# Topic 5

**Space and Time Tradeoffs** 

20 mg 1 9 vie dies Led 1

### Space-for-time tradeoffs



#### Two varieties of space-for-time algorithms:

- input enhancement preprocess the input (or its part) to store some info to be used later in solving the problem
  - counting sorts (Ch. 7.1)
  - **1** string searching algorithms
- prestructuring preprocess the input to make accessing its elements easier
  - hashing
  - indexing schemes (e.g., B-trees)

### Review: String searching by brute force

pattern: a string of m characters to search for

text: a (long) string of n characters to search in

#### Brute force algorithm

**Step 1** Align pattern at beginning of text

- Step 2 Moving from left to right, compare each character of pattern to the corresponding character in text until either all characters are found to match (successful search) or a mismatch is detected
- Step 3 While a mismatch is detected and the text is not yet exhausted, realign pattern one position to the right and repeat Step 2

  Time complexity (worst-case): O(mn)

### String searching by preprocessing



Several string searching algorithms are based on the input enhancement idea of preprocessing the pattern

- **Knuth-Morris-Pratt (KMP)** algorithm preprocesses pattern left to right to get useful information for later searching

  O(m+n) time in the worst case
- **8** Boyer Moore algorithm preprocesses pattern right to left and store information into two tables

O(m+n) time in the worst case

**A** Horspool's algorithm simplifies the Boyer-Moore algorithm by using just one table

### Horspool's Algorithm



#### A simplified version of Boyer-Moore algorithm:

- preprocesses pattern to generate a shift table that determines how much to shift the pattern when a mismatch occurs
- always makes a shift based on the text's character *c* aligned with the <u>last</u> compared (mismatched) character in the pattern according to the shift table's entry for *c*



### How far to shift?

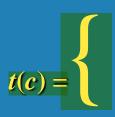


Lo	ook at first (rightmost) character in text that was compared
	The character is not in the pattern
	BAOBAB (c not in pattern)
શ	The character is in the pattern (but not the rightmost)
	BAOBAB 3
	A
	الم منكور عائن افرب وا لا
ઈ	The rightmost characters do match
	BAOBAB 2

### Shift table



**Q** Shift sizes can be precomputed by the formula



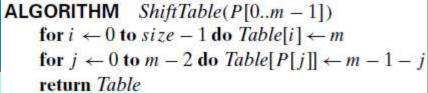
distance from c's rightmost occurrence in pattern among its first m-1 characters to its right end

pattern's length m, otherwise

by scanning pattern before search begins and stored in a table called *shift table*. After the shift, the right end of pattern is t(c) positions to the right of the last compared character in text.

**Q** Shift table is indexed by text and patte<u>rn alphabet</u>

Eg, for BAOBAB:



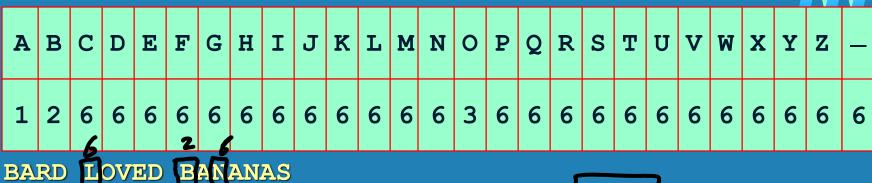
															turn										
Α	В	С	D	E	F	G	Н	Ι	J	K	L	M	N	0	P	Q	R	S	Т	U	V	W	X	Y	Z
$\vdash$																									
1	2	6	6	6	6	6	6	6	6	6	6	6	6	3	6	6	6	6	6	6	6	6	6	6	6

### Horspool's algorithm



```
ALGORITHM HorspoolMatching(P[0..m-1], T[0..n-1])
    //Implements Horspool's algorithm for string matching
    //Input: Pattern P[0..m-1] and text T[0..n-1]
    //Output: The index of the left end of the first matching substring
              or -1 if there are no matches
   -ShiftTable(P[0..m-1]) //generate Table of shifts
                                  //position of the pattern's right end
    i \leftarrow m-1
    while i \le n - 1 do
        k \leftarrow 0
                                  //number of matched characters
        while k \le m - 1 and P[m - 1 - k] = T[i - k] do
            k \leftarrow k + 1
        if k = m
        else i \leftarrow i + Table[T[i]] S hift
    return -1 \times
```

### Example of Horspool's algorithm



BARD LOVED BANANAS
BAOBAB
BAOBAB
BAOBAB



#### BAOBAB (unsuccessful search)

character c	Α	В	С	D	Е	F		R		Z	_
shift $t(c)$	4	2	6	6	1	6	6	3	6	6	6

The actual search in a particular text proceeds as follows:

# BARBER



### Hashing



- A very efficient method for implementing a dictionary, i.e., a set with the operations:
  - t find
  - **7** insert
  - 3 delete

A dictionary returns data (called element) when a key is passed. Example: Given a phone number, return the caller's name. Key: phone number; Element: caller's name

- **8** Based on representation-change and space-for-time tradeoff ideas
- **A** Important applications:
  - \ \_ symbol tables
  - databases (extendible hashing)

### Caller ID Problem



#### Given a phone number, return the caller's name

<u>Key</u>

phone number

**Element** 

caller's name

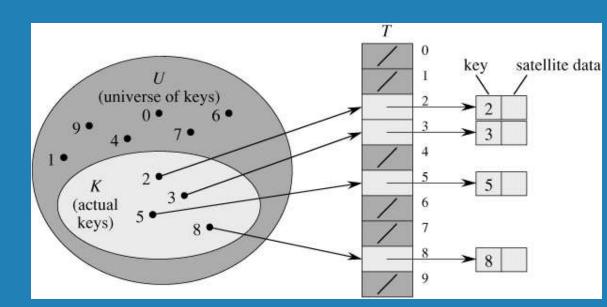
#### **Q** Solutions

- Use a linked list
- Use a balanced binary search tree
- Direct Access Table

#### DAT

#### **Direct Access Table**

- Key becomes address of the record.
- Extremely Efficient
  - Size of array becomes extremely large if a key value is large



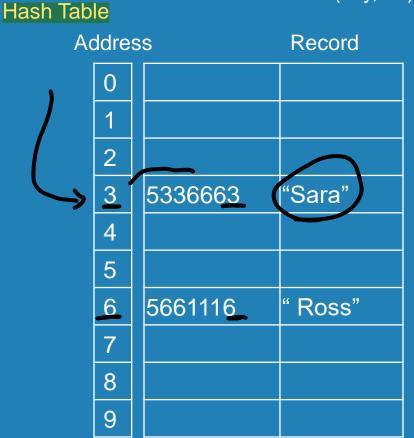
### **DAT vs Hash Table**



#### Direct Access Table

Address	Record
5336663	"Sara"
5661116	"Ross"

Hash Function = mod(key, 10)



Non-numeric keys can be converted to numeric values, for example by adding the ASCII values of all characters of the key.

#### Hash tables and hash functions



- **Nashing:** The idea is to map keys of size *n* into a *hash table* of size m.
- **Nash Function:** A predefined function for mapping

 $h: K \to \text{location (cell) in the hash table}$ 

- **Q** Generally, a hash function should:
  - **1.** be easy to compute
  - 2 distribute keys about evenly throughout the hash table
- **Some hash functions**

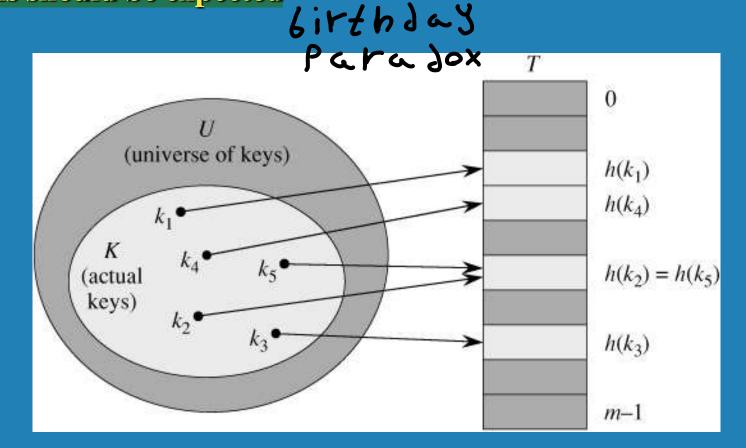
**⁴** • mod

- حدول
- L Truncation: e.g. keep 3 right most digits
- Folding: e.g. 123|456|789: add them and take mod.
- **Y** Squaring: e.g. square and truncate
- **S** Radix conversion: e.g. 1234 treat it to be base 11, truncate if necessary.

### **Collisions**

# خعارض

- و ا کار کندی  $\mathcal{E}$  ا کار کن
- collisions should be expected



### Handling Collisions 5



#### Two principal hashing schemes handle collisions differently:

- **Q** Open hashing
  - each cell is a header of linked list of all keys hashed to it البعث والأماني
- **Q** Closed hashing
  - one key per cell
  - in case of collision, finds another cell by
    - linear probing: use next free bucket
    - Quadratic Probing: use next free bucket distant by 1, 4, 9, 16, .... positions
    - double hashing: use second hash function to compute increment

### Open hashing (Separate chaining)

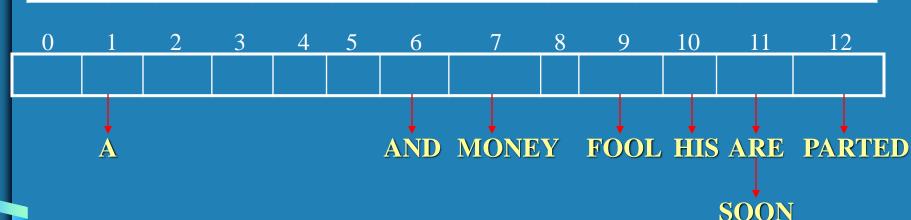


Keys are stored in linked lists <u>outside</u> a hash table whose elements serve as the lists' headers.

**Example:** A, FOOL, AND, HIS, MONEY, ARE, SOON, PARTED

h(K) = sum of K's letters' positions in the alphabet MOD 13

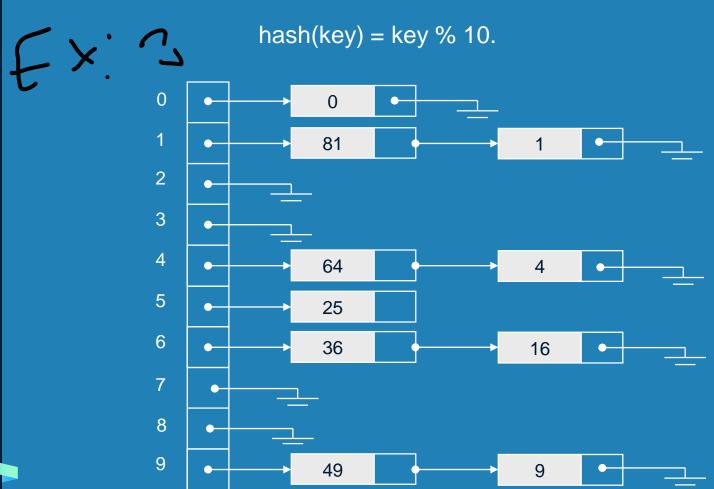
Key	A	FOOL	AND	HIS	MONEY	ARE	SOON	PARTED
h(K)	1	9	6	10	7	11	11	12



### Open hashing (Separate chaining)



Keys: 0, 1, 4, 9, 16, 25, 36, 49, 64, 81



### Open hashing (cont.)



- If hash function distributes keys uniformly, average length of linked list will be  $\alpha = n/m$ . This ratio is called *load factor*.
- **A** For ideal hash functions, the average numbers of probes in successful, S, and unsuccessful searches, U:

$$S \approx 1 + \alpha/2$$
,  $U = \alpha$  (CLRS, Ch. 11)

Toad α is typically kept small (ideally, about 1) مر مند المسافة لكن كفاءة سينة

**Q** Open hashing still works if n > m

Disadvantage: Requires the implementation of a second data structure, a linked list using pointers.

### Closed hashing (Open addressing)



#### Keys are stored inside a hash table.

Key	A	FOOL	AND	HIS	MONEY	ARE	SOON	PARTED
h(K)	1	9	6	10	7	11	11	12

0	1	2	3	4	5	6	7	8	9	10	11/	ے <sub>12</sub>
PARTED	A					AND	MONEY		FOOL	HIS	ARE	SOON

- $\mathfrak{A}$  Try slot hash(x) % S  $\mathfrak{I}$   $\mathfrak{I}$
- و If full then try (hash(x) + 1)% S المراب إلى بعد المعال الم
- If full, then try (hash(x) + 2) % S
- Q If full, then try (hash(x) + 3) % S

...

If last slot is full then the process starts again from slot 1 (wrap around)



## Closed hashing (Open addressing)

Insert items with keys:

89, 18, 49, 58, 9 into an empty hash table using linear probing



hash	(	89,	10	)	= 9	)
hash	(	18,	10	)	= 8	3
hash	(	49,	10	)	= 9	)
hash	(	58,	10	)	= 8	3
hash	(	9.	10	)	= 9	)

After insert 89 After insert 18 After insert 49 After insert 58 After insert 9

0			
1			
2			
3			
4			
5			
6			
7			
8		18	
9	89	89	

49	
18	
89	

49	49
58	58
	9
18	18
89	89

### Closed hashing (cont.)



- **Q** Does not work if n > m
- **Avoids pointers**
- الحدزى حربياشر Deletions are not straightforward
- Number of probes to find/insert/delete a key depends on load factor  $\alpha = n/m$  (hash table density) and collision resolution strategy. For linear probing:

$$S = (\frac{1}{2}) (1 + \frac{1}{(1 - \alpha)})$$
 and  $U = (\frac{1}{2}) (1 + \frac{1}{(1 - \alpha)^2})$ 

As the table gets filled (α approaches 1), number of probes in linear probing increases dramatically:

	8	U
$\alpha$	$\frac{1}{2}(1+\frac{1}{1-\alpha})$	$\frac{1}{2}(1+\frac{1}{(1-\alpha)^2})$
50%	1.5	2.5
50% 75%	2.5	8.5
90%	5.5	50.5