

DIP Homework Assignment #4

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Problem 1: DIGITAL HALFTONING

(a) (10 pt) According to the dither matrix I_2 , please perform dithering to obtain a binary image `result1.png`.

```
I2 = np.array([[1, 2], [3, 0]], dtype = 'uint8')
N = len(I2)
threshold = 255 * (I2 + 0.5) / (N * N)
threshold
```

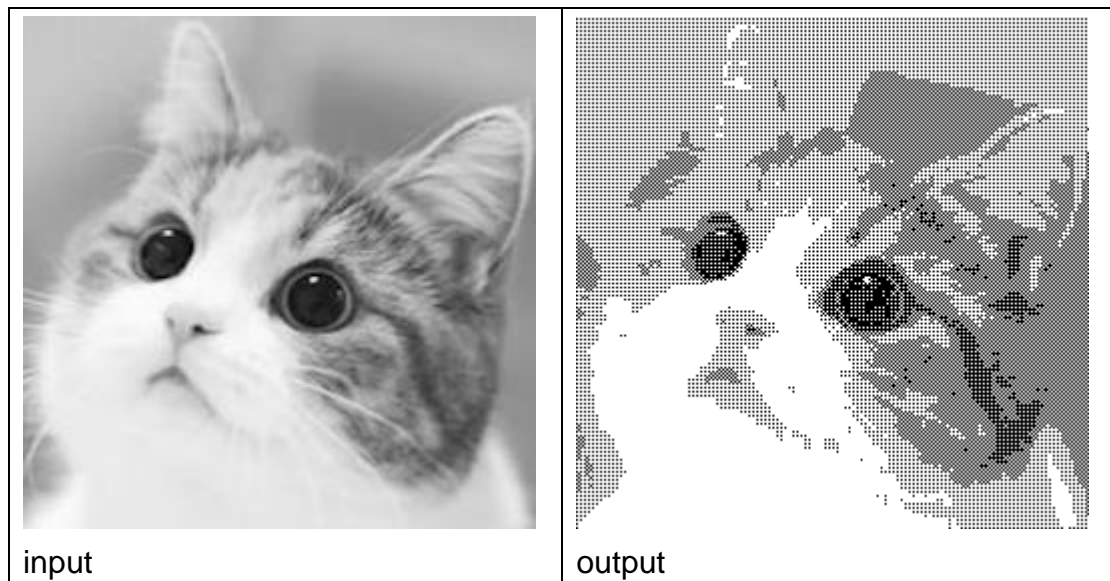
```
array([[ 95.625, 159.375],
       [223.125,  31.875]])
```

```
h, w = sample1.shape
threshold = np.tile(threshold, (h//N, w//N))
threshold
```

```
array([[ 95.625, 159.375,  95.625, ..., 159.375,  95.625, 159.375],
       [223.125,  31.875, 223.125, ...,  31.875, 223.125,  31.875],
       [ 95.625, 159.375,  95.625, ..., 159.375,  95.625, 159.375],
       ...,
       [223.125,  31.875, 223.125, ...,  31.875, 223.125,  31.875],
       [ 95.625, 159.375,  95.625, ..., 159.375,  95.625, 159.375],
       [223.125,  31.875, 223.125, ...,  31.875, 223.125,  31.875]])
```

```
result1 = np.zeros((h,w))
result1[sample1 >= threshold] = 1
```

將 I_2 擴大成與圖片一樣大後，判斷有無過 Threshold，有過的話就設為 1



看起來相當粗糙

(b) (15 pt) Expand the dither matrix I_2 to I_{256} (256×256) and use it to perform dithering. Output the result as **result2.png**. Compare result1.png and result2.png along with some discussions.

$$I_{2n}(i, j) = \begin{bmatrix} 4I_n(i, j) + 1 & 4I_n(i, j) + 2 \\ 4I_n(i, j) + 3 & 4I_n(i, j) + 0 \end{bmatrix}$$

```
n = 2
I = np.array([[1, 2], [3, 0]], dtype = 'uint8')

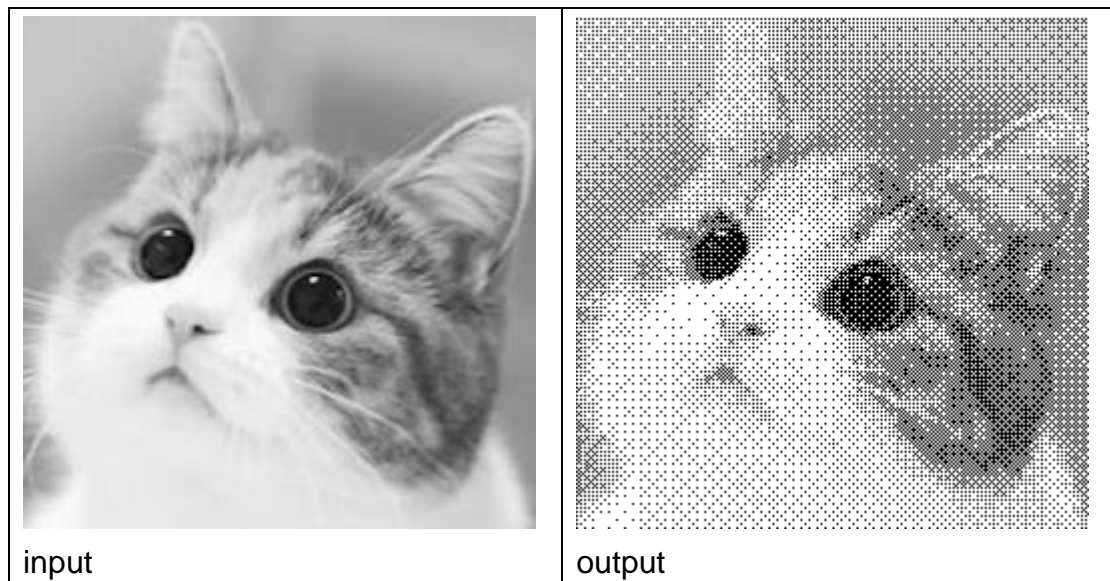
for i in range(7):
    I2 = np.zeros((n*2, n*2))

    I2[0:n, 0:n] = I*4 + 1
    I2[0:n, n: ] = I*4 + 2
    I2[n: , 0:n] = I*4 + 3
    I2[n: , n: ] = I*4 + 0

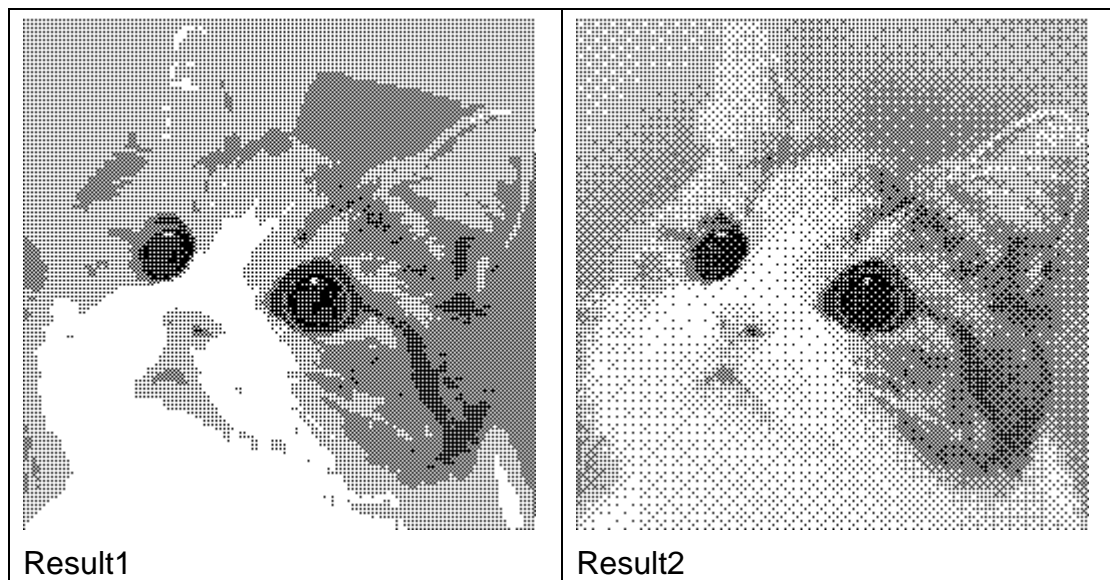
    I = I2
    n*=2

I256 = I
```

將原矩陣擴充到(256X256)後再使用跟上一題一樣的方法



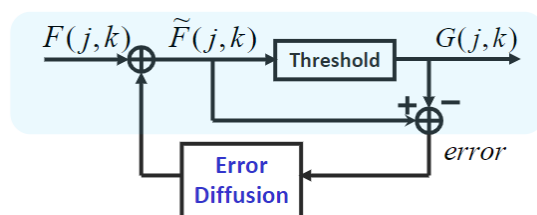
有變比較精緻一點



Result1 看起來還是會有四四方方的網格樣

Result2 的網格有較多變化

(c) (25 pt) Perform error diffusion with **Floyd-Steinberg** and **Jarvis' patterns** on **sample1.png**. Out- put the results as **result3.png** and **result4.png**, respectively. You may also try more patterns and show the results in your report. Discuss these patterns based on the results.

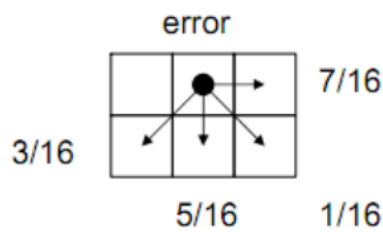


$$\text{if } \tilde{F}(j,k) \geq 0.5 \rightarrow G(j,k) = 1$$

$$\text{if } \tilde{F}(j,k) < 0.5 \rightarrow G(j,k) = 0$$

$$\text{Define } E(j,k) = \tilde{F}(j,k) - G(j,k)$$

■ 1975 Floyd Steinberg: 1976 Jarvis et al:



error

		●	7	5
3	5	7	5	3
1	3	5	3	1

(1/48)

```
# Floyd Steinberg
result3 = np.copy(np.lib.pad(sample1,(1,1),'constant')) / 255

kernel = [[0, 0, 7/16],
          [3/16, 5/16, 1/16]]

ones = np.ones((2,3))

Height, Width = result3.shape

for y in range(1, Height-1):
    for x in range(1, Width-1):

        old_value = result3[y, x]
        new_value = 0
        if (old_value >= 0.5) :
            new_value = 1

        Error = old_value - new_value

        patch = result3[y:y+2, x-1:x+2]

        NewNumber = patch + Error * ones * kernel
        NewNumber[NewNumber>1] = 1
        NewNumber[NewNumber<0] = 0

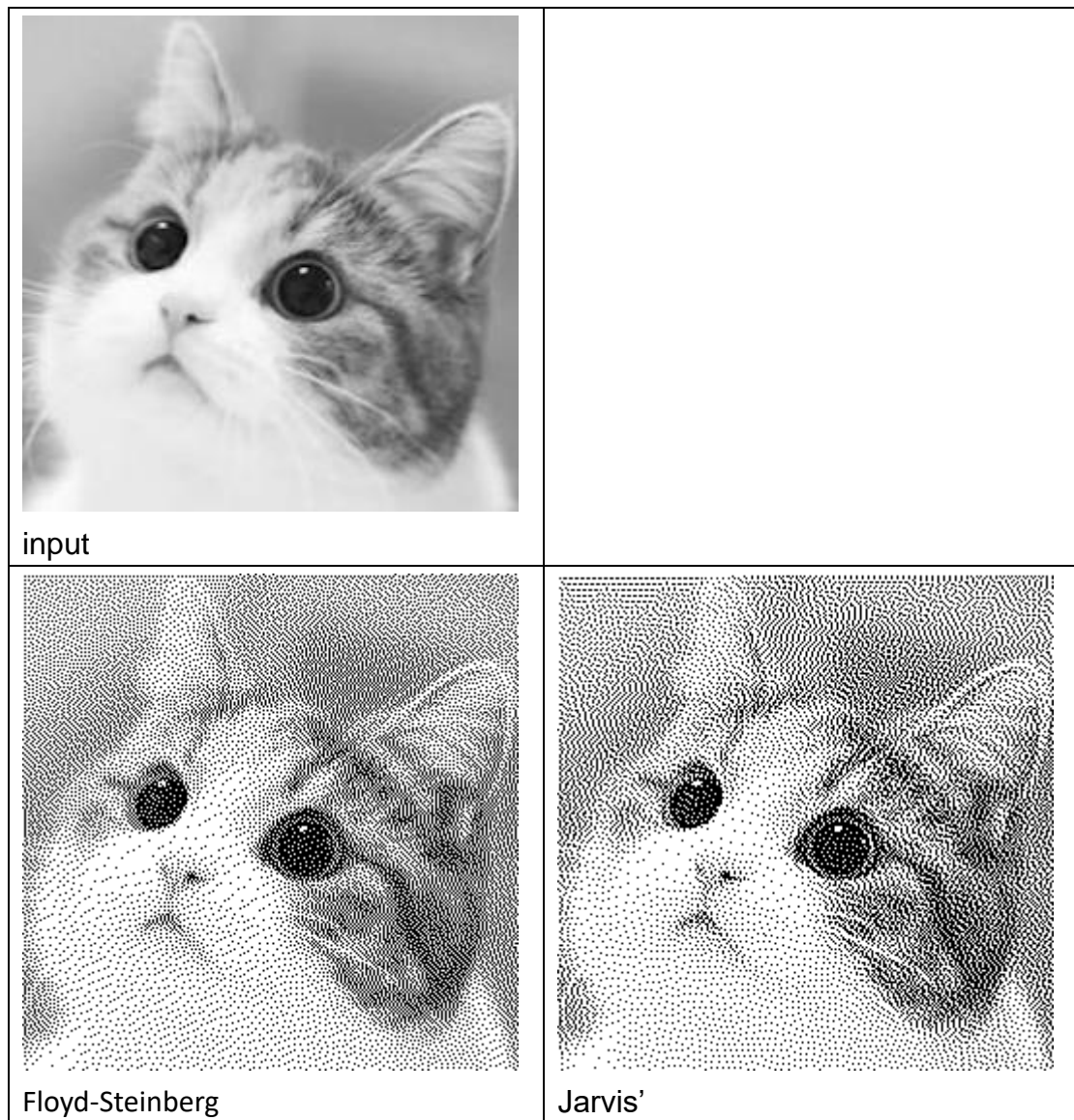
        result3[y:y+2, x-1:x+2] = NewNumber
        result3[y, x] = new_value

result3 = result3[1:257, 1:257]
```

以 Floyd-Steinberg 為例

首先判斷有無過 Threshold 給出 new_value，之後計算 Error，再將 Error 擴散給周邊 pixel(使用 kernel 計算)，擴散完後再將超過 1 的設為 1，小於 0 的設為 0

Jarvis'的算法同上，只是改變 kernel 矩陣裡的值



Discuss:

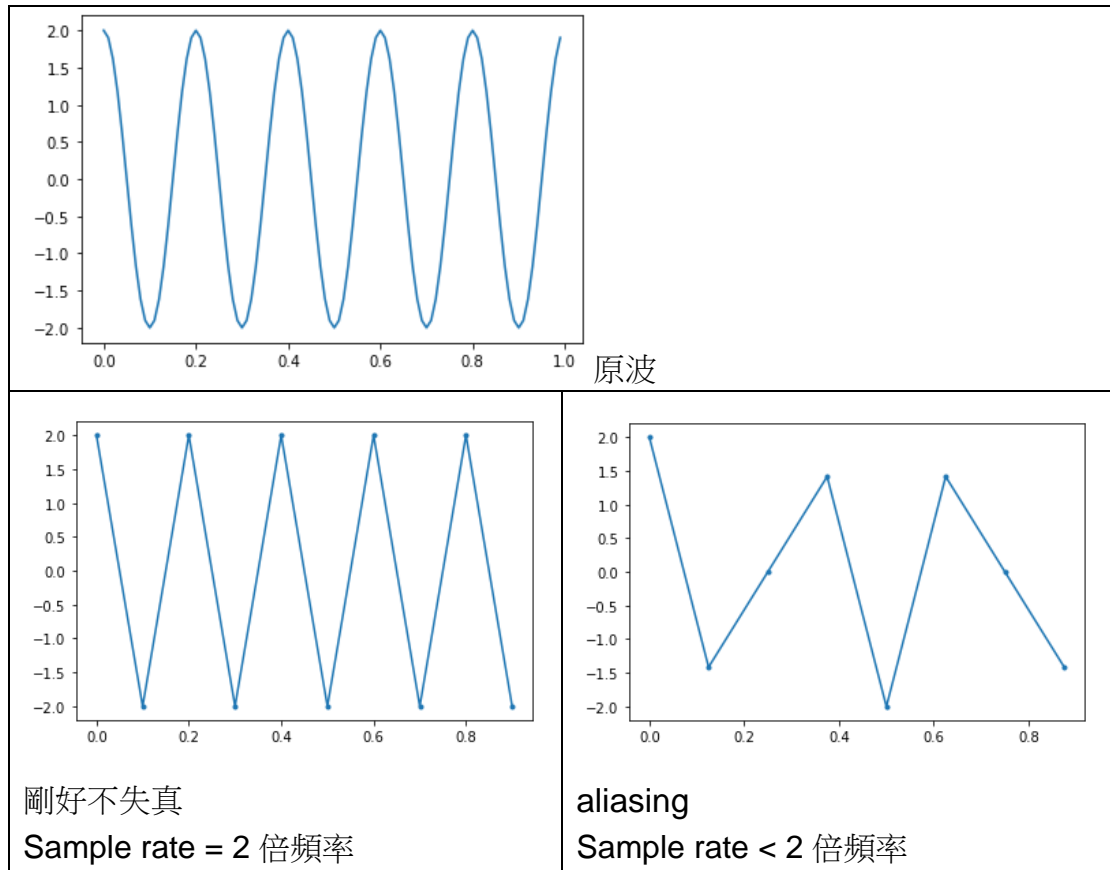
Jarvis'的眼白還有右邊鬍鬚比較明顯，空格與對比較大，Floyd-Steinberg 比較暗比較糊。

Problem 2: Image Sampling

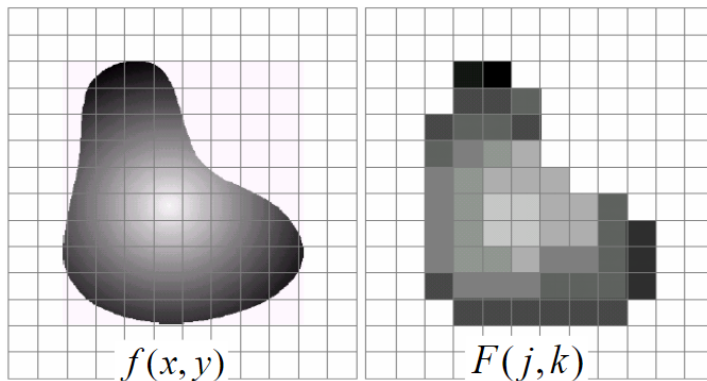
(a) (25 pt) By analyzing **sample2.png**, please explain how to perform image sampling on it to avoid aliasing. Please also perform 'inappropriate' image sampling which results in aliasing in the sampled image. Output the result as **result5.png**, specify the sampling rate you choose and discuss how it affects the resultant image.

老實說我在上課時一直半聽半懂的，因為那些公式看起來真的好可怕，不是很好理解，所以我就重新學了一下二維的 **sample**

以一維的波為例



之後又突然想到這跟老師之前在課堂上講過的圖片 **sampling** 很像，就一瞬間茅塞頓開了。

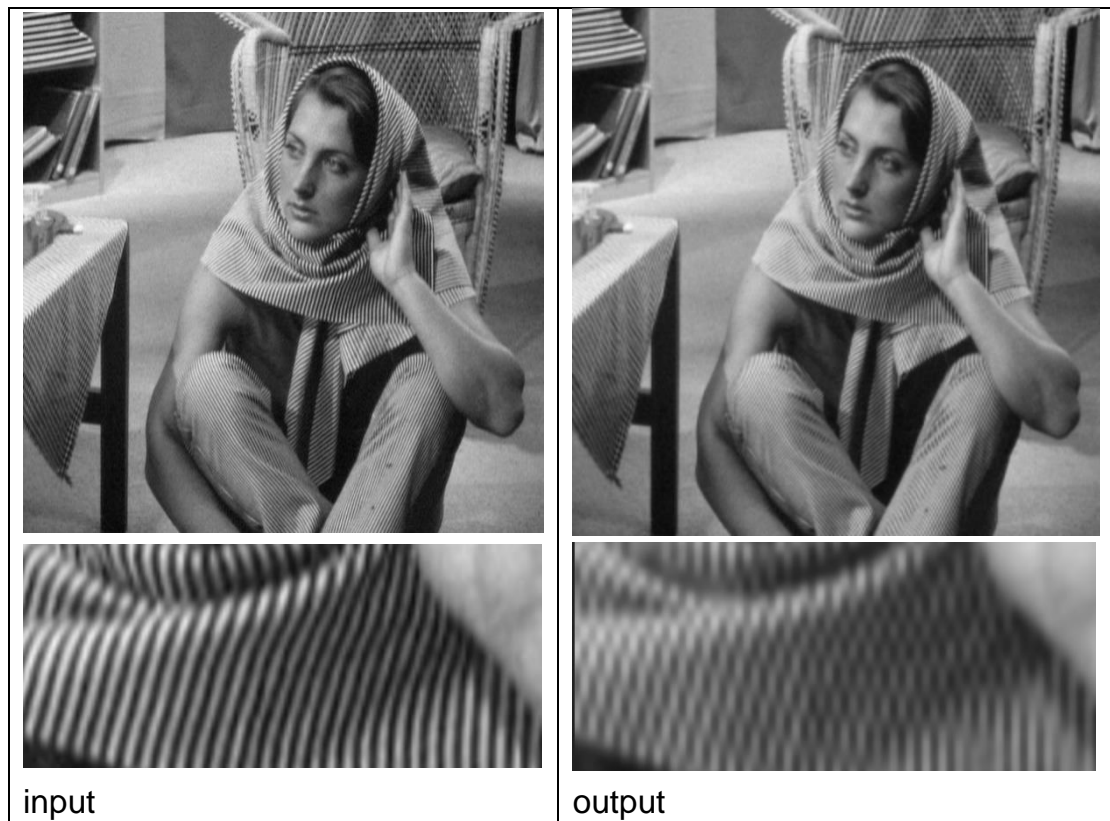


在空間域上可以把 **sample** 的頻率視為圖片解析度，**sample** 後跟原圖比有很明顯的 **aliasing**，我想在頻率域上也是一樣的原理吧。

以二維的例子來說

```
ratio = 0.5  
sample_image = cv2.resize(sample2, dsize=[0,0], fx=ratio, fy=ratio)
```

當你的 **ratio** 設為 **0.5** 時，你其實只保留了二分之一的 **col** 與 **row**，因此你的圖片喪失了一半的資訊，所以會有 **aliasing**，如同一維的例子一樣

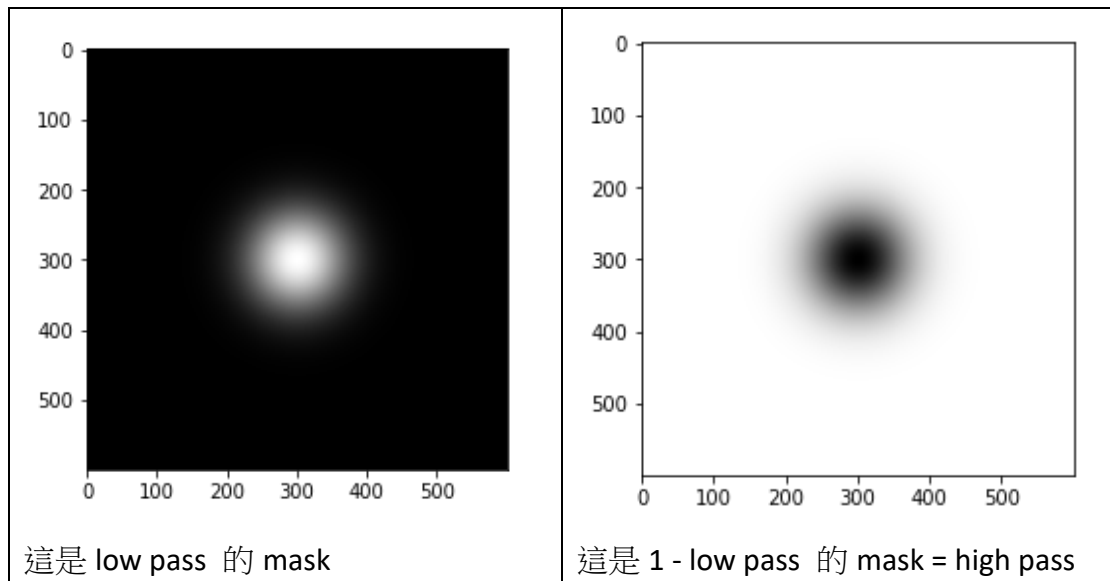


Sample 後的條紋變網格了

以這張圖來說，ratio 設 0.8 以下就會產生明顯的 aliasing，要避免產生 aliasing 就要讓 Sample rate ≥ 2 倍頻率

(b) (25 pt) Given **sample3.png**, please perform the **unsharp masking** mentioned in the lecture in the **frequency domain** and transform the result back to the pixel domain by inverse Fourier transform. Save the resultant image as **result6.png** and describe your steps in detail.

我使用的是高斯的 mask，因為比較不會有水波紋

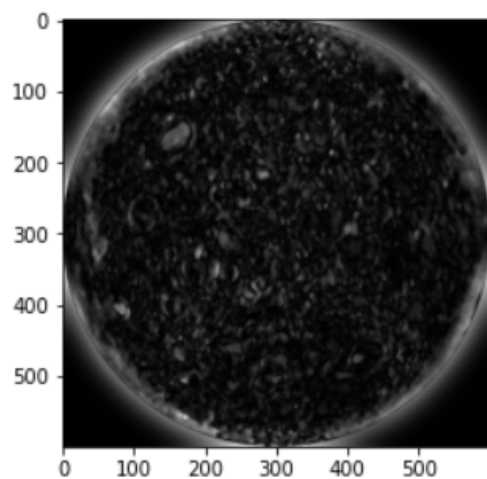


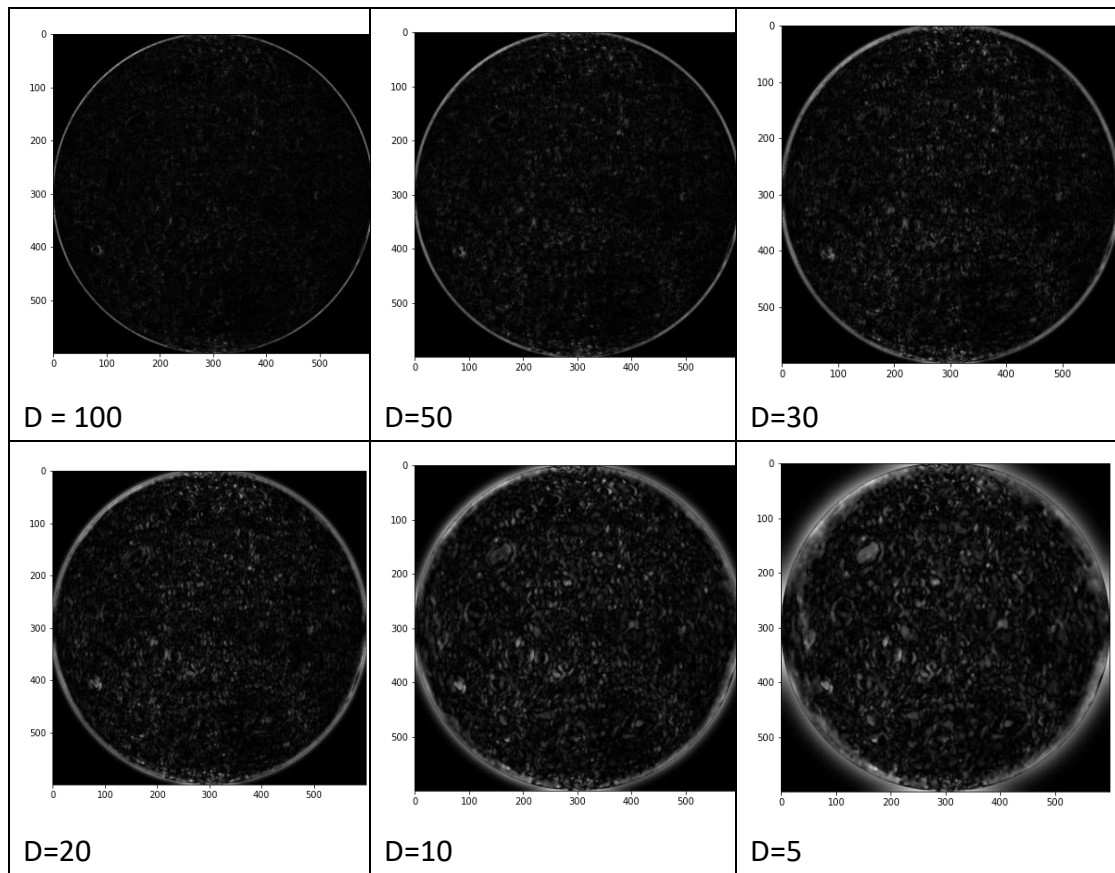
```

d0 = 5
original = np.fft.fft2(img) #傅立葉轉換
center = np.fft.fftshift(original) #將座標(0,0)轉到中心
HighPassCenter = center * gaussianHP(d0,img.shape) #乘以 high pass mask
HighPass = np.fft.ifftshift(HighPassCenter) #將座標轉回去
inverse_HighPass = np.fft.ifft2(HighPass) #做逆傅立葉轉換
result6 = np.abs(inverse_HighPass)
result6 = (result6-result6.min())/(result6.max()-result6.min())*255
plt.imshow(result6, "gray")

```

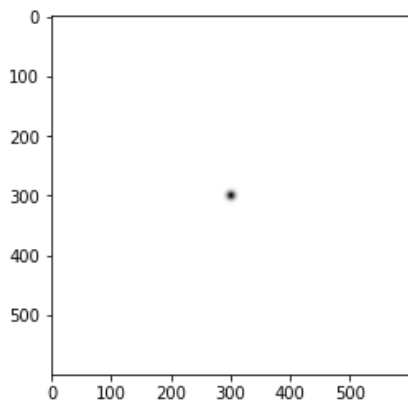
<matplotlib.image.AxesImage at 0x2521dbed700>

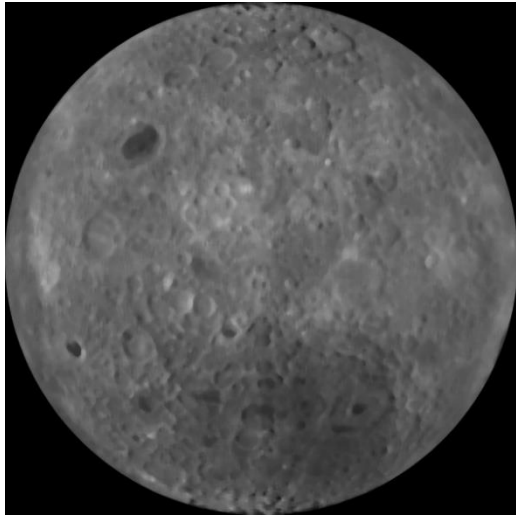




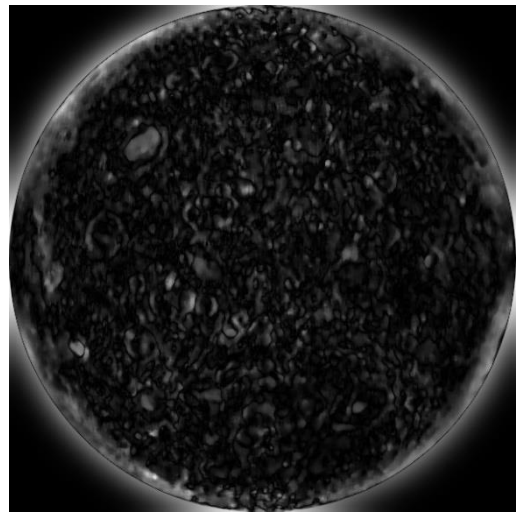
D 越小，月球表面越明顯

我最後選擇 D=5 的 mask(如下圖)，因為他能把月球的凹凸輪廓變得比較明顯





input



output