

# BAYESIAN OPTIMIZATION OVERVIEW

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# Motivations

Obtaining the predictive model for MPC is costly and time-consuming.

Typically, models are obtained through Physical modeling or Identification

- Requires domain knowledge and/or ad-hoc identification experiments
- A trade-off emerges between accuracy and complexity

It is often difficult to decide *a priori* how accurate the predictive model should be in order to achieve satisfactory closed-loop performance.

In this work:

- We introduce a data-driven framework aimed at finding the best model for MPC from calibration experiments
- We specialize this framework for a hierarchical MPC architecture often encountered in industrial applications

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# Bayesian Optimization

## Overview

One of the best *off-the-shelf* global optimization algorithms

- Iteratively updates a **stochastic surrogate model** of the unknown  $J(\theta)$  via Bayesian inference. Typically, a Gaussian Process (GP)
- Balances **exploitation** and **exploration** by optimizing an **acquisition function**  $A(\theta)$  instead of the surrogate model directly
- The acquisition function  $A(\theta)$  favors points with estimated **good performance**  $\rightarrow$  exploitation and/or **high variance**  $\rightarrow$  exploration
- The acquisition function  $A(\theta)$  is (relatively) cheap to evaluate. It is a mathematical object!

# Bayesian Optimization

## Overview

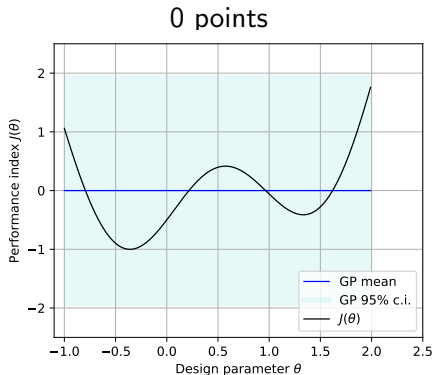
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# Bayesian Optimization

## Gaussian Process

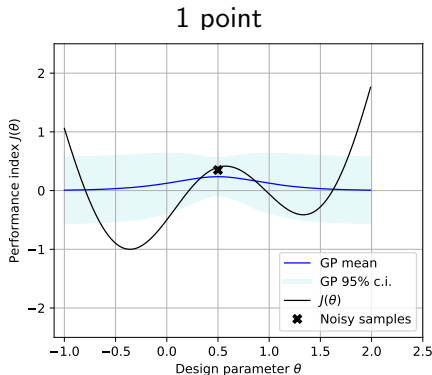
- The function  $J(\theta)$  assumed Gaussian with **prior** mean  $E[J(\theta)] = \mu(\theta)$  and covariance  $\text{cov}[J(\theta_1), J(\theta_2)] = \kappa(\theta_1, \theta_2)$ .
- The **posterior** mean and covariance given a new observation  $(\theta_i, J_i)$  is obtained in closed form



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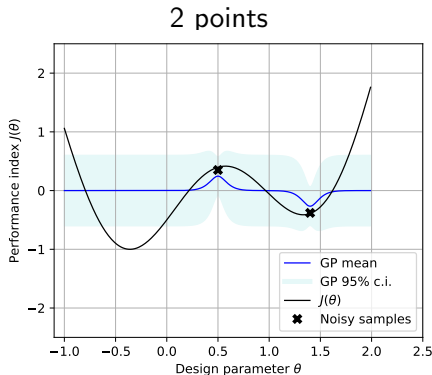




# Bayesian Optimization

## Gaussian Process

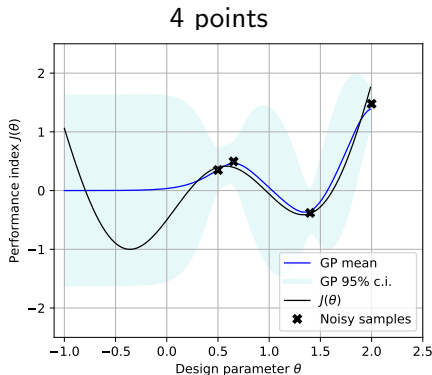
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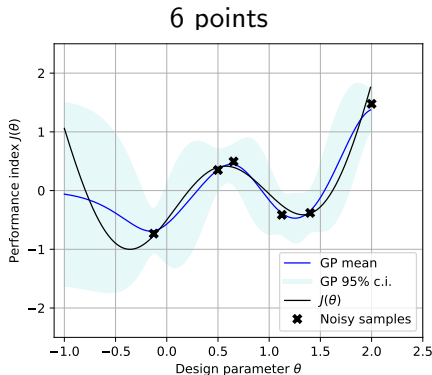
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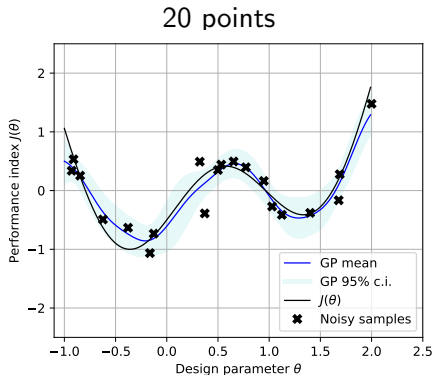
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# Bayesian Optimization

## Acquisition function

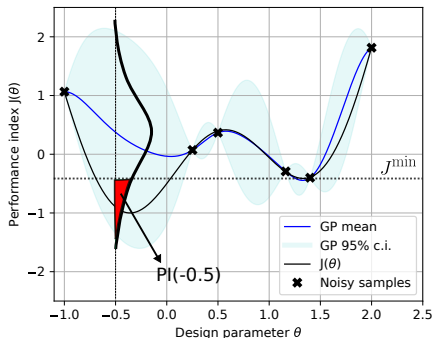
The GP provides the **probability distribution** of  $J(\theta)$  for each parameter  $\theta$ . This probability is used to define an **acquisition function**, e.g.,

Probability of Improvement

Expected improvement

$$A(\theta) = \text{PI}(\theta) = p(J(\theta) \leq J^{\min})$$

$$A(\theta) = \text{EI}(\theta) = \mathbb{E}[\max(0, J^{\min} - J(\theta))]$$



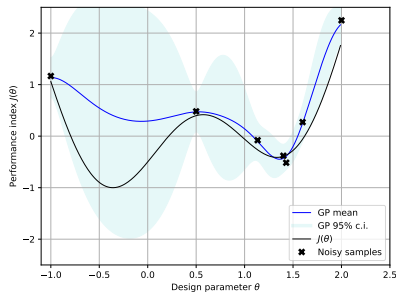
# Bayesian Optimization

## Overview

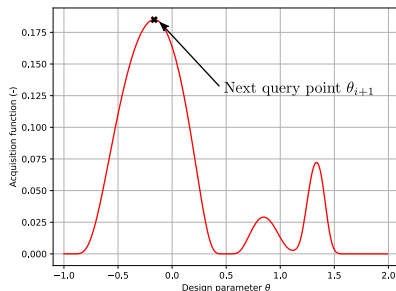
Steps of BO: for  $i = 1, 2, \dots, i_{\max}$

- 1 **Execute** experiment with  $\theta_i$ , measure  $J_i = J(\theta_i) + e_i$
- 2 **Update** the GP model  $\theta \rightarrow J(\theta)$  with  $(\theta_i, J_i)$
- 3 **Construct** acquisition function  $A(\theta)$
- 4 **Maximize**  $A(\theta)$  to obtain next query point  $\theta_{i+1}$

GP at iteration  $i$



$A(\theta)$  at iteration  $i$

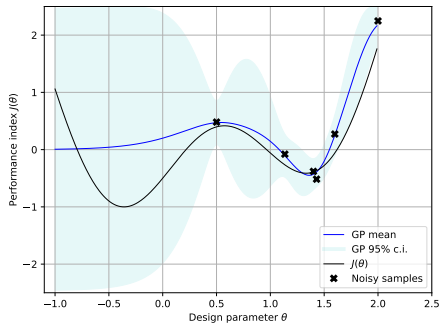


# Bayesian Optimization

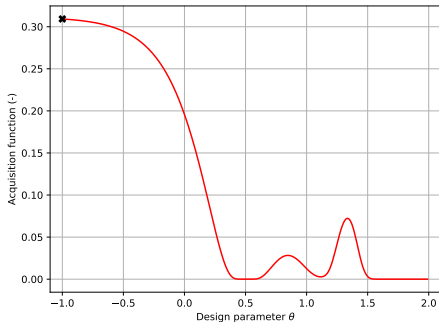
## Example

iteration 6

GP fit



$$A(\theta) = \text{EI}(\theta)$$

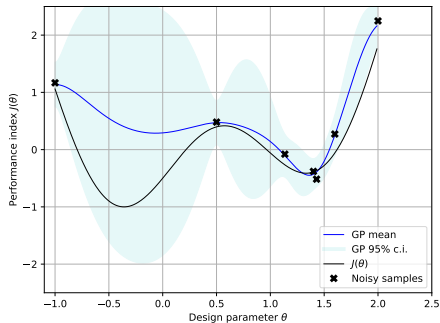


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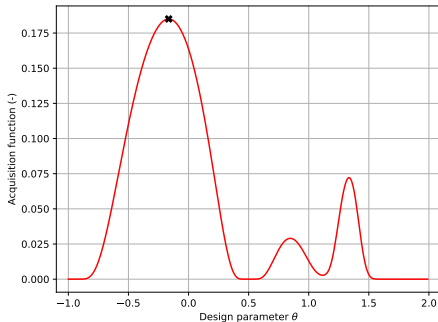
## Example

iteration 7

GP fit



$A(\theta) = \text{EI}(\theta)$



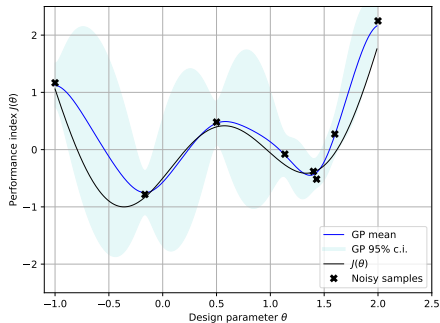


# Bayesian Optimization

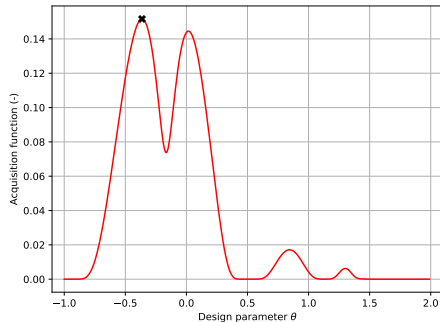
## Example

iteration 8

GP fit



$A(\theta) = \text{EI}(\theta)$

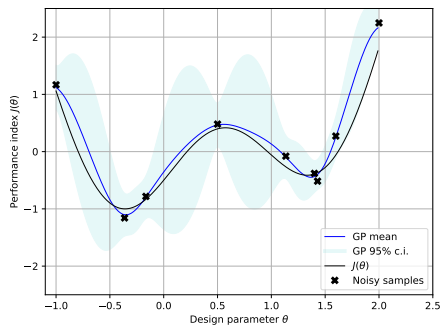


# Bayesian Optimization

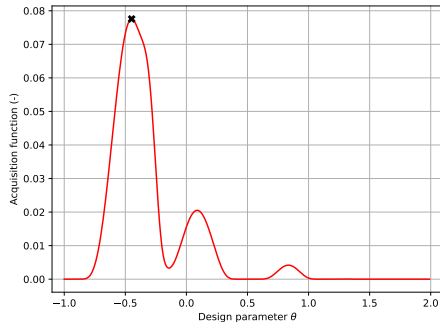
## Example

iteration 9

GP fit



$A(\theta) = \text{EI}(\theta)$

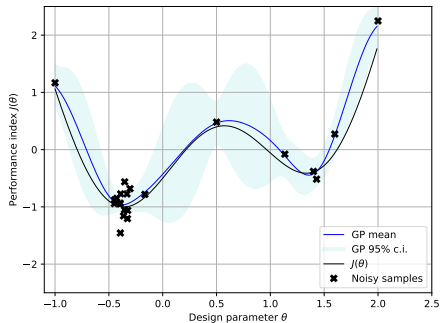


# Bayesian Optimization

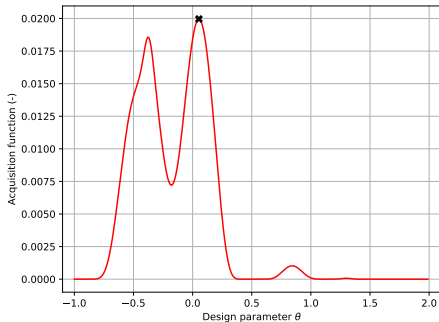
## Example

iteration 20

GP fit



$A(\theta) = \text{EI}(\theta)$

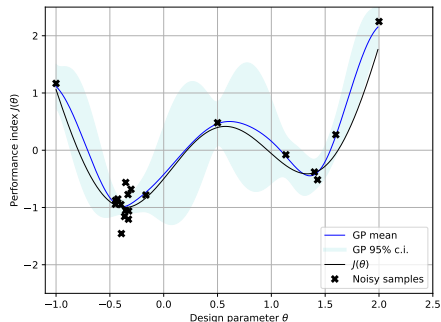


# Bayesian Optimization

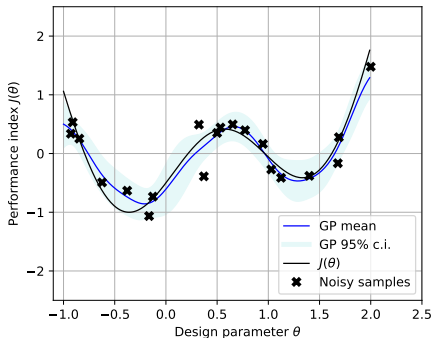
## Example

iteration 10

### Bayesian Optimization



### Random sampling



Thank you.  
Questions?