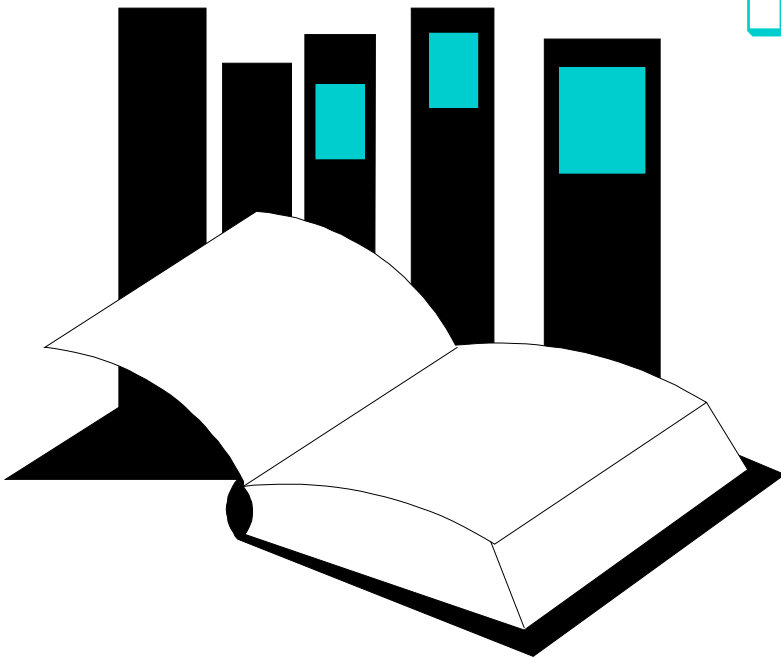


Chapter 4. The Greedy Approach



- ❑ Chapter 4 introduces an algorithm design technique called “*Greedy Approach*”.

CHAPTER 4

Foundations of Algorithms

Greedy Algorithm

□ *Greedy Algorithm*

arrives at a solution by making a *sequence of choices*, each of which simply *looks the best at the moment*

- *Once* each choice has been made and *added* to a partial solution, it *will always* be *in* the solution set.
- Each choice is locally optimal, *but not necessarily globally optimal*.

Greedy Algorithm

□ Example: Giving Change for a Purchase

Solution: a smallest number of bills/coins totaling the amount of change

*~~₩~~7,870 : one ~~₩~~5,000 bill,
two ~~₩~~1,000 bills,
one ~~₩~~500 coin,
three ~~₩~~100 coins,
one ~~₩~~50 coin,
two ~~₩~~10 coins.*

Greedy Algorithm

□ Example: Giving Change for a Purchase

```
while (there are more bills/coins and the instance is not solved)
{
    grab the largest remaining bill; //selection procedure
    if (adding the bill/coin makes the change exceed the amount owed)
        // feasibility check
        reject the bill/coin ;
    else
        add the bill/coin to the change ;
    if (the total value of the change equals the amount owed)
        // solution check
        the instance is solved ;
}
```

Greedy Algorithm

□ General Greedy Approach

- starts with an empty set, and adds items to the set in sequence until the set represents a solution to an instance of a problem
- each iteration consists of the following components:

1. Selection Procedure

chooses the next item to add to the set according to a greedy criteria

2. Feasibility Check

checks whether it is possible to complete the set in such a way as to give a solution to the instance.

3. Solution Check

determines whether the new set constitutes a solution to the instance.

4.1 Minimum Spanning Trees

□ Definitions

□ *Undirected Graph*

- a graph where its edges do not have directions

□ *Connected Graph*

- an undirected graph where there is a path between every pair of vertices

□ *Acyclic Graph*

- a graph with no cycles

□ *Tree*

- an acyclic, connected, undirected graph

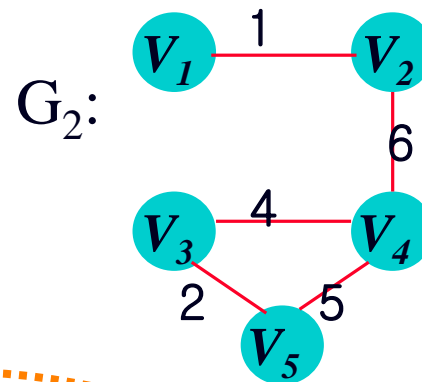
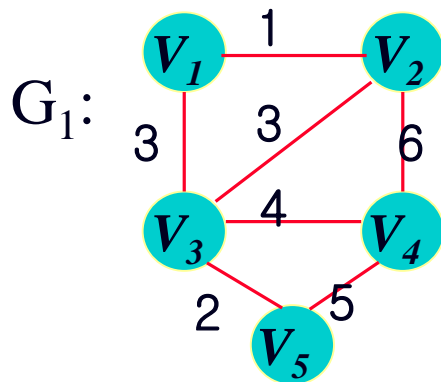
4.1 Minimum Spanning Trees

□ Definitions

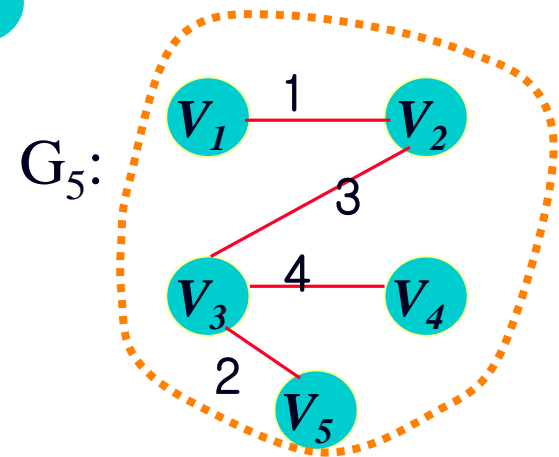
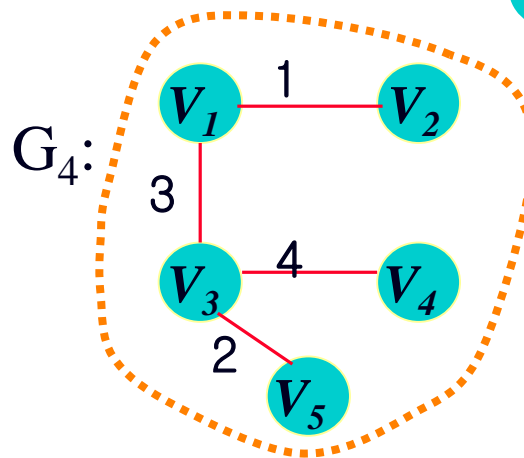
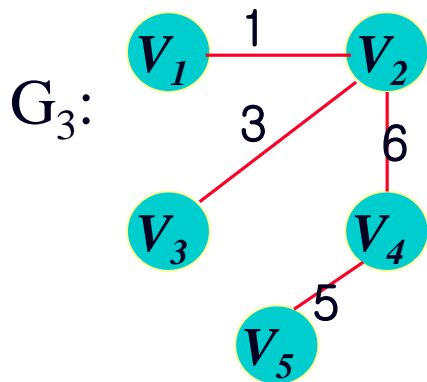
- *Spanning Tree* for undirected graph
 - a connected subgraph that contains all the vertices in G and is a tree
- *Minimum Spanning Tree* for undirected graph
 - a spanning tree of G with *minimum weight*

4.1 Minimum Spanning Trees

□ Examples of Graph



G_4, G_5 :
minimum
spanning trees
of G_1



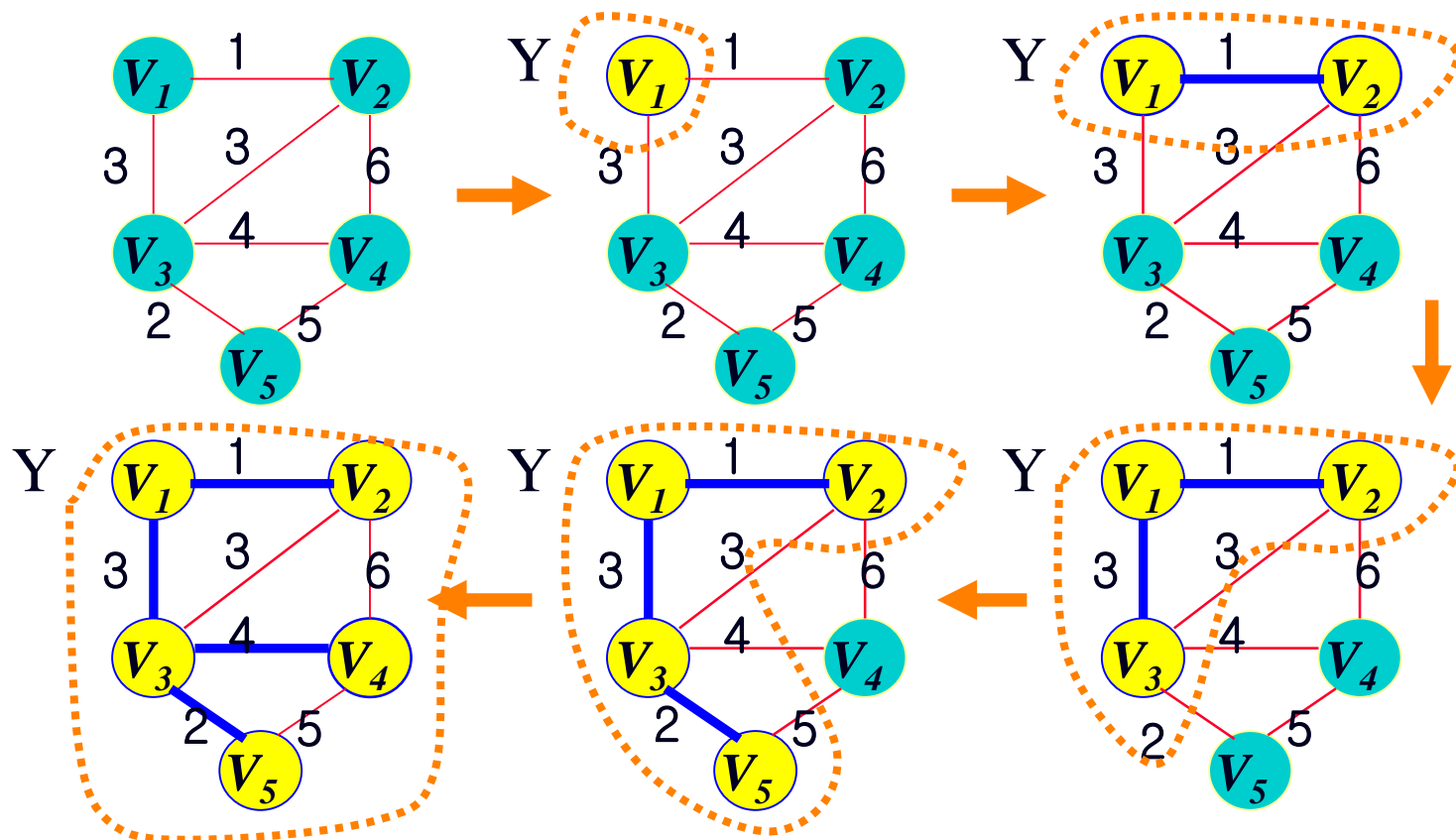
4.1 Minimum Spanning Trees

4.1.1 Prim's Algorithm

```
F =  $\emptyset$  ;  
Y = {v1}  
while (the instance is not solved)  
{  
    select a vertex in V-Y that is nearest to Y ;  
  
    add the vertex to Y ;  
    add the edge to F ;  
  
    if (Y==V)  
        the instance is solved ;  
}
```

4.1 Minimum Spanning Trees

4.1.1 Prim's Algorithm



4.1 Minimum Spanning Trees

4.1.1 Prim's Algorithm

- To find the nearest vertex from Y , we use the following arrays:

$W[i][j]$: Weight table (symmetric)

$nearest[i]$ = index of the vertex in Y nearest to V_i

$distance[i]$ = weight on edge between V_i and the vertex indexed by $nearest[i]$

- $nearest[i]$ is initialized to 1
- $distance[i]$ is initialized to $W[1][i]$
- as vertices are added to Y , two arrays are updated to reference the new vertex in Y nearest to each vertex outside Y

4.1 Minimum Spanning Trees


4.1.1 Prim's Algorithm

```

public static set_of_edges prim(
    int n, const number W[][])
{
    index i, vnear;
    index [ ] nearest = new index[2..n] ;
    number min;
    number [ ] distance = new number[2..n] ;
    edge e;
    set_of_edges F = ∅;

    for (i=2; i<=n; i++) {
        nearest[i]= 1;
        distance[i] = W[1][i];
    }
    repeat( n-1 times ) { • • • }
    return F ;
}

```



```

    min = ∞ ;
    for (i=2; i<=n; i++)
        if (0<= distance[i] < min) {
            min = distance[i] ; vnear = i ;
        }
    e = edge connecting vertices indexed
        by vnear and nearest[vnear] ;
    add e to F ;
    distance[vnear] = -1 ;
    for (i=2; i<=n; i++)
        if (W[i][vnear] < distance[i]) {
            distance[i] = W[i][vnear] ;
            nearest[i] = vnear ;
        }
}

```

4.1 Minimum Spanning Trees

□ Time Complexity of Prim's Algorithm

Basic Operation:

if-statement inside two for-i loops

Input Size:

n, the number of vertices

$$\rightarrow T(n) = 2*(n-1)*(n-1) \in \Theta(n^2)$$

4.1 Minimum Spanning Trees

❑ Does Prim's Algorithm always produce an optimal solution?

- Although greedy algorithms are often *easier to develop* than dynamic programming algorithms, usually it is more *difficult to determine whether or not* a greedy algorithm always produces *an optimal solution*.

➔ *For a greedy algorithm, we usually need a formal proof to show that it actually does.*

4.1 Minimum Spanning Trees

□ Optimality of Prim's Algorithm

- We will use the concept of “a *promising* set of edges” to prove the optimality of Prim's Algorithm.

□ Definition

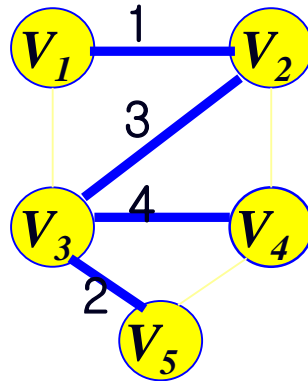
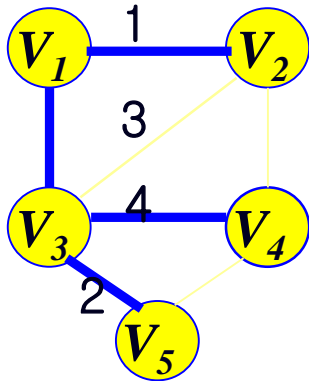
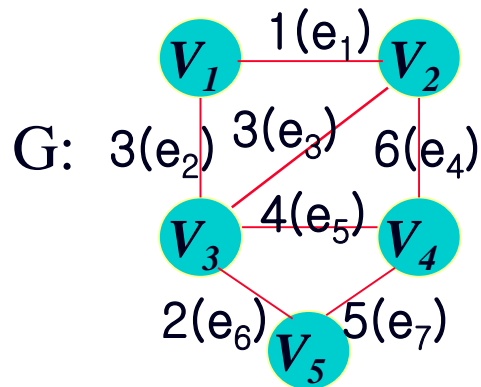
- A subset F of E is called *promising* if edges can be added to it so as to form a minimum spanning tree.

□ Proof:

- Will show by induction that the set F is promising after each iteration of the repeat loop.

4.1 Minimum Spanning Trees

□ Example:



1. $F = \{ \}$ \rightarrow *promising*
2. $F = \{e_4\}$ \rightarrow *Not promising*
3. $F = \{e_1, e_2\}$ \rightarrow *promising*
4. $F = \{e_1, e_2, e_3\}$ \rightarrow *Not promising*
5. $F = \{e_1, e_2, e_5\}$ \rightarrow *promising*
6. $F = \{e_1, e_2, e_5, e_6\}$ \rightarrow *promising*

2 minimum spanning trees of G

4.1 Minimum Spanning Trees

□ Proof of the Optimality of Prim's Algorithm

□ Induction Basis

Obviously, the empty set is *promising*.

□ Induction Hypothesis

Assume that, after a given iteration of the repeat loop, the set of edges so far selected, namely F , is *promising*.

□ Induction Step

We need to show that $F \cup \{e\}$ is *promising*, where e is an edge of minimum weight that connects a vertex in Y to a vertex in $V-Y$.

4.1 Minimum Spanning Trees

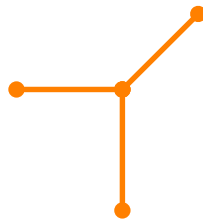
□ Proof of the Optimality of Prim's Algorithm

□ Induction Step - continued

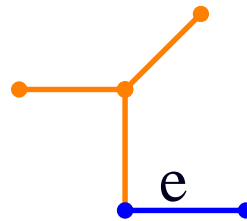
Because F is promising, there must be some set of edges F' such that $F \subseteq F'$ and (V, F') is a minimum spanning tree.

Case 1: $e \in F'$

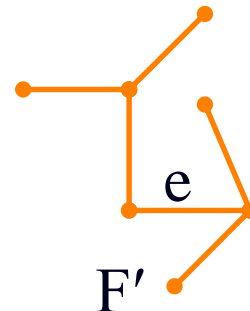
$F \cup \{e\} \subseteq F'$, so $F \cup \{e\}$ is promising. Done.



F



$F \cup \{e\}$



F'

4.1 Minimum Spanning Trees

□ Proof of the Optimality of Prim's Algorithm

□ Induction Step - continued

Case 2: $e \notin F'$

Because (V, F') is a spanning tree, $F' \cup \{e\}$ must contain exactly one cycle and e must be in the cycle. Thus, there must be another edge $e' \in F'$ in the cycle that also connects a vertex in Y to one in $V-Y$.

If we remove e' from $F' \cup \{e\}$, the cycle disappears, which means we have a spanning tree. Because e is an edge of minimum weight that connects a vertex in Y to one in $V-Y$, the weight of e must be less than or equal to that of e' (*in fact they must be equal*).

4.1 Minimum Spanning Trees

□ Proof of the Optimality of Prim's Algorithm

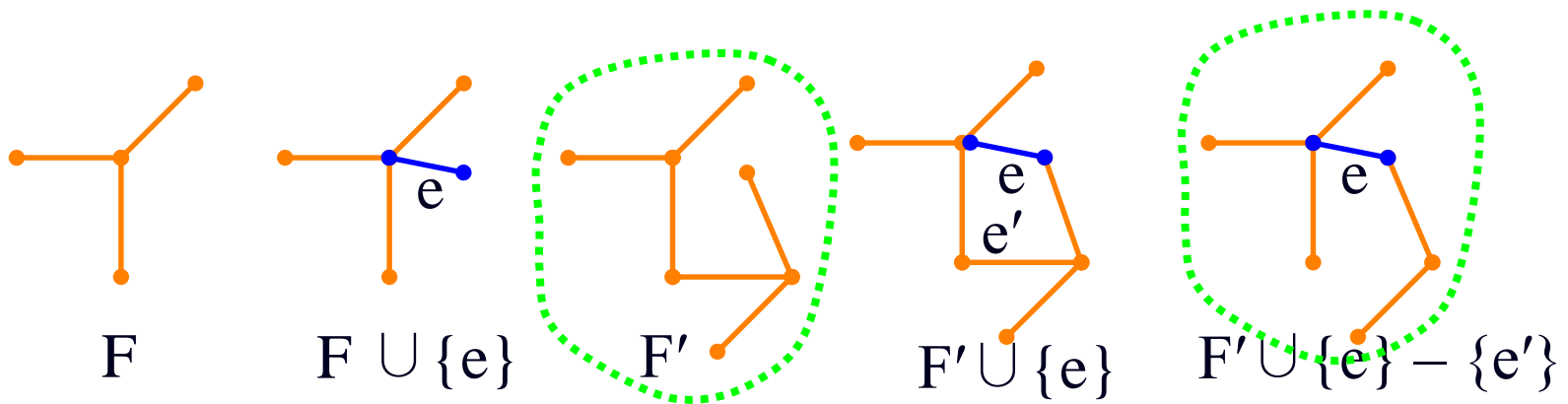
□ Induction Step

Case 2: $e \notin F'$ - continued

So, $F' \cup \{e\} - \{e'\}$ is a minimum spanning tree.

Therefore, $F \cup \{e\} \subseteq F' \cup \{e\} - \{e'\}$,

which means $F \cup \{e\}$ is *promising*.



4.1 Minimum Spanning Trees

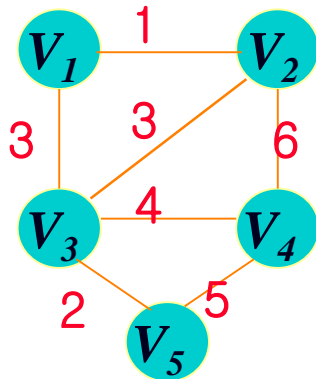
4.1.2 Kruskal's Algorithm

1. $F = \emptyset$;
2. create disjoint subsets of V , one for each vertex and containing only that vertex;
3. sort the edges in E in non-decreasing order ;
4. while (the instance is not solved) {
 select next edge from the sorted list
 if (the edge connects two vertices in disjoint subsets) {
 merge the subsets ;
 add the edge to F ;
 }
 if (all the subsets are merged)
 the instance is solved ;
}

4.1 Minimum Spanning Trees

4.1.2 Kruskal's Algorithm

□ **Example:**



1. Sorted Edges:

(v_1, v_2) 1

(v_3, v_5) 2

(v_1, v_3) 3

(v_2, v_3) 3

(v_3, v_4) 4

(v_4, v_5) 5

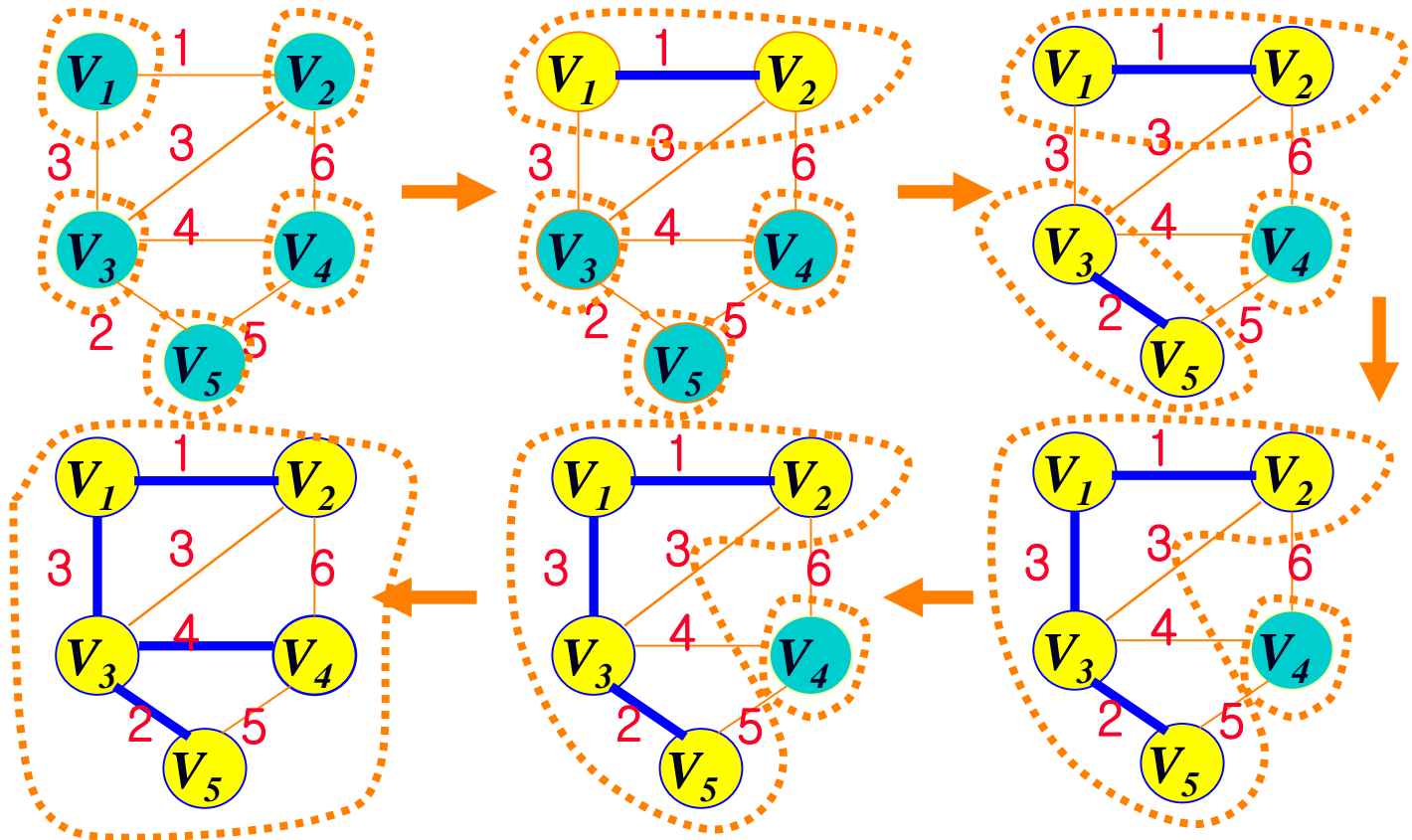
(v_2, v_4) 6

4.1 Minimum Spanning Trees

4.1.2 Kruskal's Algorithm

Sorted Edges

(v_1, v_2)	1
(v_3, v_5)	2
(v_1, v_3)	3
(v_2, v_3)	3
(v_3, v_4)	4
(v_4, v_5)	5
(v_2, v_4)	6



4.1 Minimum Spanning Trees

4.1.2 Kruskal's Algorithm

- To write a formal version of Kruskal's Algorithm, we use the following:
 - *Initial(n)* initializes n disjoint subsets, each of which contains exactly one of the indices between 1 and n
 - *p = find(i)* makes p point to the set containing index i
 - *merge(p,q)* merges the two sets, to which p and q point, into a set.
 - *equal(p,q)* returns true if both p and q point to the same set.

4.1 Minimum Spanning Trees

4.1.2 Kruskal's Algorithm

```

public static set_of_edges kruskal(
    int n, int m, set_of_edges E) {
    index i, j;
    set_pointer p, q ;
    edge e;
    set_of_edges F =  $\emptyset$  ;


```

Sort the m edges in E by weight
in nondecreasing order;

```

    initial(n) ;
    while( |F| < n-1)
    {
        ...
    }
    return F ;
}

```



e = edge with the least weight
not yet considered ;
 i, j = indices of vertices connected by e ;

```

p = find(i) ;
q = find(j) ;
if (! Equal(p,q)) {
    merge(p,q) ;
    add e to F ;
}

```

4.1 Minimum Spanning Trees

□ Time Complexity of Kruskal's Algorithm

Basic Operation:

A comparison operation

Input Size:

n , the number of vertices

m , the number of edges

1. *Time to sort the edges:*

$W(m) \in \Theta(m \lg m)$ using MergeSort

2. *Time in the while loop:*

$W(m) \in \Theta(m \lg m)$ using DisjointSet implementation

4.1 Minimum Spanning Trees

□ Time Complexity of Kruskal's Algorithm

3. Time to initialize n disjoint sets

$$T(n) \in \Theta(n)$$

➔ $W(m,n) \in \Theta(m \lg m)$ where $n-1 \leq m \leq n(n-1)/2$.

➔ Thus, in the worst case, we have

$$W(m,n) \in \Theta(m \lg m) = \Theta(n^2 \lg n^2) = \Theta(n^2 \lg n).$$

4.1 Minimum Spanning Trees

□ Optimality of Kruskal's Algorithm

- Similar to the proof of Prim's Algorithm
- Will use the concept of “a *promising* set of edges” to prove the optimality

4.1 Minimum Spanning Trees

□ Proof of the Optimality of Kruskal's Algorithm

□ Induction Basis

Obviously, the empty set is *promising*.

□ Induction Hypothesis

Assume that, after a given iteration of the repeat loop, the set of edges so far selected, namely F , is *promising*.

□ Induction Step

We need to show that $F \cup \{e\}$ is *promising*, where e is an edge of minimum weight in $E-F$ such that $F \cup \{e\}$ has no cycles.

4.1 Minimum Spanning Trees

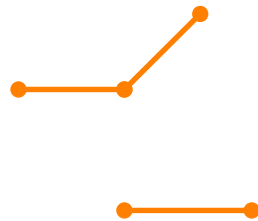
□ Proof of the Optimality of Kruskal's Algorithm

□ Induction Step - continued

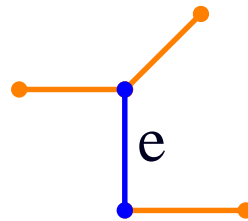
Because F is promising, there must be some set of edges F' such that $F \subseteq F'$ and (V, F') is a minimum spanning tree.

Case 1: $e \in F'$

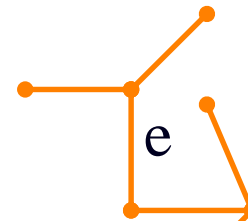
$F \cup \{e\} \subseteq F'$, so $F \cup \{e\}$ is promising. Done.



F



$F \cup \{e\}$



F'

4.1 Minimum Spanning Trees

□ Proof of the Optimality of Kruskal's Algorithm

□ Induction Step - continued

Case 2: $e \notin F'$

Because (V, F') is a spanning tree, $F' \cup \{e\}$ must contain exactly one cycle and e must be in the cycle. Thus, there must be another edge $e' \in F'$ in the cycle that is not in F . That is, $e' \in E - F$.

If we remove e' from $F' \cup \{e\}$, the cycle disappears, which means we have a spanning tree. Because e is an edge of minimum weight that is not in F , the weight of e must be less than or equal to that of e' (*in fact they must be equal*).

4.1 Minimum Spanning Trees

□ Proof of the Optimality of Kruskal's Algorithm

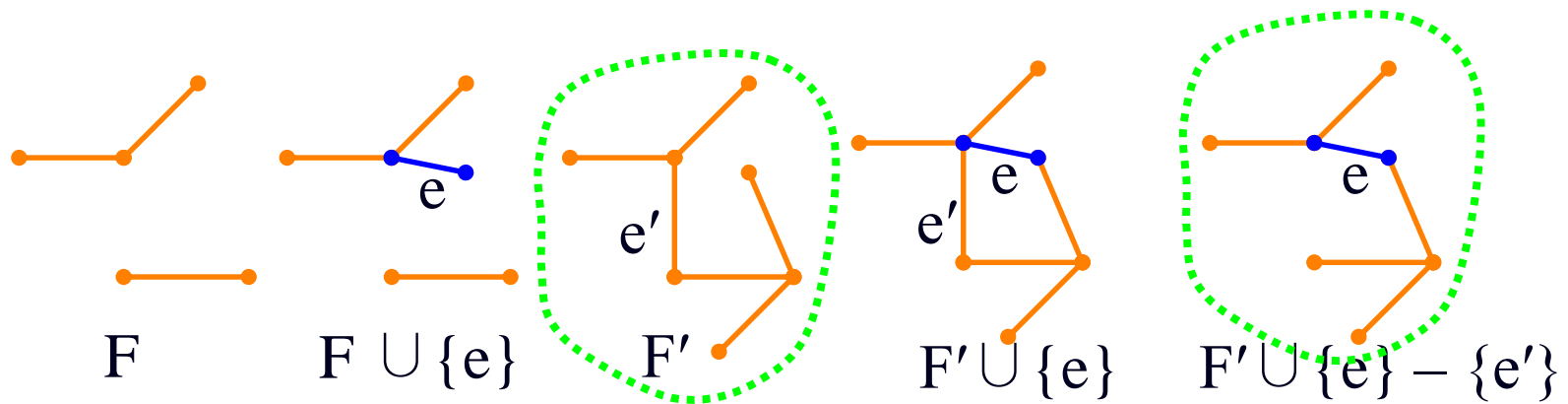
□ Induction Step

Case 2: $e \notin F'$ - continued

So, $F' \cup \{e\} - \{e'\}$ is a minimum spanning tree.

Therefore, $F \cup \{e\} \subseteq F' \cup \{e\} - \{e'\}$,

which means $F \cup \{e\}$ is promising.



4.1 Minimum Spanning Trees

4.1.3. Prim's Algorithm vs. Kruskal's Algorithm

□ Prim's Algorithm

$$T(n) \in \Theta(n^2)$$

□ Kruskal's Algorithm

$$W(m,n) \in \Theta(m \lg m) \text{ where } n-1 \leq m \leq n(n-1)/2.$$

- ➔ 1. If m is close to $n-1$, i.e., the graph is *sparse*, then $\Theta(m \lg m)$ becomes $\Theta(n \lg n)$, which is *better than* $\Theta(n^2)$.
- ➔ 2. If m is close to $n(n-1)/2$, i.e., the graph is *dense*, then $\Theta(m \lg m)$ becomes $\Theta(n^2 \lg n)$, which is *worse than* $\Theta(n^2)$.

4.4 Huffman Code

□ Huffman Code

- an efficient encoding method for data compression
- uses a *variable-length binary code* to represent a text file

Note:

□ Variable-Length Binary Code

- represents different characters using *different* numbers of bits

□ Fixed-Length Binary Code

- represents each character using the *same* number of bits

4.4 Huffman Code

❑ Fixed-Length vs. Variable-Length Binary Code

Example: Character Set { a, b, c },
String “ababcbbbc”

❑ Fixed-Length Binary Code

➔ a: 00, b: 01, c: 11

ababcbbbc: 000100011101010111 - **18** bits

❑ Variable-Length Binary Code

➔ a: 10, b: 0, c: 11

ababcbbbc: 1001001100011 - **13** bits

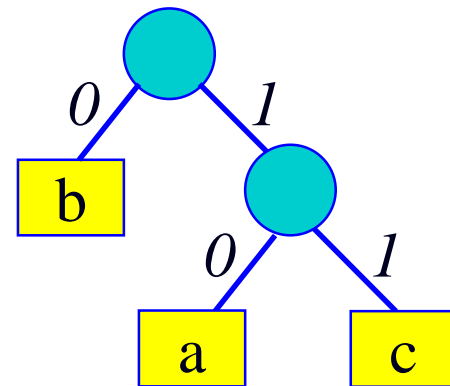
4.4 Huffman Code

4.4.1 Prefix Code

- a variable length-code in which *no codeword* for one character constitutes the *beginning* of the codeword for *another character*

□ **Example:**

➔ a: 10, b: 0, c: 11

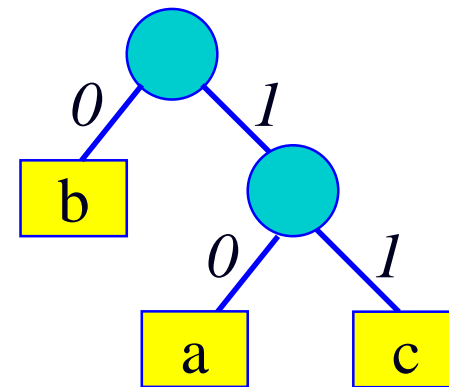


4.4 Huffman Code

- The number of bits to encode a text file
 - Given the binary tree T corresponding to some prefix code,

$$\text{minimize } \sum_{i=1}^n \text{frequency}(v_i) * \text{depth}(v_i)$$

$$\begin{aligned} & \text{frequency}(b) * 1 \\ & + \text{frequency}(a) * 2 \\ & + \text{frequency}(c) * 2 \end{aligned}$$



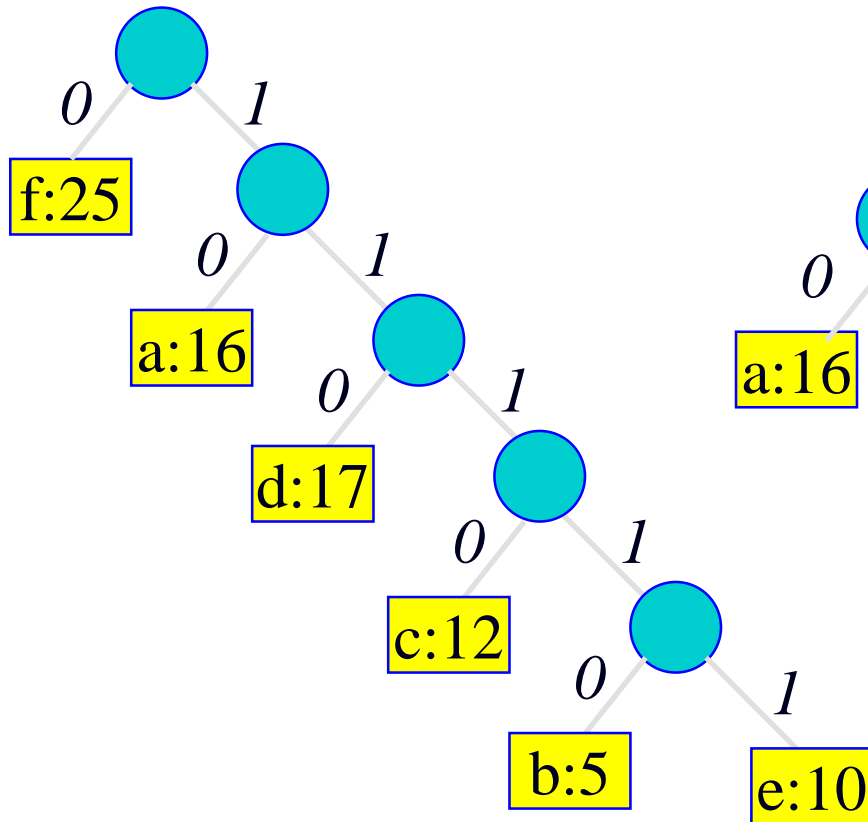
4.4 Huffman Code

Character	Frequency	Code 1 (Fixed)	Code 2 (variable)	Code 3 (Huffman)
a	16	000	10	00
b	5	001	11110	1110
c	12	010	1110	110
d	17	011	110	01
e	10	100	11111	1111
f	25	101	0	10

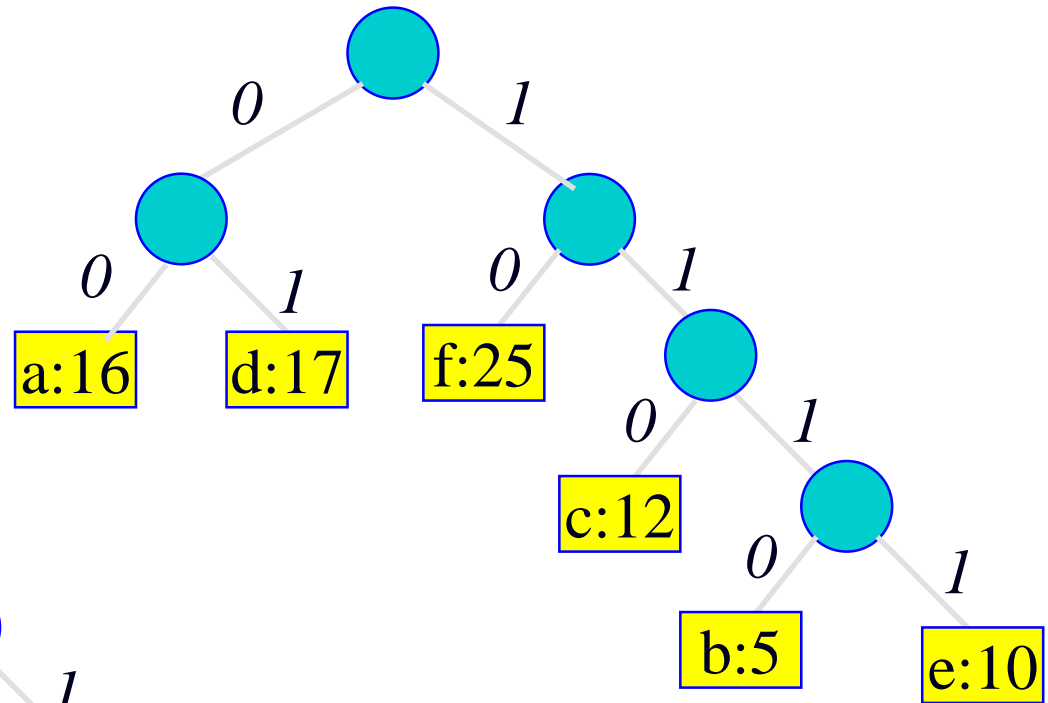
$$\sum \text{frequency}(v) * \text{depth}(v) = \quad 255 \quad 231 \quad \textcolor{blue}{212}$$

4.4 Huffman Code

Code 2



Code 3



4.4 Huffman Code

4.4.2 Huffman's Algorithm

Regard characters as a forest with n single-node trees

repeat


 merge two trees with least frequencies

until it becomes a single tree

4.4 Huffman Code

4.4.2 Huffman's Algorithm

```
for (i = 0; i < n; i++) {  
    remove(PQ, p);  
    remove(PQ, q);  
    r = new nodetype();  
    r.left = p;  
    r.right = q;  
    r.frequency = p.frequency + q.frequency;  
    insert(PQ, r);  
}  
remove(PQ, r);  
return r;
```

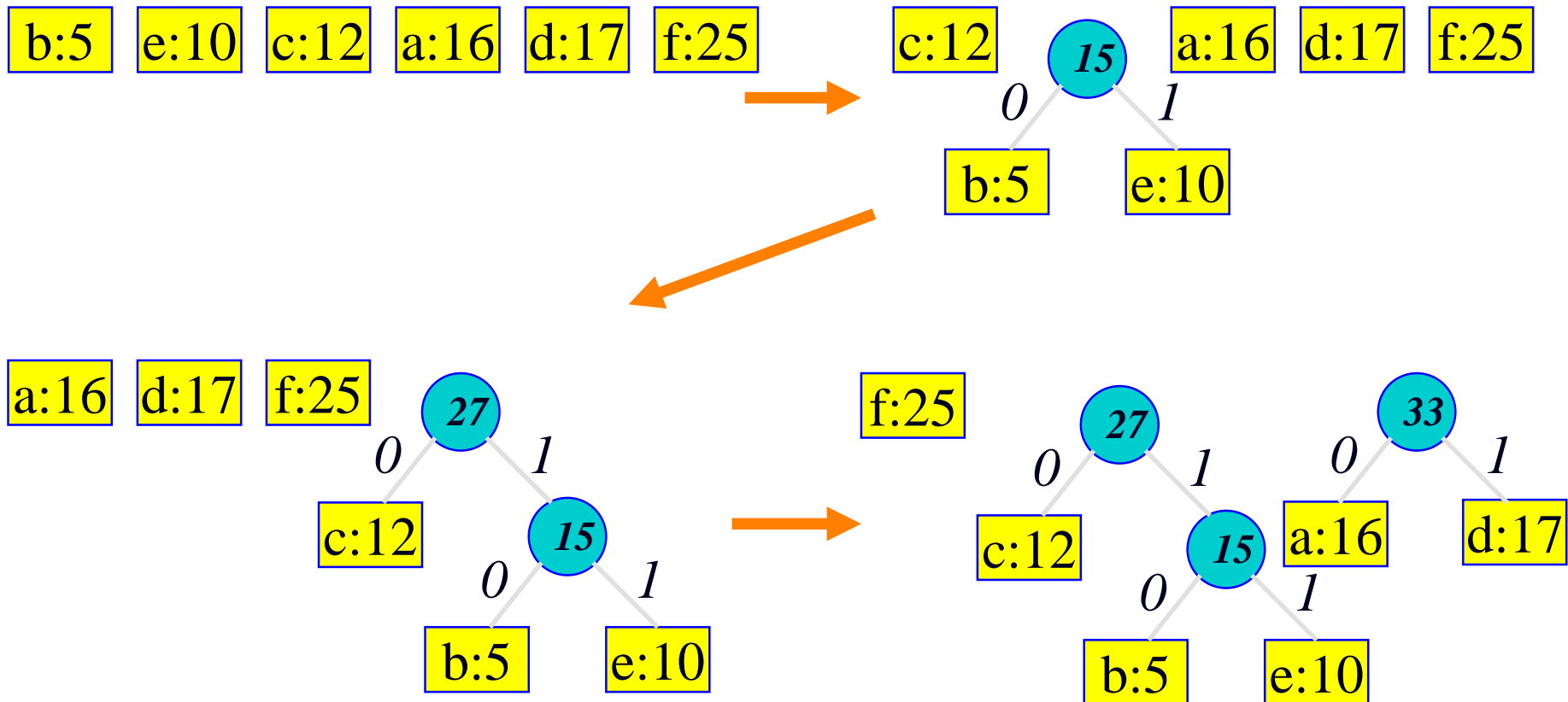


```
Public class nodetype  
{  
    char symbol;  
    int frequency;  
  
    nodetype left;  
    nodetype right;  
}
```

Time complexity
 $O(n \log n)$

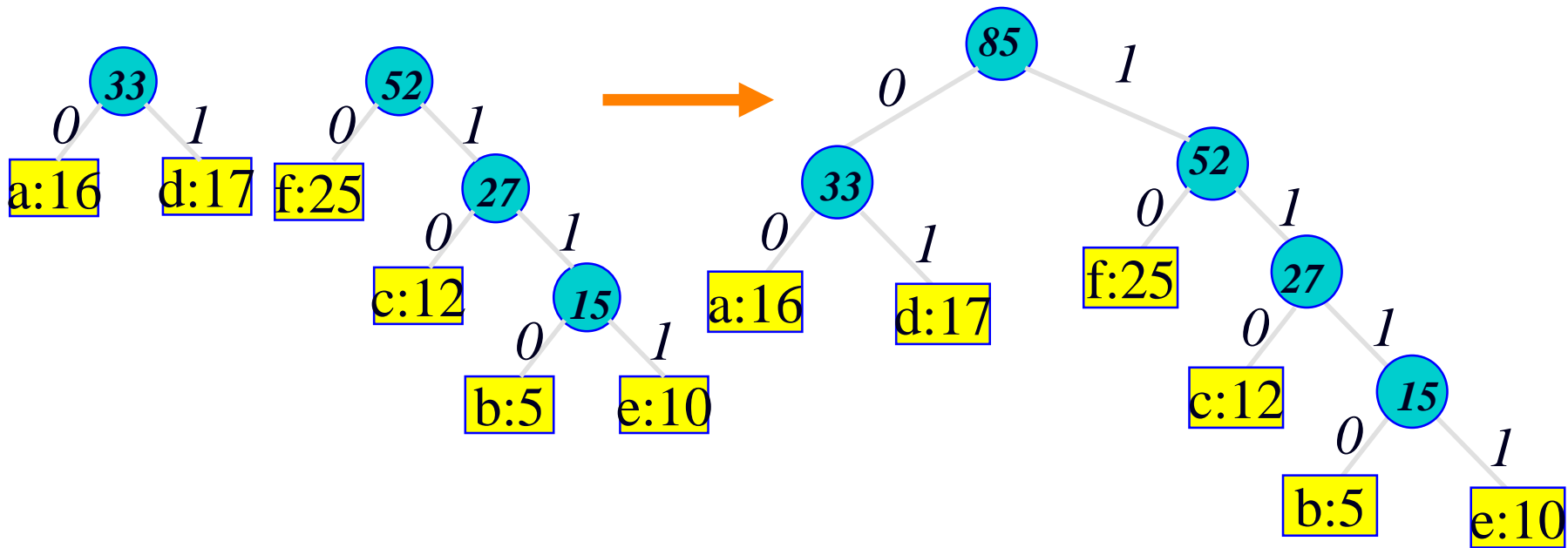
4.4 Huffman Code

□ Example



4.4 Huffman Code

□ Example (cont'd)



4.4 Huffman Code

□ Proof of the Optimality of Huffman's Algorithm

□ Induction Basis

- The set of single nodes in the 0th step
→ branches in an *optimal prefix binary tree*

□ Induction Hypothesis

- The set of trees in the i^{th} step
→ branches in an optimal prefix binary tree T

□ Induction Step

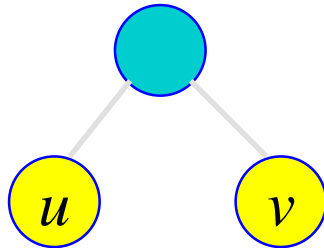
- u & v : roots of trees combined in the $(i+1)^{\text{th}}$ step
- NEXT PAGE..

4.4 Huffman Code

□ Proof of the Optimality of Huffman's Algorithm

□ Induction Step – continued

Case 1:  **in T**

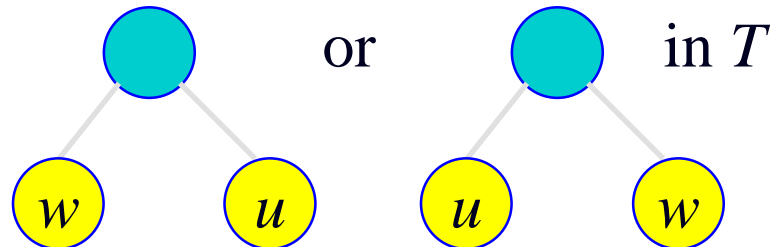


Done.

Case 2: parent of $u \neq$ parent of v in T

WLOG, $\text{depth}(u) \geq \text{depth}(v)$ in T

There exists w such that



4.4 Huffman Code

□ Proof of the Optimality of Huffman's Algorithm

□ Induction Step – continued

$\text{frequency}(w) \geq \text{frequency}(v)$ – *why?*

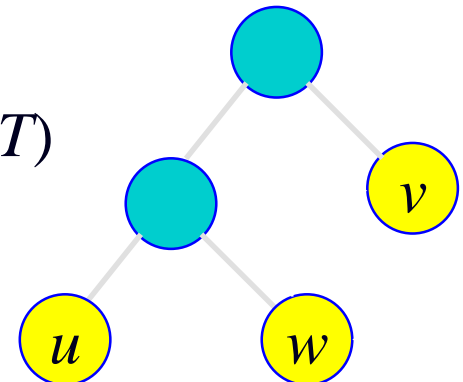
$\text{depth}(w) \geq \text{depth}(v)$ in T

Create a new tree T' by swapping the positions of the branches rooted at v & w .

$$\text{cost}(T') = \text{cost}(T) + (\text{depth}(w) - \text{depth}(v)) * \text{frequency}(v)$$

$$(\text{frequency}(v) - \text{frequency}(w)) \leq \text{cost}(T)$$

Hence, T' is optimal.



4.5 Knapsack Problem

□ A Greedy Approach to the 0-1 Knapsack Problem

□ The 0-1 Knapsack Problem

Given n items, let

$$S = \{ item_1, item_2, \dots, item_n \}$$

w_i = weight of $item_i$

p_i = profit of $item_i$

W = maximum weight the knapsack can hold,

where w_i , p_i , and W are positive integers.

Determine a **subset A** of S such that

$$\sum_{item_i \in A} p_i \text{ is } \textbf{maximized} \text{ subject to } \sum_{item_i \in A} w_i \leq W.$$

4.5 Knapsack Problem

□ A Greedy Approach to the 0-1 Knapsack Problem

□ A Brute-Force Solution to The 0-1 Knapsack Problem

1. Consider all possible subsets of S .
 2. Discard those subsets whose total weight $> W$.
 3. Of those remaining, take one with the max total profit.
- ➔ Since there are 2^n subsets containing up to n items, the complexity is *exponential in n* .

4.5 Knapsack Problem

□ A Greedy Approach to the 0-1 Knapsack Problem

□ A Simple Greedy Approach

Idea: Take items in *non-increasing order* according to *profit*.

➔ This approach wouldn't work very well if the most profitable item had a large weight in comparison with its profit.

Example:

item₁ : \$1 M and 25 Kg

item₂ : \$0.8 M and 15 Kg

item₃ : \$0.5 M and 10 Kg

item₄ : \$0.24 M and 8 Kg

maximum weight = 30 Kg

➔ **Greedy Solution:**

{item₁} (Profit : \$ 1M)

➔ **Optimal Solution:**

{item₂, item₃}
(Profit : \$ 1.3M)

4.5 Knapsack Problem

□ A Greedy Approach to the 0-1 Knapsack Problem

□ Another Simple Greedy Approach

Idea: Take items in *non-decreasing order* according to *weight*.

➔ This approach would fail badly when the light items have small profits compared with their weights.

Example:

item₁ : \$1 M and 25 Kg
item₂ : \$0.8 M and 15 Kg
item₃ : \$0.5 M and 10 Kg
item₄ : \$0.24 M and 8 Kg
maximum weight = 30 Kg

➔ **Greedy Solution:**

{item₃, item₄} (Profit: \$ 0.74M)

➔ **Optimal Solution:**

{item₂, item₃} (Profit: \$ 1.3M)

4.5 Knapsack Problem

□ A Greedy Approach to the 0-1 Knapsack Problem

□ More Sophisticated Greedy Approach

Idea: Take items in *non-increasing order* according to *profit per unit weight*.

Example 1:

item₁ : \$1 M and 25 Kg → \$40000/Kg

item₂ : \$0.8 M and 15 Kg → \$60000/Kg

item₃ : \$0.5 M and 10 Kg → \$50000/Kg

item₄ : \$0.24 M and 8 Kg → \$30000/Kg

maximum weight = 30 Kg

→ **Greedy Solution:** {item₂, item₃} (Profit: \$ 1.3M) → **Optimal**

4.5 Knapsack Problem

□ A Greedy Approach to the 0-1 Knapsack Problem

□ More Sophisticated Greedy Approach

Idea: Take items in *non-increasing order* according to *profit per unit weight*.

Example 2:

item₁ : \$5 M and 5 Kg → \$1 M/Kg

item₂ : \$6 M and 10 Kg → \$0.6 M/Kg

item₃ : \$14 M and 20 Kg → \$0.7 M/Kg

maximum weight = 30 Kg

➔ **Greedy Solution:** {item₁, item₃} (Profit: \$ 19 M)

➔ **Optimal Solution:** {item₂, item₃} (Profit: \$ 20 M)

4.5 Knapsack Problem

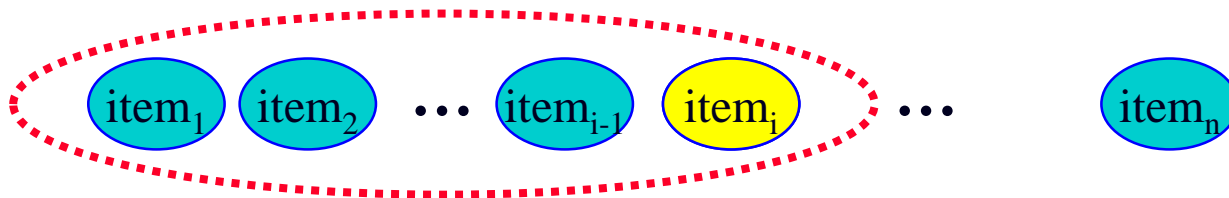
□ A Greedy Approach to the *fractional* Knapsack Problem

➔ If we allow a *fraction of item* to be put in the knapsack, the greedy approach based on the *profit per unit weight* produces an *optimal* solution.

4.5 Knapsack Problem

□ Dynamic Programming Approach to the 0-1 Knapsack Problem

Let $P[i][w]$ be the optimal profit obtained from choosing items only from the first i items under the restriction that the *total weight* cannot exceed w .



$$P[i][w] = \begin{cases} \max(P[i-1][w] , p_i + P[i-1][w-w_i]) & \text{if } w_i \leq w \\ P[i-1][w] & \text{if } w_i > w \end{cases}$$

4.5 Knapsack Problem

□ Dynamic Programming Approach to the 0-1 Knapsack Problem

$$P[i][w] = \begin{cases} \max(P[i-1][w], p_i + P[i-1][w-w_i]) & \text{if } w_i \leq w \\ P[i-1][w] & \text{if } w_i > w \end{cases}$$

➔ The value we are looking for is $P[n][W]$.

➔ We can determine this value using a two dimensional array $P[0..n][0..W]$ where

$$\begin{aligned} P[0][w] &= 0 & 0 \leq w \leq W \\ P[i][0] &= 0 & 0 \leq i \leq n \end{aligned}$$

4.5 Knapsack Problem

□ Dynamic Programming Approach

$$P[i][w] = \begin{cases} \max(P[i-1][w], p_i + P[i-1][w-w_i]) & \text{if } w_i \leq w \\ P[i-1][w] & \text{if } w_i > w \end{cases}$$

P	0	1	2	...	$W-w_n$...	W
0	0	0	0	0	0	0	0
1	0						
2	0						
...							
i							
$n-1$?	?
n	0						?

➔ 2^{n-1} entries:

$P[1][W], P[1][W - w_1], \dots$

$P[1][W - w_n - w_{n-1} \dots - w_3],$

$P[1][(W - w_n - w_{n-1} \dots - w_3) - w_2]$

➔ 2 entries: $P[n-1][W], P[n-1][W - w_n]$

➔ 1 entry: $P[n][W]$

$$\therefore 1 + 2 + 4 + \dots + 2^{n-1} \in \Theta(2^n)$$