \cos \varphi + UI \cos(2\omega t + \varphi_u + \varphi_i)$$



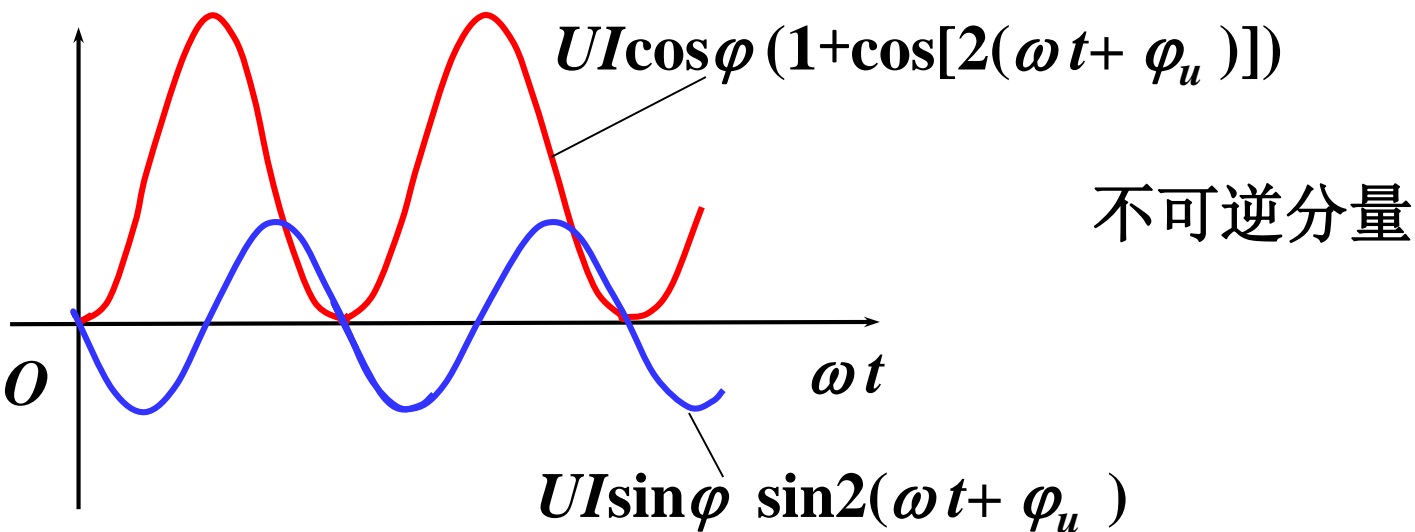
- $p > 0$, 电路吸收功率: $p < 0$, 电路发出功率;
- p 以 2ω 角频率变化
- 恒定分量: $UI \cos \varphi$
 正弦分量: $UI \cos(2\omega t + \varphi_u + \varphi_i)$

$$p = ui = UI \cos \varphi + UI \cos(2\omega t + \varphi_u + \varphi_i)$$

$$= UI \cos \varphi + UI \cos(2\omega t + 2\varphi_u - \varphi)$$

$$= UI \cos \varphi + UI \cos \varphi \cos(2\omega t + 2\varphi_u) + UI \sin \varphi \sin(2\omega t + 2\varphi_u)$$

$$= UI \cos \varphi \{1 + \cos[2(\omega t + \varphi_u)]\} + UI \sin \varphi \sin[2(\omega t + \varphi_u)]$$



不可逆分量

可逆分量，周期性变化

二、平均功率（有功功率）

$$P = \frac{1}{T} \int_0^T p dt = \frac{1}{T} \int_0^T UI [\cos \varphi + \cos(2\omega t + 2\varphi_u + \varphi_i)] dt$$

$$= UI \cos \varphi$$

P 的单位：W 瓦特

$\lambda = \cos \varphi$ 称为功率因数

$\varphi = \varphi_u - \varphi_i$ ：功率因数角。对无源网络，为其等效阻抗的阻抗角。

$$\cos \varphi \begin{cases} 1, & \text{纯电阻} \\ 0, & \text{纯电抗} \end{cases}$$

$X > 0, \varphi > 0$ ，感性，滞后功率因数

$X < 0, \varphi < 0$ ，容性，超前功率因数

三、无功功率

$$Q \stackrel{\text{def}}{=} UI \sin \varphi \quad \text{单位: var (乏)}。$$

$$p = ui = UI \cos \varphi + UI \cos(2\omega t + \varphi_u + \varphi_i)$$

$Q > 0$, 表示网络吸收无功功率;

$Q < 0$, 表示网络发出无功功率。

Q 的大小反映网络与外电路交换功率的大小。是由储能元件 L 、 C 的性质决定的

四、视在功率

$$S \stackrel{\text{def}}{=} UI \quad \text{单位: VA (伏安)}$$

反映电气设备的容量。

有功，无功，视在功率的关系：

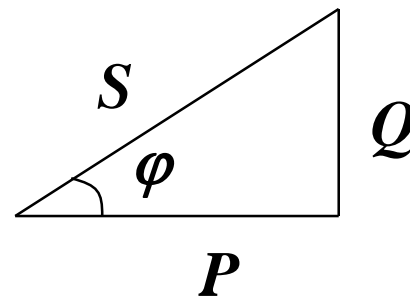
$$\text{有功功率: } P = UI \cos \varphi \quad \text{单位: W}$$

$$\text{视在功率: } S = UI \quad \text{单位: VA}$$

$$\text{无功功率: } Q = UI \sin \varphi \quad \text{单位: var}$$

$$P = S \cos \varphi, \quad Q = S \sin \varphi$$

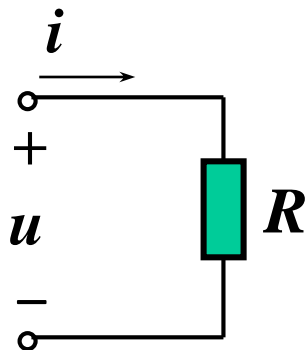
$$S = \sqrt{P^2 + Q^2}, \quad \varphi = \arctan\left(\frac{Q}{P}\right)$$



功率三角形

五、RLC元件的功率分析

1. 电阻R



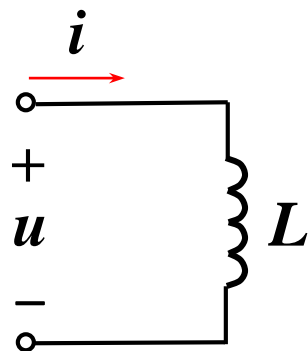
$$\varphi = \varphi_u - \varphi_i = 0$$

$$p = UI \{1 + \cos[2(\omega t + \varphi_u)]\} \geq 0$$

$$P_R = UI \cos \varphi = UI \cos 0^\circ = UI = I^2 R = U^2 / R$$

$$Q_R = UI \sin \varphi = UI \sin 0^\circ = 0$$

2. 电感L



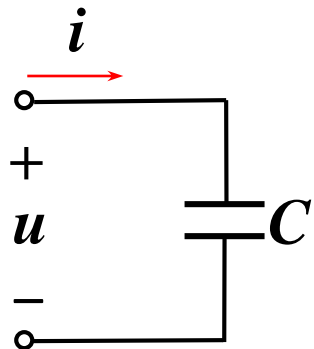
$$\varphi = \varphi_u - \varphi_i = \frac{\pi}{2}$$

$$p = UI \sin \varphi \sin [2(\omega t + \varphi_u)]$$

$$P_L = UI \cos \varphi = UI \cos 90^\circ = 0$$

$$Q_L = UI \sin \varphi = UI \sin 90^\circ = UI$$

3. 电容C



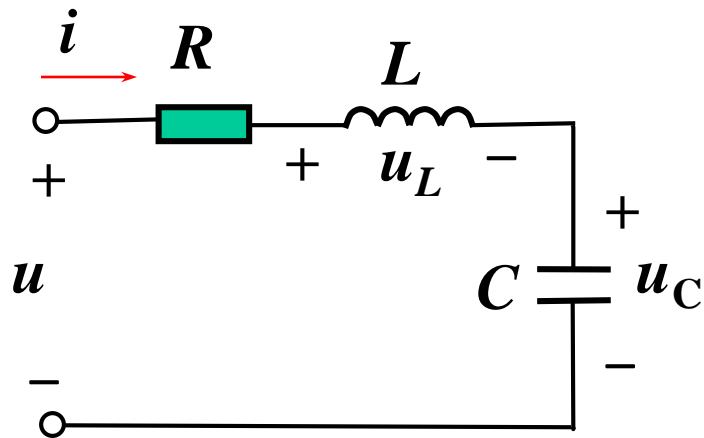
$$\varphi = \varphi_u - \varphi_i = -\frac{\pi}{2}$$

$$p = UI \sin \varphi \sin [2(\omega t + \varphi_u)] \\ = -UI \sin [2(\omega t + \varphi_u)]$$

$$P_C = UI \cos \varphi = UI \cos(-90^\circ) = 0$$

$$Q_C = UI \sin \varphi = UI \sin(-90^\circ) = -UI$$

4. RLC串联电路



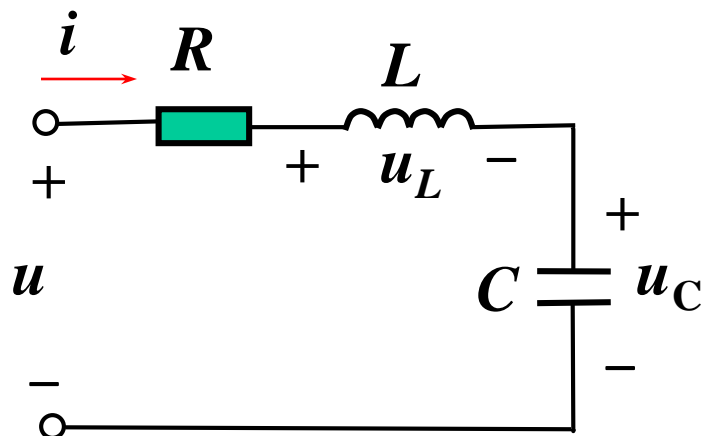
$$\varphi = \varphi_u - \varphi_i = \varphi_Z$$

$$Z = R + j(\omega L - \frac{1}{\omega C}), \varphi_z = \arctan(\frac{X}{R})$$

$$U = |Z| I, R = |Z| \cos \varphi_Z, X = |Z| \sin \varphi_Z$$

4. RLC串联电路

$$\varphi = \varphi_u - \varphi_i = \varphi_Z$$

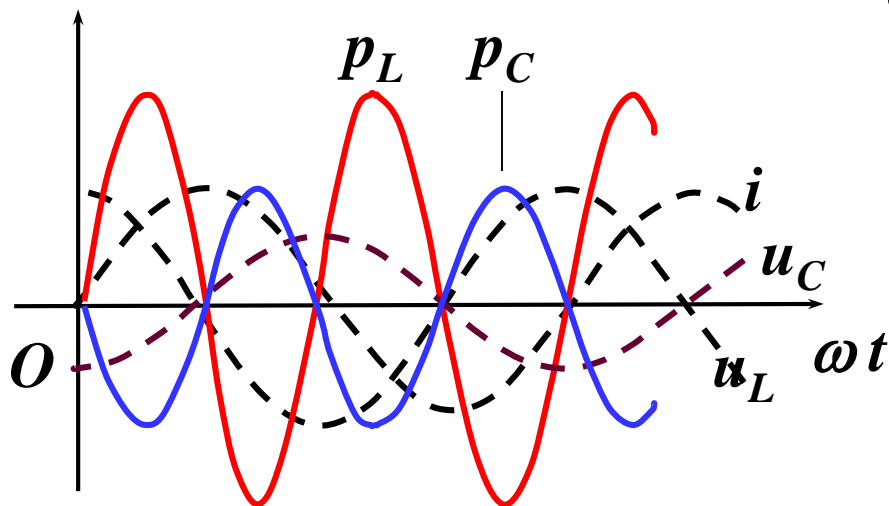


$$Z = R + j(\omega L - \frac{1}{\omega C}), \quad \varphi_z = \arctan(\frac{X}{R})$$

$$U = |Z| I, \quad R = |Z| \cos \varphi_Z, \quad X = |Z| \sin \varphi_Z$$

$$\left\{ \begin{aligned} P &= U I \cos \varphi = |Z| I^2 \cos \varphi = R I^2 \end{aligned} \right.$$

$$\left\{ \begin{aligned} Q &= U I \sin \varphi = |Z| I^2 \sin \varphi = X I^2 = (\omega L - \frac{1}{\omega C}) I^2 = Q_L + Q_C \end{aligned} \right.$$



例9-19： 单口网络电压、电流为关联参考方向，

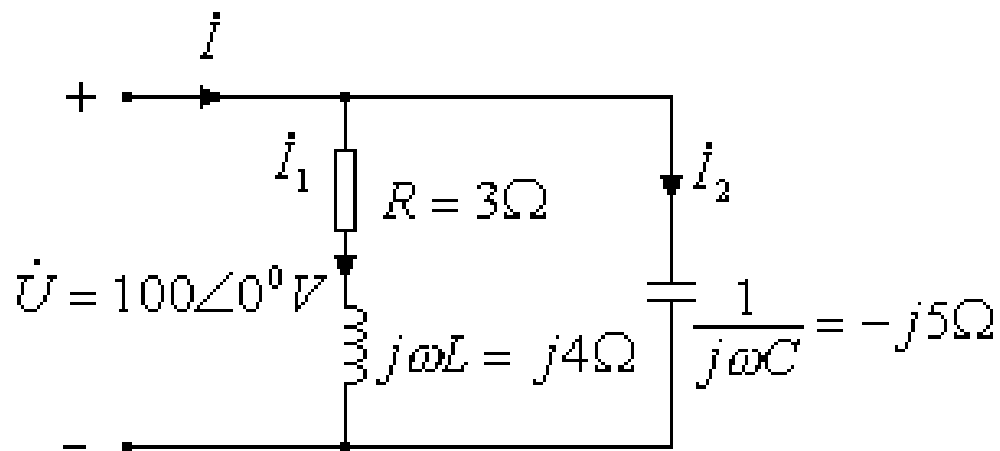
$$u = 300\sqrt{2} \cos(314t + 10^\circ) \text{ V} \quad i = 50\sqrt{2} \cos(314t - 45^\circ) \text{ A}$$

求网络吸收的平均功率。

解： $U = 300 \text{ V}$, $I = 50 \text{ A}$, $\varphi = \varphi_Z = 10^\circ - (-45^\circ) = 55^\circ$

$$P = UI \cos \varphi = 300 \times 50 \times \cos 55^\circ = 8610 \text{ W}$$

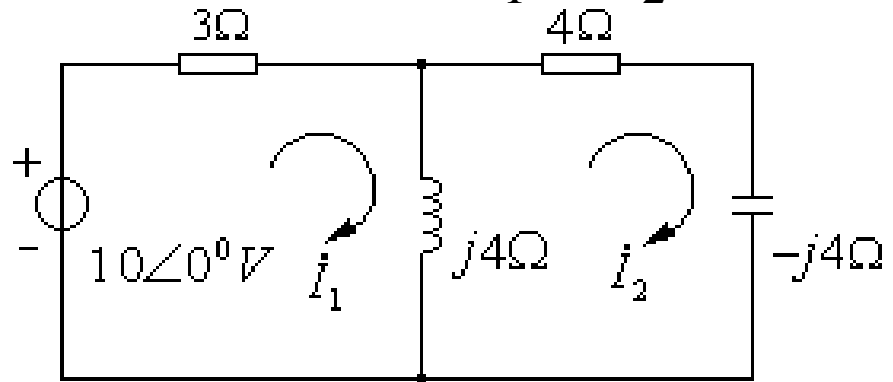
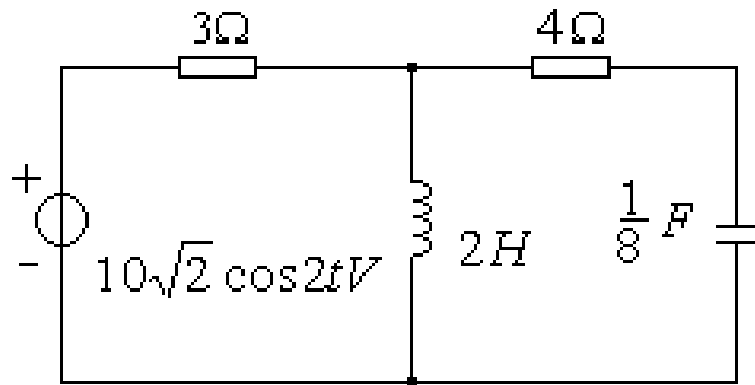
例 9-20： 电路及其相量模型如下图所示，求单口网络的功率。



已知

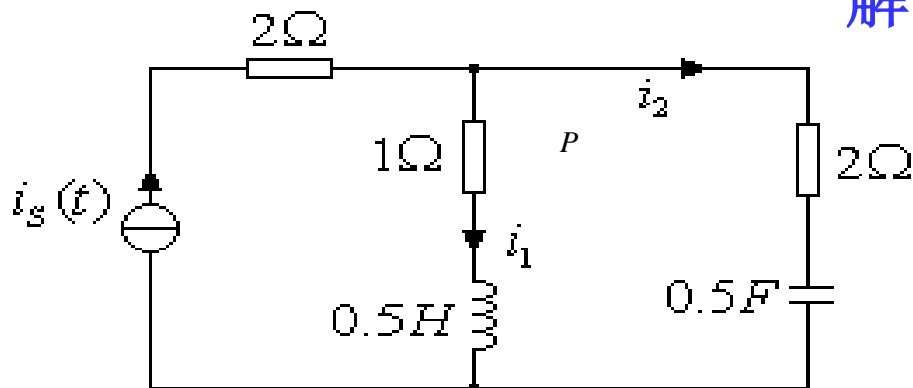
$$\begin{cases} \dot{i} = 12.65\angle 18.5^\circ \text{ A} \\ \dot{i}_1 = 20\angle -53.1^\circ \text{ A} \\ \dot{i}_2 = 20\angle 90^\circ \text{ A} \end{cases}$$

例 9-21: 求下图所示电路中电源提供的功率。 $I_1 = I_2 = 1.24 \text{ A}$



解: $P = I_1^2 \times 3 + I_2^2 \times 4 = 1.24^2 \times 3 + 1.24^2 \times 4 = 10.8 \text{ W}$

例 9-22: 下图所示电路中, $i_s = 5\sqrt{2} \cos 2t \text{ A}$, 电路处于稳态, 试求P、Q、S、 λ



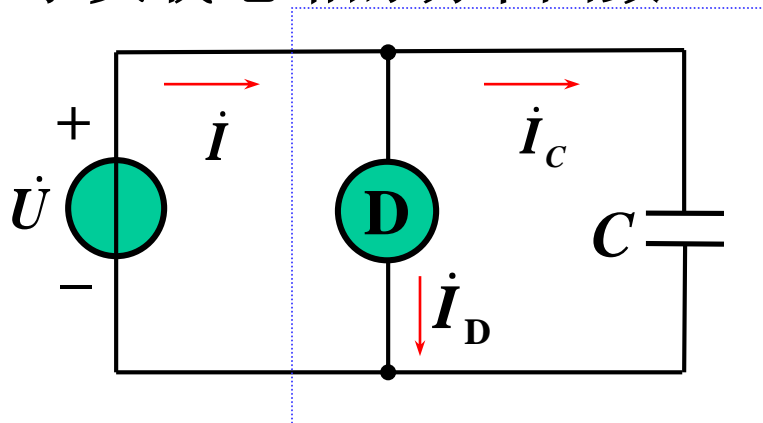
解:

$$Z = 2 + \frac{(1+j)(2-j)}{1+j+2-j} = 3 + j\frac{1}{3} \Omega$$

$$P = I^2 \operatorname{Re}[Z] = 75 \text{ W}$$

$$Q = I^2 \operatorname{Im}[Z] = \frac{25}{3} \text{ Var}$$

例9-23. 已知：电动机 $P_D=1000\text{W}$ ， $U=220\text{V}$ ， $f=50\text{Hz}$ ， $C=30\mu\text{F}$ 。
求负载电路的功率因数。D的功率因素为0.8。



解：

$$\dot{I}_D = \frac{P_D}{U \cos \varphi_D} = \frac{1000}{220 \times 0.8} = 5.68 \text{ A}$$

$$\because \cos \varphi_D = 0.8(\text{滞后}), \quad \therefore \varphi_D = 36.8^\circ$$

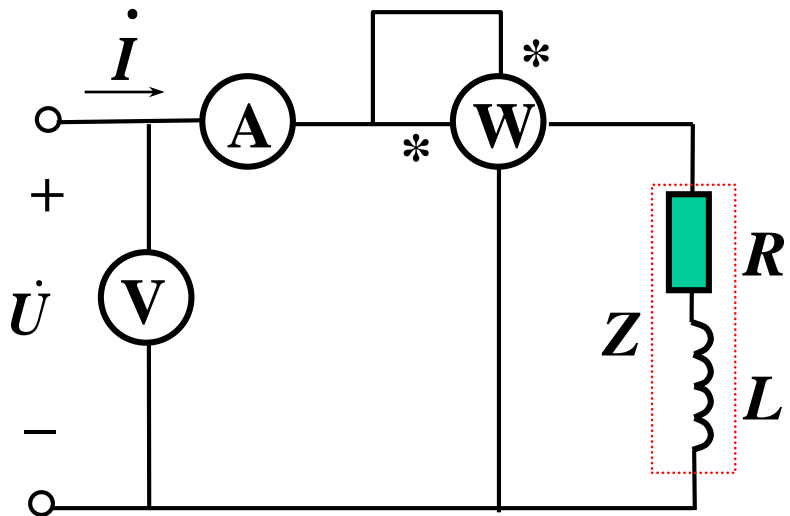
$$\text{设 } \dot{U} = 220 \angle 0^\circ$$

$$\dot{I}_D = 5.68 \angle -36.8^\circ, \quad \dot{I}_C = 220 \angle 0^\circ \cdot j\omega C = j2.08$$

$$\dot{I} = \dot{I}_D + \dot{I}_C = 4.54 - j1.33 = 4.73 \angle -16.3^\circ$$

$$\therefore \cos \varphi = \cos[0^\circ - (-16.3^\circ)] = 0.96 \quad (\text{滞后})$$

例9-24. 已知 $f=50\text{Hz}$ ，且测得 $U=50\text{V}$ ， $I=1\text{A}$ ， $P=30\text{W}$ 。



解：

$$P = I^2 R \quad \therefore R = \frac{P}{I^2} = \frac{30}{1^2} = 30\Omega$$

$$|Z| = \frac{U}{I} = \frac{50}{1} = 50\Omega$$

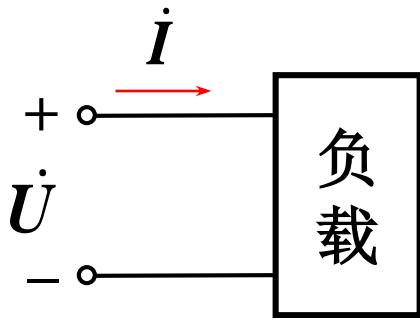
$$|Z| = \sqrt{R^2 + (\omega L)^2}$$

$$L = \frac{1}{\omega} \sqrt{|Z|^2 - R^2} = \frac{1}{314} \sqrt{50^2 - 30^2} = \frac{40}{314} = 0.127\text{H}$$

§ 9-6 复功率

一、复功率

为了用相量 \dot{U} 和 \dot{I} 来计算功率，引入“复功率”



$$\begin{aligned}\dot{U} &= U \angle \varphi_u, & \dot{I} &= I \angle \varphi_i \\ P &= UI \cos(\varphi_u - \varphi_i) = UI \operatorname{Re}[e^{j(\varphi_u - \varphi_i)}] \\ &= \operatorname{Re}(U e^{j\varphi_u} \cdot I e^{-j\varphi_i})\end{aligned}$$

$$\dot{U}$$

$$\dot{I}^*$$

$$P = \operatorname{Re}[\dot{U} \cdot \dot{I}^*]$$

定义 $\bar{S} = \dot{U}\dot{I}^*$ 为复功率，单位 VA

$$\begin{aligned}\bar{S} &= \dot{U}\dot{I}^* = UI \angle (\varphi_u - \varphi_i) = UI \angle \varphi = S \angle \varphi \\ &= UI \cos \varphi + j UI \sin \varphi \\ &= P + jQ\end{aligned}$$

复功率 \bar{S} 也可以表示为以下式子:

$$\bar{S} = \dot{U} \dot{I}^* = Z \dot{I} \cdot \dot{I}^* = Z I^2$$

$$\bar{S} = \dot{U} \dot{I}^* = \dot{U} (\dot{U} Y)^* = \dot{U} \cdot \dot{U}^* Y^* = U^2 Y^*$$

复功率守恒定理: 在正弦稳态下, 任一电路的所有支路吸收的复功率之和为零。

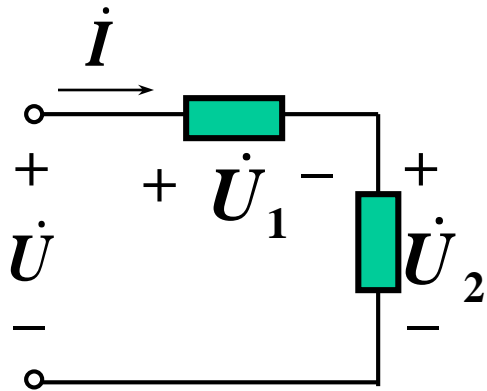
$$\sum_{k=1}^b \bar{S}_k = \mathbf{0}$$

$$\sum_{k=1}^b (P_k + \mathbf{j}Q_k) = \mathbf{0}$$

$$\sum_{k=1}^b \dot{U}_k \dot{I}_k^* = \mathbf{0}$$

$$\begin{cases} \sum_{k=1}^b P_k = \mathbf{0} \\ \sum_{k=1}^b Q_k = \mathbf{0} \end{cases}$$

* 复功率守恒 不等于 视在功率守恒



$$\begin{aligned}\bar{S} &= \dot{U} \dot{I}^* = (\dot{U}_1 + \dot{U}_2) \dot{I}^* \\ &= \dot{U}_1 \dot{I}^* + \dot{U}_2 \dot{I}^* = \bar{S}_1 + \bar{S}_2\end{aligned}$$

$$\because U \neq U_1 + U_2$$

$$\therefore S \neq S_1 + S_2$$

一般情况下:

$$S \neq \sum_{k=1}^b S_k$$

$$\text{Complex Power} = S = P + jQ = \mathbf{V}_{\text{rms}}(\mathbf{I}_{\text{rms}})^*$$

$$= |\mathbf{V}_{\text{rms}}| |\mathbf{I}_{\text{rms}}| \angle \theta_v - \theta_i$$

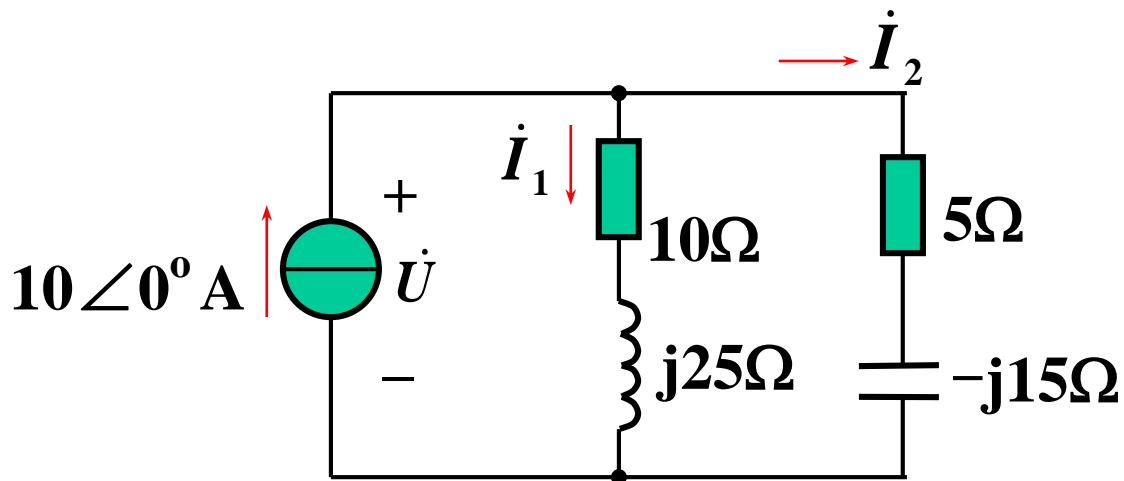
$$\text{Apparent Power} = S = |\mathbf{S}| = |\mathbf{V}_{\text{rms}}| |\mathbf{I}_{\text{rms}}| = \sqrt{P^2 + Q^2}$$

$$\text{Real Power} = P = \text{Re}(\mathbf{S}) = S \cos(\theta_v - \theta_i)$$

$$\text{Reactive Power} = Q = \text{Im}(\mathbf{S}) = S \sin(\theta_v - \theta_i)$$

$$\text{Power Factor} = \frac{P}{S} = \cos(\theta_v - \theta_i)$$

例9-25. 已知如图，求各支路的复功率。



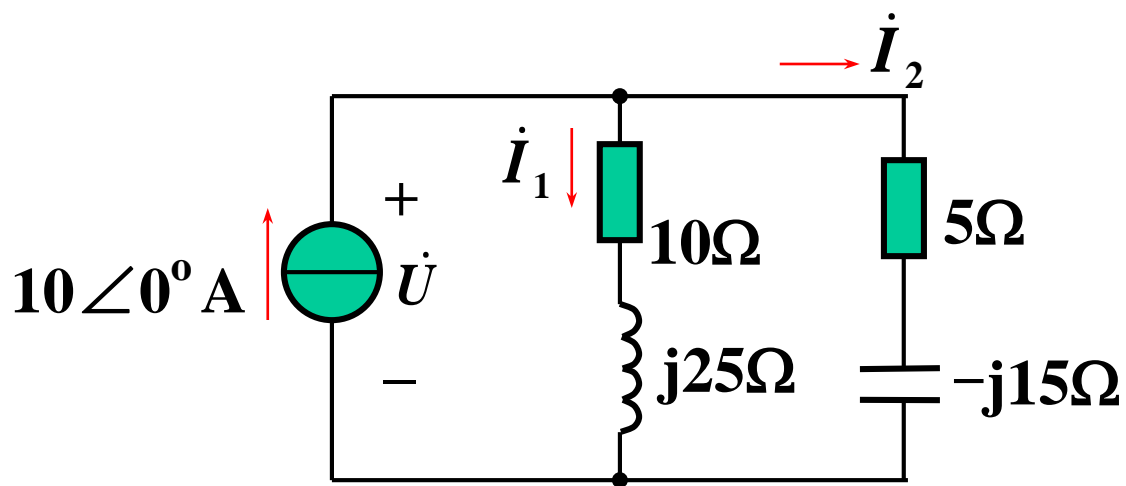
解一：

$$\begin{aligned}\dot{U} &= 10\angle 0^\circ \times [(10 + j25) // (5 - j15)] \\ &= 236\angle(-37.1^\circ) \text{ V}\end{aligned}$$

$$\bar{S}_{\text{发}} = 236\angle(-37.1^\circ) \times 10\angle 0^\circ = 1882 - j1424 \text{ VA}$$

$$\bar{S}_{1\text{吸}} = U^2 Y_1^* = 236^2 \left(\frac{1}{10 + j25} \right)^* = 768 + j1920 \text{ VA}$$

$$\bar{S}_{2\text{吸}} = U^2 Y_2^* = 1114 - j3344 \text{ VA}$$



解二:
$$\dot{I}_1 = 10\angle 0^\circ \times \frac{5 - j15}{10 + j25 + 5 - j15} = 8.77\angle(-105.3^\circ) \text{ A}$$

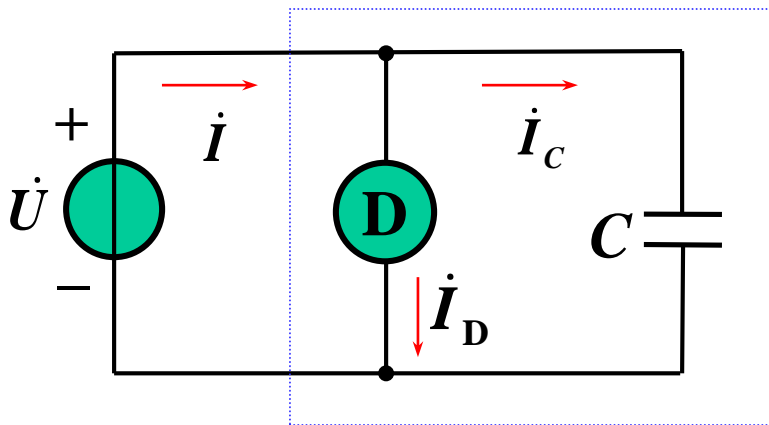
$$\dot{I}_2 = \dot{I}_s - \dot{I}_1 = 14.94\angle 34.5^\circ \text{ A}$$

$$\bar{S}_{1\text{吸}} = I_1^2 Z_1 = 8.77^2 \times (10 + j25) = 769 + j1923 \text{ VA}$$

$$\bar{S}_{2\text{吸}} = I_2^2 Z_2 = 14.94^2 \times (5 - j15) = 1116 - j3346 \text{ VA}$$

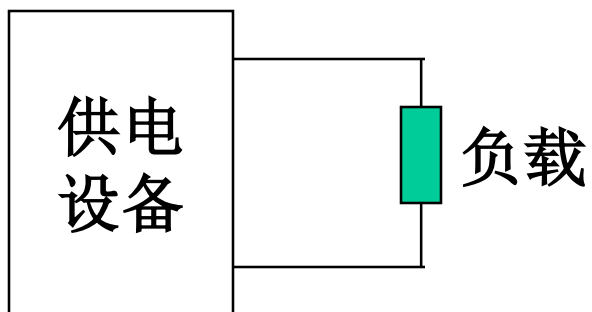
$$\begin{aligned} \bar{S}_{\text{发}} &= \dot{I}_s^* \cdot \dot{I}_1 Z_1 = 10 \times 8.77\angle(-105.3^\circ)(10 + j25) \\ &= 1885 - j1423 \text{ VA} \end{aligned}$$

三、功率因数提高



$$\cos \varphi_D = 0.8$$

$$\cos \varphi = 0.96$$



$$S = UI$$

$$P = S \cos \varphi$$

$$\cos \varphi = 1, \quad P = S$$

$$\cos \varphi = 0.7, \quad P = 0.7S$$

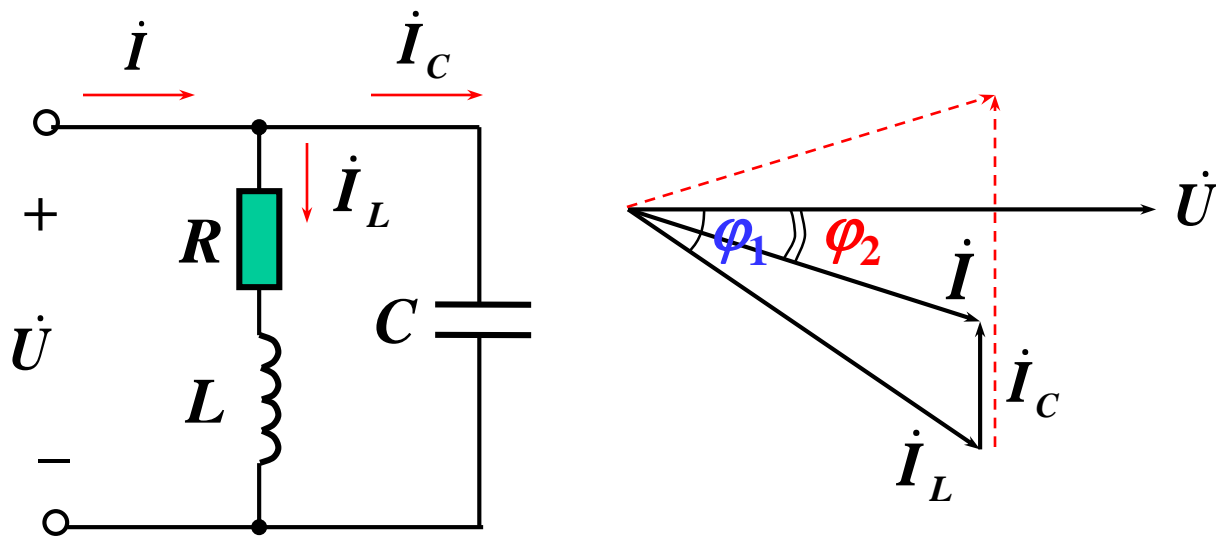
日光灯

$$\cos \varphi = 0.45 \sim 0.6$$

功率因数低带来的问题:

- (1) 设备不能充分利用，电流到了额定值，但功率容量还有；
- (2) 当输出相同的有功功率时，线路上电流大 $I=P/(U\cos\varphi)$ ，线路压降损耗大。

解决办法: 并联电容，提高功率因数 (改进自身设备)。



功率因数提高后，线路上电流减少，就可以带更多的负载，充分利用设备的能力。

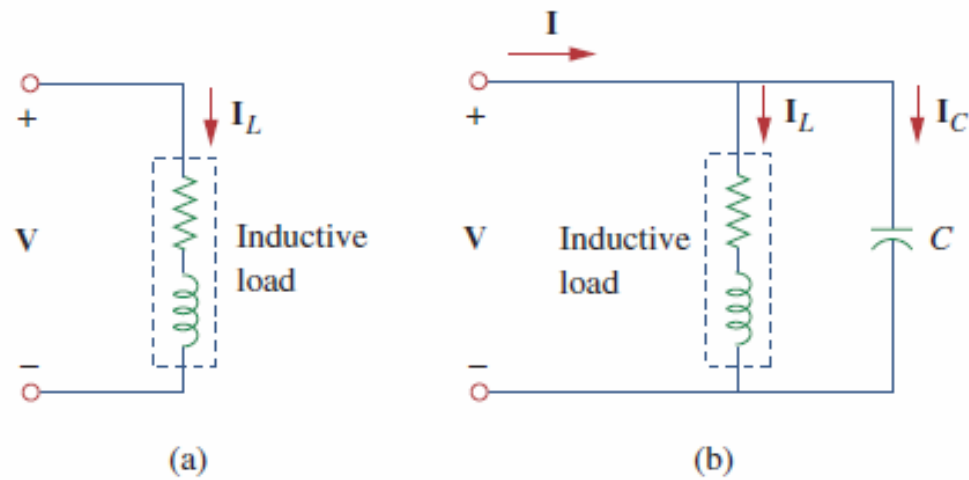


Figure 11.27

Power factor correction: (a) original inductive load, (b) inductive load with improved power factor.

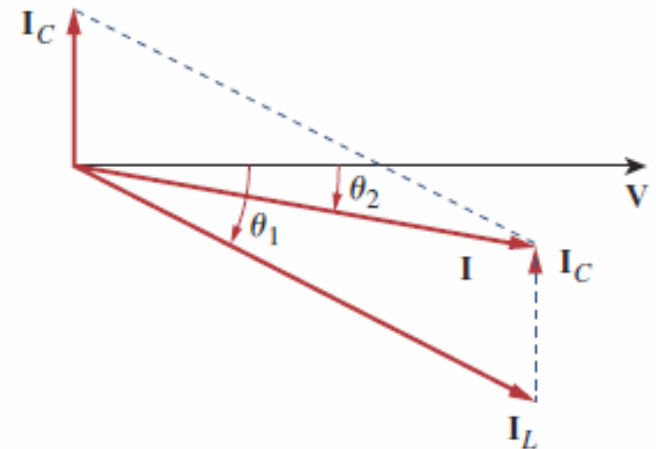
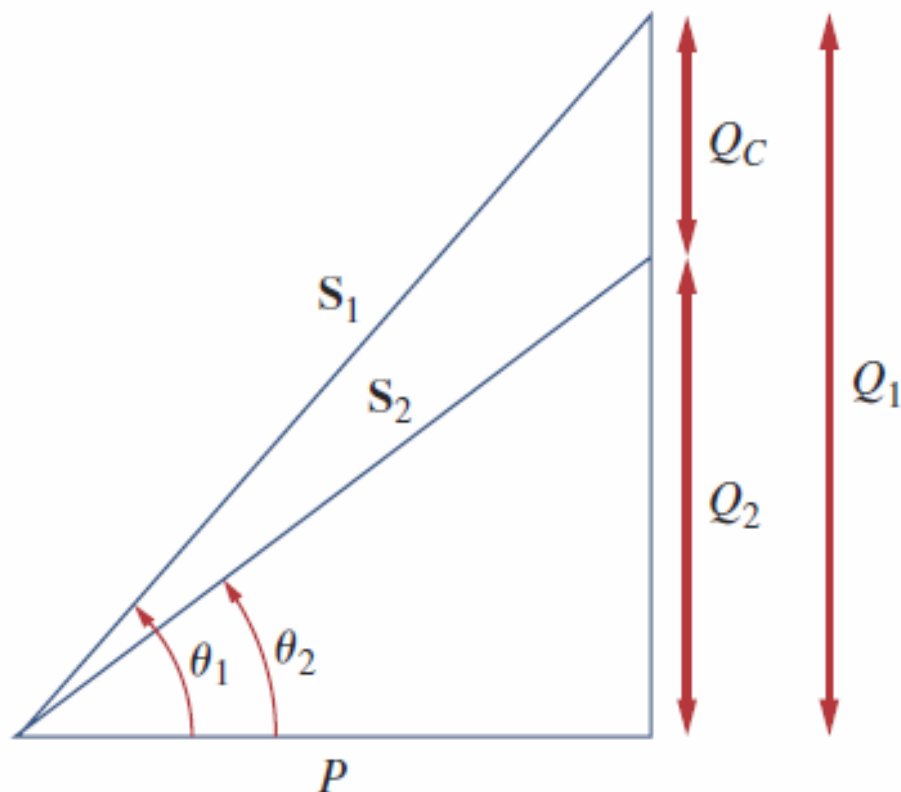


Figure 11.28

Phasor diagram showing the effect of adding a capacitor in parallel with the inductive load.



$$P = S_1 \cos \theta_1, \quad Q_1 = S_1 \sin \theta_1 = P \tan \theta_1$$

$$Q_2 = P \tan \theta_2$$

$$Q_C = Q_1 - Q_2 = P(\tan \theta_1 - \tan \theta_2)$$

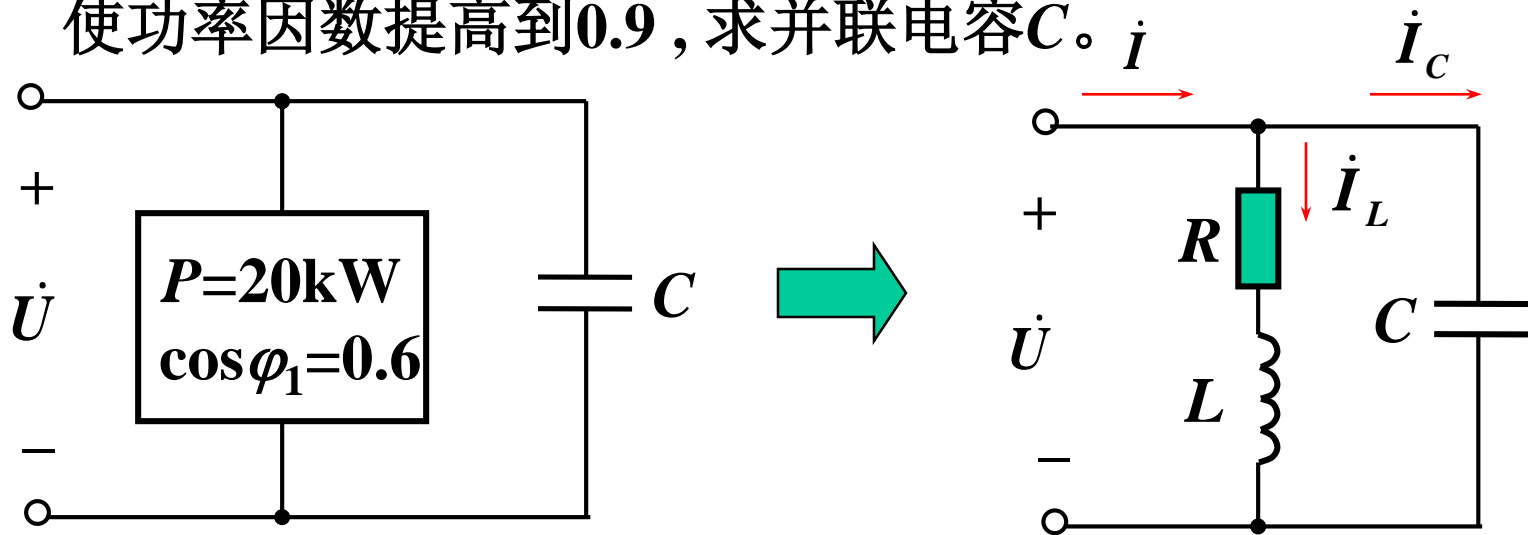
$$Q_C = V_{\text{rms}}^2 / X_C = \omega C V_{\text{rms}}^2.$$

$$C = \frac{Q_C}{\omega V_{\text{rms}}^2} = \frac{P(\tan \theta_1 - \tan \theta_2)}{\omega V_{\text{rms}}^2}$$

Figure 11.29

Power triangle illustrating power factor correction.

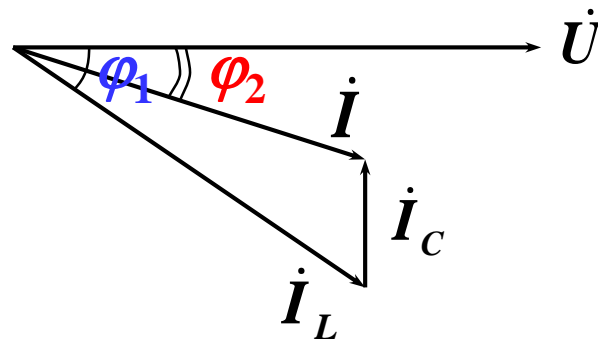
例9-26. 已知： $f=50\text{Hz}$, $U=380\text{V}$, $P=20\text{kW}$, $\cos\varphi_1=0.6$ (滞后)。要使功率因数提高到0.9, 求并联电容 C 。



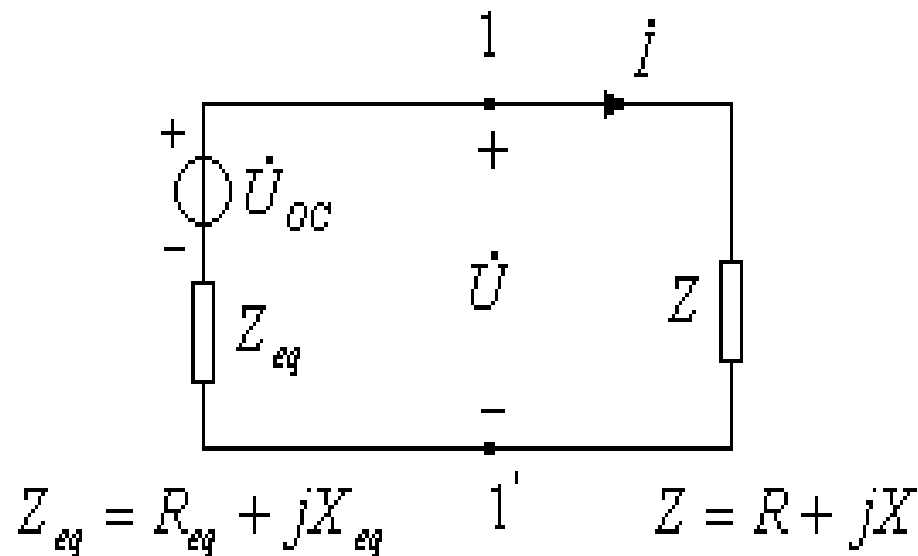
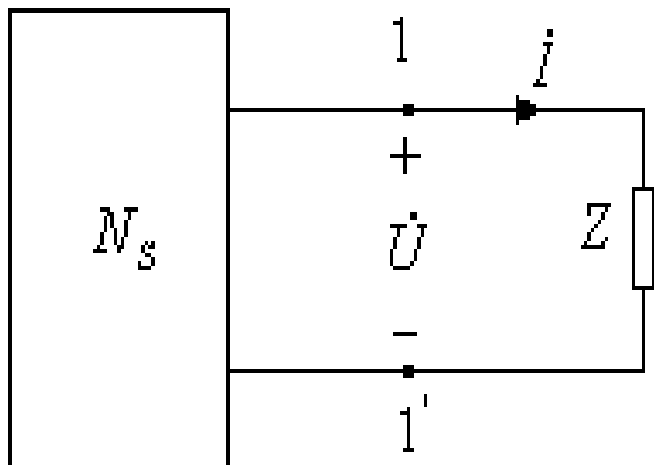
解： 由 $\cos\varphi_1 = 0.6$ 得 $\varphi_1 = 53.13^\circ$

由 $\cos\varphi_2 = 0.9$ 得 $\varphi_2 = 25.84^\circ$

$$\begin{aligned}
 C &= \frac{P}{\omega U^2} (\operatorname{tg}\varphi_1 - \operatorname{tg}\varphi_2) \\
 &= \frac{20 \times 10^3}{314 \times 380^2} (\operatorname{tg}53.13^\circ - \operatorname{tg}25.84^\circ) \\
 &= 375 \mu\text{F}
 \end{aligned}$$



§ 9-7 最大功率传输



$$\dot{I} = \frac{\dot{U}_{oc}}{Z_{eq} + Z_L}, \quad I = \frac{U_{oc}}{\sqrt{(R_{eq} + R_L)^2 + (X_{eq} + X_L)^2}}$$

$$P = RI^2 = \frac{U_{oc}^2 \cdot R}{(R + R_{eq})^2 + (X + X_{eq})^2}$$

$$\frac{\partial P}{\partial X} = \frac{U_{OC}^2 R [-2(X + X_{eq})]}{[(R + R_{eq})^2 + (X + X_{eq})^2]^2} = 0 \quad \Rightarrow \quad X = -X_{eq}$$

$$\frac{\partial P}{\partial R} = \frac{(R + R_{eq})^2 - 2R(R + R_{eq})}{(R + R_{eq})^4} U_{OC}^2 = 0 \quad \Rightarrow \quad R = R_{eq}$$

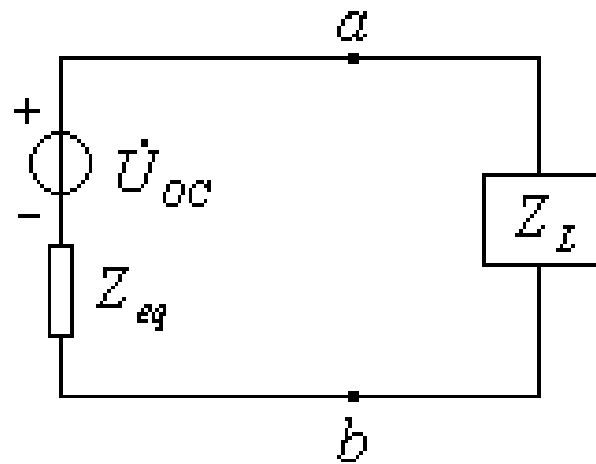
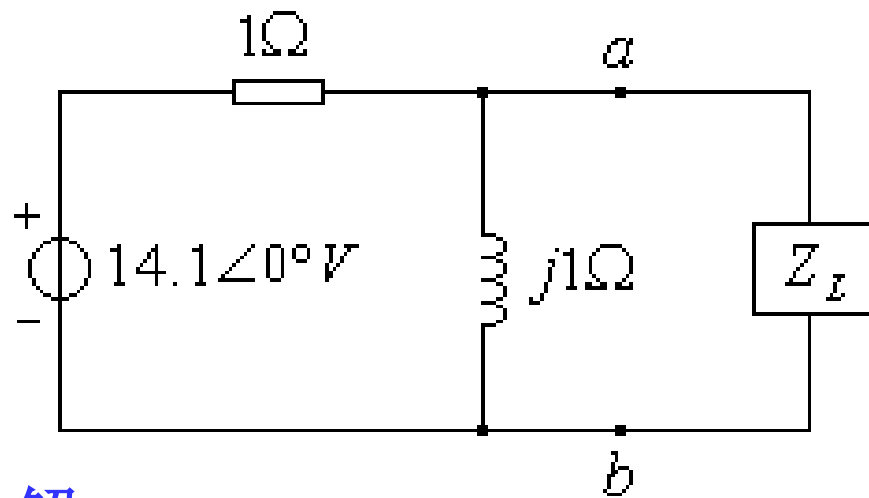
$$Z = R_{eq} - jX_{eq} = Z_{eq}^*$$

$$P_{\max} = \frac{U_{OC}^2}{4R_{eq}}$$

$$Y = Y_{eq}^*$$

$$P_{\max} = \frac{I_{SC}^2}{4G_{eq}}$$

例9-27: 电路如下图所示, 若 Z_L 的实部、虚部均能变动, 若使获得最大功率, Z_L 应为何值, 最大功率是多少?



解:

$$\dot{U}_{oc} = 14.1\angle 0^\circ \times \frac{j}{1+j} = 10\sqrt{2}\angle 0^\circ \times \frac{1\angle 90^\circ}{\sqrt{2}\angle 45^\circ} = 10\angle 45^\circ \text{ V}$$

$$Z_{eq} = \frac{1 \times j}{1+j} = \frac{1}{\sqrt{2}} \angle 45^\circ = 0.5 + j0.5 \text{ } \Omega$$

$$Z_L = 0.5 - j0.5 \text{ } \Omega,$$

$$P_{L\max} = \frac{10^2}{4 \times 0.5} = 50 \text{ W}$$